

SEL-787

Transformer Protection Relay

Instruction Manual

20140714



SCHWEITZER ENGINEERING LABORATORIES, INC.



CAUTION

The relay contains devices sensitive to Electrostatic Discharge (ESD). When working on the relay with the front panel removed, work surfaces and personnel must be properly grounded or equipment damage may result.

CAUTION

Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service.

CAUTION

There is danger of explosion if the battery is incorrectly replaced. Replace only with Ray-O-Vac® no. BR2335 or equivalent recommended by manufacturer. Dispose of used batteries according to the manufacturer's instructions.

CAUTION

Looking into optical connections, fiber ends, or bulkhead connections can result in hazardous radiation exposure.

CAUTION

Use of controls or adjustments, or performance of procedures other than those specified herein may result in hazardous radiation exposure.

WARNING

Have only qualified personnel service this equipment. If you are not qualified to service this equipment, you can injure yourself or others, or cause equipment damage.

WARNING

Use of this equipment in a manner other than specified in this manual can impair operator safety safeguards provided by this equipment.

WARNING

To install an option card, the relay must be de-energized and then reenergized. When reenergized, the relay will reboot. Therefore, de-energize the protected equipment before installing the option card to prevent damage to the equipment.

WARNING

This device is shipped with default passwords. Default passwords should be changed to private passwords at installation. Failure to change each default password to a private password may allow unauthorized access. SEL shall not be responsible for any damage resulting from unauthorized access.

DANGER

Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death.

DANGER

Contact with instrument terminals can cause electrical shock that can result in injury or death.

ATTENTION

Le relais contient des pièces sensibles aux décharges électrostatiques. Quand on travaille sur le relais avec les panneaux avant ou du dessus enlevés, toutes les surfaces et le personnel doivent être mis à la terre convenablement pour éviter les dommages à l'équipement.

ATTENTION

Les composants de cet équipement sont sensibles aux décharges électrostatiques (DES). Des dommages permanents non-décelables peuvent résulter de l'absence de précautions contre les DES. Raccordez-vous correctement à la terre, ainsi que la surface de travail et l'appareil avant d'en retirer un panneau. Si vous n'êtes pas équipés pour travailler avec ce type de composants, contacter SEL afin de retourner l'appareil pour un service en usine.

ATTENTION

Il y a un danger d'explosion si la pile électrique n'est pas correctement remplacée. Utiliser exclusivement Ray-O-Vac® No. BR2335 ou un équivalent recommandé par le fabricant. Se débarrasser des piles usagées suivant les instructions du fabricant.

ATTENTION

Regarder vers les connecteurs optiques, les extrémités des fibres ou les connecteurs de cloison peut entraîner une exposition à des rayonnements dangereux.

ATTENTION

L'utilisation de commandes ou de réglages, ou l'application de tests de fonctionnement différents de ceux décrits ci-après peuvent entraîner l'exposition à des radiations dangereuses.

AVERTISSEMENT

Seules des personnes qualifiées peuvent travailler sur cet appareil. Si vous n'êtes pas qualifiés pour ce travail, vous pourriez vous blesser avec d'autres personnes ou endommager l'équipement.

AVERTISSEMENT

L'utilisation de cet appareil suivant des procédures différentes de celles indiquées dans ce manuel peut désarmer les dispositifs de protection d'opérateur normalement actifs sur cet équipement.

AVERTISSEMENT

Pour installer une carte à option, le relais doit être éteint et ensuite rallumé. Quand il est rallumé, le relais redémarrera. Donc, il faut éteindre l'équipement protégé avant d'installer la carte à option pour empêcher des dégâts à l'équipement.

AVERTISSEMENT

Cet appareil est expédié avec des mots de passe par défaut. À l'installation, les mots de passe par défaut devront être changés pour des mots de passe confidentiels. Dans le cas contraire, un accès non-autorisé à l'équipement peut être possible. SEL décline toute responsabilité pour tout dommage résultant de cet accès non-autorisé.

DANGER

Débrancher tous les raccordements externes avant d'ouvrir cet appareil. Tout contact avec des tensions ou courants internes à l'appareil peut causer un choc électrique pouvant entraîner des blessures ou la mort.

DANGER

Tout contact avec les bornes de l'appareil peut causer un choc électrique pouvant entraîner des blessures ou la mort.

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This product is covered by the standard SEL 10-year warranty. For warranty details, visit www.selinc.com or contact your customer service representative. PM787-01

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Preface

Manual Overview

The SEL-787 Transformer Protection Relay Instruction Manual describes common aspects of transformer relay application and use. It includes the necessary information to install, set, test, and operate the relay.

An overview of each manual section and topics follows:

Preface. Describes the manual organization and conventions used to present information.

Section 1: Introduction and Specifications. Describes the basic features and functions of the SEL-787; lists the relay specifications.

Section 2: Installation. Describes how to mount and wire the SEL-787; illustrates wiring connections for various applications.

Section 3: PC Software. Describes the features, installation methods, and types of help available with the ACSELERATOR QuickSet® SEL-5030 Software.

Section 4: Protection and Logic Functions. Describes the operating characteristic of each protection element, using logic diagrams and text, and explains how to calculate element settings; describes contact output logic, automation, and report settings.

Section 5: Metering and Monitoring. Describes the operation of each metering function; describes the monitoring functions.

Section 6: Settings. Describes how to view, enter, and record settings for protection, control, communications, logic, and monitoring.

Section 7: Communications. Describes how to connect the SEL-787 to a PC for communication; shows serial port pinouts; lists and defines serial port commands. Describes the communications port interfaces and protocols supported by the relay for serial and Ethernet.

Section 8: Front-Panel Operations. Explains the features and use of the front panel, including front-panel command menu, default displays, and automatic messages.

Section 9: Analyzing Events. Describes front-panel LED operation, trip-type front-panel messages, event summary data, standard event reports, and Sequential Events Recorder (SER) report.

Section 10: Testing and Troubleshooting. Describes protection element test procedures, relay self-test, and relay troubleshooting.

Appendix A: Firmware and Manual Versions. Lists the current relay firmware version and details differences between the current and previous versions. Provides a record of changes made to the manual since the initial release.

Appendix B: Firmware Upgrade Instructions. Describes the procedure to update the firmware stored in flash memory.

Appendix C: SEL Communications Processors. Provides examples of how to use the SEL-787 with the SEL Communications Processors for total substation automation solutions.

Appendix D: DNP3 Communications. Describes the DNP3 protocol support provided by the SEL-787.

Appendix E: Modbus RTU Communications. Describes the Modbus® protocol support provided by the SEL-787.

Appendix F: IEC 61850 Communications. Describes IEC 61850 implementation in the SEL-787.

Appendix G: DeviceNet Communications. Describes the use of DeviceNet (data-link and application protocol) over CAN (hardware protocol).

Appendix H: Synchrophasors. Describes the Phasor Measurement Control Unit (PMCU), and accessing Synchrophasor data via ASCII Command (**MET PM**) and IEEE C37.118 Protocol.

Appendix I: Mirrored Bits Communications. Describes how SEL protective relays and other devices can directly exchange information quietly, securely, and with minimum cost.

Appendix J: Relay Word Bits. Lists and describes the Relay Word bits (outputs of protection and control elements).

Appendix K: Analog Quantities. Lists and describes the Analog Quantities (outputs of analog elements).

SEL-787 Relay Command Summary. Briefly describes the serial port commands that are fully described in *Section 7: Communications*.

Conventions

Typographic Conventions

There are three ways to communicate with the SEL-787:

- Using a command line interface on a PC terminal emulation window.
- Using the front-panel menus and pushbuttons.
- Using ACSELERATOR QuickSet.

The instructions in this manual indicate these options with specific font and formatting attributes. The following table lists these conventions.

Typographic Conventions


| Example | Description |
|----------------------------|---|
| STATUS | Commands typed at a command line interface on a PC. |
| <Enter> | Single keystroke on a PC keyboard. |
| <Ctrl+D> | Multiple/combination keystroke on a PC keyboard. |
| Start > Settings | PC dialog boxes and menu selections. The > character indicates submenus. |
| CLOSE | Relay front-panel pushbuttons. |
| ENABLE | Relay front- or rear-panel labels. |
| Main > Meters | Relay front-panel LCD menus and relay responses. The > character indicates submenus. |

Examples


This instruction manual uses several example illustrations and instructions to explain how to effectively operate the SEL-787. These examples are for demonstration purposes only; the firmware identification information or settings values included in these examples may not necessarily match those in the current version of your SEL-787.

Safety and General Information


This manual uses three kinds of hazard statements, formatted as follows:

 **CAUTION**

Indicates a potentially hazardous situation that, if not avoided, may result in minor or moderate injury or equipment damage.

 **DANGER**







Indicates an imminently hazardous situation that, if not avoided, **will** result in death or serious injury.

 **WARNING**

Indicates a potentially hazardous situation that, if not avoided, **could** result in death or serious injury.

Symbols

The following symbols from EN 61010-1 are often marked on SEL products.

| | | |
|-----------|---|--|
| Symbol 14 |  | Caution, Risk of Danger—Consult Documentation for Additional Information |
| Symbol 6 |  | Protective (Safety) Ground Conductor Terminal |
| Symbol 1 |  | Direct Current |
| Symbol 2 |  | Alternating Current |
| Symbol 3 |  | Direct and Alternating Current |
| Symbol 5 |  | Earth (Ground) Terminal |

Product Labels

The two labels shown below are the Product Labels for the high voltage and low voltage power supply options. The label is located on the left side panel of the product. The label shows the serial number, model number and the ratings of the product.

P/N 0787XX1XXXXXXXXXXXXX
S/N 1234567890

Supply Range (U_s) 125/250V —
120/240V ~ 50/60Hz

VA Rating 40 VA/20W
Internal Fuse T3.15A H 250V
Rated Impulse Withstand (U_{imp}) 4kV
Insulation Voltage (U_i) 300V

CONTACT OUTPUTS (OUT101-OUT103)

Operational Voltage (U_o) 240V ~ MAX
Operational Current (I_o) 3A @ 120V
1.5A @ 240V

Thermal Current (I_{the}) 5A
Utilization Category AC-15
Contact Rating Designation B300
Insulation Voltage (U_i) 300V
Short-Circuit Rating 1kA

OPTIONAL OUTPUTS / INPUTS
See manual for ratings ⚠

INSTALLATION REQUIREMENTS

Enclosure Type 12, IP65
Degree of Protection (Terminals) IP20
Wire (105°C Cu) 26 to 12 AWG
0.14 to 2.5mm²
Torque 7lb-in, 0.79Nm
Temperature See manual for ratings ⚠

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(for high-voltage supply)

P/N 0787XX2XXXXXXXXXXXXX
S/N 1234567890

Supply Range (U_s) 24/48V —

VA Rating 20W
Internal Fuse T3.15A H 250V
Rated Impulse Withstand (U_{imp}) 4kV
Insulation Voltage (U_i) 300V

CONTACT OUTPUTS (OUT101-OUT103)

Operational Voltage (U_o) 240V ~ MAX
Operational Current (I_o) 3A @ 120V
1.5A @ 240V

Thermal Current (I_{the}) 5A
Utilization Category AC-15
Contact Rating Designation B300
Insulation Voltage (U_i) 300V
Short-Circuit Rating 1kA

OPTIONAL OUTPUTS / INPUTS
See manual for ratings ⚠

INSTALLATION REQUIREMENTS

Enclosure Type 12, IP65
Degree of Protection (Terminals) IP20
Wire (105°C Cu) 26 to 12 AWG
0.14 to 2.5mm²
Torque 7lb-in, 0.79Nm
Temperature See manual for ratings ⚠

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(for low-voltage supply)

LED Emitter

⚠ CAUTION

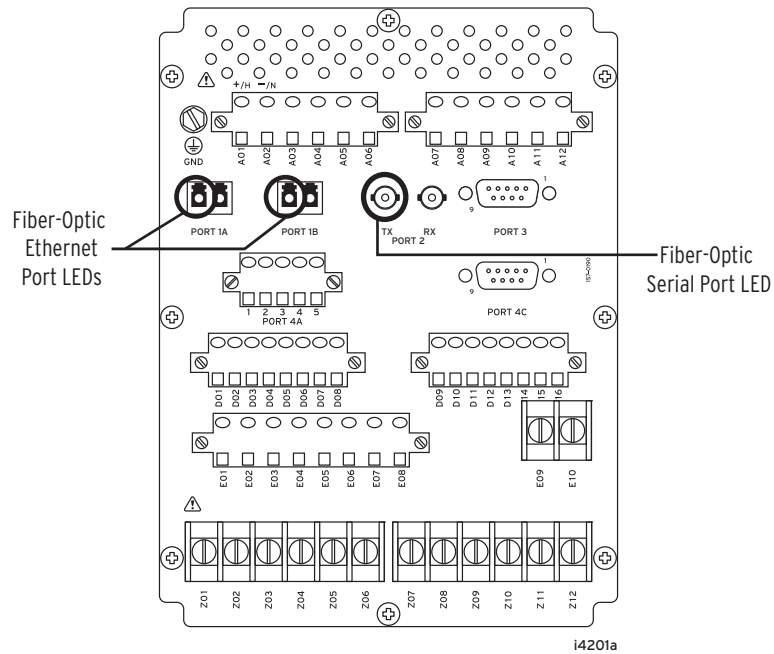
Looking into optical connections, fiber ends, or bulkhead connections can result in hazardous radiation exposure.

The following table shows LED information specific to the SEL-787 (see *Figure 2.9* for the location of fiber-optic Ethernet **PORT 1** (or 1A, 1B) and **PORT 2**, the ports using these LEDs, on the relay).

SEL-787 LED Information

| Item | Fiber-Optic Ethernet Port 1 (1A, 1B) | Port 2 |
|----------------------|--------------------------------------|-----------|
| Mode | Multimode | Multimode |
| Wavelength | 1300 nm | 820 nm |
| Source | LED | LED |
| Connector type | LC | ST |
| Typical Output power | -15.7 dBm | -16 dBm |

The following figure shows the LED location specific to the SEL-787 (see *Figure 2.9* for the complete rear-panel drawing).



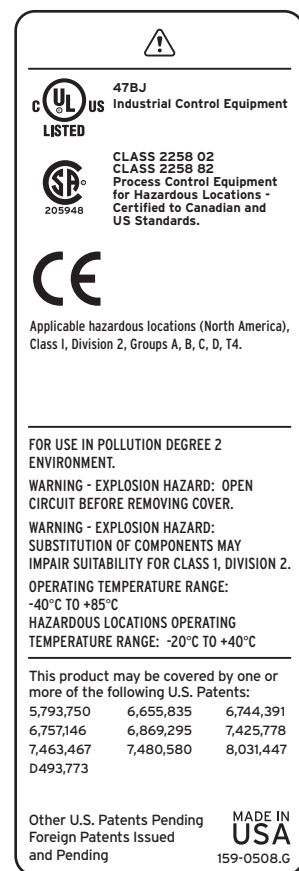
LED Location Specific to the SEL-787

LED Safety Warnings and Precautions

- Do not look into the end of an optical cable connected to an optical output.
- Do not look into the fiber ports/connectors.
- Do not perform any procedures or adjustments that are not described in this manual.
- During installation, maintenance, or testing of the optical ports only use test equipment classified as Class 1 laser products.
- Incorporated components such as transceivers and laser/LED emitters are not user serviceable. Units must be returned to SEL for repair or replacement.

Compliance Approvals

The figure shows the SEL-787 compliance label that is located on the left side of the device.



Product Compliance Label for the SEL-787

Environmental Conditions and Voltage Information

The following table lists important environmental and voltage information.

| Condition | Range/Description |
|--|----------------------------|
| Indoor/outdoor use | Indoor |
| Altitude (Consult the factory for derating specifications for higher altitude applications) | To 2000 m |
| Temperature IEC Performance Rating (per IEC/EN 60068-2-1 and IEC/EN 60068-2-2) | -40 to +85°C |
| Relative humidity | 5 to 95% |
| Main supply voltage fluctuations | To ±10% of nominal voltage |
| Overvoltage | Category II |
| Pollution | Degree 2 |
| Atmospheric pressure | 80 to 110 kPa |

Wire Sizes and Insulation

Wire sizes for grounding (earthing), current, voltage, and contact connections are dictated by the terminal blocks and expected load currents. You may use the following table as a guide in selecting wire sizes.

| Connection Type | Minimum Wire Size | Maximum Wire Size |
|---------------------------------|-------------------------------|-------------------------------|
| Grounding (Earthing) Connection | 18 AWG (0.8 mm ²) | 14 AWG (2.1 mm ²) |
| Current Connection | 16 AWG (1.3 mm ²) | 12 AWG (3.3 mm ²) |
| Potential (Voltage) Connection | 18 AWG (0.8 mm ²) | 14 AWG (2.1 mm ²) |
| Contact I/O | 18 AWG (0.8 mm ²) | 14 AWG (2.1 mm ²) |
| Other Connection | 18 AWG (0.8 mm ²) | 14 AWG (2.1 mm ²) |

Instructions for Cleaning and Decontamination

Use a mild soap or detergent solution and a damp cloth to carefully clean the SEL-787 chassis when necessary. Avoid using abrasive materials, polishing compounds, and harsh chemical solvents (such as xylene or acetone) on any surface of the relay.

Technical Assistance

WARNING

Use of this equipment in a manner other than specified in this manual can impair operator safety safeguards provided by this equipment.

Obtain technical assistance from the following address:

Schweitzer Engineering Laboratories, Inc.
 2350 NE Hopkins Court
 Pullman, WA 99163-5603 U.S.A.
 Phone: +1.509.332.1890
 Fax: +1.509.332.7990
 Internet: www.selinc.com or selindustrial.com
 E-mail: info@selinc.com

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Section 1

Introduction and Specifications

Overview

The SEL-787 Transformer Protection Relay is designed to provide current differential and overcurrent protection to two-winding transformers, buses, generators, etc. The basic relay provides current differential and instantaneous and inverse time-overcurrent protection. Voltage-based and RTD-based protection are available as options. All relay models provide monitoring functions.

This manual contains the information needed to install, set, test, operate, and maintain any SEL-787. You need not review the entire manual to perform specific tasks.

For additional technical references on applications and testing (i.e., technical papers, application guides), visit www.selinc.com/literature/.

Features

Standard Protection Features

- Phase Instantaneous Overcurrent (50P)
- Ground (Residual) Instantaneous Overcurrent (50G)
- Negative-Sequence Overcurrent (50Q)
- Phase Time Overcurrent (51P)
- Ground (Residual) Time Overcurrent (51G)
- Negative-Sequence Time Overcurrent (51Q)
- Current Differential (87)
- Breaker Failure Protection

Optional Protection Features

- Voltage-Based Protection
 - Undervoltage (27)
 - Overvoltage (59)
 - Negative-Sequence Overvoltage (59Q)
 - Directional Power (32)
 - Loss of Potential (60LOP)
 - Frequency (81)
 - Volts/Hertz (24)

- Neutral Current-Based Protection
 - Neutral Instantaneous Overcurrent (50N)
 - Neutral Time Overcurrent (51N)
 - Restricted Earth Fault (REF)
- RTD-Based Protection: As many as ten (10) RTDs may be monitored when an internal RTD card is used, or as many as twelve (12) when an external SEL-2600 RTD Module with the ST[®] option (SEL-2812 compatible) is used. There are separate Trip and Warn settings for each RTD.

Monitoring Features

- Event Summaries that contain relay ID, date and time, trip cause, and current/voltage magnitudes
- Event Reports including filtered and raw analog data
- Sequential Events Record (SER)
- Compatibility with SEL-3010 Event Messenger
- Transformer Through-Fault Event Monitor
- A complete suite of accurate metering functions

Communications and Control

- EIA-232, front-panel port
- EIA-232, EIA-485, Ethernet (single/dual copper or fiber-optic), and SEL-2812 compatible ST fiber-optic rear-panel port
- IRIG-B time-code input
- Modbus[®] RTU slave, Modbus TCP/IP, DNP3 serial or LAN/WAN, Ethernet[®] FTP, Telnet, SNTP, MIRRORING BITS[®], IEC 61850, DeviceNet[™], File Transfer Protocols, and Synchrophasors with C37.118 Protocol
- SEL ASCII, Compressed ASCII, Fast Meter, Fast Operate, Fast SER, Fast Message Protocols, and Event Messenger Protocol
- Programmable Boolean and math operators, logic functions, and analog compare

Models, Options, and Accessories

Models

Complete ordering information is not provided in this instruction manual. See the latest SEL-787 Model Option Table at www.selinc.com, under SEL Literature, Ordering Information (Model Option Tables). Options and accessories are listed below.

SEL-787 Base Unit

- Front panel with large LCD display
 - 4 programmable [buttons with 8 LEDs
 - 8 target LEDs (6 programmable)
 - Operator control interface
 - EIA-232 port

- Processor and communications card (Slot B)
 - EIA-232 serial port with IRIG-B time code input
 - Multimode (ST®) fiber-optic serial port (SEL-2812 compatible)
 - EIA-485 serial port with external IRIG-B time code input (terminals B01, B02)
- Six ac current inputs card (Slot Z)
- Power supply card with two digital inputs and three digital outputs (Slot A)
- Three expansion slots for optional cards (Slots C, D, E)
- Protocols
 - Modbus RTU
 - SEL ASCII and Compressed ASCII
 - SEL Fast Meter, Fast Operate, Fast SER, Fast Message
 - Ymodem File Transfer
 - SEL MIRRORING BITS
 - Event Messenger®
 - Synchrophasors with C37.118

Options

- Neutral AC Current Option (1 A or 5 A neutral)
- Voltage Option
 - Four-wire wye
 - Open-delta
 - Single phase connected
- Input/Output (I/O) Option
 - Additional digital I/O
 - Additional analog I/O
 - 10 RTD inputs
- Communications Options (Protocol/Ports)
 - EIA-485/EIA-232/Ethernet ports (single/dual copper or fiber-optic)
 - Modbus TCP/IP
 - DeviceNet
 - IEC 61850 Communications
 - DNP3 serial and LAN/WAN
 - Simple Network Time Protocol (SNTP)

Accessories

Contact your Technical Service Center or the SEL factory for additional detail and ordering information for the following accessories:

- External RTD protection
 - SEL-2600 RTD Module (with ST option only)
 - A simplex 62.5/125 μ m fiber-optic cable with ST connector for connecting the external RTD module to the SEL-787
- Remote I/O with SEL-2505 Remote I/O Module (SEL-2812 compatible ST option only)

- SEL-787 Configurable Labels
- Rack-Mounting Kits
 - For one relay
 - For two relays
 - For one relay and a test switch
- Wall-Mounting Kits
- Bezels for Retrofit
- Replacement Rear Connector Kit

For all SEL-787 mounting accessories for competitor products' replacement, including adapter plates, visit <http://www.selinc.com/MountingAccessories>.

Applications

Refer to *Section 2: Installation* for various applications and their related connection diagrams. The following is a list of possible application scenarios:

- Two-winding transformer protection with current differential and overcurrent elements and through-fault monitor
- Two-winding transformer protection with current differential and overcurrent elements and through-fault monitor with optional restricted earth fault protection (REF) and neutral-overcurrent protection
- Two-winding transformer protection with current differential and overcurrent elements and through-fault monitor with optional voltage elements, power elements, and frequency elements
- Two-winding transformer protection with current differential and overcurrent elements and through-fault monitor with optional internal or external RTD inputs module

Getting Started

IMPORTANT: Upon relay initial power up or Port 1 setting changes or Logic setting changes, the user may have to wait as long as two minutes before an additional setting change can occur. Note that the relay is functional with protection enabled, as soon as the **ENABLED LED** comes ON (about 5-10 seconds from power up).

Understanding basic relay operation principles and methods will help you use the SEL-787 effectively. This section presents the fundamental knowledge you need to operate the SEL-787, organized by task. These tasks help you become familiar with the relay and include the following:

- Powering the relay
- Establishing communication
- Checking relay status
- Setting the date and time

Perform these tasks to gain a fundamental understanding of relay operation.

Powering the Relay

Power the SEL-787 with 125/250 Vac/dc or 24/48 Vdc, depending on the part number.

- Observe proper polarity, as indicated by the **+/H** (terminal **A01**) and the **-/N** (terminal **A02**) on the power connections.
- Connect the ground lead; see *Grounding (Earthing) Connections* on page 2.19.
- Once connected to power, the relay does an internal self-check and the **ENABLED** LED illuminates.

Establishing Communication

The SEL-787 base model has two EIA-232 serial communications ports. The following steps require PC terminal emulation software and an SEL Cable C234A (or equivalent) to connect the SEL-787 to the PC. See *Section 7: Communications* for further information on serial communications connections and the required cable pinout.

- Step 1. Connect the PC and the SEL-787 using the serial communications cable.
- Step 2. Apply power to both the PC and the relay.
- Step 3. Start the PC terminal emulation program.
- Step 4. Set the PC terminal emulation program to the communications port settings listed in the Default Value column of *Table 1.1*. Also, set the terminal program to emulate either VT100 or VT52 terminals.
- Step 5. Press the **<Enter>** key on the PC keyboard to check the communications link.

You will see the = prompt at the left side of the computer screen.

If you do not see the = prompt, check the cable connections, and confirm that the settings in the terminal emulation program are the default values in *Table 1.1*.

- Step 6. Type **QUIT <Enter>** to view the relay response header.

You will see a computer screen display similar to *Figure 1.1*. If you see jumbled characters, change the terminal emulation type in the PC terminal emulation program.

```
=>QUIT <Enter>=>QUIT <Enter>
Transformer xyz      Date: 03/10/2008  Time: 10:31:43
Station 1           Time Source: Internal
```

Figure 1.1 Response Header

- Step 7. Type **ACC <Enter>** and the appropriate password (see *Table 7.34* for factory-default passwords) to go to Access Level 1.

NOTE: See Step 12 on page 2.11 for information about the part number displayed.

Checking Relay Status

Table 1.1 SEL-787 Serial Port Settings

| Description | Setting Label | Default Value |
|-------------------|---------------|---------------|
| SPEED | SPEED | 9600 |
| DATA BITS | BITS | 8 |
| PARITY | PARITY | N |
| STOP BITS | STOP | 1 |
| PORT TIMEOUT | T_OUT | 5 |
| HWDR HAND-SHAKING | RTSCTS | N |

Use the **STA** serial port command to view the SEL-787 operational status. Analog channel dc offset and monitored component status are listed in the status report depicted in *Figure 1.2*.

```

=>>STA <Enter>

SEL-787                                     Date: 06/28/2011   Time: 11:00:07.626
TRANSFRMR RELAY                           Time Source: Internal

Serial Num = 12345678910111
FID = SEL-787-R206-V0-Z003001-D20110610      CID = C351
PART NUM = 0787EX1BOX9X7585063X

SELF TESTS (W=Warn)
FPGA  GPSB  HMI   RAM   ROM   CR_RAM  NON_VOL  CLOCK  CID_FILE  +0.9V  +1.2V
OK    OK    OK    OK    OK    OK      OK      OK    OK       0.90  1.20

+1.5V +1.8V +2.5V +3.3V +3.75V +5.0V -1.25V -5.0V  BATT
1.49  1.81  2.51  3.33  3.74  4.96 -1.25 -4.96  3.02

Option Cards
CARD_C  CARD_D  CARD_E  CURRENT
OK      OK      OK      OK

Offsets
IAW1  IBW1  ICW1  IAW2  IBW2  ICW2  IN   VA   VB   VC
0     0     0     0     0     0     0   0   0   0

Relay Enabled

=>>

```

Figure 1.2 STA Command Response—No DeviceNet Communications Card or EIA-232/EIA-485 Communications Card

If a communications card with the DeviceNet protocol is present, the status report depicted in *Figure 1.3* applies. If a communications card with Modbus RTU protocol is present, the status report depicted in *Figure 1.2* applies.


```

=>>STA <Enter>

SEL-787                               Date: 06/28/2011   Time: 10:59:30.907
TRNSFRMR RELAY                       Time Source: Internal

Serial Num = 12345678910111
FID = SEL-787-R206-V0-Z003001-D20110610      CID = C351
PART NUM = 0787EX1BA39X7585063X

SELF TESTS (W=Warn)
FPGA  GPSB  HMI   RAM   ROM   CR_RAM  NON_VOL  CLOCK  CID_FILE  +0.9V  +1.2V
OK    OK    OK    OK    OK    OK      OK      OK     OK       0.90   1.21

+1.5V  +1.8V  +2.5V  +3.3V  +3.75V  +5.0V  -1.25V  -5.0V  BATT
1.49   1.81   2.51   3.33   3.74   4.96   -1.25   -4.96   3.02

Option Cards
CARD_C  CARD_D  CARD_E  CURRENT
OK      OK      OK      OK

DeviceNet
DN_MAC_ID  ASA  DN_RATE  DN_STATUS
3          1a28 35b3h  AUTO      0000 0000

Offsets
IAW1  IBW1  ICW1  IAW2  IBW2  ICW2  IN  VA  VB  VC
0     0     0     0     0     0     0   0   0   0

Relay Enabled

=>>

```

Figure 1.3 STA Command Response—With DeviceNet Communications Card

Table 7.48 provides the definition of each status report designator and Table 10.8 shows all the self-tests performed by the relay. The beginning of the status report printout (see Figure 1.2) contains the relay serial number, firmware identification string (FID), and checksum string (CID). These strings uniquely identify the relay and the version of the operating firmware.

Setting the Date and Time

DAT (Date Command)

Viewing the Date

Type **DAT** <Enter> at the prompt to view the date stored in the SEL-787. If the date stored in the relay is February 28, 2008, and the DATE_F setting is MDY, the relay will reply:

```
2/28/2008
```

If the DATE_F setting is YMD, the relay will reply:

```
2008/2/28
```

If the DATE_F setting is DMY, the relay will reply:

```
28/2/2008
```

Changing the Date

Type **DAT** followed by the correct date at the prompt to change the date stored in the relay. For example, to change the date to May 2, 2008 (DATE_F = MDY), enter the following at the action prompt:

```
DAT 5/2/08
```

You can separate the month, day, and year parameters with spaces, commas, slashes, colons, and semicolons.

TIM (Time Command)

Viewing the Time

Enter **TIM** at the prompt to view the time stored in the SEL-787. The relay will reply with the stored time:

```
13:52:44
```

This time is 1:52 p.m. (and 44 seconds).

Changing the Time

Enter **TIM** followed by the correct time at the action prompt to change the time stored in the relay. For example, to change the time to 6:32 a.m., enter the following at the prompt:

```
TIM 6:32:00
```

You can separate the hours, minutes, and seconds parameters with spaces, commas, slashes, colons, and semicolons.

Specifications

General

AC Current Input

Phase and Neutral Currents

$I_{NOM} = 1\text{ A}$ or 5 A secondary depending on model

$I_{NOM} = 5\text{ A}$

Continuous Rating: 15 A , linear to 96 A symmetrical

1 Second Thermal: 500 A

Burden (per phase): $< 0.1\text{ VA}$

$I_{NOM} = 1\text{ A}$

Continuous Rating: 3 A , linear to 19.2 A symmetrical

1 Second Thermal: 100 A

Burden (per phase): $< 0.01\text{ VA}$

Measurement Category: II

AC Voltage Inputs

VNOM (L-L secondary) Range: $100\text{--}250\text{ V}$ (if DELTA_Y := DELTA)
 $100\text{--}440\text{ V}$ (if DELTA_Y := WYE)

Rated Continuous Voltage: 300 Vac

10 Second Thermal: 600 Vac

Burden: $< 0.1\text{ VA}$

Input Impedance: $4\text{ M}\Omega$ differential (phase-to-phase)
 $7\text{ M}\Omega$ common mode (phase-to-chassis)

Power Supply

$125/250\text{ Vdc}$ or $120/240\text{ Vac}$

Rated Supply Voltage: $110\text{--}240\text{ Vac}$, $50/60\text{ Hz}$
 $110\text{--}250\text{ Vdc}$

Input Voltage Range: $85\text{--}264\text{ Vac}$
 $85\text{--}300\text{ Vdc}$

Power Consumption: $< 40\text{ VA}$ (ac)
 $< 20\text{ W}$ (dc)

Interruptions: 50 ms @ 125 Vac/Vdc
 100 ms @ 250 Vac/Vdc

$24/48\text{ Vdc}$

Rated Supply Voltage: $24\text{--}48\text{ Vdc}$

Input Voltage Range: $19.2\text{--}60.0\text{ Vdc}$

Power Consumption: $< 20\text{ W}$ (dc)

Interruptions: 10 ms @ 24 Vdc
 50 ms @ 48 Vdc

Output Contacts

General

OUT103 is a Form C Trip Output, all other outputs are Form A, except for the SELECT 4 DI / 3 DO card, which supports two Form-C outputs and one Form-B output.

Dielectric Test Voltage: 2500 Vac

Impulse Withstand Voltage (U_{imp}): 4700 V

Mechanical Durability: $100,000$ no load operations

Pickup/Dropout Time: $\leq 8\text{ ms}$ (coil energization to contact closure)

DC Output Ratings

Rated Operational Voltage: 250 Vdc

Rated Voltage Range: $19.2\text{--}275\text{ Vdc}$

Rated Insulation Voltage: 300 Vdc

Make: 30 A @ 250 Vdc per IEEE C37.90

Continuous Carry: 6 A @ 70°C
 4 A @ 85°C

Thermal: 50 A for 1 s

Contact Protection: 360 Vdc , 40 J MOV protection across open contacts

Breaking Capacity (10,000 operations) per IEC 60255-0-20:1974:

24 Vdc 0.75 A L/R = 40 ms

48 Vdc 0.50 A L/R = 40 ms

125 Vdc 0.30 A L/R = 40 ms

250 Vdc 0.20 A L/R = 40 ms

Cyclic (2.5 cycles/second) per IEC 60255-0-20:1974:

24 Vdc 0.75 A L/R = 40 ms

48 Vdc 0.50 A L/R = 40 ms

125 Vdc 0.30 A L/R = 40 ms

250 Vdc 0.20 A L/R = 40 ms

AC Output Ratings

Maximum Operational Voltage (U_e) Rating: 240 Vac

Insulation Voltage (U_i) Rating (excluding EN 61010-1): 300 Vac

Utilization Category: AC-15 (control of electromagnetic loads $> 72\text{ VA}$)

Contact Rating Designation: B300 (B = 5 A , 300 = rated insulation voltage)

Voltage Protection Across Open Contacts: 270 Vac , 40 J

Rated Operational Current (I_e): 3 A @ 120 Vac
 1.5 A @ 240 Vac

Conventional Enclosed Thermal Current (I_{the}) Rating: 5 A

Rated Frequency: $50/60 \pm 5\text{ Hz}$

Electrical Durability Make VA Rating: 3600 VA , $\cos\phi = 0.3$

Electrical Durability Break VA Rating: 360 VA , $\cos\phi = 0.3$

UL/CSA Digital Output Contact Temperature Derating for Operating at Elevated Temperatures

| Digital Output Cards Installed | Operating Ambient | Maximum Value of Current (I_{the}) | Duty Factor |
|--------------------------------|---|--|-------------|
| 1–3 | less than or equal to 60°C | 5.0 A | Continuous |
| 1–3 | between 60°C and 70°C | 2.5 A | Continuous |

Fast Hybrid (High-Speed High-Current Interrupting)

Make: 30 A

Carry: 6 A continuous carry at 70°C
 4 A continuous carry at 85°C

1 s Rating: 50 A

Open State Leakage Current: $< 100\text{ }\mu\text{A}$

MOV Protection (maximum voltage): $250\text{ Vac}/330\text{ Vdc}$

Pickup Time: $< 50\text{ }\mu\text{s}$, resistive load

Dropout Time: 8 ms , resistive load

Update Rate: $1/8\text{ cycle}$

Break Capacity (10000 operations):

48 Vdc 10.0 A L/R = 40 ms

125 Vdc 10.0 A L/R = 40 ms

250 Vdc 10.0 A L/R = 20 ms

Cyclic Capacity (4 cycles in 1 second, followed by 2 minutes idle for thermal dissipation):

| | | |
|---------|--------|-------------|
| 48 Vdc | 10.0 A | L/R = 40 ms |
| 125 Vdc | 10.0 A | L/R = 40 ms |
| 250 Vdc | 10.0 A | L/R = 20 ms |

NOTE: Per IEC 60255-23:1994, using the simplified method of assessment.

NOTE: Make rating per IEEE C37.90-1989.

Optoisolated Control Inputs

When Used With DC Control Signals

| | |
|--------|---|
| 250 V: | ON for 200–312.5 Vdc OFF below 150 Vdc |
| 220 V: | ON for 176–275 Vdc OFF below 132 Vdc |
| 125 V: | ON for 100–156.2 Vdc OFF below 75 Vdc |
| 110 V: | ON for 88–137.5 Vdc OFF below 66 Vdc |
| 48 V: | ON for 38.4–60 Vdc OFF below 28.8 Vdc |
| 24 V: | ON for 15–30 Vdc OFF for <5 Vdc |

When Used With AC Control Signals

| | |
|--------|---|
| 250 V: | ON for 170.6–312.5 Vac OFF below 106 Vac |
| 220 V: | ON for 150.2–275 Vac OFF below 93.3 Vac |
| 125 V: | ON for 85–156.2 Vac OFF below 53 Vac |
| 110 V: | ON for 75.1–137.5 Vac OFF below 46.6 Vac |
| 48 V: | ON for 32.8–60 Vac OFF below 20.3 Vac |
| 24 V: | ON for 14–30 Vac OFF below 5 Vac |

| | |
|-------------------------------------|--|
| Current draw at nominal dc voltage: | 2 mA (at 220–250 V) 4 mA (at 48–125 V) 10 mA (at 24 V) |
|-------------------------------------|--|

| | |
|--|--------|
| Rated Impulse Withstand Voltage (U_{imp}): | 4000 V |
|--|--------|

Analog Output (Optional)

| | 1A0 | 4A0 |
|-------------------------------|--|-----------------|
| Current: | 4–20 mA | ±20 mA |
| Voltage: | — | ±10 V |
| Load at 1 mA: | — | 0–15 k Ω |
| Load at 20 mA: | 0–300 Ω | 0–750 Ω |
| Load at 10 V: | — | >2000 Ω |
| Refresh Rate: | 100 ms | 100 ms |
| % Error, Full Scale, at 25°C: | < ±1% | < ±0.55% |
| Select From: | Analog quantities available in the relay | |

Analog Inputs (Optional)

| | |
|--------------------------------------|---|
| Maximum Input Range: | ±20 mA ±10 V Operational range set by user |
| Input Impedance: | 200 Ω (current mode) >10 k Ω (voltage mode) |
| Accuracy at 25°C: | |
| With user calibration: | 0.05% of full scale (current mode) 0.025% of full scale (voltage mode) |
| Without user calibration: | Better than 0.5% of full scale at 25°C |
| Accuracy Variation With Temperature: | ±0.015% per °C of full-scale (±20 mA or ±10 V) |

Frequency and Phase Rotation

| | |
|---------------------|--|
| System Frequency: | 50, 60 Hz |
| Phase Rotation: | ABC, ACB |
| Frequency Tracking: | 20–70 Hz (requires ac voltage inputs option) |

Time-Code Input

| | |
|---|-------------------------------|
| Format: | Demodulated IRIG-B |
| On (1) State: | $V_{ih} \geq 2.2$ V |
| Off (0) State: | $V_{il} \leq 0.8$ V |
| Input Impedance: | 2 k Ω |
| Synchronization Accuracy: | |
| Internal Clock: | ±1 μ s |
| Synchrophasor Reports (e.g., MET PM): | ±10 μ s |
| All Other Reports: | ±5 ms |
| Simple Network Time Protocol (SNTP) Accuracy: | |
| Internal Clock: | ±5 ms |
| Unsynchronized Clock Drift: | |
| Relay Powered: | 2 minutes per year, typically |

Communications Ports

| | |
|---|---------------------------|
| Standard EIA-232 (2 ports) | |
| Location: | Front Panel Rear Panel |
| Data Speed: | 300–38400 bps |
| EIA-485 Port (optional) | |
| Location: | Rear Panel |
| Data Speed: | 300–19200 bps |
| Ethernet Port (optional) | |
| Single/Dual 10/100BASE-T copper (RJ-45 connector) | |
| Single/Dual 100BASE-FX (LC connector) | |
| Standard Multimode Fiber-Optic Port | |
| Location: | Front Panel |
| Data Speed: | 300–38400 bps |

Fiber-Optic Ports Characteristics

| | |
|-------------------------------------|------------------|
| Port 1 (or 1A, 1B) Ethernet | |
| Wavelength: | 1300 nm |
| Optical Connector Type: | LC |
| Fiber Type: | Multimode |
| Link Budget: | 16.1 dB |
| Typical TX Power: | –15.7 dBm |
| RX Min. Sensitivity: | –31.8 dBm |
| Fiber Size: | 62.5/125 μ m |
| Approximate Range: | ~6.4 km |
| Data Rate: | 100 Mb |
| Typical Fiber Attenuation: | –2 dB/km |
| Port 2 Serial (SEL-2812 compatible) | |
| Wavelength: | 820 nm |
| Optical Connector Type: | ST |
| Fiber Type: | Multimode |
| Link Budget: | 8 dB |
| Typical TX Power: | –16 dBm |
| RX Min. Sensitivity: | –24 dBm |
| Fiber Size: | 62.5/125 μ m |
| Approximate Range: | ~1 km |
| Data Rate: | 5 Mb |
| Typical Fiber Attenuation: | –4 dB/km |

Optional Communications Cards

| | |
|-----------|--|
| Option 1: | EIA-232 or EIA-485 communications card |
| Option 2: | DeviceNet communications card |

Communications Protocols

SEL, Modbus, DNP, FTP, TCP/IP, Telnet, SNTP, IEC 61850, MIRRORING BITS, EVMSG, C37.118 (synchrophasors), and DeviceNet. See *Table 7.3* for details.

Operating Temperature

IEC Performance Rating: -40° to +85°C (-40° to +185°F)
(per IEC/EN 60068-2-1 & 60068-2-2)

NOTE: Not applicable to UL applications.

NOTE: LCD contrast is impaired for temperatures below -20°C and above +70°C

DeviceNet Communications
Card Rating: +60°C (140°F) maximum

Operating Environment

| | |
|-----------------------|----------------------|
| Pollution Degree: | 2 |
| Overvoltage Category: | II |
| Atmospheric Pressure: | 80–110 kPa |
| Relative Humidity: | 5–95%, noncondensing |
| Maximum Altitude: | 2000 m |

Dimensions

144.0 mm (5.67 in.) x 192.0 mm (7.56 in.) x 147.4 mm (5.80 in.)

Weight

2.0 kg (4.4 lbs)

Relay Mounting Screws (#8–32) Tightening Torque

| | |
|----------|-------------------|
| Minimum: | 1.4 Nm (12 in-lb) |
| Maximum: | 1.7 Nm (15 in-lb) |

Terminal Connections**Terminal Block**

| | |
|----------------------|------------------|
| Screw Size: | #6 |
| Ring Terminal Width: | 0.310 in maximum |

Terminal Block Tightening Torque

| | |
|----------|-------------------|
| Minimum: | 0.9 Nm (8 in-lb) |
| Maximum: | 1.4 Nm (12 in-lb) |

Compression Plug Tightening Torque

| | |
|----------|--------------------|
| Minimum: | 0.5 Nm (4.4 in-lb) |
| Maximum: | 1.0 Nm (8.8 in-lb) |

Compression Plug Mounting Ear Screw Tightening Torque

| | |
|----------|---------------------|
| Minimum: | 0.18 Nm (1.6 in-lb) |
| Maximum: | 0.25 Nm (2.2 in-lb) |

Type Tests**Environmental Tests**

| | |
|-----------------------|---|
| Enclosure Protection: | IEC 60529:2001 + CRDG:2003 IP65 enclosed in panel IP20 for terminals IP54-rated terminal dust protection assembly (SEL Part #915900170). The 10°C temperature derating applies to the temperature specifications of the relay. |
| Vibration Resistance: | IEC 60068-2-6:2007 3 G, 10–150 Hz IEC 60255-21-1:1988, Class 1 IEC 60255-21-3:1993, Class 2 |
| Shock Resistance: | IEC 60255-21-2:1988, Class 1 |
| Cold: | IEC 60068-2-1:2007 -40°C, 16 hours |

| | |
|--------------------------|---|
| Damp Heat, Steady State: | IEC 60068-2-78:2001 40°C, 93% relative humidity, 4 days |
| Damp Heat, Cyclic: | IEC 60068-2-30:2005 25–55°C, 6 cycles, 95% relative humidity |
| Dry Heat: | IEC 60068-2-2:2007 85°C, 16 hours |

Dielectric Strength and Impulse Tests

| | |
|---------------------|--|
| Dielectric (HiPot): | IEC 60255-5:2000 IEEE C37.90-2005 2.5 kVac on current inputs, ac voltage inputs, contact I/O 2.0 kVac on analog inputs 1.0 kVac on analog outputs 2.83 kVdc on power supply |
| Impulse: | IEC 60255-5:2000 IEEE C37.90-2005 0.5 J, 4.7 kV on power supply, contact I/O, ac current and voltage inputs 0.5 J, 530 V on analog outputs |

RFI and Interference Tests**EMC Immunity**

| | |
|--------------------------------------|---|
| Electrostatic Discharge Immunity: | IEC 61000-4-2:2008 IEC 60255-22-2:2008 Severity Level 4 8 kV contact discharge 15 kV air discharge |
| Radiated RF Immunity: | IEC 61000-4-3:2010 IEC 60255-22-3:2007 10 V/m IEEE C37.90.2-2004 35 V/m |
| Digital Radio Telephone RF Immunity: | ENV 50204:1995 |
| Fast Transient, Burst Immunity: | IEC 61000-4-4:2004 IEC 60255-22-4:2008 4 kV @ 5.0 kHz 2 kV @ 5.0 kHz for comm. ports |
| Surge Immunity: | IEC 61000-4-5:2005 IEC 60255-22-5:2008 2 kV line-to-line 4 kV line-to-earth |
| Surge Withstand Capability Immunity: | IEC 60255-22-1:2007 2.5 kV common mode 1.0 kV differential mode 1 kV common mode on comm. ports IEEE C37.90.1-2002 2.5 kV oscillatory 4 kV fast transient |
| Conducted RF Immunity: | IEC 61000-4-6:2008 IEC 60255-22-6:2001 10 Vrms |
| Magnetic Field Immunity: | IEC 61000-4-8:2009 1000 A/m for 3 seconds 100 A/m for 1 minute IEC 61000-4-9:2001 1000 A/m |
| Power Supply Immunity: | IEC 60255-11:2008 |
| EMC Emissions | |
| Conducted Emissions: | EN 55011:1998, Class A IEC 60255-25:2000 |
| Radiated Emissions: | EN 55011:1998, Class A IEC 60255-25:2000 |
| Electromagnetic Compatibility | |
| Product Specific: | EN 50263:1999 |

Certifications

| | |
|-----------|---|
| ISO 9001: | This product was designed and manufactured under an ISO 9001 certified quality management system. |
| UL, cUL: | Protective Relay Category NRGU, NRGU7 per UL 508, C22.2 No. 14 |
| CSA: | C22.2 No. 61010-1 |
| CE: | CE Mark–EMC Directive Low Voltage Directive IEC 61010-1:2001 IEC 60947-1 IEC 60947-4-1 IEC 60947-5-1 |

Processing Specifications and Oscillography

| | |
|------------------------------------|--|
| AC Voltage and Current Inputs: | 16 samples per power system cycle |
| Frequency Tracking Range: | 20–70 Hz (requires ac voltage inputs option) |
| Digital Filtering: | One-cycle cosine after low-pass analog filtering. Net filtering (analog plus digital) rejects dc and all harmonics greater than the fundamental. |
| Protection and Control Processing: | Processing interval is 4 times per power system cycle (except for math variables and analog quantities, which are processed every 100 ms). The 51 elements are processed 2 times per power system cycle. |

Oscillography

| | |
|------------------------|---|
| Length: | 15 or 64 cycles |
| Sampling Rate: | 16 samples per cycle unfiltered 4 samples per cycle filtered |
| Trigger: | Programmable with Boolean expression |
| Format: | ASCII and Compressed ASCII |
| Time-Stamp Resolution: | 1 ms |
| Time-Stamp Accuracy: | ±5 ms |

Sequential Events Recorder

| | |
|--|--------|
| Time-Stamp Resolution: | 1 ms |
| Time-Stamp Accuracy (with respect to time source): | ± 5 ms |

Relay Elements

Instantaneous/Definite-Time Overcurrent (50P, 50G, 50N, 50Q)

| | |
|------------------------------------|--|
| Pickup Setting Range, A secondary: | |
| 5 A models: | 0.50–96.00 A, 0.01 A steps |
| 1 A models: | 0.10–19.20 A, 0.01 A steps |
| Accuracy: | ±5% of setting plus ±0.02 • I _{NOM} A secondary (Steady State pickup) |
| Time Delay: | 0.00–5.00 seconds, 0.01 seconds steps, ±0.5% plus ±0.25 cyc |
| Pickup/Dropout Time: | <1.5 cyc |

Inverse Time Overcurrent (51P, 51G, 51N, 51Q)

| | |
|------------------------------------|--|
| Pickup Setting Range, A secondary: | |
| 5 A models: | 0.50–16.00 A, 0.01 A steps |
| 1 A models: | 0.10–3.20 A, 0.01 A steps |
| Accuracy: | ±5% of setting plus ±0.02 • I _{NOM} A secondary (Steady State pickup) |
| Time Dial: | |
| US: | 0.50–15.00, 0.01 steps |
| IEC: | 0.05–1.00, 0.01 steps |

| | |
|-----------|---|
| Accuracy: | ±1.5 cycles plus ±4% between 2 and 30 multiples of pickup (within rated range of current) |
|-----------|---|

Differential (87)

| | |
|--|-------------------------------------|
| Unrestrained Pickup Range: | 1.0–20.0 in per unit of TAP |
| Restrained Pickup Range: | 0.10–1.00 in per unit of TAP |
| Pickup Accuracy (A secondary): | |
| 5 A Model: | ±5% plus ±0.10 A |
| 1 A Model: | ±5% plus ±0.02 A |
| Unrestrained Element | |
| Pickup Time: | 0.8/1.0/1.9 cycles (Min/Typ/Max) |
| Restrained Element (with harmonic blocking) | |
| Pickup Time: | 1.5/1.6/2.2 cycles (Min/Typ/Max) |
| Restrained Element (with harmonic restraint) | |
| Pickup Time: | 2.62/2.72/2.86 cycles (Min/Typ/Max) |

Harmonics

| | |
|----------------------------------|------------------------|
| Pickup Range (% of fundamental): | 5–100% |
| Pickup Accuracy (A secondary): | |
| 5 A Model: | ±5% plus ±0.10 A |
| 1 A Model: | ±5% plus ±0.02 A |
| Time Delay Accuracy: | ±0.5% plus ±0.25 cycle |

Restricted Earth Fault (REF)

| | |
|--|---|
| 5 A Model: | 0.25–15.00 A, 0.01 A steps |
| 1 A Model: | 0.05–3.00 A, 0.01 A steps |
| Pickup Accuracy (A secondary): | |
| 5 A Model: | ±5% plus ±0.10 A |
| 1 A Model: | ±5% plus ±0.02 A |
| ANSI Extremely Inverse TOC Curve (U4 with 0.5 Time Dial) | |
| Accuracy: | ±5 cycles plus ±5% between 2 and 30 multiples of pickup (within rated range of current) |

Undervoltage (27)

| | |
|----------------------|-------------------------------------|
| Setting Range: | Off, 12.5–300.0 V |
| Accuracy: | ±1% of setting plus ±0.5 V |
| Pickup/Dropout Time: | <1.5 cycle |
| Time Delay: | 0.0–120.0 seconds, 0.1 second steps |
| Accuracy: | ±0.5% plus ±0.25 cycle |

Overvoltage (59)

| | |
|----------------------|-------------------------------------|
| Setting Range: | Off, 12.5–300.0 V |
| Accuracy: | ±1% of setting plus ±0.5 V |
| Pickup/Dropout Time: | <1.5 cycle |
| Time Delay: | 0.0–120.0 seconds, 0.1 second steps |
| Accuracy: | ±0.5% plus ±0.25 cycle |

Negative-Sequence Overvoltage (59Q)

| | |
|----------------------|-------------------------------------|
| Setting Range: | 12.5–200.0 V |
| Accuracy: | ±5% of setting plus ±2 V |
| Pickup/Dropout Time: | <1.5 cycle |
| Time Delay: | 0.0–120.0 seconds, 0.1 second steps |
| Accuracy: | ±0.5% plus ±0.25 cycle |

Volts/Hertz (24)

| | |
|-------------------------------|----------------------------|
| Definite-Time Element | |
| Pickup Range: | 100–200% |
| Steady-State Pickup Accuracy: | ±1% of setpoint |
| Pickup Time: | 25 ms @ 60 Hz (Max) |
| Time-Delay Range: | 0.00–400.00 s |
| Time-Delay Accuracy: | ±0.1% plus ±4.2 ms @ 60 Hz |

| | |
|--|--|
| Reset Time Range: | 0.00–400.00 s |
| Inverse-Time Element | |
| Pickup Range: | 100–200% |
| Steady-State Pickup Accuracy: | ±1% of setpoint |
| Pickup Time: | 25 ms @ 60 Hz (Max) |
| Curve: | 0.5, 1.0, or 2.0 |
| Factor: | 0.1–10.0 s |
| Timing Accuracy: | ±4% plus ±25 ms @ 60 Hz, for V/Hz above 1.05 multiples (Curve 0.5 and 1.0) or 1.10 multiples (Curve 2.0) of pickup setting, and for operating times >4 s |
| Reset Time Range: | 0.00–400.00 s |
| Composite-Time Element | |
| Combination of Definite-Time and Inverse-Time specifications | |
| User-Definable Curve Element | |
| Pickup Range: | 100–200% |
| Steady-State Pickup Accuracy: | ±1% of setpoint |
| Pickup Time: | 25 ms @ 60 Hz (Max) |
| Reset Time Range: | 0.00–400.00 s |

Directional Power (32)

Instantaneous/Definite Time, 3 Phase Elements

Type: +W, –W, +VAR, –VAR

Pickup Settings Range, VA secondary:

5 A Model: 1.0–6500.0 VA, 0.1 VA steps

1 A Model: 0.2–1300.0 VA, 0.1 VA steps

Accuracy: ±0.10 A • (L-L voltage secondary) and ±5% of setting at unity power factor for power elements and zero power factor for reactive power element (5 A nominal)
 ±0.02 A • (L-L voltage secondary) and ±5% of setting at unity power factor for power elements and zero power factor for reactive power element (1 A nominal)

Pickup/Dropout Time: <10 cycles

Time Delay: 0.0–240.0 seconds, 0.1 second steps

Accuracy: ±0.5% plus ±0.25 cycle

Frequency (81) (requires ac voltage option)

Setting Range: Off, 20.0–70.0 Hz

Accuracy: ±0.01 Hz (V1 > 60 V) with voltage tracking

Pickup/Dropout Time: <4 cycles

Time Delay: 0.0–240.0 seconds, 0.1 second steps

Accuracy: ±0.5% plus ±0.25 cycle

RTD Protection

Setting Range: Off, 1–250°C

Accuracy: ±2°C

RTD Open-Circuit Detection: >250°C

RTD Short-Circuit Detection: <–50°C

RTD Types: PT100, NI100, NI120, CU10

RTD Lead Resistance: 25 ohm max. per lead

Update Rate: <3 s

Noise Immunity on RTD Inputs: To 1.4 Vac (peak) at 50 Hz or greater frequency

RTD Trip/Alarm Time Delay: Approx. 6 s

Metering Accuracy

Accuracies are specified at 20°C, nominal frequency, ac currents within (0.2–20.0) • I_{NOM} A secondary, and ac voltages within 50–250 V secondary unless otherwise noted.

| | |
|--|---|
| Phase Currents: | ±1% of reading, ±1° (±2.5° at 0.2–0.5 A for relays with Inom = 1 A) |
| 3-Phase Average Current: | ±2% of reading |
| Differential Quantities: | ±5% of reading plus ±0.1 A (5 A nominal), ±0.02 A (1 A nominal) |
| Current Harmonics: | ±5% of reading plus ±0.1 A (5 A nominal), ±0.02 A (1 A nominal) |
| IG (Residual Current): | ±3% of reading, ±2° (±5.0° at 0.2–0.5 A for relays with Inom = 1 A) |
| IN (Neutral Current): | ±1% of reading, ±1° (±2.5° at 0.2–0.5 A for relays with Inom = 1 A) |
| 3I2 Negative-Sequence Current: | ±3% of reading |
| System Frequency: | ±0.01 Hz of reading for frequencies within 20.00–70.00 Hz (V1 > 60 V) with voltage tracking |
| Line-to-Line Voltages: | ±1% of reading, ±1° for voltages within 24–264 V |
| 3-Phase Average Line-to-Line Voltage: | ±1% of reading for voltages within 24–264 V |
| Line-to-Ground Voltages: | ±1% of reading, ±1° for voltages within 24–264 V |
| 3-Phase Average Line-to-Ground Voltages: | ±1% of reading for voltages within 24–264 V |
| Voltage Harmonics: | ±5% of reading plus ±0.5 V |
| 3V2 Negative-Sequence Voltage: | ±3% of reading for voltages within 24–264 V |
| Real 3-Phase Power (kW): | ±3% of reading for 0.10 < pf < 1.00 |
| Reactive 3-Phase Power (kVAR): | ±3% of reading for 0.00 < pf < 0.90 |
| Apparent 3-Phase Power (kVA): | ±3% of reading |
| Power Factor: | ±2% of reading for 0.86 ≤ pf ≤ 1 |
| RTD Temperatures: | ±2°C |

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Section 2

Installation

Overview

The first steps in applying the SEL-787 Transformer Protection Relay are installing and connecting the relay. This section describes common installation features and requirements.

To install and connect the relay safely and effectively, you must be familiar with relay configuration features and options. You should carefully plan relay placement, cable connections, and relay communication.

This section contains drawings of typical ac and dc connections to the SEL-787. Use these drawings as a starting point for planning your particular relay application.

The instructions for using the versatile front-panel custom label option are available on the SEL-787 product page on the SEL website. This allows you to use SELOGIC® control equations and slide-in configurable front-panel labels to change the function and identification of target LEDs.

Relay Placement

Proper placement of the SEL-787 helps to ensure years of trouble-free protection. Use the following guidelines for proper physical installation of the SEL-787.

Physical Location

You can mount the SEL-787 in a sheltered indoor environment (a building or an enclosed cabinet) that does not exceed the temperature and humidity ratings for the relay. The relay is IEC EN61010-1 rated at Installation/Overvoltage Category II and Pollution Degree 2. This rating allows mounting of the relay indoors or in an outdoor (extended) enclosure where the relay is protected against exposure to direct sunlight, precipitation, and full wind pressure, but neither temperature nor humidity is controlled.

You can place the relay in extreme temperature and humidity locations. (See *Operating Temperature* and *Operating Environment on page 1.11.*) For EN 61010 certification, the SEL-787 rating is 2000 m (6560 feet) above mean sea level.

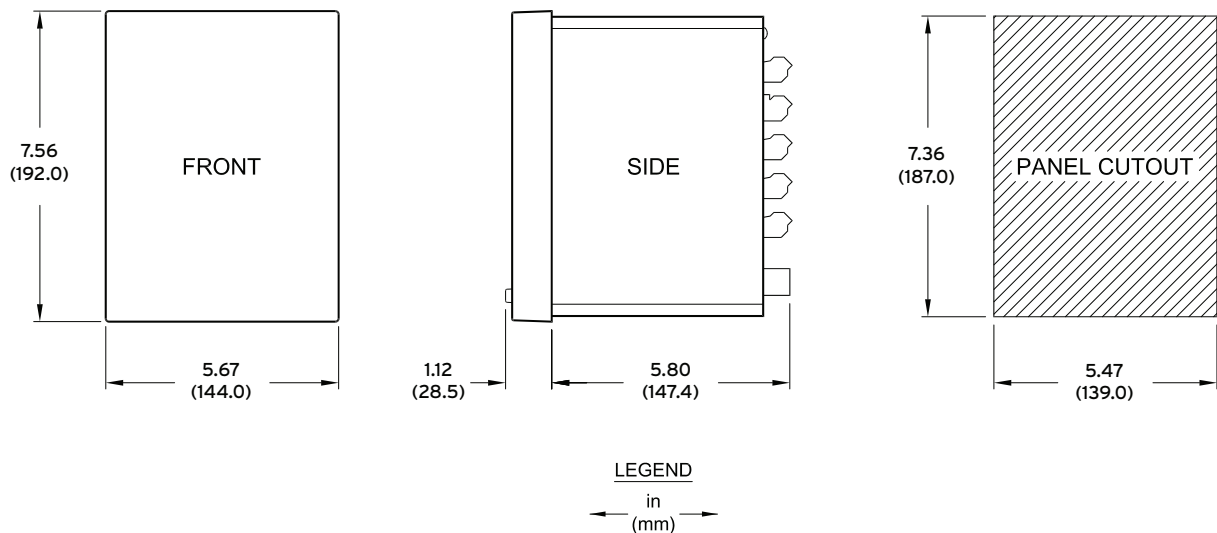
To comply with the requirements of the European ATEX standard for hazardous locations, the SEL-787 must be installed in an enclosure that meets the requirements of an Ex n enclosure rated IP54 or better. The enclosure should be certified to these requirements or be tested for compliance as part of the complete assembly. In North America, the relay is approved for Class 1, Division 2, Groups A, B, C, D, and T4 hazardous locations.

Relay Mounting

To flush mount the SEL-787 in a panel, cut a rectangular hole with the dimensions shown in *Figure 2.1*. Use the supplied front-panel gasket for protection against dust and water ingress into the panel (IP65).

For extremely dusty environments, use the optional IP54-rated terminal dust-protection assembly (SEL Part #915900170). The 10°C temperature derating applies to the temperature specifications of the relay.

CHASSIS



i9089b

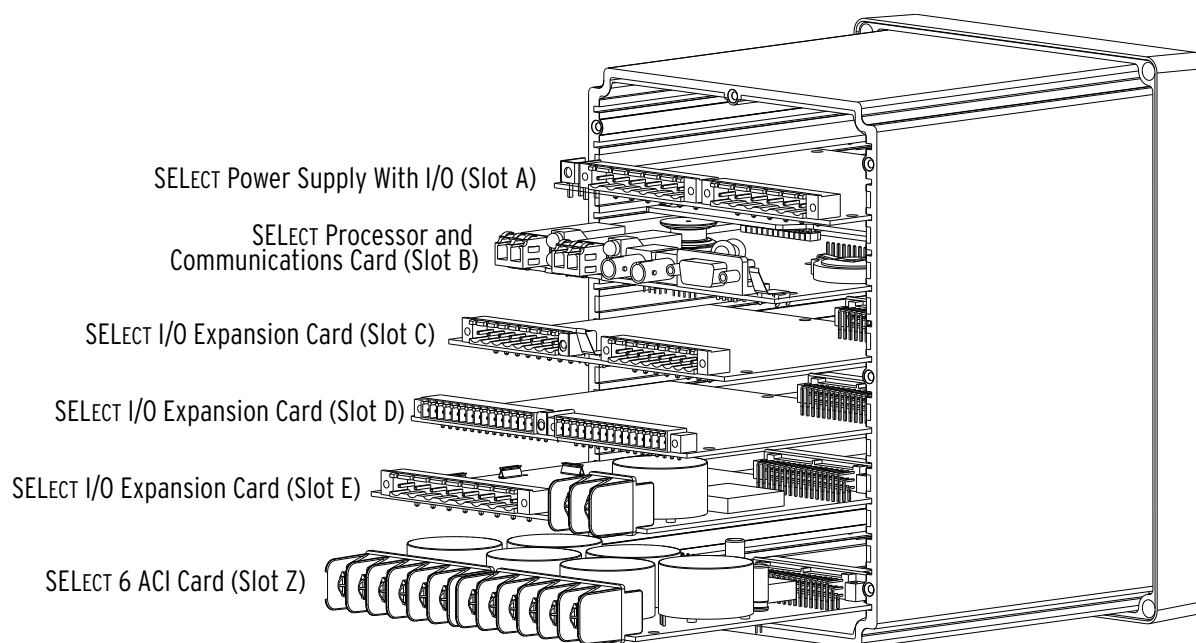
Figure 2.1 Relay Panel-Mount Dimensions

Refer to *Section 1: Introduction and Specifications, Models, Options, and Accessories* for information on mounting accessories.

I/O Configuration

Your SEL-787 offers flexibility in tailoring I/O to your specific application. In total, the SEL-787 has six rear-panel slots, labeled as Slots **A**, **B**, **C**, **D**, **E**, and **Z**. Slots **A**, **B**, and **Z** are base unit slots, each associated with a specific function. Optional digital and analog I/O, communications, RTD, and voltage cards are available for the SEL-787. *Figure 2.2* shows the slot allocations for the cards.

Because installations differ substantially, the SEL-787 offers a variety of card configurations to provide options for the many diverse applications. Choose the combination of cards most suited for your application from the following selection.



| | Rear-Panel Slot | | | | | |
|--|--|-----------------------------|---|---------------------------------------|---|----------------------|
| | A | B | C | D | E | Z |
| Software Reference | 1 (e.g., OUT101) | n/a | 3 (e.g., IN301) | 4 (e.g., OUT401) | 5 (e.g., AI501) | n/a |
| Description | Power supply and I/O card ^a | CPU/comm. card ^b | Comm. or input/output ^c card | Input/output ^c or RTD card | Input/output ^c or voltage/current card | CT card in base unit |
| Card Type | | | | | | |
| SELECT EIA-232/485 | | | 1 | n/a | n/a | |
| SELECT DeviceNet | | | 1 | n/a | n/a | |
| SELECT 3 DI/4 DO/1 AO (one card per relay) | | | 1 | 1 | 1 | |
| SELECT 4 DI/4 DO | | | 1 | 1 | 1 | |
| SELECT 4 DI/3 DO (2 Form C, 1 Form B) ^d | | | 1 | 1 | 1 | |
| SELECT 8 DI | | | 1 | 1 | 1 | |
| SELECT 4 AI/4 AO (one card per relay) | | | 1 | 1 | 1 | |
| SELECT 10 RTD | | | n/a | 1 | n/a | |
| SELECT 1 ACI/3 AVI | | | n/a | n/a | 1 | |
| SELECT 1 ACI | | | n/a | n/a | 1 | |

^a Power supply, two inputs, and three outputs.

^b IRIG-B, EIA-232/485, fiber-optic serial and/or Ethernet ports.

The IRIG-B input option is available on terminals B01, B02 for all models except models with fiber-optic Ethernet port (P1) and dual copper Ethernet port (P1). IRIG-B is also supported via fiber-optic serial port (PORT 2) and rear-panel EIA-232 serial port (PORT 3). You can use only one input at a time.

^c Digital or analog.

^d Available in firmware releases R104 or greater and R203 and greater.

Figure 2.2 Slot Allocations for Different Cards

Power Supply Card PSIO/2DI/3DO (Slot A)

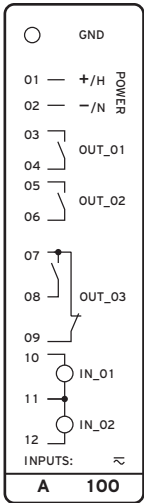

Select appropriate power supply option for the application:

- High Voltage: 110-250 Vdc, 110-240 Vac, 50/60 Hz
- Low Voltage: 24-48 Vdc

Select the appropriate digital input voltage option: 125 Vdc/Vac, 24 Vdc/Vac, 48 Vdc/Vac, 110 Vdc/Vac, 220 Vdc/Vac, or 250 Vdc/Vac.

This card is supported in Slot A (Slot 1) of the SEL-787 relay. It has two digital inputs and three digital outputs (two normally open Form-A contact outputs and one Form-C output). *Table 2.1* shows the terminal designation for the PSIO/2DI/3DO card.

Table 2.1 Power Supply Card Inputs Terminal Designation

| Side-Panel Connections Label | Terminal Number | Description |
|--|--|--|
|  |  A01, A02 A03, A04 A05, A06 A07, A08, A09 A10, A11 A12, A11 | Ground connection Power supply input terminals OUT101, driven by OUT101 SELOGIC control equation OUT102, driven by OUT102 SELOGIC control equation OUT103, driven by OUT103 SELOGIC control equation IN101, drives IN101 element IN102, drives IN102 element |

Base-Unit Communications Ports (Slot B)

Select the communications ports necessary for your application from the base-unit options shown in *Table 2.2*.

Table 2.2 Communication Ports

| Port | Location | Feature | Description |
|------|-------------|----------|--|
| F | Front Panel | Standard | Nonisolated EIA-232 serial port |
| 1 | Rear Panel | Optional | (Single/Dual) Isolated 10/100BASE-T Ethernet copper port or 100BASE-FX Ethernet port |
| 2 | Rear Panel | Standard | Isolated multimode fiber-optic serial port with ST® connectors |
| 3 | Rear Panel | Standard | Nonisolated EIA-232 or isolated EIA-485 serial port |

Port F supports the following protocols:

- SELBOOT
- Modbus® RTU Slave
- SEL ASCII and Compressed ASCII
- SEL Settings File Transfer

- Event Messenger
- C37.118 (Synchrophasor Data)

Port 1 (Ethernet) supports the following protocols:

- Modbus TCP/IP
- DNP3 LAN/WAN
- IEC 61850
- Simple Network Time Protocol (SNTP)
- FTP
- Telnet

Port 2 and **Port 3** support the following protocols:

- Modbus RTU Slave
- SEL ASCII and Compressed ASCII
- SEL Fast Meter
- SEL Fast Operate
- SEL Fast SER
- SEL Fast Message Unsolicited Write
- SEL Settings File Transfer
- SEL MIRRORING BITS® (MBA, MBB, MB8A, MB8B, MBTA, MBTB)
- Event Messenger
- DNP3 Slave Level 2
- C37.118 (Synchrophasor Data)

Communications Card

Either the DeviceNet (see *Appendix G: DeviceNet Communications*) or the EIA-232/EIA-485 communications card is supported in Slot **C**. The EIA-232/EIA-485 card provides one serial port with one of the following two serial port interfaces:

- **Port 4A**, an isolated EIA-485 serial port interface
- **Port 4C**, nonisolated EIA-232 serial port interface, supporting the +5 Vdc interface

Select either EIA-232 or EIA-485 functionality using the **Port 4** Setting COMM Interface. *Table 2.3* shows the port number, interface, and type of connector for the two protocols.

Table 2.3 Communication Card Interfaces and Connectors

| Port | Interface | Connectors |
|------|-----------|------------|
| 4A | EIA-485 | 5-pin Euro |
| 4C | EIA-232 | D-sub |

The communications card supports all of the following protocols:

- Modbus RTU Slave
- SEL ASCII and Compressed ASCII
- SEL Fast Meter
- SEL Fast Operate
- SEL Fast SER

- SEL Fast Message Unsolicited Write
- SEL Settings File Transfer
- SEL MIRRORED BITS (MBA, MBB, MB8A, MB8B, MBTB, MBTA)
- Event Messenger
- DNP3 Slave Level 2
- C37.118 (Synchrophasor Data)

Current Card (6 ACI)

Supported in Slot Z only, this card provides Winding 1 and Winding 2 current inputs for three-phase CTs. With this card installed, the SEL-787 samples the currents 16 times per cycle. You can order the following secondary current ratings:

- 1 A Winding 1, 1 A Winding 2
- 1 A Winding 1, 5 A Winding 2
- 5 A Winding 1, 5 A Winding 2

Table 2.4 6 ACI Current Card Inputs Terminal Designation

| Side-Panel Connections Label | Terminal Number | Description |
|--|-----------------|---------------------------------------|
| <div><div>Z01 •</div><div>Z02</div><div>IAW1</div></div> | Z01, Z02 | IAW1, Phase A Winding 1 current input |
| <div><div>Z03 •</div><div>Z04</div><div>IBW1</div></div> | Z03, Z04 | IBW1, Phase B Winding 1 current input |
| <div><div>Z05 •</div><div>Z06</div><div>ICW1</div></div> | Z05, Z06 | ICW1, Phase C Winding 1 current input |
| <div><div>Z07 •</div><div>Z08</div><div>IAW2</div></div> | Z07, Z08 | IAW2, Phase A Winding 2 current input |
| <div><div>Z09 •</div><div>Z10</div><div>IBW2</div></div> | Z09, Z10 | IBW2, Phase B Winding 2 current input |
| <div><div>Z11 •</div><div>Z12</div><div>ICW2</div></div> | Z11, Z12 | ICW2, Phase C Winding 2 current input |

Current/Voltage Card
(1 ACI/3 AVI or 1 ACI)

Supported in Slot E only, order this card option when you have either single- or three-phase (wye or delta) PTs and/or neutral ac current input (1 A or 5 A nominal). With this card installed, the SEL-787 samples the voltages and/or current 16 times a cycle—see *Processing Specifications and Oscillography on page 1.12* for more information. The pin connections remain the same for the 1 ACI card, which only supports the neutral current input.

Table 2.5 1 ACI/3 AVI or 1 ACI Current/Voltage Card Inputs Terminal Designation

| Side-Panel Connections Label | Terminal Number | Description |
|--|-----------------|------------------------------|
| <div> <div> <div>AVI</div> <div> <div>E 01 — VA</div> <div>E 02 — VB</div> <div>E 03 — VC</div> <div>E 04 — N</div> <div>WYE</div> <div>E 05 — N/C</div> <div>E 06 — N/C</div> <div>E 07 — N/C</div> <div>E 08 — N/C</div> </div> <div> <div>VA</div> <div>VB (COM)</div> <div>VC</div> <div>COM</div> <div>OPEN DELTA</div> </div> </div> <div> <div>ACI</div> <div> <div>E 09 •</div> <div>E 10</div> </div> <div>IN</div> </div> </div> | | |
| | E01 | VA, Phase A voltage input |
| | E02 | VB, Phase B voltage input |
| | E03 | VC, Phase C voltage input |
| | E04 | N, Return for VA, VB, VC |
| | E09, E10 | IN1, Neutral current input 1 |

Analog Input/Output Card (4 AI/4 AO)

NOTE: Analog inputs cannot provide loop power. Each analog output is self-powered and has an isolated power supply.

Supported in any one of the nonbase unit slots (Slot C, D, or E), this card has four analog inputs (AI) and four analog outputs (AO). *Table 2.6* shows the terminal allocation.

Table 2.6 Four Analog Input/Four Analog Output (4 AI/4 AO) Card Terminal Allocation

| Side-Panel Connections Label | Terminal Number | Description ^a |
|--|-----------------|------------------------------------|
| <div> <div> <div>01</div> <div>02</div> <div>03</div> <div>04</div> <div>05</div> <div>06</div> <div>07</div> <div>08</div> <div>09</div> <div>10</div> <div>11</div> <div>12</div> <div>13</div> <div>14</div> <div>15</div> <div>16</div> </div> <div> <div>AO_01</div> <div>AO_02</div> <div>AO_03</div> <div>AO_04</div> <div>AI_01</div> <div>AI_02</div> <div>AI_03</div> <div>AI_04</div> </div> </div> | | |
| | 01, 02 | AOx01, Analog Output number x01 |
| | 03, 04 | AOx02, Analog Output number x02 |
| | 05, 06 | AOx03, Analog Output number x03 |
| | 07, 08 | AOx04, Analog Output number x04 |
| | 09, 10 | AIx01, Transducer Input number x01 |
| | 11, 12 | AIx02, Transducer Input number x02 |
| | 13, 14 | AIx03, Transducer Input number x03 |
| | 15, 16 | AIx04, Transducer Input number x04 |

^a x=3, 4, or 5 (for example, AI401, AI402, etc., if the card was installed in Slot D).

I/O Input Card (3 DI/4 DO/1 AO)

NOTE: All digital input and digital output (including high-current, high-speed hybrid) connections are polarity neutral.

NOTE: Analog output is self powered and has an isolated power supply.

Supported in one nonbase unit slot (Slot C, D, or E), this card has three digital inputs, four digital outputs, and one analog output. *Table 2.7* shows the terminal allocation.

Table 2.7 I/O (3 DI/4 DO/1 AO) Card Terminal Allocation

| Side-Panel Connections Label | Terminal Number | Description ^a |
|------------------------------|-----------------|---|
| 01 OUT_01 | 01, 02 | OUTx01, driven by OUTx01 SELOGIC control equation |
| 02 OUT_02 | 03, 04 | OUTx02, driven by OUTx02 SELOGIC control equation |
| 03 OUT_03 | 05, 06 | OUTx03, driven by OUTx03 SELOGIC control equation |
| 04 OUT_04 | 07, 08 | OUTx04, driven by OUTx04 SELOGIC control equation |
| 05 AO_01 | 09, 10 | AOx01, Analog Output Number 1 |
| 06 IN_01 | 11, 12 | INx01, Drives INx01 element |
| 07 IN_02 | 13, 14 | INx02, Drives INx02 element |
| 08 IN_03 | 15, 16 | INx03, Drives INx03 element |

^a x=3, 4, or 5 (for example, OUT401, OUT402, etc., if the card was installed in Slot D).

RTD Card (10 RTD)

NOTE: All Comp/Shield terminals are internally connected to relay chassis and ground.

Supported in Slot D only, this card has 10 RTD inputs. *Table 2.8* shows the terminal allocation.

Table 2.8 RTD (10 RTD) Card Terminal Allocation

| Side-Panel Connections Label | Terminal Number | Description |
|------------------------------|-----------------|-------------------|
| 01 RTD1 | 01 | RTD01 (+) |
| 02 COMP/SHLD | 02 | RTD01 (-) |
| 03 RTD2 | 03 | RTD01 Comp/Shield |
| 04 COMP/SHLD | 04 | RTD02 (+) |
| 05 RTD3 | 05 | RTD02 (-) |
| 06 COMP/SHLD | 06 | RTD02 Comp/Shield |
| 07 RTD4 | 07 | RTD03 (+) |
| 08 COMP/SHLD | 08 | RTD03 (-) |
| 09 RTD5 | 09 | RTD03 Comp/Shield |
| 10 COMP/SHLD | • | • |
| 11 RTD6 | • | • |
| 12 COMP/SHLD | • | • |
| 13 RTD7 | • | • |
| 14 COMP/SHLD | • | • |
| 15 RTD8 | • | • |
| 16 COMP/SHLD | • | • |
| 17 RTD9 | • | • |
| 18 COMP/SHLD | • | • |
| 19 RTD10 | • | • |
| 20 COMP/SHLD | • | • |
| 21 RTD1 | • | • |
| 22 COMP/SHLD | • | • |
| 23 RTD2 | • | • |
| 24 COMP/SHLD | • | • |
| 25 RTD3 | • | • |
| 26 COMP/SHLD | • | • |
| 27 RTD4 | • | • |
| 28 COMP/SHLD | • | • |
| 29 RTD5 | • | • |
| 30 COMP/SHLD | • | • |

I/O Card (4 DI/4 DO)

NOTE: All digital inputs and digital outputs (including high-current, high-speed hybrid) connections are polarity neutral.

Supported in any nonbase unit slot (Slot **C**, **D**, or **E**), this card has four digital inputs and four outputs. The four outputs are either all normally open contact outputs or all fast hybrid (high-speed, high-current interrupting) outputs. *Table 2.9* shows the terminal allocation.

Table 2.9 Four Digital Input/Four Digital Output (4 DI/4 DO) Card Terminal Allocation

| Side-Panel Connections Label | Terminal Number | Description ^a |
|------------------------------|-----------------|---|
| | 01, 02 | OUTx01, driven by OUTx01 SELOGIC control equation |
| | 03, 04 | OUTx02, driven by OUTx02 SELOGIC control equation |
| | 05, 06 | OUTx03, driven by OUTx03 SELOGIC control equation |
| | 07, 08 | OUTx04, driven by OUTx04 SELOGIC control equation |
| | 09, 10 | INx01, drives INx01 element |
| | 11, 12 | INx02, drives INx02 element |
| | 13, 14 | INx03, drives INx03 element |
| | 15, 16 | INx04, drives INx04 element |

^a x=3, 4, or 5 (for example, OUT401, OUT402, etc., if the card was installed in Slot D).

I/O Card (8 DI)

Supported in any nonbase unit slot (Slot **C**, **D**, or **E**), this card has eight digital inputs. *Table 2.10* shows the terminal allocation.

Table 2.10 Eight Digital Input (8 DI) Card Terminal Allocation

| Side-Panel Connections Label | Terminal Number | Description ^a |
|------------------------------|-----------------|-----------------------------|
| | 01, 02 | INx01, drives INx01 element |
| | 03, 04 | INx02, drives INx02 element |
| | 05, 06 | INx03, drives INx03 element |
| | 07, 08 | INx04, drives INx04 element |
| | 09, 10 | INx05, drives INx05 element |
| | 11, 12 | INx06, drives INx06 element |
| | 13, 14 | INx07, drives INx07 element |
| | 15, 16 | INx08, drives INx08 element |

^a x=3, 4, or 5 (e.g., OUT401, OUT402, etc. if the card was installed in Slot D).

I/O Card (4 DI/3 DO)

Supported in any nonbase unit slot (Slot C through Slot E), this card has four digital inputs, one Form-B digital output (normally closed contact output) and two form-C digital output contacts. *Table 2.11* shows the terminal allocation.

Table 2.11 Four Digital Inputs, One Form-B Digital Output, Two Form-C Digital Outputs (4 DI/3DO) Card Terminal Allocation

| Side-Panel Connections Label | Terminal Number | Description ^a |
|------------------------------|-----------------|---|
| | 01, 02 | OUTx01, driven by OUTx01 SELOGIC control equation |
| | 03, 04, 05 | OUTx02, driven by OUTx02 SELOGIC control equation |
| | 06, 07, 08 | OUTx03, driven by OUTx03 SELOGIC control equation |
| | 09, 10 | INx01, drives INx01 element |
| | 11, 12 | INx02, drives INx02 element |
| | 13, 14 | INx03, drives INx03 element |
| | 15, 16 | INx04, drives INx04 element |
| | | |
| | | |
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| | | |
| | | |
| | | |
| | | |

^a x=3, 4, or 5 (e.g., OUT401, OUT402, etc. if the card was installed in Slot D).

Card Configuration Procedure

Changing card positions or expanding on the initial number of cards requires no card programming; the relay detects the new hardware and updates the software accordingly (you still have to use the **SET** command to program the I/O settings).

The SEL-787 offers flexibility in tailoring I/O to your specific application. The SEL-787 has six rear-panel slots, labeled as Slots A, B, C, D, E, and Z. Slots A, B, and Z are base unit slots, each associated with a specific function. Optional digital/analog I/O cards are available for the SEL-787 in Slots C, D, and E. Optional communications cards are available only for Slot C, an RTD card is available only for Slot D, and 1 A/5 A CT combinations for voltage/current cards are available only on Slots E and Z. *Figure 2.2* shows the slot allocations for the cards. Because installations differ substantially, the SEL-787 offers a variety of card configurations that provide options for many diverse applications. Choose the combination of cards most suited for your application.

Swapping Optional I/O Boards

When an I/O board is moved from one slot to a different slot, the associated settings for the slot the card is moved from will be lost. For example, if a 4 DI/4 DO card is installed in Slot 4 (Slot D), the SELOGIC settings OUT401–OUT404 would be available. If OUT401 = IN101 and 51P1T and the card is moved to a different slot, then the OUT4xx settings will be lost. This is true for all the digital and analog I/O cards.

Card Installation for Slots C, D, E, and Z

Perform the following steps to install cards in Slots C, D, E, or Z of the base unit.

DANGER

Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death.

- Step 1. Remove the power supply voltage from terminals A01+ and A02– and remove the ground wire from the green ground screw.
- Step 2. Disconnect all the connection plugs.
- Step 3. Loosen the eight (8) screws on the rear and remove the rear cover.
- Step 4. Remove the plastic filler plate covering the slot associated with the card being installed.
- Step 5. Insert the card in the correct slot.

Make sure the contact fingers on the printed circuit board are bent at an approximately 130° angle relative to the board for proper electromagnetic interference protection.
- Step 6. Before reattaching the rear cover, check for and remove any foreign material that may remain inside the SEL-787 case.
- Step 7. Carefully reattach the rear cover.
- Step 8. Tighten the eight (8) screws that secure the rear cover to the case.
- Step 9. Apply power supply voltage to terminals A01+ and A02– and reconnect the ground wire to the green ground screw.
- Step 10. If the card is in the proper slot, the front panel displays the following:


```
STATUS FAIL
X Card Failure
```

If you *do not* see this message and the **ENABLED** light is turned on, the card was inserted into the wrong slot. Begin again at *Step 1*.

If you *do* see this message, proceed to *Step 11*.
- Step 11. Press the **ESC** pushbutton.
- Step 12. Press the **Down Arrow** pushbutton until STATUS is highlighted.
- Step 13. Press the **ENT** pushbutton.

The front panel displays the following:

```
STATUS
Relay Status
```

- Step 14. Press the **ENT** button.

The front panel displays the following:

```
Serial Num
00000000000000000000000000000000
```

- Step 15. Press the **ENT** pushbutton.

The front panel displays the following:

```
Confirm Hardware
Config (Enter)
```

Step 16. Press the **ENT** pushbutton.

The front panel displays the following:

```
Accept New Config?
No Yes
```

Step 17. Select **Yes** and press the **ENT** pushbutton.

The front panel displays the following:

```
Config Accepted
Enter to Reboot
```

Step 18. Press the **ENT** pushbutton.

The relay restarts and the **ENABLED** light turns on to indicate the card was installed correctly.

After reconfiguration, the relay updates the part number, except for the following indicated digits. These digits remain unchanged, i.e., these digits retain the same character as before the reconfiguration. Also, a communications card installed in Slot C is reflected as an empty slot in the part number. A regular 4 DI/4 DO card and a hybrid 4 DI/4 DO card have the same device ID. When interchanging these two cards, the part number for the respective slots should be updated manually.

Use the **Status** command to view the part number.

```
PART NUM = 0 7 8 7 0 X 1 A 6 X 3 A 1 A 8 5 0 2 0 X
                ↑  ↑  ↑  ↑  ↑
                1  2  3  4  5
```

Use the **PARTNO** command from the 2AC level to enter the exact part number of the relay.

Step 19. Update the side-panel drawing with the drawing sticker provided in the card kit. If necessary, replace the rear panel with the one applicable for the card and attach the terminal-marking label provided with the card to the rear-panel cover.

Step 20. Reconnect all of the connection plugs and add any additional wiring/connectors required by the new card.

Slot B CPU Card Replacement

When replacing the Slot B card, be aware of the following issues.

1. The new card will ship with the latest firmware from the factory.
2. The firmware revision history should be reviewed for the changes that were made; note that new settings added, if any, might affect existing settings in the relay or its application.
3. If the IEC 61850 protocol option was used previously, verify that the IEC 61850 protocol is still operational after the replacement. If not, reenable it. Refer to *Relays With IEC 61850 Option* in *Appendix B: Firmware Upgrade Instructions*, for the verification process.
4. Save all the settings and event reports before replacing the card.

Perform the following steps to replace the existing CPU board with a new board:

- Step 1. Turn off the power to the relay.
- Step 2. Use a ground strap between yourself and the relay.
- Step 3. Disconnect the terminal blocks and CT/PT wires.
- Step 4. Remove the rear panel.
- Step 5. Remove the main board from its slot and insert the new board.
- Step 6. Attach the rear panel (new if applicable) and reconnect the terminal blocks and CT/PT wires.
- Step 7. Apply new side stickers to the relay.
- Step 8. Turn on the relay and log in via the terminal emulation software.
- Step 9. Issue the **STA** command and accept the new configuration.
- Step 10. From Access Level 2, type **CAL** to enter the CAL level.
Do not modify any settings other than those listed in this procedure.
The CAL level default password is CLARKE.
- Step 11. From the CAL level, issue the **SET C** command.
- Step 12. Enter the serial number and part number to the appropriate values, then type **END** and save the settings.
- Step 13. Issue the **STA C** command to reboot the relay.
- Step 14. Issue the **STA** command to verify that the serial number and part number of your relay are correct.

Slot A Power Supply Card

If replacing a power supply card, change the part number accordingly, using the **PARTNO** command from the 2AC level. Install new side stickers on the side of the relay.

Analog Input (4 AI/ 4 AO Card) Voltage/ Current Jumper Selection

Figure 2.3 shows the circuit board of an analog I/O board. Jumper x ($x = 5-8$) determines the nature of each channel. For a current channel, insert Jumper x in position 1-2; for a voltage channel, insert Jumper x in position 2-3.



Where "JMPX" is the jumper for AI channel "X"

Figure 2.3 Circuit Board of Analog I/O Board, Showing Jumper Selection

Analog Output (4 AI/ 4 AO Card) Voltage/ Current Jumper Selection

Figure 2.4 shows the locations of JMP1 through JMP4 on an analog output board. You can select each of the four analog output channels as either a current analog output or a voltage analog output.

NOTE: Analog inputs cannot provide loop power. Each analog output is self-powered and has an isolated power supply.

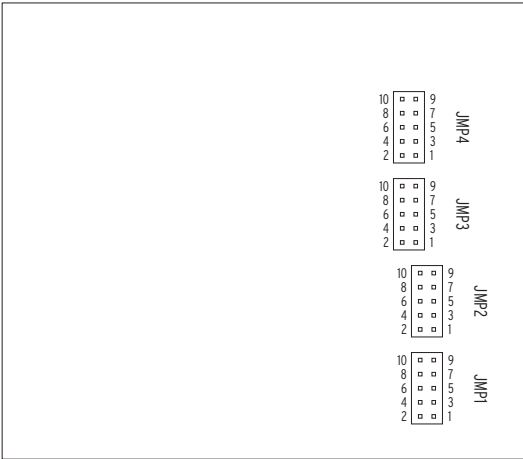
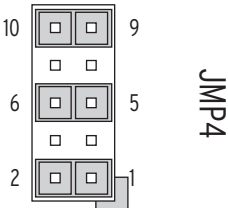


Figure 2.4 JMP1 Through JMP4 Locations on 4 AI/4 AO Board

You need to insert three jumpers for a current analog output selection and two jumpers for a voltage analog output selection. For a current analog output selection, insert a jumper between pins 1 and 2, pins 5 and 6, and pins 9 and 10. For a voltage analog output selection, insert a jumper between pins 3 and 4, and pins 7 and 8. *Figure 2.5* shows JMP4 selected as a current analog output. The current analog output selection is the default setting for JMP1 through JMP4. *Figure 2.6* shows JMP1 selected as a voltage analog output.

NOTE: There is no jumper between pins 5 and 6 for a voltage analog output selection.

JMP4 Selected as Current Output



JMP1 Selected as Voltage Output

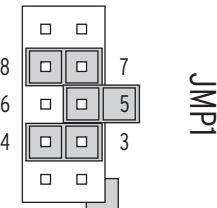
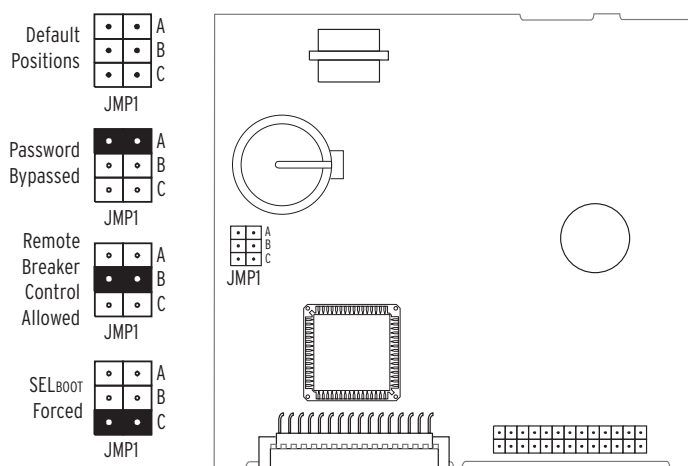


Figure 2.5 Current Output Jumpers Figure 2.6 Voltage Output Jumpers

Password, Breaker Control, and SELBOOT Jumper Selection

Figure 2.7 shows the major components of the Slot B card in the base unit. Notice the three sets of pins labeled A, B, and C.

(a) Card Layout for Relays With Firmware Versions Lower Than R200



(b) Card Layout for Relays With Firmware Versions R200 and Higher

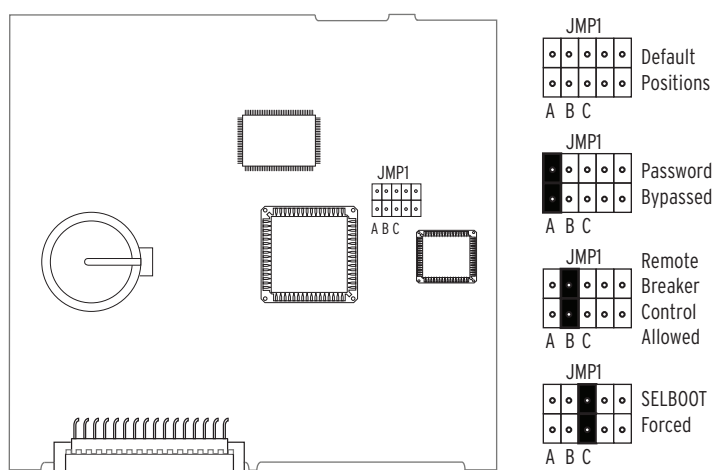


Figure 2.7 Pins for Password Jumper, Breaker Control Jumper, and SELBOOT Jumper

Pins labeled A bypass the password requirement, pins labeled B enable breaker control, and pins labeled C force the relay to the SEL operating system called SELBOOT. In the unlikely event that the SEL-787 experiences an internal failure, communication with the relay may be compromised. Forcing the relay to SELBOOT provides you with a way to downloading new firmware. To force the relay to SELBOOT, place the jumper in Position C, as shown in Figure 2.7 (SELBOOT Forced). After the relay is forced to SELBOOT, you can only communicate with it via the front-panel port.

To gain access to Level 1 and Level 2 command levels without passwords, position the jumper in position A, as shown in Figure 2.7 (Password Bypassed). Although you gain access to Level 2 without a password, the alarm contact still closes momentarily when accessing Level 2. See Table 2.12 for the functions of the three sets of pins and their jumper default positions.

Table 2.12 Jumper Functions and Default Positions

| Pins | Jumper Default Position | Description |
|------|-----------------------------------|-------------------------------------|
| A | Not bypassed (requires password) | Password bypass |
| B | Off (breaker control disabled) | Enable breaker control ^a |
| C | Not bypassed (not forced SELBOOT) | Forced SELBOOT |

^a Jumper position affects breaker control using the OPEN or CLOSE command via the serial port, front panel, or communications protocols. Jumper position does not affect breaker control using remote bits, which are always enabled.

Rear-Panel Connections

NOTE: After any change, be sure to thoroughly test the settings.

NOTE: Analog outputs are isolated from each other and from the chassis ground.

NOTE: All digital input and digital output (including high-current, high-speed hybrid) connections are polarity neutral.

Figure 2.8 shows the rear-panel connections for selected cards. Connections for additional cards are shown in Figure 2.9 through Figure 2.11.

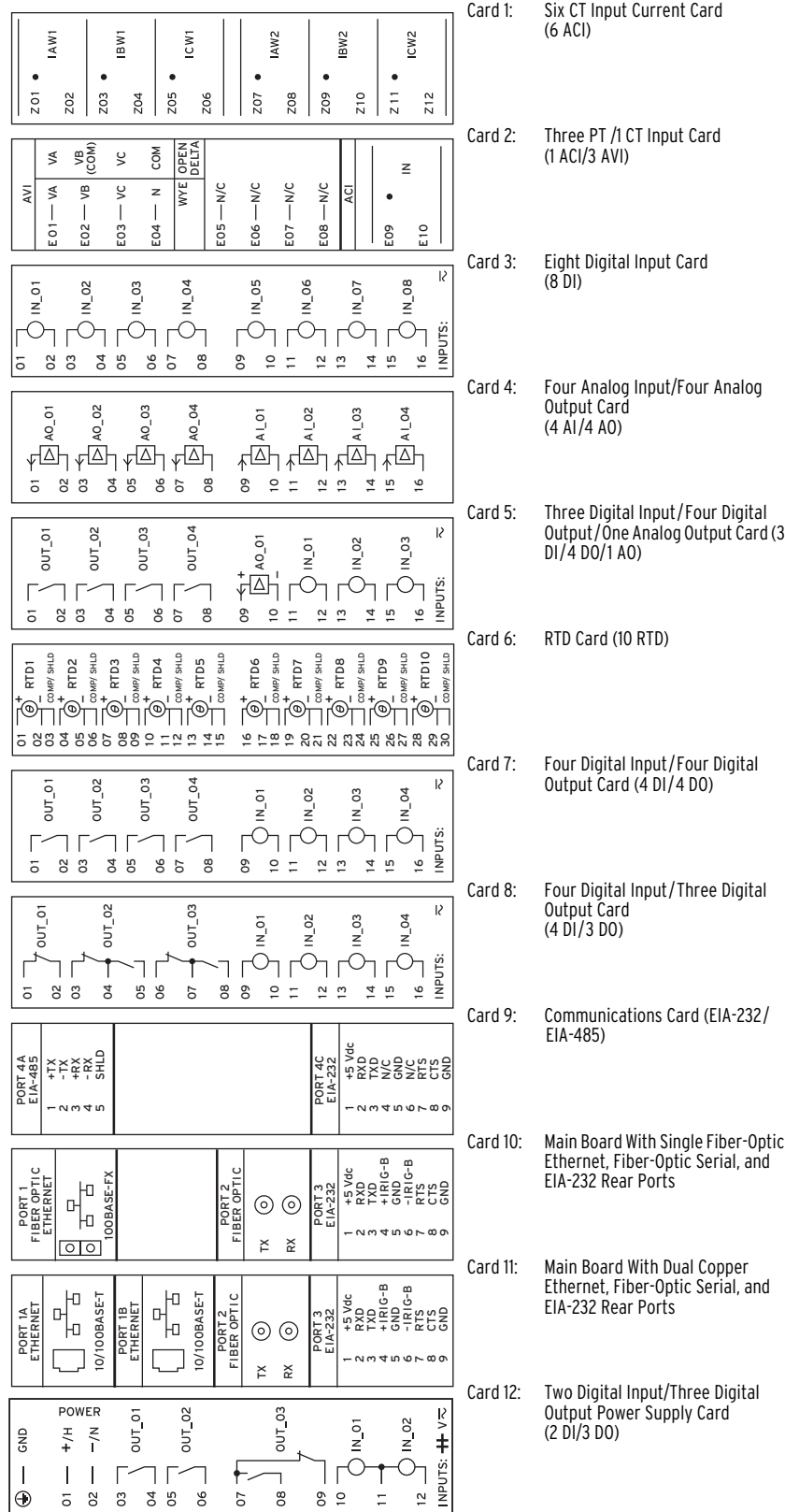
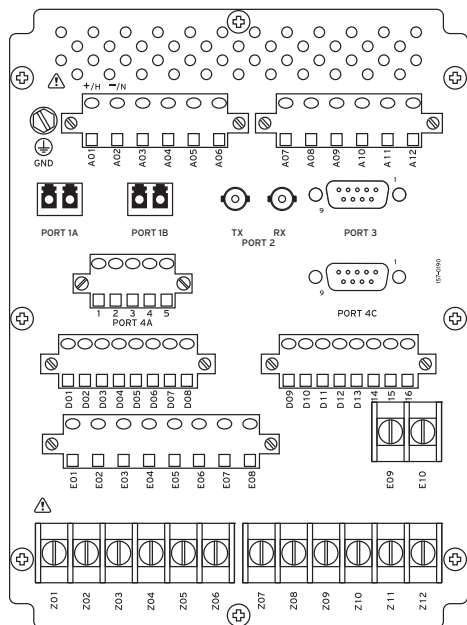


Figure 2.8 Rear-Panel Connections of Selected Cards

Rear-Panel Connections

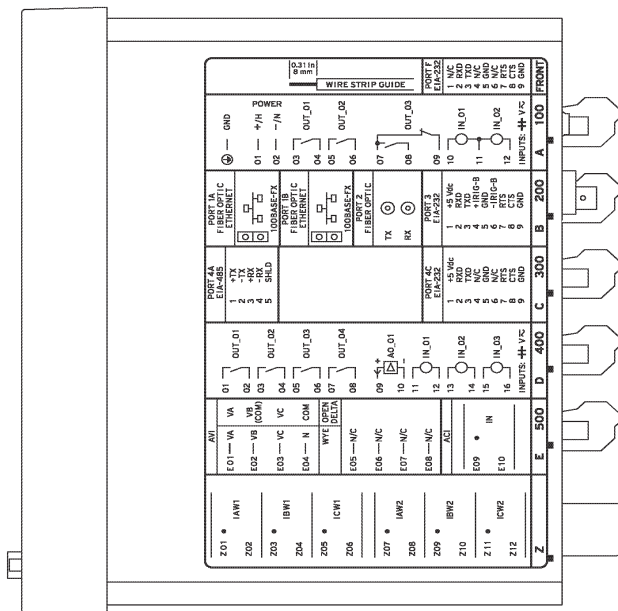
Rear-Panel and Side-Panel Diagrams

The physical layout of the connectors on the rear-panel and side-panel diagrams of three sample configurations of the SEL-787 are shown in *Figure 2.9*, *Figure 2.10*, and *Figure 2.11*.



i4201a

(A) Rear-Panel Layout

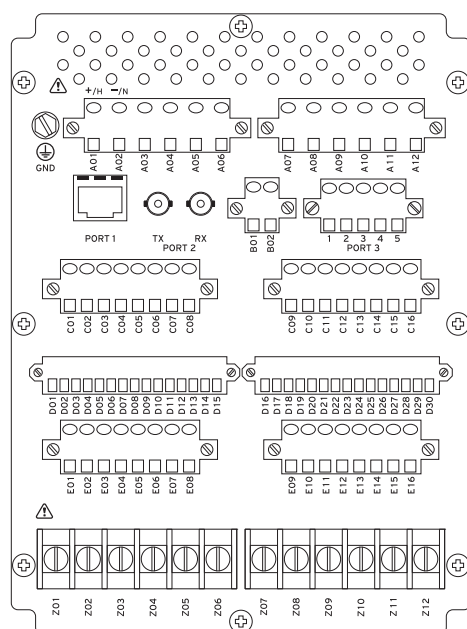


† SEE DOCUMENTATION FOR INPUT VOLTAGE RATING

i4202d

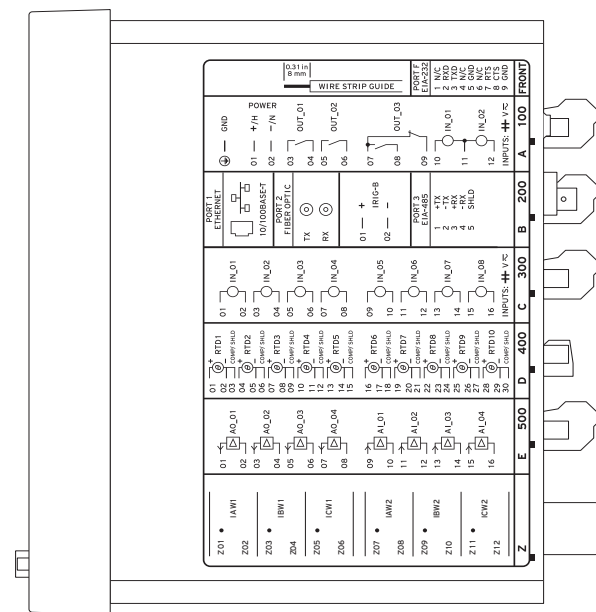
(B) Side-Panel Input and Output Designations

Figure 2.9 Dual-Fiber, Ethernet, EIA-232 Communication, 3 DI/4 DO/1 AO, and Current/Voltage (1 ACI/3 AVI) Option



i4203a

(A) Rear-Panel Layout



† SEE DOCUMENTATION FOR INPUT VOLTAGE RATING

i4204b

(B) Side-Panel Input and Output Designations

Figure 2.10 Single Copper Ethernet, 8 DI, RTD, and 4 AI/4 AO Option

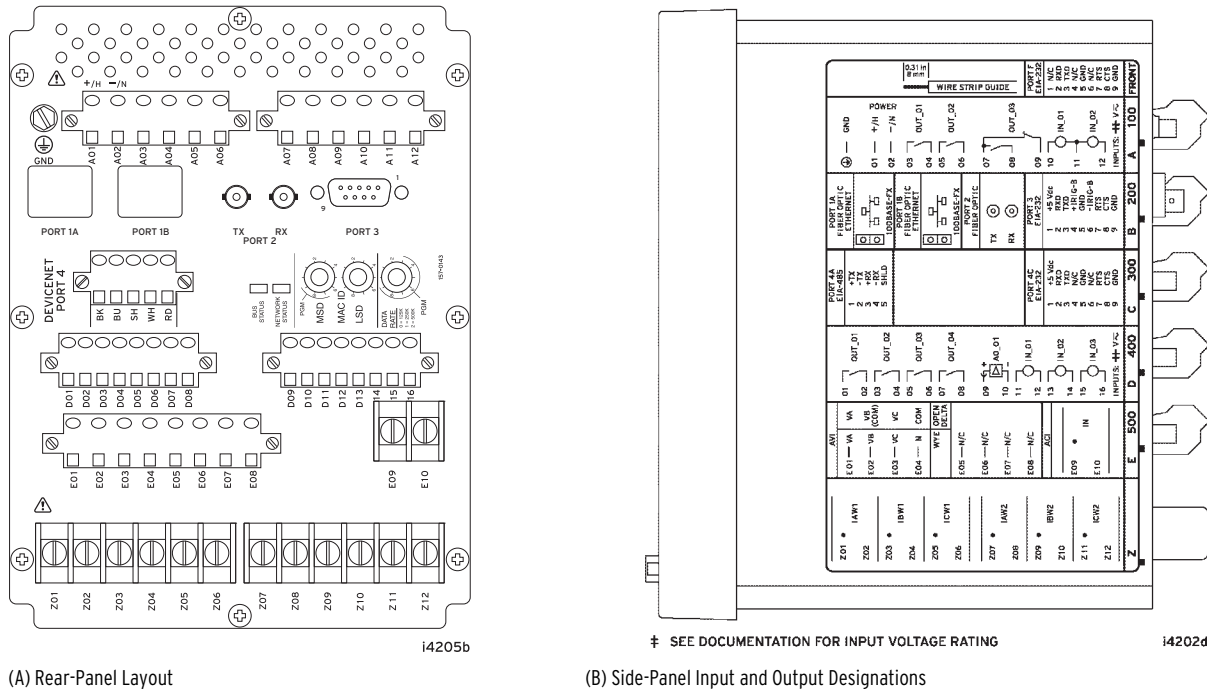


Figure 2.11 DeviceNet, Fast Hybrid 4 DI/4 DO, and Current/Voltage Option

Power Connections

⚠ DANGER

Contact with instrument terminals can cause electrical shock that can result in injury or death.

⚠ CAUTION

The relay contains devices sensitive to Electrostatic Discharge (ESD). When working on the relay with the front panel removed, work surfaces and personnel must be properly grounded or equipment damage may result.

The **POWER** terminals on the rear panel (A01 (+/H) and A02 (-/N)) must connect to 110–240 Vac, 110–250 Vdc, or 24–48 Vdc (see *Power Supply* on page 1.9 for complete power input specifications). The **POWER** terminals are isolated from chassis ground. Use 14 AWG (2.1 mm²) to 16 AWG (1.3 mm²) size wire to connect to the **POWER** terminals.

For compliance with IEC 60947-1 and IEC 60947-3, place a suitable external switch or circuit breaker in the power leads for the SEL-787; this device should interrupt both the hot (+/H) and neutral (-/N) power leads. The maximum current rating for the power disconnect circuit breaker or optional overcurrent device (fuse) should be 20 A.

Operational power is internally fused by a power supply fuse. See *Field Serviceability* on page 2.31 for details. Be sure to use fuses that comply with IEC 60127-2.

Grounding (Earthing) Connections



You must connect the ground terminal labeled **GND** on the rear panel to a rack frame or switchgear ground for proper safety and performance. Use 14 AWG (2.1 mm²) wire less than 2 m (6.6 feet) in length for the ground connection.

Serial Ports

Because all ports (F, 2, 3, and 4) are independent, you can communicate to any combination simultaneously. Although serial **Port 4** on the optional communications card consists of an EIA-485 (**4A**) and an EIA-232 (**4C**) port, only one port is available at a time. Use the **Port 4** communications interface COMMNF setting to select between EIA-485 and EIA-232.

The serial port EIA-485 plug-in connector accepts wire size AWG 24 through AWG 12. Strip the wires 8 mm (0.31 inches) and install with a small slotted-tip screwdriver. All EIA-232 ports accept 9-pin D-subminiature male connectors.

For connecting devices at distances over 100 feet, where metallic cable is not appropriate, SEL offers fiber-optic transceivers or the SEL-2812 compatible

ST fiber-optic port. The SEL-2800 family of transceivers provides fiber-optic links between devices for electrical isolation and long-distance signal transmission. Contact SEL for further information on these products.

IRIG-B Time-Code Input

The SEL-787 accepts a demodulated IRIG-B time signal to synchronize the internal clock with an external source. SEL-787 relays with an EIA-485 serial port option for **Port 3** have an external IRIG-B input at terminals **B01** and **B02**. SEL-787 relays with an EIA-232 serial port option for **Port 3** have the IRIG-B available in the EIA-232 port and can be connected to an SEL communications processor. The available communications processors are the SEL-2032, SEL-2030, SEL-2020, and the SEL-2100 Logic Processor.

Ethernet Port

The SEL-787 can be ordered with optional single/dual communications ports of a 10/100BASE-T or 100BASE-FX Ethernet port. Connect to **Port 1** of the device using a standard RJ-45 connector for the copper port and an LC connector for the fiber-optic port.

Fiber-Optic Serial Port

The optional fiber-optic serial port is compatible with the SEL-2812 Fiber-Optic Transceiver and SEL-2600 RTD Modules.

I/O Diagram

A more functional representation of two of the control (I/O) connections are shown in *Figure 2.12* and *Figure 2.13*.

NOTE: All digital input and digital output (including high-current, high-speed hybrid) connections are polarity neutral.

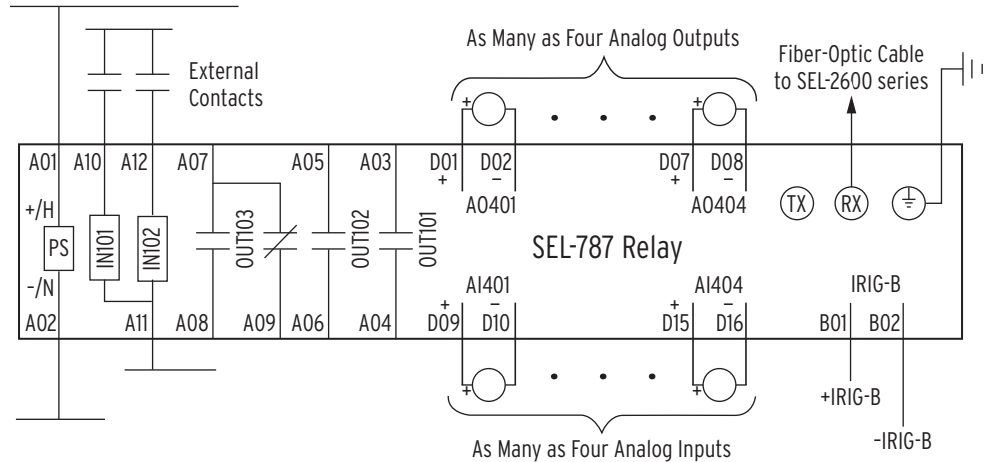
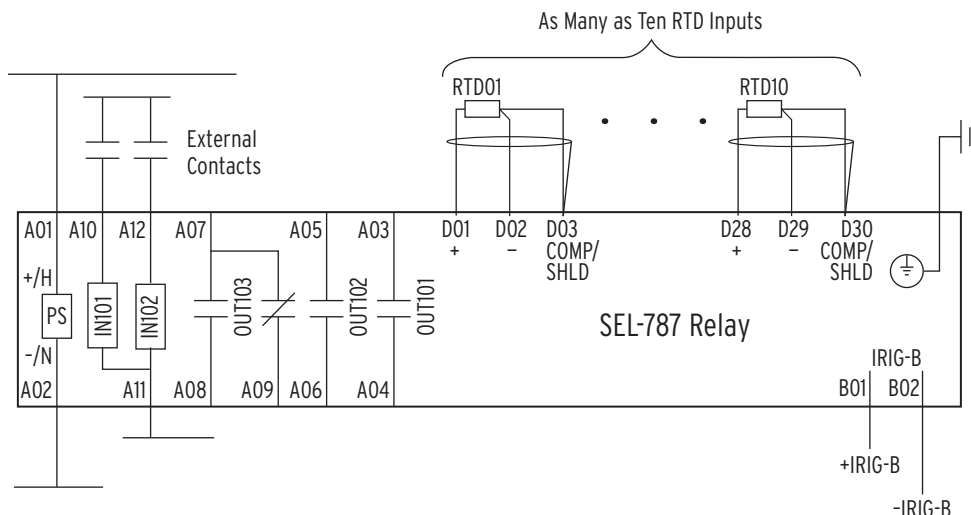


Figure 2.12 Control I/O Connections—4 AI/4 AO Option in Slot D and Fiber-Optic Port in Slot B

NOTE: All RTD Comp/Shield terminals are internally connected to the relay chassis and ground.



Notes:

- The chassis ground connector located on the rear-panel card Slot A must always be connected to the local ground mat.
- Power supply rating (125-250 Vac/dc or 24-48 Vdc) depends on relay part number.
- Optoisolated inputs IN101 and IN102 are standard and located on the card in Slot A.
- All optoisolated inputs are single-rated: 24, 48, 110, 125, 220, or 250 Vac/Vdc. Standard inputs IN101/102 may have a different rating than the optional IN401/402/403/404 (not shown).
- Output contacts OUT101, OUT102, and OUT103 are standard and located on the card in Slot A.
- The Analog (transducer) Outputs shown are located on the optional I/O Expansion card in Slot D.
- The fiber-optic serial port is located on the card in Slot B. A Simplex 62.5/125 μ m fiber-optic cable is required to connect the SEL-787 with an SEL-2600 series RTD Module. This fiber-optic cable should be 1000 meters or shorter.

Figure 2.13 Control I/O Connections—Internal RTD Option

NOTE: RTD inputs are not internally protected for electrical surges (IEC 60255-22-1 and IEC 60255-22-5). External protection is recommended if surge protection is desired.

Table 2.13 shows the maximum cable lengths for the RTD connections.

Table 2.13 Typical Maximum RTD Lead Length

| RTD Lead AWG | Maximum Length (meters) |
|--------------|-------------------------|
| 24 | 290 m |
| 22 | 455 m |
| 20 | 730 m |
| 18 | 1155 m |

Analog Output Wiring

NOTE: Connection of dc voltage to the analog output terminals could result in damage to the relay.

Connect the two terminals of the analog output as shown in *Figure 2.14*. Also connect the analog output cable shield to ground at the relay chassis ground, programmable logic controller (PLC), or meter location. Do not connect the shield to ground at both locations.

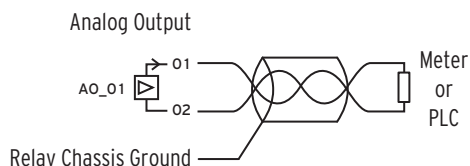


Figure 2.14 Analog Output Wiring Example

AC/DC Control Connection Diagrams

This section describes fail-safe versus nonfail-safe tripping, describes voltage connections, and provides the ac and dc wiring diagrams.

Fail-Safe/Nonfail-Safe Tripping

NOTE: When using fast hybrid output contacts, do not use the FAILSAFE mode.

Figure 2.15 shows the output **OUT103** relay coil and Form C contact. When the relay coil is de-energized, the contact between **A07** and **A08** is open while the contact between **A07** and **A09** is closed.

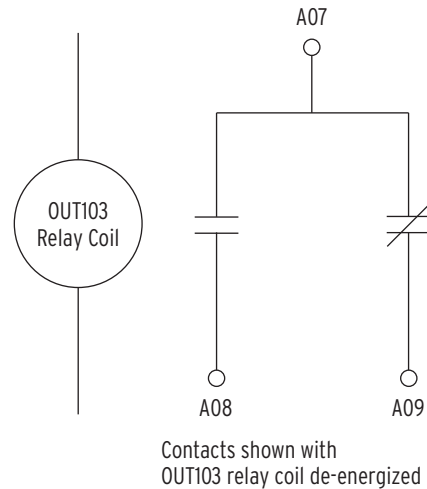


Figure 2.15 Output OUT103 Relay Output Contact Configuration

The SEL-787 provides fail-safe and nonfail-safe trip modes (setting selectable) for all output contacts. The following occurs in fail-safe mode:

- The relay coil is energized continuously if the SEL-787 is powered and operational.
- When the SEL-787 generates a trip signal, the relay coil is de-energized.
- The relay coil is also de-energized if the SEL-787 power supply voltage is removed or if the SEL-787 fails (self-test status is FAIL).

Figure 2.16 shows fail-safe and nonfail-safe wiring methods to control breakers.

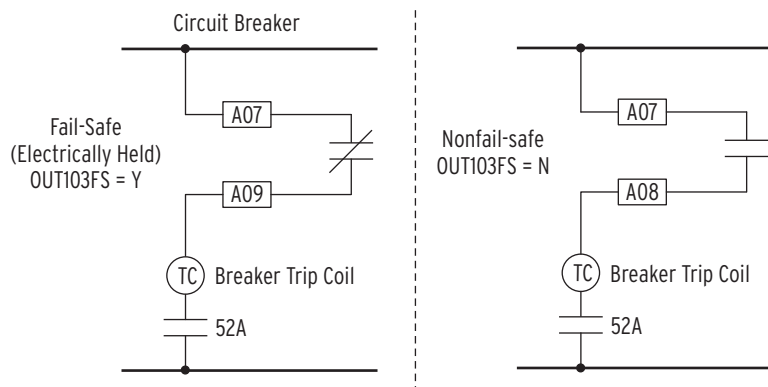
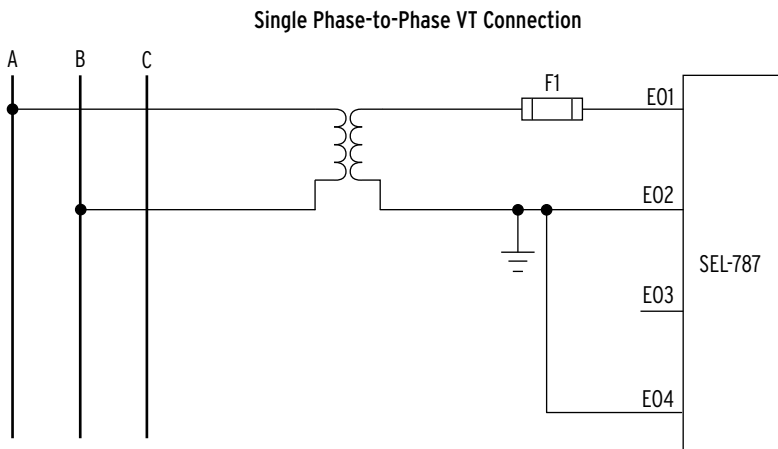
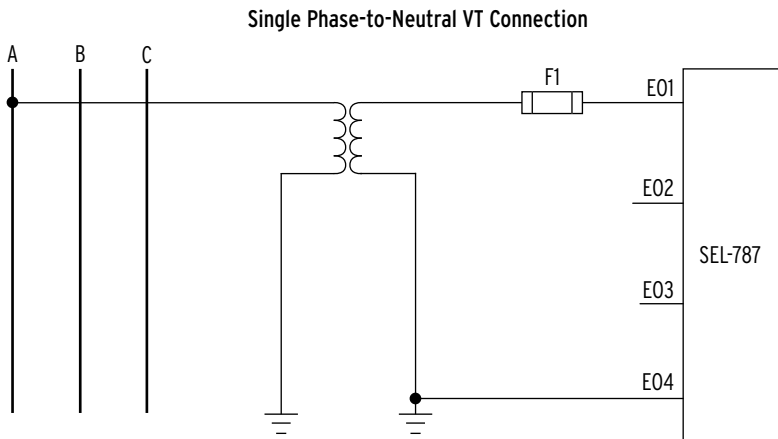


Figure 2.16 OUT103 Contact Fail-Safe and Nonfail-Safe Options

Voltage Connections

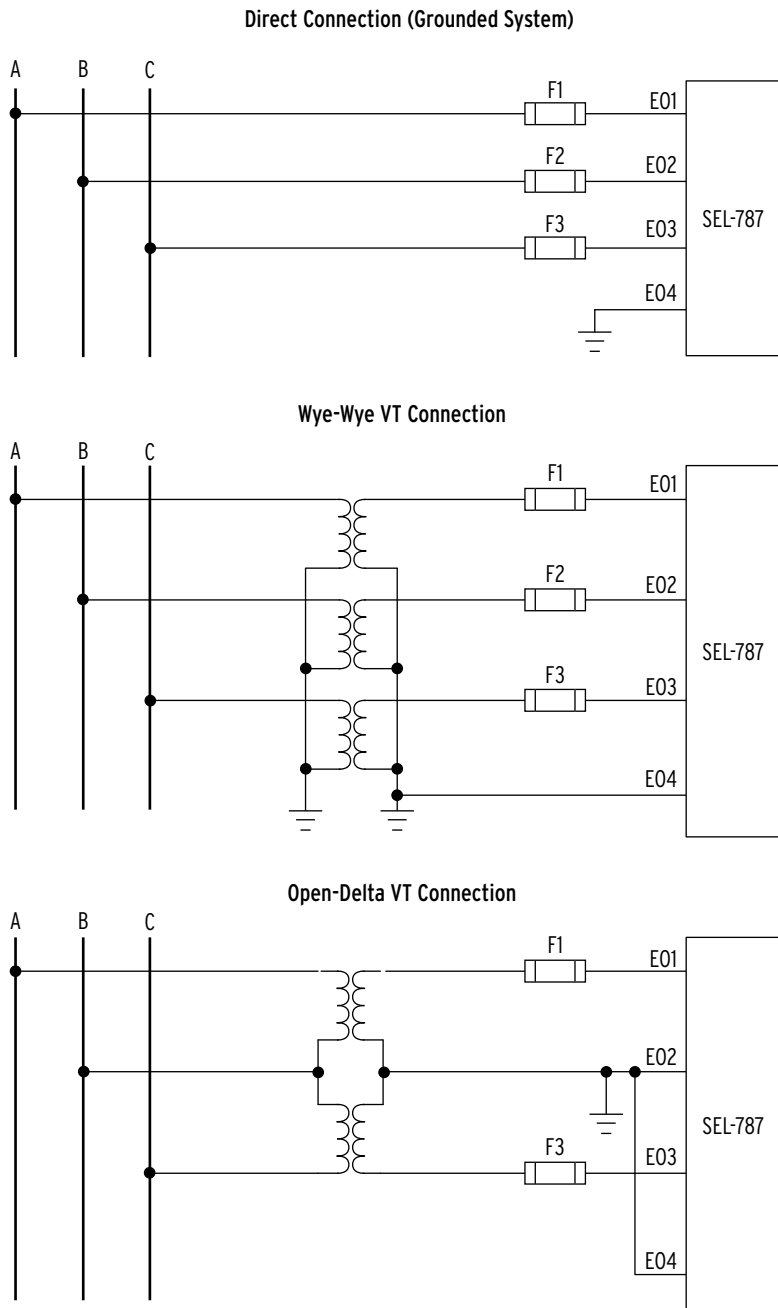
NOTE: Current limiting fuses in direct-connected voltage applications are recommended to limit short circuit arc flash incident energy.

With the voltage inputs option, the AC voltages may be directly connected, wye-wye VT connected, open-delta VT connected, or a single-phase VT can be used. *Figure 2.17* and *Figure 2.18* show the methods of connecting single-phase and three-phase voltages.



Note: The VT secondary circuit should be grounded in the relay cabinet.

Figure 2.17 Single-Phase Voltage Connections



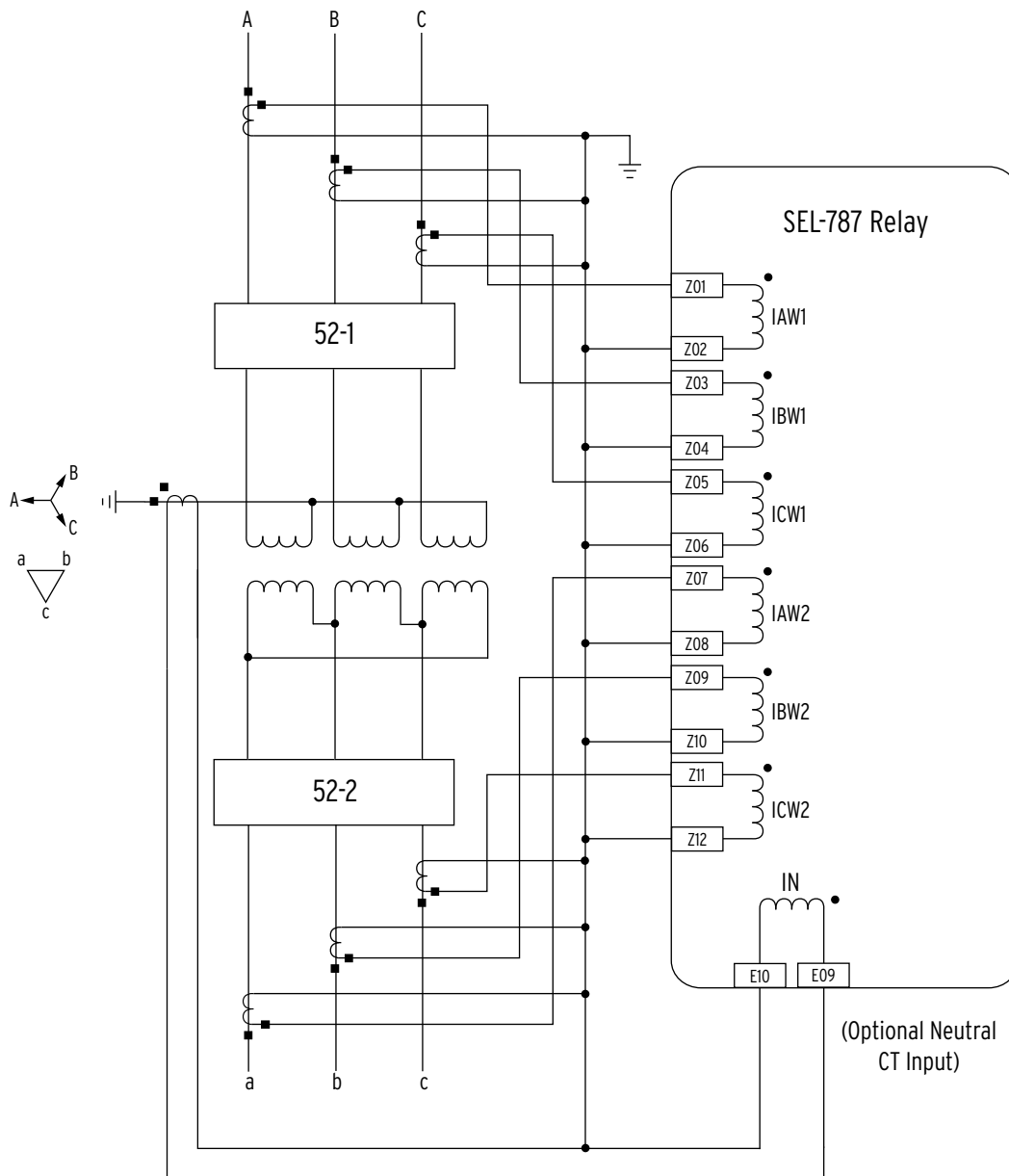
Note: The VT secondary circuit should be grounded in the relay cabinet.

Note: For open-delta VT connections, the figure shows grounding Phase B (E02). You can choose to ground Phase A or Phase C instead of Phase B, but the jumper between terminals E02 and E04 must remain as is.

Figure 2.18 Voltage Connections

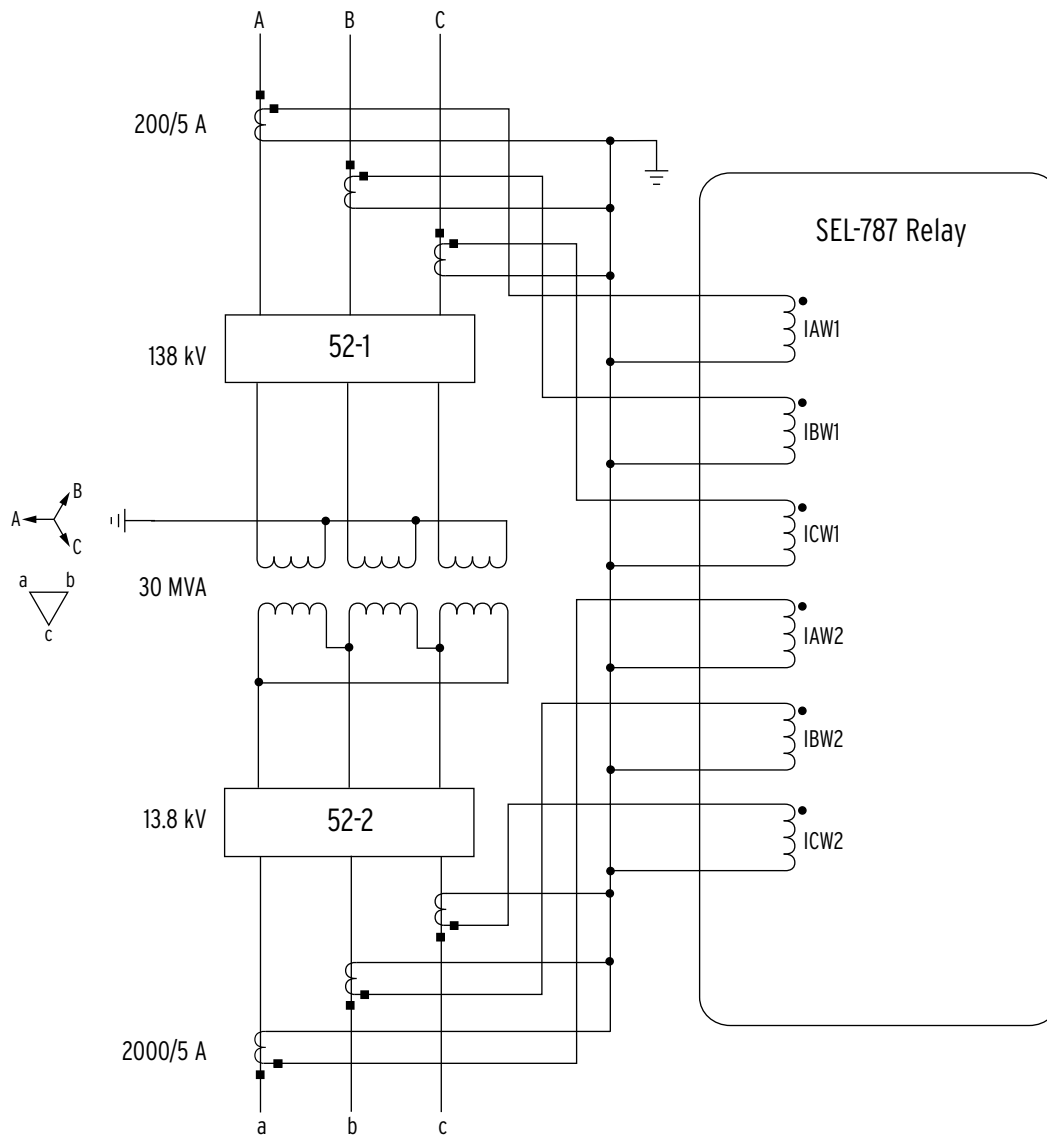
Current Connections

Figure 2.19 shows typical phase and neutral current connections for a Transformer application. Figure 2.20 through Figure 2.23 show connection diagrams for various applications. Wye-connected PTs are shown in Figure 2.22; see Figure 2.17 and Figure 2.18 for other voltage connections. Refer to Figure 2.24 for an example of dc connections for these applications



- Note
1. The IN input channel requires the optional single current channel 1 ACI current card in Slot E.
 2. The CT secondary circuit should be grounded in the relay cabinet.

Figure 2.19 Typical Current Connections

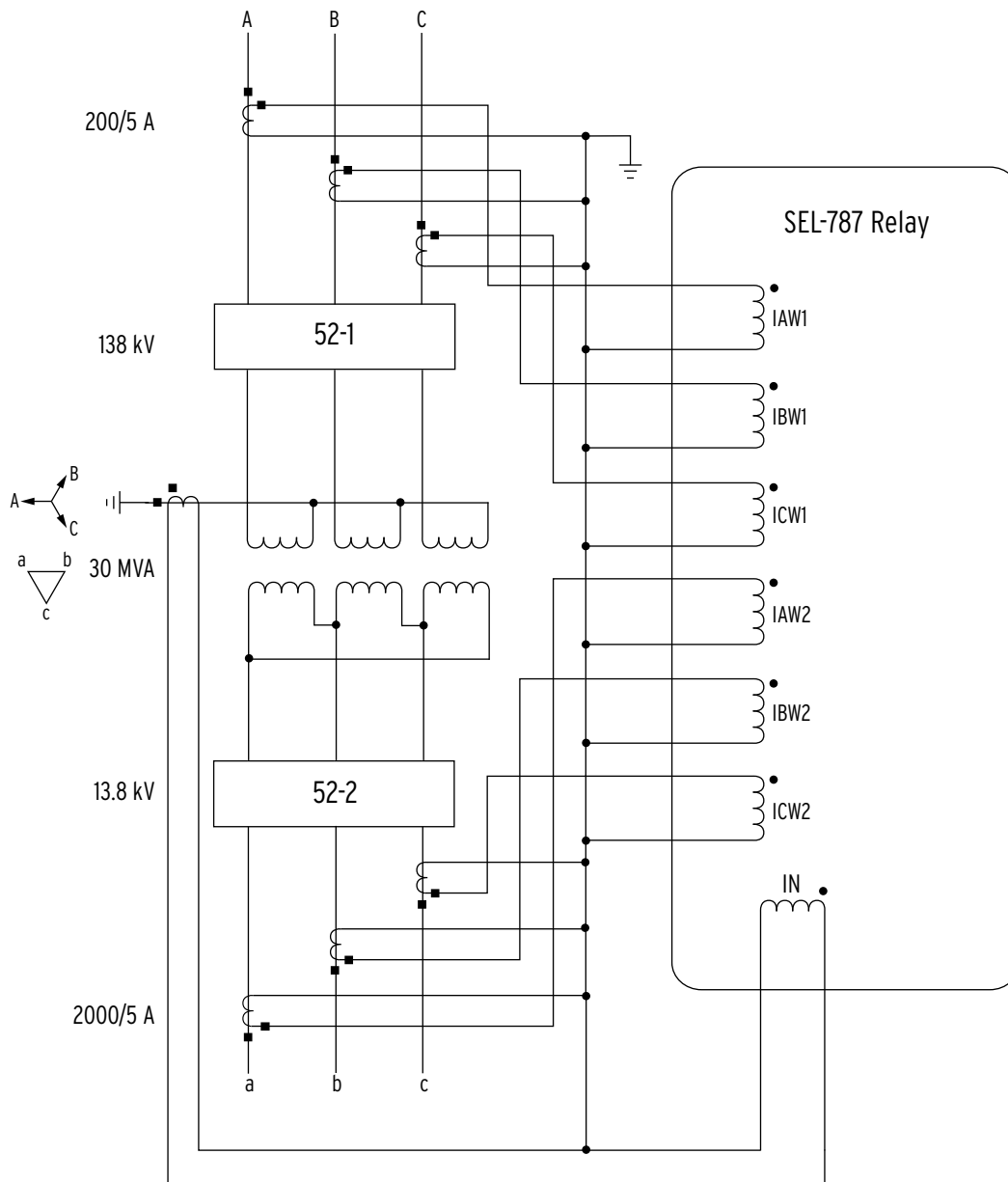


Note: The CT secondary circuit must be grounded in the relay cabinet.

The basic application of the SEL-787 relay is for a two-winding transformer. The SEL-787 base product offering provides six current channels that are used to monitor the two transformer windings. Relay contact inputs can be used to monitor high- and low-side breaker status. Relay contact outputs can be used to trip or close high and low side transformer breakers.

Refer to Figure 2.24, which illustrates tripping control of the two-power circuit breakers.

Figure 2.20 SEL-787 Provides Basic Two-Winding Transformer Differential Protection

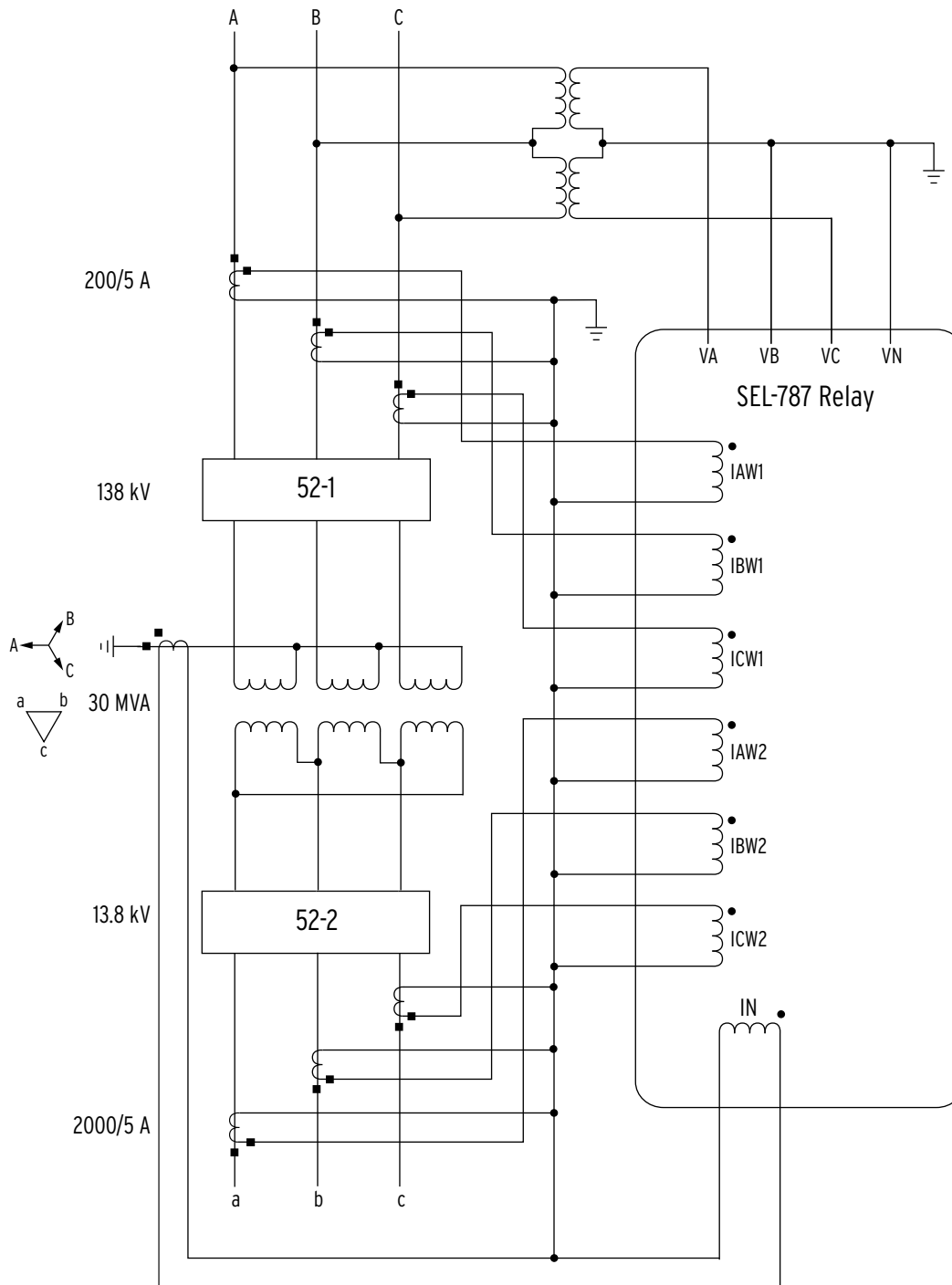


Note: The CT secondary circuit must be grounded in the relay cabinet.

By adding the 1 ACI current card option to Slot E of the relay, the relay can be used to provide neutral overcurrent and restricted earth fault protection (REF) of grounded wye transformer winding.

Refer to Figure 2.24, which illustrates tripping control of the two-power circuit breakers.

Figure 2.21 SEL-787 Provides Two-Winding Transformer Differential Protection With REF (Restricted Earth Fault) Protection

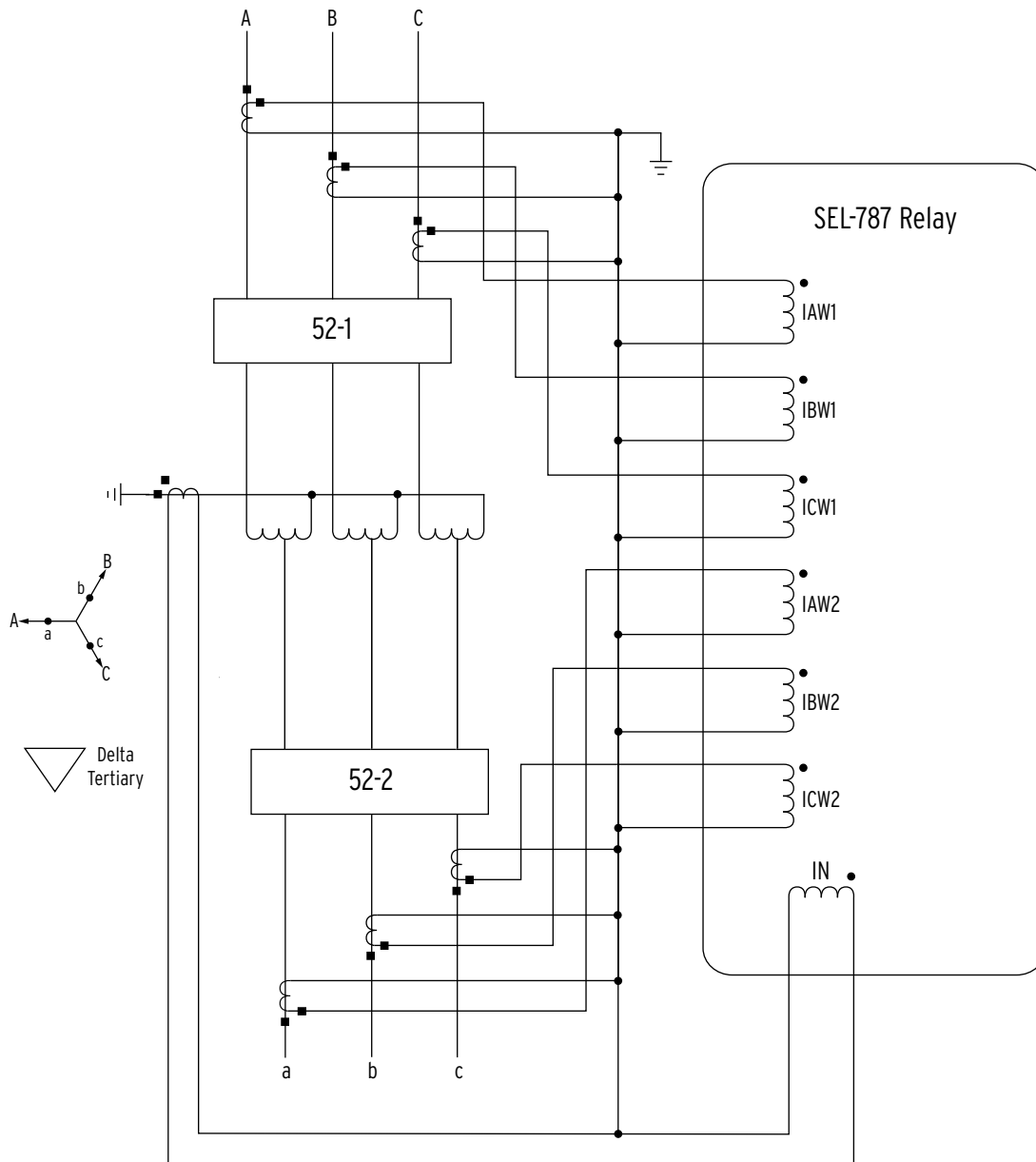


Note: The CT secondary circuit must be grounded in the relay

Installing the optional 1 ACI/3 AVI voltage/current card in Slot E of the SEL-787 provides neutral current and REF protection, as well as three-phase voltage inputs. These voltage inputs provide the relay with 20.0 to 70.0 Hz frequency tracking, over-/undervoltage elements, frequency elements, power elements, and volts-per-hertz protection of the transformer.

Refer to Figure 2.24, which illustrates tripping control of the two-power circuit breakers.

Figure 2.22 SEL-787 Provides Two-Winding Transformer Differential Protection With REF and Voltage-Based Protection



Note: The CT secondary circuit must be grounded in the relay cabinet.

This figure shows an autotransformer application with REF protection applied through the optional 1 ACI current input card in Slot E of the relay. In this application, the SEL-787 provides full differential protection, and uses the sum of the high- and low-voltage winding currents to calculate the zero-sequence currents necessary for REF protection.

Refer to Figure 2.24, which illustrates tripping control of the two-power circuit breakers.

Figure 2.23 SEL-787 Provides Autotransformer Differential Protection, Including REF Protection

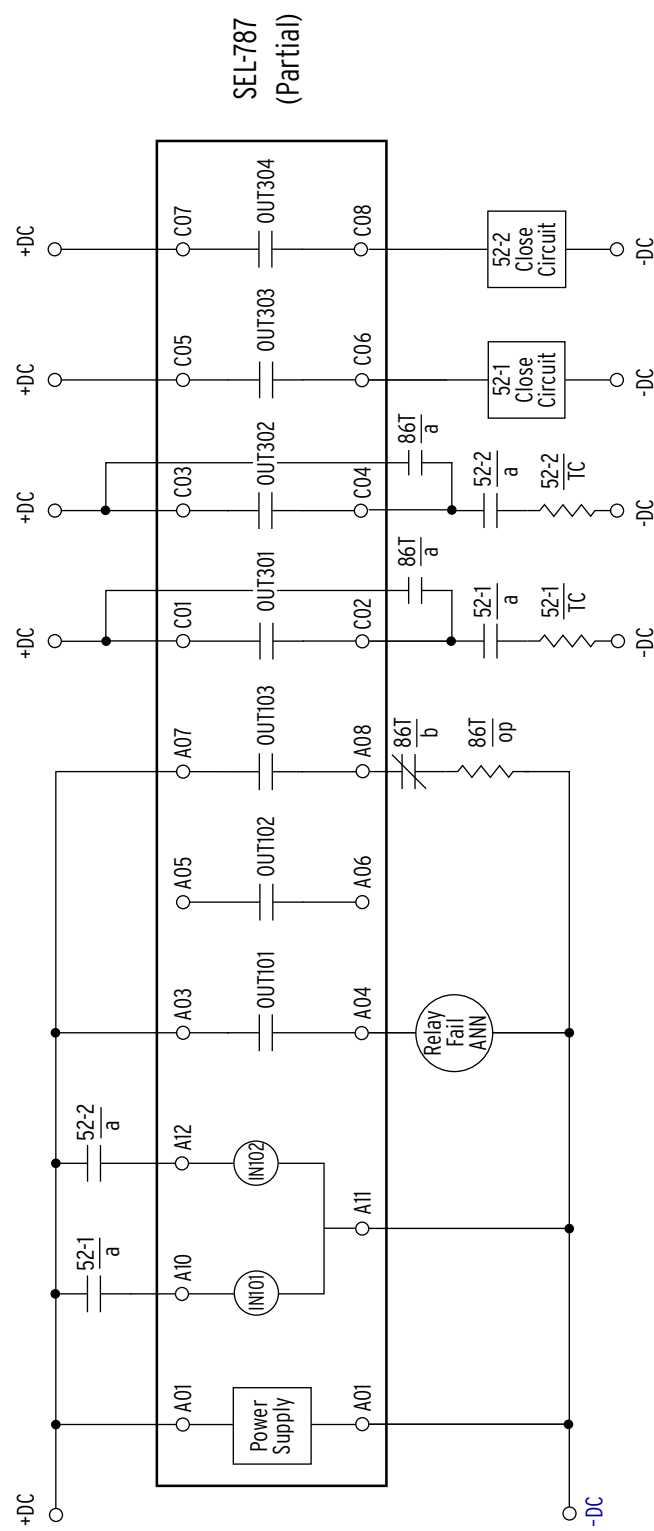


Figure 2.24 Example DC Connections

Note 1: Assumes an optional 4DI/4DO card in Slot C for OUT301–OUT304.

Note 2: Remaining 4 inputs (IN301–IN304) and 1 output (OUT102)

Settings required for the above implementation:

| | | |
|--------------------|-----------------|------------------|
| OUT101 := HALARM | OUT103FS := N | OUT302 := TRIP2 |
| OUT101FS := Y | 52A1 := IN101 | OUT303 := CLOSE1 |
| OUT102 := 0 | 52A2 := IN102 | OUT304 := CLOSE2 |
| OUT103 := TRIPXFMR | OUT301 := TRIP1 | |

Field Serviceability

⚠CAUTION

Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service.

The SEL-787 firmware may be upgraded in the field; refer to *Appendix B: Firmware Upgrade Instructions* for firmware upgrade instructions. You may know when a self-test failure has occurred by configuring an output contact to create a diagnostic alarm as explained in *Section 4: Protection and Logic Functions*. By using the metering functions, you may know if the analog front-end (not monitored by relay self-test) is functional. Refer to *Section 10: Testing and Troubleshooting* for detailed testing and troubleshooting information.

The only two components that may be replaced in the field are the power supply fuse and the real-time clock battery. A lithium battery powers the clock (date and time) if the external power source is lost or removed. The battery is a 3 V lithium coin cell, Ray-O-Vac® BR2335 or equivalent. At room temperature (25°C), the battery will operate nominally for 10 years at rated load. When the relay is powered from an external source, the battery experiences a low self-discharge rate. Thus, battery life may extend well beyond 10 years. The battery cannot be recharged.

Fuse Replacement

⚠DANGER

Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death.

To replace the power supply fuse, perform the following steps:

- Step 1. De-energize the relay.
- Step 2. Remove the four rear-panel screws and the relay rear panel.
- Step 3. Remove the Slot A printed circuit board.
- Step 4. Locate the fuse on the board.
- Step 5. Remove the fuse from the fuse holder.
- Step 6. Replace the fuse with a BUSS S505 3.15A (ceramic), Schurter T3.15AH250V, or equivalent.
- Step 7. Insert the printed circuit board into Slot A.
- Step 8. Replace the relay rear panel and energize the relay.

Real-Time Clock Battery Replacement

⚠CAUTION

There is danger of explosion if the battery is incorrectly replaced. Replace only with Ray-O-Vac® no. BR2335 or equivalent recommended by manufacturer. Dispose of used batteries according to the manufacturer's instructions.

To replace the real-time clock battery, perform the following steps:

- Step 1. De-energize the relay.
- Step 2. Remove the four rear-panel screws and the relay rear panel.
- Step 3. Remove the Slot B printed circuit board.
- Step 4. Locate the battery clip (holder) on the board.
- Step 5. Carefully remove the battery from beneath the clip.
Properly dispose of the old battery.
- Step 6. Install the new battery with the positive (+) side facing up.
- Step 7. Insert the printed circuit board into Slot B.
- Step 8. Replace the relay rear panel and energize the relay.
- Step 9. Set the relay date and time.

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Section 3

PC Software

Overview

SEL provides many PC software solutions (applications) to support the SEL-787 and other SEL devices. *Table 3.1* lists SEL-787 software solutions.

Table 3.1 SEL Software Solutions

| Part Number | Product Name | Description |
|-------------|--|--|
| SEL-5010 | SEL-5010 Relay Assistant Software | Manages a connection directory and settings of multiple devices. |
| SEL-5030 | ACSELERATOR QuickSet® SEL-5030 Software | See <i>Table 3.2</i> . |
| SEL-5032 | ACSELERATOR Architect® SEL-5032 Software | Configures IEC 61850 communications. |
| SEL-5040 | ACSELERATOR Report Server™ SEL-5040 Software | Automatically retrieves, files, and summarizes reports. |
| SEL-5601 | ACSELERATOR Analytic Assistant™ SEL-5601 Software | Converts SEL Compressed ASCII event report files to oscillography. |
| SEL-5801 | SEL-5801 Cable Selector Software | Selects the proper SEL cables for your application. |
| SEL-5806 | SEL-5806 Volts/Hertz User Curve Designer PC Software | Designs user-defined, volts/Hz inverse-time characteristic curve to match any transformer characteristic (refer to <i>Section 4: Protection and Logic Functions</i>). |

This section describes how to get started with the SEL-787 and ACSELERATOR QuickSet SEL-5030 Software. ACSELERATOR QuickSet is a powerful setting, event analysis, and measurement tool that aids in setting, applying, and using the SEL-787. *Table 3.2* shows the suite of ACSELERATOR QuickSet applications provided for the SEL-787.

Table 3.2 ACSELERATOR QuickSet SEL-5030 Software

| Application | Description |
|---|--|
| Rules-Based Settings Editor | Provides on-line or off-line device settings that include interdependency checks. Use this feature to create and manage settings for multiple devices in a database. |
| HMI | Provides a summary view of device operation. Use this feature to simplify commissioning. |
| Design Templates (Available in licensed versions of ACSELERATOR QuickSet) | Allows you to customize relay settings to particular applications and store those settings in Design Templates. You can lock settings to match your standards or lock and hide settings that are not used. |
| Event Analysis | Provides oscillography and other event analysis tools. |
| Settings Database Management | ACSELERATOR QuickSet uses a database to manage the settings of multiple devices. |
| Terminal | Provides a direct connection to the SEL device. Use this feature to ensure proper communications and directly interface with the device. |
| Help | Provides general ACSELERATOR QuickSet and device-specific ACSELERATOR QuickSet context. |

Setup

Follow the steps outlined in *Section 2: Installation* to prepare the SEL-787 for use. Perform the following steps to initiate communications:

- Step 1. Connect the appropriate communications cable between the SEL-787 and the PC.
- Step 2. Apply power to the SEL-787.
- Step 3. Start ACSELERATOR QuickSet.

Communications

ACSELERATOR QuickSet uses relay communications **Port 1** through **Port 4**, or **Port F** (front panel) to communicate with the SEL-787. Perform the following steps to configure ACSELERATOR QuickSet to communicate effectively with the relay.

- Step 1. Select **Communications** from the ACSELERATOR QuickSet main menu bar, as shown in *Figure 3.1*.

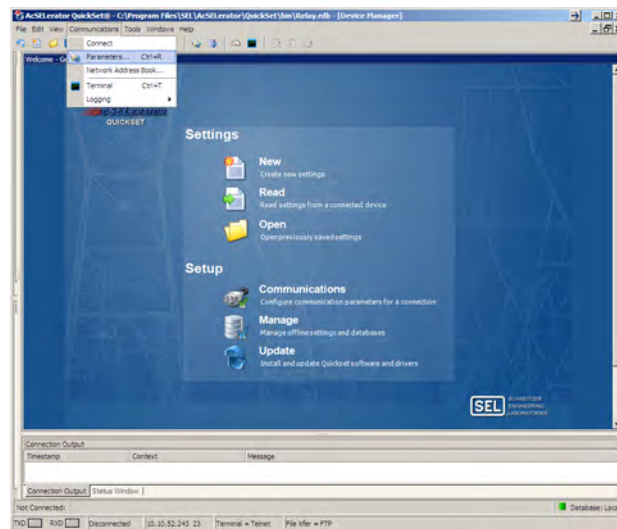


Figure 3.1 Serial Port Communication Dialog Box

- Step 2. Select the **Parameters** submenu to display the screen shown in *Figure 3.2*. Configure the PC port to match the relay communications settings.
- Step 3. Configure ACSELERATOR QuickSet to match the SEL-787 default settings by entering Access Level 1 and Access Level 2 passwords in the respective text boxes.
- Step 4. If a telephone modem is chosen from the relay text box, enter the dial-up telephone number in the **Phone Number** text box.

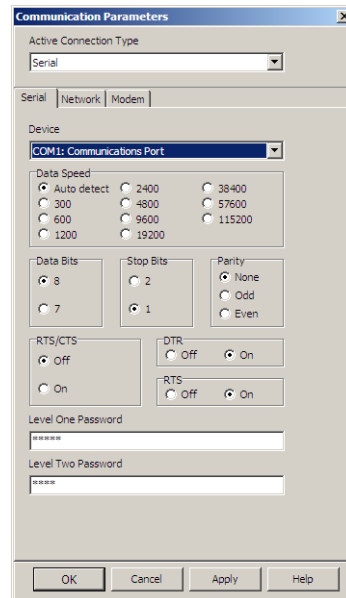


Figure 3.2 Serial Port Communication Parameters Dialog Box

Step 5. For network communications, check the **Use Network** check box and enter the network parameters as shown in *Figure 3.3*.

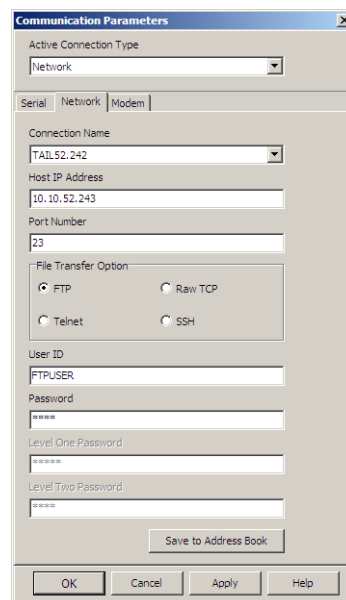


Figure 3.3 Network Communication Parameters Dialog Box

Step 6. Exit the menus by clicking **OK** when finished.

Terminal

Terminal Window

Select **Tools > Terminal** on the ACSELERATOR QuickSet main menu bar to open the terminal window (shown in *Figure 3.4*).



Figure 3.4 Tools Menu

The terminal window is an ASCII interface with the relay. This is a basic terminal emulation. Many third-party terminal emulation programs are available with file transfer encoding schemes. Open the terminal window by either clicking **Tools > Terminal** or by pressing **<Ctrl+T>**. Verify proper communications with the relay by opening a terminal window, pressing **<Enter>** a few times, and verifying that a prompt is received. If a prompt is not received, verify proper setup.

Terminal Logging

To create a file that contains all terminal communications with the relay, select **Terminal Logging** in the **Log** menu, and specify a file at the prompt. ACSELERATOR QuickSet records communications events and errors in this file. Click **Log > Connect Log** to view the log. Clear the log by selecting **Log > Clear Connection Log**.

Drivers and Part Number

After clicking **Tools > Terminal**, access the relay at Access Level 1. Issue the **ID** command to receive an identification report, as shown in *Figure 3.5*.

```
=>ID <Enter>

"FID=SEL-787-R100-V0-Z001001-D20080407","0947"
"BFID=BO0TLDR-R303-V0-Z000000-D20060612","0949"
"CID=26FF","0271"
"DEVID=SEL-787","03D0"
"DEVCODE=71","030F"
"PARTNO=0787EX1B0X0X7585023X","073D"
"CONFIG=11111201","03EB"
"iedName =TEMPLATE","0380"
"type =SEL-787","028F"
"configVersion =ICD-787-R100-V0-Z001001-D20080326","0629"

=>
```

Figure 3.5 Device Response to the ID Command

Locate and record the Z number (Z001001) in the FID string. The first portion of the Z number (Z001...) determines the ACSELERATOR QuickSet relay settings driver version when you are creating or editing relay settings files. The use of the Device Editor driver version will be discussed in more detail later in this section—see *Settings Editor (Editor Mode)* on page 3.8. Compare the part number (PARTNO=0787XXXXXXXXXXXXXXX) with the Model Option Table (MOT) to ensure the correct relay configuration.

Settings Database Management and Drivers

ACSELERATOR QuickSet uses a database to save relay settings. ACSELERATOR QuickSet contains sets of all settings files for each relay specified in the Database Manager. Choose appropriate storage backup methods and a secure location for storing database files.

Database Manager

Select **File > Database Manager** on the main menu bar to create new databases and manage records within existing databases.

Settings Database

- Step 1. Open the Database Manager to access the database. Click **File > Database Manager**. A dialog box appears.

The default database file already configured in ACSELERATOR QuickSet is Relay.rdb. This database contains example settings files for the SEL products with which you can use ACSELERATOR QuickSet.

- Step 2. Enter descriptions for the database and for each relay or relay in the database in the **Database Description** and **Settings Description** dialog boxes.

- Step 3. Enter special operating characteristics that describe the relay settings in the **Settings Description** dialog box. These can include the protection scheme settings and communications settings.

- Step 4. Highlight one of the relays listed in **Settings in Database** and select the **Copy** option button to create a new collection of settings.

ACSELERATOR QuickSet prompts for a new name. Be sure to enter a new description in **Settings Description**.

Copy/Move Settings Between Databases

- Step 1. Select the **Copy/Move Settings Between Databases** tab to create multiple databases with the **Database Manager**; these databases are useful for grouping similar protection schemes or geographic areas.

- Step 2. Click the **Open B** option button to open a relay database.

- Step 3. Type a filename and click **Open**.

- Highlight a device or settings file in **Settings Database A**.
- Select **Copy** or **Move**, and click the > button to create a new device or settings file in **Settings Database B**.

- Step 4. Reverse this process to take a device or settings file from **Settings Database B** to **Settings Database A**. **Copy** creates an identical device or settings file that appears in both databases. **Move** removes the device or settings file from one database and places the device or settings file in another database.


Create a New Database, Copy an Existing Database

To create and copy an existing database of devices to a new database:

- Step 1. Click **File > Database Manager**, and select the **New** button. ACSELERATOR QuickSet prompts you for a file name.
- Step 2. Type the new database name (and location if the new location differs from the existing one), and click **Save**. ACSELERATOR QuickSet displays the message `Settings [path and filename] was successfully created`.
- Step 3. Click **OK**.

To copy an exiting database of devices to a new database:

- Step 1. Click **File > Database Manager**, and select the **Copy/Move Settings Between Databases** tab in the **Database Manager** dialog box.

ACSELERATOR QuickSet opens the last active database and assigns it as **Settings Database A**.
- Step 2. Click the **Settings Database B**  button; ACSELERATOR QuickSet prompts you for a file location.
- Step 3. Type a new database name, click the **Open** button.

Settings

ACSELERATOR QuickSet offers the capability of creating settings for one or more SEL-787 relays. Store existing relay settings downloaded from SEL-787 relays with ACSELERATOR QuickSet, creating a library of relay settings, then modify and upload these settings from the settings library to an SEL-787. ACSELERATOR QuickSet makes setting the relay easy and efficient. However, you do not have to use ACSELERATOR QuickSet to configure the SEL-787; you can use an ASCII terminal or a computer running terminal emulation software. ACSELERATOR QuickSet provides the advantages of rules-based settings checks, SELOGIC® control equation Expression Builder, operator control and metering HMI, event analysis, and help.

Settings Editor

The Settings Editor shows the relay settings in easy-to-understand categories. The SEL-787 settings structure makes setting the relay easy and efficient. Settings are grouped logically, and relay elements that are not used in the selected protection scheme are not accessible. For example, if there is only one analog card installed in the relay, you can access settings for this one card only. Settings for the other slots are dimmed (grayed) in the ACSELERATOR QuickSet menus. ACSELERATOR QuickSet shows all of the settings categories in the settings tree view. The settings tree view remains constant whether settings categories are enabled or disabled. However, any disabled settings are dimmed when accessed by clicking an item in the tree view.

Settings Menu

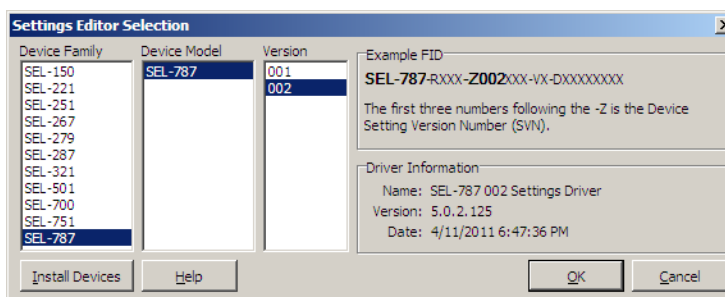
ACSELERATOR QuickSet uses a database to store and manage SEL relay settings. Each unique relay has its own record of settings. Use the **File** menu to **Open** an existing record, create and open a **New** record, or **Read** relay settings from a connected SEL-787 and then create and open a new record. Use **Tools** menu to **Convert** and open an existing record. The record will be opened in the **Setting Editor** as a **Setting Form** (template) or in **Editor Mode**.

Table 3.3 File/Tools Menus

| Menus | Description |
|---------|---|
| <<, >> | Use these navigation menu buttons to move from one category to the next |
| New | Open a New record |
| Open | Open an existing record |
| Read | Read device settings and then create and open a new record |
| Convert | Convert and open an existing record |

File > New

Selecting the **New** menu item creates new settings files. ACSELERATOR QuickSet makes the new settings files from the driver that you specify in the **Settings Editor Selection** dialog box. ACSELERATOR QuickSet uses the Z number in the FID string to create a particular version of settings. To get started making SEL-787 settings with the **Settings Editor** in the **Editor Mode**, select **File > New** from the main menu bar, and SEL-787 and 001 from the **Settings Editor Selection** window as shown in *Figure 3.6*.

**Figure 3.6 Selection of Drivers**

After the relay model and settings driver selection, ACSELERATOR QuickSet presents the **Relay Part Number** dialog box. Use this dialog box to configure the Relay Editor to produce settings for a relay with options determined by the part number, as shown in *Figure 3.7*. Press **OK** when finished.

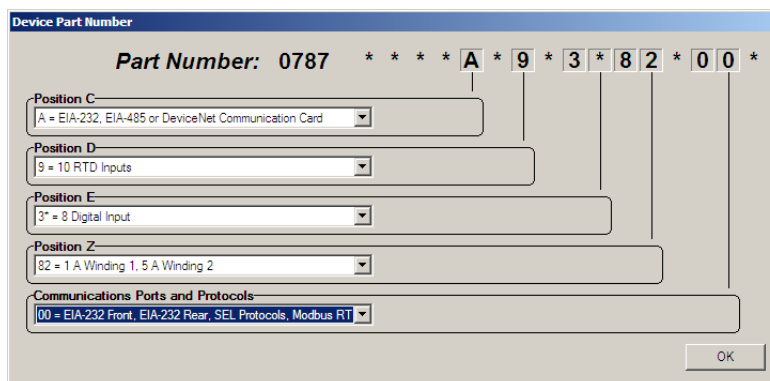
**Figure 3.7 Update Part Number**

Figure 3.8 shows the **Settings Editor** screen. View the bottom of the Settings Editor window to check the **Settings Driver** number. Compare the ACSELERATOR QuickSet Settings Driver number and the first portion of the Z number in the FID string (select **Tools > Meter & Control > Status**). These numbers must match. ACSELERATOR QuickSet uses this first portion of the Z number to determine the correct **Settings Editor** to display.

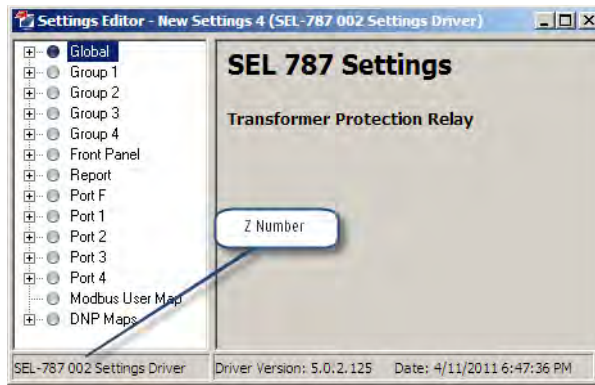


Figure 3.8 New Setting Screen

File > Open

The **Open** menu item opens an existing device from the active database folder. ACSELERATOR QuickSet prompts for a device to load into the **Settings Editor**.

File > Read

When the **Read** menu item is selected, ACSELERATOR QuickSet reads the device settings from a connected device. As ACSELERATOR QuickSet reads the device, a **Transfer Status** window appears. ACSELERATOR QuickSet uses serial protocols to read settings from SEL devices.

Tools > Convert

Use the **Convert** menu item to convert from one settings version to another. Typically, this utility is used to upgrade an existing settings file to a newer version because devices are using a newer version number. ACSELERATOR QuickSet provides a **Convert Settings** report that shows missed, changed, and invalid settings created as a result of the conversion. Review this report to determine whether changes are required.

Settings Editor (Editor Mode)

Use the **Settings Editor (Editor Mode)** to enter settings. These features include the ACSELERATOR QuickSet settings driver version number (the first three digits of the Z number) in the lower left corner of the Settings Editor.

Entering Settings

NOTE: Setting changes made during the edit session are not read by the relay unless they are transferred to the relay with a Send menu item.


- Step 1. Click the + marks and the buttons in the **Settings Tree View** to expand and select the settings you want to change.
- Step 2. Use **Tab** to navigate through the settings, or click on a setting.
- Step 3. To restore the previous value for a setting, right-click the mouse over the setting and select **Previous Value**.
- Step 4. To restore the factory-default setting value, right-click in the setting dialog box and select **Default Value**.
- Step 5. If you enter a setting that is out of range or has an error, ACSELERATOR QuickSet shows the error at the bottom of the **Settings Editor**. Double-click the error listing to go to the setting and enter a valid input.

Expression Builder

NOTE: Be sure to enable the functions you need (Logic Settings > SELogic Enable) before using Expression Builder.

SELOGIC control equations are a powerful means for customizing device performance. ACSELERATOR QuickSet simplifies this process with the Expression Builder, a rules-based editor for programming SELOGIC control equations. The Expression Builder organizes device elements, analog quantities, and SELOGIC control equation variables.

Access the Expression Builder

Use the Ellipsis buttons  in the Settings dialog boxes of **Settings Editor** windows to create expressions, as shown in *Figure 3.9*.

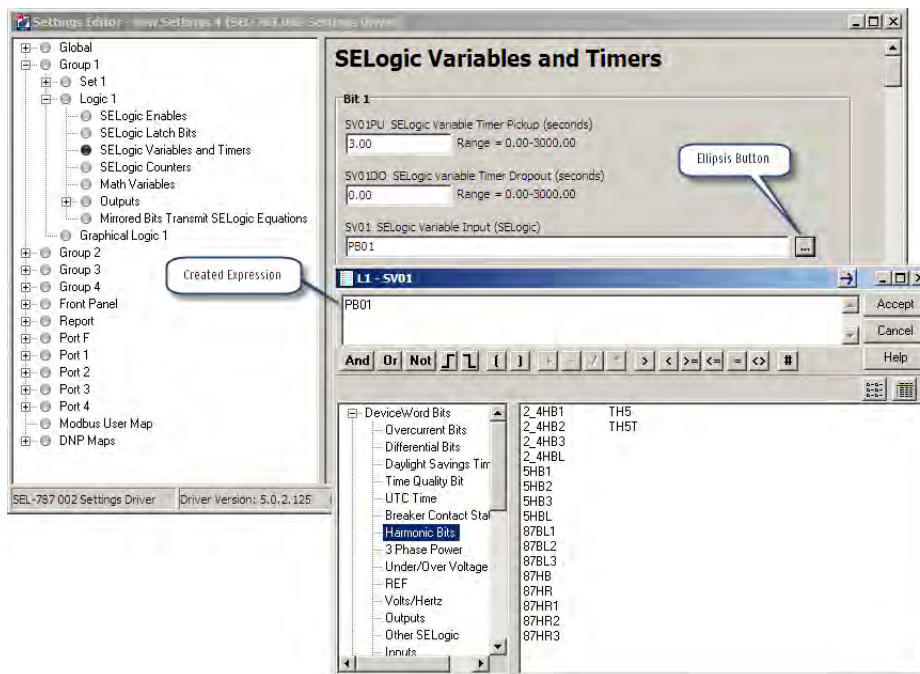


Figure 3.9 Expressions Created With Expression Builder

Expression Builder Organization

The **Expression Builder** dialog box is organized into two main parts representing the left side (LVALUE) and right side (RVALUE) of the SELOGIC control equation. The LVALUE is fixed for all settings.

Using the Expression Builder

Use the right side of the equation (RVALUE) to select broad categories of device elements, analog quantities, counters, timers, latches, and logic variables. Select a category in the RVALUE tree view, and the **Expression Builder** displays all operands for that category in the list box at the bottom right side. Directly underneath the right side of the equation, choose operators to include in the RVALUE. These operators include basic logic, rising- and falling-edge triggers, expression compares, and comments.

File > Save

Select the **Save** menu item from the **File** menu item of the **Settings Editor** once settings are entered into ACSELERATOR QuickSet. This will help ensure the settings are not lost.

File > Send

To transfer the edits made in the ACSELERATOR QuickSet edit session, you must send the settings to the relay. Select **Send** from the **File** menu. In the dialog box that opens, select the settings section you want transferred to the relay by checking the appropriate box.

Edit > Part Number

Use this menu item to change the part number if it was entered incorrectly during an earlier step.

Text Files

Select **Tools > Import** and **Tools > Export** on the ACSELERATOR QuickSet menu bar to import or export settings from or to a text file. Use this feature to create a small file that can be more easily stored or sent electronically.

Event Analysis

ACSELERATOR QuickSet has integrated analysis tools that help you retrieve information about relay operations quickly and easily. Use the event information that the SEL-787 stores to evaluate the performance of a system (select **Tools > Events > Get Event Files**). *Figure 3.10* shows composite screens for retrieving events.

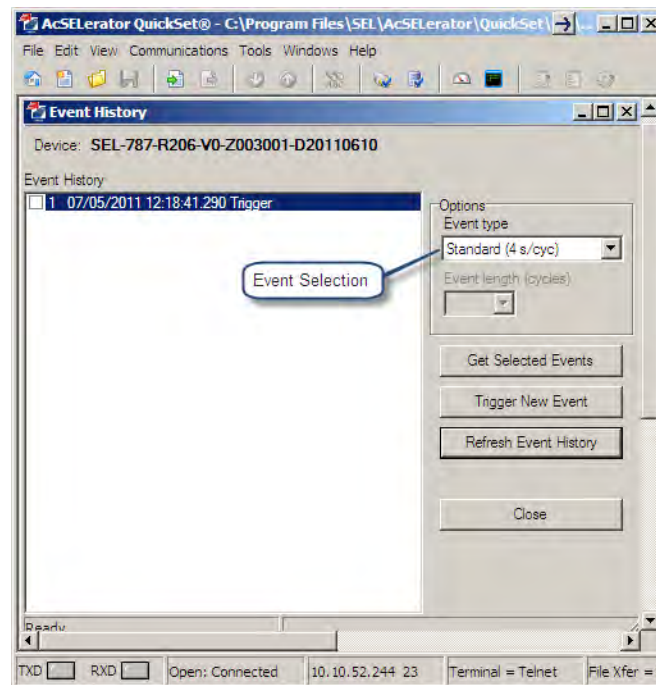


Figure 3.10 Composite Screens for Retrieving Events

Event Waveforms

The relay provides two types of event data captures: event reports that use 4 samples/cycle filtered data and 16 samples/cycle unfiltered (raw) data. See *Section 9: Analyzing Events* for information on recording events. Use the **Options** function in *Figure 3.10* to select the 16 samples/cycle unfiltered (raw) data event (default is 4 samples/cycle filtered data).

View Event History

You can retrieve event files stored in the relay and transfer these files to a computer. For information on the types of event files and data capture, see *Section 9: Analyzing Events*. To download event files from the device, click **Tools > Events > Get Event Files**. The **Event History** dialog box appears, as shown in *Figure 3.10*.

Get Event

Highlight the event you want to view (e.g., Event 3 in *Figure 3.10*), select the event type with the Options Event type function (4 samples or 16 samples), and click the **Get Selected Event** button. When downloading is complete, ACSELERATOR QuickSet queries whether to save the file on your computer, as shown in *Figure 3.11*.

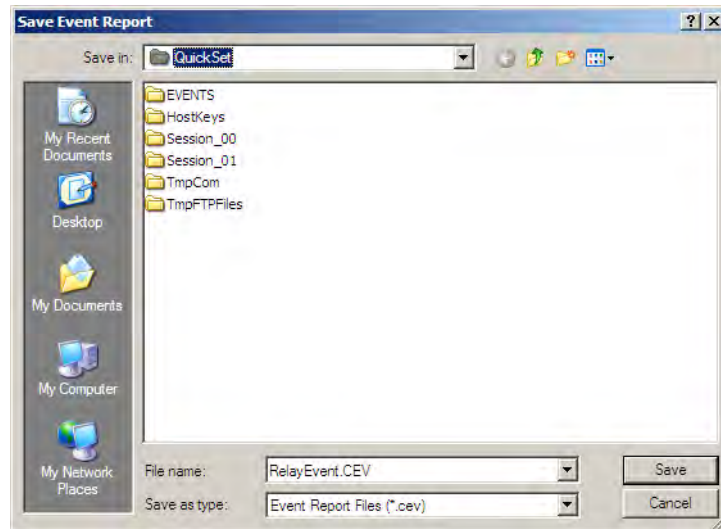


Figure 3.11 Saving the Retrieved Event

Enter a suitable name in the **File name** text box, and select the appropriate location where ACSELERATOR QuickSet should save the event record.

View Event Files

To view the saved events, you need ACSELERATOR Analytic Assistant. Use the **View Event Files** function from the **Tools > Events** menu to select the event you want to view (ACSELERATOR QuickSet remembers the location where you stored the previous event record). Use **View Combined Event Files** to simultaneously view as many as three separate events.

Meter and Control

Click on **Tools > Meter & Control** to bring up the screen shown in *Figure 3.12*. The HMI tree view shows all the functions available from the HMI function. Unlike the self-configuration of the device, the HMI tree remains the same regardless of the type of cards installed. For example, if no Analog Input card is installed, the Analog Input function is still available, but the device responds as follows:

No Analog Input Card Present.

Device Overview

The device overview screen provides an overview of the device. The Contact I/O portion of the window displays the status of the two inputs and three outputs of the main board. You cannot change these assignments.

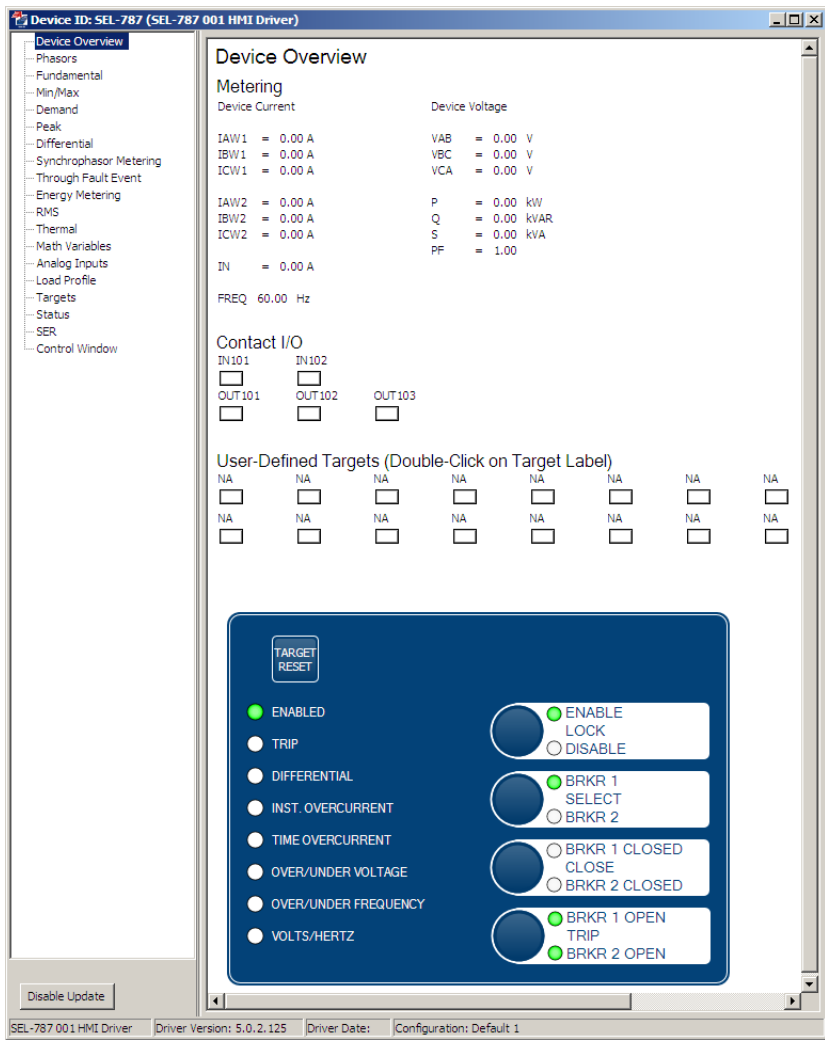


Figure 3.12 Device Overview Screen

You can assign any Relay Word bit to the 16 user-defined target LEDs. To change the present assignment, double-click on the text above the square you want to change. After double-clicking on the text, a box with available Relay Word bits appears in the lower left corner of the screen. Select the appropriate Relay Word bit, and click the **Update** button to assign the Relay Word bit to

the LED. To change the color of the LED, click in the square and make your selection from the color palette.

The front-panel LEDs display the status of the 16 front-panel LEDs. Use the front-panel settings to change the front-panel LED assignment.

The **Phasors**, **Fundamental**, **Min/Max**, etc., screens display the corresponding values.

Click on the **Targets** button to view the status of all the Relay Word bits. When a Relay Word bit has a value of 1 (ENABLED = 1), the Relay Word bit is asserted. Similarly, when a Relay Word bit has a value of 0 (RB02 = 0), the Relay Word bit is deasserted.

The **Status** and **SER** screens display the same information as the ASCII **STA** and **SER** commands.

Figure 3.13 shows the control screen. From here you can clear the Event History, MIRRORED BITS report, SER, trigger events, and reset metering data. You can also reset the targets, synchronize with IRIG, and set the time and date. The Through-Fault Event (TFE) Monitor Pre-load can be entered here also.

Figure 3.13 Control Screen

To control the Remote bits, click on the appropriate square, then select the operation from the box shown in *Figure 3.14*.

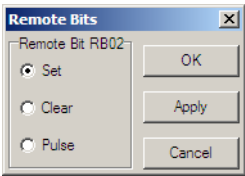


Figure 3.14 Remote Operation Selection

ACSELERATOR QuickSet Help

Various forms of ACSELERATOR QuickSet help are available, as shown in *Table 3.4*. Press <F1> to open a context-sensitive help file with the appropriate topic as the default.

Table 3.4 ACSELERATOR QuickSet Help

| Help | Description |
|------------------------------|---|
| General ACSELERATOR QuickSet | Select Help> Contents from the main menu bar |
| HMI Application | Select Help > HMI Help from the main menu bar. |
| Relay Settings | Select Help > Settings Help from the from the main menu bar. |
| Database Manager | Select Help from the bottom of the Database Manager window. |
| Communications Parameters | Select Help from the bottom of the Communication Parameters window. |

Section 4

Protection and Logic Functions

Overview

NOTE: Each SEL-787 is shipped with default factory settings. Calculate the settings for your application to ensure secure and dependable protection. Document and enter the settings (see Section 6: Settings).

This section describes the SEL-787 Transformer Protection Relay settings, including the protection elements and basic functions, control I/O logic, as well as the settings that control the communications ports and front-panel displays.

This section includes the following subsections:

Application Data. Lists information that you will need to know about the protected equipment before calculating the relay settings.

Group Settings (SET Command). Lists settings that configure the relay inputs to accurately measure and interpret the ac current and optional voltage input signals.

Basic Protection. Lists settings for the differential, optional restricted earth fault, and the overcurrent protection elements.

RTD-Based Protection. Lists settings associated with the RTD inputs. You can skip this subsection if your application does not include RTD inputs.

Voltage-Based Protection. Lists settings associated with the optional ac voltage-based protection elements. You can skip this subsection if your relay is not equipped with optional voltage inputs.

Demand Metering. Lists settings associated with demand metering.

Trip/Close Logic. Lists Trip and Close logic.

Logic Settings (SET L Command). Lists settings associated with latches, timers, and output contacts.

Global Settings (SET G Command). Lists settings that allow you to configure the relay to your power system, date format, analog inputs/outputs, and logic equations of global nature.

Port Settings (SET P Command). Lists settings that configure the relay front and rear ports.

Front-Panel Settings (SET F Command). Lists settings for the front-panel display, pushbuttons, and LED control.

Report Settings (SET R Command). Lists settings for the sequential event reports, event reports, and load profile reports.

DNP Map Settings (SET DNP n Command, n = 1, 2, or 3). Shows DNP user map register settings.

Modbus Map Settings (SET M Command). Shows Modbus® user map register settings.

When you calculate the protection element settings, proceed through the subsections listed earlier. Skip the RTD, voltage-based, and frequency protection subsections if they do not apply to your specific relay model or installation. See *Section 6: Settings* for the list of all settings (*SEL-787 Settings Sheets*) and various methods of accessing them. All current and voltage settings in the SEL-787 are in secondary.

NOTE: The DeviceNet port parameters can only be set at the rear of the relay on the DeviceNet card (see Figure G.1).

You can enter the settings by using the front-panel SET RELAY function (see *Section 8: Front-Panel Operations*), the serial ports (see *Section 7: Communications*), the DeviceNet port (see *Appendix G: DeviceNet Communications*), or the Ethernet port (see *Section 7: Communications*).

Application Data

It is faster and easier for you to calculate settings for the SEL-787 if you collect the following information before you begin:

NOTE: The terms winding and terminal are used interchangeably in this manual.

- Power transformer data: MVA rating, winding configurations and voltages, impedance, etc.
- Highest expected load current
- Current transformer primary and secondary ratings and connections
- System phase rotation and nominal frequency
- Voltage transformer ratios and connections, if used
- Type and location of resistance temperature devices (RTDs), if used
- Expected fault current magnitudes for ground and three-phase faults

Group Settings (SET Command)

ID Settings

All models of the SEL-787 have the identifier settings described in *Table 4.1*.

Table 4.1 Identifier Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------|---------------|------------------------------------|
| UNIT ID LINE 1 | 16 Characters | RID := SEL-787 |
| UNIT ID LINE 2 | 16 Characters | TID := TRNSFRMR RELAY |

The SEL-787 prints the Relay and Terminal Identifier strings at the top of the responses to serial port commands to identify messages from individual relays.

Enter as many as 16 characters, including letters A–Z (not case sensitive), numbers 0–9, periods (.), dashes (-), and spaces. Suggested identifiers include the location or number of the protected transformer.

Configuration Settings

Table 4.2 Configurations and Ratings (Phase CTs, Power Transformer)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------|--|---------------------------------|
| WDG1 CT CONN | DELTA, WYE | W1CT := WYE |
| WDG2 CT CONN | DELTA, WYE | W2CT := WYE |
| WDG1 PHASE CTR | 1–10000 {5 A IW1NOM} 1–50000 {1 A IW1NOM} | CTR1 := 100 |
| WDG2 PHASE CTR | 1–10000 {5 A IW2NOM} 1–50000 {1 A IW2NOM} | CTR2 := 1000 |
| MAX XFMR CAP | OFF, 0.2–5000.0 MVA | MVA := 50.0 |
| DEFINE CT COMP | Y, N | ICOM := N |
| WDG1 CT COMP | 0, 1, ... 12 | W1CTC := 12 |
| WDG2 CT COMP | 0, 1, ... 12 | W2CTC := 12 |
| WDG1 L-L VOLTS | 0.20–1000.00 kV | VWDG1 := 138.00 |
| WDG2 L-L VOLTS | 0.20–1000.00 kV | VWDG2 := 13.80 |

The winding CT connection settings are used to appropriately configure protection (differential, overcurrent, etc.) and power metering functions.

The CT ratio settings configure the relay to accurately scale measured values and report the primary quantities. Calculate the phase and neutral CT ratios by dividing the primary rating by the secondary rating.

EXAMPLE 4.1 Phase CT Ratio Setting Calculations

Consider an application where the Winding 1 CT rating is 600:5 A.

Set CTR1 := 600/5 := 120.

Use the highest expected transformer rating, such as the FOA (Forced Oil and Air cooled) rating or a higher emergency rating, when setting the maximum transformer capacity (MVA).

The ICOM setting defines whether the input currents need any correction, either to accommodate phase shifts in the transformer or CTs or to remove zero-sequence components from the secondary currents. If this setting is Y, the relay permits the user, in the next group of settings, to define the amount of shift needed to properly align the secondary currents for the differential calculation.

The amount of compensation to each set of winding currents is defined by settings W1CTC and W2CTC for Winding 1 and 2 respectively. These settings properly account for phase shifts in transformer winding connections and also in CT connections. For example, this correction is needed if both wye and delta power transformer windings are present, but all of the CTs are connected in wye. The effect of the compensation is to create phase shift and removal of zero-sequence current components.

Set VWDG1 and VWDG2 equal to the nominal line-to-line transformer terminal voltages of Winding 1 and Winding 2 respectively. If the transformer differential zone includes a load tap-changer, assume that it is in the neutral position. The setting units are kilovolts.

Table 4.3 shows additional configuration settings for relay models with optional voltage and/or neutral CT inputs.

Table 4.3 Configurations and Ratings (Optional Neutral CT, Phase PT)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|--|------------------------------------|
| NEUT 1 CT RATIO | 1–10000 { 5 A InNOM} 1–50000 { 1 A InNOM} | CTRN1 := 120 |
| PHASE PT RATIO | 1.00–10000.00 | PTR := 120.00 |
| NOMINAL VOLTAGE | 0.20–10000.00 kV | VNOM := 13.80 |
| PT CONNECTION | DELTA, WYE | DELTA_Y := DELTA |
| VOLT-CURR WDG | 1, 2 | VIWDG := 2 |
| COMP ANGLE | 0–360 Deg | COMPANG := 0 |
| SINGLE V INPUT | Y, N | SINGLEV := N |

Neutral CT ratio setting is used to convert the current input to primary, similar to the phase CT ratio settings.

The remaining settings shown in Table 4.3 configure the optional relay voltage inputs to correctly measure and scale the voltage signals. Set the phase PT ratio (PTR) setting equal to the VT ratio (see Example 4.2 for sample calculations).

EXAMPLE 4.2 Phase VT Ratio Setting Calculations

Consider a 13.8 kV Transformer application where 14400:120 V rated voltage transformers (connected in open delta) are used.

Set PTR := 14400/120 := 120, VNOM := 13.8, and DELTA_Y := DELTA.

VNOM is the rated transformer line-to-line voltage in kV at the protected winding determined by setting VIWDG. Consider the transformer tap when calculating this setting. For example, a 345 kV transformer set on the 327.75 kV TAP would have VNOM := 327.75. VNOM is used by the *Volts Per Hertz Elements* and the *Loss-of-Potential (LOP) Protection*.

When phase-to-phase potentials are connected to the relay, set DELTA_Y to DELTA. When phase-to-neutral potentials are connected to the relay, set DELTA_Y to WYE.

Use the VIWDG setting to tell the relay which winding current to use when calculating power for the meter report. For example, set VIWDG := 2 when the voltage inputs to the relay are derived from Winding 2 side.

COMPANG setting adjusts the power metering to account for angular differences that may be present resulting from delta connected CTs. Set the COMPANG equal to the angle by which the current input lags the corresponding phase voltage input (e.g. IA and VA inputs) at unity power factor.

In applications where only a single voltage is available, set SINGLEV equal to Y. As shown in Figure 2.17, the single voltage must be connected to the A-phase input, but it may be an A-N or an A-B voltage. Be sure to set DELTA_Y equal to WYE for an A-N input or DELTA_Y equal to DELTA for an A-B input voltage.

When you set SINGLEV equal to Y, the relay performance changes in the following ways:

- **Power and Voltage Elements.** When you use one voltage, the relay assumes that the system voltages are balanced in both magnitude and phase angle. Power, power factor, and positive-sequence impedance are calculated assuming balanced voltages.
- **Metering.** When you use one voltage, the relay displays magnitude and phase angle for the measured PT. The relay displays zero for the magnitudes of the unmeasured voltages. Balanced voltages are assumed for power, power factor, VG, and 3V2 metering.

Relays that are not equipped with phase voltage inputs hide these settings and disable voltage-based protection and metering functions.

VNOM Range Check

The relay performs a range check for the VNOM setting that depends upon the voltage-input delta or wye configuration. Valid nominal voltage is 100–250 V secondary (I-I) when DELTA_Y is DELTA; it is 100–440 V when DELTA_Y is WYE.

Note that the VNOM setting is always in line-to-line primary kV, even when set for a wye configuration. You should be careful to use a solidly-grounded wye system for VNOM inputs greater than 250 V (I-I, secondary) to avoid a 1.73 increase in terminal voltages from a line-to-ground fault.

Basic Protection

Differential Element

Application Description

Protect your apparatus with dual-slope percentage differential protection. Percentage differential protection provides more sensitive and secure protection than traditional differential protection; the dual-slope characteristic compensates for steady-state, proportional, and transient differential errors within the zone of protection. Steady-state errors are those that do not vary with loading through the differential zone. These include transformer magnetizing current and unmonitored loads. Proportional errors are those that vary with loading. These include relay measuring error, CT ratio errors, and errors because of tap changing. Transient errors are those that occur temporarily because of transients. A transient caused by CT saturation is an example of how transient errors are introduced.

The relay allows you to choose harmonic blocking, harmonic restraint, or both, providing stability during transformer inrush conditions. Even-numbered harmonics (second and fourth) provide security during energization, while fifth-harmonic blocking provides security for overexcitation conditions.

Operating Characteristic

The SEL-787 has three differential elements (87R-1, 87R-2, and 87R-3). These elements employ Operate (IOP) and Restraint (IRT) quantities that the relay calculates from the winding input current. *Figure 4.1* shows the relay characteristic. You can set the characteristic as either a single-slope,

percentage differential characteristic or as a dual-slope, variable-percentage differential characteristic. Tripping occurs if the Operate quantity is greater than the curve value for the particular restraint quantity. A minimum pickup level for the Operate quantity must also be satisfied.

The four settings that define the characteristic are:

O87P = minimum IOP level required for operation

SLP1 = initial slope, beginning at the origin and intersecting O87P at
 $IRT = O87P \cdot 100 / SLP1$

IRS1 = limit of IRT for SLP1 operation; intersection where SLP2 begins

SLP2 = second slope must be greater than or equal to SLP1

By careful selection of these settings, you can duplicate closely the characteristics of existing differential relays that have been in use for many years.

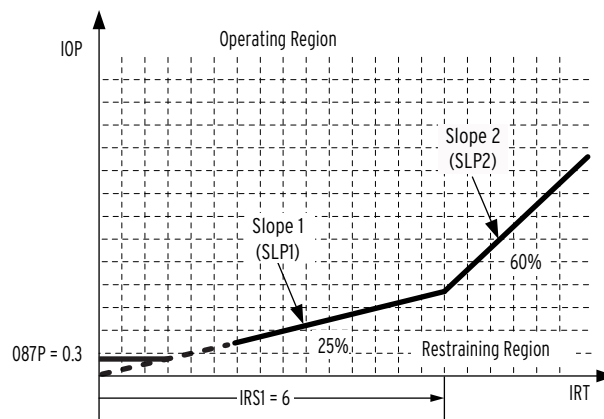


Figure 4.1 Percentage Restraint Differential Characteristic

Figure 4.2, Figure 4.3, and Figure 4.4 illustrate how input currents are acquired and used in the unrestrained and restrained differential elements. Data acquisition, filtering, tap scaling, and transformer and CT connection compensation for Winding 1 are shown in Figure 4.2.

Four digital filters extract the fundamental, second, fourth, and fifth (not shown) harmonics of the input currents.

Using the transformer MVA rating as a common reference point, TAP scaling converts all secondary currents entering the relay from the two windings to per unit values, thus changing the ampere values into dimensionless multiples of TAP. Throughout the text, the term “TAP” refers to the per-unit value common to both windings, whereas “TAP_n” refers to the ampere value of a particular winding(s); TAP_{min} and TAP_{max} refer to the least and greatest of the two TAP_n values. This method ensure that, for full-load through-current conditions, all incoming current multiples of tap sum to 1.0 and all outgoing current multiples of tap sum to –1.0, with a reference direction into the transformer windings.

Transformer and CT connection compensation adjusts the sets of three-phase currents for the phase angle and phase interaction effects introduced by the winding connection of the transformer and CTs. Settings W1CTC and W2CTC determine the mathematical corrections to the three-phase currents for Winding 1 and Winding 2, respectively. CTC1 is shown in Figure 4.2 as the phase angle and sequence quantity adjustment for Winding 1.

I1W1C1, I2W1C1, and I3W1C1 are the fundamental frequency A-phase, B-phase, and C-phase compensated currents for Winding 1. Similarly, I1W1C2, I2W1C2, and I3W1C2 are the second-harmonic compensated currents for Winding 1. The fourth-harmonic and fifth-harmonic compensated currents use similar names. The I1 compensated currents are used with differential element 87-1, I2 with element 87-2, and I3 with element 87-3.

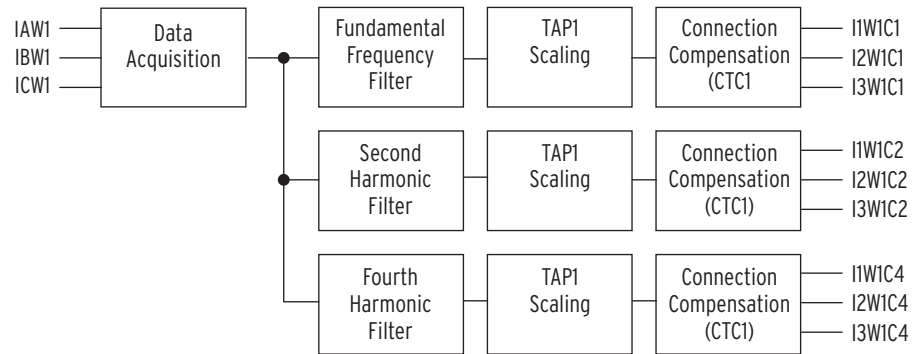


Figure 4.2 Winding 1 Compensated Currents

NOTE: The SEL-787 restraint quantity IRT_n calculation differs from the SEL-587 and SEL-387 by a factor of 2.

Figure 4.3 illustrated how the IOP1 (operate), IRT1 (restraint), I1H24 (harmonic restraint), I1H2 (second harmonic), and I1H4 (fourth harmonic) quantities are calculated for the 87-1 element. IOP1 is generated by summing the winding currents in a phasor addition. IRT1 is generated by summing the magnitudes of the winding currents in a simple scalar addition. The 87-2 and 87-3 quantities are calculated in a similar manner.

For each restraint element (87R-1, 87R-2, 87R-3), the quantities are summed as phasors and the magnitude becomes the Operate quantity (IOP_n). For a through-current condition, IOP_n should calculate to about $1 + (-1) = 0$, at rated load. Calculation of the restraint quantity (IRT_n) occurs through a summation of all current magnitudes. For a through-current condition, this will calculate to about $(|1| + |-1|) = 2$, at rated load.

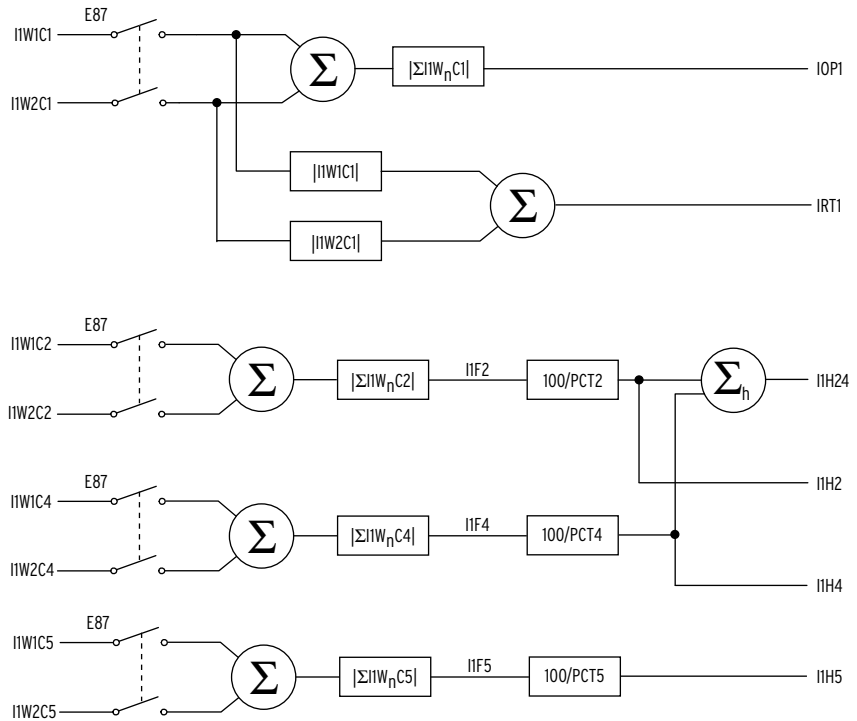


Figure 4.3 Differential Element (87-1) Quantities

Figure 4.4 shows how the differential element quantities are used to generate the unrestrained 87Un (87U1, 87U2, 87U3) and restrained 87Rn/87HRn (87R1, 87R2, 87R3, 87HR1, 87HR2, 87HR3) elements.

Unrestrained elements (87U1, 87U2, and 87U3) compare the IOP quantity to a setting value (U87P), typically about 10 times TAP, and trip if this level is exceeded. Elements 87U1, 87U2, and 87U3 are combined to form element 87U, as shown in the lower left corner of Figure 4.4. Harmonic blocking or restraint is not performed on the unrestrained elements. Use these elements to protect your transformer bushings and end windings while maintaining security for inrush and through-fault conditions. Operating current elements 87On (87O1, 87O2, 87O3) are not available as Relay Word bits.

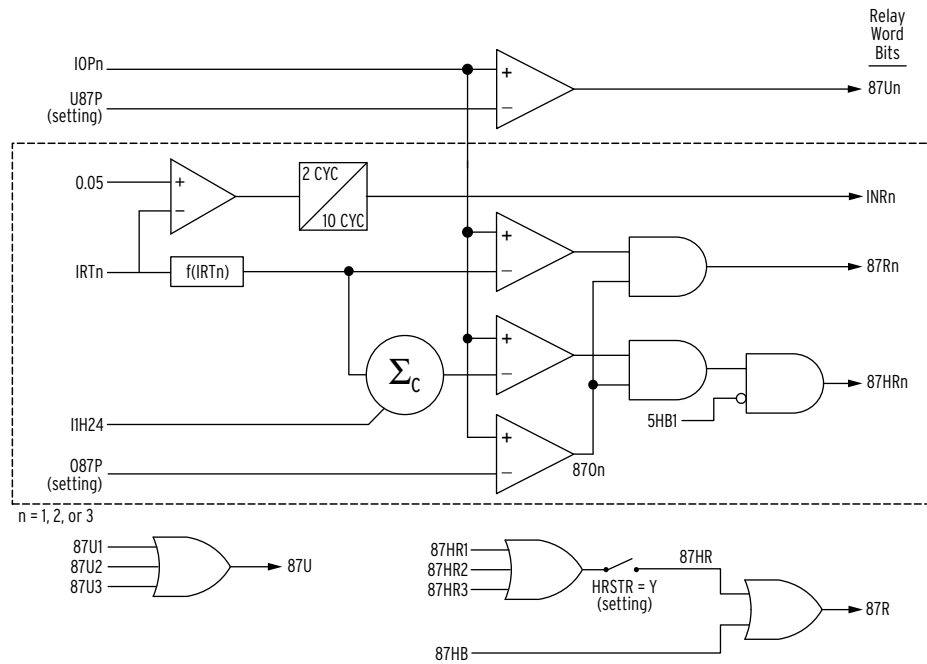


Figure 4.4 Differential Element Decision Logic

Restrained elements (87R1, 87R2, and 87R3) determine whether the IOP quantity is greater than the restraint quantity using the differential characteristic shown in *Figure 4.1*. This characteristic is modified by increasing the restraint current threshold as a function of the second- and fourth-harmonic content in the input currents for the harmonic restraint elements (87HR1, 87HR2, and 87HR3). Set HRSTR = Y to activate the harmonic restraint element 87HR.

In element 87Rn, for example, the IOP_n and IRT_n quantities determine whether the relay trips. The logic enclosed within the dotted line of *Figure 4.4* implements the *Figure 4.1* characteristic. The differential element calculates a threshold as a function of IRT_n . IOP_n must exceed this threshold to assert 87Rn. The function uses the SLP1, SLP2, and IRS1 setting values, along with IRT_n , to calculate the IOP value. The relay uses SLOPE2 in place of SLOPE1 when the Relay Word bit INRn is asserted. This feature provides a high security mode of operation for 10 cycles when the transformer is energized. The differential element decision logic compares the calculated value, denoted $f(IRT_n)$, to the actual IOP_n . If IOP_n is greater, one input of the AND gate at the right receives a logic 1. Comparison of IOP_n with the O87P setting determines the second AND input. If IOP_n is greater than O87P, the bit 87On asserts. The AND gate condition is then satisfied, and Relay Word bit 87Rn asserts, indicating operation of the restrained differential element, n. This does not, as yet, produce a trip. The relay still needs the results of the harmonic blocking decision logic, which is described later.

Harmonic Restraint

Consider the harmonic restraint feature (HRSTR = Y) if your practices require independent harmonic restraint. Blocking features are discussed in more detail later in this section.

For harmonic blocking, the harmonic content of the differential current must exceed the individual (PCT2 or PCT4) threshold values, i.e., the thresholds are treated as independent measurements of each harmonic value. For harmonic restraint, the values of the second- and fourth-harmonic currents are summed,

and that value is used in the relay characteristic. Consider, for example, the simple case of Slope 1, i.e., a straight line through the origin. The general equation for a line is:

$$y = m \cdot x + c$$

More specifically, in the SEL-787:

$$IOP = SLP1 \cdot IRT + c$$

Because the line starts at the origin, the value of c is normally zero. The sum of the second- and fourth-harmonic currents now forms the constant c in the equation, raising the relay characteristic proportionally to the harmonic values.

Harmonic Blocking

While the restrained differential elements are making decisions, a parallel blocking decision process occurs regarding the magnitudes of specific harmonics in the IOP quantities.

Figure 4.5 shows how blocking elements, (87BL1, 87BL2, and 87BL3) supervise the restrained differential elements if the second-, fourth-, or fifth-harmonic operating current is above its set threshold. The blocking prevents improper tripping during transformer inrush or allowable overexcitation conditions. The SEL-787 uses common (cross-phase) blocking. Common blocking prevents all restrained elements (87R n) from tripping if any blocking element is picked up.

However, an independent blocking is used for the fifth-harmonic current. In this logic, an individual element will only disable tripping of that element.

An additional alarm function for fifth harmonic to warn of overexcitation (not shown in Figure 4.5) employs a separate threshold (TH5P) and an adjustable timer (TH5D). This threshold and timer may be useful for transformer applications in or near generating stations.

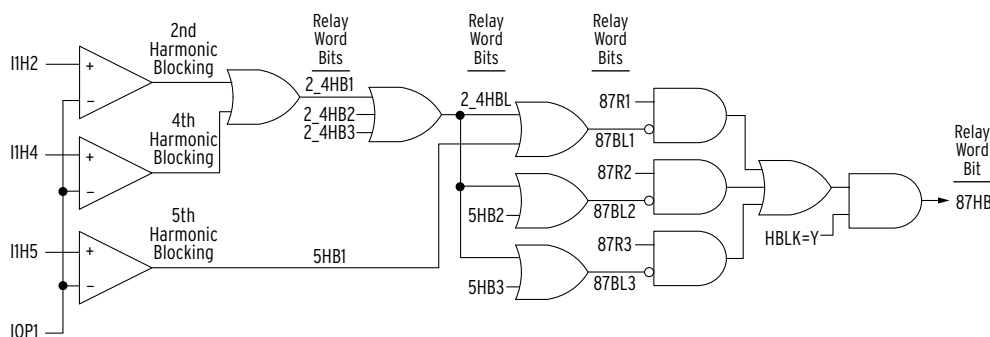


Figure 4.5 Differential Element Harmonic Blocking Logic

Relay Word bits 87R and 87U are high-speed elements that must trip all breakers. The factory default assigns 87R and 87U to trip variable setting TRXFMR. If either bit asserts, this variable asserts bit TRIPXFMR, which drives contact OUT103. OUT103 connects to an 86 lockout device, which trips all breakers via multiple sets of contacts.

Table 4.4 Differential Element Settings (Sheet 1 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------------------|------------------------------------|
| XFMR DIFF ENABLE | Y, N | E87 := Y |
| WDG1 CURR TAP | 0.50–31.00 A ^a | TAP1 := 2.09 |

Table 4.4 Differential Element Settings (Sheet 2 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------------------|------------------------------------|
| WDG2 CURR TAP | 0.50–31.00 A ^a | TAP2 := 2.09 |
| OPERATE CURR LVL | 0.10–1.00 TAP | O87P := 0.30 |
| DIFF CURR AL LVL | OFF, 0.05–1.00 TAP | 87AP := 0.15 |
| DIFF CURR AL DLY | 1.0–120.0 sec | 87AD := 5.0 |
| RESTRAINT SLOPE1 | 5–90 % | SLP1 := 25 |
| RESTRAINT SLOPE2 | 5–90 % | SLP2 := 70 |
| RES SLOPE1 LIMIT | 1.0–20.0 TAP | IRS1 := 6.0 |
| UNRES CURR LVL | 1.0–20.0 TAP | U87P := 10.0 |
| 2ND HARM BLOCK | OFF, 5–100 % | PCT2 := 15 |
| 4TH HARM BLOCK | OFF, 5–100 % | PCT4 := 15 |
| 5TH HARM BLOCK | OFF, 5–100 % | PCT5 := 35 |
| 5TH HARM AL LVL | OFF, 0.02–3.20 TAP | TH5P := OFF |
| 5TH HARM AL DLY | 0.0–120.0 sec | TH5D := 1.0 |
| HARMONIC RESTRNT | Y, N | HRSTR := Y |
| HARMONIC BLOCK | Y, N | HBLK := N |

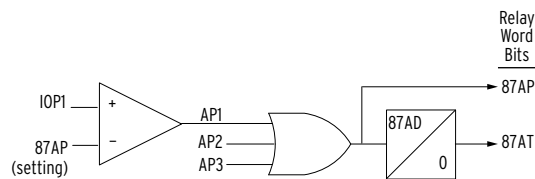
^a Range shown for $I_{NOM} = 5$ A; Range for $I_{NOM} = 1$ A is 0.10–6.20 A.

Selecting Y for E87 enables differential element settings.

When a value is entered in the MVA setting (i.e., MVA is not set to “OFF”), the relay uses the MVA, winding voltage, CT ratio, and CT connection settings (see *Table 4.2*) you have entered and automatically calculates the TAP1 and TAP2 values. You can also directly enter tap values when MVA := OFF. TAP_{MAX}/TAP_{MIN} must be less than or equal to 7.5.

Set the operating current level O87P at a minimum for increased sensitivity (0.2 to 0.3 for transformers and around 1.0 for buses), but high enough to avoid operation because of unmonitored loads and transformer excitation current. $TAP \cdot O87P$ must be greater than or equal to $0.1 \cdot INOM$ for each tap value.

The SEL-787 includes a differential current alarm feature. Set the 87AP level above the highest expected differential current under normal operations (typically lower than O87P) setting) and a security delay 87AD. See *Figure 4.6* for the logic diagram of this feature. Assertion of Relay Word bit 87AT indicates a problem in the differential current circuit (e.g., open CT). You must program the 87AT bit to take appropriate action (alarm, display message, SER, etc.) as desired.

**Figure 4.6 Differential Current Alarm Logic Diagram**

Use the restraint slope percentage settings to discriminate between internal and external faults. Set SLP1 to accommodate current differences from

steady-state and proportional errors such as power transformer tap-changer, CT errors, and relay error. Set SLP2 to accommodate transient error caused by CT saturation.

A two-slope, or variable-percentage differential application, improves sensitivity in the region where CT error is less and increases security in the high-current region where CT error is greater. We must define both slopes, as well as the Slope 1 limit or point IRS1, where SLP1 and SLP2 intersect. If you want a single slope characteristic, set both SLOPE1 and SLOPE2 to the desired slope value.

The purpose of the instantaneous unrestrained current element is to react quickly to very heavy current levels that clearly indicate an internal fault. Set the pickup level U87P to 8 to 10 times tap. The unrestrained differential element only responds to the fundamental frequency component of the differential operating current. It is unaffected by the SLP1, SLP2, IRS1, PCT2, or PCT5 settings. Thus, you must set the element pickup level high enough so as not to react to large inrush currents.

Energization of a transformer causes a temporary large flow of magnetizing inrush current into one terminal of a transformer, without the other terminal seeing this current. Thus, it appears as a differential current that could cause improper relay operation. Magnetizing inrush currents contain greater amounts of even-harmonic current than do fault currents. This even-harmonic current can be used to identify the inrush phenomenon and to prevent relay misoperation. The SEL-787 measures the amount of second-harmonic and fourth-harmonic currents flowing in the transformer. You can set the relay to block the percentage restrained differential element if the ratio of the second-harmonic and/or fourth-harmonic current to fundamental current (IF2/IF1, IF4/IF1) is greater than the PCT2 or PCT4 setting, respectively. Also, the differential element automatically goes into a high security mode for 10 cycles when the transformer is energized, see *Figure 4.4* and the associated description.

According to industry standards (ANSI/IEEE C37.91, C37.102), overexcitation occurs when the ratio of the voltage to frequency (V/Hz) applied to the transformer terminals exceeds 1.05 per unit at full load or 1.1 per unit at no load. Transformer overexcitation produces odd-order harmonics (primarily fifth harmonic), which can appear as differential current to a transformer differential relay. The SEL-787 measures the amount of fifth-harmonic current flowing in the transformer. You can set the relay to block the percentage restrained differential element if the ratio of fifth-harmonic current to fundamental current (IF5/IF1) is greater than the PCT5 setting. Unit-generator step-up transformers at power plants are the primary users of fifth-harmonic blocking. Transformer voltage and generator frequency may vary somewhat during startup, overexciting the transformers.

Fifth-harmonic alarm level and delay settings (TH5P and TH5D) use the presence of fifth-harmonic differential current to assert a Relay Word bit TH5T. This bit indicates that the rated transformer excitation current is exceeded. You may consider triggering an alarm and/or event report if fifth-harmonic current exceeds the fifth-harmonic threshold that you set.

The SEL-787 includes common harmonic blocking (cross-phase blocking) and harmonic restraint logic; you can select either one or both of them. The combination of both logic functions provides optimum differential element operating speed and security. Use the HRSTR = Y setting to enable the harmonic restraint logic and the HBLK = Y setting to enable the harmonic blocking logic.

Common harmonic blocking provides superior security against tripping on magnetizing inrush during transformer energization, yet allows faster differential element tripping for an energized transformer fault. Differential tripping through the harmonic restraint logic is slightly slower, but provides a dependable tripping function when energizing a faulted transformer that might otherwise have the differential tripping element blocked by common harmonic blocking logic.

Differential Element Settings in SEL-787, SEL-387, and SEL-587

The SEL-787 restraint quantity IRT_n calculation differs from the SEL-587 and SEL-387 by a factor of 2. To achieve the same characteristics for the differential elements in the SEL-787, SEL-387, and SEL-587, we must account for this factor of 2. Find below the settings relationships among the three products.

Convert SEL-387 and SEL-587 Relay Settings to the SEL-787 Relay

$$O87P_{787} = O87P_{387/587}$$

$$SLP1_{787} = 1/2 \cdot SLP1_{387/587}$$

$$SLP2_{787} = 1/2 \cdot SLP2_{387/587}$$

$$IRS1_{787} = 2 \cdot IRS1_{387/587}$$

$$U87P_{787} = U87P_{387/587}$$

Convert SEL-787 Relay Settings to the SEL-387 and SEL-587 Relays

$$O87P_{387/587} = O87P_{787}$$

$$SLP1_{387/587} = 2 \cdot SLP1_{787}$$

$$SLP2_{387/587} = 2 \cdot SLP2_{787}$$

$$IRS1_{387/587} = 1/2 \cdot IRS1_{787}$$

$$U87P_{387/587} = U87P_{787}$$

Setting Calculation

General Discussion of Connection Compensation

The general expression for current compensation is as follows:

$$\begin{bmatrix} IAW_nC \\ IBW_nC \\ ICW_nC \end{bmatrix} = [CTC(m)] \cdot \begin{bmatrix} IAW_n \\ IBW_n \\ ICW_n \end{bmatrix}$$

where IAW_n , etc., are the three-phase currents entering terminal “n” of the relay; IAW_nC , etc., are the corresponding phase currents after compensation; and $[CTC(m)]$ is the three-by-three compensation matrix.

Setting $WnCTC = m$ specifies which $[CTC(m)]$ matrix the relay is to use. The setting values are 0, 1, 2, ..., 11, 12. These are discrete values “m” can assume in $[CTC(m)]$; the values physically represent the “m” number of increments of 30 degrees that a balanced set of currents with ABC phase sequence will be rotated in a counterclockwise direction when multiplied by $[CTC(m)]$.

If a balanced set of currents with ACB phase rotation undergoes the same exercise, the rotations by the $[CTC(m)]$ matrices are in the clockwise direction. This is because the compensation matrices, when performing phasor addition or subtraction involving B or C phases, will produce “mirror image” shifts relative to Phase A, when ACB phase rotation is used instead of ABC.

In ACB phase rotation the three phases still rotate in a counterclockwise direction, but C-phase is in the 120-degree lagging position and B-phase leads by 120 degrees, relative to A-phase.

The discussions below assume ABC phase rotation, unless mentioned otherwise.

The “0” setting value is intended to create no changes at all in the currents and merely multiplies them by an identity matrix. Thus, for $WnCTC = 0$,

$$[CTC(0)] \bullet \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

that is,

$$IAWnC = IAWn$$

$$IBWnC = IBWn$$

$$ICWnC = ICWn$$

The “1” setting performs a 30-degree compensation in the counterclockwise direction, as would a delta CT connection of type DAB (30-degree leading). The name for this connection comes from the fact that the polarity end of the A phase CT connects to the nonpolarity end of the B phase CT, and so on, in forming the delta. Thus, for $WnCTC = 1$, the relay uses the following $[CTC(m)]$ matrix:

$$[CTC(1)] = \frac{1}{\sqrt{3}} \bullet \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -1 & 0 & 1 \end{bmatrix}$$

that is,

$$IAWnC = \frac{(IAWn - IBWn)}{\sqrt{3}}$$

$$IBWnC = \frac{(IBWn - ICWn)}{\sqrt{3}}$$

$$ICWnC = \frac{(ICWn - IAWn)}{\sqrt{3}}$$

The “11” setting performs a 330-degree compensation ($11 \bullet 30$) in the counterclockwise direction, or a 30-degree compensation in the clockwise direction, as would a delta CT connection of type DAC (30-degree lagging). The name for this connection comes from the fact that the polarity end of the A phase CT connects to the nonpolarity end of the C phase CT, and so on, in forming the delta. Thus, for $WnCTC = 11$, the relay uses the following $[CTC(m)]$ matrix:

$$[CTC(11)] = \frac{1}{\sqrt{3}} \bullet \begin{bmatrix} 1 & 0 & -1 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

that is,

$$\begin{aligned} IAW_{nC} &= \frac{(IAW_n - ICW_n)}{\sqrt{3}} \\ IBW_{nC} &= \frac{(IBW_n - IAW_n)}{\sqrt{3}} \\ ICW_{nC} &= \frac{(ICW_n - IBW_n)}{\sqrt{3}} \end{aligned}$$

The effect of each compensation on balanced three-phase currents is to rotate them $m \cdot 30^\circ$ without a magnitude change.

The compensation matrix [CTC(12)] is similar to [CTC(0)], in that it produces no phase shift (or, more correctly, 360 degrees of shift) in a balanced set of phasors separated by 120 degrees. However, it removes zero-sequence components from the winding current, as do all of the matrices having nonzero values of m .

$$[CTC(12)] = \frac{1}{3} \cdot \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

that is,

$$\begin{aligned} IAW_{nC} &= \frac{(+2 \cdot IAW_n - IBW_n - ICW_n)}{3} \\ IBW_{nC} &= \frac{(-IAW_n + 2 \cdot IBW_n - ICW_n)}{3} \\ ICW_{nC} &= \frac{(-IAW_n - IBW_n + 2 \cdot ICW_n)}{3} \end{aligned}$$

We could use this type of compensation in applications having wye-connected transformer windings (no phase shift) with wye CT connections for each winding. Using $W_nCTC = 12$ for each winding removes zero-sequence components, just as connection of the CTs in delta would do, but without producing a phase shift. (One might also use $W_nCTC = 1$ or 11 for this same application, yielding compensation similar to that from connection of the CTs on both sides in DAB or DAC.)

The Complete List of Compensation Matrices (m = 1 to 12)

$$\begin{aligned}
 [\text{CTC}(1)] &= \frac{1}{\sqrt{3}} \cdot \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -1 & 0 & 1 \end{bmatrix} & [\text{CTC}(2)] &= \frac{1}{3} \cdot \begin{bmatrix} 1 & -2 & 1 \\ 1 & 1 & -2 \\ -2 & 1 & 1 \end{bmatrix} \\
 [\text{CTC}(3)] &= \frac{1}{\sqrt{3}} \cdot \begin{bmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ -1 & 1 & 0 \end{bmatrix} & [\text{CTC}(4)] &= \frac{1}{3} \cdot \begin{bmatrix} -1 & -1 & 2 \\ 2 & -1 & -1 \\ -1 & 2 & -1 \end{bmatrix} \\
 [\text{CTC}(5)] &= \frac{1}{\sqrt{3}} \cdot \begin{bmatrix} -1 & 0 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix} & [\text{CTC}(6)] &= \frac{1}{3} \cdot \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \\
 [\text{CTC}(7)] &= \frac{1}{\sqrt{3}} \cdot \begin{bmatrix} -1 & 1 & 0 \\ 0 & -1 & 1 \\ 1 & 0 & -1 \end{bmatrix} & [\text{CTC}(8)] &= \frac{1}{3} \cdot \begin{bmatrix} -1 & 2 & -1 \\ -1 & -1 & 2 \\ 2 & -1 & -1 \end{bmatrix} \\
 [\text{CTC}(9)] &= \frac{1}{\sqrt{3}} \cdot \begin{bmatrix} 0 & 1 & -1 \\ -1 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix} & [\text{CTC}(10)] &= \frac{1}{3} \cdot \begin{bmatrix} 1 & 1 & -2 \\ -2 & 1 & -1 \\ 1 & -2 & 1 \end{bmatrix} \\
 [\text{CTC}(11)] &= \frac{1}{\sqrt{3}} \cdot \begin{bmatrix} 1 & 0 & -1 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} & [\text{CTC}(12)] &= \frac{1}{3} \cdot \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}
 \end{aligned}$$

The matrices for odd values of m (1, 3, 5, 7, 9, 11) are similarly constructed, as are the matrices for even values of m (2, 4, 6, 8, 10, 12). Also, $[\text{CTC}(m)]$ equals the minus of $[\text{CTC}(m \pm 6)]$, because these matrices represent shifts separated by exactly 180 degrees.

Selecting the Correct Values of $W_n\text{CTC}$ for Each Winding

The process of choosing the correct $W_n\text{CTC}$ setting value for each winding involves a complete knowledge of the transformer winding connections and phase relationships, the CT connections, and the system phase sequence (ABC or ACB). The following brief review discusses the nature of various connections, their phase shifts, and the reference motion for selection $W_n\text{CTC}$ based on system phase rotation.

Winding Connection Review

Figure 4.7 shows the three basic winding connections, consisting of a wye connection and the two possible delta connections.

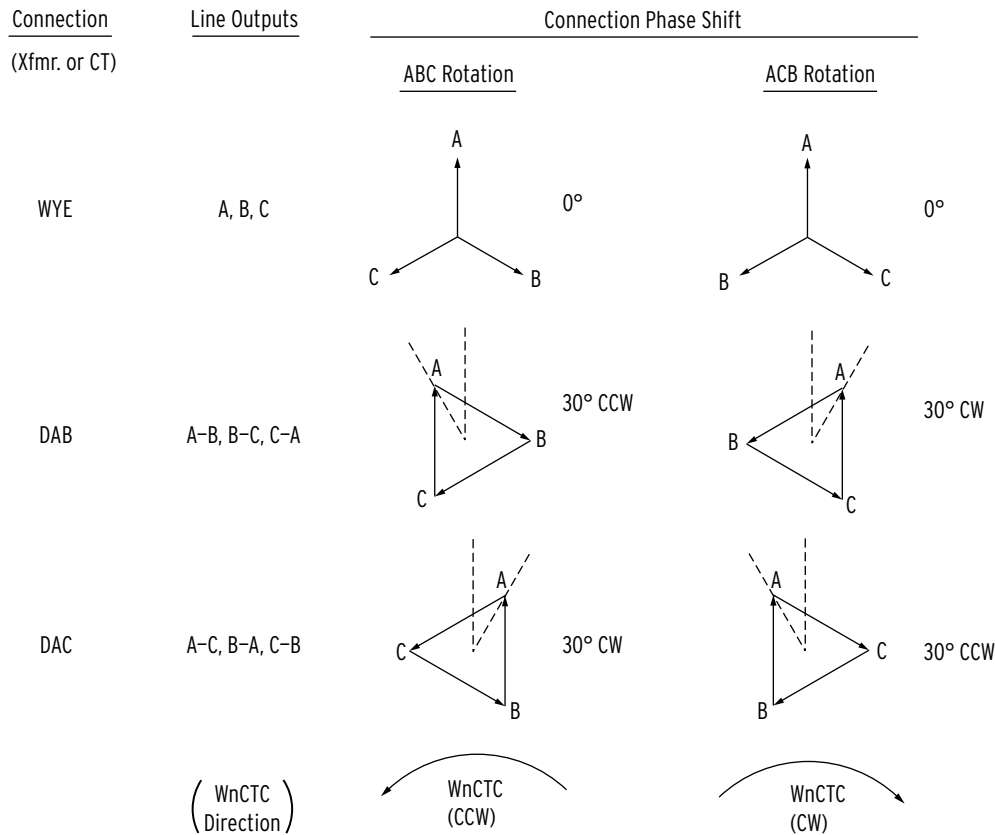


Figure 4.7 Winding Connections, Phase Shifts, and Compensation Direction

The wye connection consists of connecting one end of each winding to a common or neutral point, leaving the other ends of each winding for the line terminals. Because the windings do not interconnect at the line ends, the line current equals the respective winding current, A, B, or C, and no phase shift occurs in the line currents with respect to the winding currents. The neutral point, if it is grounded, permits flow of zero-sequence current components in the windings and line outputs.

There are two possible delta connections. In determining WnCTC, it is essential to know not only that the CTs or transformer windings are connected in delta but in which delta. In this manual we call these delta connections DAB and DAC. In the DAB connection the polarity end of the A winding connects to the nonpolarity end of the B winding, and so on, to produce the delta. In the DAC connection the polarity end of the A winding connects to the nonpolarity end of the C winding, and so on, to produce the delta. In *Figure 4.7*, an arrowhead indicates the polarity end of each winding.

These arrangements involve a connection point between two windings at each line terminal; the line currents are not the same as the winding currents, but are in fact the phasor difference between the associated winding currents. Therefore, the line currents will shift in phase by some amount with respect to the winding currents. In the DAB connection the line currents from the A, B, and C line terminals are, respectively, A-B, B-C, and C-A in terms of the winding currents. In the DAC connection the line currents from the A, B, and C line terminals are, respectively, A-C, B-A, and C-B in terms of the winding currents. The phase shift produced by each physical type of delta depends on the system phase sequence.

NOTE: The terms “lead” and “lag” refer to the assumed counterclockwise (CCW) rotation of the phasors for both ABC and ACB phase rotation. “Lead” implies movement in the CCW direction; “lag” is movement in the clockwise (CW) direction.

In the ABC phase sequence B lags A by 120 degrees and C leads A by 120 degrees. The DAB connection line current at terminal A is A-B, which in this case is a phasor that leads A winding current by 30 degrees. For this reason, DAB is often referred to as the “leading connection.” However, DAB is the leading connection only for ABC phase sequence. In the ACB phase sequence C lags A by 120 degrees, and B leads A by 120 degrees. Terminal A line current is still A-B, but current now lags A winding current by 30 degrees.

The DAC connection produces opposite shifts to DAB. In the ABC phase sequence line current from terminal A is A-C, which lags A winding current by 30 degrees. In the ACB phase sequence line current A is still A-C, but this result leads A winding current by 30 degrees.

Five-Step Compensation Process

The process of determining $WnCTC$ for each winding involves the following five basic steps. Two examples illustrate important points about the five steps. For an additional resource, see the “Winding Compensation Settings Worksheet” (SEL_WCTC_R1_0.xls, available on the SEL-787 Product Literature CD).

- Step 1. Establish the phase direction for the terminal-A line voltage for each three-phase winding of the transformer. (This step requires transformer nameplate drawings and/or internal connection diagrams.)
- Step 2. Adjust the terminal-A line voltage direction for each set of input currents by the phase shift (if any) of the current transformer connection. (Reference *Figure 4.7* for this step.)
- Step 3. Select any one of the adjusted terminal-A directions from *Step 2*, to serve as the reference direction. (The relay compensates all other windings to line up with this reference.)
- Step 4. Choose a setting for $WnCTC$ for each set of winding input currents. This setting is the number of 30-degree increments needed to adjust each nonreference winding to line it up with the reference. This number will range from 0 to 12 increments.
For ABC phase sequence, begin at the winding direction and proceed in a CCW direction until reaching the reference. For ACB phase sequence, begin at the winding direction and proceed in a CW direction until reaching the reference. *Figure 4.7* shows these compensation directions.
- Step 5. If any winding needs no phase correction (zero degrees), but is a grounded-wye winding having wye-connected CTs, choose $WnCTC = 12$ for that winding, rather than $WnCTC = 0$. This setting will remove zero-sequence current components from the relay currents to prevent false differential tripping on external ground faults. (All non-zero values of $WnCTC$ remove zero-sequence current.)

Example 1 for $WnCTC$ Selection

Figure 4.8 illustrates the first example. This is a two-winding transformer with a DAB delta primary and secondary connected in grounded wye. The secondary winding has DAB delta-connected CTs. We assume ABC phase rotation. Using the “hour of the clock” convention for specifying transformer connections, the transformer is a “Dy1” connection. This means the transformer has a high-voltage delta whose reference is “noon” and a wye

secondary winding whose direction is at “one o’clock” with respect to the direction of the delta. The CT currents go to relay winding inputs 1 and 2 from left to right as *Figure 4.8* illustrates.

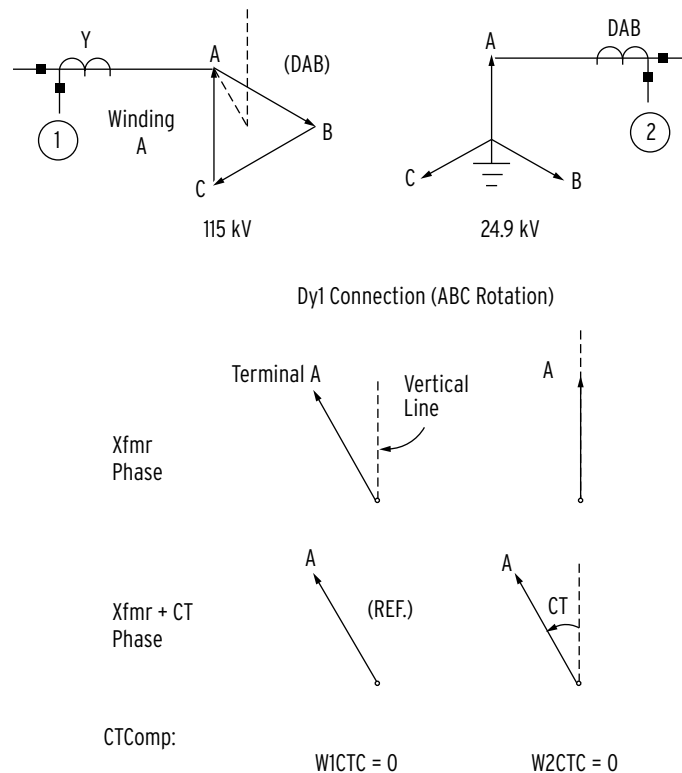


Figure 4.8 Example 1 for WnCTC Selection

The 115 kV delta primary and the 24.9 kV grounded-wye secondary represent a traditional “DAB Y” two-winding application. This application has wye CTs on the delta side and delta CTs on the wye side, using the same CT delta connection as the primary of the transformer. Perform the following simple steps to handle these traditional connections.

- Step 1. Establish the line terminal directions.

Refer to the line following the transformer drawings in *Figure 4.8* and note that the delta winding A line terminal direction is at 30 degrees CCW from the A winding direction (vertical), as we would expect for a DAB connection with ABC phase rotation. The A winding of the 24.9 kV winding is vertical.

- Step 2. Adjust the CT connections.

In this case, the primary winding with wye CTs need no adjustment. The 24.9 kV winding, with DAB CTs, needs a 30-degree correction in the CCW direction. *Figure 4.8* shows this adjustment in the second line under the transformer drawings.

- Step 3. Select a reference direction for the transformer.

You can use either one of the two winding directions as the reference, but this need not be the case. You could establish any of the 12 possible directions, separated by 30 degrees around with complete circle of 360 degrees, as the reference. Both

windings would then receive adjustments to correlate them with this reference. As *Figure 4.8* illustrates, the primary winding direction serves as reference in this example.

Step 4. Choose the $WnCTC$ settings for the windings.

Because Winding 1 is the reference, we need no adjustment; the setting is $W1CTC = 0$. Note that the adjusted Winding 2 inputs coincide exactly with the reference direction; we need make no adjustment for the 24.9 kV winding either. Therefore, the setting is $W2CTC = 0$. As mentioned earlier, these two windings represent a classical DABY application. We can see this from the fact that the $WnCTC$ setting is zero for both windings. The CT connections themselves perform exactly the right correction without additional help from the relay. The process is nearly complete.

Step 5. As a final step, ensure that no wye-connected winding having wye-connected CTs is set at $WnCTC = 0$ (uncompensated).

Were this the case, zero-sequence currents could appear in these relay inputs but in no others, and a possible false trip could occur for external ground faults. Any non-zero value of $WnCTC$ will eliminate the zero-sequence. In this example there is no wye-connected winding with wye-connected CTs. The selection is complete. The relay receives the settings as $W1CTC = 0$ and $W2CTC = 0$ (alternately, you can set $ICOM := N$ because no compensation is required from the relay).

Example 2 for $WnCTC$ Selection

Figure 4.9 illustrates the second example. This is another two-winding transformer, for which we have chosen rather unusual winding phase relationships in order to show the flexibility of the winding compensation feature in the SEL-787.

The transformer has a 115 kV primary winding that is wye connected, with wye-connected CTs. The 34.5 kV secondary winding is DAB connected, but designated with the A line terminal at the “7 o’clock” position with respect to the primary A line terminal. It has wye-connected CTs. This transformer is therefore a “Yd7” connection type. We assume ABC phase rotation. The CT currents go to relay winding inputs 1 and 2 from left to right as *Figure 4.9* shows.

Step 1. Establish the phase direction for the three A line terminals.

Figure 4.9 shows these phase directions in the first line below the transformer drawing. Based on the transformer designation, the terminal direction are shown at “noon” and “7 o’clock.”

Step 2. Adjust the transformer winding directions based on the CT connections. Neither windings need correction, because they both have wye-connected CTs.

Step 3. Select a reference direction. In this example we have chosen the delta secondary winding as reference.

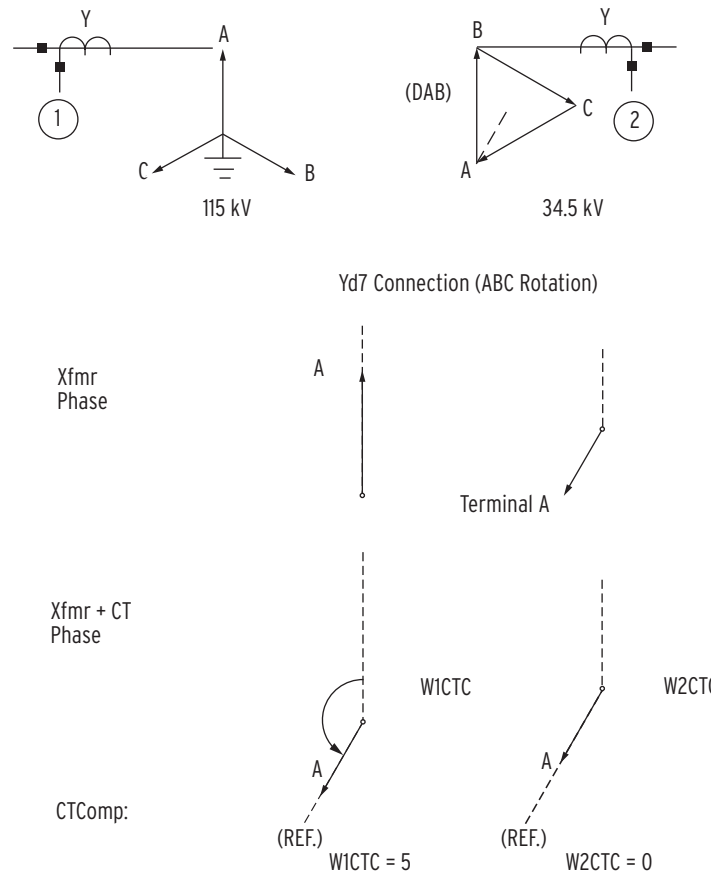


Figure 4.9 Example 2 for WnCTC Selection

Step 4. Select values of $WnCTC$ for each winding.

We have selected $W2CTC = 0$ as the setting for Winding 2, the reference winding. Beginning with Winding 1 at “noon,” adjust the Winding 1 position in the CCW direction until arrival at the “7 o’clock” reference direction. This procedure requires five 30-degree increments, or five “hours” of adjustment. Thus, we choose $W1CTC = 5$ as the setting.

Step 5. Ensure that there will be no wye windings with wye CTs and a setting of $WnCTC = 0$. In this case, the primary winding is wye-connected and has wye-connected CTs.

In *Step 4*, because we chose the delta winding as reference, we were able to set $W2CTC$ at zero. This allowed the wye winding to be delta compensated using Matrix 5.

The process is now complete. The relay receives the two settings as $W1CTC = 5$ and $W2CTC = 0$.

Winding Line-to-Line Voltages

Enter the nominal line-to-line transformer terminal voltages. If a load tap changer is included in the transformer differential zone, assume that it is in the neutral position. The setting units are kilovolts.

Current TAP

The relay uses a standard equation to set TAP_n , based on settings entered for the particular winding (n denotes the winding number.)

$$TAP_n = \frac{MVA \bullet 1000}{\sqrt{3} \bullet VWDG \bullet CTR_n} \bullet C$$

where:

- $C = 1$ if $WnCT$ setting = Y (wye-connected CTs)
- $C = \sqrt{3}$ if $WnCT$ setting = D (delta-connected CTs)
- MVA = maximum power transformer capacity setting (must be the same for all TAP_n calculations)
- $VWDG_n$ = winding line-to-line voltage setting, in kV
- CTR_n = current transformer ratio setting

The relay calculates TAP_n with the following limitations:

- The tap settings are within the range $0.1 \bullet I_{NOMn}$ and $6.2 \bullet I_{NOMn}$
- The ratio $TAP_{MAX}/TAP_{MIN} \leq 7.5$

Restrained Element Operating Current Pickup

The O87P setting range is 0.1 to 1.0; we suggest an O87P setting of 0.2 to 0.3. The setting must be at a minimum for increased sensitivity but high enough to avoid operation because of steady-state errors such as unmonitored station service loads, transformer excitation current, and relay measuring error at very low current levels. The setting must also yield an operating current greater than or equal to $0.1 \bullet I_{NOM}$, when multiplied by the smallest of TAP_1 and TAP_2 . Stated another way,

$$O87P_{MIN} \geq (0.1 \bullet I_{NOM}) / TAP_{MIN}$$

The above restriction applies to each winding sides (irrespective of TAP magnitudes) when 1A and 5A nominal CTs are used in the same relay.

Restraint Slope Percentage

The purpose of the percentage restraint characteristic is to allow the relay to differentiate between differential current from an internal fault versus differential current during normal or external fault conditions. You must select slope characteristic settings that balance security and dependability. To do this, it is helpful to determine what slope ratio is characteristic of normal conditions (slope must exceed that for security) and what slope ratio is characteristic of an internal fault (the slope must be below that for dependability). In the case of the SEL-787 Relay, the slope ratio for a bolted internal fault is 100%.

The sources of differential current for external faults fall into three categories:

- Differential current that is not proportional to the current flow through the zone (steady state).
- Differential current that is proportional to current flow through the zone (proportional).
- Differential current that is transient in nature (transient).

SLP1 should be set above normal steady-state and proportional errors. SLP2 is used to accommodate transient errors. The following is a list of typical sources of error that must be considered.

- Excitation current (typically 1 to 4%)
- CT accuracy (typically less than 3% in the nominal range)
- No-Load Tap Changer (NLTC) (typically $\pm 5\%$)
- Load Tap-Changer (LTC) (typically $\pm 10\%$)
- Relay accuracy (± 5 percent or $\pm 0.02 \cdot I_{\text{NOM}}$, whichever is largest.)

We recognize that the excitation current of the transformer is not proportional to load flow. However, a conservative approach would include it as a proportional error.

CTs create both steady-state and transient errors, which can result in false differential current. IEEE Standard Requirements for Instrument Transformers, IEEE Standard C57.13-1993 specifies that a relay-accuracy CT must be 3 percent accurate at rated current and 10 percent accurate at 20 times rated current when ZB is the standard burden. It is important to note that the rated current specified in the standard is a symmetrical sinusoidal waveform (it does not have a transient DC component). Because the burden is usually designed to be much smaller than the standard burden, the error current will likely be much less than 3 percent for current flow at low multiples of the nominal rating of the CTs.

The errors can be added to determine the amount of error that the SLP1 characteristic must accommodate for normal system conditions. At that point, use the following equation and add margin to determine SLP1 and determine the minimum limit of the allowable slope ratio.

$$\text{SLP1}_{\text{MIN}}\% = \left(\frac{\text{Err}\%}{(200 - \text{Err}\%) \cdot k} \right) \cdot 100$$

where:

SLP1_{MIN} = slope ratio that will just accommodate Err with no margin

Err = amount of error expected in normal operation

k = AVERAGE restraint scaling factor (1 for the SEL-787)

The variable restraint characteristic provided by SLP2 at high multiples of TAP for a through fault accommodates transient CT error. SLP2 can be set fairly high without jeopardizing sensitivity for low-grade partial winding faults. The CTs should be evaluated for the likelihood of going into saturation for a through fault, and SLP2 should be adjusted accordingly. Another consideration for selecting the SLP2 setting is that the effectiveness of the variable percentage depends on SLP1 and IRS1, which determine the starting point of SLP2. If SLP1 is set very low, a higher SLP2 may be warranted.

Unrestrained Element Current Pickup

The instantaneous unrestrained current element is intended to react quickly to very heavy current levels that clearly indicate an internal fault. Set the pickup level (U87P) to approximately 8 to 10 times TAP. The unrestrained differential element only responds to the fundamental frequency component of the differential operating current. It is not affected by the SLP1, SLP2, IRS1, PCT2, or PCT5 settings. Thus, it must be set high enough so as not to react to large inrush currents.

Note that U87P must be set lower than $31 \cdot I_{nom}/TAP_{max}$, where TAP_{max} is the largest of the TAP settings.

Second-Harmonic Blocking

Transformer simulations show that magnetizing inrush current usually yields more than 30 percent of IF2/IF1 in the first cycle of the inrush. A setting of 15 percent usually provides a margin for security. However, some types of transformers, or the presence within the differential zone of equipment that draws a fundamental current of its own, may require setting the threshold as low as 7 percent. For example, the additional fundamental frequency charging current of a long cable run on the transformer secondary terminals could “dilute” the level of second harmonic seen at the primary to less than 15 percent.

Fourth-Harmonic Blocking

Transformer magnetizing inrush currents are generated during transformer energization when the current contains a dc offset due to point-on-wave switching. Inrush conditions typically are detected using even harmonics and are used to prevent misoperations due to inrush. The largest even-harmonic current component is usually second harmonic followed by fourth harmonic. Use fourth-harmonic blocking to provide additional security against inrush conditions; set PCT4 less than PCT2.

Fifth-Harmonic Blocking

Fourier analysis of transformer currents during overexcitation indicates that a 35 percent fifth-harmonic setting is adequate to block the percentage differential element. To disable fifth-harmonic blocking, set PCT5 to OFF.

You may use the presence of fifth-harmonic differential current to assert an alarm output during startup. This alarm indicates that the rated transformer excitation current is exceeded. At full load, a TH5P setting of 0.1 corresponds to 10 percent of the fundamental current. A delay, TH5D, that you can set prevents the relay from indicating transient presence of fifth-harmonic currents.

You may consider triggering an event report if transformer excitation current exceeds the fifth-harmonic threshold.

There are two criteria for setting TH5P:

$$TH5P \cdot TAP_n \geq 0.05 \cdot I_{nom}$$

where:

$$n = 1, 2 \text{ and } I_{nom} \text{ is nominal current of corresponding CT}$$

Example of Setting the SEL-787 Relay

The example represents a typical transformer application and demonstrates the use of CT compensation settings and tap calculations.

Figure 2.19 illustrates the application. The transformer is a 138 kV to 13.8 kV. The transformer has a maximum rating of 30 MVA. Both windings have wye-connected current transformers, with ratios of 200/5 A at 138 kV, and 2000/5 A at 13.8 kV. We have connected the transformer per IEEE standards, with the low voltage delta lagging the high-voltage wye by 30 degrees.

Step 1. Enable the differential settings as follows:

$$E87 := Y$$

Step 2. Select settings for the current transformer connection and ratio for each winding.

All CTs connect in wye. The ratios are equal to primary current divided by secondary current. The settings are as follows:

| 138 kV | 13.8 kV |
|---------------|----------------|
| W1CT = WYE | W2CT = WYE |
| CTR1 = 40 | CTR2 = 400 |

Step 3. SSet the transformer maximum rating.

We use this rating for all windings in the later tap calculation:

$$MVA = 30$$

Step 4. Decide whether to use internal CT compensation and determine compensation settings.

Because there are both wye and delta transformer windings but only wye CTs, we must adjust for the phase angle shift. In the “traditional” differential relay connection the wye transformer windings would have their CTs connected in delta to produce a shift in the same direction as that produced in the transformer. In this case a “DAC” or “30-degree lagging” connection would have been used. This would not only shift the currents, but it would remove the zero-sequence current component by physically subtracting the appropriate phase currents via the delta connection. We achieve the same effect within the relay by using the selected compensation. The settings are:

$$ICOM = Y \text{ (choose to define the CT compensation)}$$

$$W1CTC = 11 \text{ } W2CTC = 0$$

The relay will multiply the wye CT currents from the wye transformer windings by the matrix [CTC(11)] to give the same results as the physical DAC CT connection.

Step 5. Enter winding line-to-line voltages.

The relay needs these voltages for the tap calculation. Voltages are in units of kV. For this example we enter the following values:

$$VWDG1 = 138 \qquad VWDG2 = 13.8$$

The relay now calculates each tap current, using the formula stated previously:

$$TAP_n = \frac{MVA \bullet 1000}{\sqrt{3} \bullet VWDG_n \bullet CTR_n} \bullet C$$

where

$$C = 1 \text{ for wye CTs}$$

Thus, we have the following:

$$TAP1 = \frac{30MVA \bullet 1000}{\sqrt{3} \bullet 138kV \bullet 40}$$

$$TAP1 = 3.14$$

$$TAP2 = \frac{30MVA \bullet 1000}{\sqrt{3} \bullet 13.8kV \bullet 400}$$

$$TAP2 = 3.14$$

The relay calculates these taps automatically if MVA is given. If MVA is set to OFF, you must calculate the taps and enter them individually.

The relay will check to see if a violation of the maximum tap ratio has occurred, and will notify you of the violation.

- Step 6. Set the differential element characteristic. Select the settings according to our suggestions in the earlier setting descriptions.

For this example, we have selected a two slope, variable-percentage differential characteristic for maximum sensitivity at low currents and greater tolerance for CT saturation on external high-current faults.

The minimum error for selecting SLP1 for this application is determined as follows:

- Excitation current (4%)
- CT accuracy (3%)
- No-Load Tap Changer (NLTC) (5%)
- Load Tap-Changer (LTC) (0%)
- Relay accuracy (± 5 percent or $\pm 0.02 \cdot I_{NOM}$, whichever is largest) (5%)

$$SLP1_{MIN}\% = \left(\frac{17}{(200 - 17)} \right) \cdot 100 = 9.3\%$$

The CTs have been evaluated for maximum through fault and found to be unlikely to saturate severely. So, SLP2 does not have to be set higher than normal.

The settings are as follows:

- O87P = 0.3 (Operate current pickup in multiple of tap)
- SLP1 = 15 (15 percent initial slope)
- SLP2 = 50 (50 percent second slope)
- IRS1 = 6.0 (limit of Slope 1, Restraint current in multiple of tap)
- U87P = 10 (unrestrained differential Operate current level, multiple of tap)
- PCT4 = 15 (block operation if fourth harmonic is above 15 percent)
- PCT5 = 35 (block operation if fifth harmonic is above 35 percent)
- TH5P = OFF (no fifth-harmonic alarm)
- HRSTR = Y (harmonic restraint enabled)
- HBLK = Y (harmonic blocking enabled)

Remember that the O87P setting must yield an operating current value of at least $0.1 \cdot I_{NOM}$, at the least tap. In this case $O87P_{MIN} = (0.1 \cdot I_{NOM}) / TAP_{MIN} = 0.5 / 3.14 = 0.159$. Therefore, the O87P setting of 0.3 is valid.

The differential unit settings are complete for this specific application. At this point you can also choose to set backup overcurrent elements which we discuss at the end of this section.

Application Guidelines

It is vital that you select adequate current transformers for a transformer differential application. Use the following procedure, based on ANSI/IEEE Standard C37.110: 1996, *IEEE Guide for the Application of Current Transformers Used for Protective Relaying Purposes*.

CT Arrangements

Use separate relay restraint circuits for each power source to the relay. In the SEL-787 you may apply two restraint inputs to the relay. You may connect CT secondary windings in parallel only if both circuits meet the following criteria:

- They are connected at the same voltage level.
- Both have CTs that are matched in ratio and C voltage ratings.
- Both circuits are radial (no fault current contributions).

CT Sizing

Sizing a CT to avoid saturation for the maximum asymmetrical fault current is ideal but not always possible. Such sizing requires CTs with C voltage ratings greater than $(1 + X/R)$ times the burden voltage for the maximum symmetrical fault current, where X/R is the reactance-to-resistance ratio of the primary system.

As a rule of thumb, CT performance will be satisfactory if the CT secondary maximum symmetrical external fault current multiplied by the total secondary burden in ohms is less than half of the C voltage rating of the CT. The following CT selection procedure uses this second guideline.

CT Ratio Selection

- Step 1. Determine the secondary side burdens in ohms for all current transformers connected to the relay.
- Step 2. Select the CT ratio, considering the maximum continuous secondary current, I_{HS} , based on the highest MVA rating of the transformer.

For wye-connected CTs, the relay current, I_{REL} , equals I_{HS} . For delta-connected CTs, I_{REL} equals $\sqrt{3} \cdot I_{HS}$. Select the nearest standard ratio such that I_{REL} is between $0.1 \cdot I_{NOM}$ and $1.0 \cdot I_{NOM}$ A secondary, where I_{NOM} is the relay nominal secondary current, 1 A or 5 A.

- Step 3. Select the remaining CT ratios (e.g., CTR2) by considering the maximum continuous secondary current, I_{LS} .

As before, for wye-connected CTs I_{REL} equals I_{LS} . For delta-connected CTs I_{REL} equals $\sqrt{3} \cdot I_{LS}$. Select the nearest standard ratio such that I_{REL} is between $0.1 \cdot I_{NOM}$ and $1.0 \cdot I_{NOM}$ A secondary.

The SEL-787 calculates settings TAP1 and TAP2 if the ratio TAP_{MAX}/TAP_{MIN} is less than or equal to 7.5. When the relay calculates the tap settings, it reduces CT mismatch to less than 1 percent. Allowable tap settings are in the range $(0.1-6.2) \cdot I_{NOM}$.

If the ratio TAP_{MAX}/TAP_{MIN} is greater than 7.5, select a different CT ratio to meet the above conditions. You can often do this by selecting a higher CT ratio for the smallest rated winding, but you may need to apply auxiliary CTs to achieve the required ratio. In this case, repeat Step 2 and Step 3.

Step 4. Calculate the maximum symmetrical fault current for an external fault, and verify that the CT secondary currents do not exceed your utility standard maximum allowed CT current, typically $20 \cdot I_{NOM}$. If necessary, reselect the CT ratios and repeat Step 2 through Step 4.

Step 5. For each CT, multiply the burdens calculated in Step 1 by the magnitude, in secondary amperes, of the expected maximum symmetrical fault current for an external fault. Select a nominal accuracy class voltage for each CT that is greater than twice the calculated voltage.

If necessary, select a higher CT ratio to meet this requirement, then repeat Step 2 through Step 5. This selection criterion helps reduce the likelihood of CT saturation for a fully offset fault current signal.

Please note that the effective C voltage rating of a CT is lower than the nameplate rating if a tap other than the maximum is used. Derate the CT C voltage rating by a factor of ratio used/ratio max.

Restricted Earth Fault Element

Restricted earth-fault (REF) protection comes from a zero-sequence directional element that provides sensitive detection of ground faults near the neutral of a grounded wye-connected transformer winding. To provide REF protection, the element compares the direction of a polarizing current, derived from the line-end CTs, with the operating current, obtained from the neutral CT. Figure 4.10 shows the characteristic of the REF element, with the shaded area indicating the tripping area.

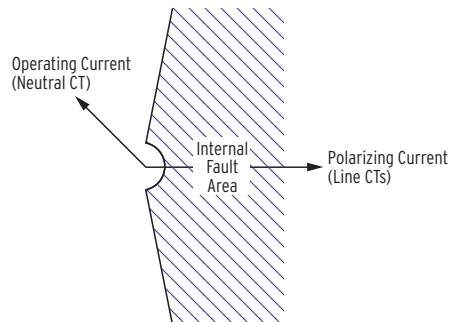


Figure 4.10 REF Directional Element

Because the REF element employs a neutral CT at one end of the winding and a set of three CTs at the line end of the winding, REF protection can detect only ground faults within that particular wye-connected winding. The element is restricted in the sense that protection is limited to ground faults within a zone defined by neutral and line CT placement.

The REF element uses comparison of zero-sequence currents, so the line-end CTs must be connected in wye for the element to function. Delta-connected CTs cancel out all zero-sequence components of the currents, eliminating one of the quantities the REF element needs for comparison.

The SEL-787 has one REF element, REF1. The settings are identified in Table 4.5. The operating quantity associated with the REF1 element is tied to the relay input IN1 (E09–E10) as identified in Table 2.5.

Figure 4.11 through Figure 4.14 show the REF1 element logic diagrams. Figure 4.11 shows the REF1 element enable output, REF1E. The operating quantity is the output current from the neutral CT connected to the relay input

IN1 (E09–E10). The polarizing quantity is the zero-sequence current from the selected terminal CTs that are part of the scheme. Both the operating and polarizing currents are normalized for use within the logic. The normalization, as shown in *Figure 4.12*, is explained later.

The comparator C1 compares the magnitude of the normalized IN1 value, defined as INWPU1, against the 50REF1P setting and asserts 50NREF1 if the measured quantity exceeds the threshold. Comparator C2 compares 0.8 of the 50REF1P setting value against the magnitude of the normalized polarizing current, IGWPU1, and asserts 50GREF1 if the measured quantity exceeds the threshold. The 0.8 multiplier secures the operation of the REFF1 element by ensuring that 50GREF1 always asserts before 50NREF1. If 50NREF1, 50GREF1, and the SELOGIC torque control, REF1TC, all evaluate to logical 1, then the output REF1E is asserted. When REF1E asserts, the relay enables the logic that performs the directional calculations as shown in *Figure 4.12*.

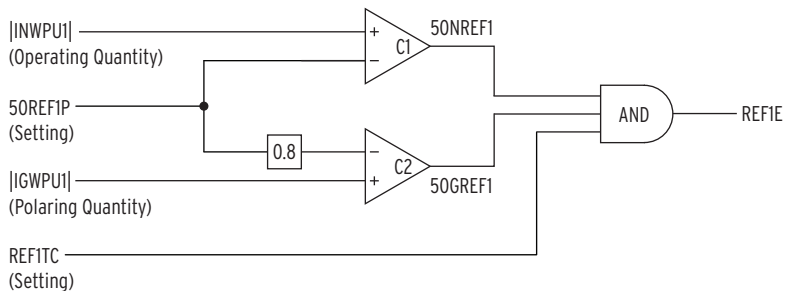


Figure 4.11 REF1 Enable Logic

Figure 4.12 shows the REF1 torque control output, REFTQ1. The Switch S1 (S1a and S1b) selects the zero-sequence vector currents from the line CTs that are part of the REF calculations as determined by the setting REF1POL. As an example, refer to *Figure 4.14*. For a single-wye winding, the logic requires one neutral CT and one set of line CTs for the REF function. If this set of line CTs is from Terminal 1, then Switch S1a will be in Position 2, while Switch S1b remains in Position 1. Current inputs from those terminals in Position 1 are not included in any REF element calculations. After closing the appropriate cells of Switch S1, the relay converts the currents to primary values by multiplying each current times the appropriate CT ratio. The relay then sums these currents vectorially to produce the polarizing current in vector form. To bring this value to the same base as the neutral CT, the algorithm divides the polarizing current by the product of the neutral CT ratio and the neutral CT nominal rating ($CTR1 \cdot INOM1$). These calculations produce IGWPU1, the normalized polarizing current in vector form. For the operating current, the algorithm normalizes IN1 with INOMN1 to produce INWPU1, the normalized operating current in vector form. INOMN1 is the nominal rating of the neutral CT, 5 A or 1 A.

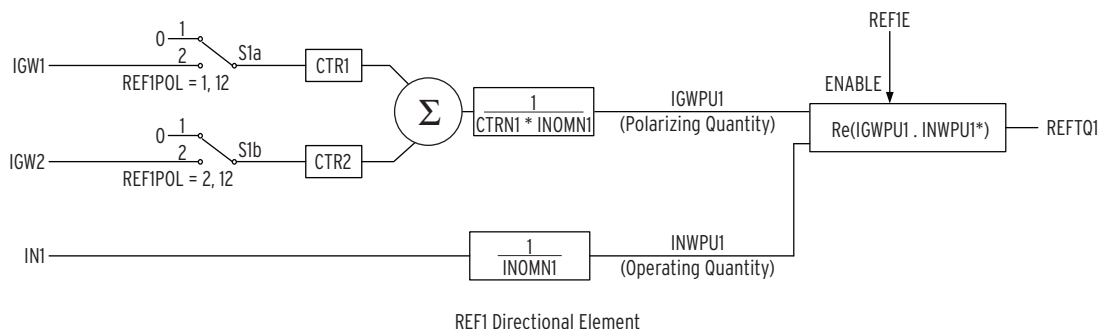


Figure 4.12 REF1 Directional Element

When the algorithm meets the conditions in *Figure 4.11*, REF1E asserts and enables the calculations of the directional element. To determine the direction, the algorithm calculates the real part of the product of the polarizing quantity and the conjugate of the operating quantity. This calculation yields the signed torque quantity REFTQ1 (this calculation is equivalent to $|IOP1|$ times $|IPOL1|$ times the cosine of the angle between them). REFTQ1 is positive if the angle is within ± 90 degrees, indicating a forward or internal fault. Conversely, REFTQ1 is negative if the angle is greater than $+90$ or less than -90 degrees, indicating a reverse or external fault.

Figure 4.13 shows the logic that compares REFTQ1 to positive threshold (THRES1P) and negative threshold (THRES1N), to ensure security for very small currents or for an angle near $+90$ or -90 degrees.

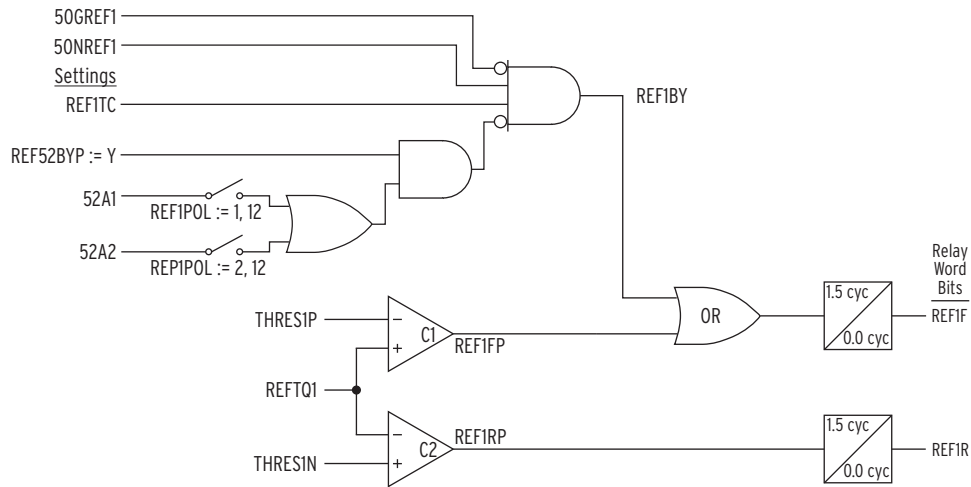


Figure 4.13 REF Element Trip Output

If REFTQ1 exceeds either threshold, it must persist for at least 1.5 cycles before Relay Word bit REFF1 (forward) or REFR1 (reverse) asserts. Assertion of REFF1 constitutes an internal ground fault.

A second path can also assert the REF1F bit. This path comes from the output of the AND gate in *Figure 4.13*, REF1 bypass logic. Assertion of this gate indicates substantial neutral current and no line-end current flow. *Figure 4.14* shows the need for the bypass logic. For the directional element to produce a meaningful result, both operating and restraint quantities must be present. If Fault F1 occurs with the LV breaker open, no current flows through the LV CT, and there is no polarizing quantity present. Assertions of 50NREF1 and a negated 50GREF1 identify this condition in *Figure 4.13*. Under this condition, the output of the bypass logic, REF1BY, causes the REF1F bit to assert to clear the internal fault. In most applications with REF52BYP:=Y, a 52A interlock enhances performance of the logic. Set REF52BYP := 0 if your application requires disregarding 52A for the bypass (e.g., the protected transformer is the only source of zero-sequence fault current).

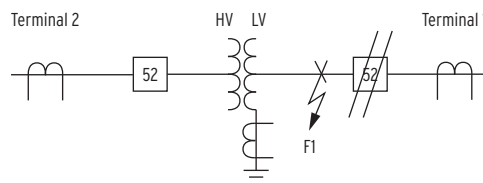


Figure 4.14 Internal Fault With LV Breaker Open

For fast tripping, include REFF1, the output of the REF1 element, into one or more of the trip equations, TR_x (where $x = 1, 2$, or XFMR) as appropriate. If you want additional security, the relay is programmed to use REF1F to torque control an inverse-time curve for delayed tripping, as discussed in the following text. *Figure 4.15* shows the output of the REF1 protection function. Timing is on an extremely inverse-time overcurrent curve (Curve U4) at the time-dial setting (0.5) and with 50REF1P as the pickup setting.

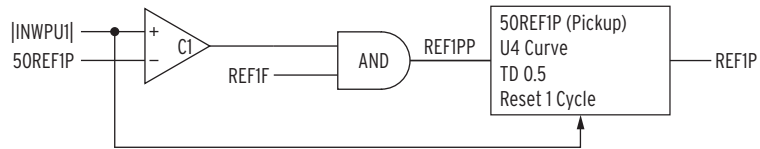


Figure 4.15 REF Protection Output (Extremely Inverse-Time O/C)

Relay Word bit REF1F (forward fault) torque controls the timing curve, and IN1PU operates the timing function. The curve resets in one cycle if current drops below pickup or if REF1F deasserts. When the curve times out, Relay Word bit REF1P asserts. You can use this bit directly as an input to the appropriate trip variables, TR_x (where $x = 1$ or XFMR), to trip the breaker or breakers that feed the fault.

Setting Descriptions and Applications

Table 4.5 identifies the settings associated with the REF1 element.

Table 4.5 Restricted Earth Fault Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|---------------------------------|
| POL QTY FROM WDG | OFF, 1, 2, 12 | REF1POL := OFF |
| REF1 TRQ CTRL | SELOGIC | REF1TC := 1 |
| REF1 CURR LEVEL | 0.05–3.00 pu | 50REF1P := 0.25 |
| 52A BYPASS ENABL | Y, N | REF52BYP := Y |

The setting REF1POL tells the relay which winding or combination of windings it should use in calculating residual current, which acts as the polarizing quantity for the corresponding directional element, *Figure 4.12*. The setting REF1TC is a SELOGIC control equation setting that defines the conditions under which the relay enables the corresponding REF1 element.

You can set the neutral current sensitivity threshold, 50REF1P, to as low as 0.05 times nominal current for a 1 A CT (0.25 A for 5 A nominal CT current), the minimum neutral current sensitivity of the relay. However, the minimum acceptable value of 50REF1P must be greater than any natural 3I0 unbalance resulting from load conditions.

Selection of the Restraint Quantity

The operating quantity/polarizing quantity relationship is according to software assignment (instead of a fixed relationship), so you can apply the REF element to any primary plant configuration with the correct CT arrangement. In general, identify all lines that are electrically connected to the grounded winding that you want to protect with the REF element. Then enter those terminals at the REF1POL setting. Following are examples of a few applications, assuming that both differential and REF elements protect the transformer in each example.

Figure 4.16 shows an ungrounded HV winding and a grounded-wye LV winding. Because two terminals are needed for the differential protection, assign Terminal 1 to the HV side and Terminal 2 to the LV side. Configure the REF1 element for REF protection. This element requires that the neutral CT is wired to Terminal IN. Although Terminals 1 and 2 are enabled, only Terminal 2 electrically connects to the winding earmarked for REF protection. Therefore, set REF1POL := 2.

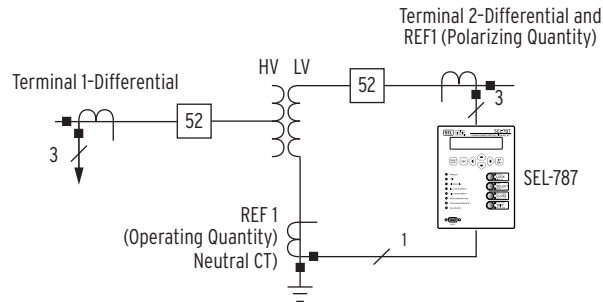


Figure 4.16 Single-Wye Winding REF Application (REF1POL := 2)

Figure 4.17 shows an autotransformer. Because two terminals are needed for the differential protection, assign Terminal 1 to the HV side and Terminal 2 to the LV side. In this case, both Terminal 1 and Terminal 2 connect electrically to the winding earmarked for REF protection. Therefore, set REF1POL := 12.

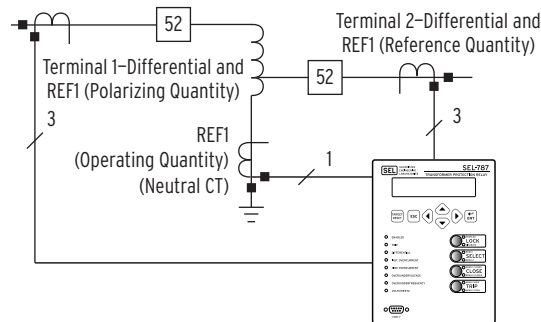


Figure 4.17 Autotransformer REF Application (REF1POL := 12)

Overcurrent Elements

Four levels of phase, and two levels each of residual and negative sequence, instantaneous/definite-time overcurrent elements are available for each of the two transformer windings as shown in Table 4.6 through Table 4.8 and in Figure 4.18.

Each element can be torque controlled using appropriate SELOGIC control equations (e.g., when 50P11TC := IN401, the 50P11 element will be operational only if IN401 is asserted).

Table 4.6 Winding n Maximum Phase Overcurrent Settings (n = 1 or 2)
(Sheet 1 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|---|------------------------------------|
| PHASE IOC LEVEL | OFF, 0.50–96.00 A ^a , 0.10–19.20 A ^b | 50Pn1P := OFF 50Pn1P := OFF |
| PHASE IOC DELAY | 0.00–5.00 sec | 50Pn1D := 0.00 |
| PH IOC TRQCTRL | SELOGIC | 50Pn1TC := 1 |
| PHASE IOC LEVEL | OFF, 0.50–96.00 A ^a , 0.10–19.20 A ^b | 50Pn2P := OFF 50Pn2P := OFF |

Table 4.6 Winding n Maximum Phase Overcurrent Settings (n = 1 or 2)
(Sheet 2 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|---|------------------------------------|
| PHASE IOC DELAY | 0.00–5.00 sec | 50Pn2D := 0.00 |
| PH IOC TRQCTRL | SELOGIC | 50Pn2TC := 1 |
| PHASE IOC LEVEL | OFF, 0.50–96.00 A ^a , 0.10–19.20 A ^b | 50Pn3P := OFF 50Pn3P := OFF |
| PHASE IOC DELAY | 0.00–5.00 sec | 50Pn3D := 0.00 |
| PH IOC TRQCTRL | SELOGIC | 50Pn3TC := 1 |
| PHASE IOC LEVEL | OFF, 0.50–96.00 A ^a , 0.10–19.20 A ^b | 50Pn4P := OFF 50Pn4P := OFF |
| PHASE IOC DELAY | 0.00–5.00 sec | 50Pn4D := 0.00 |
| PH IOC TRQCTRL | SELOGIC | 50Pn4TC := 1 |

^a For $I_{NOM} = 5$ A.^b For $I_{NOM} = 1$ A.

NOTE: The cosine filter provides excellent performance in removing dc offset and harmonics. However, the bipolar peak detector has the best performance in situations of severe CT saturation when the cosine filter magnitude estimation is significantly degraded. Combining the two methods provides an elegant solution for ensuring dependable short circuit overcurrent element operation.

The phase instantaneous overcurrent elements (50Pn1 through 50Pn4; see *Figure 4.18*) normally operate using the output of the one cycle cosine filtered phase current. During severe CT saturation, the cosine filtered phase current magnitude may be substantially reduced because of the distorted secondary waveform. If the overcurrent element relied only on the output of the cosine filtered secondary current, this may severely delay and may even jeopardize the operation of any high-set instantaneous overcurrent element. For any phase instantaneous overcurrent element in the SEL-787 relay set above eight times the relay current input rating (40 A in a 5 A relay), the overcurrent element also operates on the output of a bipolar peak detector if the current waveform is highly distorted, as is the case with severe CT saturation. This ensures fast operation of the 50P phase overcurrent elements even with severe CT saturation.

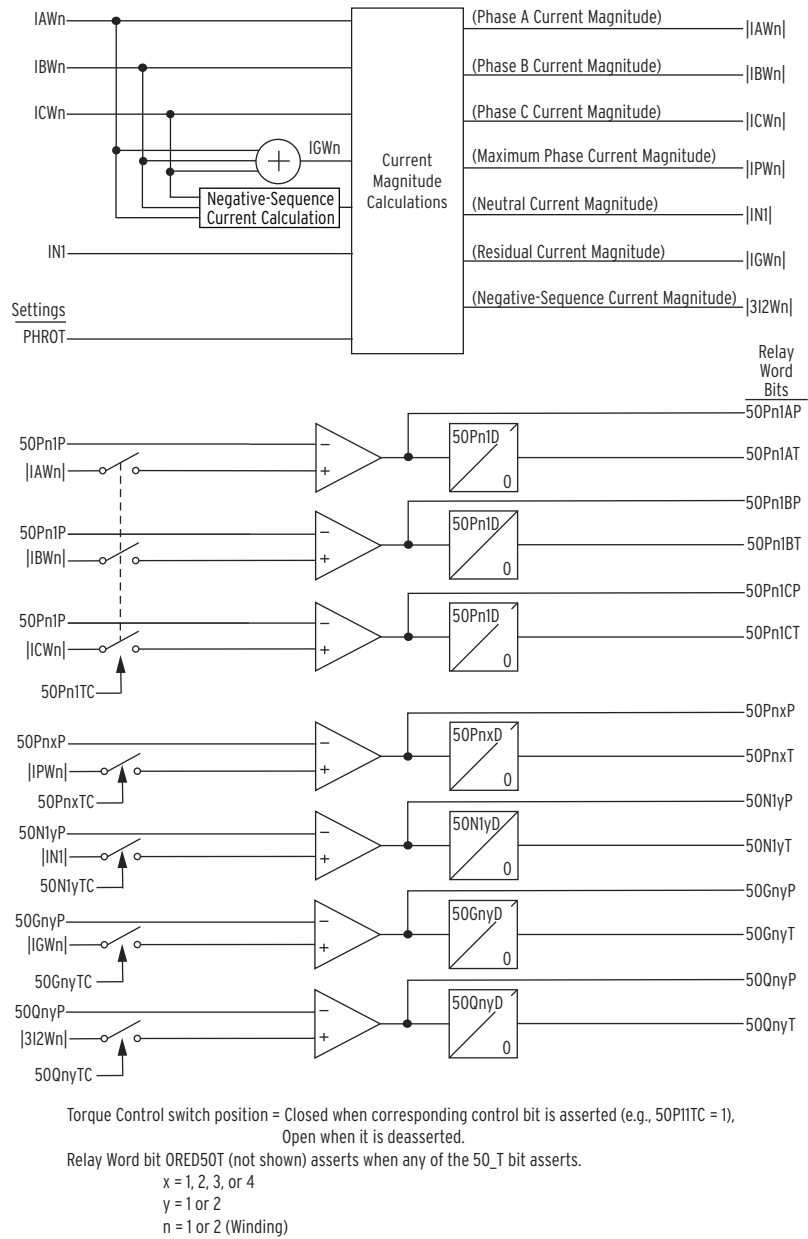


Figure 4.18 Instantaneous Overcurrent Element Logic

When the harmonic distortion index exceeds the fixed threshold, which indicates severe CT saturation, the phase overcurrent elements operate on the output of the peak detector. When the harmonic distortion index is below the fixed threshold, the phase overcurrent elements operate on the output of the cosine filter.

Table 4.7 Winding n Residual Overcurrent Settings (n = 1, 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|---|------------------------------------|
| RES IOC LEVEL | OFF, 0.50–96.00 A ^a , 0.10–19.20 A ^b | 50Gn1P := OFF |
| RES IOC DELAY | 0.00–5.00 sec | 50Gn1D := 0.50 |
| RES IOC TRQCTRL | SELOGIC | 50Gn1TC := 1 |
| RES IOC LEVEL | OFF, 0.50–96.00 A ^a , 0.10–19.20 A ^b | 50Gn2P := OFF |
| RES IOC DELAY | 0.00–5.00 sec | 50Gn2D := 0.50 |
| RES IOC TRQCTRL | SELOGIC | 50Gn2TC := 1 |

^a For $I_{NOM} = 5$ A.^b For $I_{NOM} = 1$ A.

The relay offers two types of ground fault detecting overcurrent elements. The neutral overcurrent elements (50N11T and 50N12T) operate with current measured by the IN1 input (see *Table 4.13* and *Table 4.14*). The residual (RES) overcurrent elements (50Gn1T and 50Gn2T) operate with the current derived from each winding phase currents (see *Figure 4.18*).

Table 4.8 Winding n Negative-Sequence Overcurrent Settings (n = 1 or 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---|------------------------------------|
| NSEQ IOC LEVEL | OFF, 0.50–96.00 A ^a , 0.10–19.20 A ^b | 50Q1P := OFF |
| NSEQ IOC DELAY | 0.10–120.00 sec | 50Q1D := 0.20 |
| NSEQ IOC TRQCTRL | SELOGIC | 50Q1TC := 1 |
| NSEQ IOC LEVEL | OFF, 0.50–96.00 A ^a , 0.10–19.20 A ^b | 50Q2P := OFF |
| NSEQ IOC DELAY | 0.10–120.00 sec | 50Q2D := 0.20 |
| NSEQ IOC TRQCTRL | SELOGIC | 50Q2TC := 1 |

^a For $I_{NOM} = 5$ A.^b For $I_{NOM} = 1$ A.

The relay offers two negative-sequence overcurrent elements per winding to detect phase-to-phase faults, phase reversal, single phasing, and unbalance load.

Time-Overcurrent Elements

One level of inverse time element is available for maximum phase, A-phase, B-phase, C-phase, residual, and negative-sequence overcurrent per transformer winding. See *Table 4.9* through *Table 4.12* for available settings.

You can select from five U.S. and five IEC inverse characteristics. *Table 4.15* and *Table 4.16* show equations for the curves and *Figure 4.24* through *Figure 4.33* show the curves. The curves and equations shown do not account for constant time adder and minimum response time (settings 51_CT and 51_MR respectively, each assumed equal to zero). Use the 51_CT if you want to raise the curves by a constant time. Also, you can use the 51_MR if you want to ensure the curve times no faster than a minimum response time.

Each element can be torque controlled using appropriate SELOGIC equations (e.g., when 51P1TC := IN401, the 51P1P element is operational only if IN401 is asserted).

Table 4.9 Winding n Maximum Phase Time-Overcurrent (n = 1 or 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|--|------------------------------------|
| PHASE TOC LEVEL | OFF, 0.50–16.00 A ^a , 0.10–3.20 A ^b | 51PnP := OFF 51PnP := OFF |
| PHASE TOC CURVE | U1, U2, U3, U4, U5, C1, C2, C3, C4, C5 | 51PnC := U3 |
| PHASE TOC TDIAL | 0.50–15.00 ^c , 0.05–1.00 ^d | 51PnTD := 3.00 |
| EM RESET DELAY | Y, N | 51PnRS := N |
| CONST TIME ADDER | 0.00–1.00 sec | 51PnCT := 0.00 |
| MIN RESPONSE TIM | 0.00–1.00 sec | 51PnMR := 0.00 |
| PH TOC TRQCTRL | SELOGIC | 51PnTC := 1 |

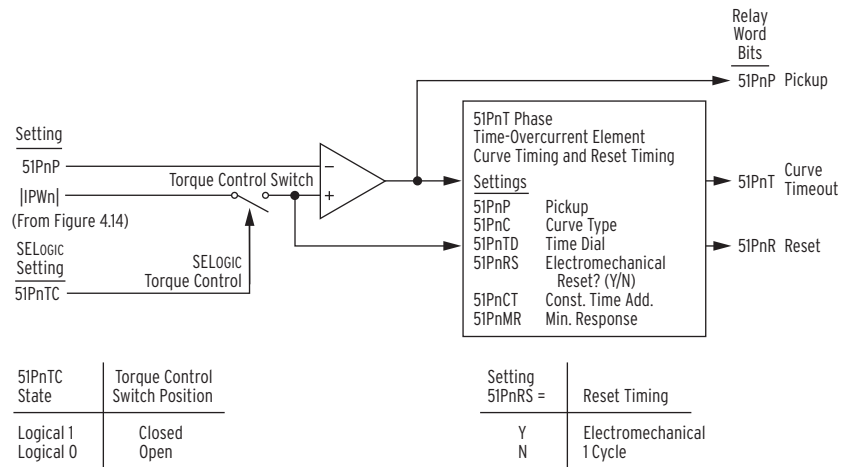
^a For I_{NOM} = 5 A.

^b For I_{NOM} = 1 A.

^c For 51_C := U_.

^d For 51_C := C_.

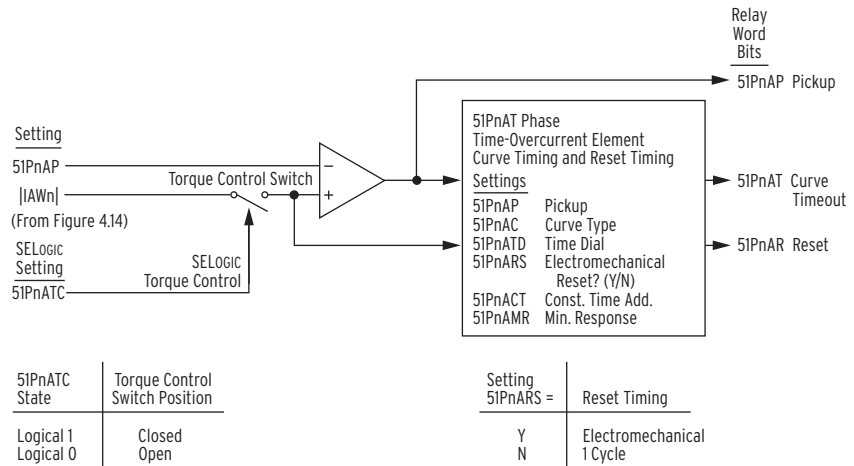
The maximum phase time-overcurrent elements, 51P1T and 51P2T, respond to the highest of A, B, and C-phase currents as shown in *Figure 4.19*.



Note: n = 1 or 2 (Winding 1 or 2).

Figure 4.19 Maximum Phase Time-Overcurrent Elements 51P1T and 51P2T

The phase time-overcurrent elements, 51PnAT, 51PnBT, and 51PnCT, respond to the A, B, and C-phase currents for winding *n* as shown in *Figure 4.20*.



Note: *n* = 1 or 2 (Winding 1 or 2).
 Shown for A Phase (phases B and C are similar).

Figure 4.20 Phase A, B, and C Time-Overcurrent Elements

Table 4.10 Winding *n* Phase A, B, and C Time-Overcurrent (*n* = 1 or 2)
 (Sheet 1 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|--|---------------------------------|
| PHASE TOC LVL | OFF, 0.50–16.00 A ^a 0.10–3.20 A ^b | 51PnAP := OFF |
| PHASE TOC CURVE | U1, U2, U3, U4, U5, C1, C2, C3, C4, C5 | 51PnAC := U3 |
| PHASE TOC TDIAL | 0.50–15.00 ^c 0.05–1.00 ^d | 51PnATD := 3.00 |
| EM RESET DELAY | Y, N | 51PnARS := N |
| CONST TIME ADDER | 0.00–1.00 sec | 51PnACT := 0.00 |
| MIN RESPONSE TIM | 0.00–1.00 sec | 51PnAMR := 0.00 |
| PH A TOC TRQCTRL | SELOGIC | 51PnATC := 1 |
| PHASE TOC LVL | OFF, 0.50–16.00 A ^a 0.10–3.20 A ^b | 51PnBP := OFF |
| PHASE TOC CURVE | U1, U2, U3, U4, U5, C1, C2, C3, C4, C5 | 51PnBC := U3 |
| PHASE TOC TDIAL | 0.50–15.00 ^c 0.05–1.00 ^d | 51PnBTD := 3.00 |
| EM RESET DELAY | Y, N | 51PnBRS := N |
| CONST TIME ADDER | 0.00–1.00 sec | 51PnBCT := 0.00 |
| MIN RESPONSE TIM | 0.00–1.00 sec | 51PnBMR := 0.00 |
| PH B TOC TRQCTRL | SELOGIC | 51PnBTC := 1 |
| PHASE TOC LVL | OFF, 0.50–16.00 A ^a 0.10–3.20 A ^b | 51PnCP := OFF |
| PHASE TOC CURVE | U1, U2, U3, U4, U5, C1, C2, C3, C4, C5 | 51PnCC := U3 |
| PHASE TOC TDIAL | 0.50–15.00 ^c 0.05–1.00 ^d | 51PnCTD := 3.00 |

Table 4.10 Winding n Phase A, B, and C Time-Overcurrent (n = 1 or 2)
(Sheet 2 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|------------------------------------|
| EM RESET DELAY | Y, N | 51PnCRS := N |
| CONST TIME ADDER | 0.00–1.00 sec | 51PnCCT := 0.00 |
| MIN RESPONSE TIM | 0.00–1.00 sec | 51PnCMR := 0.00 |
| PH A TOC TRQCTRL | SELOGIC | 51PnCTC := 1 |

^a For $I_{NOM} = 5$ A.

^b For $I_{NOM} = 1$ A.

^c For 51_C := U_.

^d For 51_C := C_.

Table 4.11 Residual Time-Overcurrent Settings (n = 1 or 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|--|------------------------------------|
| RES TOC LEVEL | OFF, 0.50–16.00 A ^a , 0.10–3.20 A ^b | 51GnP := OFF 51GnP := OFF |
| RES TOC CURVE | U1, U2, U3, U4, U5, C1, C2, C3, C4, C5 | 51GnC := U3 |
| RES TOC TDIAL | 0.50–15.00 ^c , 0.05–1.00 ^d | 51GnTD := 1.50 |
| EM RESET DELAY | Y, N | 51GnRS := N |
| CONST TIME ADDER | 0.00–1.00 sec | 51GnCT := 0.00 |
| MIN RESPONSE TIM | 0.00–1.00 sec | 51GnMR := 0.00 |
| RES TOC TRQCTRL | SELOGIC | 51GnTC := 1 |

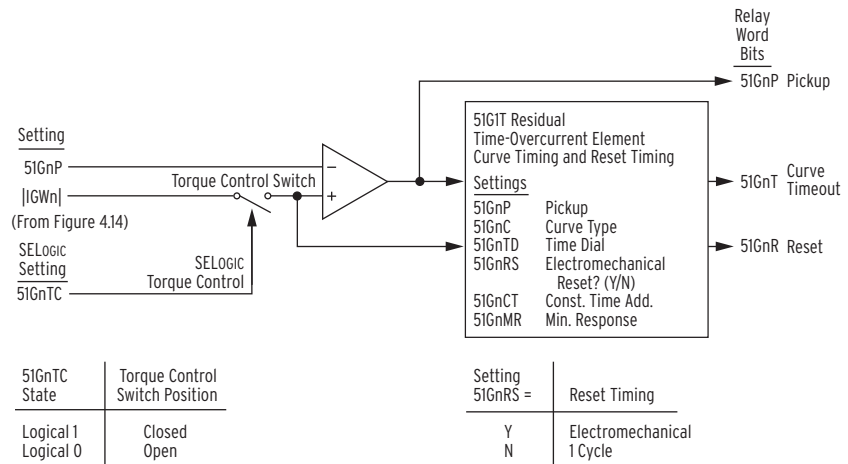
^a For $I_{NOM} = 5$ A.

^b For $I_{NOM} = 1$ A.

^c For 51_C := U_.

^d For 51_C := C_.

The residual time-overcurrent elements, 51G1T and 51G2T, respond to residual currents IGW1 and IGW2 as shown in *Figure 4.21*.



Note: 51G1T element shown above; 51G2T is similar.

Figure 4.21 Residual Time-Overcurrent Elements 51G1T and 51G2T

Table 4.12 Winding n Negative-Sequence Time-Overcurrent Settings (n = 1, 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|--|------------------------------------|
| NSEQ TOC LEVEL | OFF, 0.50–16.00 A ^a , 0.10–3.20 A ^b | 51QnP := OFF 51QnP := OFF |
| NSEQ TOC CURVE | U1, U2, U3, U4, U5, C1, C2, C3, C4, C5 | 51QnC := U3 |
| NSEQ TOC TDIAL | 0.50–15.00 ^c , 0.05–1.00 ^d | 51QnTD := 3.00 |
| EM RESET DELAY | Y, N | 51QnRS := N |
| CONST TIME ADDER | 0.00–1.00 sec | 51QnCT := 0.00 |
| MIN RESPONSE TIM | 0.00–1.00 sec | 51QnMR := 0.00 |
| NSEQ TOC TRQCTRL | SELOGIC | 51QnTC := 1 |

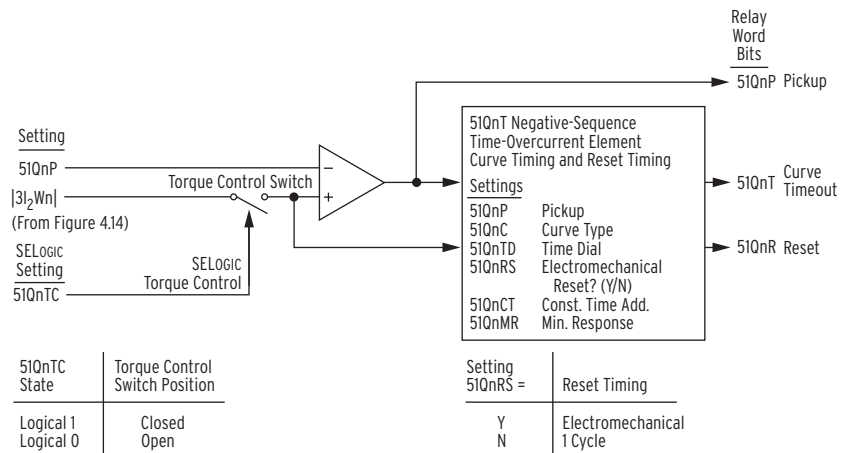
^a For $I_{NOM} = 5$ A.

^b For $I_{NOM} = 1$ A.

^c For 51_C := U_.

^d For 51_C := C_.

The negative-sequence time-overcurrent element 51QnT responds to the 3I₂ current as shown in *Figure 4.22*.


Figure 4.22 Negative-Sequence Time-Overcurrent Element 51Q1T and 51Q2T

False negative-sequence current can transiently appear when a circuit breaker is closed and balanced load current suddenly appears. To avoid tripping for this transient condition, do not use a time-dial setting that results in curve times below three cycles.

Table 4.13 Neutral Overcurrent Settings (Sheet 1 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---|------------------------------------|
| NEUT IOC LEVEL | OFF, 0.50–96.00 A ^a , 0.10–19.20 A ^b | 50N11P := OFF |
| NEUT IOC DELAY | 0.00–5.00 sec | 50N11D := 0.50 |
| NEUT IOC TRQCTRL | SELOGIC | 50N11TC := 1 |
| NEUT IOC LEVEL | OFF, 0.50–96.00 A 0.10–19.20 A ^b | 50N12P := OFF |

Table 4.13 Neutral Overcurrent Settings (Sheet 2 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|------------------------------------|
| NEUT IOC DELAY | 0.00–5.00 sec | 50N12D := 0.50 |
| NEUT IOC TRQCTRL | SELOGIC | 50N12TC := 1 |

^a For $I_{NOM} = 5$ A.

^b For $I_{NOM} = 1$ A.

Table 4.14 Neutral Time-Overcurrent Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|--|------------------------------------|
| NEUT TOC LEVEL | OFF, 0.50–16.00 A ^a 0.10–3.20 A ^b , | 51N1P := OFF |
| NEUT TOC CURVE | U1, U2, U3, U4, U5, C1, C2, C3, C4, C5 | 51N1C := U3 |
| NEUT TOC TDIAL | 0.50–15.00 ^c 0.05–1.00 ^d | 51N1TD := 1.50 |
| EM RESET DELAY | Y, N | 51N1RS := N |
| CONST TIME ADDER | 0.00–1.00 sec | 51N1CT := 0.00 |
| MIN RESPONSE TIM | 0.00–1.00 sec | 51N1MR := 0.00 |
| NEUT TOC TRQCTRL | SELOGIC | 51N1TC := 1 |

^a For $I_{NOM} = 5$ A.

^b For $I_{NOM} = 1$ A.

^c For 51_C := U_.

^d For 51_C := C_.

The neutral overcurrent and time-overcurrent elements, 50N11T, 50N12T, and 51N1T, respond to neutral channel current IN1 as shown in *Figure 4.18* and *Figure 4.23*.

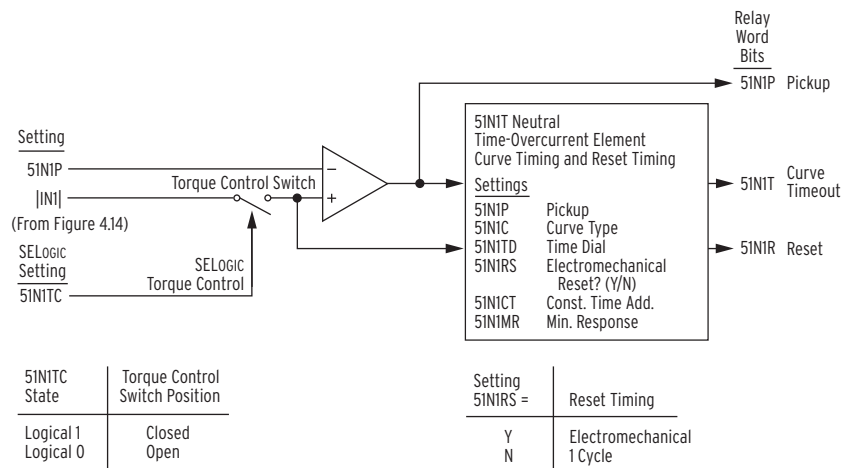


Figure 4.23 Neutral Time-Overcurrent Elements 51N1T and 51N2T

Relay Word Bit ORED51T

Relay Word bit ORED51T is asserted if any of the relay word bits 51P1T, 51P2T, 51G1T, 51G2T, 51Q1T, 51Q2T, OR 51N1T are asserted.

Time-Overcurrent Curves

The following information describes the curve timing for the curve and time dial settings made for the time-overcurrent elements (see *Table 4.15* and *Table 4.16*). The U.S. and IEC time-overcurrent relay curves are shown in *Figure 4.24* through *Figure 4.33*. Curves U1, U2, and U3 (*Figure 4.24* through *Figure 4.26*) conform to IEEE C37.112-1996 IEEE Standard Inverse-Time Characteristic Equations for Overcurrent Relays.

Table 4.15 Equations Associated With U.S. Curves

| Curve Type | Operating Time | Reset Time | Figure |
|--|--|---|--------------------|
| U1 (Moderately Inverse) | $t_p = TD \cdot \left(0.0226 + \frac{0.0104}{M^{0.02} - 1} \right)$ | $t_r = TD \cdot \left(\frac{1.08}{1 - M^2} \right)$ | <i>Figure 4.24</i> |
| U2 (Inverse) | $t_p = TD \cdot \left(0.180 + \frac{5.95}{M^2 - 1} \right)$ | $t_r = TD \cdot \left(\frac{5.95}{1 - M^2} \right)$ | <i>Figure 4.25</i> |
| U3 (Very Inverse) | $t_p = TD \cdot \left(0.0963 + \frac{3.88}{M^2 - 1} \right)$ | $t_r = TD \cdot \left(\frac{3.88}{1 - M^2} \right)$ | <i>Figure 4.26</i> |
| U4 (Extremely Inverse) | $t_p = TD \cdot \left(0.0352 + \frac{5.67}{M^2 - 1} \right)$ | $t_r = TD \cdot \left(\frac{5.67}{1 - M^2} \right)$ | <i>Figure 4.27</i> |
| U5 (Short-Time Inverse) | $t_p = TD \cdot \left(0.00262 + \frac{0.00342}{M^{0.02} - 1} \right)$ | $t_r = TD \cdot \left(\frac{0.323}{1 - M^2} \right)$ | <i>Figure 4.28</i> |
| t_p = operating time in seconds t_r = electromechanical induction-disk emulation reset time in seconds (if you select electromechanical reset setting) TD = time-dial setting M = applied multiples of pickup current [for operating time (t_p), $M > 1$; for reset time (t_r), $M \leq 1$] | | | |

Table 4.16 Equations Associated With IEC Curves

| Curve Type | Operating Time | Reset Time | Figure |
|--|---|--|--------------------|
| C1 (Standard Inverse) | $t_p = TD \cdot \left(\frac{0.14}{M^{0.02} - 1} \right)$ | $t_r = TD \cdot \left(\frac{13.5}{1 - M^2} \right)$ | <i>Figure 4.29</i> |
| C2 (Very Inverse) | $t_p = TD \cdot \left(\frac{13.5}{M - 1} \right)$ | $t_r = TD \cdot \left(\frac{47.3}{1 - M^2} \right)$ | <i>Figure 4.30</i> |
| C3 (Extremely Inverse) | $t_p = TD \cdot \left(\frac{80}{M^2 - 1} \right)$ | $t_r = TD \cdot \left(\frac{80}{1 - M^2} \right)$ | <i>Figure 4.31</i> |
| C4 (Long-Time Inverse) | $t_p = TD \cdot \left(\frac{120}{M - 1} \right)$ | $t_r = TD \cdot \left(\frac{120}{1 - M} \right)$ | <i>Figure 4.32</i> |
| C5 (Short-Time Inverse) | $t_p = TD \cdot \left(\frac{0.05}{M^{0.04} - 1} \right)$ | $t_r = TD \cdot \left(\frac{4.85}{1 - M^2} \right)$ | <i>Figure 4.33</i> |
| t_p = operating time in seconds t_r = electromechanical induction-disk emulation reset time in seconds (if you select electromechanical reset setting) TD = time-dial setting M = applied multiples of pickup current [for operating time (t_p), $M > 1$; for reset time (t_r), $M \leq 1$] | | | |

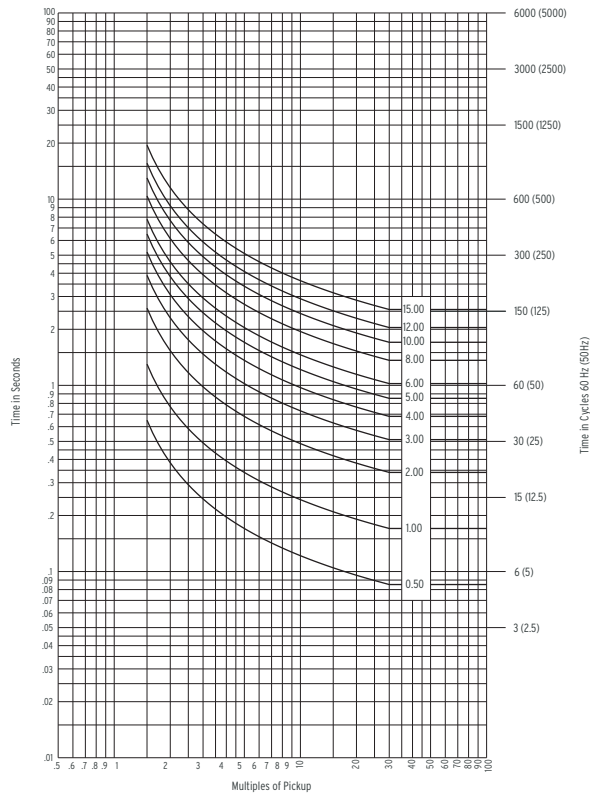


Figure 4.24 U.S. Moderately Inverse Curve: U1

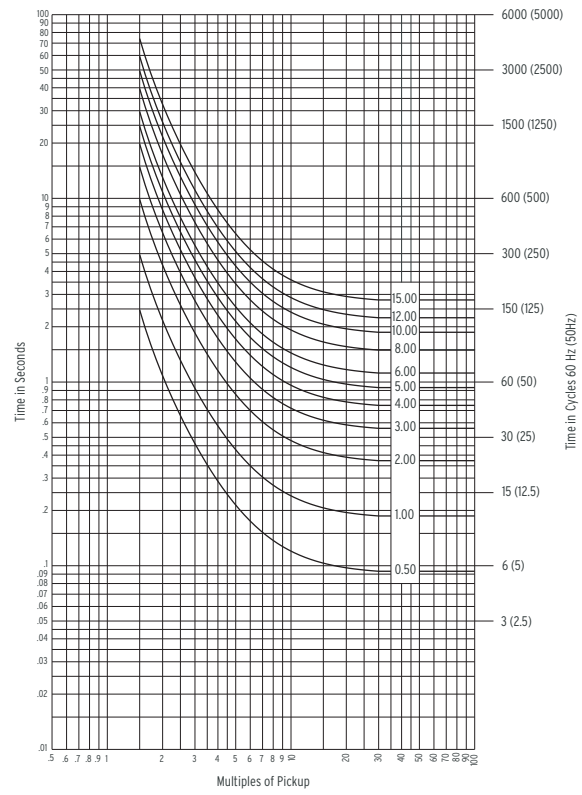


Figure 4.25 U.S. Inverse Curve: U2

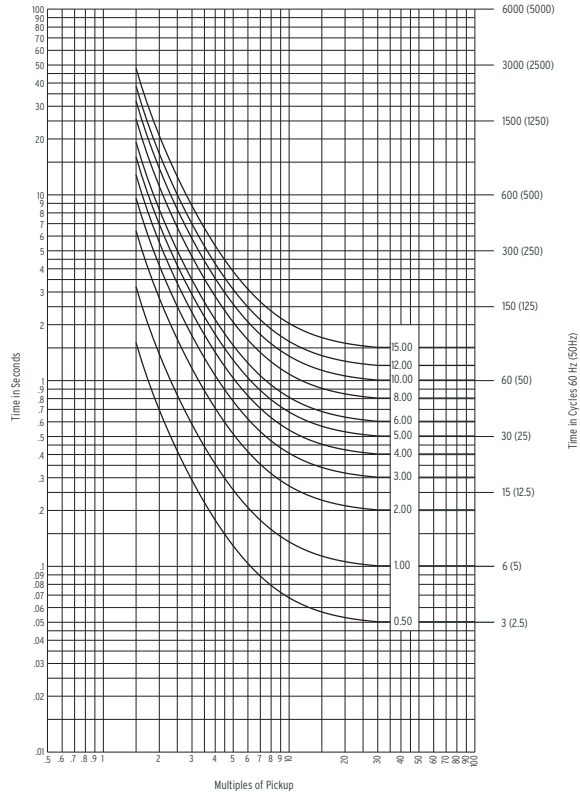


Figure 4.26 U.S. Very Inverse Curve: U3

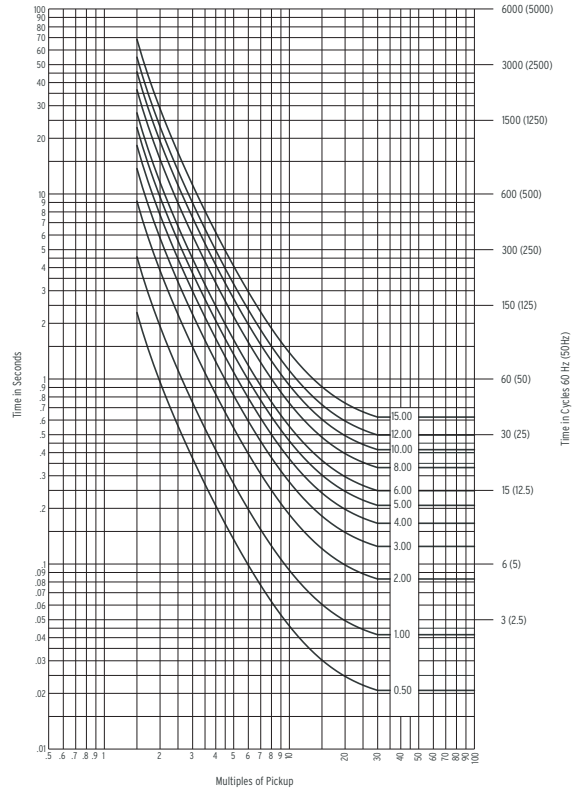


Figure 4.27 U.S. Extremely Inverse Curve: U4

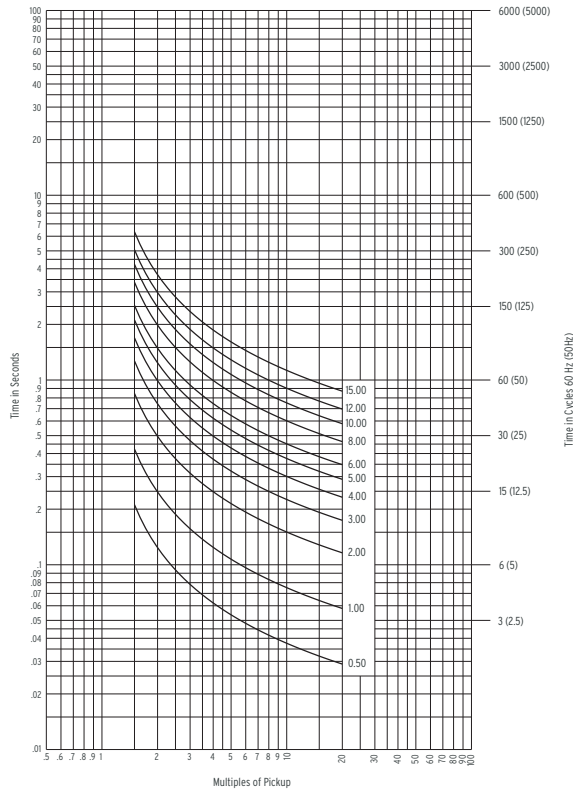


Figure 4.28 U.S. Short-Time Inverse Curve: U5

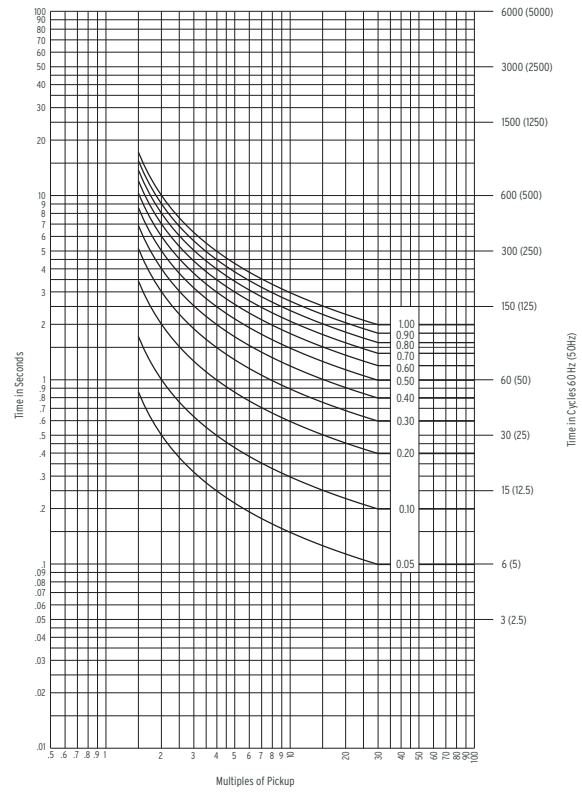


Figure 4.29 IEC Class A Curve (Standard Inverse): C1

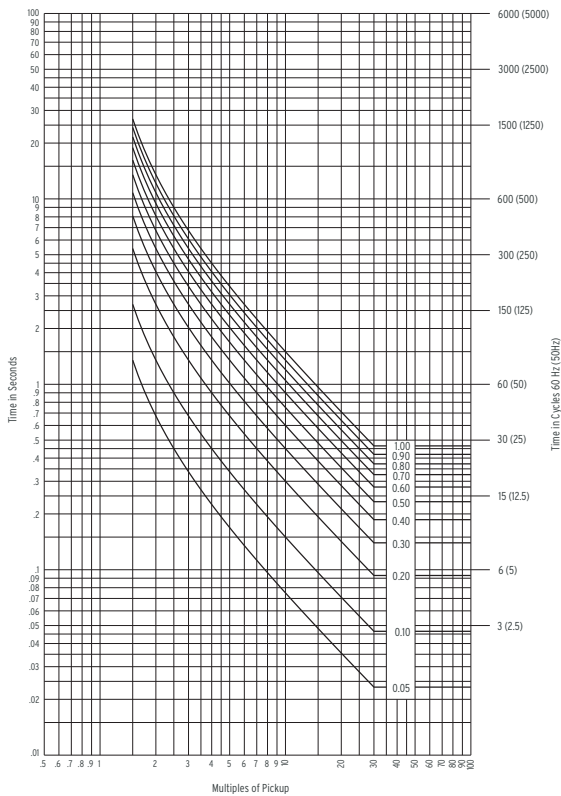


Figure 4.30 IEC Class B Curve (Very Inverse): C2

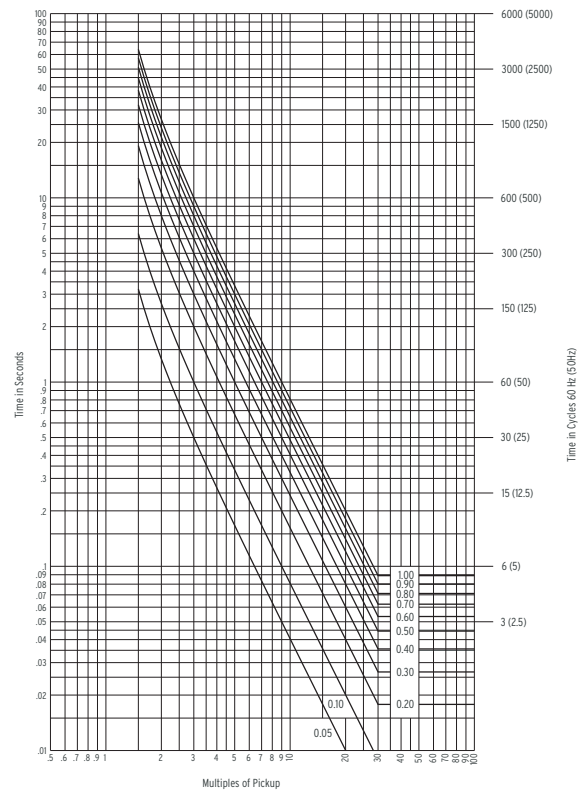


Figure 4.31 IEC Class C Curve (Extremely Inverse): C3

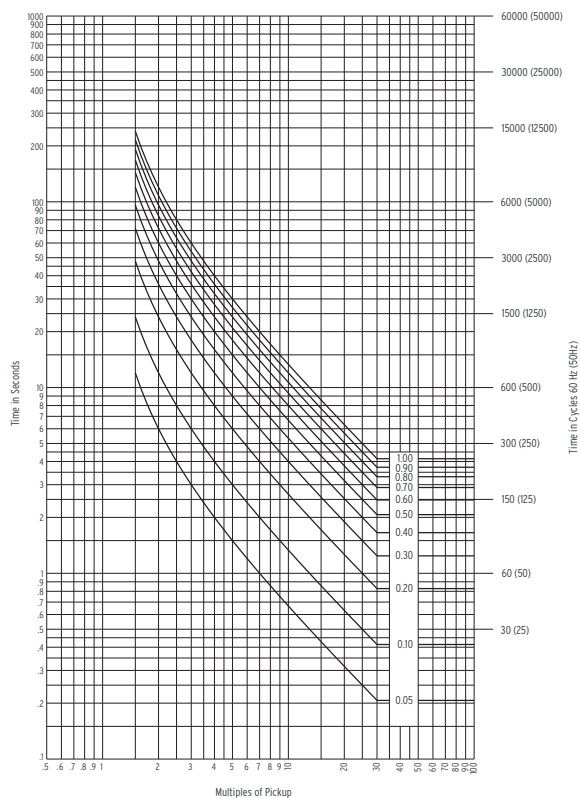


Figure 4.32 IEC Long-Time Inverse Curve: C4

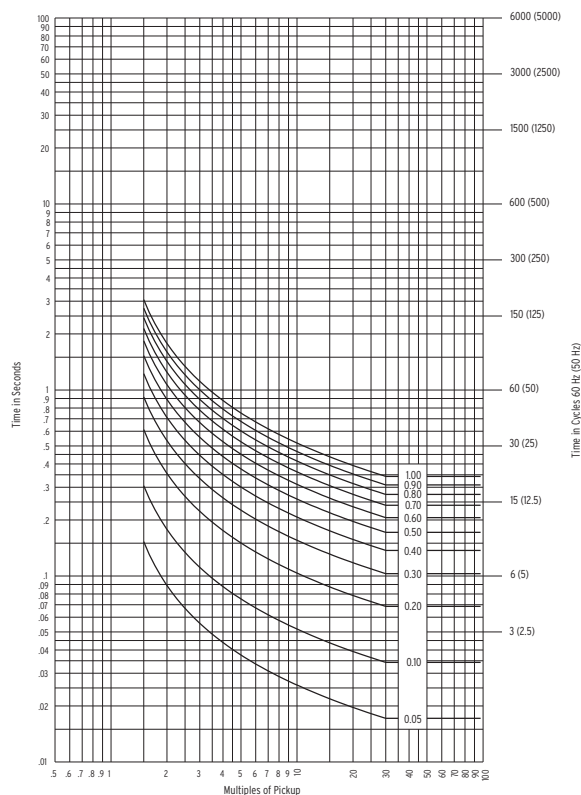


Figure 4.33 IEC Short-Time Inverse Curve: C5

RTD-Based Protection

RTD Input Function

NOTE: The SEL-787 can monitor as many as 10 RTDs connected to an internal RTD card or as many as 12 RTDs connected to an external SEL-2600 RTD Module. Table 4.17 shows Location, Type, and Trip/Warn Level settings only for RTD1; settings for RTD2-RTD12 are similar.

NOTE: RTD curves in SEL products are based on the DIN/IEC 60751 standard.

When you connect an SEL-2600 RTD Module (set E49RTD := EXT) or order the internal RTD card (set E49RTD := INT) option, the SEL-787 offers several protection and monitoring functions, settings for which are described in Table 4.17. See Figure 2.12 for the RTD module fiber-optic cable connections. If relay does not have internal or external RTD inputs, set E49RTD := NONE.

Table 4.17 RTD Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|---------------------------|------------------------------------|
| RTD ENABLE | INT, EXT, NONE | E49RTD := NONE |
| RTD1 LOCATION | OFF, AMB, OTH | RTD1LOC := OFF |
| RTD1 IDENTIFIER | 10 characters | RTDNAME := |
| RTD1 TYPE | PT100, NI100, NI120, CU10 | RTD1TY := PT100 |
| RTD1 TRIP LEVEL | OFF, 1–250 °C | TRTMP1 := OFF |
| RTD1 WARN LEVEL | OFF, 1–250 °C | ALTMP1 := OFF |
| • | • | • |
| • | • | • |
| • | • | • |

RTD Location

The relay allows you to independently define the location of each monitored RTD by using the RTD location settings.

Define the RTD location settings through use of the following suggestions:

- If an RTD is not connected to an input or has failed in place and will not be replaced, set the RTD location for that input equal to OFF.
- For the input connected to an RTD measuring ambient air temperature, set the RTD location equal to AMB. Only one ambient temperature RTD is allowed.
- For inputs connected to monitor temperatures of apparatus, such as transformer oil and winding temperature, set the RTD location equal to OTH. Use the RTD identifier setting to assign an appropriate name to the RTD, for example set RTD1NAM := XFRMR1 OIL.

If an RTD location setting is equal to OFF, the relay does not request that an RTD type setting be entered for that input.

RTD Type

The four available RTD types are:

- 100-ohm platinum (PT100)
- 100-ohm nickel (NI100)
- 120-ohm nickel (NI120)
- 10-ohm copper (CU10)

RTD Trip/Warning Levels

The SEL-787 provides temperature warnings and trips through use of the RTD temperature measurements and the warning and trip temperature settings in *Table 4.17*.

The relay issues a temperature warning if any of the healthy RTDs indicates a temperature greater than the relay RTD warning temperature setting. The relay issues a temperature trip if one of the healthy RTDs indicates a temperature greater than the RTD trip temperature setting.

To disable any of the temperature warning or trip functions, set the appropriate temperature setting to OFF.

Only healthy RTDs can contribute temperatures to the warning and trip functions. The relay includes specific logic to indicate if RTD leads are shorted or open.

Table 4.18 lists the RTD resistance versus temperature for the four supported RTD types.

Table 4.18 RTD Resistance Versus Temperature (Sheet 1 of 2)

| Temp (°F) | Temp (°C) | 100 Platinum | 120 Nickel | 100 Nickel | 10 Copper |
|-----------|-----------|--------------|------------|------------|-----------|
| -58 | -50.00 | 80.31 | 86.17 | 74.30 | 7.10 |
| -40 | -40.00 | 84.27 | 92.76 | 79.10 | 7.49 |
| -22 | -30.00 | 88.22 | 99.41 | 84.20 | 7.88 |

NOTE: To improve security, RTD ALARM and TRIP are delayed by approximately 6 seconds.

Table 4.18 RTD Resistance Versus Temperature (Sheet 2 of 2)

| Temp (°F) | Temp (°C) | 100 Platinum | 120 Nickel | 100 Nickel | 10 Copper |
|--------------|--------------|-----------------|---------------|---------------|--------------|
| –4 | –20.00 | 92.16 | 106.15 | 89.30 | 8.26 |
| 14 | –10.00 | 96.09 | 113.00 | 94.60 | 8.65 |
| 32 | 0.00 | 100.00 | 120.00 | 100.00 | 9.04 |
| 50 | 10.00 | 103.90 | 127.17 | 105.60 | 9.42 |
| 68 | 20.00 | 107.79 | 134.52 | 111.20 | 9.81 |
| 86 | 30.00 | 111.67 | 142.06 | 117.10 | 10.19 |
| 104 | 40.00 | 115.54 | 149.79 | 123.00 | 10.58 |
| 122 | 50.00 | 119.39 | 157.74 | 129.10 | 10.97 |
| 140 | 60.00 | 123.24 | 165.90 | 135.30 | 11.35 |
| 158 | 70.00 | 127.07 | 174.25 | 141.70 | 11.74 |
| 176 | 80.00 | 130.89 | 182.84 | 148.30 | 12.12 |
| 194 | 90.00 | 134.70 | 191.64 | 154.90 | 12.51 |
| 212 | 100.00 | 138.50 | 200.64 | 161.80 | 12.90 |
| 230 | 110.00 | 142.29 | 209.85 | 168.80 | 13.28 |
| 248 | 120.00 | 146.06 | 219.29 | 176.00 | 13.67 |
| 266 | 130.00 | 149.83 | 228.96 | 183.30 | 14.06 |
| 284 | 140.00 | 153.58 | 238.85 | 190.90 | 14.44 |
| 302 | 150.00 | 157.32 | 248.95 | 198.70 | 14.83 |
| 320 | 160.00 | 161.05 | 259.30 | 206.60 | 15.22 |
| 338 | 170.00 | 164.77 | 269.91 | 214.80 | 15.61 |
| 356 | 180.00 | 168.47 | 280.77 | 223.20 | 16.00 |
| 374 | 190.00 | 172.17 | 291.96 | 231.80 | 16.39 |
| 392 | 200.00 | 175.85 | 303.46 | 240.70 | 16.78 |
| 410 | 210.00 | 179.15 | 315.31 | 249.80 | 17.17 |
| 428 | 220.00 | 183.17 | 327.54 | 259.20 | 17.56 |
| 446 | 230.00 | 186.82 | 340.14 | 268.90 | 17.95 |
| 464 | 240.00 | 190.45 | 353.14 | 278.90 | 18.34 |
| 482 | 250.00 | 194.08 | 366.53 | 289.10 | 18.73 |

Voltage-Based Protection

The following information applies to relay models with voltage inputs.

Undervoltage Function

Table 4.19 Undervoltage Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------|-------------------|------------------------------------|
| PHASE UV LEVEL | OFF, 12.5–300.0 V | 27P1P := OFF |
| PHASE UV DELAY | 0.0–120.0 sec | 27P1D := 0.5 |
| PHASE UV LEVEL | OFF, 12.5–300.0 V | 27P2P := OFF |
| PHASE UV DELAY | 0.0–120.0 sec | 27P2D := 5.0 |

Overvoltage Function

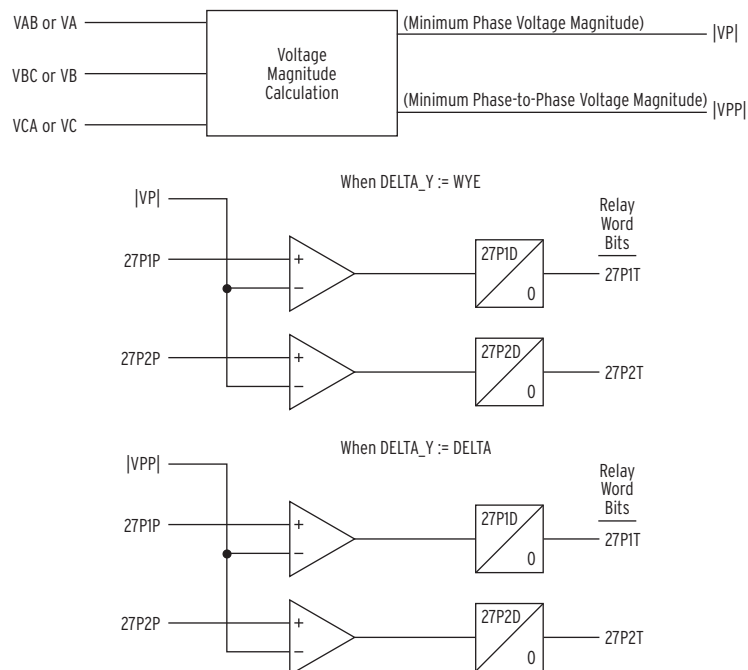
Table 4.20 Overvoltage Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------|-------------------|------------------------------------|
| PHASE OV LEVEL | OFF, 12.5–300.0 V | 59P1P := OFF |
| PHASE OV DELAY | 0.0–120.0 sec | 59P1D := 0.5 |
| PHASE OV LEVEL | OFF, 12.5–300.0 V | 59P2P := OFF |
| PHASE OV DELAY | 0.0–120.0 sec | 59P2D := 5.0 |
| NSEQ OV LEVEL | OFF, 12.5–300.0 V | 59Q1P := OFF |
| NSEQ OV DELAY | 0.0–120.0 sec | 59Q1D := 0.5 |
| NSEQ OV LEVEL | OFF, 12.5–300.0 V | 59Q2P := OFF |
| NSEQ OV DELAY | 0.0–120.0 sec | 59Q2D := 5.0 |

When you connect the SEL-787 voltage inputs to phase-to-phase connected VTs (single-phase or three-phase), as in *Figure 2.17* or *Figure 2.18*, the relay provides two levels of phase-to-phase overvoltage and undervoltage elements.

When you connect the SEL-787 voltage inputs to phase-to-neutral connected VTs (single-phase or three-phase), as shown in *Figure 2.17* or *Figure 2.18*, the relay provides two levels of phase-to-neutral overvoltage and undervoltage elements. The SEL-787 also includes two levels of negative-sequence overvoltage elements. Use these elements for alarm or trip when three-phase voltage inputs (wye or delta) are connected to the relay.

Each of the elements has an associated time delay. You can use these elements as you choose for tripping and warning. *Figure 4.34* and *Figure 4.35* show the logic diagram for the undervoltage and overvoltage elements, respectively. To disable any of these elements, set the level settings equal to OFF.


Figure 4.34 Undervoltage Element Logic

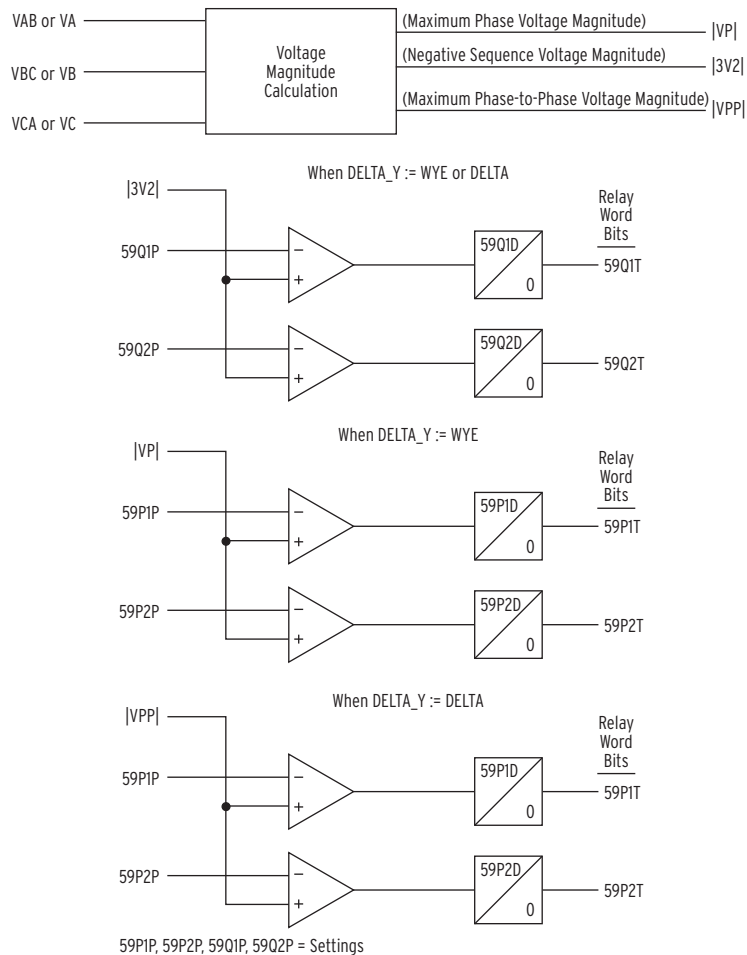


Figure 4.35 Overvoltage Element Logic

Volts Per Hertz Elements

Overexcitation occurs when a transformer magnetic core becomes saturated. When this happens, stray flux is induced in nonlaminated components, causing overheating. In the SEL-787 Relay a volts/hertz element detects overexcitation. The SEL-787 provides a sensitive definite time volts/hertz element, plus a tripping element with a composite operating time. The relay calculates the present transformer volts/hertz as a percent of nominal, based on the present and nominal voltages and frequencies. The settings VNOM and FNOM define the nominal transformer voltage and frequency, respectively.

Figure 4.36 shows a logic diagram of the volts/hertz elements. If the torque-control 24TC SELOGIC control equation is true and the present volts/hertz exceed the 24D1P setting, the relay asserts the 24D1 Relay Word bit and starts the 24D1D timer. If the condition remains for 24D1D seconds, the relay asserts the 24D1T Relay Word bit. Typically, you should apply this element as an overexcitation alarm.

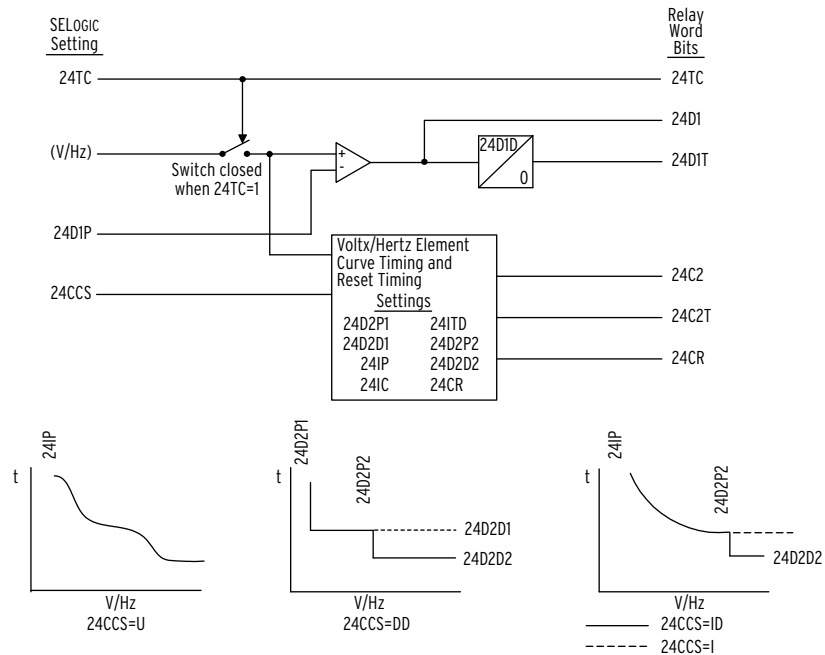


Figure 4.36 V/Hz Element Logic

For volts/hertz tripping the relay provides a time-integrating element with a settable operating characteristic. You can set the element to operate as an inverse-time element; a user-defined curve element (using the SEL-5806 PC Software); a composite element with an inverse-time characteristic and a definite-time characteristic; or as a dual-level, definite-time element. In any case, the element provides a linear reset characteristic with a settable reset time. This element also is supervised by the 24TC torque-control setting.

The volts/hertz tripping element has a percent-travel operating characteristic similar to that employed by an induction-disk time-overcurrent element. This characteristic coincides well with the heating effect that overexcitation has on transformer components.

The element compares the three phase voltages and uses the highest of the values for the volts/hertz magnitude calculations. The relay asserts 24C2 Relay Word bit without time delay when the transformer volts/hertz exceeds the element pickup setting, and asserts 24C2T Relay Word bit after a delay determined by the characteristic setting. The relay tracks the frequency over the range 20 to 70 Hz.

Volts/hertz tripping elements are usually used to trip the transformer breaker. Volts/hertz logic is discussed in the following section.

Figure 4.37 and Figure 4.38 are similar to *IEEE C37.102 : 2006 IEEE Guide for AC Generator Protection Figure 4.5.4-1 and Figure 4.5.4-2.*

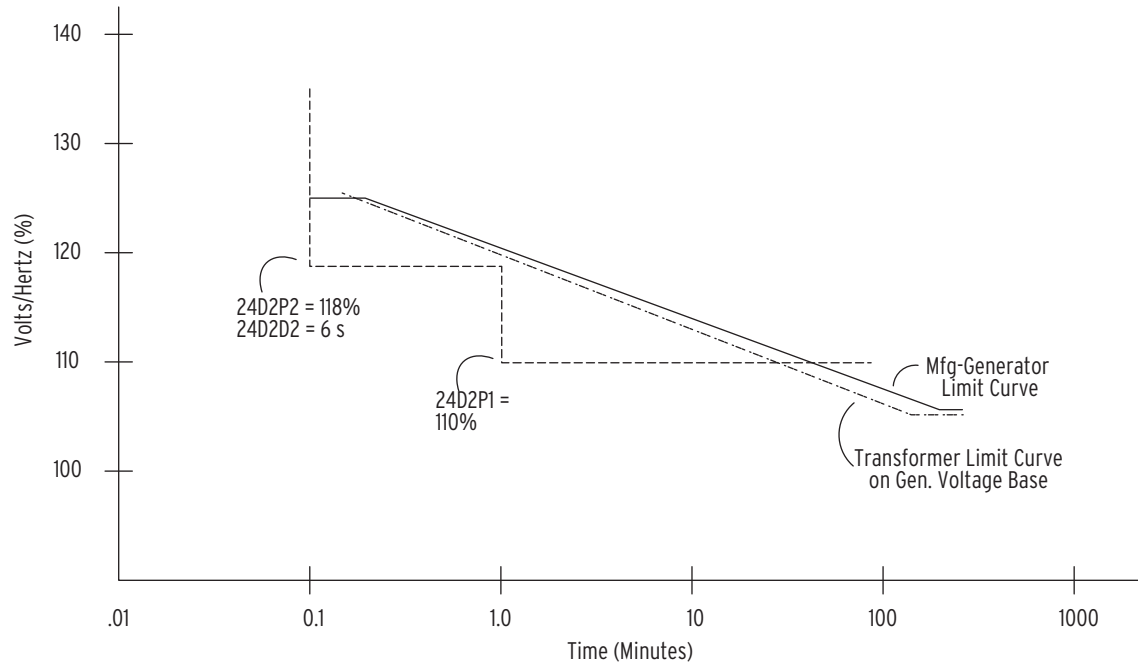


Figure 4.37 Dual-Level Volts/Hertz Time-Delay Characteristic, 24CCS = DD

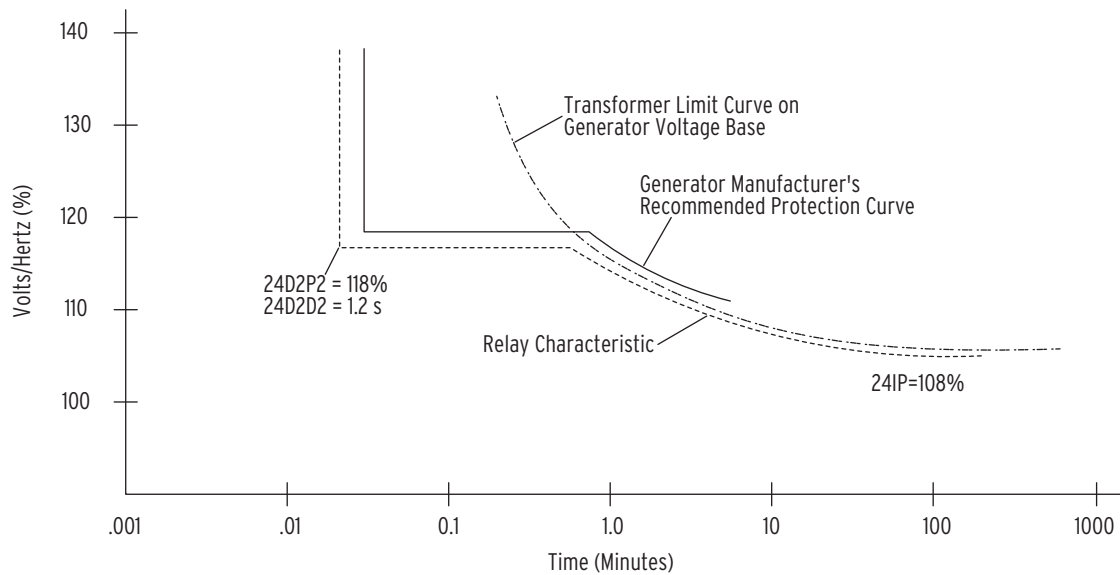


Figure 4.38 Composite Inverse/Definite-Time Overexcitation Characteristic, 24CCS = ID

Table 4.21 Volts Per Hertz Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-------------------|-------------------|------------------------------------|
| ENABLE V/HZ PROT | Y, N | E24 := Y |
| XFMR WDG CONN | DELTA, WYE | 24WDG := WYE |
| LVL1 V/HZ PICKUP | 100–200 % | 24D1P := 105 |
| LVL1 TIME DLY | 0.04–400.00 sec | 24D1D := 1.00 |
| LVL2 CURVE SHAPE | OFF, DD, ID, I, U | 24CCS := ID |
| LVL2 INV-TM PU | 100–200 % | 24IP := 105 |
| LVL2 INV-TM CURV | 0.5, 1.0, 2.0 | 24IC := 2.0 |
| LVL2 INV-TM FCTR | 0.1–10.0 sec | 24ITD := 0.1 |
| LVL2 PICKUP 2 | 101–200 % | 24D2P2 := 176 |
| LVL2 TIME DLY 2 | 0.04–400.00 s | 24D2D2 := 3.00 |
| LVL2 RESET TIME | 0.00–400.00 s | 24CR := 240.00 |
| 24 ELEM TRQ-CNTRL | SELOGIC | 24TC := 1 |

Collect this information before calculating volts/hertz element settings:

- Transformer manufacturer's overexcitation limit curve
- Transformer nominal phase-phase voltage

Select the transformer winding that is most likely to suffer overexcitation. The relay voltage input should be from a source that most reliably reflects that winding voltage.

Set E24 := Y to enable volts/hertz protection elements. If you do not need volts/hertz protection, set E24 := N. When E24 := N, the 24TC, 24D1, 24D1T, 24C2, 24C2T, and 24CR Relay Word bits are inactive. The relay hides corresponding settings; you do not need to enter these settings.

When three PTs are available, the most common PT winding connection is to connect both HV and LV sides in wye, leaving the power transformer winding connections as the only variable. For wye-connected power transformer windings, the power transformer phase-to-neutral voltage is readily measured through wye-wye connected PTs. Set 24WDG := WYE. When the power transformer windings are delta connected, the relay cannot measure the phase voltage directly, but needs to calculate the voltage values. The relay calculates the differences between the voltages presented to the relay from the wye-wye connected PTs and thus the voltage connected to the power transformer windings. Set 24WDG := DELTA. Thus, voltage values selection to calculate the volts/hertz protection and sequence components is based on the 24WDG selection; phase to phase for 24WDG := DELTA and phase-to-neutral for 24WDG = WYE.

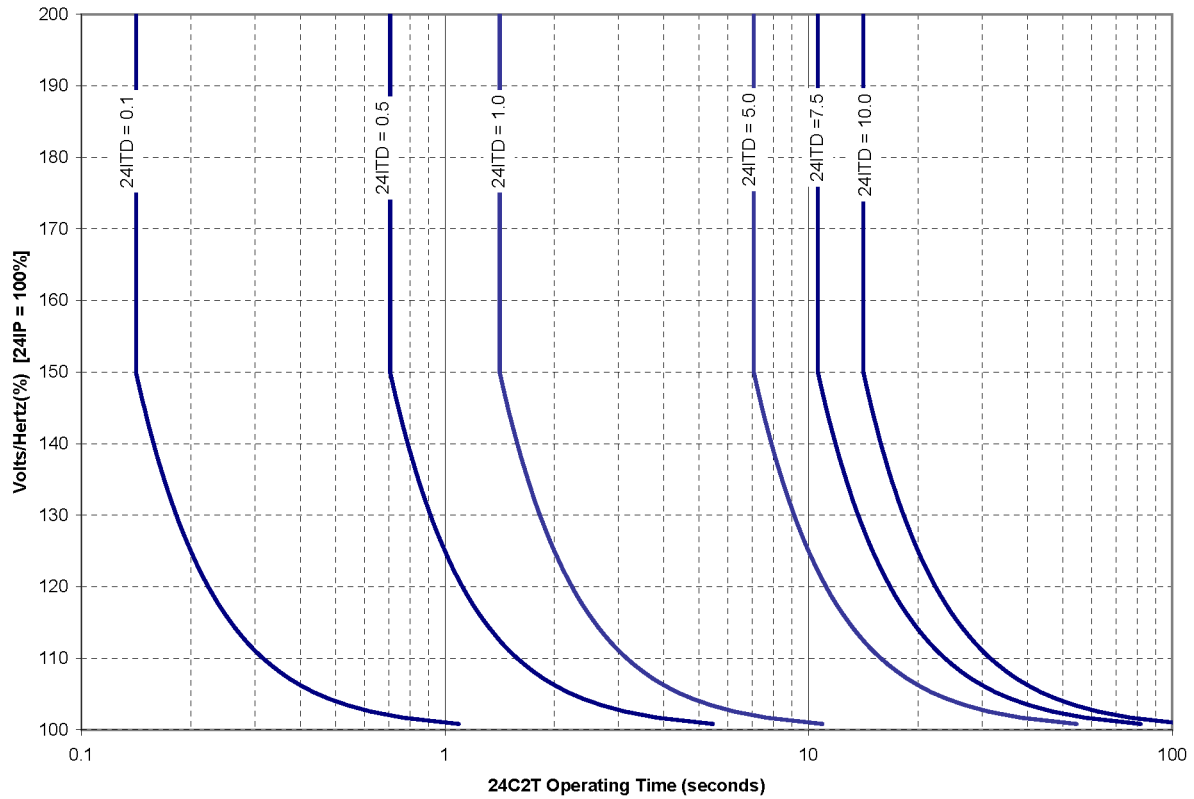
Use the Level 1 volts/hertz element as an overexcitation alarm. Set 24D1P equal to or greater than 105 percent, but less than the minimum pickup of the Level 2 element. Use a 24D1D time delay of 1.0 second to allow time for correction of an overexcitation condition prior to an alarm.

The 24CCS setting defines the overexcitation tripping element time-delay characteristic as shown in *Figure 4.34*. Set 24CCS := OFF if you do not require Level 2 volts/hertz protection. When 24CCS := OFF, the other Level 2 settings are hidden and do not need to be entered.

- When 24CCS := DD the element operates with a dual-level definite-time characteristic with pickup and delay of 24D2Pn and 24D2Dn (n = 1 or 2).
- When 24CCS := ID the element operates with a composite inverse-time and definite-time characteristic with pickup of 24IP (Inverse-time) and 24D2P2 (definite-time). The 24IC and 24ITD settings define the inverse-time curve shape (see *Table 4.37* through *Table 4.39*).
- When 24CCS := I the element operates with a simple inverse-time characteristic, defined by the 24IP, 24IC and 24ITD settings described above.
- When 24CCS := U the element operates with a user-defined inverse-time characteristic with a pickup of 24IP. The user curve should be set using SEL-5806 PC Software. This program handles individual mapping of points to make a curve that matches any transformer characteristic. It also handles all relay communication by either uploading the current curve or programming a new curve.

The 24CR setting defines the composite element reset time. When the element times out to trip, it will fully reset 24CR seconds after the applied volts/hertz drops below the element pickup setting. The reset characteristic is linear, so if the element times 60 percent toward a trip, it will fully reset $(0.6 \cdot 24CR)$ seconds after the applied volts/hertz drops below the element pickup setting. When the element is reset, the relay asserts the 24CR Relay Word bit.

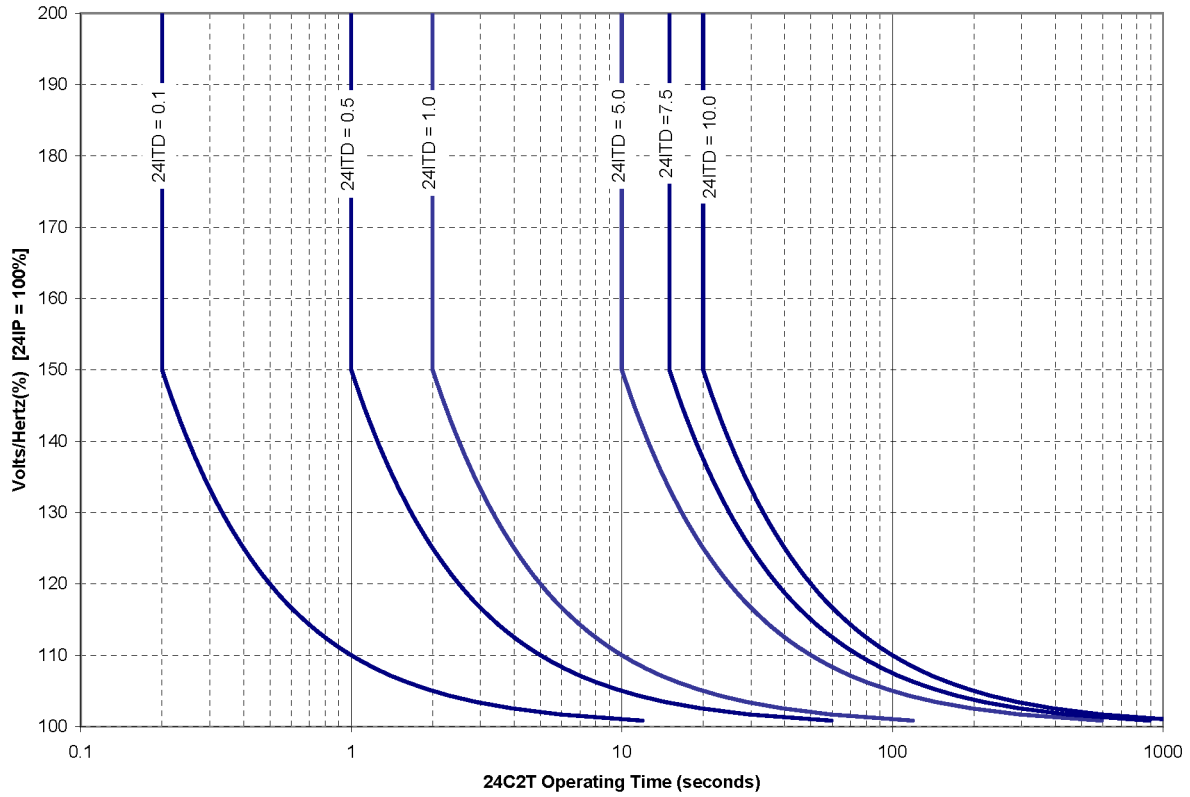
Both volts/hertz elements are disabled when the 24TC SELOGIC control equation equals logical 0. The elements are allowed to operate when the 24TC SELOGIC control equation equals logical 1, the default setting. You can add other supervisory conditions if you need these for your application.



$$t_p = \frac{24ITD}{\left(\left(\frac{\frac{VPP \cdot PTR}{freq} \cdot \frac{FNOM}{VNOM \cdot 10^3}}{\frac{24IP}{100}} \right) - 1 \right)^{0.5}} \text{ seconds} \quad \text{if } V/Hz \leq 1.5 \cdot 24IP$$

$$t_p = 1.414 \cdot 24ITD \text{ seconds} \quad \text{if } V/Hz > 1.5 \cdot 24IP$$

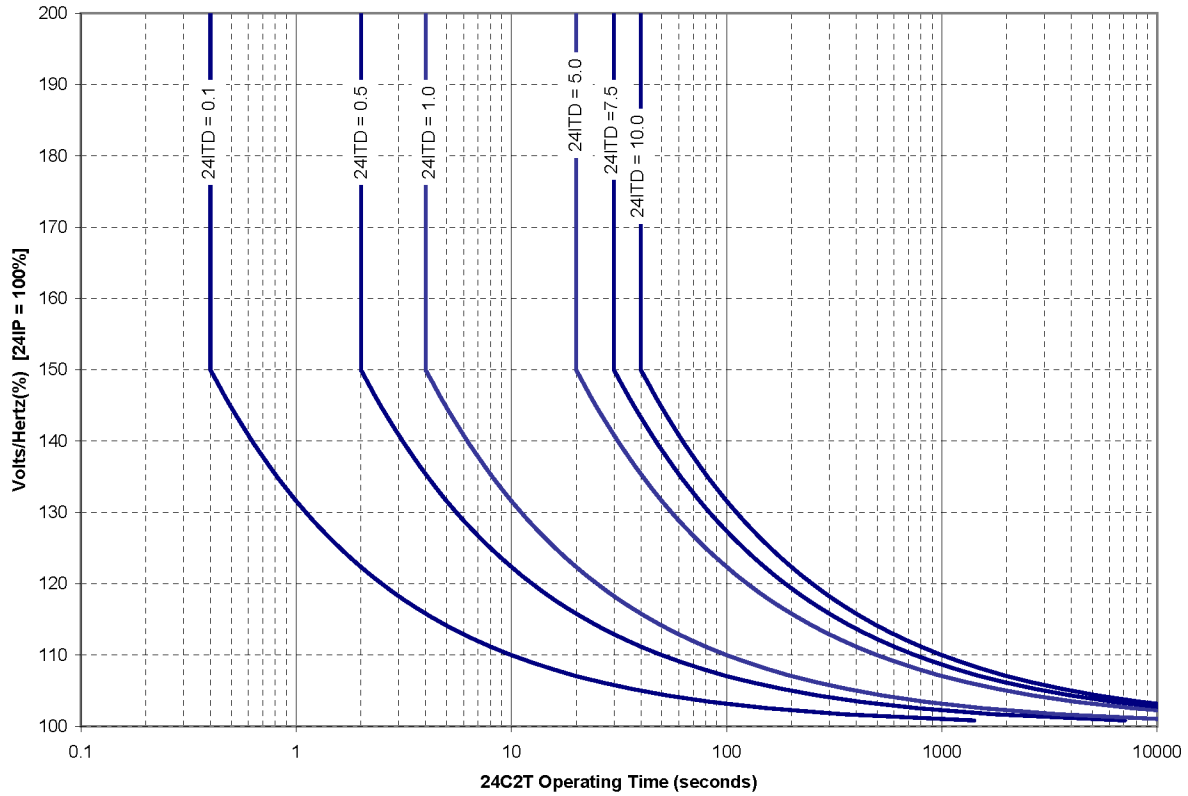
Figure 4.39 Volts/Hertz Inverse-Time Characteristic, 24IC = 0.5



$$t_p = \frac{24ITD}{\left(\left(\frac{\frac{VPP \cdot PTR}{freq} \cdot \frac{FNOM}{VNOM \cdot 10^3}}{\frac{24IP}{100}} \right) - 1 \right)^{1.0}} \text{ seconds} \quad \text{if } V/Hz \leq 1.5 \cdot 24IP$$

$$t_p = 2.0 \cdot 24ITD \text{ seconds} \quad \text{if } V/Hz > 1.5 \cdot 24IP$$

Figure 4.40 Volts/Hertz Inverse-Time Characteristic, 24IC = 1



$$t_p = \frac{24ITD}{\left(\frac{\frac{VPP \cdot PTR}{freq} \cdot \frac{FNOM}{VNOM \cdot 10^3}}{\frac{24IP}{100}} - 1 \right)^{2.0}} \text{ seconds} \quad \text{if } V/Hz \leq 1.5 \cdot 24IP$$

$$t_p = 4.0 \cdot 24ITD \text{ seconds} \quad \text{if } V/Hz > 1.5 \cdot 24IP$$

Figure 4.41 Volts/Hertz Inverse-Time Characteristic, 24IC = 2

Power Elements

You can enable as many as two independent three-phase power elements in the SEL-787 relay. Each enabled element can be set to detect real power or reactive power. When voltage inputs to the relay are from delta connected PTs or when single voltage input is used, the relay cannot account for unbalance in the voltages in calculating the power. Take this into consideration in applying the power elements.

With SELOGIC control equations, the power elements provide a wide variety of protection and control applications. Typical applications are:

- Overpower and/or underpower protection/control
- Reverse power protection/control
- VAR control for capacitor banks

Table 4.22 Power Element Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|---|------------------------------------|
| ENABLE PWR ELEM | N, 3P1, 3P2 | EPWR := N |
| 3PH PWR ELEM PU | OFF, 1.0–6500.0 VA (secondary) ^a | 3PWR1P := OFF |
| PWR ELEM TYPE | +WATTS, –WATTS, +VARS, –VARS | PWR1T := +VARS |
| PWR ELEM DELAY | 0.0–240.0 sec | PWR1D := 0.0 |
| 3PH PWR ELEM PU | OFF, 1.0–6500.0 VA (secondary) ^a | 3PWR2P := OFF |
| PWR ELEM TYPE | +WATTS, –WATTS, +VARS, –VARS | PWR2T := +VARS |
| PWR ELEM DELAY | 0.0–240.0 sec | PWR2D := 0.0 |

^a The range shown is for 5 A input; range for 1 A input is OFF, 0.2–1300.0 VA.

EPWR := 3P1 enables one three-phase power element. Set EPWR := 3P2 if you want to use both elements.

Set the element pickup, 3PH PWR ELEM PU to desired values in secondary VA units. *Figure 4.42* shows the power element logic diagram and *Figure 4.43* shows the operation in the Real/Reactive power plane.

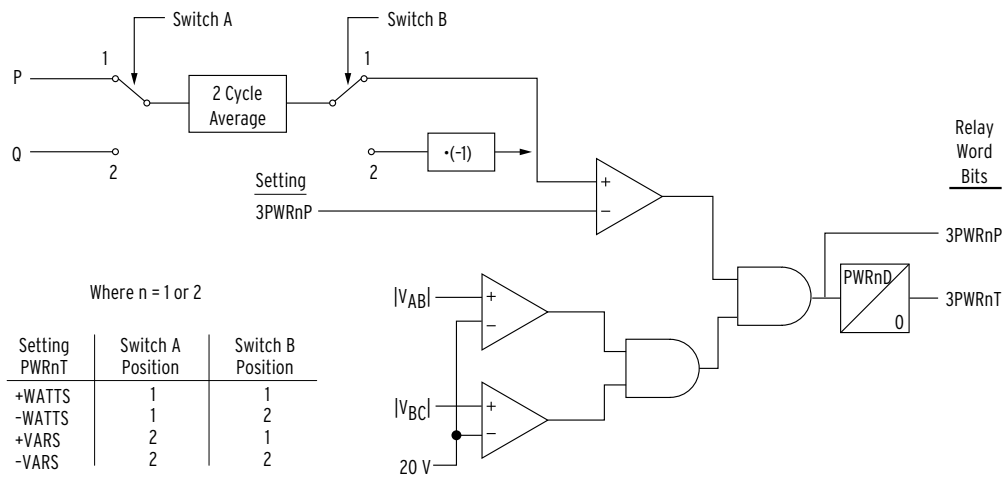


Figure 4.42 Three-Phase Power Elements Logic

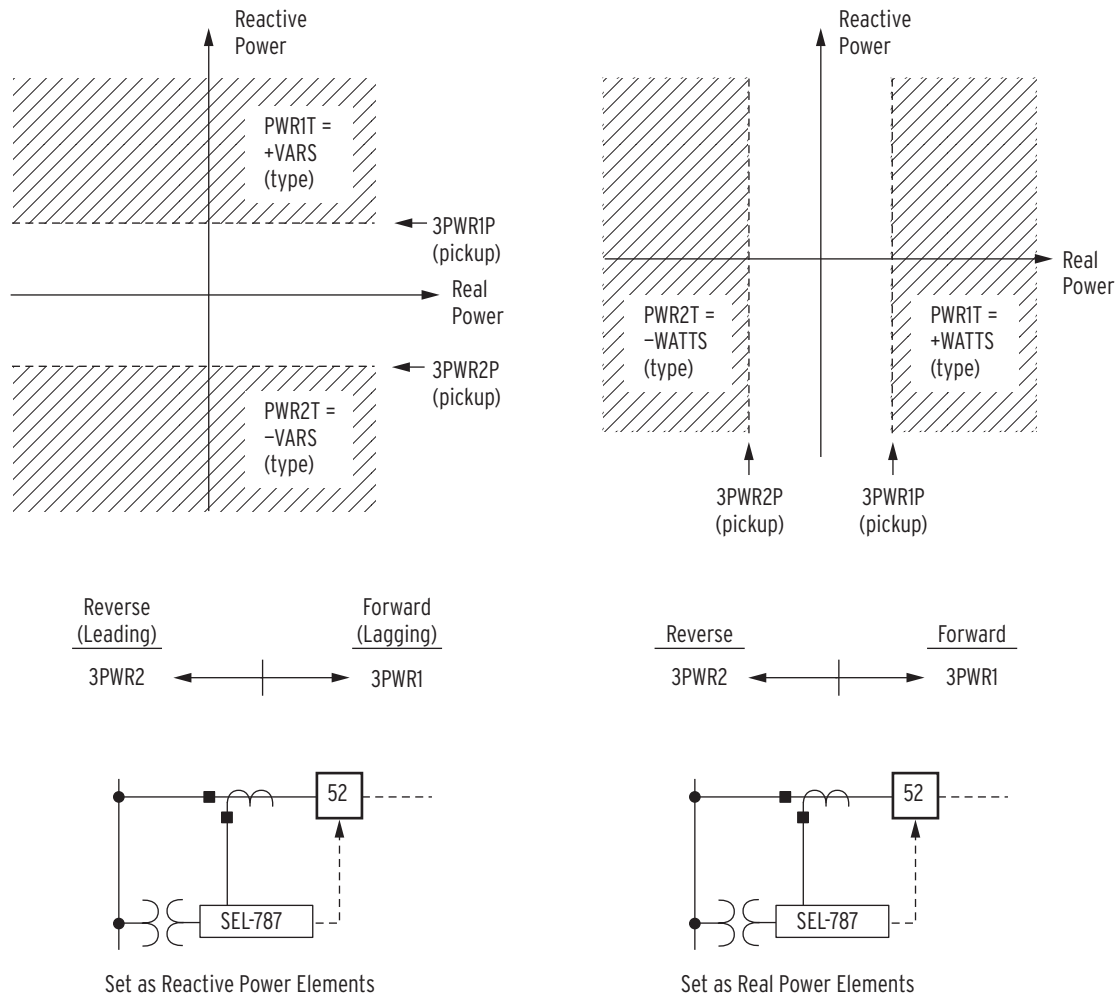


Figure 4.43 Power Elements Operation in the Real/Reactive Power Plane

The power element type settings are made in reference to the load convention:

- +WATTS: positive or forward real power
- -WATTS: negative or reverse real power
- +VARS: positive or forward reactive power (lagging)
- -VARS: negative or reverse reactive power (leading)

The two power element time delay settings ($PWR1D$ and $PWR2D$) can be set to have no intentional delay for testing purposes. For protection applications involving the power element Relay Word bits, SEL recommends a minimum time delay setting of 0.1 second for general applications. The classical power calculation is a product of voltage and current, to determine the real and reactive power quantities. During a system disturbance, because of the high sensitivity of the power elements, the changing system phase angles and/or frequency shifts may cause transient errors in the power calculation.

The power elements are not supervised by any relay elements other than the minimum voltage check shown in *Figure 4.42*. If the protection application requires overcurrent protection in addition to the power elements, there may be a race condition, during a fault, between the overcurrent element(s) and the power element(s) if the power element(s) are still receiving sufficient operating quantities. Use the power element time delay setting to avoid such race conditions.

Frequency Elements

Table 4.23 Frequency Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|-------------------|------------------------------------|
| FREQ1 TRIP LEVEL | OFF, 20.0–70.0 Hz | 81D1TP := OFF |
| FREQ1 TRIP DELAY | 0.0–240.0 sec | 81D1TD := 1.0 |
| FREQ2 TRIP LEVEL | OFF, 20.0–70.0 Hz | 81D2TP := OFF |
| FREQ2 TRIP DELAY | 0.0–240.0 sec | 81D2TD := 1.0 |
| FREQ3 TRIP LEVEL | OFF, 20.0–70.0 Hz | 81D3TP := OFF |
| FREQ3 TRIP DELAY | 0.0–240.0 sec | 81D3TD := 1.0 |
| FREQ4 TRIP LEVEL | OFF, 20.0–70.0 Hz | 81D4TP := OFF |
| FREQ4 TRIP DELAY | 0.0–240.0 sec | 81D4TD := 1.0 |

NOTE: The relay measures system frequency for these elements with the positive-sequence voltage if the applied positive-sequence voltage is greater than 0.75 volts for at least four cycles. Otherwise, the relay assumes the frequency is the same as the nominal frequency determined by the FNOM setting.

The SEL-787 provides four trip over- or underfrequency elements with independent level and time-delay settings. When an element level setting is less than the nominal frequency setting, the element operates as an underfrequency element. When the level setting is greater than the nominal frequency setting, the element operates as an overfrequency element. *Figure 4.44* shows the logic diagram for the frequency elements.

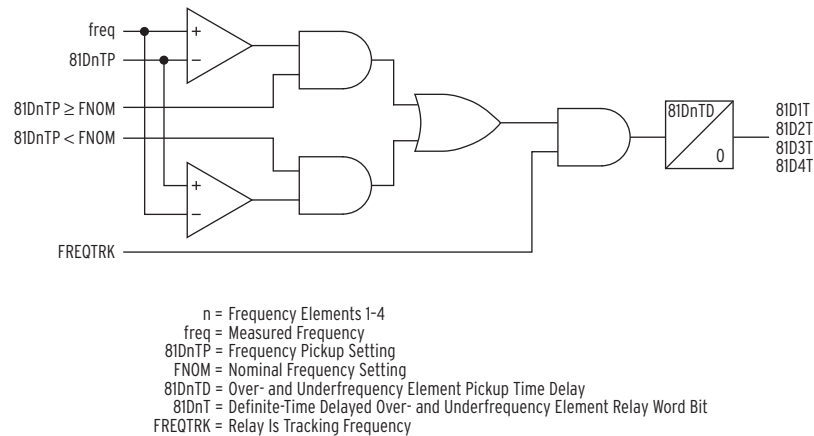


Figure 4.44 Over- and Underfrequency Element Logic

Loss-of-Potential (LOP) Protection

The SEL-787 sets Relay Word bit LOP (loss-of-potential) upon detecting a loss of relay ac voltage input such as that caused by blown potential fuses or by the operation of molded-case circuit breakers. Because accurate relaying potentials are required by certain protection elements (undervoltage 27 elements, for example), you can use the LOP function to supervise these protection elements.

The relay declares an LOP when there is more than a 25 percent drop in the measured positive-sequence voltage (V1) with no corresponding magnitude or angle change (above a pre-determined threshold) in positive-sequence (I1), negative-sequence (I2), or zero-sequence currents (I0).

If this condition persists for 60 cycles, then the relay latches the LOP Relay Word bit at logical 1. The relay resets LOP when the positive-sequence voltage (V1) returns to a level greater than $0.75 \cdot \text{Nominal Voltage}$ while negative-sequence voltage (V2) and zero-sequence voltage (V0) are both less than 5 V secondary.

Settings

The LOP function has no settings and is always active. You must incorporate the LOP function in a SELOGIC control equation to supervise relay protection elements (see *Example 4.3*).

LOP Impact on Other Protection Elements

Undervoltage and directional power elements require accurate relaying potentials for correct operation. It is critical that the relay detects an LOP condition and prevents operation of these elements. For example, when dropping a wrench on the phase-voltage input fuse holders, the relay LOP logic accurately determines that this loss of input voltages is an LOP condition and does not trip (if the LOP Relay Word bit supervises selected tripping elements, see *Example 4.3*). If you are using voltage-determined relay elements for tripping decisions, then blocking these elements is crucial when the voltage component is no longer valid.

EXAMPLE 4.3 Supervising Voltage-Element Tripping With LOP

To supervise undervoltage by LOP one of the trip equations can be set as follows:

TR2:= ... **OR ((27P1T OR 27P2T) AND NOT LOP)**

Similarly, if you want the additional voltage-affected elements (e.g., 3PWRT) to act only when there are correct relaying potentials voltage, use the following in the equation:

... **OR ((27P1T OR 27P2T OR 3PWRT) AND NOT LOP)**

You can supervise each element separately or as a group when these elements occur in the trip equations, as shown in this example.

LOP Monitoring and Alarms

You should take steps to immediately correct an LOP problem so that normal protection is rapidly re-established. Include the LOP Relay Word bit in an output contact alarm to notify operation personnel of abnormal voltage input conditions and failures that can be detrimental to the protection system performance if not quickly corrected.

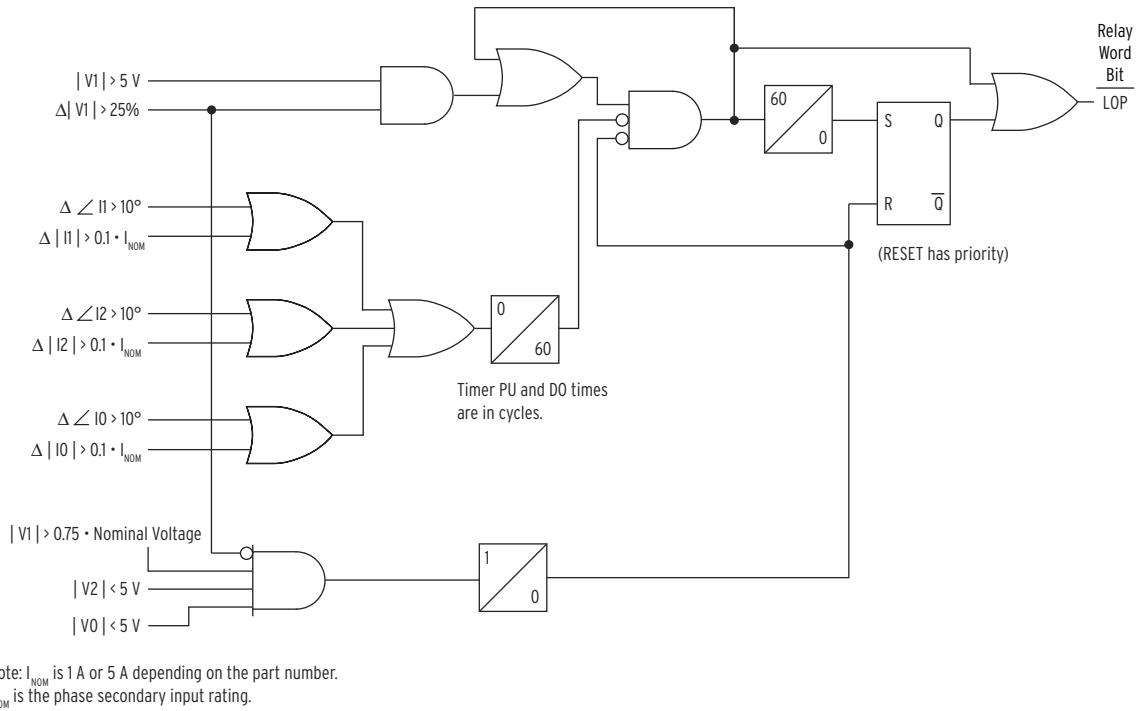


Figure 4.45 Loss-of-Potential (LOP) Logic

Demand Metering

The SEL-787 provides demand and peak demand metering, selectable between thermal and rolling demand types, for the following values for either Winding 1 or Winding 2 currents:

- IA, IB, IC, phase currents (A primary)
- IG Residual ground current (A primary; $IG = 3I_0 = IA + IB + IC$)
- 3I2 Negative-sequence current (A primary)

Table 4.24 shows the demand metering settings. Also refer to *Section 5: Metering and Monitoring* and *Section 7: Communications* for other related information for the demand meter.

Table 4.24 Demand Meter Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---|--|
| ENABLE DEM MTR | OFF, W1, W2 | EDEM := OFF |
| DEMAND MTR TYPE | THM, ROL | DEMTY := THM |
| DEM TIME CONSTNT | 5, 10, 15, 30, 60 min | DMTC := 5 |
| PH CURR DEM LVL | OFF, 0.50-16.00 A ^a OFF, 0.10-3.20 A ^b | PHDEMP := 5.00 ^a PHDEMP := 1.00 ^b |
| RES CURR DEM LVL | OFF, 0.50-16.00 A ^a OFF, 0.10-3.2 A ^b | GNDEMP := 1.00 ^a GNDEMP := 0.20 ^b |
| 3I2 CURR DEM LVL | OFF, 0.50-16.00 A ^a OFF, 0.10-3.2 A ^b | 3I2DEMP := 1.00 ^a 3I2DEMP := 0.20 ^b |

^a For $I_{nom} = 5$ A.

^b For $I_{nom} = 1$ A.

The demand current level settings are applied to demand current meter outputs as shown in *Figure 4.46*. For example, when residual ground demand current IGD goes above corresponding demand pickup GNDAMP, Relay Word bit GNDAMP asserts to logical 1. Use these demand current logic outputs (PHDEM, GNDAMP, and 3I2DAMP) to alarm for high loading or unbalance conditions.

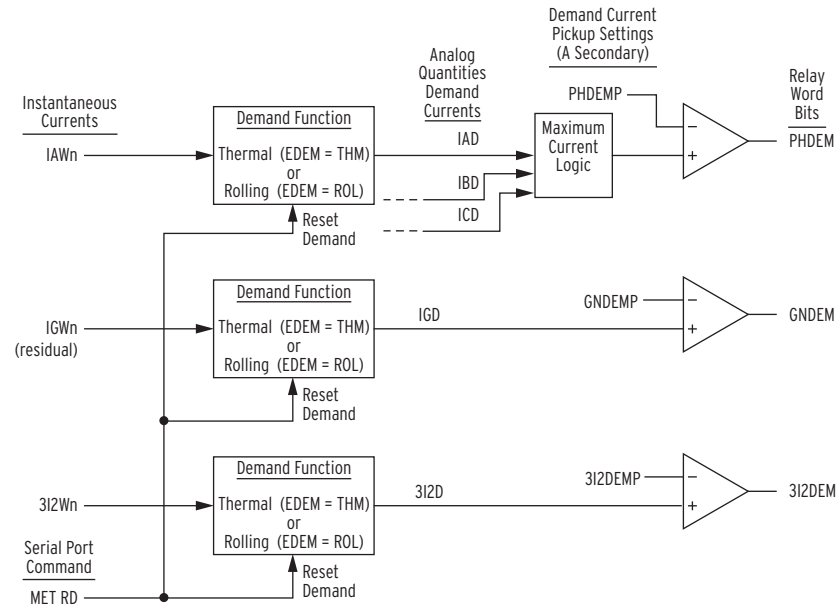


Figure 4.46 Demand Current Logic Outputs

The demand values are updated approximately once a second. The relay stores peak demand values to nonvolatile storage every six hours (it overwrites the previous stored value if it is exceeded). Should the relay lose control power, it will restore the peak demand values saved by the relay.

Demand metering peak recording is momentarily suspended when SELOGIC control equation setting FAULT is asserted (= logical 1).

The differences between thermal and rolling demand metering are explained in the following discussion.

Comparison of Thermal and Rolling Demand Meters

The example in *Figure 4.47* shows the response of thermal and rolling demand meters to a step current input. The current input is at a magnitude of zero and then suddenly goes to an instantaneous level of 1.0 per unit (a “step”).

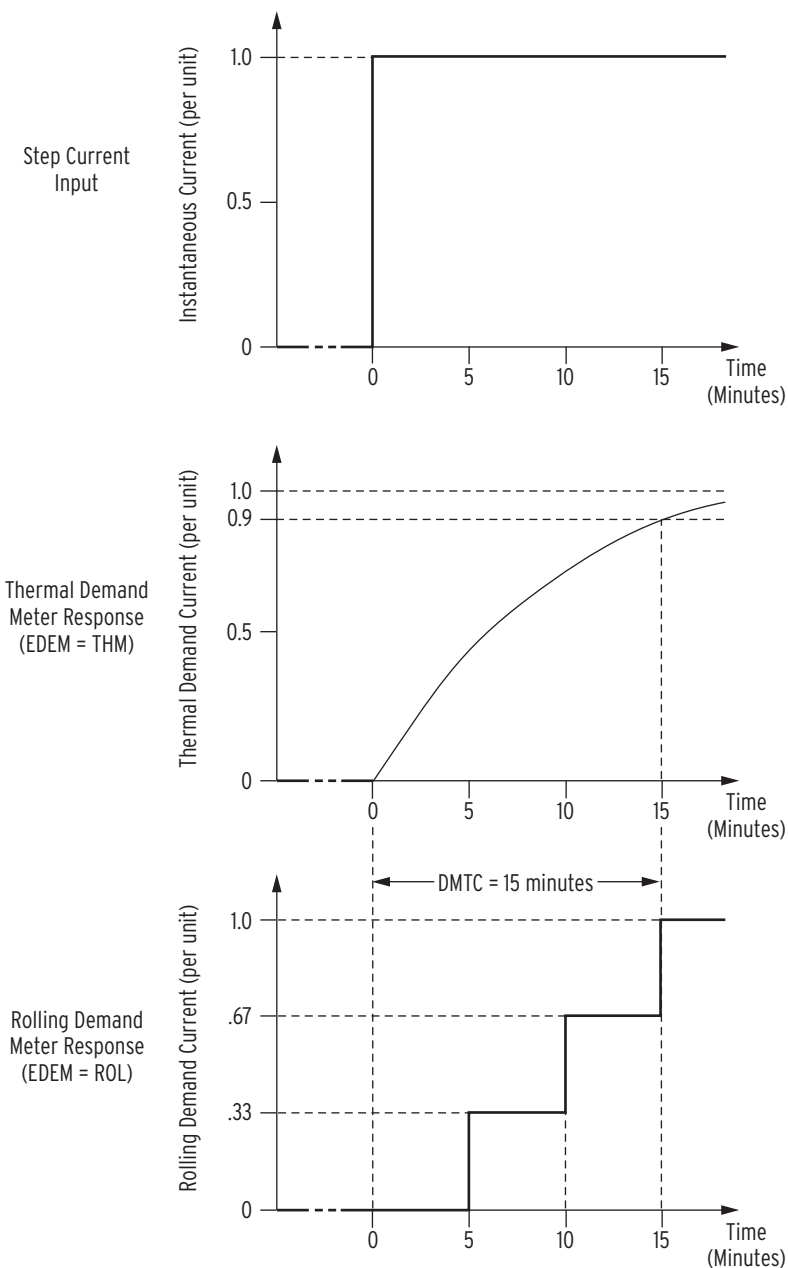


Figure 4.47 Response of Thermal and Rolling Demand Meters to a Step Input (Setting DMTC = 15 minutes)

Thermal Demand Meter Response

The response of the thermal demand meter in *Figure 4.47* (middle) to the step current input (top) is analogous to the series RC circuit in *Figure 4.48*.

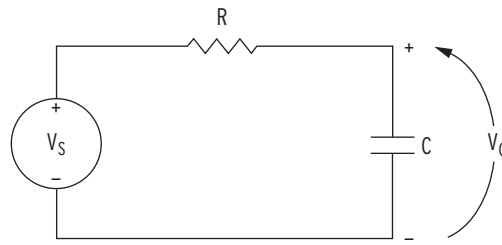


Figure 4.48 Voltage V_S Applied to Series RC Circuit

In the analogy:

Voltage V_S in *Figure 4.48* corresponds to the step current input in *Figure 4.47* (top).

Voltage V_C across the capacitor in *Figure 4.48* corresponds to the response of the thermal demand meter in *Figure 4.47* (middle).

If voltage V_S in *Figure 4.48* has been at zero ($V_S = 0.0$ per unit) for some time, voltage V_C across the capacitor in *Figure 4.48* is also at zero ($V_C = 0.0$ per unit). If voltage V_S is suddenly stepped up to some constant value ($V_S = 1.0$ per unit), voltage V_C across the capacitor starts to rise toward the 1.0 per unit value. This voltage rise across the capacitor is analogous to the response of the thermal demand meter in *Figure 4.47* (middle) to the step current input (top).

In general, as voltage V_C across the capacitor in *Figure 4.48* cannot change instantaneously, the thermal demand meter response is not immediate either for the increasing or decreasing applied instantaneous current. The thermal demand meter response time is based on the demand meter time constant setting DMTC (see *Table 4.24*). Note in *Figure 4.47*, the thermal demand meter response (middle) is at 90 percent (0.9 per unit) of full applied value (1.0 per unit) after a time period equal to setting DMTC = 15 minutes, referenced to when the step current input is first applied.

The SEL-787 updates thermal demand values approximately every second.

Rolling Demand Meter Response

The response of the rolling demand meter in *Figure 4.47* (bottom) to the step current input (top) is calculated with a sliding time-window arithmetic average calculation. The width of the sliding time-window is equal to the demand meter time constant setting DMTC (see *Table 4.24*). Note in *Figure 4.47*, the rolling demand meter response (bottom) is at 100 percent (1.0 per unit) of full applied value (1.0 per unit) after a time period equal to setting DMTC = 15 minutes, referenced to when the step current input is first applied.

The rolling demand meter integrates the applied signal (e.g., step current) input in five-minute intervals. The integration is performed approximately every second. The average value for an integrated five-minute interval is derived and stored as a five-minute total. The rolling demand meter then averages a number of the five-minute totals to produce the rolling demand meter response. In the *Figure 4.47* example, the rolling demand meter averages the three latest five-minute totals because setting DMTC = 15 ($15/5 = 3$). The rolling demand meter response is updated every five minutes, after a new five-minute total is calculated.

The following is a step-by-step calculation of the rolling demand response example in *Figure 4.47* (bottom).

Time = 0 Minutes

Presume that the instantaneous current has been at zero for quite some time before “Time = 0 minutes” (or the demand meters were reset). The three five-minute intervals in the sliding time-window at “Time = 0 minutes” each integrate into the following five-minute totals:

| Five-Minute Totals | Corresponding Five-Minute Interval |
|--------------------|------------------------------------|
| 0.0 per unit | –15 to –10 minutes |
| 0.0 per unit | –10 to –5 minutes |
| 0.0 per unit | –5 to 0 minutes |
| 0.0 per unit | |

Rolling demand meter response at “Time = 0 minutes” = $0.0/3 = 0.0$ per unit.

Time = 5 Minutes

The three five-minute intervals in the sliding time-window at “Time = 5 minutes” each integrate into the following five-minute totals:

| Five-Minute Totals | Corresponding Five-Minute Interval |
|--------------------|------------------------------------|
| 0.0 per unit | –10 to –5 minutes |
| 0.0 per unit | –5 to 0 minutes |
| 1.0 per unit | 0 to 5 minutes |
| 1.0 per unit | |

Rolling demand meter response at “Time = 5 minutes” = $1.0/3 = 0.33$ per unit.

Time = 10 Minutes

The three five-minute intervals in the sliding time-window at “Time = 10 minutes” each integrate into the following five-minute totals:

| Five-Minute Totals | Corresponding Five-Minute Interval |
|--------------------|------------------------------------|
| 0.0 per unit | –5 to 0 minutes |
| 1.0 per unit | 0 to 5 minutes |
| 1.0 per unit | 5 to 10 minutes |
| 2.0 per unit | |

Rolling demand meter response at “Time = 10 minutes” = $2.0/3 = 0.67$ per unit.

Time = 15 Minutes

The three five-minute intervals in the sliding time-window at “Time = 15 minutes” each integrate into the following 5-minute totals:

| Five-Minute Totals | Corresponding Five-Minute Interval |
|--------------------|------------------------------------|
| 1.0 per unit | 0 to 5 minutes |
| 1.0 per unit | 5 to 10 minutes |
| 1.0 per unit | 10 to 15 minutes |
| 3.0 per unit | |

Rolling demand meter response at “Time = 15 minutes” = $3.0/3 = 1.0$ per unit.

Trip/Close Logic

Trip/Close Logic Settings

Table 4.25 Trip/Close Logic Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|--|
| MIN TRIP TIME | 0.0–400.0 sec | TDURD := 0.5 |
| CLOSE 1 FAIL DLY | 0.0–400.0 sec | CFD1 := 0.5 |
| CLOSE 2 FAIL DLY | 0.0–400.0 sec | CFD2 := 0.5 |
| TRIP 1 EQUATION | SV | TR1 := 50P11T OR 51P1T OR 51Q1T OR NOT LT02 AND SV04T OR OC1 |
| TRIP 2 EQUATION | SV | TR2 := 51P2T OR 51Q2T OR LT02 AND SV04T OR OC2 |
| TRIP XFMR EQN | SV | TRXFMR := 87R OR 87U |
| REMOTE TRIP EQN | SV | REMTRIP := 0 |
| UNLATCH TRIP 1 | SV | ULTRIP1 := NOT (51P1P OR 51Q1P OR 52A1) |
| UNLATCH TRIP 2 | SV | ULTRIP2 := NOT (51P2P OR 51Q2P OR 52A2) |
| UNLATCH TRP XFMR | SV | ULTRXFMR := NOT (87R OR 87U) |
| BREAKER1 STATUS | SV | 52A1 := 0 |
| CLOSE1 EQUATION | SV | CL1 := SV03T AND NOT LT02 OR CC1 |
| UNLATCH CLOSE 1 | SV | ULCL1 := TRIP1 OR TRIPXFMR |
| BREAKER 2 STATUS | SV | 52A2 := 0 |
| CLOSE 2 EQUATION | SV | CL2 := SV03T AND LT02 OR CC2 |
| UNLATCH CLOSE 2 | SV | ULCL2 := TRIP2 OR TRIPXFMR |

The trip logic and close logic for the SEL-787 operate in a similar manner. Each has a SELOGIC control equation setting to set or latch the logic and another SELOGIC control equation setting to reset or unlatch the logic. Each also has other elements or functions that will unlatch the logic. The output of each logic is a Relay Word bit that can be assigned to operate output contacts, or in any other manner for which a Relay Word bit can be used. The specifics of each type of logic are discussed below.

TDURD Minimum Trip Time

This timer establishes the minimum time duration for which the TRIP Relay Word bits assert. This is a rising-edge initiated timer.

Trips initiated by TR_m ($m = 1, 2, \text{XFMR}$) Relay Word bits (includes **OPEN** command from front-panel and serial ports) are maintained for at least the duration of the minimum trip duration time (TDURD) setting.

TR Trip Conditions SELOGIC Control Equations

There are three trip logic equations within the SEL-787. They are designed to operate when SELOGIC control equation trip variable setting TR_m is asserted ($m = 1, 2, \text{XFMR}$), and to unlatch when SELOGIC control equation setting $ULTR_m$ is asserted. The TR1 and TR2 are intended for breaker 1 and 2 respectively and the TRXFMR for the transformer lockout relay. The output of the logic is Relay Word bit $TRIP_m$.

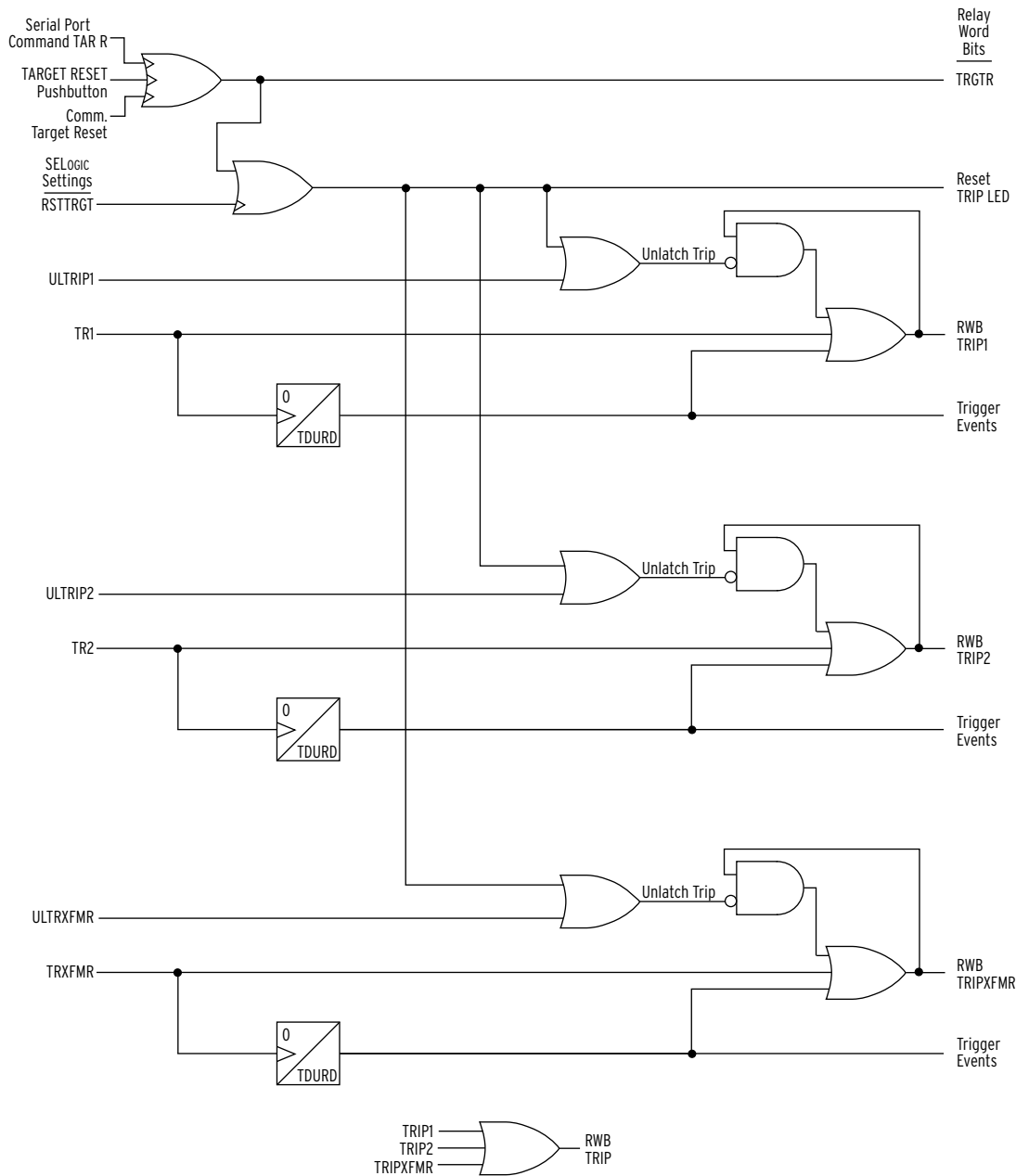


Figure 4.49 Trip Logic

The relay controls the tripping output contact(s) when the Relay Word bit $TRIP_m$ appears in an output contact SELOGIC control equation. Default relay settings have output **OUT103** set to **TRIPXFM** (see *Table 4.33*). Assign Relay Word bits **TRIP1** and **TRIP2** to other available outputs as required by your application. See *Figure 2.24* for typical trip circuit connection.

Set the TR_m SELOGIC control equations to include an OR-combination of all the Relay Word bits that you want to cause the associated trip bits to assert. The factory-default setting already includes all commonly required Relay Word bits.

REMTRIP Remote Trip Conditions SELOGIC Control Equation

You can map any Relay Word bit or SELOGIC equation to the REMTRIP to trip a breaker or the transformer. For example, you can map a control input to REMTRIP and map the REMTRIP to appropriate TR_m equation.

Unlatch Trip Logic

Each of the three trip logic equations has an associated unlatch trip SELOGIC equation. Following a fault, the appropriate trip signal is maintained until all of the following conditions are true:

NOTE: The factory-default setting of the ULTRIP provides an automatic reset of the trip when the breaker opens and selected 50/51 elements are not picked up.

- Minimum trip duration time (TDURD) passes.
- The TR_m ($m = 1, 2, \text{XFMR}$) SELOGIC control equation result deasserts to logical 0.
- One of the following occurs:
 - Unlatch Trip SELOGIC control equation setting ULTRIP asserts to logical 1.
 - Target Reset SELOGIC control equation setting RSTTRGT asserts to logical 1.
 - Target Reset Relay Word TRGTR asserts. The TRGTR is asserted when the front-panel **TARGET RESET** pushbutton is pressed or a target reset serial port command is executed (ASCII, Modbus, or DeviceNet).

52A Breaker Status Conditions SELOGIC Control Equations

You can connect an auxiliary contact of the high and low side breaker to the relay. The SELOGIC control equations 52A1 and 52A2 allow you to configure the relay for either 52b or 52a contact input (or other contact that indicates a closed breaker). The factory-default setting assumes no auxiliary contact connection (both 52A1 and 52A2 := 0).

If you connect the breaker auxiliary contact to a digital input, you must change the factory-default logic equation. For example, set 52A1 := IN101 if you connect the 52a contact of breaker 52-1 to input IN101.

Figure 4.50 shows a close logic diagram of breaker 52-1; the logic of breaker 52-2 is similar.

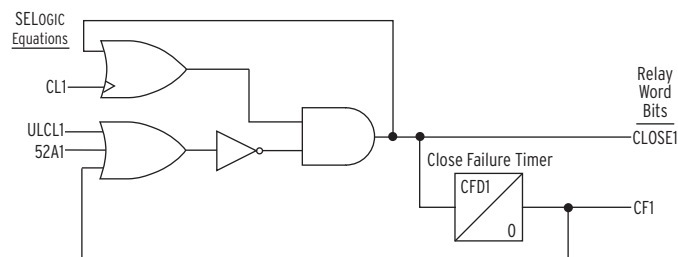


Figure 4.50 Close Logic

CL Close SELOGIC Control Equation

There are two close logic equations within the SEL-787. They are designed to operate when SELOGIC control equation close variable setting CL_m is asserted ($m = 1, 2$) and to unlatch when SELOGIC control equation setting $ULCL_m$ is asserted. The output of the logic is Relay Word bits $CLOSE_m$.

The relay controls the closing output contact(s) when the Relay Word bit $CLOSE_m$ appears in an output contact SELOGIC control equation. Assign the CLOSE bits to desired output relays as required by your application. See *Figure 2.20* for typical close circuit connection.

Set the CL_m SELOGIC control equations to include an OR-combination of all Relay Word bits that you want to cause the associated close bits to assert. The factory-default setting already includes all commonly required Relay Word bits.

Unlatch Close Logic

Each of the two close logic equations has an associated unlatch close SELOGIC equation. Once a CLOSE bit is asserted it is sealed-in until all of the following conditions are true:

- Unlatch Close SELOGIC control equation setting $ULCL_1$ (or $ULCL_2$) asserts to logical 1.
- Relay Word 52A1 (or 52A2) asserts to logical 1.
- Close failure Relay Word bit asserts to logical 1.

Close Failure Logic

Each of the two close logic equations includes a close failure detection with an associated delay setting (CFD_1 and CFD_2). Set the close failure delay equal to the longest close time of the breaker plus a safety margin. If the breaker fails to close, the Relay Word CF_1 (or CF_2) will assert for 1/4 cycle. Use the CF bits as desired.

Logic Settings (SET L Command)

Settings associated with latches, timers, counters, math variables, and output contacts are listed below. Note that SELOGIC equations are processed every quarter cycle while math variable equations and analog quantities are updated every 100 ms.

SELOGIC Enables

IMPORTANT: Upon relay initial power up or Port 1 setting changes or Logic setting changes, the user may have to wait as long as two minutes before an additional setting change can occur. Note that the relay is functional with protection enabled, as soon as the **ENABLED LED** comes on (approximately 5–10 seconds from power up).

Table 4.26 shows the enable settings for latch bits (ELAT), SELOGIC control equations (including timers) (ESV), Counters (ESC), and math variable equations (EMV). This helps limit the number of settings that you need to make. For example, if you need six timers, only enable six timers.

Table 4.26 Enable Settings

| Setting Prompt | Setting Range | Default Setting |
|------------------|---------------|-----------------|
| SELOGIC Latches | N, 1–32 | ELAT := 4 |
| SV/Timers | N, 1–32 | ESV := 5 |
| SELOGIC Counters | N, 1–32 | ESC := N |
| Math Variables | N, 1–32 | EMV := N |

Latch Bits

Latch control switches (latch bits are the outputs of these switches) replace traditional latching devices. Traditional latching devices maintain output contact state. The SEL-787 latch control switch also retains state even when power to the device is lost. If the latch control switch is set to a programmable output contact and power to the device is lost, the state of the latch control switch is stored in nonvolatile memory, but the device de-energizes the output contact. When power to the device is restored, the programmable output contact will go back to the state of the latch control switch after device initialization. Traditional latching device output contact states are changed by pulsing the latching device inputs (see *Figure 4.51*). Pulse the set input to close (set) the latching device output contact. Pulse the reset input to open (reset) the latching device output contact. The external contacts wired to the latching device inputs are often from remote control equipment (e.g., SCADA, RTU).

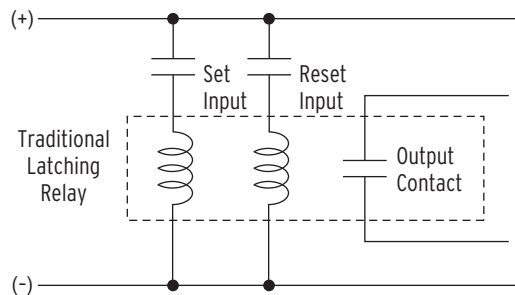


Figure 4.51 Schematic Diagram of a Traditional Latching Device

Thirty-two latch control switches in the SEL-787 provide latching device functionality. *Figure 4.52* shows the logic diagram of a latch switch. The output of the latch control switch is a Relay Word bit LTn ($n = 01-32$), called a latch bit.

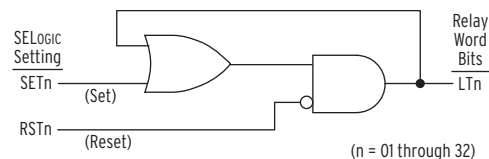


Figure 4.52 Logic Diagram of a Latch Switch

If setting $SETn$ asserts to logical 1, latch bit LTn asserts to logical 1. If setting $RSTn$ asserts to logical 1, latch bit LTn deasserts to logical 0. If both settings $SETn$ and $RSTn$ assert to logical 1, setting $RSTn$ has priority and latch bit LTn deasserts to logical 0. You can use these latch bits in SELOGIC control equations to create custom logic for your application.

The SEL-787 includes 32 latches. *Table 4.27* shows the **SET** and **RESET** default settings for Latch 1 through Latch 4. The remaining latches are all set to NA.

Table 4.27 Latch Bits Equation Settings

| Settings Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|---------------|--|
| SET01 | SELOGIC | SET01 := R_TRIG SV01T AND NOT LT01 |
| RST01 | SELOGIC | RST01 := R_TRIG SV01T AND LT01 |
| SET02 | SELOGIC | SET02 := R_TRIG SV02T AND NOT LT02 AND PB02 |
| RST02 | SELOGIC | RST02 := R_TRIG SV02T AND LT02 AND PB02 |
| SET03 | SELOGIC | SET03 := (PB03 AND R_TRIG SV02T) AND LT01 AND NOT (52A1 AND NOT LT02 OR 52A2 AND LT02) |
| RST03 | SELOGIC | RST03 := (R_TRIG SV02T OR SV03T) AND LT03 |
| SET04 | SELOGIC | SET04 := (PB04 AND R_TRIG SV02T) AND (52A1 AND NOT LT02 OR 52A2 AND LT02) |
| RST04 | SELOGIC | RST04 := (R_TRIG SV02T OR SV04T) AND LT04 |
| • | • | • |
| • | • | • |
| • | • | • |
| SET32 | SELOGIC | SET32 := NA |
| RST32 | SELOGIC | RST32 := NA |

Latch Bits: Nonvolatile State

Power Loss

The states of the latch bits (LT01–LT32) are retained if power to the device is lost and then restored. If a latch bit is asserted (e.g., LT02 := logical 1) when power is lost, it is asserted (LT02 := logical 1) when power is restored. If a latch bit is deasserted (e.g., LT03 := logical 0) when power is lost, it is deasserted (LT03 := logical 0) when power is restored.

Settings Change

If individual settings are changed, the states of the latch bits (Relay Word bits LT01 through LT32) are retained, as in the preceding *Power Loss* on page 4.70 explanation. If the individual settings change causes a change in SELOGIC control equation settings SET n or RST n ($n = 1$ through 32), the retained states of the latch bits can be changed, subject to the newly enabled settings SET n or RST n .

Make Latch Control Switch Settings With Care

The latch bit states are stored in nonvolatile memory so they can be retained during power loss or settings change. The nonvolatile memory is rated for a finite number of writes for all cumulative latch bit state changes. Exceeding the limit can result in a flash self-test failure. *An average of 5000 cumulative latch bit state changes per day can be made for a 25-year device service life.*

Settings SET n and RST n cannot result in continuous cyclical operation of latch bit LT n . Use timers to qualify conditions set in settings SET n and RST n . If you use any optoisolated inputs in settings SET n and RST n , the inputs each

have a separate debounce timer that can help in providing the necessary time qualification.

SELogic Control Equation Variables/Timers

Enable the number of SELOGIC control equations necessary for your application. Only the enabled SELOGIC control equations appear for settings. Each SELOGIC control equation variable/timer has a SELOGIC control equation setting input and variable/timer outputs as shown in *Figure 4.53*. Timers SV01T through SV32T in *Figure 4.53* have a setting range of 0.00–3000.00 seconds. This timer setting range applies to both pickup and dropout times (SVnPU and SVnDO, $n = 1$ through 32).

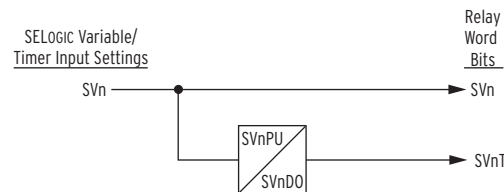


Figure 4.53 SELogic Control Equation Variable/Timers SV01/SV01T–SV32T

You can enter as many as 15 elements per SELOGIC equation, including a total of 14 elements in parentheses (see *Table 4.28* for more information).

SELogic Control Equation Operators

Use the Boolean operators to combine values with a resulting Boolean value. Edge trigger operators provide a pulse output. Combine the operators and operands to form statements that evaluate complex logic. SELOGIC control equations are either Boolean type or math type. Because the equals sign (=) is already used as an equality comparison, both Boolean type and math type of SELOGIC control equation settings begin with an “assignment” operator (:=) instead of with an equals sign.

Boolean SELOGIC control equation settings use logic similar to Boolean algebra logic, combining Relay Word bits together with one or more of the Boolean operators listed in *Table 4.28*. Math SELOGIC control equation settings operate on numerical values, using one or more of the Mathematical operators listed in *Table 4.28*. These numerical values can be mathematical variables or actual real numbers.

The executed result of a math SELOGIC control equation is stored in a math variable. The smallest and largest values a math variable can represent are –16777215.99 and +16777215.99, respectively. If the executed result exceeds these limits, it will be clipped at the limit value. For example, when the MV01:= executed result is –16777219.00, MV01 will be –16777215.99. Similarly, when the MV02 := executed result is +16777238.00, MV02 will be +16777215.99.

Comments can be added to both boolean and math SELOGIC control equations by inserting a # symbol. Everything following the # symbol in a SELOGIC control equation is treated as a comment. See *Table 4.29* for this and other Boolean and math operators and values.

Operator Precedence

When you combine several operators and operands within a single expression, the SEL-787 evaluates the operators from left to right, starting with the highest precedence operators and working down to the lowest precedence. This means that if you write an equation with three AND operators, for example SV01 AND SV02 AND SV03, each AND will be evaluated from the

left to the right. If you substitute NOT SV04 for SV03 to make SV01 AND SV02 AND NOT SV04, the device evaluates the NOT operation of SV04 first and uses the result in subsequent evaluation of the expression.

Table 4.28 SELogic Control Equation Operators (Listed in Operator Precedence)

| Operator | Function | Function Type (Boolean and/or Mathematical) |
|--------------|-----------------------------|---|
| () | parentheses | Boolean and Mathematical (highest precedence) |
| – | negation | Mathematical |
| NOT | NOT | Boolean |
| R_TRIG | rising-edge trigger/detect | Boolean |
| F_TRIG | falling-edge trigger/detect | Boolean |
| * | multiply | Mathematical |
| / | divide | Mathematical |
| + | add | Mathematical |
| - | subtract | Mathematical |
| <, >, <=, >= | comparison | Boolean |
| = | equality | Boolean |
| <> | inequality | Boolean |
| AND | AND | Boolean |
| OR | OR | Boolean (lowest precedence) |

Parentheses Operator ()

You can use more than one set of parentheses in a SELOGIC control equation setting. For example, the following Boolean SELOGIC control equation setting has two sets of parentheses:

SV04 := (SV04 OR IN102) AND (PB01_LED OR RB01)

In the above example, the logic within the parentheses is processed first and then the two parentheses resultants are ANDed together. Use as many as 14 sets of parentheses in a single SELOGIC control equation setting. The parentheses can be “nested” (parentheses within parentheses).

Math Negation Operator (-)

The negation operator – changes the sign of a numerical value. For example:

MV01 := RB01

When Remote bit RB01 asserts, Math variable MV01 has a value of 1, i.e., MV01 = 1. We can change the sign on MV01 with the following expression:

MV01 := -1 * RB01

Now, when Remote bit RB01 asserts, Math variable MV01 has a value of –1, i.e., MV01 = –1.

Boolean NOT Operator (NOT)

Apply the NOT operator to a single Relay Word bit and to multiple elements (within parentheses).

An example of a single Relay Word bit is as follows:

SV01 := NOT RB01

When Remote bit RB01 asserts from logical 0 to logical 1, the Boolean NOT operator, in turn, changes the logical 1 to a logical 0. In this example, SV01 deasserts when RB01 asserts.

Following is an example of the NOT operator applied to multiple elements within parentheses.

The Boolean SELOGIC control equation OUT101 setting could be set as follows:

OUT101 := NOT(RB01 OR SV02)

If both RB01 and SV02 are deasserted (= logical 0), output contact OUT101 asserts, i.e., $OUT101 := NOT (logical\ 0\ OR\ logical\ 0) = NOT (logical\ 0) = logical\ 1$.

In a Math SELOGIC control equation, use the NOT operator with any Relay Word bits. This allows a simple if/else type equation, as shown in the example below.

MV01 := 12 * IN101 + (MV01 + 1) * NOT IN101

The equation above sets MV01 to 12 whenever IN101 asserts, otherwise it increments MV01 by 1 each time the equation is executed.

Boolean Rising-Edge Operator (R_TRIG)

Apply the rising-edge operator, R_TRIG, to individual Relay Word bits only; you cannot apply R_TRIG to groups of elements within parentheses. When any Relay Word bit asserts (going from logical 0 to logical 1), R_TRIG interprets this logical 0 to logical 1 transition as a “rising edge” and asserts to logical 1 for one processing interval.

For example, the Boolean SELOGIC control equation event report generation setting uses rising-edge operators:

ER := R_TRIG IN101 OR R_TRIG IN102

The rising-edge operators detect a logical 0 to logical 1 transition each time one of IN101 or IN102 asserts. Using these settings, the device triggers a new event report each time IN101 or IN102 asserts anew, if the device is not already recording an event report. You can use the rising-edge operator with the NOT operator as long as the NOT operator precedes the R_TRIG operator. The NOT R_TRIG combination produces a logical 0 for one processing interval when it detects a rising edge on the specified element.

Boolean Falling-Edge Operator (F_TRIG)

Apply the falling-edge operator, F_TRIG, to individual Relay Word bits only; you cannot apply F_TRIG to groups of elements within parentheses. The falling-edge operator, F_TRIG, operates similarly to the rising-edge operator, but operates on Relay Word bit deassertion (elements going from logical 1 to logical 0) instead of Relay Word bit assertion. When the Relay Word bit deasserts, F_TRIG interprets this logical 1 to logical 0 transition as a “falling edge” and asserts to logical 1 for one processing interval, as shown in *Figure 4.54*.

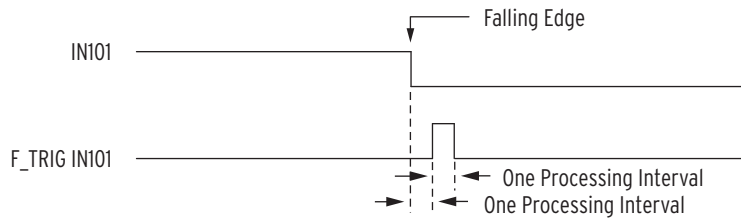


Figure 4.54 Result of Falling-Edge Operator on a Deasserting Input

You can use the falling-edge operator with the NOT operator as long as the NOT operator precedes the F_TRIG operator. The NOT F_TRIG combination produces a logical 0 for one processing interval when it detects a falling edge on the specified element.

Math Arithmetic Operators (*, /, +, and -)

If Relay Word bits (which are effectively Boolean resultants, equal to logical 1 or logical 0) are used in mathematical operations, they are treated as numerical values 0 and 1, depending on if the Relay Word bit is equal to logical 0 or logical 1, respectively.

Boolean Comparison Operators (<, >, <=, and >=)

Comparisons are mathematical operations that compare two numerical values, with the result being a logical 0 (if the comparison is not true) or logical 1 (if the comparison is true). Thus, what starts out as a mathematical comparison ends up as a Boolean resultant. For example, if the output of a math variable is above a certain value, an output contact is asserted:

OUT103 := MV01 > 8

If the math variable (MV01) is greater than 8 in value, output contact OUT103 asserts (OUT103 = logical 1). If the math variable (MV01) is less than or equal to 8 in value, output contact OUT103 deasserts (OUT103 = logical 0).

Boolean Equality (=) and Inequality (<>) Operators

Equality and inequality operators operate similar to the comparison operators. These are mathematical operations that compare two numerical values, with the result being a logical 0 (if the comparison is not true), or logical 1 (if the comparison is true). Thus, what starts out as a mathematical comparison, ends up as a Boolean resultant. For example, if the output of a math variable is not equal to a certain value, an output contact is asserted:

OUT102 := MV01 <> 45

If the math variable (MV01) is not equal to 45 in value, output contact OUT102 asserts (effectively OUT102 := logical 1). If the math variable (MV01) is equal to 45 in value, output contact OUT102 deasserts (effectively OUT102 := logical 0). *Table 4.29* shows other operators and values that you can use in writing SELOGIC control equations.

Table 4.29 Other SELOGIC Control Equation Operators/Values

| Operator/ Value | Function | Function Type (Boolean and/or Mathematical) |
|--------------------|--|---|
| 0 | Set SELOGIC control equation directly to logical 0 (XXX := 0) | Boolean |
| 1 | Set SELOGIC control equation directly to logical 1 (XXX := 1) | Boolean |
| # | Characters entered after the # operator are not processed and deemed as comments | Boolean and Mathematical |
| \ | Indicates that the preceding logic should be continued on the next line (“\” is entered only at the end of a line) | Boolean and Mathematical |

Timers Reset When Power Lost or Settings Changed

If the device loses power or settings change, the SELOGIC control equation variables/timers reset. Relay Word bits SV n and SV n T ($n = 01\text{--}32$) reset to logical 0 after power restoration or a settings change. *Figure 4.55* shows an effective seal-in logic circuit, created by the use of Relay Word bit SV07 (SELOGIC control equation variable SV07) in SELOGIC control equation SV07:

$$SV07 = (SV07 \text{ OR } OUT101) \text{ AND } (OUT102 \text{ OR } OUT401)$$

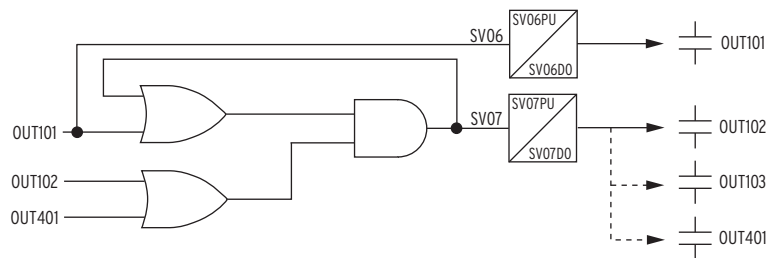


Figure 4.55 Example Use of SELOGIC Variables/Timers

SV/Timers Settings

The SEL-787 includes 32 SELOGIC variables. *Table 4.30* shows the pickup, dropout, and equation settings for SV01 through SV05. The remaining SELOGIC variables are not enabled (see *Table 4.26*).

Table 4.30 SELOGIC Variable Settings (Sheet 1 of 2)

| Setting Prompt | Setting Range | Default Settings |
|------------------|------------------|--------------------------------------|
| SV TIMER PICKUP | 0.00–3000.00 sec | SV01PU := 3.00 |
| SV TIMER DROPOUT | 0.00–3000.00 sec | SV01DO := 0.00 |
| SV INPUT | SELOGIC | SV01 := PB01 |
| SV TIMER PICKUP | 0.00–3000.00 sec | SV02PU := 0.25 |
| SV TIMER DROPOUT | 0.00–3000.00 sec | SV02DO := 0.00 |
| SV INPUT | SELOGIC | SV02 := PB01 OR PB02 OR PB03 OR PB04 |
| SV TIMER PICKUP | 0.00–3000.00 sec | SV03PU := 0.00 |
| SV TIMER DROPOUT | 0.00–3000.00 sec | SV03DO := 0.00 |
| SV INPUT | SELOGIC | SV03 := LT03 |
| SV TIMER PICKUP | 0.00–3000.00 sec | SV04PU := 0.00 |
| SV TIMER DROPOUT | 0.00–3000.00 sec | SV04DO := 0.00 |

Table 4.30 SELogic Variable Settings (Sheet 2 of 2)

| Setting Prompt | Setting Range | Default Settings |
|------------------|------------------|--|
| SV INPUT | SELOGIC | SV04 := LT04 |
| SV TIMER PICKUP | 0.00–3000.00 sec | SV05PU := 0.25 |
| SV TIMER DROPOUT | 0.00–3000.00 sec | SV05DO := 0.25 |
| SV INPUT | SELOGIC | SV05 := (PB01 OR PB02 OR LT03 OR LT04) AND NOT SV05T |
| • | • | • |
| • | • | • |
| • | • | • |

The pickup times of 0 for the SV03PU and SV04PU settings shown above provide an immediate Close and Trip actions from front-panel pushbuttons. For a delayed Close, set SV03PU to the desired delay. Similarly, set SV04PU for a delayed Trip action. See *Table 8.4* for more detail.

Counter Variables

NOTE: These counter elements conform to the standard counter function block #3 in IEC 1131-3 First Edition 1993-03 International Standard for Programmable controllers—Part 3: Programming languages.

NOTE: For device configurations that include voltage cards, the SEL-787 tracks the frequency. When tracking the frequency, the processing interval varies with the frequency.

NOTE: If setting SCnnCD is set to NA, the entire counter nn is disabled).

SELOGIC counters are up- or down-counting elements, updated every processing interval.

Each counter element consists of one count setting, four control inputs, two digital outputs, and one analog output. *Figure 4.56* shows Counter 01, the first of 32 counters available in the device.

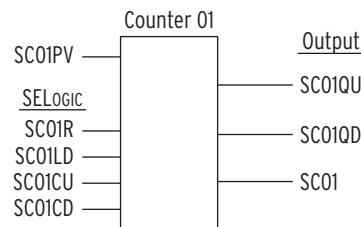


Figure 4.56 Counter 01

Digital output SC01QD asserts when the counter is at position zero, and Digital output SC01QU asserts when the counter reaches the programmable count value. Use the reset input (SC01R) to force the count to zero, and the analog output (SCnn) with analog comparison operators. *Table 4.31* describes the counter inputs and outputs, and *Table 4.32* shows the order of precedence of the control inputs.

Table 4.31 Counter Input/Output Description (Sheet 1 of 2)

| Name | Type | Description |
|--------|-------------------|---|
| SCnnLD | Active High Input | Load counter with the preset value to assert the output (SCnQU) (follows SELOGIC setting). |
| SCnnPV | Input Value | This Preset Value is loaded when SCnLD pulsed. This Preset Value is the number of counts before the output (SCnQU) asserts (follows SELOGIC setting). |
| SCnnCU | Rising-Edge Input | Count Up increments the counter (follows SELOGIC setting). |
| SCnnCD | Rising-Edge Input | Count Down decrements the counter (follows SELOGIC setting). |
| SCnnR | Active High Input | Reset counter to zero (follows SELOGIC setting) |

Table 4.31 Counter Input/Output Description (Sheet 2 of 2)

| Name | Type | Description |
|--------|--------------------|---|
| SCnnQU | Active High Output | This Q Up output asserts when the Preset Value (maximum count) is reached ($SCn = SCnPV$, $n = 01$ to 32). |
| SCnnQD | Active High Output | This Q Down output asserts when the counter is equal to zero ($SCn = 0$, $n = 01$ to 32). |
| SCnn | Output Value | This counter output is an analog value that may be used with analog comparison operators in a SELOGIC control equation and viewed using the COU command. |

Table 4.32 Order of Precedence of the Control Inputs

| Order | Input |
|-------|--------|
| 1 | SCnnR |
| 2 | SCnnLD |
| 3 | SCnnCU |
| 4 | SCnnCD |

Figure 4.57 shows an example of the effects of the input precedence, with SC01PV set to 7. The vertical dashed line indicates the relationship between SC01CU first being seen as a rising edge and the resultant outputs. This indicates that there is no intentional lag between the control input asserting and the count value changing. Most of the pulses in the diagram are on every second processing interval. The “one processing interval” valley is an example where the CD and CU pulses are only separated by one processing interval.

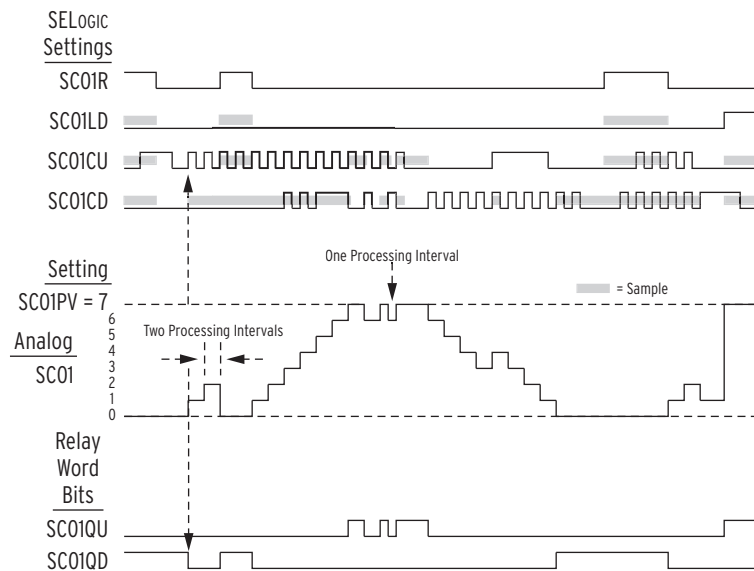


Figure 4.57 Example of the Effects of the Input Precedence

The shaded areas illustrate the precedence of the inputs:

- When SC01R is asserted, the SC01LD input is ignored.
- When SC01R or SC01LD is asserted, rising edges on the SC01CU or SC01CD inputs are ignored.
- When input SC01CU has a rising edge, a rising edge on SC01CD is ignored (unless SC01 is already at the maximum value SC01PV (= 7), in which case SC01CU is ignored, and the SC01CD is processed). An example of this exception appears in the above diagram, just before the “one processing interval” notation.

A maintained logical 1 state on the SC01CU or SC01CD inputs is ignored (after the rising edge is processed). A rising edge received on the SC01CU or SC01CD inputs is ignored when the SC01R or SC01LD inputs are asserted.

A maintained logical 1 on the SC01CU or SC01CD inputs does not get treated as a rising edge when the SC01R or SC01LD input deasserts.

The same operating principles apply for all of the counters: SC01–SC mm , where mm = the number of enabled counters. When a counter is disabled by setting, the present count value is forced to 0 (SC nn := 0), causing Relay Word bit SC nn QD to assert (SC nn QD := logical 1), and Relay Word bit SC nn QU to deassert (SC nn QU := logical 0).

Output Contacts

NOTE: When an output contact is not used for a specific function you must set the associated SELogic control equation to either 0 or 1.

NOTE: Four digital outputs in Slot **D** are shown. The outputs in Slots **C** and **E** have similar settings.

Table 4.33 Control Output Equations and Contact Behavior Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|---------------------------------|
| OUT101 FAIL-SAFE | Y, N | OUT101FS := Y |
| OUT101 | SELOGIC | OUT101 := HALARM OR SALARM |
| OUT102 FAIL-SAFE | Y, N | OUT102FS := N |
| OUT102 | SELOGIC | OUT102 := 0 |
| OUT103 FAIL-SAFE | Y, N | OUT103FS := N |
| OUT103 | SELOGIC | OUT103 := TRIPXFMR |
| • | • | • |
| • | • | • |
| • | • | • |
| OUT401 FAIL-SAFE | Y, N | OUT401FS := N |
| OUT401 | SELOGIC | OUT401 := 0 |
| OUT402 FAIL-SAFE | Y, N | OUT402FS := N |
| OUT402 | SELOGIC | OUT402 := 0 |
| OUT403 FAIL-SAFE | Y, N | OUT403FS := N |
| OUT403 | SELOGIC | OUT403 := 0 |
| OUT404 FAIL-SAFE | Y, N | OUT404FS := N |
| OUT404 | SELOGIC | OUT404 := 0 |
| • | • | • |
| • | • | • |
| • | • | • |

The SEL-787 provides the ability to use SELOGIC control equations to map protection (trip and warning) and general-purpose control elements to the

outputs. In addition, you can enable fail-safe output contact operation for relay contacts on an individual basis.

If the contact fail-safe is enabled, the relay output is held in its energized position when relay control power is applied. The output falls to its de-energized position when control power is removed. Contact positions with de-energized output relays are indicated on the relay chassis and in *Figure 2.12* and *Figure 2.13*.

When TRIP output fail-safe is enabled and the TRIP contact is appropriately connected (see *Figure 2.16*), the breaker is automatically tripped when relay control power fails.

MIRRORED BITS Transmit SELogic Control Equations

See *Appendix I: Mirrored Bits Communications* and *SEL-787 Settings Sheets* for details.

Global Settings (SET G Command)

General Settings

Table 4.34 General Global Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|---------------------------------|-------------------------|--|
| PHASE ROTATION | ABC, ACB | PHROT := ABC |
| RATED FREQ. | 50, 60 Hz | FNOM := 60 |
| DATE FORMAT | MDY, YMD, DMY | DATE_F := MDY |
| FAULT CONDITION | SELOGIC | FAULT := 51P1P OR 51P2P OR 51G1P OR 51G2P OR 51N1P OR TRIP |
| EVE MSG PTS ENABL | N, 1–32 | EMP := N |
| MESSENGER POINT MP01 TRIGGER | Off, 1 Relay Word bit | MPTR01 := OFF |
| MESSENGER POINT MP01 AQ | None, 1 analog quantity | MPAQ01 := NONE |
| MESSENGER POINT MP01 TEXT | 148 characters | MPTX01 := (blank) |
| • | • | • |
| • | • | • |
| • | • | • |
| MESSENGER POINT MP32 TRIGGER | Off, 1 Relay Word bit | MPTR32 := OFF |
| MESSENGER POINT MP32 AQ | None, 1 analog quantity | MPAQ32 := NONE |
| MESSENGER POINT MP32 TEXT | 148 characters | MPTX32 := (blank) |

The phase rotation setting tells the relay your phase labeling standard. Set PHROT equal to ABC when B-phase current lags A-phase current by 120 degrees. Set PHROT equal to ACB when B-phase current leads A-phase current by 120 degrees.

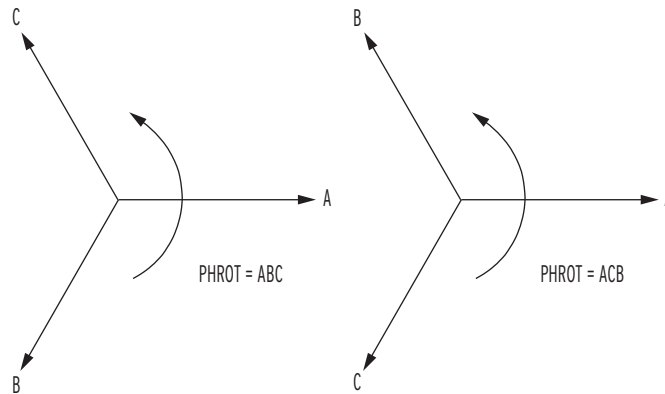


Figure 4.58 Phase Rotation Setting

Set the FNOM setting equal to your system nominal frequency. The DATE_F setting allows you to change the relay date presentation format to the North American standard (Month/Day/Year), the engineering standard (Year/Month/Day), or the European standard (Day/Month/Year).

Set the SELOGIC equation FAULT to temporarily block *Maximum and Minimum Metering*, *Energy Metering*, and *Demand Metering*.

Event Messenger Points

The SEL-787 can be configured to automatically send ASCII message on a communications port when trigger condition is satisfied. Use the **SET P** command to set PROTO := EVMSG on the desired port to select the port. This feature is designed to send messages to the SEL-3010 Event Messenger, however, any device capable of receiving ASCII messages can be used.

Set EMP to enable the desired number of message points.

Set each of MPTR_{xx} (xx = 01–32) to the desired Relay Word bits, the rising edge of which defines the trigger condition.

MPAQ_{xx} is an optional setting and can be used to specify an Analog Quantity to be formatted into a single message as described next.

Use MPTX_{xx} to construct the desired message. Note that by default the analog quantity value, if specified, will be added at the end of the message, rounded to the nearest integer value (see *Example 4.4*).

EXAMPLE 4.4 Setting MPTX_{xx} Using the Default Location of Analog Quantity

MPTX01 := THE LOAD CURRENT IS

MPAQ01 value = 157.44

Formatted message out when triggered: THE LOAD CURRENT IS 157

Location and resolution of the analog quantity value within the message can be specified by using “%.pf”, where,

% defines location of the value

p defines number of digits (as many as 6, defaults to 6 if omitted)

f indicates floating point value (use %d if nearest whole number is desired)

EXAMPLE 4.5 Setting MPTXxx With a Specified Location of Analog Quantity

MPTX01 := THE LOAD CURRENT IS %.2f AMPERES

MPAQ01 value = 157.44

Formatted message out when triggered: THE LOAD CURRENT IS 157.44 AMPERES

MPTX01 := THE LOAD CURRENT IS %d AMPERES

MPAQ01 value = 157.44

Formatted message out when triggered: THE LOAD CURRENT IS 157 AMPERES

Group Selection

Table 4.35 Setting Group Selection

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------|---------------|---------------------------------|
| GRP CHG DELAY | 0–400 sec | TGR := 3 |
| SELECT GROUP1 | SELOGIC | SS1 := 1 |
| SELECT GROUP2 | SELOGIC | SS2 := 0 |
| SELECT GROUP3 | SELOGIC | SS3 := 0 |
| SELECT GROUP4 | SELOGIC | SS4 := 0 |

The TGR setting defines the amount of time that the SS1, SS2, SS3, and SS4 SELOGIC control equation logic results must remain stable before the relay enables a new setting group. Typically, a one-second delay is sufficient.

SS1, SS2, SS3, and SS4 are SELOGIC control equations that help define when setting Group 1, 2, 3, and 4 are active. With the settings shown above, SS1 is set equal to logical 1, thus setting Group 1 always is active.

Synchrophasor Measurement

The SEL-787 relay provides Phasor Measurement Control Unit (PMCU) capabilities when connected to an IRIG-B time source. See *Appendix H: Synchrophasors* for description and *Table H.1* for the settings.

Time and Date Management Settings

The SEL-787 supports several methods of updating the relay time and date. For IRIG-B and Phasor Measurement Unit (PMU) synchrophasor applications, refer to *Appendix H: Synchrophasors* for the description and *Table H.1* for the settings. For SNTP applications, refer to *Simple Network Time Protocol (SNTP)* on page 7.12. For time update from a DNP Master, see *Time Synchronization* on page D.9.

Table 4.36 shows the time and date management settings that are available in the Global settings.

Table 4.36 Time and Date Management Settings (Sheet 1 of 2)

| Setting Description | Setting Range | Setting Name := Factory Default |
|--------------------------------|---|---------------------------------|
| IRIG-B Control Bits Definition | NONE, C37.118 | IRIGC := NONE |
| Offset From UTC | -24.00 to 24.00 hours, rounds up to nearest 0.25 hour | UTC_OFF := 0.00 |
| Month To begin DST | OFF, 1–12 | DST_BEGM := OFF |

Table 4.36 Time and Date Management Settings (Sheet 2 of 2)

| Setting Description | Setting Range | Setting Name := Factory Default |
|--------------------------------|--|------------------------------------|
| Week Of The Month To Begin DST | 1–3, L | DST_BEGW := 2 |
| Day Of The Week To Begin DST | SUN, MON, TUE, WED, THU, FRI, SAT, SUN | DST_BEGD := SUN |
| Local Hour To Begin DST | 0–23 | DST_BEGH := 2 |
| Month To End DST | 1–12 | DST_ENDM := 11 |
| Week Of The Month To End DST | 1–3, L | DST_ENDW := 1 |
| Day Of The Week To End DST | SUN, MON, TUE, WED, THU, FRI, SAT, SUN | DST_ENDD := SUN |
| Local Hour To End DST | 0–23 | DST_ENDH := 2 |

IRIGC

IRIGC defines whether IEEE C37.118 control bit extensions are in use. Control bit extensions contain information such as Leap Second, UTC time, Daylight-Saving Time, and Time Quality. When your satellite-synchronized clock provides these extensions, your relay will be able adjust the synchrophasor time-stamp accordingly.

- IRIGC := NONE will ignore bit extensions
- IRIGC := C37.118 will extract bit extensions and correct synchrophasor time accordingly

Coordinated Universal Time (UTC) Offset Setting

The SEL-787 has a Global setting UTC_OFF, settable from –24.00 to 24.00 hours, in 0.25 hour increments.

The relay uses the UTC_OFF setting to calculate local (relay) time from the UTC source when configured for Simple Network Time Protocol (SNTP) updating via Ethernet. When a time source other than SNTP is updating the relay time, the UTC_OFF setting is not considered because the other time sources are defined as local time.

Automatic Daylight-Saving Time Settings

The SEL-787 can automatically switch to and from daylight-saving time, as specified by the eight Global settings DST_BEGM through DST_ENDH. The first four settings control the month, week, day, and time that daylight-saving time will begin, while the last four settings control the month, week, day, and time that daylight-saving time will end.

Once configured, the SEL-787 will change to and from daylight-saving time every year at the specified time. Device Word bit DST asserts when daylight-saving time is active.

The SEL-787 interprets the week number settings DST_BEGW and DST_ENDW (1–3, L = Last) as follows:

- The first seven days of the month are considered to be in week 1.
- The second seven days of the month are considered to be in week 2.

- The third seven days of the month are considered to be in week 3.
- The last seven days of the month are considered to be in week “L”.

This method of counting the weeks allows easy programming of statements like “the first Sunday”, “the second Saturday”, or “the last Tuesday” of a month.

As an example, consider the following settings:

```
DST_BEGM = 3
DST_BEGW = L
DST_BEGD = SUN
DST_BEGH = 2
DST_ENDM = 10
DST_ENDW = 3
DST_ENDD = WED
DST_ENDH = 3
```

With these example settings, the relay will enter daylight-saving time on the last Sunday in March at 0200 h, and leave daylight-saving time on the third Wednesday in October at 0300 h. The relay asserts Relay Word bit DST when DST is active.

When an IRIG-B time source is being used, the relay time follows the IRIG-B time, including daylight-saving time start and end, as commanded by the time source. If there is a discrepancy between the daylight-saving time settings and the received IRIG-B signal, the relay follows the IRIG-B signal.

When using IEEE C37.118 compliant IRIG-B signals (e.g., Global setting IRIGC = C37.118), the relay automatically populates the DST Relay Word bit, regardless of the daylight-saving time settings.

When using regular IRIG-B signals (e.g., Global setting IRIGC = NONE), the relay only populates the DST Relay Word bit of the daylight-saving time settings are properly configured.

Simple Network Time Protocol (SNTP)

The SEL-787 Port 1 (Ethernet Port) supports the SNTP Client protocol. See *Section 7: Communications, Simple Network Time Protocol (SNTP) on page 7.12* for a description and *Table 7.4* for the settings.

Breaker Failure Setting

Table 4.37 Breaker Failure Setting

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|--|
| 52A INTERLOCK | Y, N | 52ABF := N |
| BRKR1 FAIL DELAY | 0.00–2.00 sec | BFD1 := 0.50 |
| BRKR1 FAIL INIT | SELOGIC | BFI1 := R_TRIG TRIP1 OR R_TRIG TRIPXFMR |
| BRKR2 FAIL DELAY | 0.00–2.00 sec | BFD2 := 0.50 |
| BRKR2 FAIL INIT | SELOGIC | BFI2 := R_TRIG TRIP2 OR R_TRIG TRIPXFMR |

The SEL-787 provides flexible breaker failure logic (see *Figure 4.59*) for two breakers. In the default breaker failure logic, assertion of trip Relay Word bits associated with a breaker starts a BFD timer if the sum of positive and negative-sequence breaker current is above $0.02 \cdot I_{NOM}$. If the current remains

above the threshold for BFD delay setting, Relay Word bit BFT will assert. Use the BFT to operate an output relay to trip appropriate backup breakers. Changing the BFI and/or 52ABF settings can modify the default breaker failure logic.

- Set BFI1 = R_TRIG TRIP1 OR R_TRIG TRIPXFMR AND NOT IN102 if input IN102 is manual trip only and breaker failure initiation is not desired when the tripping is caused by this input.
- Set 52ABF = Y if you want the breaker failure logic to detect failure of breaker/contactor auxiliary contact to operate during the trip operation as defined by the BFI setting.

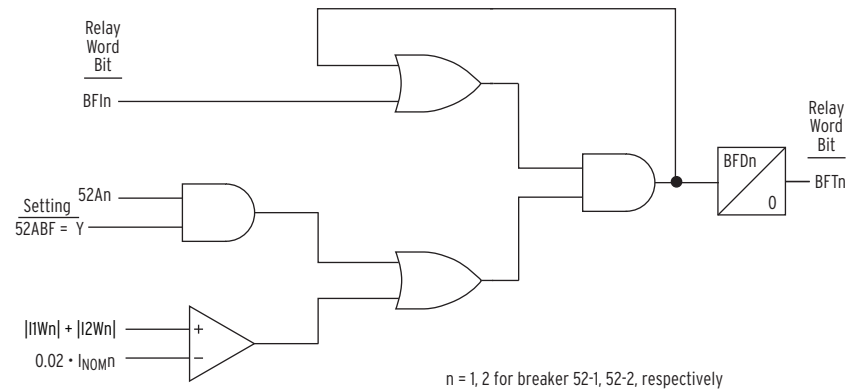


Figure 4.59 Breaker Failure Logic

Through-Fault Monitoring

The power transformers are subjected to heavy through currents for the system faults outside the transformer protection zone. The SEL-787 provides monitoring of the Through-Fault current. See *Section 5: Metering and Monitoring* for description and *Table 5.10* for the settings.

Analog Inputs

The SEL-787 samples the analog inputs four times per cycle. For analog inputs, set the following parameters for each input:

- Analog type
- High and low input levels
- Engineering units

Because of the flexibility to install different cards in the rear-panel slots on the device, the setting prompt adapts to the x and y variables shown in *Figure 4.60*. Variable x displays the slot position (3 through 5), and variable y displays the transducer (analog) input number (1 through 4).

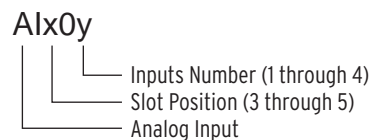


Figure 4.60 Analog Input Card Adaptive Name

Analog Input Calibration Process

In the analog input circuit, the dominant error is signal offset. To minimize the signal offset, we adjust each of the device analog input channels by a compensation factor. These compensation factors correct the signal offset errors to within $\pm 1 \mu\text{A}$ or $\pm 1 \text{ mV}$.

Signal offset compensation factor calculation procedure:

- Step 1. Turn the SEL-787 on and allow it to warm up for a few minutes.
- Step 2. Set the analog inputs for each analog channel to the desired range using the $AI_{xxx}TYP$, $AI_{xxx}L$, $AI_{xxx}H$, $AI_{xxx}EL$, and $AI_{xxx}EH$ settings (for example, ± 1 mA).
- Step 3. Short each analog input in turn at the device terminals using short, low resistance leads with solid connections.
- Step 4. Issue the command **MET AI 10** to obtain 10 measurements for each channel.
- Step 5. Record these 10 measurements, then calculate the average of the 10 measurements by adding the 10 values algebraically, and dividing the sum by 10. This is the average offset error in engineering units at zero input (for example, -0.014 mA).
- Step 6. Negate this value (flip the sign) and add the result to each of the $AI_{xxx}EL$ and $AI_{xxx}EH$ quantities. For this example, the new $AI_{xxx}EL$ and $AI_{xxx}EH$ values are -0.986 mA and 1.014 mA.

Analog Input Setting Example

Assume we installed an analog card in Slot 3. On Input 1 of this analog card, we connect a 4–20 mA transducer driven from a device that measures temperature on a transformer load tap changer mechanism. For this temperature transducer, 4 mA corresponds to -50°C , and 20 mA corresponds to 150°C . You have already installed the correct hardware jumper (see *Figure 2.3* for more information) for Input 1 to operate as a current input.

Table 4.38 summarizes the steps and describes the settings we will carry out in this example.

Table 4.38 Summary of Steps (Sheet 1 of 2)

| | Step | Activity | Terse Description |
|-----------------------------------|------|-------------------|--|
| General | 1 | SET G AI301NAM | Access settings for INPUT 1 |
| | 2 | TX_TEMP | Enter a Tag name |
| | 3 | I | Select type of analog input; “I” for current |
| Transducer High/Low Output | 4 | 4 | Enter transducer low output (LOW IN VAL) |
| | 5 | 20 | Enter transducer high output (HI IN VAL) |
| Level | 6 | Degrees C | Enter Engineering unit |
| | 7 | -50 | Enter Engineering unit value LOW |
| | 8 | 150 | Enter Engineering unit value HIGH |
| Low Warning/Alarm | 9 | OFF | Enter LOW WARNING 1 value |
| | 10 | OFF | Enter LOW WARNING 2 value |
| | 11 | OFF | Enter LOW ALARM value |

Table 4.38 Summary of Steps (Sheet 2 of 2)

| | Step | Activity | Terse Description |
|------------------------|------|----------|----------------------------|
| High Warning/ Alarm | 12 | 65 | Enter HIGH WARNING 1 value |
| | 13 | 95 | Enter HIGH WARNING 2 value |
| | 14 | 105 | Enter HIGH ALARM value |

NOTE: The AIxOyNAM setting cannot accept the following and will issue the Invalid Element message:

Analog Quantities
Duplicate Names
Other AI Names

Because the analog card is in Slot 3, type **SET G AI301NAM <Enter>** to go directly to the setting for Slot 3, Input 1. Although the device accepts alphanumeric characters, the name AIxOyNAM setting must begin with an alpha character (A through Z) and not a number. The device displays the following prompt:

```
AI301 TAG NAME (8 Characters)  AI301NAM:= AI301 ?
```

Use the Instrument Tag Name to give the analog quantity a more descriptive name. This tag name appears in reports (EVENT, METER, and SUMMARY) instead of the default name of AI301. SELOGIC control equations, Signal Profiles, and Fast Message Read use the default names. Use as many as eight valid tag name characters to name the analog quantity. Valid tag name characters are: 0–9, A–Z, and the underscore (_). For this example, we assign TX_TEMP as the tag name.

Because this is a 4–20 mA transducer, enter **I <Enter>** (for current driven device) at AI301TYP, the next prompt (enter **V** if this is a voltage-driven device). The next two settings define the lower level (AI301L) and the upper level (AI301H) of the transducer. In this example, the low level is 4 mA and the high level is 20 mA.

```
AI301 TYPE (I,V)  AI301TYP:= I ?
```

NOTE: Because the SEL-787 accepts current values ranging from -20.48 to 20.48 mA, be sure to enter the correct range values.

The next three settings define the applicable engineering unit (AI301EU), the lower level in engineering units (AI301EL) and the upper level in engineering units (AI301EH). Engineering units refer to actual measured quantities, i.e., temperature, pressure, etc. Use the 16 available characters to assign descriptive names for engineering units. Because we measure temperature in this example, enter “degrees C” (without quotation marks) as engineering units. Enter **-50 <Enter>** for the lower level and **150 <Enter>** for the upper level.

With the levels defined, the next six settings provide two warning settings and one alarm setting for low temperature values, as well as two warning settings and one alarm setting for high temperature values. State the values in engineering units, not the setting range of the transducer. Note the difference between low warnings and alarm functions and high warnings and alarm functions: low warnings and alarm functions assert when the measured value falls below the setting; high warnings and alarm functions assert when the measured values rise above the setting.

In this example, we measure the oil temperature of a power transformer, and we want the following three actions to take place at three different temperature values:

- At 65°C, start the cooling fans
- At 95°C, send an alarm
- At 105°C, trip the transformer

Because we are only interested in cases when the temperature values exceed their respective temperature settings (high warnings and alarm functions), we do not use the low warnings and alarm functions. Therefore, set the lower values (AI301LW1, AI301LW2, AI301LAL) to OFF, and the three higher

values as shown in *Figure 4.61*. Set inputs connected to voltage driven transducers in a similar way.

```

=>>SET G AI301NAM TERSE <Enter>
Global
AI 301 Settings
AI301 TAG NAME (8 characters)
AI301NAM:= AI301
? TX_TEMP <Enter>
AI301 TYPE (I,V)                AI301TYP:= I      ? <Enter>
AI301 LOW IN VAL (-20.480 to 20.480 mA)  AI301L := 4.000  ? <Enter>
AI301 HI IN VAL (-20.480 to 20.480 mA)  AI301H := 20.000 ? <Enter>
AI301 ENG UNITS (16 characters)
AI301EU := mA
? degrees C <Enter>
AI301 EU LOW (-99999.000 to 99999.000)  AI301EL := 4.000  ? -50 <Enter>
AI301 EU HI (-99999.000 to 99999.000)  AI301EH := 20.000 ? 150 <Enter>
AI301 LO WARN L1 (OFF, -99999.000 to 99999.000) AI301LW1:= OFF  ? <Enter>
AI301 LO WARN L2 (OFF, -99999.000 to 99999.000) AI301LW2:= OFF  ? <Enter>
AI301 LO ALARM (OFF, -99999.000 to 99999.000) AI301LAL:= OFF  ? <Enter>
AI301 HI WARN L1 (OFF, -99999.000 to 99999.000) AI301HW1:= OFF  ? 65 <Enter>
AI301 HI WARN L2 (OFF, -99999.000 to 99999.000) AI301HW2:= OFF  ? 95 <Enter>
AI301 HI ALARM (OFF, -99999.000 to 99999.000) AI301HAL:= OFF  ? 115 <Enter>
AI 302 Settings
AI302 TAG NAME (8 characters)
AI302NAM:= AI302
? END <Enter>
Save changes (Y,N)? Y <Enter>
Settings Saved
=>>

```

Figure 4.61 Settings to Configure Input 1 as a 4-20 mA Transducer Measuring Temperatures Between -50°C and 150°C

Analog (DC Transducer) Input Board

Table 4.39 shows the setting prompt, setting range, and factory-default settings for an analog input card in Slot 3. For the name setting (AI301NAM, for example), enter only alphanumeric and underscore characters. Characters are not case sensitive, but the device converts all lowercase characters to uppercase. Although the device accepts alphanumeric characters, the name AI301NAM setting must begin with an alpha character (A–Z) and not a number.

Table 4.39 Analog Input Card in Slot 3 (Sheet 1 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|-------------------------------|---------------------------------|
| AI301 TAG NAME | 8 characters 0–9, A–Z, _ | AI301NAM := AI301 |
| AI301 TYPE | I, V | AI301TYP := I |
| AI301 LOW IN VAL | –20.480 to +20.480 mA | AI301L := 4.000 |
| AI301 HI IN VAL | –20.480 to +20.480 mA | AI301H := 20.000 |
| AI301 LOW IN VAL | –10.240 to +10.240 V | AI301L := 0.000 ^a |
| AI301 HI IN VAL | –10.240 to +10.240 V | AI301H := 10.000 ^a |
| AI301 ENG UNITS | 16 characters | AI301EU := mA |
| AI301 EU LOW | –99999.000 to +99999.000 | AI301EL := 4.000 |
| AI301 EU HI | –99999.000 to +99999.000 | AI301EH := 20.000 |
| AI301 LO WARN 1 | OFF, –99999.000 to +99999.000 | AI301LW1 := OFF |
| AI301 LO WARN 2 | OFF, –99999.000 to +99999.000 | AI301LW2 := OFF |
| AI301 LO ALARM | OFF, –99999.000 to +99999.000 | AI301LAL := OFF |
| AI301 HI WARN 1 | OFF, –99999.000 to +99999.000 | AI301HW1 := OFF |

Table 4.39 Analog Input Card in Slot 3 (Sheet 2 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|-------------------------------|------------------------------------|
| AI301 HI WARN 2 | OFF, -99999.000 to +99999.000 | AI301HW2 := OFF |
| AI301 HI ALARM | OFF, -99999.000 to +99999.000 | AI301HAL := OFF |

^a Voltage setting range for a voltage transducer, i.e., when AI301TYP := V.

Analog Outputs

If an SEL-787 configuration includes the four analog inputs and four analog outputs (4 AI/4 AO) card, the analog outputs are allocated to output numbers 1-4. *Figure 4.62* shows the *x* and *y* variable allocation for the analog output card.

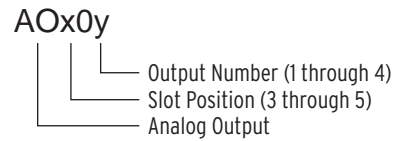


Figure 4.62 Analog Output Number Allocation

For an analog input/output card in Slot 3, setting AO301AQ identifies the analog quantity we assign to Analog Output 1 (when set to OFF, the device hides all associated AOx0y settings and no value appears on the output). You can assign any of the analog quantities listed in *Appendix K: Analog Quantities*.

Table 4.40 shows the setting prompt, setting range, and factory-default settings for an analog card in Slot 3.

Table 4.40 Output Setting for a Card in Slot 3

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------------------------------|------------------------------------|
| AO301 ANALOG QTY | Off, 1 analog quantity | AO301AQ := OFF |
| AO301 TYPE | I, V | AO301TYP := I |
| AO301 AQTY LO | -2147483647.000 to +2147483647.000 | AO301AQL := 4.000 |
| AO301 AQTY HI | -2147483647.000 to +2147483647.000 | AO301AQH := 20.000 |
| AO301 LO OUT VAL | -20.480 to +20.480 mA | AO301L := 4.000 |
| AO301 HI OUT VAL | -20.480 to +20.480 mA | AO301H := 20.000 |
| AO301 LO OUT VAL | -10.240 to +10.240 V | AO301L := 0.000 ^a |
| AO301 HI OUT VAL | -10.240 to +10.240 V | AO301H := 10.000 ^a |

^a Voltage setting range for a voltage transducer, i.e., when AO301TYP := V.

NOTE: The SEL-787 hides the following settings with default values when you use a 3 DI/4 DO/1 AO card:
AOxx1TYP := I
AOxx1L := 4.000
AOxx1H := 20.000

Example

In this example, assume we want to display in the station control room the analog quantity (refer to *Appendix K: Analog Quantities*) IAW1_MAG, Phase A Current Magnitude in Primary Amps (0 to 3000 Amps range) using a -20 to +20 mA Analog Output channel. We install an analog input/output card in slot C (SELECT 4 AI/ 4 AO) and set the card channel AO301 as shown in *Figure 4.62* below. Note that the AO301 channel has to be configured as a “current analog output” channel (refer to *Figure 2.5*).

The display instrument expects -20 mA when the IAW1_MAG current is 0 amperes primary and +20 mA when it is 3000 amperes primary.

```

=>>SET G A0301AQ TERSE <Enter>
Global
A0 301 Settings
A0301 ANALOG QTY (OFF, 1 analog quantity)
A0301AQ := OFF
? IAW1_MAG <Enter>
A0301 TYPE (I,V)                                A0301TYP:= I      ? <Enter>
A0301 AQTY LO (-2147483647.000 to 2147483647.000) A0301AQL:= 4.000 ? 0 <Enter>
A0301 AQTY HI (-2147483647.000 to 2147483647.000) A0301AQH:= 20.000 ? 3000 <Enter>
A0301 LO OUT VAL (-20.480 to 20.480 mA)           A0301L := 4.000 ? -20 <Enter>
A0301 HI OUT VAL (-20.480 to 20.480 mA)           A0301H := 20.000 ? 20 <Enter>
A0 302 Settings
A0302 ANALOG QTY (OFF, 1 analog quantity)
A0302AQ := OFF
? END <Enter>
Save changes (Y,N)? Y <Enter>
Settings Saved
=>>

```

Figure 4.63 Analog Output Settings

Digital Input Debounce

To comply with different control voltages, the SEL-787 offers dc debounce as well as ac debounce modes. Therefore, if the control voltage is dc, select the dc mode of operation, and if the control voltage is ac, select the ac mode of operation. In general, debounce refers to a qualifying time delay before processing the change of state of a digital input. Normally, this delay applies to both the processing of the debounced input when used in device logic, as well as to the time stamping in the SER. Following is a description of the two modes.

DC Mode Processing (DC Control Voltage)

Figure 4.64 shows the logic for the dc debounce mode of operation. To select the dc mode of debounce, set IN101D to any number between 0 and 65000 ms. In the figure, Input IN101 becomes IN101R (internal variable), after analog-to-digital conversion. On assertion, IN101R starts Debounce Timer, producing Relay Word bit IN101 after the debounce time delay. The debounce timer is a pickup/dropout combination timer, with debounce setting IN101D applying to both pickup (pu) and dropout (do) timers, i.e., you cannot set any timer individually. For example, a setting of IN101D = 20 ms delays processing of the input signal by 20 ms (pu) and maintains the output of the timer (do) for 20 ms. Relay Word bit IN101 is the output of the debounce timer. If you do not want to debounce a particular input, still use Relay Word bit IN101 in logic programming, but set the debounce time delay to 0 (IN101D = 0).

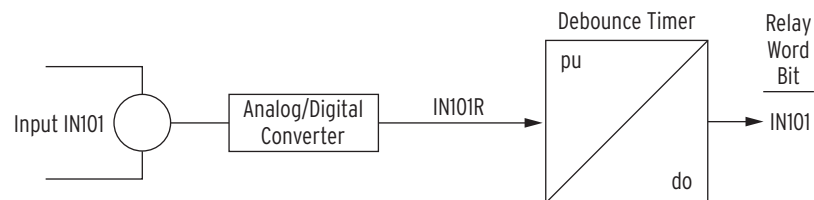


Figure 4.64 DC Mode Processing

AC Mode Processing (AC Control Voltage)

Figure 4.65 shows IN101R from Input IN101 applied to a pickup/dropout timer. Different from the dc mode, there are no time settings for the debounce timer in the ac mode: the pickup time delay is fixed at 2 ms, and the dropout time is fixed at 16 ms. Relay Word bit IN101 is the output of the debounce timer. To select the ac mode of debounce, set IN101D = AC.

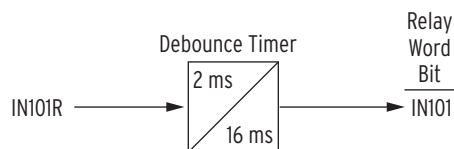


Figure 4.65 AC Mode Processing

Figure 4.66 shows a timing diagram for the ac mode of operation. On the rising edge of IN101R, the pickup timer starts timing (points marked 1 in Figure 4.66). If IN101R deasserts (points marked 2 in Figure 4.66) before expiration of the pickup time setting, Relay Word bit IN101 does not assert, and remains at logical 0. If, however, IN101R remains asserted for a period longer than the pickup timer setting, then Relay Word bit IN101 asserts to a logical 1.

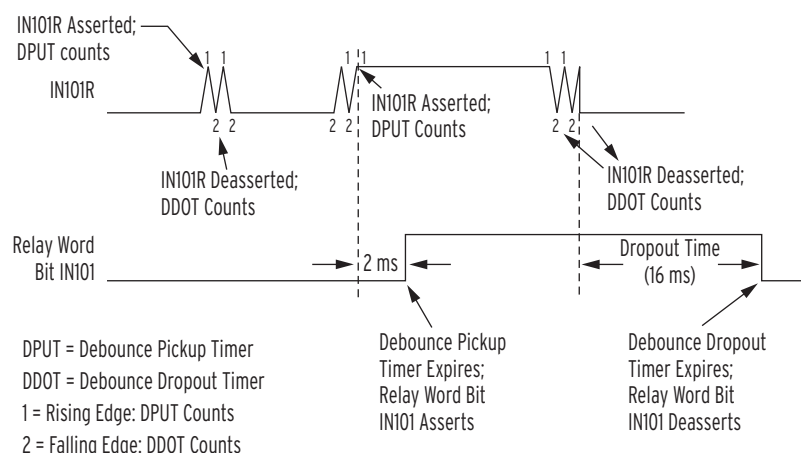


Figure 4.66 Timing Diagram for Debounce Timer Operation When Operating in AC Mode

Deassertion follows the same logic. On the falling edge of IN101R, the dropout timer starts timing. If IN101R remains deasserted for a period longer than the dropout timer setting, then Relay Word bit IN101 deasserts to a logical 0.

Table 4.41 shows the settings prompt, setting range, and factory-default settings for a card in Slot C. See the *SEL-787 Settings Sheets* for a complete list of input debounce settings.

Table 4.41 Slot C Input Debounce Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------|----------------|------------------------------------|
| IN301 Debounce | AC, 0–65000 ms | IN301D := 10 |
| IN302 Debounce | AC, 0–65000 ms | IN302D := 10 |
| IN303 Debounce | AC, 0–65000 ms | IN303D := 10 |
| IN304 Debounce | AC, 0–65000 ms | IN304D := 10 |
| IN305 Debounce | AC, 0–65000 ms | IN305D := 10 |
| IN306 Debounce | AC, 0–65000 ms | IN306D := 10 |
| IN307 Debounce | AC, 0–65000 ms | IN307D := 10 |
| IN308 Debounce | AC, 0–65000 ms | IN308D := 10 |

Data Reset

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|---------------|------------------------------------|
| RESET TARGETS | SELOGIC | RSTTRGT := 0 |
| RESET ENERGY | SELOGIC | RSTENRGY := 0 |
| RESET MAX/MIN | SELOGIC | RSTMXMN := 0 |
| RESET DEMAND | SELOGIC | RSTDEN := 0 |
| RESET PK DEMAND | SELOGIC | RSTPKDEM := 0 |

The RSTTRGT setting resets the trip output and front-panel TRIP LED, provided there is no trip condition present. See *Figure 4.49* for more details. The RSTENRGY and RSTMXMN settings reset the Energy and Max/Min Metering values respectively. You should assign a contact input (for example, RSTTRGT := IN401) to each of these settings if you want remote reset. The RSTDEN and RSTPKDEM settings reset demand and peak-demand. See *Figure 4.46* for the demand current logic diagram.

Access Control

NOTE: DSABLSET does not disable the setting changes from the serial ports.

The DSABLSET setting defines conditions for disabling all setting changes from the front-panel interface. To disable setting changes from the front-panel interface, assign, for example, a contact input (e.g., DSABLSET := IN402) to the DSABLSET setting. When Relay Word bit DSABLSET asserts, you can view the device settings from the front-panel interface, but you can only change settings using serial port commands. *Table 4.42* shows the settings prompt, setting range, and factory-default settings.

The BLOCK MODBUS SET setting is used to block relay settings changes via Modbus or DeviceNet protocols. The factory-default setting, BLKMBSET := NONE, allows all setting changes via Modbus or DeviceNet communications. The BLKMBSET := R_S setting prevents Modbus or DeviceNet communications from resetting to the factory-default settings. The BLKMBSET := ALL setting blocks all changes to the settings via the Modbus or the DeviceNet protocol.

Table 4.42 Setting Change Disable Setting

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|----------------|------------------------------------|
| DISABLE SETTINGS | SELOGIC | DSABLSET := 0 |
| BLOCK MODBUS SET | NONE, R_S, ALL | BLKMBSET := NONE |

Time-Synchronization Source

The SEL-787 accepts a demodulated IRIG-B time signal. *Table 4.43* shows the setting to identify the input for the signal. Set TIME_SRC := IRIG1 when you use relay terminals B01/B02 or EIA-232 serial Port 3 for the time signal input. When you use fiber-optic Port 2 for the signal, set the TIME_SRC := IRIG2. Refer to *IRIG-B Time-Code Input* on page 2.20 and *IRIG-B* on page 7.5 for additional information.

Table 4.43 Time-Synchronization Source Setting

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|------------------------------------|
| IRIG TIME SOURCE | IRIG1, IRIG2 | TIME_SRC := IRIG1 |

Port Settings (SET P Command)

The SEL-787 provides settings that allow you to configure the parameters for the communications ports. See *Section 2: Installation* for a detailed description of port connections. On the base unit: **Port F** (front panel) is an EIA-232 port; **Port 1** is an optional Ethernet port(s); **Port 2** is a fiber-optic serial port; and **Port 3** (rear) is optionally an EIA-232 or EIA-485 port. On the optional communications card, you can select **Port 4** as either EIA-485 or EIA-232 (not both) with the COMMINF setting. See *Table 4.44* through *Table 4.48* for the serial port settings, also see appropriate Appendix for additional information on the protocol (DNP, MODBUS, IEC-61850, DeviceNet, Synchrophasors, and MIRRORED BIT) of interest.

PORT F

Table 4.44 Front-Panel Serial Port Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|----------------------|------------------------------------|
| PROTOCOL | SEL, MOD, EVMSG, PMU | PROTO := SEL |
| SPEED | 300–38400 bps | SPEED := 9600 |
| DATA BITS | 7, 8 bits | BITS := 8 |
| PARITY | O, E, N | PARITY := N |
| STOP BITS | 1, 2 bits | STOP := 1 |
| HDWR HANDSHAKING | Y, N | RTSCTS := N |
| PORT TIME-OUT | 0–30 min | T_OUT := 5 |
| SEND AUTOMESSAGE | Y, N | AUTO := N |
| MODBUS SLAVE ID | 1–247 | SLAVEID := 1 |

PORT 1

IMPORTANT: Upon relay initial power up or Port 1 setting changes or Logic setting changes, the user may have to wait as long as two minutes before an additional setting change can occur. Note that the relay is functional with protection enabled, as soon as the **ENABLED LED** comes ON (about 5–10 seconds from power up).

Table 4.45 Ethernet Port^a Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------------------------|------------------------------|------------------------------------|
| IP ADDRESS | zzz.yyy.xxx.www | IPADDR := 192.168.1.2 |
| SUBNET MASK | 15 characters | SUBNETM := 255.255.255.0 |
| DEFAULT ROUTER | 15 characters | DEFRTR := 192.168.1.1 |
| Enable TCP Keep-Alive | Y, N | ETCPKA := Y |
| TCP Keep-Alive Idle Range | 1–20 sec | KAIDLE := 10 |
| TCP Keep-Alive Interval Range | 1–20 sec | KAINTV := 1 |
| TCP Keep-Alive Count Range | 1–20 sec | KACNT := 6 |
| FAST OP MESSAGES | Y, N | FASTOP := N |
| OPERATING MODE | FIXED, FAILOVER, SWITCHED | NETMODE := FAILOVER |
| FAILOVER TIMEOUT | 0.10–65.00 sec | FTIME := 1.00 |
| PRIMARY NETPORT | A, B, D | NETPORT := A |
| NETWRK PORTA SPD | AUTO, 10, 100 Mbps | NETASPD := AUTO |
| NETWRK PORTB SPD | AUTO, 10, 100 Mbps | NETBSPD := AUTO |
| TELNET PORT | 23, 1025–65534 | TPORT := 23 |
| TELNET TIME OUT | 1–30 min | TIDLE := 15 |
| FTP USER NAME | 20 characters | FTPUSER := FTPUSER |
| Enable IEC 61850 Protocol | Y, N | E61850 := N |
| Enable IEC 61850 GSE | Y, N | EGSE := N |
| Enable DNP Sessions ^b | 0–3 | EDNP := 0 |
| Enable Modbus Sessions | 0–2 | EMOD := 0 |
| MODBUS TCP PORT 1 | (1–65534) | MODNUM1 := 502 |
| MODBUS TCP PORT 2 | (1–65534) | MODNUM2 := 502 |
| Modbus Timeout 1 | (15–900 sec) | MTIMEO1 := 15 |
| Modbus Timeout 2 | (15–900 sec) | MTIMEO2 := 15 |

^a The SEL-787 Port 1 (Ethernet Port) supports SNTP Client protocol. See Section 7: Communications, Simple Network Time Protocol (SNTP) for the description and Table 7.4 for the settings.

^b See Table D.7 for a complete list of the DNP3 session settings.

PORT 2

NOTE: For additional settings when PROTO := MBxx, see Table I.5 as well as MIRRORED BITS Transmit SELogic Equations on page SET.25. For additional settings when PROTO := DNP, see Table D.7 for a complete list of the DNP3 session settings.

Table 4.46 Fiber-Optic Serial Port Settings (Sheet 1 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------|--|------------------------------------|
| PROTOCOL | SEL, DNP, MOD, EVMSG, PMU, MBA, MBB, MB8A, MB8B, MBTA, MBTB | PROTO := SEL |
| SPEED | 300–38400 bps | SPEED := 9600 |
| DATA BITS | 7, 8 bits | BITS := 8 |
| PARITY | O, E, N | PARITY := N |
| STOP BITS | 1, 2 bits | STOP := 1 |

Table 4.46 Fiber-Optic Serial Port Settings (Sheet 2 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|------------------------------------|
| PORT TIME-OUT | 0–30 min | T_OUT := 5 |
| SEND AUTOMESSAGE | Y, N | AUTO := N |
| FAST OP MESSAGES | Y, N | FASTOP := N |
| MODBUS SLAVE ID | 1–247 | SLAVEID := 1 |

PORT 3

NOTE: For additional settings when PROTO := MBxx, see Table I.5 as well as MIRRORED BITS Transmit SELOGIC Equations on page SET.25. For additional settings when PROTO := DNP, see Table D.7 for a complete list of the DNP3 session settings.

Table 4.47 Rear-Panel Serial Port Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---|------------------------------------|
| PROTOCOL | SEL, DNP, MOD, EVMSG, PMU, MBA, MBB, MB8A, MB8B, MBTA, MBTB | PROTO := SEL |
| SPEED | 300–38400 bps | SPEED := 9600 |
| DATA BITS | 7, 8 bits | BITS := 8 |
| PARITY | O, E, N | PARITY := N |
| STOP BITS | 1, 2 bits | STOP := 1 |
| PORT TIMEOUT | 0–30 min | T_OUT := 5 |
| SEND AUTOMESSAGE | Y, N | AUTO := N |
| HDWR HANDSHAKING | Y, N | RTSCTS := N |
| FAST OP MESSAGES | Y, N | FASTOP := N |
| MODBUS SLAVE ID | 1–247 | SLAVEID := 1 |

PORT 4

NOTE: For additional settings when PROTO := MBxx, see Table I.5 as well as MIRRORED BITS Transmit SELOGIC Equations on page SET.25. For additional settings when PROTO := DNP, see Table D.7 for a complete list of the DNP3 session settings.

Table 4.48 Rear-Panel Serial Port (EIA-232/EIA-485) Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---|------------------------------------|
| PROTOCOL | SEL, MOD, DNET, DNP, EVMSG, PMU, MBA, MBB, MB8A, MB8B, MBTA, MBTB | PROTO := SEL |
| COMM INTERFACE | 232, 485 | COMMINF := 232 |
| SPEED | 300–38400 bps | SPEED := 9600 |
| DATA BITS | 7, 8 bits | BITS := 8 |
| PARITY | O, E, N | PARITY := N |
| STOP BITS | 1, 2 bits | STOP := 1 |
| PORT TIMEOUT | 0–30 min | T_OUT := 5 |
| SEND AUTOMESSAGE | Y, N | AUTO := N |
| HDWR HANDSHAKING | Y, N | RTSCTS := N |
| FAST OP MESSAGES | Y, N | FASTOP := N |
| MODBUS SLAVE ID | 1–247 | SLAVEID := 1 |

Set the speed, data bits, parity, and stop bits settings to match the serial port configuration of the equipment that is communicating with the serial port.

After Port Timeout minutes of inactivity on a serial port at Access Level 2, the port automatically returns to Access Level 0. This security feature helps prevent unauthorized access to the relay settings if the relay is accidentally left in Access Level 2. If you do not want the port to time out, set Port Timeout equal to 0 minutes.

Set PROTO := SEL (standard SEL ASCII protocol), MOD (Modbus RTU protocol), or one of the MIRRORRED BITS protocols, as needed for your application. For detailed information, refer to *Appendix C: SEL Communications Processors*, *Appendix E: Modbus RTU Communications*, and *Appendix I: Mirrored Bits Communications*.

Use the MBT option if you are using a Pulsar MBT9600 baud modem (see *Appendix I: Mirrored Bits Communications* for more information). With this option set, the relay transmits a message every second processing interval and the device deasserts the RTS signal on the EIA-232 connector. Also, the device monitors the CTS signal on the EIA-232 connector, which the modem deasserts if the channel has too many errors. The modem uses the device RTS signal to determine whether the MB or MB8 MIRRORRED BITS protocol is in use.

Set the AUTO := Y to allow automatic messages at a serial port.

The relay EIA-232 serial ports support software (XON/XOFF) flow control. If you want to enable support for hardware (RTS/CTS) flow control, set the RTSCTS setting equal to Y.

Set FASTOP := Y to enable binary Fast Operate messages at the serial port. Set FASTOP := N to block binary Fast Operate messages. Refer to *Appendix C: SEL Communications Processors* for the description of the SEL-787 Fast Operate commands.

Set PROTO := DNET to establish communications when the DeviceNet card is used. *Table 4.49* shows the additional settings, which can be set only at the rear on the DeviceNet card. Once the relay detects the DeviceNet card, all **Port 4** settings are hidden. Refer to *Appendix G: DeviceNet Communications* for details on DeviceNet.

Table 4.49 Rear-Panel DeviceNet Port Settings

| Setting Name | Setting Range |
|--------------|--------------------------------------|
| MAC_ID | 0–63 |
| ASA | 8 Hex characters assigned by factory |
| DN_Rate | 125, 250, 500 kbps |

Front-Panel Settings (SET F Command)

General Settings

Local bits provide control from the front panel (local bits), and display points display selected information on the LCD display. However, you need to first enable the appropriate number of local bits and display points necessary for your application. When your SEL-787 arrives, four display points are already enabled, but no local bits are enabled. If more display points are necessary for your application, use the EDP setting to enable as many as 32 display points. Use the ELB setting to enable as many as 32 local bits.

Table 4.50 Display Point and Local Bit Default Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-------------------|---------------|------------------------------------|
| DISPLAY PTS ENABL | N, 1–32 | EDP := 4 |
| LOCAL BITS ENABL | N, 1–32 | ELB := N |

To optimize the time you spend on setting the device, only the number of enabled display points and enabled local bits become available for use. Use the front-panel LCD timeout setting (FP_TO) as a security measure. If the display is within an Access Level 2 function when a timeout occurs, such as the device setting entry, the function is automatically terminated (without saving changes) after inactivity for this length of time. After terminating the function, the front-panel display returns to the default display. If you prefer to disable the front-panel timeout function during device testing, set the LCD timeout equal to OFF. Use the front-panel LCD contrast setting (FP_CONT) to adjust the contrast of the liquid crystal display.

Use the front-panel automessage setting FP_AUTO to define displaying of Trip/Warning messages. Set FP_AUTO either to Override or add to the Rotating display when the relay triggers a Trip/Warning message. Set RSTLED := Y to reset the latched LEDs automatically when the breaker or the contactor closes.

Table 4.51 Front-Panel General Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|--------------------|------------------------------------|
| LCD TIMEOUT | OFF, 1–30; min | FP_TO := 15 |
| LCD CONTRAST | 1–8 | FP_CONT := 5 |
| FP AUTOMESSAGES | OVERRIDE, ROTATING | FP_AUTO := OVERRIDE |
| CLOSE RESET LEDS | Y, N | RSTLED := Y |

Display Points

NOTE: The rotating display is updated approximately every two (2) seconds.

Use display points to view either the state of internal relay elements (Boolean information) or analog information on the LCD display. Although the LCD screen displays a maximum of 16 characters at a time, you can enter as many as 60 valid characters. Valid characters are 0–9, A–Z, -, /, ", {, }, space. For text exceeding 16 characters, the LCD displays the first 16 characters, then scrolls through the remaining text not initially displayed on the screen.

Table 4.52 LCD Display Point Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|--------------------|---------------|------------------------------------|
| DISPLAY POINT DP01 | 60 characters | DP01 := RID,"{16}" |
| DISPLAY POINT DP02 | 60 characters | DP02 := TID,"{16}" |
| DISPLAY POINT DP03 | 60 characters | DP03 := IAVW1MAG, "W1 AVE I {5} A" |
| DISPLAY POINT DP04 | 60 characters | DP04 := IAVW2MAG, "W2 AVE I {5} A" |
| DISPLAY POINT DP05 | 60 characters | DP05 := |
| • | • | • |
| • | • | • |
| • | • | • |
| DISPLAY POINT DP32 | 60 characters | DP32 := |

Boolean Display Point Entry Composition

Boolean information is the status of Relay Word bits (see *Appendix J: Relay Word Bits*). In general, the legal syntax for Boolean display points consists of the following four fields or strings, separated by commas:

Relay Word Bit Name, “Alias”, “Set String”, “Clear String”.

where:

Name = Relay Word bit name (IN101, for example). All binary quantities occupy one line on the front-panel display (all analog quantities occupy two lines).

Alias = A more descriptive name for the Relay Word bit (such as TRANSFORMER 3), or the analog quantity (such as TEMPERATURE).

Set String = State what should be displayed on the LCD when the Relay Word bit is asserted (CLOSED, for example)

Clear String = State what should be displayed on the LCD when the Relay Word bit is deasserted (OPEN, for example)

Any or all of Alias, Set String, or Clear String can be empty. Although the relay accepts an empty setting Name as valid, a display point with an empty Name setting is always hidden (see below). Commas are significant in identifying and separating the four strings. Use quotation marks only if the text you enter for Alias, Set String, or Clear String contains commas or spaces. For example, DP01 = Name,Text is valid, but Name, Alias 3 is not valid (contains a space). Correct the Alias name by using the quotation marks: Name, “Text 3”. You can customize the data display format by entering data in selected strings only. *Table 4.53* shows the various display appearances resulting from entering data in selected strings.

Hidden (No Display)

A display point is hidden when settings are entered (DP n = XX, where n = 01 through 32 and XX = any valid setting), but nothing shows on the front-panel display. *Table 4.53* shows examples of settings that always, never, or conditionally hide a display point.

Table 4.53 Settings That Always, Never, or Conditionally Hide a Display Point

| Programmable Automation Controller Setting | Name | Alias | Set String | Clear String | Comment |
|--|-------|--------|------------|--------------|---------------------------------|
| DP01 := IN101,TRFR1,CLOSED,OPEN | IN101 | TRFR1 | CLOSED | OPEN | Never hidden |
| DP01 := IN101,TRFR1 | IN101 | TRFR1 | — | — | Never hidden |
| DP01 := NA | — | — | — | — | Always hidden |
| DP01 := IN101,,, | IN101 | — | — | — | Always hidden |
| DP01 := IN101,TRFR1,, | IN101 | TRFR1 | — | — | Always hidden |
| DP01 := IN101,TRFR1,CLOSED, | IN101 | TRFR1 | CLOSED | — | Hidden when IN101 is deasserted |
| DP01 := IN101,"TRFR 1",,OPEN | IN101 | TRFR 1 | — | OPEN | Hidden when IN101 is asserted |

Following are examples of selected display point settings, showing the resulting front-panel displays. For example, at a certain station we want to display the status of both HV and LV circuit breakers of Transformer 1. When the HV circuit breaker is open, we want the LCD display to show: TRFR 1 HV BRKR: OPEN, and when the HV circuit breaker is closed, we want the display to

show: TRFR 1 HV BRKR: CLOSED. We also want similar displays for the LV breaker.

After connecting a form a (normally open) auxiliary contact from the HV circuit breaker to Input **IN101** and a similar contact from the LV circuit breaker to Input **IN102** of the SEL-787, we are ready to program the display points, using the following information for the HV breaker (LV breaker similar):

- Relay Word bit—IN101
- Alias—TRFR 1 HV BRKR:
- Set String—CLOSED (the form a [normally open] contact asserts or sets Relay Word bit IN101 when the circuit breaker is closed)
- Clear String—OPEN (the form a [normally open] contact deasserts or clears Relay Word bit IN101 when the circuit breaker is open)

Name, Alias, Set String, and Clear String

When all four strings have entries, the relay reports all states.

Table 4.54 Entries for the Four Strings

| Name | Alias | Set String | Clear String |
|-------|----------------|------------|--------------|
| IN101 | TRFR 1 HV BRKR | CLOSED | OPEN |

Figure 4.67 shows the settings for the example, using the **SET F** command. Use the **>** character to move to the next settings category.

```

=>>SET F TERSE <Enter>
Front Panel
General Settings
DISPLY PTS ENABL (N,1-32)                                EDP      := 4      ? > <Enter>
.
.
.
Target LED Set
TRIP LATCH T_LED (Y,N)                                T01LEDL := Y      ? > <Enter>
Display Point Settings (maximum 60 characters):
(Boolean): Relay Word Bit Name, "Alias", "Set String", "Clear String"
(Analog) : Analog Quantity Name, "User Text and Formatting"
DISPLAY POINT DP01 (60 characters)
DP01      := RID,"{16}"
? IN101,"TRFR 1 HV BRKR:",CLOSED,OPEN <Enter>
DISPLAY POINT DP02 (60 characters)
DP02      := TID,"{16}"
? IN102,"TRFR 1 LV BRKR:",CLOSED,OPEN <Enter>
DISPLAY POINT DP03 (60 characters)
DP03      := IAV, "IAV CURR {5} A"
? END <Enter>
Save changes (Y,N)? Y <Enter>
Settings Saved
=>>

```

Figure 4.67 Display Point Settings

Figure 4.68 shows the display when both HV and LV breakers are open (both IN101 and IN102 deasserted). Figure 4.69 shows the display when the HV breaker is closed, and the LV breaker is open (IN101 asserted, but IN102 still deasserted).



Figure 4.68 Front-Panel Display—Both HV and LV Breakers Open

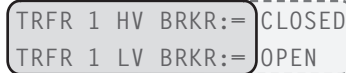


Figure 4.69 Front-Panel Display—HV Breaker Closed, LV Breaker Open

Name String, Alias String, and Either Set String or Clear String Only

The following discusses omission of the Clear String; omission of the Set String gives similar results. Omitting the Clear String causes the relay to only show display points in the set state, using the **SET F** command as follows:

```
DP01      := RID, "{16}"
? IN101, "TRFR 1 HV BRKR:", CLOSED <Enter>
```

When the Relay Word bit IN101 deasserts, the relay removes the complete line with the omitted Clear String (TRFR 1 HV BRKR). When both breakers are closed, the relay has the set state information for both HV and LV breakers, and the relay displays the information as shown in *Figure 4.70*. When the HV breaker opens (LV breaker is still closed), the relay removes the line containing the HV breaker information because the Clear String information was omitted. Because the line containing the HV breaker information is removed, the relay now displays the LV breaker information on the top line, as shown in *Figure 4.71*.



Figure 4.70 Front-Panel Display—Both HV and LV Breakers Closed



Figure 4.71 Front-Panel Display—HV Breaker Open, LV Breaker Closed

If you want the relay to display a blank state when IN101 deasserts instead of removing the line altogether, use the curly brackets {} for the Clear String, as follows:

```
DP01      := RID, "{16}"
? IN101, "TRFR 1 HV BRKR:", CLOSED, {} <Enter>
```

When Input IN101 now deasserts, the relay still displays the line with the HV breaker information, but the state is left blank, as shown in *Figure 4.72*.



Figure 4.72 Front-Panel Display—HV Breaker Open, LV Breaker Closed

Name Only

Table 4.55 shows an entry in the Name String only (leaving the Alias string, Set String, and Clear String void), using the **SET F** command as follows:

```
DP01      := RID, "{16}"
? IN101 <Enter>
```

Table 4.55 Binary Entry in the Name String Only

| Name | Alias | Set String | Clear String |
|-------|-------|------------|--------------|
| IN101 | — | — | — |

Figure 4.73 shows the front-panel display for the entry in Table 4.55. Input IN101 is deasserted in this display (IN101=0), but changes to IN101=1 when Input IN101 asserts.

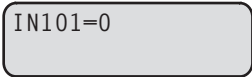


Figure 4.73 Front-Panel Display for a Binary Entry in the Name String Only

Analog Display Point Entry Composition

In general, the legal syntax for analog display points consists of the following two fields or strings:

Name, “User Text and Formatting.”
where:

- Name = Analog quantity name (AI301 for example). All analog quantities occupy two lines on the front-panel display (all binary quantities occupy one line on the display).
- User text and numerical formatting = Display the user text, replacing the numerical formatting {width.dec,scale} with the value of Name, scaled by “scale”, formatted with total width “width” and “dec” decimal places. Name can be either an analog quantity or a Relay Word bit. The width value includes the decimal point and sign character, if applicable. The “scale” value is optional; if omitted, the scale factor is 1. If the numeric value is smaller than the string size requested, the string is padded with spaces to the left of the number. If the numeric value does not fit within the string width given, the string grows (to the left of the decimal point) to accommodate the number.

Unlike binary quantities, the relay displays analog quantities on both display lines. Table 4.56 shows an entry in the Name string only (leaving the User Text and Formatting string void) with the following syntax:

Table 4.56 Analog Entry in the Name String Only

| Name | Alias | Set String | Clear String |
|-------|-------|------------|--------------|
| AI301 | — | — | — |

Figure 4.74 shows the front-panel display for the entry in Table 4.56, using the SET F command as follows:

| | |
|---------|----------------|
| DP01 | := RID, “{16}” |
| ? AI301 | <Enter> |

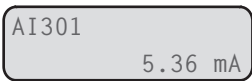


Figure 4.74 Front-Panel Display for an Analog Entry in the Name String Only

Name and Alias

For a more descriptive name of the Relay Word bit, enter the Relay Word bit in the Name String, and an alias name in User Text and Formatting String. Table 4.57 shows a Boolean entry in the Name and Alias Strings (DP01) and an entry in the Name and User Text and Formatting Strings (DP02), using the SET F command as follows:

| | |
|------------------------|----------------|
| DP01 | := RID, "{16}" |
| ? IN101,"INPUT IN101:" | <Enter> |
| DP02 | := TID, "{16}" |
| ? AI301,TEMPERATURE: | <Enter> |

Table 4.57 Entry in the Name String and the Alias Strings

| Name | Alias | Set String | Clear String |
|-------|-------------|------------|--------------|
| IN101 | INPUT IN101 | — | — |
| AI301 | TEMPERATURE | — | — |

Figure 4.75 shows the front-panel display for the entry in Table 4.57. Input IN101 is deasserted in this display (0), and the display changes to INPUT IN101=1 when Input IN101 asserts.

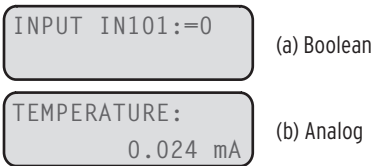


Figure 4.75 Front-Panel Display for an Entry in (a) Boolean Name and Alias Strings and (b) Analog Name and User Text and Formatting Strings

If the engineering units are set, then the front-panel display shows the engineering units. For example, in the Group setting example, we set AI301EU to degrees C. With this setting, the front-panel display looks as shown in Figure 4.76.

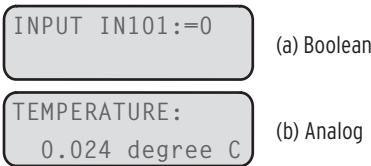


Figure 4.76 Front-Panel Display for an Entry in (a) Boolean Name and Alias Strings and (b) Analog Name, User Text and Formatting Strings, and Engineering Units

For fixed text, enter a 1 in the Name String, then enter the fixed text as the alias text. For example, to display the word DEFAULT and SETTINGS on two different lines, use a display point for each word, i.e., DP01 = 1,“DEFAULT” and DP02 = 1,“SETTINGS.” Table 4.58 shows other options and front-panel displays for the User Text and Formatting settings.

Table 4.58 Example Settings and Displays

| Example Display Point Setting Value | Example Display |
|-------------------------------------|------------------|
| AI301,"TEMP {4}deg C" | TEMP 1234 deg C |
| AI301,"TEMP = {4.1}" | TEMP =xx.x |
| AI301,"TEMP = {5}" | TEMP = 1230 |
| AI301,"TEMP={4.2,0.001} C" | TEMP=1.23 C |
| AI301,"TEMP HV HS1={4,1000}" | TEMP HV HS1=1234 |
| 1,{} | Empty line |

Following is an example of an application of analog settings. Assume we also want to know the hot-spot temperature, oil temperature, and winding temperature of the transformer at a certain installation. To measure these temperatures, we have installed an analog card in relay Slot C, and connected 4–20 mA transducers inputs to analog inputs AI301 (hot-spot temperature), AI302 (oil temperature), and AI303 (winding temperature).

First enable enough display points for the analog measurements (e.g. EDP = 5). *Figure 4.77* shows the settings to add the three transducer measurements. (Use the > character to move to the next settings category).

```

=>>SET F TERSE <Enter>
Front Panel
General Settings
DISPLAY PTS ENABL (N,1-32)          EDP    := 4          ? 5 <Enter>
LOCAL BITS ENABL (N,1-32)          ELB    := 1          ? > <Enter>
.
.
.
Target LED Set
TRIP LATCH T_LED (Y,N)              T01LEDL := Y          ? > <Enter>
Display Point Settings (maximum 60 characters):
(Boolean): Relay Word Bit Name, "Alias", "Set String", "Clear String"
(Analog) : Analog Quantity Name, "User Text and Formatting"
DISPLAY POINT DP01 (60 characters)
DP01    := IN101,"TRFR 1 HV BRKR:",CLOSED,OPEN
? <Enter>
DISPLAY POINT DP02 (60 characters)
DP02    := IN102,"TRFR 1 LV BRKR:",CLOSED,OPEN
? <Enter>
DISPLAY POINT DP03 (60 characters)
DP03    := IAV, "IAV CURR {5} A"
? AI301,"HOT SPOT TEMP" <Enter>
DISPLAY POINT DP04 (60 characters)
DP04    := IG_MAG, "GND CURR {5} %"
? AI302,"OIL TEMPERATURE" <Enter>
DISPLAY POINT DP05 (60 characters)
DP05    := IA_MAG, "IA {7.1} A pri"
? AI303,"WINDING TEMP" <Enter>
Save changes (Y,N)? Y <Enter>
Settings Saved
=>>

```

Figure 4.77 Adding Temperature Measurement Display Points

Rotating Display

With more than two display points enabled, the relay scrolls through all enabled display points, thereby forming a rotating display, as shown in *Figure 4.78*.

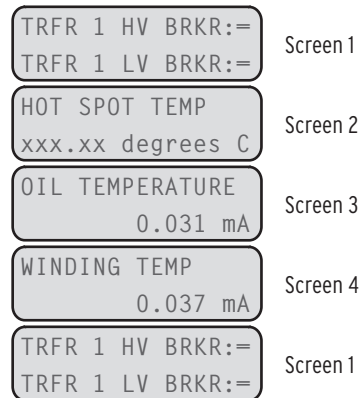


Figure 4.78 Rotating Display

To change the temperature units to more descriptive engineering units, enter the desired units with the `AIxxxEU` (e.g., `AI302EU`) setting.

Local Bits

Local bits are variables (`LBnn`, where *nn* means 01 through 32) that are controlled from front-panel pushbuttons. Use local bits to replace traditional panel switches. The state of the local bits is stored in nonvolatile memory every second. When power to the device is restored, the local bits will go back to their states after the device initialization.

Each local bit requires three of the following four settings, using a maximum of 14 valid characters for the `NLBnn` setting, and a maximum seven valid characters (0–9, A–Z, -, /, ., space) for the remainder:

- **NLBnn:** Name the switch (normally the function that the switch performs, such as `SUPERV SW`) that will appear on the LCD display.
- **CLBnn:** Clear local bit. Enter the text that describes the intended operation of the switch (this text appears on the display) when `LBnn` deasserts (`OPEN`, for example).
- **SLBnn:** Set local bit. Enter the text that describes the intended operation of the switch (this text appears on the display) when `LBnn` asserts (`CLOSE`, for example).
- **PLBnn:** Pulse local bit. When selecting the pulse operation, `LBnn` asserts for only one processing interval before deasserting again. Enter the text that describes the intended operation when `LBnn` asserts (`START`, for example).
- Omit either `SLBnn` or `PLBnn` (never `CLBnn`) by setting the omitted setting to `NA`.

For the transformer in our example, configure two local bits: one to replace a supervisory switch, and the other to start a fan motor. Local bit 1 replaces a supervisory switch (`SUPERV SW`) and we use the clear/set combination. Local bit 2 starts a fan motor (`START`) that only needs a short pulse to seal itself in, and we use the clear/pulse combination. *Figure 4.79* shows the settings to program the two local bits.

```

=>>SET F TERSE <Enter>
Front Panel
General Settings
DISPLY PTS ENABL (N,1-32)          EDP      := 5      ? <Enter>
LOCAL BITS ENABL (N,1-32)          ELB      := N      ? 2 <Enter>
LCD TIMEOUT (OFF,1-30 min)         FP_TO    := 15     ? > <Enter>
.
.
.
Target LED Set
TRIP LATCH T_LED (Y,N)              T01LEDL := Y      ? > <Enter>
Display Point Settings (maximum 60 characters):
(Boolean): Relay Word Bit Name, "Alias", "Set String", "Clear String"
(Analog) : Analog Quantity Name, "User Text and Formatting"
DISPLAY POINT DP01 (60 characters)
DP01      := IN101,"TRFR 1 HV BRKR:",CLOSED,OPEN
? > <Enter>
Local Bits Labels:
LB_NAME (14 characters; Enter NA to null)
NLB01      :=
? SPERV SW <Enter>
CLEAR LB_LABEL (7 characters; Enter NA to null)
CLB01      :=
? OPEN <Enter>
SET LB_LABEL (7 characters; Enter NA to null)
SLB01      :=
? CLOSE <Enter>
PULSE LB_LABEL (7 characters; Enter NA to null)
PLB01      :=
? NA <Enter>
LB_NAME (14 characters; Enter NA to null)
NLB02      :=
? FAN START <Enter>
CLEAR LB_LABEL (7 characters; Enter NA to null)
CLB02      :=
? OFF <Enter>
SET LB_LABEL (7 characters; Enter NA to null)
SLB02      :=
? NA <Enter>

PULSE LB_LABEL (7 characters; Enter NA to null)
PLB02      :=
? START <Enter>
Save changes (Y,N)? Y <Enter>
Settings Saved
=>>

```

Figure 4.79 Adding Two Local Bits

Target LED Settings

The SEL-787 offers the following two types of LEDs. See *Figure 8.1* and *Figure 8.25* for the programmable LED locations:

- Six Target LEDs
- Eight Pushbutton LEDs

You can program all 14 LEDs using SELOGIC control equations, the only difference being that the Target LEDs also include a latch function.

Target LEDs

NOTE: If the LED latch setting (TnLEDL) is set to Y, and TRIP asserts, the LED latches to the state at TRIP assertion. The latched LED targets can be reset with TARGET RESET if the target conditions are absent.

Settings $TnLEDL$ ($n = 01$ through 06) and Tn_LED ($n = 01$ through 06) control the six front-panel LEDs. With $TnLEDL$ set to Y, the LEDs latch the LED state at TRIP assertion. To reset these latched LEDs, the corresponding LED equation must be deasserted (logical 0) and one of the following takes place:

- Pressing **TARGET RESET** on the front panel.
- Issuing the serial port command **TAR R**.
- The assertion of the SELOGIC equation RSTTRGT.

With $TnLEDL$ settings set to N, the LEDs do not latch and directly follow the state of the associated SELOGIC control equation setting.

Enter any of the Relay Word bits (or combinations of Relay Word bits) as conditions in the Tn_LED SELOGIC control equation settings. When these Relay Word bits assert, the corresponding LED also asserts.

Table 4.59 Target LED Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|---|
| TRIP LATCH T_LED | Y, N | T01LEDL := Y |
| LED1 EQUATION | SELOGIC | T01_LED := 87U OR 87R |
| TRIP LATCH T_LED | Y, N | T02LEDL := Y |
| LED2 EQUATION | SELOGIC | T02_LED := ORED50T |
| TRIP LATCH T_LED | Y, N | T03LEDL := Y |
| LED3 EQUATION | SELOGIC | T03_LED := ORED51T |
| TRIP LATCH T_LED | Y, N | T04LEDL := Y |
| LED4 EQUATION | SELOGIC | T04_LED := 27P1T OR 27P2T OR 59P1T OR 59P2T OR 59Q1T OR 59Q2T |
| TRIP LATCH T_LED | Y, N | T05LEDL := Y |
| LED5 EQUATION | SELOGIC | T05_LED := 81D1T OR 81D2T OR 81D3T OR 81D4T |
| TRIP LATCH T_LED | Y, N | T06LEDL := Y |
| LED6 EQUATION | SELOGIC | T06_LED := 24D1T OR 24C2T |

Pushbutton LEDs

Enter any of the Relay Word bits (or combinations of Relay Word bits) as conditions in the PBp_LED ($p = 1A, 1B, \dots, 4A, 4B$) SELOGIC control equation settings. When these Relay Word bits assert, the corresponding LED also asserts. *Table 4.60* shows the setting prompts, settings ranges, and default settings for the LEDs.

Table 4.60 Pushbutton LED Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-------------------|---------------|---|
| PB1A_LED EQUATION | SELOGIC | PB1A_LED := NOT LT01 OR SV01 AND NOT SV01T AND SV05T |
| PB1B_LED EQUATION | SELOGIC | PB1B_LED := LT01 OR SV01 AND NOT SV01T AND SV05T |
| PB2A_LED EQUATION | SELOGIC | PB2A_LED := NOT LT02 OR SV02 AND NOT SV02T AND SV05T AND PB02 |
| PB2B_LED EQUATION | SELOGIC | PB2B_LED := LT02 OR SV02 AND NOT SV02T AND SV05T AND PB02 |
| PB3A_LED EQUATION | SELOGIC | PB3A_LED := 52A1 OR (SV03 AND SV05T AND NOT SV03T AND NOT LT02) |
| PB3B_LED EQUATION | SELOGIC | PB3B_LED := 52A2 OR (SV03 AND SV05T AND NOT SV03T AND LT02) |
| PB4A_LED EQUATION | SELOGIC | PB4A_LED := NOT 52A1 OR (SV04 AND SV05T AND NOT SV04T AND NOT LT02) |
| PB4B_LED EQUATION | SELOGIC | PB4B_LED := NOT 52A2 OR (SV04 AND SV05T AND NOT SV04T AND LT02) |

Report Settings (SET R Command)

The report settings use Relay Word bits for the SER trigger as shown in *Table 4.62* (see *Appendix J: Relay Word Bits* for more information).

SER Chatter Criteria

The SER includes an automatic deletion and reinsertion function to prevent overfilling of the SER buffer with chattering information. Each processing interval the relay checks the Relay Word bits in the four SER reports for any changes of state. When detecting a change of state, the relay adds a record to the SER report containing the Relay Word bit(s), new state, time stamp, and checksum (see *Section 9: Analyzing Events* for more information).

When detecting oscillating SER items, the relay automatically deletes these oscillating items from SER recording. *Table 4.61* shows the auto-removal settings.

Table 4.61 Auto-Removal Settings

| Settings Prompt | Setting Range | Factory Default |
|---------------------|------------------|-----------------|
| Auto-Removal Enable | Y, N | ESERDEL := N |
| Number of Counts | 2–20 counts | SRDLCNT := 5 |
| Removal Time | 0.1–90.0 seconds | SRDLTIM := 1.0 |

To use the automatic deletion and reinsertion function, proceed with the following steps:

- Step 1. Set Report setting ESERDEL (Enable SER Delete) to Y to enable this function.
- Step 2. Select values for the setting SRDLCNT (SER Delete Count) and the setting SRDLTIM (SER Delete Time) that mask the chattering SER element.

Setting SRDLTIM declares a time interval during which the relay qualifies an input by comparing the changes of state of each input against the SRDLCNT setting. When an item changes state more than SRDLCNT times in an SRDLTIM interval, the relay automatically removes these Relay Word bits from SER recording. Once deleted from recording, the item(s) will be ignored for the next nine intervals. At the ninth interval, the chatter criteria will again be checked and, if the point does not exceed the criteria, it will be automatically reinserted into recording at the starting of the tenth interval. The user can enable or disable the auto-deletion function via the SER settings. Any auto-deletion notice entry will be lost during changes of settings. The deleted items can be viewed in the SER Delete Report (Command **SER D**—refer to *Section 7: Communications* for additional information).

SER Trigger Lists

To capture element state changes in the SER report, enter the Relay Word bit into one of the four SER (SER1 through SER4) trigger equations. Each of the four programmable trigger equations allows entry of as many as 24 Relay Word bits separated by spaces or commas; the SER report accepts a total of 96 Relay Word bits. *Table 4.62* shows the settings prompt and default settings for the four SER trigger equations.

Table 4.62 SER^a Trigger Settings

| Setting Prompt | Setting Name := Factory Default |
|----------------|--|
| SER1 | SER1 := IN101 IN102 PB01 PB02 PB03 PB04 52A1 52A2 TRIP1 TRIP2 TRIPXFMR |
| SER2 | SER2 := ORED51T ORED50T 87U 87R 27P1T 27P2T 59P1T 59P2T 59Q1T 59Q2T 3PWR1T 3PWR2T REF1F 24D1T 24C2T RTDT |
| SER3 | SER3 := 81D1T 81D2T 81D3T 81D4T |
| SER4 | SER4 := SALARM |

^a Use as many as 24 Relay Word elements separated by spaces or commas for each setting.

Relay Word Bit Aliases

Table 4.63 Enable Alias Settings

| Setting Prompt | Setting Range | Setting Name = Factory Default |
|---------------------------------|---------------|--------------------------------|
| Enable ALIAS Settings (N, 1–20) | N, 1–20 | EALIAS = 4 |

To simplify your review of the information displayed in the SER record, the relay provides the Alias setting function. Using the Alias settings, you can change the way relay elements listed in the SER settings above are displayed in the SER report. In addition, the Alias settings allow you to change the text displayed when a particular element is asserted and deasserted. The relay permits as many as 20 unique aliases, as defined by the Enable Alias Settings (EALIAS) setting. Factory-default alias settings are shown in *Table 4.64*.

Define the enabled alias settings by entering the Relay Word bit name, a space, the desired alias, a space, the text to display when the condition asserts, a space, and the text to display when the condition deasserts.

ALIAS1 = PB01 FP_AUX1 PICKUP DROPOUT

See *Table J.1* for the complete list of Relay Word bits. Use as many as 15 characters to define the alias, asserted text, and deasserted text strings. You can use capital letters (A–Z), numbers (0–9), and the underscore character (_) within each string. Do not attempt to use a space within a string because the relay will interpret a space as the break between two strings. If you wish to clear a string, simply type **NA**.

Table 4.64 SET R SER Alias Settings

| Setting Prompt | Relay Word Bit | Alias | Asserted Text | Deasserted Text |
|--------------------|----------------|----------------|---------------|-----------------|
| ALIAS1 := | PB01 | FP_LOCK | PICKUP | DROPOUT |
| ALIAS2 := | PB02 | FP_BRKR_SELECT | PICKUP | DROPOUT |
| ALIAS3 := | PB03 | FP_CLOSE | PICKUP | DROPOUT |
| ALIAS4 := | PB04 | FP_TRIP | PICKUP | DROPOUT |
| ALIAS5 –ALIAS20 | NA | | | |

Event Report Settings

NOTE: Event report data stored in the relay will be lost when you change the LER setting. You must save the data before changing the setting.

Table 4.65 Event Report Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|-----------------|---------------|---------------------------------|
| EVENT TRIGGER | SELOGIC | ER := 0 |
| EVENT LENGTH | 15, 64 cyc | LER := 15 |
| PREFault LENGTH | 1–59 cyc | PRE := 5 |

Event reports can be either 15 cycles or 64 cycles in length as determined by the LER setting. For LER of 15, the prefault length, PRE, must be in the range 1–10. The relay can hold at least seventy-seven 15-cycle event reports or nineteen 64-cycle event reports.

Load Profile Settings

IMPORTANT: All stored load data are lost when changing the LDLIST.

Use the LDLIST setting to declare the analog quantities you want included in the Load Profile Report. Enter as many as 17 analog quantities, separated by spaces or commas, into LDLIST setting. See *Appendix K: Analog Quantities* for a list of the available Analog Quantities. Also set the LDAR to the desired acquisition rate for the report.

Table 4.66 Load Profile Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------|-------------------------------------|---------------------------------|
| LDP LIST | NA, as many as 17 analog quantities | LDLIST := NA |
| LDP ACQ RATE | 5, 10, 15, 30, 60 min | LDAR := 15 |

DNP Map Settings (SET DNP n Command, n = 1, 2, or 3)

Table 4.67 shows the available settings. See *Appendix D: DNP3 Communications* for additional details.

Table 4.67 DNP Map Settings^a (Sheet 1 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------------------|---------------|---------------------------------|
| DNP Binary Input Label Name | 10 characters | BI_00 := ENABLED |
| DNP Binary Input Label Name | 10 characters | BI_01 := TRIPXFMR |
| DNP Binary Input Label Name | 10 characters | BI_02 := TRIP1 |
| DNP Binary Input Label Name | 10 characters | BI_03 := TRIP2 |
| • | • | • |
| • | • | • |
| • | • | • |
| DNP Binary Input Label Name | 10 characters | BI_99 := NA |
| DNP Binary Output Label Name | 10 characters | BO_00 := RB01 |
| • | • | • |
| • | • | • |
| • | • | • |
| DNP Binary Output Label Name | 10 characters | BO_31 := RB32 |
| DNP Analog Input Label Name | 24 characters | AI_00 := IAW1_MAG |

Table 4.67 DNP Map Settings^a (Sheet 2 of 2)

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------------------|---------------|------------------------------------|
| DNP Analog Input Label Name | 24 characters | AI_01 := IBW1_MAG |
| • | • | • |
| • | • | • |
| • | • | • |
| DNP Analog Input Label Name | 24 characters | AI_99 := NA |
| DNP Analog Output Label Name | 6 characters | AO_00 := NA |
| • | • | • |
| • | • | • |
| • | • | • |
| DNP Analog Output Label Name | 6 characters | AO_31 := NA |
| DNP Counter Label Name | 11 characters | CO_00 := NA |
| • | • | • |
| • | • | • |
| • | • | • |
| DNP Counter Label Name | 11 characters | CO_31 := NA |

^a See Appendix D: DNP3 Communications for complete list of the DNP Map Labels and factory-default settings.

Modbus Map Settings (SET M Command)

Modbus User Map

Table 4.68 shows the available settings. See *Appendix E: Modbus RTU Communications* for additional details.

Table 4.68 User Map Register Settings^a

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|----------------|-----------------------------|------------------------------------|
| USER REG#001 | NA, 1 Modbus Register Label | MOD_001 := IAW1_MAG |
| • | • | • |
| • | • | • |
| • | • | • |
| USER REG#125 | NA, 1 Modbus Register Label | MOD_125 := NA |

^a See Appendix E: Modbus RTU Communications for a complete list of the Modbus Register Labels and factory-default settings.

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Section 5

Metering and Monitoring

Overview

The SEL-787 Transformer Protection Relay includes metering functions to display the present values of current, voltage (if included), analog inputs (if included), and RTD measurements (with the external SEL-2600 RTD Module or an internal RTD card).

The relay provides the following methods to read the present meter values:

- Front-panel rotating display
- Front-panel menu
- EIA-232 serial ports (using SEL ASCII text commands or ACSELERATOR QuickSet® SEL-5030 Software)
- Telnet via Ethernet port
- Modbus® via EIA-485 port or EIA-232 port
- Modbus TCP via Ethernet® port
- DNP3 Serial via EIA-232 port or EIA-485 port
- DNP3 LAN/WAN via Ethernet port
- DeviceNet port
- Analog outputs
- IEC 61850 via Ethernet port
- C37.118 Synchrophasor Protocol via serial port

Load monitoring and trending are possible using the Load Profile function. The relay automatically configures itself to save as many as 17 quantities (selected from the Analog Quantities) every 5, 10, 15, 30, or 60 minutes. The data are stored in nonvolatile memory. As many as 6500 time samples are stored.

The SEL-787 has a through-fault event monitoring function that gathers current level, duration and date/time for each through fault experienced by the transformer. The function calculates and tracks accumulated I^2t through fault and alarms excess I^2t over time. This monitor function can be used to schedule proactive transformer bank maintenance.

Power Measurement Conventions

The SEL-787 uses the IEEE convention for power measurement. The implications of this convention are depicted in *Figure 5.1*.

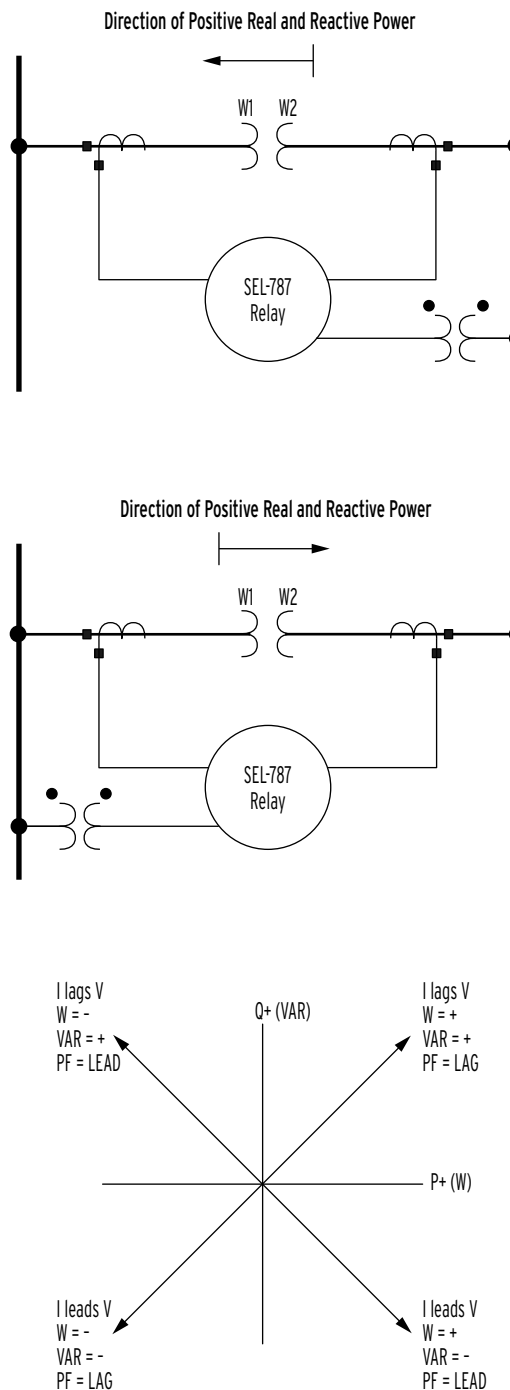


Figure 5.1 Complex Power Measurement Conventions

Metering

The SEL-787 meter data fall into the following categories:

- Fundamental metering
- Differential metering
- Thermal metering: RTD metering (with the external SEL-2600 RTD Module or an internal RTD option)
- Energy metering
- Maximum and minimum metering
- Math variable metering (analog quantities metering)
- RMS metering
- Analog transducer input metering
- Demand and peak demand metering
- Harmonic metering
- Synchrophasor metering

Fundamental Metering

Table 5.1 details each of the fundamental meter data types in the SEL-787. *Section 8: Front-Panel Operations* and *Section 7: Communications* describe how to access the various types of meter data using the relay front panel and communications ports.

If the winding phase CTs are delta connected, the primary currents displayed are derived from the secondary values by multiplying them with CTR (CT ratio) and dividing them by the square root of 3. The phase angles shown are the same as the secondary values. If the CT connection type is known (DAB or DAC), the user can correct the phase angles. The MET response is meant to show steady-state primary values. During unbalanced conditions the primary line currents cannot be reproduced accurately because the delta-connected CTs filter out the zero-sequence component of the line current. Wye-connected CTs do not have any such issue.

Table 5.1 Measured Fundamental Meter Values (Sheet 1 of 2)

| Relay Option | Meter Values |
|-----------------------------------|---|
| All Models | <p>Line Currents: IAW1, IBW1, ICW1 and IAW2, IBW2, ICW2 magnitudes (A primary) and phase angles (deg)</p> <p>IGW1, IGW2 (Residual Ground Fault Current) magnitude (A primary) and phase angle (deg) for Winding 1 and 2</p> <p>IAVW1, IAVW2 (Average Current Magnitude for Winding 1 and 2) (A primary)</p> <p>Negative-Sequence Currents (3I2W1 and 3I2W2) (A primary)</p> |
| With Neutral Current Option (REF) | <p>IN magnitude (A primary) phase angle (deg)</p> |
| With Voltage Option | <p>VAB, VBC, VCA or VAN, VBN, VCN, VG magnitudes (V primary) and phase angles (deg)</p> <p>Average Voltage (L-L or L-N) (V primary)</p> <p>Negative-Sequence (3V2) (V primary)</p> <p>Real Power (kW)</p> <p>Reactive Power (kVAR)</p> |

Table 5.1 Measured Fundamental Meter Values (Sheet 2 of 2)

| Relay Option | Meter Values |
|--------------|--|
| | Apparent Power (kVA) Power Factor Volts/Hertz (%), System frequency (Hz) |

All angles are displayed between –180 and +180 degrees. The angles are referenced to VAB or VAN (for delta- or wye-connected PT, respectively) or IAW1. If the voltage channels are not supported, or if VAB < 13 V (for delta-connected PT) or VAN < 13 V (for wye-connected PT), the angles are referenced to IAW1 current. *Figure 5.2* shows an example of the **METER** command report.

NOTE: Calculated phase-to-phase voltages for wye-connected PTs are available in the analog quantities and can be selected as display points. See Appendix K: Analog Quantities.

=>>MET <Enter>

SEL-787 Date: 01/23/2008 Time: 13:46:49
TRNSFRMR RELAY Time Source: Internal

| | | | | | | |
|-------------------|--------|--------|--------|--------|-------|--------|
| | IAW1 | IBW1 | ICW1 | IGW1 | 3I2W1 | IAVW1 |
| Wdg1 Mag (A pri.) | 118.4 | 122.5 | 120.6 | 4.1 | 3.1 | 120.5 |
| Wdg1 Angle (deg) | -2.4 | -122.3 | 117.9 | -151.2 | 154.3 | 0.0 |
| | IAW2 | IBW2 | ICW2 | IGW2 | 3I2W2 | IAVW2 |
| Wdg2 Mag (A pri.) | 2357.6 | 2457.8 | 2402.2 | 97.3 | 76.8 | 2405.9 |
| Wdg2 Angle (deg) | -2.2 | -122.3 | 118.0 | -150.4 | 141.9 | 0.0 |

| | |
|----------------------|-------|
| | IN |
| Neutral Mag (A pri.) | 147.0 |
| Neutral Angle (deg) | -1.0 |

| | | | | | | |
|-------------------|---------|---------|---------|--------|-------|---------|
| | VA | VB | VC | VG | 3V2 | VAVE |
| Volt Mag (V pri.) | 12094.5 | 12268.1 | 11894.3 | 1037.3 | 752.4 | 12085.6 |
| Volt Angle (deg) | 0.0 | -120.0 | 124.0 | -131.9 | -5.6 | 0.0 |

| | |
|-----------------------|-------|
| Real Power (kW) | 87032 |
| Reactive Power (kVAR) | 5360 |
| Apparent Power (kVA) | 87197 |
| Power Factor (LAG) | 1.00 |

| | |
|----------------|-------|
| Frequency (Hz) | 60.0 |
| V/Hz (%) | 153.9 |

=>>

Figure 5.2 METER Command Report With Voltage Option

Differential Metering

The differential metering function in the SEL-787 reports the fundamental frequency operate and restraint currents for each differential element (87) in multiples of TAP. *Table 5.2* shows the value reported. *Figure 5.3* shows an example of the **METER DIF** (differential) command report.

Table 5.2 Measured Differential Meter Values

| Relay Option | Differential Values |
|--------------|--|
| All | <p>Operate currents IOP1, IOP2, IOP3 in pu of TAP value for elements 87-1, 87-2, and 87-3, respectively</p> <p>Restraint currents IRT1, IRT2, IRT3 in pu of TAP value for elements 87-1, 87-2, and 87-3, respectively</p> <p>IOP1F2, IOP2F2, and IOP3F2 are 2nd harmonic currents as a percentage of IOP1, IOP2, and IOP3, respectively.</p> <p>IOP1F4, IOP2F4, IOP3F4 are 4th harmonic currents as a percentage of IOP1, IOP2, and IOP3, respectively.</p> <p>IOP1F5, IOP2F5, and IOP3F5 are 5th harmonic currents as a percentage of IOP1, IOP2, and IOP3, respectively.</p> |

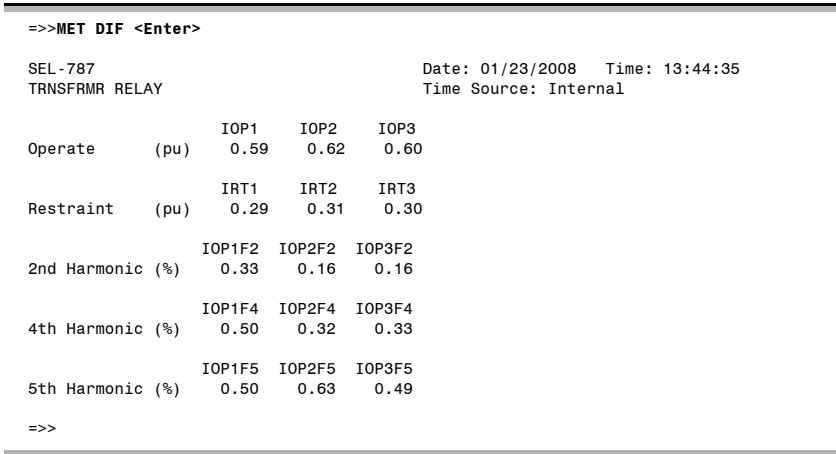


Figure 5.3 METER DIF (Differential) Command Report

Thermal Metering

The thermal metering function reports the RTD meter values (see *Table 5.3* for details) and also reports the state of connected RTDs if any have failed (see *Table 5.4* for details).

Table 5.3 Thermal Meter Values

| Relay Option | Thermal Values |
|--|----------------------|
| With External SEL-2600 RTD Module or Internal RTD Option | All RTD Temperatures |

Table 5.4 RTD Input Status Messages

| Message | Status |
|-----------|---|
| Open | RTD leads open |
| Short | RTD leads shorted |
| Comm Fail | Fiber-optic communications to SEL-2600 RTD Module have failed |
| Stat Fail | SEL-2600 RTD Module self-test status failure |

Figure 5.4 provides an example of the **METER T** command report.

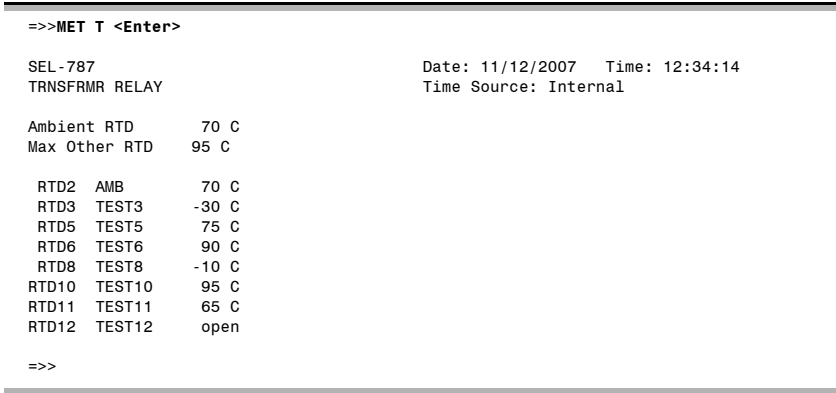


Figure 5.4 METER T Command Report With RTDs

Energy Metering

The SEL-787 with the voltage option includes energy metering. Use this form of metering to quantify real and reactive energy supplied by the transformer. Refer to *Figure 5.1* for the definitions of positive real power, negative real power, positive reactive power, and negative reactive power. Below are the energy meter values:

- MWhP—Positive real 3-phase energy
- MWhN—Negative real 3-phase energy
- MVARhP—Positive reactive 3-phase energy
- MVARhN—Negative reactive 3-phase energy
- Last date and time energy meter quantities were reset

NOTE: Energy values roll over after 99,999,999 MVAh and reset to 0.

Figure 5.5 shows the device response to the **METER E** command.

```
=>MET E <Enter>

SEL-787                               Date: 02/23/2009 Time: 13:48:27
TRANSFRMR RELAY                       Time Source: Internal

Energy
Positive MWH (MWh)                     5.300
Negative MWH (MWh)                     0.000
Positive MVARH (MVarh)                 0.000
Negative MVARH (MVarh)                 0.411

LAST RESET = 02/20/2009 10:55:52
=>
```

Figure 5.5 METER E Command Report

To reset energy meter values, issue the **MET RE** command as shown in *Figure 5.6*.

```
=>>MET RE <Enter>
Reset Metering Quantities (Y,N)? Y <Enter>
Reset Complete
=>>
```

Figure 5.6 METER RE Command Report

Energy metering values are stored to nonvolatile memory four times per day and within one minute of the energy metering values being reset.

Maximum and Minimum Metering

Maximum and minimum metering allows you to determine maximum and minimum operating quantities such as currents, voltages, power, analog input quantities, RTD quantities and frequency. *Table 5.5* lists the max/min metering quantities.

Table 5.5 Maximum/Minimum Meter Values (Sheet 1 of 2)

| Relay Option | Max/Min Meter Values |
|-----------------------------------|--|
| Base Model | Maximum and minimum line currents IAW1, IBW1, ICW1, IAW2, IBW2, ICW2 (A primary) Maximum and minimum IG (residual ground fault current) magnitude (A primary) |
| With Neutral Current Option (REF) | Maximum and minimum neutral current IN magnitudes (A primary) |

Table 5.5 Maximum/Minimum Meter Values (Sheet 2 of 2)

| Relay Option | Max/Min Meter Values |
|--|---|
| With Voltage Option | VAB, VBC, VCA or VAN, VBN, VCN magnitudes (V primary) Maximum and minimum real, reactive and apparent 3-phase power (kW, kVAR, kVA) Maximum and minimum system frequency (Hz) |
| With RTD option or SEL-2600 RTD Module | Maximum and minimum RTD temperatures (°C) |
| With analog input option | Maximum and minimum analog input values (engineering units) |

All maximum and minimum metering values will have the date and time that they occurred. The analog quantities from *Table 5.5* are checked approximately every 1.0 seconds and, if a new maximum or minimum value occurs, this value is saved along with the date and time that the maximum or minimum value occurred. Maximum and minimum values are only checked if relay element FAULT is deasserted (no fault condition exists) for at least one second. Additionally, the following minimum thresholds must also be met:

- Current magnitudes of IAW_n, IBW_n, and ICW_n: 3% of the nominal current (INOM • CTR_n). (*n* = 1 or 2 depending on the winding)
- Current magnitude of IGW_n: IAW_n, IBW_n, and ICW_n all must be above their thresholds (*n* = 1 or 2 depending on the winding)
- Current magnitude of IN: 3% of the nominal IN rating (INOM • CTRN)
- Voltage values (phase-neutral and phase-to-phase): 7.5 • PTR V and 13 • PTR V, respectively.
- Power values (real, reactive, and apparent): All three currents (IAW_n, IBW_n, ICW_n) and all three voltages (VA, VB, VC or VAB, VBC, VCA) must be above their thresholds.

Figure 5.7 shows an example device response to the **METER M** command.

| | | | | | | | |
|---|--------|------------|----------|---------------------------------|------------|----------|--|
| ==>MET M <Enter> | | | | | | | |
| SEL-787 | | | | Date: 11/01/2007 Time: 14:32:32 | | | |
| TRNSFRMR RELAY | | | | Time Source: Internal | | | |
| | MAX | DATE | TIME | MIN | DATE | TIME | |
| IAW1 (A) | 607.5 | 11/01/2007 | 10:57:48 | 485.9 | 11/01/2007 | 10:56:20 | |
| IBW1 (A) | 608.3 | 11/01/2007 | 11:02:09 | 604.8 | 11/01/2007 | 10:56:35 | |
| ICW1 (A) | 733.7 | 11/01/2007 | 10:56:13 | 609.7 | 11/01/2007 | 11:02:44 | |
| IGW1 (A) | 1411.5 | 11/01/2007 | 10:57:57 | 2.1 | 11/01/2007 | 11:02:57 | |
| IN (A) | 3002.3 | 11/01/2007 | 11:03:07 | 177.7 | 11/01/2007 | 10:55:58 | |
| IAW2 (A) | 607.8 | 11/01/2007 | 10:57:48 | 116.2 | 11/01/2007 | 10:56:20 | |
| IBW2 (A) | 606.8 | 11/01/2007 | 11:02:09 | 235.8 | 11/01/2007 | 10:56:35 | |
| ICW2 (A) | 608.4 | 11/01/2007 | 10:56:13 | 364.5 | 11/01/2007 | 11:02:44 | |
| IGW2 (A) | 1200.5 | 11/01/2007 | 10:58:04 | 158.8 | 11/01/2007 | 11:03:33 | |
| VA (V) | 10004 | 11/01/2007 | 10:57:41 | 6701.4 | 11/01/2007 | 11:03:30 | |
| VB (V) | 10006 | 11/01/2007 | 10:58:02 | 6704.9 | 11/01/2007 | 11:02:32 | |
| VC (V) | 10025 | 11/01/2007 | 10:56:55 | 6714.7 | 11/01/2007 | 11:00:30 | |
| KW3P (kW) | 9626.1 | 11/01/2007 | 11:02:03 | -1561.9 | 11/01/2007 | 10:56:21 | |
| KVAR3P (kVAR) | 1814.3 | 11/01/2007 | 10:57:42 | -7408.9 | 11/01/2007 | 11:01:17 | |
| KVA3P (kVA) | 12133 | 11/01/2007 | 11:02:57 | 2330.7 | 11/01/2007 | 10:56:07 | |
| FREQ (Hz) | 60.0 | 11/01/2007 | 11:01:18 | 60.0 | 11/01/2007 | 10:58:05 | |
| LAST RESET = LAST RESET = 11/01/2007 10:55:52 | | | | | | | |
| ==> | | | | | | | |

Figure 5.7 METER M Command Report

Math Variable
Metering

RMS Metering

To reset maximum/minimum meter values, issue the **MET RM** command as shown in *Figure 5.8*. The max/min meter values can be reset from the serial port, the front panel, or assertion of the RSTMXMN relay element. The date and time of the reset are preserved and shown in the max/min meter report.

```
=>>MET RM <Enter>
Reset Metering Quantities (Y,N)? Y <Enter>
Reset Complete
=>>
```

Figure 5.8 METER RM Command Response

All maximum and minimum metering values are stored to nonvolatile memory four times per day and within one minute of the maximum and minimum metering values being reset.

The SEL-787 includes 32 math variables. When you receive your SEL-787, no math variables are enabled. To use math variables, enable the number of math variables (between 1 and 32) you require, using the EMV setting in the Logic setting category. *Figure 5.9* shows the device response to the **METER MV M(ath) V(ariable)** command with 8 of the 32 math variables enabled.

```
=>>MET MV <Enter>

SEL-787                                     Date: 03/11/2008   Time: 12:32:10
TRNSFRMR RELAY                             Time Source: Internal

MV01      1.00
MV02    -32767.00
MV03      -1.00
MV04       0.00
MV05    1000.59
MV06   -1000.61
MV07    2411.01
MV08    2410.99

=>>
```

Figure 5.9 MET MV Command Report

The SEL-787 includes root mean squared (rms) metering. Use rms metering to measure the entire signal (including harmonics). You can measure the rms quantities shown in *Table 5.6*.

Table 5.6 RMS Meter Values

| Relay Option | RMS Meter Values |
|----------------------------------|---|
| Base Model | RMS current IAW1, IBW1, ICW1, IAW2, IBW2, and ICW2 magnitudes (A primary) |
| With Neutral Current (IN) Option | RMS current IN magnitude (A primary) |
| With Voltage Option | VAB, VBC, VCA or VAN, VBN, VCN, and VG magnitudes (V primary) |

RMS quantities contain the total signal, including harmonics. This differs from the fundamental meter (**METER** command) in that the fundamental meter quantities only contain the fundamental frequency (60 Hz for a 60-Hz system). *Figure 5.10* shows the **METER RMS** command report.

```

=>MET RMS <Enter>

SEL-787                               Date: 01/23/2008   Time: 13:44:57
TRNSFRMR RELAY                       Time Source: Internal

RMS (A pri.)    IAW1    IBW1    ICW1
                118.0    122.5    120.7

RMS (A pri.)    IAW2    IBW2    ICW2
                2351.7   2461.3   2401.1

RMS (A pri.)    IN
                146.6

RMS (V pri.)    VAB     VBC     VCA
                12090    11893    21180

=>

```

Figure 5.10 METER RMS Command Report

Analog Input Metering

The SEL-787 can monitor analog (transducer) quantities that it is measuring if equipped with optional analog inputs. Analog input metering shows transducer values from standard voltage and current transducers. These values can then be used for monitoring automation and control applications.

Through the global settings, you can set each type of analog input to the type of transducer that drives that analog input. You also set the range of the transducer output. Analog inputs can accept both current and voltage transducer outputs. Ranges for the current transducers are ± 20 mA and ranges for the voltage transducers are ± 10 V. You also set the corresponding output of the analog inputs in engineering units. See *Section 4: Protection and Logic Functions* for an explanation of how to set up analog inputs for reading transducers. *Figure 5.11* shows an example of analog input metering.

```

=>MET AI <Enter>

SEL-787                               Date: 01/23/2008   Time: 13:44:44
TRNSFRMR RELAY                       Time Source: Internal

Input Card 3
AI301 (mA)    -0.008
AI302 (mA)    -0.007
AI303 (mA)    -0.001
AI304 (mA)    -0.006

=>

```

Figure 5.11 METER AI Command Report

Demand Metering

The SEL-787 offers the choice between two types of demand metering, settable with the enable setting:

EDEM = THM (Thermal Demand Metering)

or

EDEM = ROL (Rolling Demand Metering)

The relay provides demand (**METER DE** command) and peak demand (**METER PE** command) metering for the winding selected (Winding 1 or Winding 2). *Table 5.7* shows the values reported. *Figure 5.12* provides an example of the **METER DE** (Demand) command report and *Figure 5.13* provides an example of the **METER PE** (Peak Demand) command report. Refer to *Demand Metering on page 4.60* for detailed descriptions and settings selection.

Table 5.7 Demand Values

| Relay Option | Demand/Peak Demand Values |
|--------------|--|
| All | <p>Demand/Peak Demand values of line currents IAW_n, IBW_n, and ICW_n magnitudes (A primary)</p> <p>Demand/Peak Demand Value of IGW_n (residual ground fault current) magnitude (A primary)</p> <p>Demand/peak demand value of negative-sequence current (3I2W_n) magnitude (A primary), where $n = 1$ or 2 depending on the winding selected.</p> |

=>MET DEM <Enter>

```

SEL-787                               Date: 01/23/2008   Time: 13:46:56
TRANSFRMR RELAY                       Time Source: Internal

                                IAD    IBD    ICD    IGD    3I2D
DEMAND (A pri.)    53.9    55.9    54.8    2.1    1.4

LAST RESET = 01/23/2008 13:45:38
=>

```

Figure 5.12 METER DEM Command Report

=>MET P <Enter>

```

SEL-787                               Date: 01/23/2008   Time: 13:47:00
TRANSFRMR RELAY                       Time Source: Internal

                                IAPD    IBPD    ICPD    IGPD    3I2PD
DEMAND (A pri.)    55.8    57.8    56.7    2.1    1.4

LAST RESET = 01/23/2008 13:45:37
=>

```

Figure 5.13 METER P Command Report

Peak demand metering values are stored to nonvolatile memory four times per day and within one minute of the peak demand metering values being reset. Demand metering is stored in volatile memory only, and the data will be lost when power to the relay is removed.

Harmonic Metering

The harmonic metering function in the SEL-787 reports the current and voltage harmonics through the fifth harmonic and the total harmonic distortion percentage (THD %). *Table 5.8* shows the harmonic values reported. *Figure 5.14* provides an example of the **METER H** (Harmonic) command report.

Table 5.8 Measured Harmonic Meter Values

| Relay Option | Harmonic Values |
|----------------------------------|--|
| All | Fundamental magnitude (secondary A) and 2nd, 3rd, 4th, harmonic % values and THD % of line currents IAW1, IBW1, ICW1, IAW2, IBW2, and ICW2 |
| With Neutral Current (IN) option | Fundamental magnitude (secondary A), 2nd, 3rd, 4th, 5th harmonic % values, and THD % of neutral current IN |
| With Voltage Option | Fundamental magnitude (secondary V), 2nd, 3rd, 4th, and 5th harmonic % values and THD % of voltages VAB, VBC, VCA or VAN, VBN, VCN |

```

=>MET H <Enter>

SEL-787                               Date: 01/23/2008   Time: 13:44:27
TRNSFRMR RELAY                       Time Source: Internal

      IAW1  IBW1  ICW1  IAW2  IBW2  ICW2  IN   VAB  VBC  VCA
Fund (sec)  1.0   1.0   1.0   2.0   2.0   2.0  1.2  67.2  66.1  117.7
2nd (%)     0.3   0.4   0.5   0.2   0.3   0.3  0.4   0.0   0.0   0.0
3rd (%)     0.5   0.6   0.6   0.2   0.3   0.2  0.3   0.0   0.0   0.0
4th (%)     0.4   0.4   0.5   0.2   0.2   0.3  0.2   0.0   0.0   0.0
5th (%)     0.6   0.6   0.9   0.3   0.3   0.2  0.4   0.0   0.0   0.0
THD (%)     0.9   1.0   1.2   0.5   0.5   0.5  0.7   0.0   0.0   0.0

=>

```

Figure 5.14 METER H Command Report

Synchrophasor Metering

The **MET PM** serial port ASCII command may be used to view the SEL-787 synchrophasor measurements. There are multiple ways to use the **MET PM** command:

- As a test tool, to verify connections, phase rotation, and scaling
- As an analytical tool, to capture synchrophasor data at an exact time, in order to compare it with similar data captured in other phasor measurement unit(s) at the same time. As a method of periodically gathering synchrophasor data through a communications processor.

The **MET PM** command displays the same set of analog synchrophasor information, regardless of the Global settings PHDATAV, PHDATAI, and PHCURR. The **MET PM** command can function even when no serial ports are sending synchrophasor data. It is unaffected by serial port setting PROTO.

The **MET PM** command will only operate when the SEL-787 is in the IRIG timekeeping mode, as indicated by Relay Word bit TSOK = logical 1. *Table 5.9* below, shows the measured values for the **MET PM** Command. *Figure H.4* in *Appendix H: Synchrophasors*, shows a sample **MET PM** command response. The **MET PM TIME** command can be used to direct the SEL-787 to display the synchrophasor for an exact specified time, in 24-hour format. For example, entering the command **MET PM 14:14:12** will result in a response similar to *Figure H.4*, occurring just after 14:14:12, with the time stamp 14:14:12.000. Refer to *Appendix H: Synchrophasors*, for further details on synchrophasor measurements, settings, C37.118 Protocol etc.

Table 5.9 Synchrophasor Measured Values

| Relay Option | Meter Values |
|---------------------|---|
| All Models | Currents: IAW1, IBW1, ICW1, I1W1 (Winding 1 positive-sequence current) and IAW2, IBW2, ICW2, I1W2 (Winding 2 positive-sequence current), magnitudes (A primary) and phase angles (deg) |
| Digitals | TSOK and SV17–SV32 Relay Word Bit status |
| Analogs | MV29–MV32 Math Variables ^a System Frequency (Hz) = 50 or 60 Hz Rate of change of Frequency = 0 |
| With Voltage Option | Voltage phasors: VAB, VBC, VCA or VAN, VBN, VCN, and V1 (positive-sequence voltage), magnitudes (V or kV) and phase angles (deg) System Frequency (Hz) Rate of change of Frequency (Hz/s) |

^a These data are calculated every 100 ms. Only the data that occurs at the “Top of the Second” will be used for MET PM responses.

Small Signal Cutoff for Metering

The relay applies a threshold to the secondary voltage and current magnitude metering quantities to force a reading to zero when the measurement is near zero. The threshold for fundamental metering current values is $0.01 \cdot \text{INOM A}$ (secondary) and for voltage values is 0.1 V (secondary). The threshold for RMS metering current values is $0.03 \cdot \text{INOM A}$ (secondary) and for voltage values is 0.3 V (secondary).

Load Profiling

The SEL-787 includes a load profiling function. The relay automatically records selected quantities into nonvolatile memory every 5, 10, 15, 30, or 60 minutes, depending on the LDAR load profile report setting (see *Load Profile Settings* on page 4.108). Choose which analog quantities you want to monitor from the analog quantities listed in *Appendix K: Analog Quantities*. Set these quantities into the LDLIST load profile list report setting.

The relay memory can hold data for 6500 time-stamped entries. For example, if you chose to monitor 10 values at a rate of every 15 minutes, you could store 66 days worth of data.

Download the load rate profile data using the serial port **LDP** command described in *LDP Command (Load Profile Report)* on page 7.29. Figure 5.15 shows an example **LDP** serial port command response.

| =>LDP <Enter> | | | | | | | | | |
|----------------|------------|--------------|----------|----------|---------------------------------|----------|----------|----------|--|
| SEL-787 | | | | | Date: 2008/01/17 Time: 18:07:05 | | | | |
| TRNSFRMR RELAY | | | | | Time Source: Internal | | | | |
| # | DATE | TIME | IAW1_MAG | IAW1_ANG | IBW1_MAG | IBW1_ANG | ICW1_MAG | ICW1_ANG | |
| 23 | 2008/01/14 | 16:16:40.992 | 0.099 | 0.000 | 0.225 | -52.125 | 0.344 | -108.435 | |
| 22 | 2008/01/14 | 16:21:40.270 | 124.580 | 0.000 | 124.853 | -119.627 | 123.668 | 120.426 | |
| 21 | 2008/01/14 | 16:26:40.157 | 124.346 | 0.000 | 124.902 | -119.358 | 123.626 | 120.711 | |
| 20 | 2008/01/14 | 16:31:40.019 | 124.309 | 0.000 | 124.886 | -119.598 | 123.973 | 120.577 | |
| 19 | 2008/01/14 | 16:36:40.024 | 124.293 | 0.000 | 124.836 | -119.361 | 123.403 | 120.631 | |
| 18 | 2008/01/14 | 16:41:40.056 | 124.559 | 0.000 | 124.813 | -119.709 | 123.970 | 120.493 | |
| 17 | 2008/01/14 | 16:46:40.275 | 124.249 | 0.000 | 124.774 | -119.646 | 123.907 | 120.574 | |
| 16 | 2008/01/14 | 16:51:40.333 | 124.589 | 0.000 | 124.671 | -119.569 | 123.603 | 120.483 | |
| 15 | 2008/01/14 | 16:56:40.908 | 0.088 | 0.000 | 0.188 | 45.000 | 0.395 | -26.565 | |
| 14 | 2008/01/15 | 17:01:40.934 | 124.293 | 0.000 | 124.842 | -119.504 | 123.485 | 120.619 | |
| 13 | 2008/01/15 | 17:06:40.972 | 124.490 | 0.000 | 124.758 | -119.463 | 123.546 | 120.518 | |
| 12 | 2008/01/15 | 17:11:40.038 | 124.341 | 0.000 | 124.741 | -119.297 | 123.424 | 120.779 | |
| 11 | 2008/01/16 | 17:16:40.045 | 124.320 | 0.000 | 125.130 | -119.517 | 123.630 | 120.623 | |
| 10 | 2008/01/16 | 17:21:40.295 | 124.476 | 0.000 | 124.687 | -119.537 | 123.518 | 120.455 | |
| 9 | 2008/01/16 | 17:26:40.070 | 124.284 | 0.000 | 124.874 | -119.413 | 123.649 | 120.818 | |
| 8 | 2008/01/16 | 17:31:40.168 | 0.129 | 0.000 | 0.182 | 106.928 | 0.210 | 49.399 | |
| 7 | 2008/01/17 | 17:36:40.215 | 124.313 | 0.000 | 125.154 | -119.530 | 123.752 | 120.662 | |
| 6 | 2008/01/17 | 17:41:40.803 | 124.383 | 0.000 | 124.992 | -119.613 | 123.796 | 120.550 | |
| 5 | 2008/01/17 | 17:46:40.282 | 124.446 | 0.000 | 124.799 | -119.464 | 123.600 | 120.444 | |
| 4 | 2008/01/17 | 17:51:40.077 | 124.432 | 0.000 | 124.710 | -119.774 | 123.728 | 120.379 | |
| 3 | 2008/01/17 | 17:56:40.114 | 124.288 | 0.000 | 125.274 | -119.590 | 123.905 | 120.605 | |
| 2 | 2008/01/17 | 18:01:41.047 | 124.392 | 0.000 | 124.730 | -119.483 | 123.404 | 120.576 | |
| 1 | 2008/01/17 | 18:06:41.020 | 0.210 | 0.000 | 0.099 | -8.130 | 0.182 | -57.529 | |
| => | | | | | | | | | |

Figure 5.15 LDP Command Report

Through-Fault Event Monitoring

Figure 5.16 shows a fault that occurs outside the area of unit protection of the transformer. Such through faults can last for several cycles, subjecting the transformer windings to mechanical stress and the transformer winding insulation to thermal stress. Monitor and document this through-fault activity with the through-fault element in the SEL-787. The through-fault element also calculates the cumulative mechanical stress on the transformer windings.

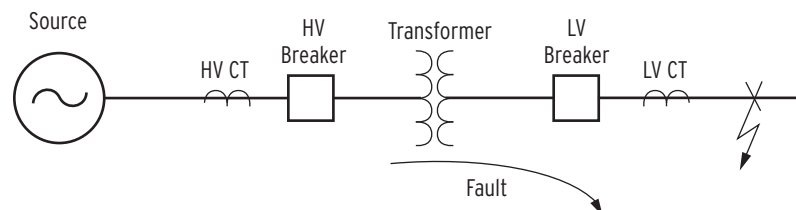


Figure 5.16 Transformer Bank Subjected to Through Fault

Figure 5.17 shows through-fault curves for Category IV transformers as published in IEEE Standard C57.109-1993. These curves apply to transformers that are covered by the IEEE standard or, in general, to transformers that were built beginning in the early 1970s. For transformers built prior to 1970, consult the manufacturer to obtain the transformer short-circuit withstand capabilities.

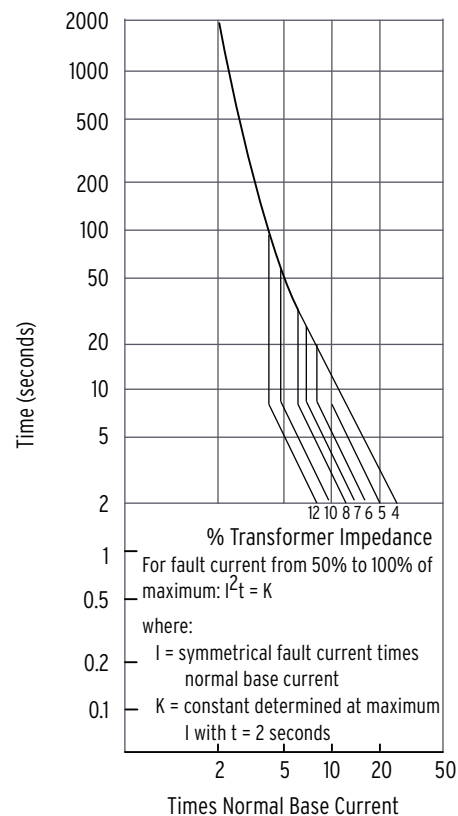


Figure 5.17 Category IV Transformers Through-Fault Protection Curves

The curves in Figure 5.17 are a function of the transformer short-circuit impedance, and is keyed to the maximum I^2t of the worst-case mechanical duty (maximum fault current for 2 seconds). Equation 5.1 through

Equation 5.3 show the three equations that the element uses to evaluate the thermal curve each processing interval. Note that the calculated currents are in primary values. To convert the secondary current to primary current, the element multiplies the secondary current by the CT ratio of the particular winding.

$$I_{PU} = \frac{I \cdot \sqrt{3} \cdot kV_{LL}}{1000 \cdot S}$$

Equation 5.1

$$I_{MAX_PU} = \frac{1}{Z_{PU}}$$

Equation 5.2

$$t(I_{PU}) = \frac{K}{(I_{PU})^2}$$

Equation 5.3

where:

- I = Measured current
- S = Transformer MVA rating (MVA)
- kV_{LL} = Line-to-line voltage (kV)
- Z_{PU} = Transformer impedance (per unit)
- K = 1250 if $(4.5 \leq I_{PU} \leq 0.5 \cdot I_{MAX_PU})$ or
 $2 \cdot (I_{MAX_PU})^2$ if $I_{PU} > 0.5 \cdot I_{MAX_PU}$

There are only four settings to set the through-fault event monitor, all under the Through Fault category in Global Settings (**SET G** command) (see *Table 5.10*). Enable the through fault element by setting the SELOGIC equation ETHRFLT for the conditions that you want the element to run. The default setting for ETHRFLT := NOT TRXFMR disables Through-Fault Monitor for all transformer internal faults (Relay Word Bit TRFXMR := 1). Use Setting THFLTD to select the winding that you want the element to use when calculating the through-fault current. Switch S1 in *Figure 5.18* selects OFF or one of windings 1 or 2. Set the through-fault alarm pickup (THFLTPU) to the desired value, and enter the transformer percentage impedance at the XFMRZ setting.

NOTE: When you change the ETHRFLT setting, the relay also clears the data and records, i.e., it has the same effect as the **TFE C** or **TFE R** command.

Table 5.10 Through-Fault Element Settings

| Setting Prompt | Setting Range | Setting Name := Factory Default |
|------------------|---------------|---------------------------------|
| THR FLT WDG | OFF, 1, 2 | THFLTD := OFF |
| ENABLE THR FLT | SELOGIC | ETHRFLT := NOT TRXFMR |
| THR FLT ALARM PU | 50.0–900.0 % | THFLTPU := 100.0 |
| XFMR IMPEDANCE | 2.0–40.0 % | XFMRZ := 10.0 |

NOTE: The MVA setting must be set to the transformer MVA rating when the THFLTD setting is set to 1 or 2.

On the basis that mechanical stress takes effect only at high current values, the through-fault element runs only if the selected phase current is greater than 4.75 times full load current. Allowing a hysteresis of 0.25 of full load, the through-fault element resets when the current falls below 4.5 times the full load current.

Figure 5.18 shows a functional diagram of the through-fault element for the A-phase of Winding 1 (THFLTD = 1), the B-phase and C-phase elements have identical diagrams. When SELOGIC equation ETHRFLT asserts and the A-phase current exceeds 4.75 times the transformer full-load current, Enable asserts and the 1-minute Timer starts.

When Enable asserts, the following occurs:

- The thermal element advances the A-phase fault counter by 1 count.
- The thermal element advances the total fault counter by 1 count.
- The thermal element records the time when the fault starts (rising edge of Enable).
- The process to determine the maximum through-fault current for the fault duration starts.
- The integration process starts, whereby the element sums the values (*Equation 5.3*) calculated each processing interval (1/4 of a power system cycle).

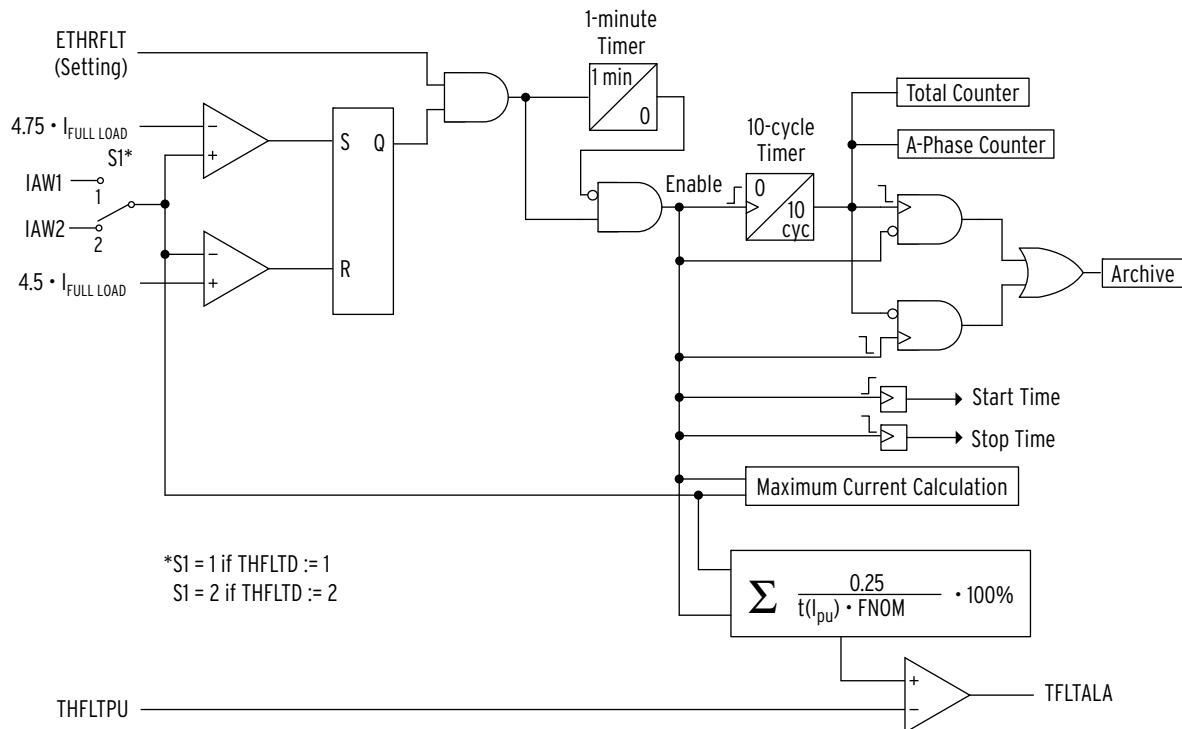


Figure 5.18 Through-Fault Diagram

The 10-cycle Timer avoids the inadvertent increment of the counters or archiving of the data if the fault current momentarily drops below the lower threshold level.

Setting threshold THFLTPU would usually be set to alarm for excessive, cumulative transformer bank stress. When the integration exceeds the value as specified by the THFLTPU setting, Relay Word bit TFLTALA asserts. Assign output Relay Word bit TFLTALA to an output for annunciation or control action such as to modify distribution feeder auto-reclosing (e.g., reduce the number of reclosures from 3 to 2).

When the fault current falls below 4.5 times the full load level, the element deasserts, and the following occurs:

- The thermal element records the stop time; then calculates (and records) the fault duration.
- The thermal element records the maximum value of the fault current during the fault.
- The integration process stops.

The relay can store (archive) the data of 500 through faults in a first-in-first-out (FIFO) buffer. The element automatically archives the data when one of the following conditions is true:

- The 10-cycle Timer deasserts and the enable signal is already de-asserted.
- The 10-cycle Timer is already de-asserted and the enable signal de-asserts.

Through-Fault Element (TFE) Serial Command

The format of the **TFE** command is as follows:

TFE [nnn A|P|C|R]

where:

- nnn Specifies number of through faults to display.
- A The relay displays all the Through Fault Records in the memory.
- P Use to specify pre-loading
- C or R Sets the accumulated values to 0 and deletes the history.

Figure 5.19 displays the relay response to the **TFE** (no other parameters) command. Notice that Winding 1 is the winding whose current inputs the element uses in the calculations (THFLTD = 1). The **TFE** command lists as many as 20 of the most recent through-faults. "Total Number of Transformer Through Faults:" is the sum of the detected through faults of all three phases since the last reset, with a maximum of 65,535 counts. "Number of n Phase Through Faults:" (n = A, B, C) refers to the through faults detected for that particular phase since the last reset, also with a maximum of 65,535 counts. The "Total Accumulated Percentage of Through Fault Capability" shows the per phase value. The value represents the percent amount of through fault capability used up based on the per unitized capability from the curve of *Figure 5.17*. The through-fault alarm state is either a 1 (indicating an alarm state), or a 0 (indicating a normal state).

```

=>>TFE <Enter>

SEL-787                               Date: 04/03/2008   Time: 15:24:02
TRNSFRMR RELAY                       Time Source: Internal

Winding 1
Total Number of Transformer Through Faults: 4
Total Number of A Phase Through Faults:    2
Total Number of B Phase Through Faults:    1
Total Number of C Phase Through Faults:    1

Total Accumulated Percentage of Through Fault Capability:
      A-Phase   B-Phase   C-Phase
      95.97     60.00     60.00
Through Fault Alarm: 0         0         0

Last Reset: 04/03/2008 15:16:27

#   DATE       TIME       Duration   IA   IB   IC   A   B   C   Alarm
      (seconds) (max primary kA) (Increment %)
1   04/03/2008 15:23:37.102 19.983 1.99 0.00 0.00 35.97 0.00 0.00
2   04/03/2008 15:20:23.256 1.663  0.00 0.00 3.28 0.00 0.00 50.94 ABC
3   04/03/2008 15:20:19.918 1.675  0.00 6.37 0.00 0.00 99.99 0.00 AB
4   04/03/2008 15:20:16.596 1.650  1.99 0.00 0.00 2.97 0.00 0.00 A

=>>

```

Figure 5.19 Result of the TFE Command

Following is a description of each column (#, Date, Time, etc.) of the event report. Through-fault events are numbered (# column) from 1 (the most recent event, at the top) to a maximum of 500 through-fault events.

Under the date and time columns, the event shows the date of occurrence and the start time of each event (the date format depends upon the DATE_F setting).

Although the element processes all values each cycle, event duration (Duration column) is reported in seconds with processing interval resolution. If the event duration is equal to or greater than 60 seconds, the element appends a “+” to the time value of 60 seconds.

IA, IB, and IC show the maximum primary current for each phase, with a maximum of 100,000 A primary.

A, B, and C show the amount (percent increase) of the present fault for each phase. Alarm shows those phase(s) that were in the alarm state at the end of the through-fault event.

Table 5.11 shows events report messages and the reason why these messages may appear in the events report.

Table 5.11 Through-Fault Events Report Messages

| Message | Cause |
|---|---|
| Invalid Data | The accumulated data are corrupt. |
| Through Fault Event Monitor Disabled | The ETHRFLT setting is NA, or evaluates to logical 0. |
| Too many events - Data Lost | The memory is full. |
| Through Fault Event Buffer Empty | There are no event records in the nonvolatile memory |
| Memory resources are low; check for activity on other ports | There is insufficient memory to display the event records |

Use the **TFE A** command to list all the stored through-fault events (not only the last 20 events) since the monitor was last reset. To list a particular number of through-fault events, enter the **TFE n** command ($n = 1$ to 500).

To clear event accumulated data, and all event records, use either the **TFE C** (clear) or **TFE R** (reset) command. Both commands have the same result, so you can use either of them. Note that when you change the ETHRFLT setting, the relay also clears the data and records, i.e. it has the same effect as the **TFE C** or **TFE R** command.

Use the **TFE P** command to preload or change the values of the through fault event accumulated data, as shown in *Figure 5.20*. Enter these values in percent for each phase, to a maximum value of 100.0 percent.

```
=>>TFE P
Winding 1 Total Accumulated Percentage of Through Fault Capability:
A_Phase = 0.00? 60.20
B_Phase = 0.00? 56.0
C_Phase = 0.00? 52
Are you sure (Y,N)? Y
Command Completed
=>>
```

Figure 5.20 Preload the Values of the Accumulated Data

Section 6

Settings

Overview

IMPORTANT: Upon relay initial power up or Port 1 setting changes or Logic setting changes, the user may have to wait as long as two minutes before an additional setting change can occur. Note that the relay is functional with protection enabled, as soon as the **ENABLED LED** comes ON (about 5-10 seconds from power up).

The SEL-787 Transformer Protection Relay stores the settings you enter in nonvolatile memory. Settings are divided into the following eight setting classes:

1. Group
2. Logic
3. Global
4. Port p (where $p = F, 1$ [Ethernet], 2, 3, or 4)
5. Front Panel
6. Report
7. Modbus[®]
8. DNP3

Some setting classes have multiple instances. In the above list, there are five port setting instances, one for each port. Settings may be viewed or set in several ways, as shown in *Table 6.1*.

Table 6.1 Methods of Accessing Settings

| | Serial Port Commands ^a | Front Panel HMI Set/Show Menu ^b | ACSELERATOR QuickSet [®] SEL-5030 (PC Software) ^c |
|-------------------------|-----------------------------------|--|---|
| Display Settings | All settings (SHO command) | Global, Group, and Port settings | All settings |
| Change Settings | All settings (SET command) | Global, Group, and Port settings | All settings |

^a Refer to Section 7: Communications for detailed information on set-up and use of the serial communications port.

^b Refer to Section 8: Front-Panel Operations for detailed information on the front-panel layout, menus and screens, and operator control pushbuttons.

^c Refer to Section 3: PC Software for detailed information.

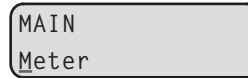
Setting entry error messages, together with corrective actions, are also discussed in this section to assist in correct settings entry.

The *SEL-787 Settings Sheets* at the end of this section list all SEL-787 settings, the setting definitions, and input ranges. Refer to *Section 4: Protection and Logic Functions* for detailed information on individual elements and settings.

View/Change Settings With Front Panel

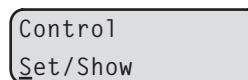
You can use the pushbuttons on the front panel to view/change settings. *Section 8: Front-Panel Operations* presents the operating details of the front panel.

Enter the front-panel menu by pushing the **ESC** pushbutton. It will display the following message:



```
MAIN
Meter
```

Scroll down the menu by using the **Down Arrow** pushbutton until the display shows the following message:



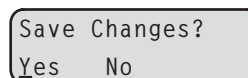
```
Control
Set/Show
```

The cursor (underline) should be on the **Set/Show** command. Enter the **Set/Show** command by pushing the **ENT** pushbutton. The display shows the following message:



```
SET/SHOW
Global
```

Enter the underlined **RELAY** message with the **ENT** pushbutton, and the relay will present you with the **RELAY** settings as listed in the *SEL-787 Settings Sheets*. Use the **Up Arrow**, **Down Arrow**, **Left Arrow**, and **Right Arrow** pushbuttons to scroll through the relay settings. View and change the settings according to your needs by selecting and editing them. After viewing or changing the **RELAY** settings, press the **ESC** pushbutton until the following message appears:



```
Save Changes?
Yes No
```

Select and enter the appropriate command by pushing the **ENT** pushbutton. Select **Yes** to save the settings changes and **No** to discard the changes.

Figure 6.1 shows a front-panel menu navigation example for the relay to enter the **PHASE PT RATIO, PTR** setting.

NOTE: Each SEL-787 is shipped with default factory settings. Calculate the settings for your application to ensure secure and dependable protection. Document the settings on the SEL-787 Settings Sheets at the end of this section before entering new settings in the relay.

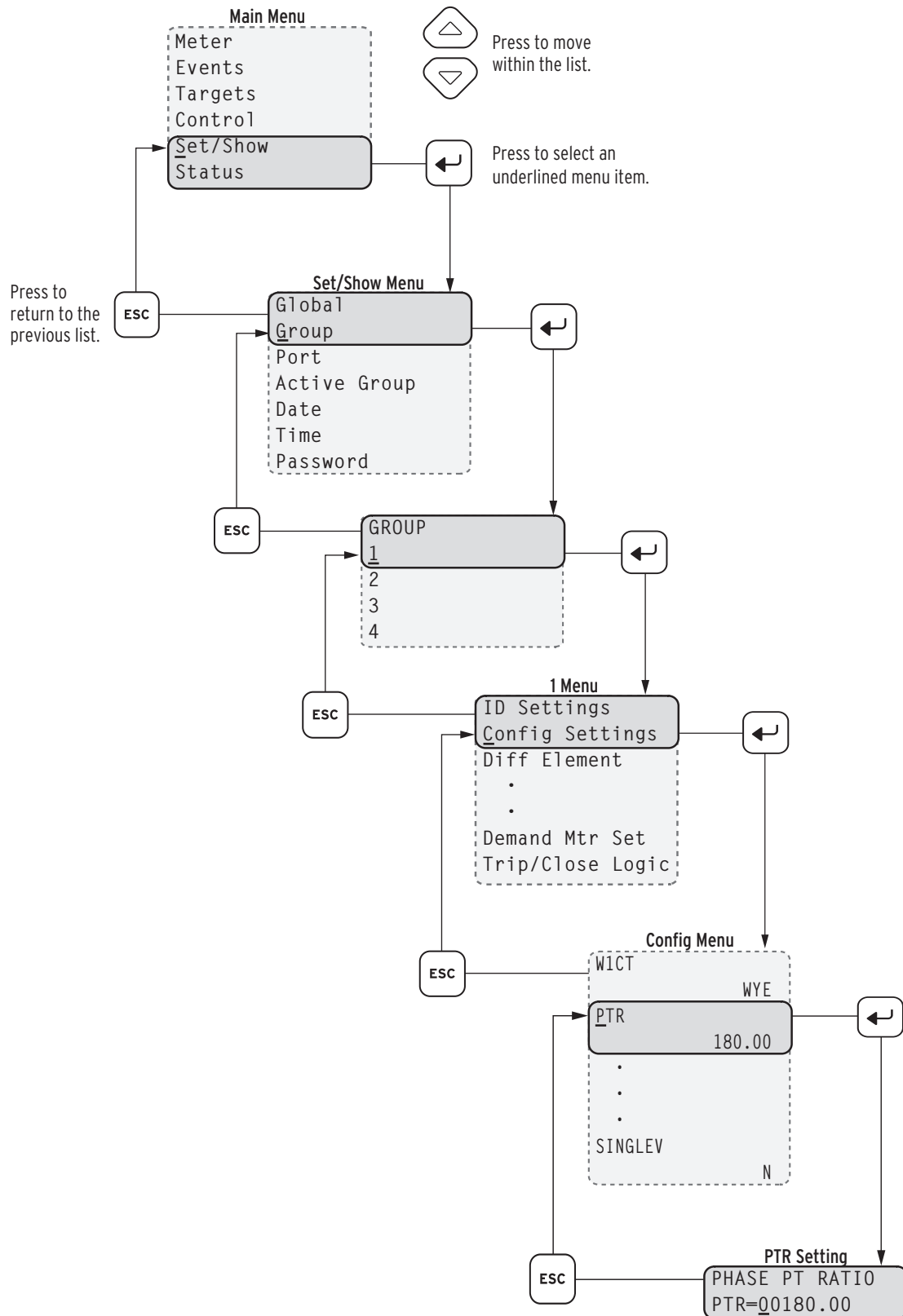


Figure 6.1 Front-Panel Setting Entry Example

View/Change Settings Over Communications Port

Refer to *Section 7: Communications* for information on how to set up and access the relay serial or Ethernet port with a personal computer and how to use ASCII commands to communicate with the relay.

View Settings

Use the **SHOW** command to view relay settings. The **SHOW** command is available from Access Level 1 and Access Level 2. *Table 6.2* lists the **SHOW** command options.

Table 6.2 SHOW Command Options

| Command | Description |
|-----------------------|---|
| SHOW <i>n</i> | Show relay group settings. (<i>n</i> specifies the settings group 1, 2, or 3; <i>n</i> defaults to the active settings group if not listed.) |
| SHO D | Show DNP3 map settings. |
| SHO F | Show front-panel display and LED settings. |
| SHO G | Show global configuration settings. |
| SHO L <i>n</i> | Show logic settings. (<i>n</i> specifies the settings group 1, 2, or 3; <i>n</i> defaults to the active settings group if not listed.) |
| SHO M | Show Modbus map settings. |
| SHO P <i>n</i> | Show serial port settings for Port <i>n</i> (<i>n</i> = F, 1, 2, 3, or 4). |
| SHO R | Show Sequential Event Report (SER) and Event Report settings. |

You may append a setting name to each of the commands to specify the first setting to display (e.g., **SHO 50P11P** displays the relay settings starting with setting **50P11P**). The default is the first setting. The **SHOW** command displays only the enabled settings.

Enter Settings

The **SET** command (available from Access Level 2) allows you to view or change settings. *Table 6.3* lists the **SET** command options.

Table 6.3 SET Command Options

| Command | Settings Type | Description |
|-----------------------|---------------|--|
| SET <i>n</i> | Relay | Protection elements, timers, etc. (<i>n</i> specifies the settings group 1, 2, or 3.) |
| SET D | DNP | DNP3 map settings |
| SET F | Front Panel | Front-panel display and LED settings |
| SET G | Relay | Global configuration settings |
| SET L <i>n</i> | Logic | General logic settings (<i>n</i> specifies the settings group 1, 2, or 3.) |
| SET M | Modbus | Modbus user map |
| SET P <i>n</i> | Port | Serial port settings (<i>n</i> specifies the serial port 1, 2, 3, 4, or F.) |
| SET R | Reports | SER and Event Report settings |

NOTE: The **SET** command is not available as long as 90 seconds after the relay is powered up and as long as 40 seconds after a setting change. If you issue a **SET** command during this period, the relay responds with the following message:

Command Unavailable;
Relay Configuration in
Progress, Try Again.

You may append a setting name to each of the commands to specify the first setting to display (e.g., **SET 50P1P** displays the relay settings starting with setting 50P1P). The default is the first setting.

When you issue the **SET** command, the relay presents a list of settings one at a time. Enter a new setting or press **<Enter>** to accept the existing setting. Editing keystrokes are listed in *Table 6.4*.

Table 6.4 SET Command Editing Keystrokes

| Press Key(s) | Results |
|---------------------------|---|
| <Enter> | Retains the setting and moves to the next setting. |
| ^ <Enter> | Returns to the previous setting. |
| < <Enter> | Returns to the previous setting category. |
| > <Enter> | Moves to the next setting category. |
| END <Enter> | Exits the editing session, then prompts you to save the settings. |
| <Ctrl+X> | Aborts the editing session without saving changes. |

The relay checks each entry to ensure that the entry is within the setting range. If it is not in range, an *Out of Range* message is generated, and the relay prompts you for the setting again.

When all the settings are entered, the relay displays the new settings and prompts you for approval to enable them. Press **Y <Enter>** to enable the new settings. The relay is disabled for as long as five seconds while it saves the new settings. The ALARM Relay Word bit is set momentarily, and the **ENABLED LED** extinguishes while the relay is disabled.

To change a specific setting, enter the command shown in *Table 6.5*.

Table 6.5 SET Command Format

| SET n m s TERSE | |
|------------------------|---|
| where: | |
| <i>m</i> | is left blank or is F, 1, 2, 3, or 4 when <i>n</i> = P. |
| <i>n</i> | is left blank or is D, G, L, F, R, M, or P to identify the class of settings. |
| <i>s</i> | is the name of the specific setting you wish to jump to and begin setting. If <i>s</i> is not entered, the relay starts at the first setting (e.g., enter 50P11P to start at Phase Overcurrent Trip level setting). |
| TERSE | instructs the relay to skip the settings display after the last setting. Use this parameter to speed up the SET command. If you wish to review the settings before saving, do not use the TERSE option. |

Setting Entry Error Messages

As you enter relay settings, the relay checks the setting entered against the range for the setting as published on the relay setting sheet. If any setting entered falls outside the corresponding range for that setting, the relay immediately responds *Out of Range* and prompts you to reenter the setting.

In addition to the immediate range check, several of the settings have interdependency checks with other settings. The relay checks setting interdependencies after you answer *Y* to the *Saves Settings?* prompt, but before the settings are stored. If any of these checks fail, the relay issues a self-explanatory error message, and returns you to the settings list for a correction. *Table 6.6* shows the settings interdependency error messages that require some additional explanation and guidance.

Table 6.6 Setting Interdependency Error Messages

| Error Message | Setting/Function | Correct the Condition |
|--|---|---|
| Tap(s) out of range, enter values manually ^a | Group settings, differential element autocalculation of TAP1 and TAP2 | Check: $0.1 \cdot \text{INOM}_n < \text{TAP}_n < 6.2 \cdot \text{INOM}_n$. ($\text{INOM}_n = 5$ or 1 for 5 A and 1 A winding CT based on PARTNO). Should either TAP_n value violate this requirement, adjust the affected TAP_n to satisfy the check ($n = 1$ or 2). |
| Maximum-to-minimum TAP ratio must be ≤ 7.5 ^a | Group settings, differential element autocalculation of TAP1 and TAP2 | Check: $[\text{MAX}(\text{TAP1}/\text{INOM1}, \text{TAP2}/\text{INOM2})/\text{MIN}(\text{TAP1}/\text{INOM1}, \text{TAP2}/\text{INOM2})] \leq 7.5$. Adjust TAP1 or TAP2 setting until the check is satisfied. |
| WnCT, REF1POL Setting Combination Invalid $n = 1$ or 2 | Group settings, REF element | REF Element is only available when setting $\text{WnCT} := \text{WYE}$ ($n = 1$ or 2). |

^a Relay forces MVA := OFF prior to this message.

SEL-787 Settings Sheets

These settings sheets include the definition and input range for each setting in the relay. You can access the settings from the relay front panel and the serial ports.

- Some settings require an optional module (see *Section 4: Protection and Logic Functions* for details).
- Some of the settings ranges may be more restrictive than shown, because of settings interdependency checks performed when new settings are saved (see *Setting Entry Error Messages on page 6.6*).
- The settings are not case sensitive.

Group Settings (SET Command)

Identifier

| | | |
|--------------------------------|------------|----------|
| UNIT ID LINE 1 (16 Characters) | RID | := _____ |
| UNIT ID LINE 2 (16 Characters) | TID | := _____ |

Configuration

| | | |
|---|----------------|----------|
| WDG1 CT CONN (DELTA, WYE) | W1CT | := _____ |
| WDG2 CT CONN (DELTA, WYE) | W2CT | := _____ |
| WDG1 PHASE CTR (1–10000 {5 A IW1NOM}; 1–50000 {1 A IW1NOM}) | CTR1 | := _____ |
| WDG2 PHASE CTR (1–10000 {5 A IW2NOM}; 1–50000 {1 A IW2NOM}) | CTR2 | := _____ |
| MAX XFMR CAP (OFF, 0.2–5000.0 MVA) | MVA | := _____ |
| DEFINE CT COMP (Y, N) | ICOM | := _____ |
| WDG1 CT COMP (0–12) (<i>Hidden if ICOM := N</i>) | W1CTC | := _____ |
| WDG2 CT COMP (0–12) (<i>Hidden if ICOM := N</i>) | W2CTC | := _____ |
| WDG1 L-L VOLTS (0.20–1000.00 kV) (<i>Hidden if MVA := OFF</i>) | VWDG1 | := _____ |
| WDG2 L-L VOLTS (0.20–1000.00 kV) (<i>Hidden if MVA := OFF</i>) | VWDG2 | := _____ |
| NEUT 1 CT RATIO (1–10000 {5 A InNOM}; 1–50000 {1 A InNOM}) (<i>Hidden if neutral CT not included</i>) | CTRN1 | := _____ |
| PHASE PT RATIO (1.00–10000.00) (<i>Hidden if voltages not included</i>) | PTR | := _____ |
| NOMINAL VOLTAGE (0.20–1000.00 kV) (<i>Hidden if voltages not included</i>) | VNOM | := _____ |
| PT CONNECTION (DELTA, WYE) (<i>Hidden if voltages not included</i>) | DELTA_Y | := _____ |
| VOLT-CURR WDG (1, 2) (<i>Hidden if voltages not included</i>) | VIWDG | := _____ |
| COMP ANGLE (0–360 Deg) (<i>Hidden if voltages not included, or if W1CT := Wye and VIWDG := 1, or if W2CT := Wye and VIWDG := 2</i>) | COMPANG | := _____ |
| SINGLE V INPUT (Y, N) (<i>Hidden if voltages not included</i>) | SINGLEV | := _____ |

Differential

| | | |
|---|--------------|----------|
| XFMR DIFF ENABLE (Y, N) <i>(All Differential settings below are hidden if E87 := N)</i> | E87 | := _____ |
| Note: TAP1 and TAP2 are autoreset by relay if MVA setting is not OFF. | | |
| WDG1 CURR TAP (0.1–6.2 A [1 A nom.], 0.5–31.0 A [5 A nom.]) | TAP1 | := _____ |
| WDG2 CURR TAP (0.1–6.2 A [1 A nom.], 0.5–31.0 A [5 A nom.]) | TAP2 | := _____ |
| OPERATE CURR LVL (0.10–1.00 TAP) | O87P | := _____ |
| DIFF CURR AL LVL (OFF, 0.05–1.00 TAP) | 87AP | := _____ |
| DIFF CURR AL DLY (1.0–120.0 sec.) <i>(Hidden if 87AP := OFF)</i> | 87AD | := _____ |
| RESTRAINT SLOPE1 (5–90 %) | SLP1 | := _____ |
| RESTRAINT SLOPE2 (5–90 %) | SLP2 | := _____ |
| RES SLOPE1 LIMIT (1.0–20.0 TAP) | IRS1 | := _____ |
| UNRES CURR LVL (1.0–20.0 TAP) | U87P | := _____ |
| 2ND HARM BLOCK (OFF, 5–100 %) | PCT2 | := _____ |
| 4TH HARM BLOCK (OFF, 5–100 %) | PCT4 | := _____ |
| 5TH HARM BLOCK (OFF, 5–100 %) | PCT5 | := _____ |
| 5TH HARM AL LVL (OFF, 0.02–3.20 TAP) | TH5P | := _____ |
| 5TH HARM AL DLY (0.0–120.0 s) <i>(Hidden if TH5P := OFF)</i> | TH5D | := _____ |
| HARMONIC RESTRNT (Y, N) | HRSTR | := _____ |
| HARMONIC BLOCK (Y, N) | HBLK | := _____ |

Restricted Earth Fault *(Hidden if neutral CT is not included.)*

| | | |
|----------------------------------|-----------------|----------|
| POL QTY FROM WDG (OFF, 1, 2, 12) | REF1POL | := _____ |
| REF1 TRQ CTRL (SELOGIC) | REF1TC | := _____ |
| REF1 CURR LEVEL (0.05–3.00 pu) | 50REF1P | := _____ |
| 52A BYPASS ENABL (Y, N) | REF52BYP | := _____ |

Winding 1 Maximum Phase Overcurrent

| | | |
|--|----------------|----------|
| PHASE IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50P11P | := _____ |
| PHASE IOC DELAY (0.00–5.00 sec) <i>(Hidden if 50P11P := OFF)</i> | 50P11D | := _____ |
| PH IOC TRQCTRL (SELOGIC) <i>(Hidden if 50P11P := OFF)</i> | 50P11TC | := _____ |
| PHASE IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50P12P | := _____ |
| PHASE IOC DELAY (0.00–5.00 sec) <i>(Hidden if 50P12P := OFF)</i> | 50P12D | := _____ |
| PH IOC TRQCTRL (SELOGIC) <i>(Hidden if 50P12P := OFF)</i> | 50P12TC | := _____ |
| PHASE IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50P13P | := _____ |

| | | |
|--|----------------|----------|
| PHASE IOC DELAY (0.00–5.00 sec) (Hidden if 50P13P := OFF) | 50P13D | := _____ |
| PH IOC TRQCTRL (SELOGIC) (Hidden if 50P13P := OFF) | 50P13TC | := _____ |
| PHASE IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50P14P | := _____ |
| PHASE IOC DELAY (0.00–5.00 sec) (Hidden if 50P14P := OFF) | 50P14D | := _____ |
| PH IOC TRQCTRL (SELOGIC) (Hidden if 50P14P := OFF) | 50P14TC | := _____ |

Winding 1 Residual Overcurrent

(All settings below are hidden when WICT := DELTA.)

| | | |
|--|----------------|----------|
| RES IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50G11P | := _____ |
| RES IOC DELAY (0.00–5.00 sec) (Hidden if 50G11P := OFF) | 50G11D | := _____ |
| RES IOC TRQCTRL (SELOGIC) (Hidden if 50G11P := OFF) | 50G11TC | := _____ |
| RES IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50G12P | := _____ |
| RES IOC DELAY (0.00–5.00 sec) (Hidden if 50G12P := OFF) | 50G12D | := _____ |
| RES IOC TRQCTRL (SELOGIC) (Hidden if 50G12P := OFF) | 50G12TC | := _____ |

Winding 1 Negative-Sequence Overcurrent

| | | |
|---|----------------|----------|
| NSEQ IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50Q11P | := _____ |
| NSEQ IOC DELAY (0.00–5.00 sec) (Hidden if 50Q11P := OFF) | 50Q11D | := _____ |
| NSEQ IOC TRQCTRL (SELOGIC) (Hidden if 50Q11P := OFF) | 50Q11TC | := _____ |
| NSEQ IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50Q12P | := _____ |
| NSEQ IOC DELAY (0.00–5.00 sec) (Hidden if 50Q12P := OFF) | 50Q12D | := _____ |
| NSEQ IOC TRQCTRL (SELOGIC) (Hidden if 50Q12P := OFF) | 50Q12TC | := _____ |

Winding 1 Maximum Phase Time Overcurrent

| | | |
|---|---------------|----------|
| PHASE TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.]) | 51P1P | := _____ |
| PHASE TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) (Hidden if 51P1P := OFF) | 51P1C | := _____ |
| PHASE TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) (Hidden if 51P1P := OFF) | 51P1TD | := _____ |
| EM RESET DELAY (Y, N) (Hidden if 51P1P := OFF) | 51P1RS | := _____ |
| CONST TIME ADDER (0.00–1.00 sec) (Hidden if 51P1P := OFF) | 51P1CT | := _____ |
| MIN RESPONSE TIM (0.00–1.00 sec) (Hidden if 51P1P := OFF) | 51P1MR | := _____ |
| PH TOC TRQCTRL (SELOGIC) (Hidden if 51P1P := OFF) | 51P1TC | := _____ |

Winding 1 Phase A Time Overcurrent

| | | |
|---|----------------|----------|
| PHASE TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.] | 51P1AP | := _____ |
| PHASE TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) <i>(Hidden if 51P1AP := OFF)</i> | 51P1AC | := _____ |
| PHASE TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) <i>(Hidden if 51P1AP := OFF)</i> | 51P1ATD | := _____ |
| EM RESET DELAY (Y, N) <i>(Hidden if 51P1AP := OFF)</i> | 51P1ARS | := _____ |
| CONST TIME ADDER (0.00–1.00 sec) <i>(Hidden if 51P1AP := OFF)</i> | 51P1ACT | := _____ |
| MIN RESPONSE TIM (0.00–1.00 sec) <i>(Hidden if 51P1AP := OFF)</i> | 51P1AMR | := _____ |
| PH TOC TRQCTRL (SELOGIC) <i>(Hidden if 51P1AP := OFF)</i> | 51P1ATC | := _____ |

Winding 1 Phase B Time Overcurrent

| | | |
|---|----------------|----------|
| PHASE TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.] | 51P1BP | := _____ |
| PHASE TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) <i>(Hidden if 51P1BP := OFF)</i> | 51P1BC | := _____ |
| PHASE TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) <i>(Hidden if 51P1BP := OFF)</i> | 51P1BTD | := _____ |
| EM RESET DELAY (Y, N) <i>(Hidden if 51P1BP := OFF)</i> | 51P1BRS | := _____ |
| CONST TIME ADDER (0.00–1.00 sec) <i>(Hidden if 51P1BP := OFF)</i> | 51P1BCT | := _____ |
| MIN RESPONSE TIM (0.00–1.00 sec) <i>(Hidden if 51P1BP := OFF)</i> | 51P1BMR | := _____ |
| PH TOC TRQCTRL (SELOGIC) <i>(Hidden if 51P1BP := OFF)</i> | 51P1BTC | := _____ |

Winding 1 Phase C Time Overcurrent

| | | |
|---|----------------|----------|
| PHASE TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.] | 51P1CP | := _____ |
| PHASE TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) <i>(Hidden if 51P1CP := OFF)</i> | 51P1CC | := _____ |
| PHASE TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) <i>(Hidden if 51P1CP := OFF)</i> | 51P1CTD | := _____ |
| EM RESET DELAY (Y, N) <i>(Hidden if 51P1CP := OFF)</i> | 51P1CRS | := _____ |
| CONST TIME ADDER (0.00–1.00 sec) <i>(Hidden if 51P1CP := OFF)</i> | 51P1CCT | := _____ |
| MIN RESPONSE TIM (0.00–1.00 sec) <i>(Hidden if 51P1CP := OFF)</i> | 51P1CMR | := _____ |
| PH TOC TRQCTRL (SELOGIC) <i>(Hidden if 51P1CP := OFF)</i> | 51P1CTC | := _____ |

Winding 1 Residual Time Overcurrent

All settings below are hidden when W1CT := DELTA.

| | | |
|--|--------------|----------|
| RES TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.] | 51G1P | := _____ |
|--|--------------|----------|

| | | |
|--|---------------|----------|
| RES TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) (Hidden if 51G1P := OFF) | 51G1C | := _____ |
| RES TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) (Hidden if 51G1P := OFF) | 51G1TD | := _____ |
| EM RESET DELAY (Y, N) (Hidden if 51G1P := OFF) | 51G1RS | := _____ |
| CONST TIME ADDER (0.00–1.00 sec) (Hidden if 51G1P := OFF) | 51G1CT | := _____ |
| MIN RESPONSE TIM (0.00–1.00 sec) (Hidden if 51G1P := OFF) | 51G1MR | := _____ |
| RES TOC TRQCTRL (SELOGIC) (Hidden if 51G1P := OFF) | 51G1TC | := _____ |

Winding 1 Negative-Sequence Time Overcurrent

| | | |
|---|---------------|----------|
| NSEQ TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.]) | 51Q1P | := _____ |
| NSEQ TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) (Hidden if 51Q1P := OFF) | 51Q1C | := _____ |
| NSEQ TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) (Hidden if 51Q1P := OFF) | 51Q1TD | := _____ |
| EM RESET DELAY (Y, N) (Hidden if 51Q1P := OFF) | 51Q1RS | := _____ |
| CONST TIME ADDER (0.00–1.00 sec) (Hidden if 51Q1P := OFF) | 51Q1CT | := _____ |
| MIN RESPONSE TIM (0.00–1.00 sec) (Hidden if 51Q1P := OFF) | 51Q1MR | := _____ |
| NSEQ TOC TRQCTRL (SELOGIC) (Hidden if 51Q1P := OFF) | 51Q1TC | := _____ |

Winding 2 Maximum Phase Overcurrent

| | | |
|--|----------------|----------|
| PHASE IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50P21P | := _____ |
| PHASE IOC DELAY (0.00–5.00 sec) (Hidden if 50P21P := OFF) | 50P21D | := _____ |
| PH IOC TRQCTRL (SELOGIC) (Hidden if 50P21P := OFF) | 50P21TC | := _____ |
| PHASE IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50P22P | := _____ |
| PHASE IOC DELAY (0.00–5.00 sec) (Hidden if 50P22P := OFF) | 50P22D | := _____ |
| PH IOC TRQCTRL (SELOGIC) (Hidden if 50P22P := OFF) | 50P22TC | := _____ |
| PHASE IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50P23P | := _____ |
| PHASE IOC DELAY (0.00–5.00 sec) (Hidden if 50P23P := OFF) | 50P23D | := _____ |
| PH IOC TRQCTRL (SELOGIC) (Hidden if 50P23P := OFF) | 50P23TC | := _____ |
| PHASE IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50P24P | := _____ |
| PHASE IOC DELAY (0.00–5.00 sec) (Hidden if 50P24P := OFF) | 50P24D | := _____ |
| PH IOC TRQCTRL (SELOGIC) (Hidden if 50P24P := OFF) | 50P24TC | := _____ |

Winding 2 Residual Overcurrent

All settings below are hidden when W2CT := DELTA.

| | | |
|--|----------------|----------|
| RES IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50G21P | := _____ |
| RES IOC DELAY (0.00–5.00 sec) <i>(Hidden if 50G21P := OFF)</i> | 50G21D | := _____ |
| RES IOC TRQCTRL (SELOGIC) <i>(Hidden if 50G21P := OFF)</i> | 50G21TC | := _____ |
| RES IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50G22P | := _____ |
| RES IOC DELAY (0.00–5.00 sec) <i>(Hidden if 50G22P := OFF)</i> | 50G22D | := _____ |
| RES IOC TRQCTRL (SELOGIC) <i>(Hidden if 50G22P := OFF)</i> | 50G22TC | := _____ |

Winding 2 Negative-Sequence Overcurrent

| | | |
|---|----------------|----------|
| NSEQ IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50Q21P | := _____ |
| NSEQ IOC DELAY (0.00–5.00 sec) <i>(Hidden if 50Q21P := OFF)</i> | 50Q21D | := _____ |
| NSEQ IOC TRQCTRL (SELOGIC) <i>(Hidden if 50Q21P := OFF)</i> | 50Q21TC | := _____ |
| NSEQ IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.]) | 50Q22P | := _____ |
| NSEQ IOC DELAY (0.00–5.00 sec) <i>(Hidden if 50Q22P := OFF)</i> | 50Q22D | := _____ |
| NSEQ IOC TRQCTRL (SELOGIC) <i>(Hidden if 50Q22P := OFF)</i> | 50Q22TC | := _____ |

Winding 2 Maximum Phase Time Overcurrent

| | | |
|--|---------------|----------|
| PHASE TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.]) | 51P2P | := _____ |
| PHASE TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) <i>(Hidden if 51P2P := OFF)</i> | 51P2C | := _____ |
| PHASE TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) <i>(Hidden if 51P2P := OFF)</i> | 51P2TD | := _____ |
| EM RESET DELAY (Y, N) <i>(Hidden if 51P2P := OFF)</i> | 51P2RS | := _____ |
| CONST TIME ADDER (0.00–1.00 sec) <i>(Hidden if 51P2P := OFF)</i> | 51P2CT | := _____ |
| MIN RESPONSE TIM (0.00–1.00 sec) <i>(Hidden if 51P2P := OFF)</i> | 51P2MR | := _____ |
| PH TOC TRQCTRL (SELOGIC) <i>(Hidden if 51P2P := OFF)</i> | 51P2TC | := _____ |

Winding 2 Phase A Time Overcurrent

| | | |
|---|----------------|----------|
| PHASE TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.]) | 51P2AP | := _____ |
| PHASE TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) <i>(Hidden if 51P2AP := OFF)</i> | 51P2AC | := _____ |
| PHASE TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) <i>(Hidden if 51P2AP := OFF)</i> | 51P2ATD | := _____ |
| EM RESET DELAY (Y, N) <i>(Hidden if 51P2AP := OFF)</i> | 51P2ARS | := _____ |

CONST TIME ADDER (0.00–1.00 sec)
(Hidden if 51P2AP := OFF)

51P2ACT := _____

MIN RESPONSE TIM (0.00–1.00 sec)
(Hidden if 51P2AP := OFF)

51P2AMR := _____

PH A TOC TRQCTRL (SELOGIC) (Hidden if 51P2AP := OFF)

51P2ATC := _____

Winding 2 Phase B Time Overcurrent

PHASE TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.],
0.10–3.20 A [1 A nom.])

51P2BP := _____

PHASE TOC CURVE (U1, U2, U3, U4, U5,
C1, C2, C3, C4, C5) (Hidden if 51P2BP := OFF)

51P2BC := _____

PHASE TOC TDIAL (0.50–15.00 for U1–U5 OR
0.05–1.00 for C1–C5) (Hidden if 51P2BP := OFF)

51P2BTD := _____

EM RESET DELAY (Y, N) (Hidden if 51P2BP := OFF)

51P2BRS := _____

CONST TIME ADDER (0.00–1.00 sec)
(Hidden if 51P2BP := OFF)

51P2BCT := _____

MIN RESPONSE TIM (0.00–1.00 sec)
(Hidden if 51P2BP := OFF)

51P2BMR := _____

PH B TOC TRQCTRL (SELOGIC) (Hidden if 51P2BP := OFF)

51P2BTC := _____

Winding 2 Phase C Time Overcurrent

PHASE TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.],
0.10–3.20 A [1 A nom.])

51P2CP := _____

PHASE TOC CURVE (U1, U2, U3, U4, U5,
C1, C2, C3, C4, C5) (Hidden if 51P2CP := OFF)

51P2CC := _____

PHASE TOC TDIAL (0.50–15.00 for U1–U5 OR
0.05–1.00 for C1–C5) (Hidden if 51P2CP := OFF)

51P2CTD := _____

EM RESET DELAY (Y, N) (Hidden if 51P2CP := OFF)

51P2CRS := _____

CONST TIME ADDER (0.00–1.00 sec)
(Hidden if 51P2CP := OFF)

51P2CCT := _____

MIN RESPONSE TIM (0.00–1.00 sec)
(Hidden if 51P2CP := OFF)

51P2CMR := _____

PH C TOC TRQCTRL (SELOGIC) (Hidden if 51P2CP := OFF)

51P2CTC := _____

Winding 2 Residual Time Overcurrent

All settings below are hidden when W2CT := DELTA.

RES TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20
A [1 A nom.])

51G2P := _____

RES TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5)
(Hidden if 51G2P := OFF)

51G2C := _____

RES TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for
C1–C5) (Hidden if 51G2P := OFF)

51G2TD := _____

EM RESET DELAY (Y, N) (Hidden if 51G2P := OFF)

51G2RS := _____

CONST TIME ADDER (0.00–1.00 sec)
(Hidden if 51G2P := OFF)

51G2CT := _____

MIN RESPONSE TIM (0.00–1.00 sec)
(Hidden if 51G2P := OFF)

51G2MR := _____

RES TOC TRQCTRL (SELOGIC) (Hidden if 51G2P := OFF)

51G2TC := _____

Winding 2 Negative-Sequence Time Overcurrent

| | | |
|--|---------------|----------|
| NSEQ TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.] | 51Q2P | := _____ |
| NSEQ TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) (Hidden if 51Q2P := OFF) | 51Q2C | := _____ |
| NSEQ TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) (Hidden if 51Q2P := OFF) | 51Q2TD | := _____ |
| EM RESET DELAY (Y, N) (Hidden if 51Q2P := OFF) | 51Q2RS | := _____ |
| CONST TIME ADDER (0.00–1.00 sec) (Hidden if 51Q2P := OFF) | 51Q2CT | := _____ |
| MIN RESPONSE TIM (0.00–1.00 sec) (Hidden if 51Q2P := OFF) | 51Q2MR | := _____ |
| NSEQ TOC TRQCTRL (SELOGIC) (Hidden if 51Q2P := OFF) | 51Q2TC | := _____ |

Neutral Overcurrent

The following settings are hidden if neutral CT is not included.

| | | |
|--|----------------|----------|
| NEUT IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.] | 50N11P | := _____ |
| NEUT IOC DELAY (0.00–5.00 sec) (Hidden if 50N11P := OFF) | 50N11D | := _____ |
| NEUT IOC TRQCTRL (SELOGIC) (Hidden if 50N11P := OFF) | 50N11TC | := _____ |
| NEUT IOC LEVEL (OFF, 0.50–96.00 A [5 A nom.], 0.10–19.20 A [1 A nom.] | 50N12P | := _____ |
| NEUT IOC DELAY (0.00–5.00 sec) (Hidden if 50N12P := OFF) | 50N12D | := _____ |
| NEUT IOC TRQCTRL (SELOGIC) (Hidden if 50N12P := OFF) | 50N12TC | := _____ |

Neutral Time Overcurrent

The following settings are hidden if neutral CT is not included.

| | | |
|---|---------------|----------|
| NEUT TOC LEVEL (OFF, 0.50–16.00 A [5 A nom.], 0.10–3.20 A [1 A nom.] | 51N1P | := _____ |
| RES TOC CURVE (U1, U2, U3, U4, U5, C1, C2, C3, C4, C5) (Hidden if 51N1P := OFF) | 51N1C | := _____ |
| RES TOC TDIAL (0.50–15.00 for U1–U5 OR 0.05–1.00 for C1–C5) (Hidden if 51N1P := OFF) | 51N1TD | := _____ |
| EM RESET DELAY (Y, N) (Hidden if 51N1P := OFF) | 51N1RS | := _____ |
| CONST TIME ADDER (0.00–1.00 sec) (Hidden if 51N1P := OFF) | 51N1CT | := _____ |
| MIN RESPONSE TIM (0.00–1.00 sec) (Hidden if 51N1P := OFF) | 51N1MR | := _____ |
| RES TOC TRQCTRL (SELOGIC) (Hidden if 51N1P := OFF) | 51N1TC | := _____ |

RTD

| | | |
|--|---------------|----------|
| RTD ENABLE (INT, EXT, NONE) (All RTD settings below hidden if E49RTD := NONE) (INT hidden if Internal RTD card not detected) | E49RTD | := _____ |
|--|---------------|----------|

RTD1 LOCATION (OFF, AMB, OTH)
RTD1 IDENTIFIER (10 characters)
(Hidden if RTD1LOC := OFF or AMB)
RTD1 TYPE (PT100, NI100, NI120, CU10)
(All RTD settings below hidden if E49RTD := NONE)
RTD1 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD1LOC := OFF)
RTD1 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD1LOC := OFF)

RTD1LOC := _____
RTD1NAM := _____
RTD1TY := _____
TRTMP1 := _____
ALTMP1 := _____

RTD2 LOCATION (OFF, AMB, OTH)
RTD2 IDENTIFIER (10 characters)
(Hidden if RTD2LOC := OFF or AMB)
RTD2 TYPE (PT100, NI100, NI120, CU10)
(Hidden if RTD2LOC := OFF)
RTD2 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD2LOC := OFF)
RTD2 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD2LOC := OFF)

RTD2LOC := _____
RTD2NAM := _____
RTD2TY := _____
TRTMP2 := _____
ALTMP2 := _____

RTD3 LOCATION (OFF, AMB, OTH)
RTD3 IDENTIFIER (10 characters)
(Hidden if RTD3LOC := OFF or AMB)
RTD3 TYPE (PT100, NI100, NI120, CU10)
(Hidden if RTD3LOC := OFF)
RTD3 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD3LOC := OFF)
RTD3 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD3LOC := OFF)

RTD3LOC := _____
RTD3NAM := _____
RTD3TY := _____
TRTMP3 := _____
ALTMP3 := _____

RTD4 LOCATION (OFF, AMB, OTH)
RTD4 IDENTIFIER (10 characters)
(Hidden if RTD4LOC := OFF or AMB)
RTD4 TYPE (PT100, NI100, NI120, CU10)
(Hidden if RTD4LOC := OFF)
RTD4 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD4LOC := OFF)
RTD4 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD4LOC := OFF)

RTD4LOC := _____
RTD4NAM := _____
RTD4TY := _____
TRTMP4 := _____
ALTMP4 := _____

RTD5 LOCATION (OFF, AMB, OTH)
RTD5 IDENTIFIER (10 characters)
(Hidden if RTD5LOC := OFF or AMB)
RTD5 TYPE (PT100, NI100, NI120, CU10)
(Hidden if RTD5LOC := OFF)
RTD5 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD5LOC := OFF)
RTD5 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD5LOC := OFF)

RTD5LOC := _____
RTD5NAM := _____
RTD5TY := _____
TRTMP5 := _____
ALTMP5 := _____

RTD6 LOCATION (OFF, AMB, OTH)
 RTD6 IDENTIFIER (10 characters)
(Hidden if RTD6LOC := OFF or AMB)
 RTD6 TYPE (PT100, NI100, NI120, CU10)
(Hidden if RTD6LOC := OFF)
 RTD6 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD6LOC := OFF)
 RTD6 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD6LOC := OFF)

RTD6LOC := _____
RTD6NAM := _____
RTD6TY := _____
TRTMP6 := _____
ALTMP6 := _____

RTD7 LOCATION (OFF, AMB, OTH)
 RTD7 IDENTIFIER (10 characters)
(Hidden if RTD7LOC := OFF or AMB)
 RTD7 TYPE (PT100, NI100, NI120, CU10)
(Hidden if RTD7LOC := OFF)
 RTD7 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD7LOC := OFF)
 RTD7 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD7LOC := OFF)

RTD7LOC := _____
RTD7NAM := _____
RTD7TY := _____
TRTMP7 := _____
ALTMP7 := _____

RTD8 LOCATION (OFF, AMB, OTH)
 RTD8 IDENTIFIER (10 characters)
(Hidden if RTD8LOC := OFF or AMB)
 RTD8 TYPE (PT100, NI100, NI120, CU10)
(Hidden if RTD8LOC := OFF)
 RTD8 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD8LOC := OFF)
 RTD8 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD8LOC := OFF)

RTD8LOC := _____
RTD8NAM := _____
RTD8TY := _____
TRTMP8 := _____
ALTMP8 := _____

RTD9 LOCATION (OFF, AMB, OTH)
 RTD9 IDENTIFIER (10 characters)
(Hidden if RTD9LOC := OFF or AMB)
 RTD9 TYPE (PT100, NI100, NI120, CU10)
(Hidden if RTD9LOC := OFF)
 RTD9 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD9LOC := OFF)
 RTD9 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD9LOC := OFF)

RTD9LOC := _____
RTD9NAM := _____
RTD9TY := _____
TRTMP9 := _____
ALTMP9 := _____

RTD10 LOCATION (OFF, AMB, OTH)
 RTD10 IDENTIFIER (10 characters)
(Hidden if RTD10LOC := OFF or AMB)
 RTD10 TYPE (PT100, NI100, NI120, CU10)
(Hidden if RTD10LOC := OFF)
 RTD10 TRIP LEVEL (OFF, 1–250 degC)
(Hidden if RTD10LOC := OFF)
 RTD10 WARN LEVEL (OFF, 1–250 degC)
(Hidden if RTD10LOC := OFF)

RTD10LOC := _____
RTD10NAM := _____
RTD10TY := _____
TRTMP10 := _____
ALTMP10 := _____

RTD11 LOCATION (OFF, AMB, OTH)

(Hidden if E49RTD := INT)

RTD11 IDENTIFIER (10 characters)

(Hidden if RTD11LOC := OFF or AMB, or E49RTD := INT)

RTD11 TYPE (PT100, NI100, NI120, CU10)

(Hidden if RTD11LOC := OFF or E49RTD := INT)

RTD11 TRIP LEVEL (OFF, 1–250 degC)

(Hidden if RTD11LOC := OFF or E49RTD := INT)

RTD11 WARN LEVEL (OFF, 1–250 degC)

(Hidden if RTD11LOC := OFF or E49RTD := INT)

RTD12 LOCATION (OFF, AMB, OTH)

(Hidden if E49RTD := INT)

RTD12 IDENTIFIER (10 characters)

(Hidden if RTD12LOC := OFF or AMB, or E49RTD := INT)

RTD12 TYPE (PT100, NI100, NI120, CU10)

(Hidden if RTD12LOC := OFF or E49RTD := INT)

RTD12 TRIP LEVEL (OFF, 1–250 degC)

(Hidden if RTD12LOC := OFF or E49RTD := INT)

RTD12 WARN LEVEL (OFF, 1–250 degC)

(Hidden if RTD12LOC := OFF or E49RTD := INT)

RTD11LOC := _____

RTD11NAM := _____

RTD11TY := _____

TRTMP11 := _____

ALTMP11 := _____

RTD12LOC := _____

RTD12NAM := _____

RTD12TY := _____

TRTMP12 := _____

ALTMP12 := _____

Phase Undervoltage *(Hidden if voltages not included.)*

PHASE UV LEVEL (OFF, 12.5–300.0 V)

PHASE UV DELAY (0.0–120.0 sec)

(Hidden if 27P1P := OFF)

PHASE UV LEVEL (OFF, 12.5–300.0 V)

PHASE UV DELAY (0.0–120.0 sec)

(Hidden if 27P2P := OFF)

27P1P := _____

27P1D := _____

27P2P := _____

27P2D := _____

Phase Overvoltage *(Hidden if voltages not included.)*

PHASE OV LEVEL (OFF, 12.5–300.0 V)

PHASE OV DELAY (0.0–120.0 sec)

(Hidden if 59P1P := OFF)

PHASE OV LEVEL (OFF, 12.5–300.0 V)

PHASE OV DELAY (0.0–120.0 sec)

(Hidden if 59P2P := OFF)

59P1P := _____

59P1D := _____

59P2P := _____

59P2D := _____

Negative-Sequence Overvoltage

(Hidden if voltages not included)

NSEQ OV LEVEL (OFF, 12.5–300.0 V)

NSEQ OV DELAY (0.0–120.0 sec) *(Hidden if 59Q1P := OFF)*

NSEQ OV LEVEL (OFF, 12.5–300.0 V)

NSEQ OV DELAY (0.0–120.0 sec) *(Hidden if 59Q2P := OFF)*

59Q1P := _____

59Q1D := _____

59Q2P := _____

59Q2D := _____

Volts/Hertz *(Hidden if voltages not included)*

ENABLE V/HZ PROT (Y, N)

(All V/HZ settings below hidden if E24 := N)

E24 := _____

| | | |
|--|--------|----|
| XFMR WDG CONN (DELTA, WYE) | 24WDG | := |
| LVL1 V/HZ PICKUP (100–200 %) | 24D1P | := |
| LVL1 TIME DLY (0.04–400.00 s) | 24D1D | := |
| LVL2 CURVE SHAPE (OFF, DD, ID, I, U) | 24CCS | := |
| LVL2 INV-TM PU (100–200 %) (Hidden if 24CCS := OFF or DD) | 24IP | := |
| LVL2 INV-TM CURV (0.5, 1.0, 2.0) (Hidden if 24CCS := OFF, DD or U) | 24IC | := |
| LVL2 INV-TM FCTR (0.1–10.0 s) (Hidden if 24CCS := OFF, DD or U) | 24ITD | := |
| LVL2 PICKUP 1 (100–200 %) (Hidden if 24CCS := OFF, ID, I or U) | 24D2P1 | := |
| LVL2 TIME DLY1 (0.04–400.00 s) (Hidden if 24CCS := OFF, ID, I or U) | 24D2D1 | := |
| LVL2 PICKUP 2 (101–200 %) (Hidden if 24CCS := OFF, I or U) | 24D2P2 | := |
| LVL2 TIME DLY2 (0.04–400.00 s) (Hidden if 24CCS := OFF, I or U) | 24D2D2 | := |
| LVL2 RESET TIME (0.00–400.00 s) (Hidden if 24CCS := OFF) | 24CR | := |
| 24ELEM TRQ-CNTRL (SELOGIC) | 24TC | := |

Power *(Hidden if voltages not included)*

| | | |
|---|--------|----|
| ENABLE POWER ELEM (N, 3P1, 3P2) (All Power element settings below hidden if EPWR := N) | EPWR | := |
| 3PH PWR ELEM PU (OFF, 0.2–1300.00 VA (1 A phase CTs), 1.0–6500.0 VA (5 A phase CTs) | 3PWR1P | := |
| PWR ELEM TYPE (+WATTS, -WATTS, +VARS, -VARS) (Hidden if 3PRW1P := OFF) | PWR1T | := |
| PWR ELEM DELAY (0.0–240.0 s) (Hidden if 3PRW1P := OFF) | PWR1D | := |
| 3PH PWR ELEM PU (OFF, 0.2–1300.00 (1 A phase CTs), 1.0–6500.0 VA (5 A phase CTs) (Hidden if EPWR := 3P1) | 3PWR2P | := |
| PWR ELEM TYPE (+WATTS, -WATTS, +VARS, -VARS) (Hidden if 3PRW2P := OFF or if EPWR := 3P1) | PWR2T | := |
| PWR ELEM DELAY (0.0–240.0 s) (Hidden if 3PRW2P := OFF or if EPWR := 3P1) | PWR2D | := |

Frequency *(Hidden if voltages not included)*

| | | |
|---|--------|----|
| FREQ1 TRIP LEVEL (OFF, 20.0–70.0 Hz) | 81D1TP | := |
| FREQ1 TRIP DELAY (0.0–240.0 sec) (Hidden if 81D1TP := OFF) | 81D1TD | := |
| FREQ2 TRIP LEVEL (OFF, 20.0–70.0 Hz) | 81D2TP | := |
| FREQ2 TRIP DELAY (0.0–240.0 sec) (Hidden if 81D2TP := OFF) | 81D2TD | := |
| FREQ3 TRIP LEVEL (OFF, 20.0–70.0 Hz) | 81D3TP | := |
| FREQ3 TRIP DELAY (0.0–240.0 sec) (Hidden if 81D3TP := OFF) | 81D3TD | := |

FREQ4 TRIP LEVEL (OFF, 20.0–70.0 Hz)

81D4TP := _____

FREQ4 TRIP DELAY (0.0–240.0 sec)

81D4TD := _____

(Hidden if 81D4TP := OFF)

Demand Metering

ENABLE DEM MTR (OFF, W1, W2)

EDEM := _____

DEMAND MTR TYPE (THM, ROL)

DEMTY := _____

(Hidden if EDEM := OFF)

DEM TIME CONSTNT (5, 10, 15, 30, 60 min)

DMTC := _____

(Hidden if EDEM := OFF)

PH CURR DEM LVL (OFF, 0.50–16.00 A [5 A nom],
0.10–3.20 A [1 A nom]) *(Hidden if EDEM := OFF)*

PHDEMP := _____

RES CURR DEM LVL (OFF, 0.50–16.00 A [5 A nom],
0.10–3.20 A [1 A nom]) *(Hidden if EDEM := OFF)*

GNDEMP := _____

3I2 CURR DEM LVL (OFF, 0.50–16.00 A [5 A nom],
0.10–3.20 A [1 A nom]) *(Hidden if EDEM := OFF)*

3I2DEMP := _____

Trip/Close Logic

MIN TRIP TIME (0.0–400.0 sec)

TDURD := _____

CLOSE 1 FAIL DLY (0.0–400.0 sec)

CFD1 := _____

CLOSE 2 FAIL DLY (0.0–400.0 sec)

CFD2 := _____

TRIP 1 EQUATION (SELogIC)

TR1 := _____

TRIP 2 EQUATION (SELogIC)

TR2 := _____

TRIP XFMR EQN (SELogIC)

TRXFMR := _____

REMOTE TRIP EQN (SELogIC)

REMTRIP := _____

UNLATCH TRIP 1 (SELogIC)

ULTRIP1 := _____

UNLATCH TRIP 2 (SELogIC)

ULTRIP2 := _____

UNLATCH TRP XFMR (SELogIC)

ULTRXFMR := _____

BREAKER 1 STATUS (SELogIC)

52A1 := _____

CLOSE 1 EQUATION (SELogIC)

CL1 := _____

UNLATCH CLOSE 1 EQUATION (SELogIC)

ULCL1 := _____

BREAKER 2 STATUS (SELogIC)

52A2 := _____

CLOSE 2 EQUATION (SELogIC)

CL2 := _____

UNLATCH CLOSE 2 EQUATION (SELogIC)

ULCL2 := _____

Logic Settings (SET L Command)

SELogic Enables

| | | | |
|----------------------------|------|----|-------|
| SELOGIC LATCHES (N, 1–32) | ELAT | := | _____ |
| SV/TIMERS (N, 1–32) | ESV | := | _____ |
| SELOGIC COUNTERS (N, 1–32) | ESC | := | _____ |
| MATH VARIABLES (N, 1–32) | EMV | := | _____ |

Latch Bits Equations

| | | |
|-------|----|-------|
| SET01 | := | _____ |
| RST01 | := | _____ |
| SET02 | := | _____ |
| RST02 | := | _____ |
| SET03 | := | _____ |
| RST03 | := | _____ |
| SET04 | := | _____ |
| RST04 | := | _____ |
| SET05 | := | _____ |
| RST05 | := | _____ |
| SET06 | := | _____ |
| RST06 | := | _____ |
| SET07 | := | _____ |
| RST07 | := | _____ |
| SET08 | := | _____ |
| RST08 | := | _____ |
| SET09 | := | _____ |
| RST09 | := | _____ |
| SET10 | := | _____ |
| RST10 | := | _____ |
| SET11 | := | _____ |
| RST11 | := | _____ |
| SET12 | := | _____ |
| RST12 | := | _____ |
| SET13 | := | _____ |
| RST13 | := | _____ |
| SET14 | := | _____ |
| RST14 | := | _____ |
| SET15 | := | _____ |

| | | |
|--------------|-----------|-------|
| RST15 | := | _____ |
| SET16 | := | _____ |
| RST16 | := | _____ |
| SET17 | := | _____ |
| RST17 | := | _____ |
| SET18 | := | _____ |
| RST18 | := | _____ |
| SET19 | := | _____ |
| RST19 | := | _____ |
| SET20 | := | _____ |
| RST20 | := | _____ |
| SET21 | := | _____ |
| RST21 | := | _____ |
| SET22 | := | _____ |
| RST22 | := | _____ |
| SET23 | := | _____ |
| RST23 | := | _____ |
| SET24 | := | _____ |
| RST24 | := | _____ |
| SET25 | := | _____ |
| RST25 | := | _____ |
| SET26 | := | _____ |
| RST26 | := | _____ |
| SET27 | := | _____ |
| RST27 | := | _____ |
| SET28 | := | _____ |
| RST28 | := | _____ |
| SET29 | := | _____ |
| RST29 | := | _____ |
| SET30 | := | _____ |
| RST30 | := | _____ |
| SET31 | := | _____ |
| RST31 | := | _____ |
| SET32 | := | _____ |
| RST32 | := | _____ |

SV/Timers

SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)

SV01PU := _____
SV01DO := _____
SV01 := _____
SV02PU := _____
SV02DO := _____
SV02 := _____
SV03PU := _____
SV03DO := _____
SV03 := _____
SV04PU := _____
SV04DO := _____
SV04 := _____
SV05PU := _____
SV05DO := _____
SV05 := _____
SV06PU := _____
SV06DO := _____
SV06 := _____
SV07PU := _____
SV07DO := _____
SV07 := _____
SV08PU := _____
SV08DO := _____
SV08 := _____
SV09PU := _____
SV09DO := _____
SV09 := _____
SV10PU := _____
SV10DO := _____
SV10 := _____
SV11PU := _____
SV11DO := _____
SV11 := _____
SV12PU := _____
SV12DO := _____
SV12 := _____

Date _____
Group _____

SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)

SV13PU := _____
SV13DO := _____
SV13 := _____
SV14PU := _____
SV14DO := _____
SV14 := _____
SV15PU := _____
SV15DO := _____
SV15 := _____
SV16PU := _____
SV16DO := _____
SV16 := _____
SV17PU := _____
SV17DO := _____
SV17 := _____
SV18PU := _____
SV18DO := _____
SV18 := _____
SV19PU := _____
SV19DO := _____
SV19 := _____
SV20PU := _____
SV20DO := _____
SV20 := _____
SV21PU := _____
SV21DO := _____
SV21 := _____
SV22PU := _____
SV22DO := _____
SV22 := _____
SV23PU := _____
SV23DO := _____
SV23 := _____
SV24PU := _____
SV24DO := _____
SV24 := _____
SV25PU := _____

SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)
SV TIMER PICKUP (0.00–3000.00 sec)
SV TIMER DROPOUT (0.00–3000.00 sec)
SV INPUT (SELogIC)

SV25DO := _____
SV25 := _____
SV26PU := _____
SV26DO := _____
SV26 := _____
SV27PU := _____
SV27DO := _____
SV27 := _____
SV28PU := _____
SV28DO := _____
SV28 := _____
SV29PU := _____
SV29DO := _____
SV29 := _____
SV30PU := _____
SV30DO := _____
SV30 := _____
SV31PU := _____
SV31DO := _____
SV31 := _____
SV32PU := _____
SV32DO := _____
SV32 := _____

Counters Equations

SC PRESET VALUE (1–65000)
SC RESET INPUT (SELogIC)
SC LOAD PV INPUT (SELogIC)
SC CNT UP INPUT (SELogIC)
SC CNT DN INPUT (SELogIC)
SC PRESET VALUE (1–65000)
SC RESET INPUT (SELogIC)
SC LOAD PV INPUT (SELogIC)
SC CNT UP INPUT (SELogIC)
SC CNT DN INPUT (SELogIC)
SC PRESET VALUE (1–65000)
SC RESET INPUT (SELogIC)
SC LOAD PV INPUT (SELogIC)

SC01PV := _____
SC01R := _____
SC01LD := _____
SC01CU := _____
SC01CD := _____
SC02PV := _____
SC02R := _____
SC02LD := _____
SC02CU := _____
SC02CD := _____
SC03PV := _____
SC03R := _____
SC03LD := _____

Date _____
Group _____

| | | |
|----------------------------|---------------|-----------|
| SC CNT UP INPUT (SELogiC) | SC03CU | : = _____ |
| SC CNT DN INPUT (SELogiC) | SC03CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC04PV | : = _____ |
| SC RESET INPUT (SELogiC) | SC04R | : = _____ |
| SC LOAD PV INPUT (SELogiC) | SC04LD | : = _____ |
| SC CNT UP INPUT (SELogiC) | SC04CU | : = _____ |
| SC CNT DN INPUT (SELogiC) | SC04CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC05PV | : = _____ |
| SC RESET INPUT (SELogiC) | SC05R | : = _____ |
| SC LOAD PV INPUT (SELogiC) | SC05LD | : = _____ |
| SC CNT UP INPUT (SELogiC) | SC05CU | : = _____ |
| SC CNT DN INPUT (SELogiC) | SC05CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC06PV | : = _____ |
| SC RESET INPUT (SELogiC) | SC06R | : = _____ |
| SC LOAD PV INPUT (SELogiC) | SC06LD | : = _____ |
| SC CNT UP INPUT (SELogiC) | SC06CU | : = _____ |
| SC CNT DN INPUT (SELogiC) | SC06CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC07PV | : = _____ |
| SC RESET INPUT (SELogiC) | SC07R | : = _____ |
| SC LOAD PV INPUT (SELogiC) | SC07LD | : = _____ |
| SC CNT UP INPUT (SELogiC) | SC07CU | : = _____ |
| SC CNT DN INPUT (SELogiC) | SC07CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC08PV | : = _____ |
| SC RESET INPUT (SELogiC) | SC08R | : = _____ |
| SC LOAD PV INPUT (SELogiC) | SC08LD | : = _____ |
| SC CNT UP INPUT (SELogiC) | SC08CU | : = _____ |
| SC CNT DN INPUT (SELogiC) | SC08CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC09PV | : = _____ |
| SC RESET INPUT (SELogiC) | SC09R | : = _____ |
| SC LOAD PV INPUT (SELogiC) | SC09LD | : = _____ |
| SC CNT UP INPUT (SELogiC) | SC09CU | : = _____ |
| SC CNT DN INPUT (SELogiC) | SC09CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC10PV | : = _____ |
| SC RESET INPUT (SELogiC) | SC10R | : = _____ |
| SC LOAD PV INPUT (SELogiC) | SC10LD | : = _____ |
| SC CNT UP INPUT (SELogiC) | SC10CU | : = _____ |
| SC CNT DN INPUT (SELogiC) | SC10CD | : = _____ |

| | | |
|----------------------------|---------------|----------|
| SC PRESET VALUE (1–65000) | SC11PV | := _____ |
| SC RESET INPUT (SELogIC) | SC11R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC11LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC11CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC11CD | := _____ |
| SC PRESET VALUE (1–65000) | SC12PV | := _____ |
| SC RESET INPUT (SELogIC) | SC12R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC12LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC12CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC12CD | := _____ |
| SC PRESET VALUE (1–65000) | SC13PV | := _____ |
| SC RESET INPUT (SELogIC) | SC13R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC13LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC13CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC13CD | := _____ |
| SC PRESET VALUE (1–65000) | SC14PV | := _____ |
| SC RESET INPUT (SELogIC) | SC14R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC14LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC14CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC14CD | := _____ |
| SC PRESET VALUE (1–65000) | SC15PV | := _____ |
| SC RESET INPUT (SELogIC) | SC15R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC15LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC15CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC15CD | := _____ |
| SC PRESET VALUE (1–65000) | SC16PV | := _____ |
| SC RESET INPUT (SELogIC) | SC16R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC16LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC16CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC16CD | := _____ |
| SC PRESET VALUE (1–65000) | SC17PV | := _____ |
| SC RESET INPUT (SELogIC) | SC17R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC17LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC17CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC17CD | := _____ |
| SC PRESET VALUE (1–65000) | SC18PV | := _____ |
| SC RESET INPUT (SELogIC) | SC18R | := _____ |

Date _____
Group _____

| | | |
|----------------------------|---------------|-----------|
| SC LOAD PV INPUT (SELogIC) | SC18LD | : = _____ |
| SC CNT UP INPUT (SELogIC) | SC18CU | : = _____ |
| SC CNT DN INPUT (SELogIC) | SC18CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC19PV | : = _____ |
| SC RESET INPUT (SELogIC) | SC19R | : = _____ |
| SC LOAD PV INPUT (SELogIC) | SC19LD | : = _____ |
| SC CNT UP INPUT (SELogIC) | SC19CU | : = _____ |
| SC CNT DN INPUT (SELogIC) | SC19CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC20PV | : = _____ |
| SC RESET INPUT (SELogIC) | SC20R | : = _____ |
| SC LOAD PV INPUT (SELogIC) | SC20LD | : = _____ |
| SC CNT UP INPUT (SELogIC) | SC20CU | : = _____ |
| SC CNT DN INPUT (SELogIC) | SC20CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC21PV | : = _____ |
| SC RESET INPUT (SELogIC) | SC21R | : = _____ |
| SC LOAD PV INPUT (SELogIC) | SC21LD | : = _____ |
| SC CNT UP INPUT (SELogIC) | SC21CU | : = _____ |
| SC CNT DN INPUT (SELogIC) | SC21CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC22PV | : = _____ |
| SC RESET INPUT (SELogIC) | SC22R | : = _____ |
| SC LOAD PV INPUT (SELogIC) | SC22LD | : = _____ |
| SC CNT UP INPUT (SELogIC) | SC22CU | : = _____ |
| SC CNT DN INPUT (SELogIC) | SC22CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC23PV | : = _____ |
| SC RESET INPUT (SELogIC) | SC23R | : = _____ |
| SC LOAD PV INPUT (SELogIC) | SC23LD | : = _____ |
| SC CNT UP INPUT (SELogIC) | SC23CU | : = _____ |
| SC CNT DN INPUT (SELogIC) | SC23CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC24PV | : = _____ |
| SC RESET INPUT (SELogIC) | SC24R | : = _____ |
| SC LOAD PV INPUT (SELogIC) | SC24LD | : = _____ |
| SC CNT UP INPUT (SELogIC) | SC24CU | : = _____ |
| SC CNT DN INPUT (SELogIC) | SC24CD | : = _____ |
| SC PRESET VALUE (1–65000) | SC25PV | : = _____ |
| SC RESET INPUT (SELogIC) | SC25R | : = _____ |
| SC LOAD PV INPUT (SELogIC) | SC25LD | : = _____ |
| SC CNT UP INPUT (SELogIC) | SC25CU | : = _____ |

| | | |
|----------------------------|---------------|----------|
| SC CNT DN INPUT (SELogIC) | SC25CD | := _____ |
| SC PRESET VALUE (1–65000) | SC26PV | := _____ |
| SC RESET INPUT (SELogIC) | SC26R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC26LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC26CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC26CD | := _____ |
| SC PRESET VALUE (1–65000) | SC27PV | := _____ |
| SC RESET INPUT (SELogIC) | SC27R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC27LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC27CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC27CD | := _____ |
| SC PRESET VALUE (1–65000) | SC28PV | := _____ |
| SC RESET INPUT (SELogIC) | SC28R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC28LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC28CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC28CD | := _____ |
| SC PRESET VALUE (1–65000) | SC29PV | := _____ |
| SC RESET INPUT (SELogIC) | SC29R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC29LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC29CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC29CD | := _____ |
| SC PRESET VALUE (1–65000) | SC30PV | := _____ |
| SC RESET INPUT (SELogIC) | SC30R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC30LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC30CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC30CD | := _____ |
| SC PRESET VALUE (1–65000) | SC31PV | := _____ |
| SC RESET INPUT (SELogIC) | SC31R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC31LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC31CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC31CD | := _____ |
| SC PRESET VALUE (1–65000) | SC32PV | := _____ |
| SC RESET INPUT (SELogIC) | SC32R | := _____ |
| SC LOAD PV INPUT (SELogIC) | SC32LD | := _____ |
| SC CNT UP INPUT (SELogIC) | SC32CU | := _____ |
| SC CNT DN INPUT (SELogIC) | SC32CD | := _____ |

Math Variables

| | | |
|------|----|-------|
| MV01 | := | _____ |
| MV02 | := | _____ |
| MV03 | := | _____ |
| MV04 | := | _____ |
| MV05 | := | _____ |
| MV06 | := | _____ |
| MV07 | := | _____ |
| MV08 | := | _____ |
| MV09 | := | _____ |
| MV10 | := | _____ |
| MV11 | := | _____ |
| MV12 | := | _____ |
| MV13 | := | _____ |
| MV14 | := | _____ |
| MV15 | := | _____ |
| MV16 | := | _____ |
| MV17 | := | _____ |
| MV18 | := | _____ |
| MV19 | := | _____ |
| MV20 | := | _____ |
| MV21 | := | _____ |
| MV22 | := | _____ |
| MV23 | := | _____ |
| MV24 | := | _____ |
| MV25 | := | _____ |
| MV26 | := | _____ |
| MV27 | := | _____ |
| MV28 | := | _____ |
| MV29 | := | _____ |
| MV30 | := | _____ |
| MV31 | := | _____ |
| MV32 | := | _____ |

Base Output

| | |
|-------------------------|-------------|
| OUT101 FAIL-SAFE (Y, N) | OUT101FS := |
| OUT101 := | |
| OUT102 FAIL-SAFE (Y, N) | OUT102FS := |
| OUT102 := | |
| OUT103 FAIL-SAFE (Y, N) | OUT103FS := |
| OUT103 := | |

Slot C Output

| | |
|-------------------------|-------------|
| OUT301 FAIL-SAFE (Y, N) | OUT301FS := |
| OUT301 := | |
| OUT302 FAIL-SAFE (Y, N) | OUT302FS := |
| OUT302 := | |
| OUT303 FAIL-SAFE (Y, N) | OUT303FS := |
| OUT303 := | |
| OUT304 FAIL-SAFE (Y, N) | OUT304FS := |
| OUT304 := | |

Slot D Output

| | |
|-------------------------|-------------|
| OUT401 FAIL-SAFE (Y, N) | OUT401FS := |
| OUT401 := | |
| OUT402 FAIL-SAFE (Y, N) | OUT402FS := |
| OUT402 := | |
| OUT403 FAIL-SAFE (Y, N) | OUT403FS := |
| OUT403 := | |
| OUT404 FAIL-SAFE (Y, N) | OUT404FS := |
| OUT404 := | |

Slot E Output

| | |
|-------------------------|-------------|
| OUT501 FAIL-SAFE (Y, N) | OUT501FS := |
| OUT501 := | |
| OUT502 FAIL-SAFE (Y, N) | OUT502FS := |
| OUT502 := | |
| OUT503 FAIL-SAFE (Y, N) | OUT503FS := |
| OUT503 := | |
| OUT504 FAIL-SAFE (Y, N) | OUT504FS := |
| OUT504 := | |

MIRRORED BITS Transmit SELogic Equations

(Hidden if PROTO is not MBxx on any of the communications ports.)

| | | |
|--------------|-----------|-------|
| TMB1A | := | _____ |
| TMB2A | := | _____ |
| TMB3A | := | _____ |
| TMB4A | := | _____ |
| TMB5A | := | _____ |
| TMB6A | := | _____ |
| TMB7A | := | _____ |
| TMB8A | := | _____ |
| TMB1B | := | _____ |
| TMB2B | := | _____ |
| TMB3B | := | _____ |
| TMB4B | := | _____ |
| TMB5B | := | _____ |
| TMB6B | := | _____ |
| TMB7B | := | _____ |
| TMB8B | := | _____ |

Global Settings (SET G Command)

General

| | | |
|-----------------------------|---------------|----------|
| PHASE ROTATION (ABC, ACB) | PHROT | := _____ |
| RATED FREQ. (50, 60 Hz) | FNOM | := _____ |
| DATE FORMAT (MDY, YMD, DMY) | DATE_F | := _____ |
| FAULT CONDITION (SELogic) | FAULT | := _____ |
| EVE MSG PTS ENABL (N, 1–32) | EMP | := _____ |

Event Messenger Points (Only the points enabled by EMP are visible)

| | | |
|--|---------------|----------|
| MESSENGER POINT MP01 TRIGGER (Off, 1 Relay Word bit) | MPTR01 | := _____ |
| MESSENGER POINT MP01 AQ (None, 1 analog quantity) | MPAQ01 | := _____ |
| MESSENGER POINT MP01 TEXT (148 characters) | MPTX01 | := _____ |
| MESSENGER POINT MP02 TRIGGER (Off, 1 Relay Word bit) | MPTR02 | := _____ |
| MESSENGER POINT MP02 AQ (None, 1 analog quantity) | MPAQ02 | := _____ |
| MESSENGER POINT MP02 TEXT (148 characters) | MPTX02 | := _____ |
| MESSENGER POINT MP03 TRIGGER (Off, 1 Relay Word bit) | MPTR03 | := _____ |
| MESSENGER POINT MP03 AQ (None, 1 analog quantity) | MPAQ03 | := _____ |
| MESSENGER POINT MP03 TEXT (148 characters) | MPTX03 | := _____ |
| MESSENGER POINT MP04 TRIGGER (Off, 1 Relay Word bit) | MPTR04 | := _____ |
| MESSENGER POINT MP04 AQ (None, 1 analog quantity) | MPAQ04 | := _____ |
| MESSENGER POINT MP04 TEXT (148 characters) | MPTX04 | := _____ |
| MESSENGER POINT MP05 TRIGGER (Off, 1 Relay Word bit) | MPTR05 | := _____ |
| MESSENGER POINT MP05 AQ (None, 1 analog quantity) | MPAQ05 | := _____ |
| MESSENGER POINT MP05 TEXT (148 characters) | MPTX05 | := _____ |
| MESSENGER POINT MP06 TRIGGER (Off, 1 Relay Word bit) | MPTR06 | := _____ |
| MESSENGER POINT MP06 AQ (None, 1 analog quantity) | MPAQ06 | := _____ |
| MESSENGER POINT MP06 TEXT (148 characters) | MPTX06 | := _____ |
| MESSENGER POINT MP07 TRIGGER (Off, 1 Relay Word bit) | MPTR07 | := _____ |
| MESSENGER POINT MP07 AQ (None, 1 analog quantity) | MPAQ07 | := _____ |
| MESSENGER POINT MP07 TEXT (148 characters) | MPTX07 | := _____ |
| MESSENGER POINT MP08 TRIGGER (Off, 1 Relay Word bit) | MPTR08 | := _____ |
| MESSENGER POINT MP08 AQ (None, 1 analog quantity) | MPAQ08 | := _____ |
| MESSENGER POINT MP08 TEXT (148 characters) | MPTX08 | := _____ |
| MESSENGER POINT MP09 TRIGGER (Off, 1 Relay Word bit) | MPTR09 | := _____ |
| MESSENGER POINT MP09 AQ (None, 1 analog quantity) | MPAQ09 | := _____ |
| MESSENGER POINT MP09 TEXT (148 characters) | MPTX09 | := _____ |
| MESSENGER POINT MP10 TRIGGER (Off, 1 Relay Word bit) | MPTR10 | := _____ |

| | | |
|--|---------------|-----------|
| MESSENGER POINT MP10 AQ (None, 1 analog quantity) | MPAQ10 | : = _____ |
| MESSENGER POINT MP10 TEXT (148 characters) | MPTX10 | : = _____ |
| MESSENGER POINT MP11 TRIGGER (Off, 1 Relay Word bit) | MPTR11 | : = _____ |
| MESSENGER POINT MP11 AQ (None, 1 analog quantity) | MPAQ11 | : = _____ |
| MESSENGER POINT MP11 TEXT (148 characters) | MPTX11 | : = _____ |
| MESSENGER POINT MP12 TRIGGER (Off, 1 Relay Word bit) | MPTR12 | : = _____ |
| MESSENGER POINT MP12 AQ (None, 1 analog quantity) | MPAQ12 | : = _____ |
| MESSENGER POINT MP12 TEXT (148 characters) | MPTX12 | : = _____ |
| MESSENGER POINT MP13 TRIGGER (Off, 1 Relay Word bit) | MPTR13 | : = _____ |
| MESSENGER POINT MP13 AQ (None, 1 analog quantity) | MPAQ13 | : = _____ |
| MESSENGER POINT MP13 TEXT (148 characters) | MPTX13 | : = _____ |
| MESSENGER POINT MP14 TRIGGER (Off, 1 Relay Word bit) | MPTR14 | : = _____ |
| MESSENGER POINT MP14 AQ (None, 1 analog quantity) | MPAQ14 | : = _____ |
| MESSENGER POINT MP14 TEXT (148 characters) | MPTX14 | : = _____ |
| MESSENGER POINT MP15 TRIGGER (Off, 1 Relay Word bit) | MPTR15 | : = _____ |
| MESSENGER POINT MP15 AQ (None, 1 analog quantity) | MPAQ15 | : = _____ |
| MESSENGER POINT MP15 TEXT (148 characters) | MPTX15 | : = _____ |
| MESSENGER POINT MP16 TRIGGER (Off, 1 Relay Word bit) | MPTR16 | : = _____ |
| MESSENGER POINT MP16 AQ (None, 1 analog quantity) | MPAQ16 | : = _____ |
| MESSENGER POINT MP16 TEXT (148 characters) | MPTX16 | : = _____ |
| MESSENGER POINT MP17 TRIGGER (Off, 1 Relay Word bit) | MPTR17 | : = _____ |
| MESSENGER POINT MP17 AQ (None, 1 analog quantity) | MPAQ17 | : = _____ |
| MESSENGER POINT MP17 TEXT (148 characters) | MPTX17 | : = _____ |
| MESSENGER POINT MP18 TRIGGER (Off, 1 Relay Word bit) | MPTR18 | : = _____ |
| MESSENGER POINT MP18 AQ (None, 1 analog quantity) | MPAQ18 | : = _____ |
| MESSENGER POINT MP18 TEXT (148 characters) | MPTX18 | : = _____ |
| MESSENGER POINT MP19 TRIGGER (Off, 1 Relay Word bit) | MPTR19 | : = _____ |
| MESSENGER POINT MP19 AQ (None, 1 analog quantity) | MPAQ19 | : = _____ |
| MESSENGER POINT MP19 TEXT (148 characters) | MPTX19 | : = _____ |
| MESSENGER POINT MP20 TRIGGER (Off, 1 Relay Word bit) | MPTR20 | : = _____ |
| MESSENGER POINT MP20 AQ (None, 1 analog quantity) | MPAQ20 | : = _____ |
| MESSENGER POINT MP20 TEXT (148 characters) | MPTX20 | : = _____ |
| MESSENGER POINT MP21 TRIGGER (Off, 1 Relay Word bit) | MPTR21 | : = _____ |
| MESSENGER POINT MP21 AQ (None, 1 analog quantity) | MPAQ21 | : = _____ |
| MESSENGER POINT MP21 TEXT (148 characters) | MPTX21 | : = _____ |
| MESSENGER POINT MP22 TRIGGER (Off, 1 Relay Word bit) | MPTR22 | : = _____ |
| MESSENGER POINT MP22 AQ (None, 1 analog quantity) | MPAQ22 | : = _____ |

| | | |
|--|---------------|----------|
| MESSENGER POINT MP22 TEXT (148 characters) | MPTX22 | := _____ |
| MESSENGER POINT MP23 TRIGGER (Off, 1 Relay Word bit) | MPTR23 | := _____ |
| MESSENGER POINT MP23 AQ (None, 1 analog quantity) | MPAQ23 | := _____ |
| MESSENGER POINT MP23 TEXT (148 characters) | MPTX23 | := _____ |
| MESSENGER POINT MP24 TRIGGER (Off, 1 Relay Word bit) | MPTR24 | := _____ |
| MESSENGER POINT MP24 AQ (None, 1 analog quantity) | MPAQ24 | := _____ |
| MESSENGER POINT MP24 TEXT (148 characters) | MPTX24 | := _____ |
| MESSENGER POINT MP25 TRIGGER (Off, 1 Relay Word bit) | MPTR25 | := _____ |
| MESSENGER POINT MP25 AQ (None, 1 analog quantity) | MPAQ25 | := _____ |
| MESSENGER POINT MP25 TEXT (148 characters) | MPTX25 | := _____ |
| MESSENGER POINT MP26 TRIGGER (Off, 1 Relay Word bit) | MPTR26 | := _____ |
| MESSENGER POINT MP26 AQ (None, 1 analog quantity) | MPAQ26 | := _____ |
| MESSENGER POINT MP26 TEXT (148 characters) | MPTX26 | := _____ |
| MESSENGER POINT MP27 TRIGGER (Off, 1 Relay Word bit) | MPTR27 | := _____ |
| MESSENGER POINT MP27 AQ (None, 1 analog quantity) | MPAQ27 | := _____ |
| MESSENGER POINT MP27 TEXT (148 characters) | MPTX27 | := _____ |
| MESSENGER POINT MP28 TRIGGER (Off, 1 Relay Word bit) | MPTR28 | := _____ |
| MESSENGER POINT MP28 AQ (None, 1 analog quantity) | MPAQ28 | := _____ |
| MESSENGER POINT MP28 TEXT (148 characters) | MPTX28 | := _____ |
| MESSENGER POINT MP29 TRIGGER (Off, 1 Relay Word bit) | MPTR29 | := _____ |
| MESSENGER POINT MP29 AQ (None, 1 analog quantity) | MPAQ29 | := _____ |
| MESSENGER POINT MP29 TEXT (148 characters) | MPTX29 | := _____ |
| MESSENGER POINT MP30 TRIGGER (Off, 1 Relay Word bit) | MPTR30 | := _____ |
| MESSENGER POINT MP30 AQ (None, 1 analog quantity) | MPAQ30 | := _____ |
| MESSENGER POINT MP30 TEXT (148 characters) | MPTX30 | := _____ |
| MESSENGER POINT MP31 TRIGGER (Off, 1 Relay Word bit) | MPTR31 | := _____ |
| MESSENGER POINT MP31 AQ (None, 1 analog quantity) | MPAQ31 | := _____ |
| MESSENGER POINT MP31 TEXT (148 characters) | MPTX31 | := _____ |
| MESSENGER POINT MP32 TRIGGER (Off, 1 Relay Word bit) | MPTR32 | := _____ |
| MESSENGER POINT MP32 AQ (None, 1 analog quantity) | MPAQ32 | := _____ |
| MESSENGER POINT MP32 TEXT (148 characters) | MPTX32 | := _____ |

Group Selection

| | | |
|---------------------------|------------|----------|
| GRP CHG DELAY (0–400 sec) | TGR | := _____ |
| SELECT GROUP1 (SELogic) | SS1 | := _____ |
| SELECT GROUP2 (SELogic) | SS2 | := _____ |
| SELECT GROUP3 (SELogic) | SS3 | := _____ |
| SELECT GROUP4 (SELogic) | SS4 | := _____ |

Phasor Measurement (PMU)

EN SYNCHRO PHSOR (Y, N) *(All subsequent PMU settings hidden if EPMU := N)*

MESSAGES PER SEC (1, 2, 5, 10)

STATION NAME (16 characters)

PMU HARDWARE ID (1–65534)

VOLTAGE DATA SET (V1, ALL, NA) *(Hidden if no voltages)*

VOLT COMP ANGLE (-179.99 to 180.00 deg) *(Hidden if PHDATAV := NA)*

CURRENT DATA SET (I1, ALL, NA)

CURRENT SOURCE (IW1, IW2, BOTH) *(Hidden if PHDATAI := NA)*

IW1 COMP ANGLE (-179.99 to 180.00 deg) *(Hidden if PHCURR := IW2 or if PHDATAI := NA)*

IW2 COMP ANGLE (-179.99 to 180.00 deg) *(Hidden if PHCURR := IW1 or if PHDATAI := NA)*

NUM ANALOGS (0–4)

NUM 16BIT DIGITAL (0, 1)

TRIG REASON BIT1 (SELogIC)

TRIG REASON BIT2 (SELogIC)

TRIG REASON BIT3 (SELogIC)

TRIG REASON BIT4 (SELogIC)

TRIGGER ((SELogIC)

EPMU := _____

MRATE := _____

PMSTN := _____

PMID := _____

PHDATAV := _____

VCOMP := _____

PHDATAI := _____

PHCURR := _____

IW1COMP := _____

IW2COMP := _____

NUMANA := _____

NUMDSW := _____

TREA1 := _____

TREA2 := _____

TREA3 := _____

TREA4 := _____

PMTRIG := _____

Time and Date Management

CTRL BITS DEFN (NONE, C37.118)

OFFSET FROM UTC (-24.00 to 24.00) rounded up to quarter

MONTH TO BEGIN DST (OFF, 1–12)

WEEK OF THE MONTH TO BEGIN DST (1–3, L) L = Last week of the month *(Hidden if DST_BEGM := OFF)*

DAY OF THE WEEK TO BEGIN DST (SUN, MON, TUE, WED, THU, FRI, SAT) *(Hidden if DST_BEGM := OFF)*

LOCAL HOUR TO BEGIN DST (0–23) *(Hidden if DST_BEGM := OFF)*

MONTH TO END DST (1–12) *(Hidden if DST_BEGM := OFF)*

WEEK OF THE MONTH TO END DST (1–3, L) L = Last week of the month *(Hidden if DST_BEGM := OFF)*

DAY OF THE WEEK TO END DST (SUN, MON, TUE, WED, THU, FRI, SAT) *(Hidden if DST_BEGM := OFF)*

LOCAL HOUR TO END DST (0–23) *(Hidden if DST_BEGM := OFF)*

IRIGC := _____

UTC_OFF := _____

DST_BEGM := _____

DST_BEGW := _____

DST_BEGD := _____

DST_BEGH := _____

DST_ENDM := _____

DST_ENDW := _____

DST_ENDD := _____

DST_ENDH := _____

Breaker Failure

52A INTERLOCK (Y, N)

52ABF := _____

BRKR1 FAIL DELAY (0.00–2.00 sec)
BRKR1 FAIL INITIATE ((SELOGIC)
BRKR2 FAIL DELAY (0.00–2.00 sec)
BRKR2 FAIL INITIATE ((SELOGIC)

BFD1 := _____
BFI1 := _____
BFD2 := _____
BFI2 := _____

Through Fault

THR FLT WDG (OFF, 1, 2)
ENABLE THR FLT ((SELOGIC)
(Hidden if THFLTD := OFF)
THR FLT ALARM PU (50.0–900.0 %)
(Hidden if THFLTD := OFF)
XFMR IMPEDANCE (2.0–40.0 %)
(Hidden if THFLTD := OFF)

THFLTD := _____
ETHRFLT := _____
THFLTPU := _____
XFMRZ := _____

Analog Inputs

For the following settings, x is the card position (3, 4, or 5 in Slot C, D, and E, respectively).

AIx01

AIx01 TAG NAME (8 characters 0–9, A–Z, _)
AIx01 TYPE (I, V)
If AIx01TYP = I
AIx01 LOW IN VAL (–20.480 to +20.480; mA)
AIx01 HI IN VAL (–20.480 to +20.480; mA)
If AIx01TYP = V
AIx01 LOW IN VAL (–10.240 to +10.240 V)
AIx01 HI IN VAL (–10.240 to +10.240 V)

AIx01NAM := _____
AIx01TYP := _____
AIx01L := _____
AIx01H := _____
AIx01L := _____
AIx01H := _____

NOTE: Set Warn and Alarm to a value between Engr Low and Engr High settings.

AIx01 ENG UNITS (16 characters)
AIx01 EU LOW (–99999.000 to +99999.000)
AIx01 EU HI (–99999.000 to +99999.000)
AIx01 LO WARN L1 (OFF, –99999.000 to +99999.000)
AIx01 LO WARN L2 (OFF, –99999.000 to +99999.000)
AIx01 LO ALARM (OFF, –99999.000 to +99999.000)
AIx01 HI WARN L1 (OFF, –99999.000 to +99999.000)
AIx01 HI WARN L2 (OFF, –99999.000 to +99999.000)
AIx01 HI ALARM (OFF, –99999.000 to +99999.000)

AIx01EU := _____
AIx01EL := _____
AIx01EH := _____
AIx01LW1 := _____
AIx01LW2 := _____
AIx01LAL := _____
AIx01HW1 := _____
AIx01HW2 := _____
AIx01HAL := _____

AIx02

AIx02 TAG NAME (8 characters 0–9, A–Z, _)
AIx02 TYPE (I, V)

AIx02NAM := _____
AIx02TYP := _____

If ALx02TYP = I

ALx02 LOW IN VAL (−20.480 to +20.480; mA)

ALr02L := _____

ALx02 HI IN VAL (−20.480 to +20.480; mA)

ALr02H := _____

If ALx02TYP = V

ALx02 LOW IN VAL (−10.240 to +10.240 V)

ALr02L := _____

ALx02 HI IN VAL (−10.240 to +10.240 V)

ALr02H := _____

ALx02 ENG UNITS (16 characters)

ALr02EU := _____

ALx02 EU LOW (−99999.000 to +99999.000)

ALr02EL := _____

ALx02 EU HI (−99999.000 to +99999.000)

ALr02EH := _____

ALx02 LO WARN L1 (OFF, −99999.000 to +99999.000)

ALr02LW1 := _____

ALx02 LO WARN L2 (OFF, −99999.000 to +99999.000)

ALr02LW2 := _____

ALx02 LO ALARM (OFF, −99999.000 to +99999.000)

ALr02LAL := _____

ALx02 HI WARN L1 (OFF, −99999.000 to +99999.000)

ALr02HW1 := _____

ALx02 HI WARN L2 (OFF, −99999.000 to +99999.000)

ALr02HW2 := _____

ALx02 HI ALARM (OFF, −99999.000 to +99999.000)

ALr02HAL := _____

ALx03

ALx03 TAG NAME (8 characters 0–9, A–Z, _)

ALr03NAM := _____

ALx03 TYPE (I, V)

ALr03TYP := _____

If ALx03TYP = I

ALx03 LOW IN VAL (−20.480 to +20.480; mA)

ALr03L := _____

ALx03 HI IN VAL (−20.480 to +20.480; mA)

ALr03H := _____

If ALx03TYP = V

ALx03 LOW IN VAL (−10.240 to +10.240 V)

ALr03L := _____

ALx03 HI IN VAL (−10.240 to +10.240 V)

ALr03H := _____

ALx03 ENG UNITS (16 characters)

ALr03EU := _____

ALx03 EU LOW (−99999.000 to +99999.000)

ALr03EL := _____

ALx03 EU HI (−99999.000 to +99999.000)

ALr03EH := _____

ALx03 LO WARN L1 (OFF, −99999.000 to +99999.000)

ALr03LW1 := _____

ALx03 LO WARN L2 (OFF, −99999.000 to +99999.000)

ALr03LW2 := _____

ALx03 LO ALARM (OFF, −99999.000 to +99999.000)

ALr03LAL := _____

ALx03 HI WARN L1 (OFF, −99999.000 to +99999.000)

ALr03HW1 := _____

ALx03 HI WARN L2 (OFF, −99999.000 to +99999.000)

ALr03HW2 := _____

ALx03 HI ALARM (OFF, −99999.000 to +99999.000)

ALr03HAL := _____

ALx04

ALx04 TAG NAME (8 characters 0–9, A–Z, _)

ALr04NAM := _____

ALx04 TYPE (I, V)

ALr04TYP := _____

If ALx04TYP = I

ALx04 LOW IN VAL (−20.480 to +20.480; mA)

ALr04L := _____

ALx04 HI IN VAL (–20.480 to +20.480; mA)
If ALx04TYP = V
ALx04 LOW IN VAL (–10.240 to +10.240 V)
ALx04 HI IN VAL (–10.240 to +10.240 V)
ALx04 ENG UNITS (16 characters)
ALx04 EU LOW (–99999.000 to +99999.000)
ALx04 EU HI (–99999.000 to +99999.000)
ALx04 LO WARN L1 (OFF, –99999.000 to +99999.000)
ALx04 LO WARN L2 (OFF, –99999.000 to +99999.000)
ALx04 LO ALARM (OFF, –99999.000 to +99999.000)
ALx04 HI WARN L1 (OFF, –99999.000 to +99999.000)
ALx04 HI WARN L2 (OFF, –99999.000 to +99999.000)
ALx04 HI ALARM (OFF, –99999.000 to +99999.000)

ALx04H := _____
ALx04L := _____
ALx04H := _____
ALx04EU := _____
ALx04EL := _____
ALx04EH := _____
ALx04LW1 := _____
ALx04LW2 := _____
ALx04LAL := _____
ALx04HW1 := _____
ALx04HW2 := _____
ALx04HAL := _____

Analog Outputs

For the following settings, x is the card position (3, 4, or 5 in Slot C, D, and E, respectively).

AOx01

AOx01 ANALOG QTY (Off, 1 analog quantity)
AOx01 TYPE (I, V)
AOx01 AQTY LOW (–2147483647 to +2147483647)
AOx01 AQTY HI (–2147483647 to +2147483647)
If AOx01TYP = I
AOx01 LO OUT VAL (–20.480 to +20.480 mA)
AOx01 HI OUT VAL (–20.480 to +20.480 mA)
If AOx01TYP = V
AOx01 LO OUT VAL (–10.240 to +10.240 V)
AOx01 HI OUT VAL (–10.240 to +10.240 V)

AOx01AQ := _____
AOx01TYP := _____
AOx01AQL := _____
AOx01AQH := _____
AOx01L := _____
AOx01H := _____
AOx01L := _____
AOx01H := _____

AOx02

AOx02 ANALOG QTY (Off, 1 analog quantity)
AOx02 TYPE (I, V)
AOx02 AQTY LOW (–2147483647 to +2147483647)
AOx02 AQTY HI (–2147483647 to +2147483647)
If AOx02TYP = I
AOx02 LO OUT VAL (–20.480 to +20.480 mA)
AOx02 HI OUT VAL (–20.480 to +20.480 mA)
If AOx02TYP = V
AOx02 LO OUT VAL (–10.240 to +10.240 V)
AOx02 HI OUT VAL (–10.240 to +10.240 V)

AOx02AQ := _____
AOx02TYP := _____
AOx02AQL := _____
AOx02AQH := _____
AOx02L := _____
AOx02H := _____
AOx02L := _____
AOx02H := _____

AOx03

AOx03 ANALOG QTY (Off, 1 analog quantity)
AOx03 TYPE (I, V)
AOx03 AQTY LOW (−2147483647 to +2147483647)
AOx03 AQTY HI (−2147483647 to +2147483647)
If AOx03TYP = I
 AOx03 LO OUT VAL (−20.480 to +20.480 mA)
 AOx03 HI OUT VAL (−20.480 to +20.480 mA)
If AOx03TYP = V
 AOx03 LO OUT VAL (−10.240 to +10.240 V)
 AOx03 HI OUT VAL (−10.240 to +10.240 V)

AOx03AQ := _____
AOx03TYP := _____
AOx03AQL := _____
AOx03AQH := _____

AOx03L := _____
AOx03H := _____

AOx03L := _____
AOx03H := _____

AOx04

AOx04 ANALOG QTY (Off, 1 analog quantity)
AOx04 TYPE (I, V)
AOx04 AQTY LOW (−2147483647 to +2147483647)
AOx04 AQTY HI (−2147483647 to +2147483647)
If AOx04TYP = I
 AOx04 LO OUT VAL (−20.480 to +20.480 mA)
 AOx04 HI OUT VAL (−20.480 to +20.480 mA)
If AOx04TYP = V
 AOx04 LO OUT VAL (−10.240 to +10.240 V)
 AOx04 HI OUT VAL (−10.240 to +10.240 V)

AOx04AQ := _____
AOx04TYP := _____
AOx04AQL := _____
AOx04AQH := _____

AOx04L := _____
AOx04H := _____

AOx04L := _____
AOx04H := _____

Input Debounce Settings (Base Unit)

IN101 Debounce (AC, 0–65000 ms)
IN102 Debounce (AC, 0–65000 ms)

IN101D := _____
IN102D := _____

Input Debounce Settings (Slot C)

IN301 Debounce (AC, 0–65000 ms)
IN302 Debounce (AC, 0–65000 ms)
IN303 Debounce (AC, 0–65000 ms)
IN304 Debounce (AC, 0–65000 ms)
IN305 Debounce (AC, 0–65000 ms)
IN306 Debounce (AC, 0–65000 ms)
IN307 Debounce (AC, 0–65000 ms)
IN308 Debounce (AC, 0–65000 ms)

IN301D := _____
IN302D := _____
IN303D := _____
IN304D := _____
IN305D := _____
IN306D := _____
IN307D := _____
IN308D := _____

Input Debounce Settings (Slot D)

IN401 Debounce (AC, 0–65000 ms)
IN402 Debounce (AC, 0–65000 ms)
IN403 Debounce (AC, 0–65000 ms)
IN404 Debounce (AC, 0–65000 ms)
IN405 Debounce (AC, 0–65000 ms)
IN406 Debounce (AC, 0–65000 ms)
IN407 Debounce (AC, 0–65000 ms)
IN408 Debounce (AC, 0–65000 ms)

IN401D := _____
IN402D := _____
IN403D := _____
IN404D := _____
IN405D := _____
IN406D := _____
IN407D := _____
IN408D := _____

Input Debounce Settings (Slot E)

IN501 Debounce (AC, 0–65000 ms)
IN502 Debounce (AC, 0–65000 ms)
IN503 Debounce (AC, 0–65000 ms)
IN504 Debounce (AC, 0–65000 ms)
IN505 Debounce (AC, 0–65000 ms)
IN506 Debounce (AC, 0–65000 ms)
IN507 Debounce (AC, 0–65000 ms)
IN508 Debounce (AC, 0–65000 ms)

IN501D := _____
IN502D := _____
IN503D := _____
IN504D := _____
IN505D := _____
IN506D := _____
IN507D := _____
IN508D := _____

Data Reset

RESET TARGETS (SELogIC)
RESET ENERGY (SELogIC)
RESET MAX/MIN (SELogIC)
RESET DEMAND ((SELogIC)
RESET PK DEMAND ((SELogIC)

RSTTRGT := _____
RSTENRGY:= _____
RSTMXMN:= _____
RSTDDEM := _____
RSTPKDEM:= _____

Access Control

DISABLE SETTINGS (SELogIC)
BLOCK MODBUS SET (NONE, R_S, ALL)

DSABLSET:= _____
BLKMBSET:= _____

Time Synchronization Source

IRIG TIME SOURCE (IRIG1, IRIG2)

TIME_SRC := _____

SET PORT p (p = F, 1, 2, 3, or 4) Command

PORT F

PROTOCOL (SEL, MOD, EVMSG, PMU)

PROTO

:=

Communications

SPEED (300, 1200, 2400, 4800, 9600, 19200, 38400 bps)

SPEED

:=

DATA BITS (7, 8 bits) *(Hidden if PROTO := MOD, EVMSG, or PMU)*

BITS

:=

PARITY (O, E, N) *(Hidden if PROTO := EVMSG or PMU)*

PARITY

:=

STOP BITS (1, 2 bits) *(Hidden if PROTO := MOD or EVMSG)*

STOP

:=

PORT TIME-OUT (0–30 min) *(Hidden if PROTO := MOD, EVMSG or PMU)*

T_OUT

:=

SEND AUTOMESSAGE (Y, N) *(Hidden if PROTO := MOD, EVMSG, or PMU)*

AUTO

:=

HDWR HANDSHAKING (Y, N) *(Hidden if PROTO := MOD or EVMSG)*

RTSCTS

:=

Modbus Protocol

MODBUS SLAVE ID (1–247) *(Hidden if PROTO := SEL, EVMSG, or PMU)*

SLAVEID

:=

PORT 1 (Ethernet Port in Slot B)

All Ethernet settings are hidden if an Ethernet option is not available.

(IP addresses are entered using zzz = 1-126, 128-223; yyy = 0-255; xxx = 0-255; www = 0-255)

IP ADDRESS (zzz.yyy.xxx.www)

IPADDR

:=

SUBNET MASK (zzz.yyy.xxx.www)

SUBNETM

:=

DEFAULT ROUTER (zzz.yyy.xxx.www)

DEFRTR

:=

(NOTE: Setting DEFRTR := 0.0.0.0 disables the default router)

Enable TCP Keep-Alive (Y, N)

ETCPKA

:=

TCP Keep-Alive Idle Range (1–20 sec) *(Hidden if ETCPKA := N)*

KAIDLE

:=

TCP Keep-Alive Interval Range (1–20 sec)
(Hidden if ETCPKA := N)

KAINTV

:=

TCP Keep-Alive Count Range (1–20 sec)
(Hidden if ETCPKA := N)

KACNT

:=

FAST OP MESSAGES (Y, N)

FASTOP

:=

OPERATING MODE (Fixed, Failover, Switched)
(Hidden if not dual redundant Ethernet Port option)

NETMODE

:=

FAILOVER TIMEOUT (0.10–65.00 sec)
(Hidden if not dual redundant Ethernet Port option or if NETMODE is not FAILOVER)

FTIME

:=

PRIMARY NET PORT (A, B, D)
(Hidden if not dual redundant Ethernet Port option)

NETPORT

:=

NETWRK PORTA SPD (Auto, 10, 100 Mbps)

NETASPD

:=

NETWRK PORTB SPD (Auto, 10, 100 Mbps)
(Hidden if not dual redundant Ethernet Port option)

NETBSPD

:=

TELNET PORT (23, 1025–65534)

TPORT

:=

(NOTE: See Table SET.1 and the note at the end of Port 1 settings)

| | | |
|---|----------------|----------|
| TELNET TIME-OUT (1–30 min) | TIDLE | := _____ |
| FTP USER NAME (20 characters) | FTPUSER | := _____ |
| Enable IEC 61850 Protocol (Y, N) <i>(Hidden if 61850 not supported)</i> | E61850 | := _____ |
| Enable IEC 61850 GSE (Y, N) <i>(Hidden if E61850 := N)</i> | EGSE | := _____ |
| Enable Modbus Sessions (0–2) | EMOD | := _____ |
| Modbus TCP Port1 (1–65534) <i>(Hidden if EMOD := 0)</i> <i>(NOTE: See Table SET.1 and the note at the end of Port 1 settings)</i> | MODNUM1 | := _____ |
| Modbus TCP Port2 (1–65534) <i>(Hidden if EMOD := 0 or 1)</i> <i>(NOTE: See Table SET.1 and the note at the end of Port 1 settings)</i> | MODNUM2 | := _____ |
| Modbus Timeout 1 (15–900 sec) <i>(Hidden if EMOD := 0)</i> | MTIMEO1 | := _____ |
| Modbus Timeout 2 (15–900 sec) <i>(Hidden if EMOD := 0 or 1)</i> | MTIMEO2 | := _____ |

DNP3 Protocol

All DNP3 settings below are hidden if DNP3 is not an option.

| | | |
|---|---------------|----------|
| Enable DNP3 Sessions (0–3) (DNP3 settings below <i>hidden if EDNP := 0</i>) | EDNP | := _____ |
| DNP TCP and UDP Port (1–65534) <i>(NOTE: See Table SET.1 and the note at the end of Port 1 settings)</i> | DNPNUM | := _____ |
| DNP Address (0–65519) | DNPADR | := _____ |

Session 1

NOTE: The DNP IP address of each session (DNPIP1, DNPIP2, etc.) must be unique

| | | |
|---|-----------------|----------|
| IP Address [zzz.yyy.xxx.www] (15 characters) | DNPIP1 | := _____ |
| Transport Protocol (UDP, TCP) | DNPTR1 | := _____ |
| UDP Response Port (REQ, 1–65534) | DNPUDP1 | := _____ |
| DNP Address to Report to (0–65519) | REPADR1 | := _____ |
| DNP Map (1–3) | DNPMAP1 | := _____ |
| Analog Input Default Variation (1–6) | DVARAI1 | := _____ |
| Class for Binary Event Data (0–3) | ECLASSB1 | := _____ |
| Class for Counter Event Data (0–3) | ECLASSC1 | := _____ |
| Class for Analog Event Data (0–3) | ECLASSA1 | := _____ |
| Currents Scaling Decimal Places (0–3) | DECPLA1 | := _____ |
| Voltages Scaling Decimal Places (0–3) | DECPLV1 | := _____ |
| Misc Data Scaling Decimal Places (0–3) | DECPLM1 | := _____ |
| Amps Reporting Deadband Counts (0–32767) <i>(Hidden if ECLASSA1 := 0)</i> | ANADBA1 | := _____ |
| Volts Reporting Deadband Counts (0–32767) <i>(Hidden if ECLASSA1 := 0)</i> | ANADBV1 | := _____ |
| Misc Data Reporting Deadband Counts (0–32767) <i>(Hidden if ECLASSA1 := 0 and ECLASSC1 := 0)</i> | ANADBM1 | := _____ |
| Minutes for Request Interval (I, M, 1–32767) | TIMERQ1 | := _____ |
| Seconds to Select/Operate Time-Out (0.0–30.0) | STIMEO1 | := _____ |

| | | | |
|---|----------------|-----------|-------|
| Seconds to send Data Link Heartbeat (0–7200) (Hidden if <i>DNPTR1 := UDP</i>) | DNPINA1 | := | _____ |
| Event Message Confirm Time-Out (1–50 sec)) | ETIMEO1 | := | _____ |
| Enable Unsolicited Reporting (Y, N) (Hidden if <i>ECLASSA1 := 0, ECLASSB1 := 0, ECLASSC1 := 0, and ECLASSV1 := 0</i>) | UNSOL1 | := | _____ |
| Enable Unsolicited Reporting at Power-Up (Y, N) (Hidden if <i>UNSOL1 := N</i>) | PUNSOL1 | := | _____ |
| Number of Events to Transmit On (1–200) (Hidden if <i>UNSOL1 := N</i>) | NUMEVE1 | := | _____ |
| Oldest Event to Tx On (0.0–99999.0 sec) (Hidden if <i>UNSOL1 := N</i>) | AGEEVE1 | := | _____ |
| Unsolicited Message Max Retry Attempts (2–10) (Hidden if <i>UNSOL1 := N</i>) | URETRY1 | := | _____ |
| Unsolicited Message Offline Time-Out (1–5000 sec) (Hidden if <i>UNSOL1 := N</i>) | UTIMEO1 | := | _____ |

Session 2

All Session 2 settings are hidden if EDNP < 2.

| | | | |
|---|-----------------|-----------|-------|
| IP Address [zzz.yyy.xxx.www] (15 characters) | DNPIP2 | := | _____ |
| Transport Protocol (UDP, TCP) | DNPTR2 | := | _____ |
| UDP Response Port (REQ, 1–65534) | DNPUDP2 | := | _____ |
| DNP Address to Report to (0–65519) | REPADR2 | := | _____ |
| DNP Map (1–3) | DNPMAP2 | := | _____ |
| Analog Input Default Variation (1–6) | DVARAI2 | := | _____ |
| Class for Binary Event Data (0–3) | ECLASSB2 | := | _____ |
| Class for Counter Event Data (0–3) | ECLASSC2 | := | _____ |
| Class for Analog Event Data (0–3) | ECLASSA2 | := | _____ |
| Currents Scaling Decimal Places (0–3) | DECPLA2 | := | _____ |
| Voltages Scaling Decimal Places (0–3) | DECPLV2 | := | _____ |
| Misc Data Scaling Decimal Places (0–3) | DECPLM2 | := | _____ |
| Amps Reporting Deadband Counts (0–32767) (Hidden if <i>ECLASSA2 := 0</i>) | ANADBA2 | := | _____ |
| Volts Reporting Deadband Counts (0–32767) (Hidden if <i>ECLASSA2 := 0</i>) | ANADBV2 | := | _____ |
| Misc Data Reporting Deadband Counts (0–32767) (Hidden if <i>ECLASSA2 := 0 and ECLASSC2 := 0</i>) | ANADBM2 | := | _____ |
| Minutes for Request Interval (I, M, 1–32767) | TIMERQ2 | := | _____ |
| Seconds to Select/Operate Time-Out (0.0–30.0) | STIMEO2 | := | _____ |
| Seconds to send Data Link Heartbeat (0–7200) (Hidden if <i>DNPTR2 := UDP</i>) | DNPINA2 | := | _____ |
| Event Message Confirm Time-Out (1–50 sec)) | ETIMEO2 | := | _____ |
| Enable Unsolicited Reporting (Y, N) (Hidden if <i>ECLASSA2 := 0, ECLASSB2 := 0, ECLASSC2 := 0, and ECLASSV2 := 0</i>) | UNSOL2 | := | _____ |

Enable Unsolicited Reporting at Power-Up (Y, N)
(Hidden if UNSOL2 := N)

Number of Events to Transmit On (1–200)
(Hidden if UNSOL2 := N)

Oldest Event to Tx On (0.0–99999.0 sec)
(Hidden if UNSOL2 := N)

Unsolicited Message Max Retry Attempts (2–10)
(Hidden if UNSOL2 := N)

Unsolicited Message Offline Time-Out (1–5000 sec)
(Hidden if UNSOL2 := N)

PUNSOL2 := _____

NUMEVE2 := _____

AGEEVE2 := _____

URETRY2 := _____

UTIMEO2 := _____

Session 3

All Session 3 settings are hidden if EDNP < 3.

IP Address [zzz.yyy.xxx.www] (15 characters)

Transport Protocol (UDP, TCP)

UDP Response Port (REQ, 1–65534)

DNP Address to Report to (0–65519)

DNP Map (1–3)

Analog Input Default Variation (1–6)

Class for Binary Event Data (0–3)

Class for Counter Event Data (0–3)

Class for Analog Event Data (0–3)

Currents Scaling Decimal Places (0–3)

Voltages Scaling Decimal Places (0–3)

Misc Data Scaling Decimal Places (0–3)

Amps Reporting Deadband Counts (0–32767)
(Hidden if ECLASSA3 := 0)

Volts Reporting Deadband Counts (0–32767)
(Hidden if ECLASSA3 := 0)

Misc Data Reporting Deadband Counts (0–32767)
(Hidden if ECLASSA3 := 0 and ECLASSC3 := 0)

Minutes for Request Interval (I, M, 1–32767)

Seconds to Select/Operate Time-Out (0.0–30.0)

Seconds to send Data Link Heartbeat (0–7200)
(Hidden if DNPTR3 := UDP)

Event Message Confirm Time-Out (1–50 sec))

Enable Unsolicited Reporting (Y, N)
(Hidden if ECLASSA3 := 0, ECLASSB3 := 0, ECLASSC3 := 0, and ECLASSV3 := 0)

Enable Unsolicited Reporting at Power-Up (Y, N)
(Hidden if UNSOL3 := N)

Number of Events to Transmit On (1–200)
(Hidden if UNSOL3 := N)

Oldest Event to Tx On (0.0–99999.0 sec)
(Hidden if UNSOL3 := N)

DNPIP3 := _____

DNPTR3 := _____

DNPUDP3 := _____

REPADR3 := _____

DNPMAP3 := _____

DVARAI3 := _____

ECLASSB3 := _____

ECLASSC3 := _____

ECLASSA3 := _____

DECPLA3 := _____

DECPLV3 := _____

DECPLM3 := _____

ANADBA3 := _____

ANADBV3 := _____

ANADBM3 := _____

TIMERQ3 := _____

STIMEO3 := _____

DNPINA3 := _____

ETIMEO3 := _____

UNSOL3 := _____

PUNSOL3 := _____

NUMEVE3 := _____

AGEEVE3 := _____

Unsolicited Message Max Retry Attempts (2–10)
(Hidden if UNSOL3 := N)

URETRY3 := _____

Unsolicited Message Offline Time-Out (1–5000 sec)
(Hidden if UNSOL3 := N)

UTIMEO3 := _____

SNTP Client Protocol Settings

Enable SNTP Client (OFF, UNICAST, MANYCAST, BROADCAST)

ESNTP := _____

Make the following settings when ESNTP ≠ OFF.

Primary Server IP Address (zzz.yyy.xxx.www)

SNTPPSIP := _____

NOTE: To accept updates from any server when ESNTP = BROADCAST, set SNTPPSIP to 0.0.0.0.

NOTE: Only IP addresses in the range 224.0.0.1 through 239.255.255.255 are valid when ESNTP = MANYCAST.

Make the following setting when ESNTP = UNICAST.

Backup Server IP Address (zzz.yyy.xxx.www)

SNTPBSIP := _____

SNTP IP (Local) Port Number (1-65534)

NOTE: See *Table SET.1* and the note at the end of Port 1 settings.

SNTPPORT := _____

SNTP Update Rate (15–3600 seconds)

SNTPRATE := _____

Make the following setting when ESNTP = UNICAST or MANYCAST.

SNTP Timeout (5–20 seconds)

SNTPTO := _____

NOTE: SNTPTO must be less than setting SNTPRATE.

Port Number Settings Must be Unique

When making the SEL-787 Port 1 settings, port number settings cannot be used for more than one protocol. The relay checks all of the settings shown in *Table SET.1* before saving changes. If a port number is used more than once, or if it matches any of the fixed port numbers (20, 21, 102, 502, 23), the relay will display an error message and return to the first setting that is in error or contains a duplicate value.

Table SET.1 Port Number Settings That Must be Unique

| Setting | Name | Setting Required When |
|----------|----------------------------|-----------------------|
| TPORT | Telnet Port | Always |
| MODNUM1 | Modbus TCP Port 1 | EMOD > 0 |
| MODNUM2 | Modbus TCP Port 2 | EMOD > 1 |
| DNPNUM | DNPTCP and UDP Port | EDNP > 0 |
| SNTPPORT | SNTPIP (Local) Port Number | ESNTP • OFF |

PORT 2 (Fiber-Optic Serial Port in Slot B)

(Hidden if E49RTD := EXT.)

PROTOCOL (SEL, DNP, MOD, EVMSG, PMU, MBA, MBB, MB8A, MB8B, MBTA, MBTB)

PROTO := _____

Communications

| | | |
|--|---------------|----------|
| SPEED (300, 1200, 2400, 4800, 9600, 19200, 38400 bps) | SPEED | := _____ |
| DATA BITS (7, 8 bits) <i>(Hidden if PROTO := MOD, DNP, PMU, EVMSG, or MB_)</i> | BITS | := _____ |
| PARITY (O, E, N) <i>(Hidden if PROTO := EVMSG, PMU or MB_)</i> | PARITY | := _____ |
| STOP BITS (1, 2 bits) <i>(Hidden if PROTO := MOD, EVMSG, or MB_)</i> | STOP | := _____ |
| PORT TIME-OUT (0–30 min) <i>(Hidden if PROTO := MOD, EVMSG, PMU or MB_)</i> | T_OUT | := _____ |
| SEND AUTOMESSAGE (Y, N) <i>(Hidden if PROTO := MOD, DNP, PMU, EVMSG, or MB_)</i> | AUTO | := _____ |
| FAST OP MESSAGES (Y, N) <i>(Hidden if PROTO := MOD, EVMSG, DNP, PMU or MB_)</i> | FASTOP | := _____ |
| HDWR HANDSHAKING (Y, N) <i>(Hidden if PROTO := MOD, EVMSG, DNP, SEL or MB_)</i> | RTSCTS | := _____ |

DNP3 Protocol

(Hidden if PROTO := SEL, EVMSG, MB, PMU or MOD.)

| | | |
|--|-----------------|----------|
| DNP Address (0–65519) | DNPADR | := _____ |
| DNP Address to Report to (0–65519) | REPADR1 | := _____ |
| DNP Map (1–3) | DNPMAPI | := _____ |
| Analog Input Default Variation (1–6) | DVARAI1 | := _____ |
| Class for Binary Event Data (0–3) | ECLASSB1 | := _____ |
| Class for Counter Event Data (0–3) | ECLASSC1 | := _____ |
| Class for Analog Event Data (0–3) | ECLASSA1 | := _____ |
| Currents Scaling Decimal Places (0–3) | DECPLA1 | := _____ |
| Voltages Scaling Decimal Places (0–3) | DECPLV1 | := _____ |
| Misc Data Scaling Decimal Places (0–3) | DECPLM1 | := _____ |
| Amps Reporting Deadband Counts (0–32767) <i>(Hidden if ECLASSA1 := 0)</i> | ANADBA1 | := _____ |
| Volts Reporting Deadband Counts (0–32767) <i>(Hidden if ECLASSA1 := 0)</i> | ANADBV1 | := _____ |
| Misc Data Reporting Deadband Counts (0–32767) <i>(Hidden if ECLASSA1 := 0 and ECLASSC1 := 0)</i> | ANADBM1 | := _____ |
| Minutes for Request Interval (I, M, 1–32767) | TIMERQ1 | := _____ |
| Seconds to Select/Operate Time-Out (0.0–30.0) | STIMEO1 | := _____ |
| Data Link Retries (0–15) | DRETRY1 | := _____ |
| Seconds to Data Link Time-Out (0–5) <i>(Hidden if DRETRY1 := 0)</i> | DTIMEO1 | := _____ |
| Event Message Confirm Time-Out (1–50 sec) | ETIMEO1 | := _____ |
| Enable Unsolicited Reporting (Y, N) <i>(Hidden if ECLASSA1 := 0, ECLASSB1 := 0 and ECLASSC1 := 0)</i> | UNSOL1 | := _____ |
| Enable Unsolicited Reporting at Power-Up (Y, N) <i>(Hidden if UNSOL1 := N)</i> | PUNSOL1 | := _____ |

Number of Events to Transmit On (1–200)
(Hidden if *UNSOL1 := N*)

NUMEVE1 := _____

Oldest Event to Tx On (0.0–99999.0 sec)
(Hidden if *UNSOL1 := N*)

AGEEVE1 := _____

Unsolicited Message Max Retry Attempts (2–10)
(Hidden if *UNSOL1 := N*)

URETRY1 := _____

Unsolicited Message Offline Time-Out (1–5000 sec)
(Hidden if *UNSOL1 := N*)

UTIMEO1 := _____

Modbus Protocol

MODBUS SLAVE ID (1–247) (Hidden if *PROTO := SEL, DNP, PMU, EVMSG, or MB_*)

SLAVEID := _____

MIRRORED BITS Protocol

(Hidden if *PROTO := SEL, EVMSG, DNP, PMU, or MOD.*)

MB Transmit Identifier (1–4)

TXID := _____

MB Receive Identifier (1–4)

RXID := _____

MB RX Bad Pickup Time (0–10000 seconds)

RBADPU := _____

MB Channel Bad Pickup (1–10000 ppm)

CBADPU := _____

MB Receive Default State (8 characters)

RXDFLT := _____

RMB1 Pickup Debounce Messages (1–8)

RMB1PU := _____

RMB1 Dropout Debounce Messages (1–8)

RMB1DO := _____

RMB2 Pickup Debounce Messages (1–8)

RMB2PU := _____

RMB2 Dropout Debounce Messages (1–8)

RMB2DO := _____

RMB3 Pickup Debounce Messages (1–8)

RMB3PU := _____

RMB3 Dropout Debounce Messages (1–8)

RMB3DO := _____

RMB4 Pickup Debounce Messages (1–8)

RMB4PU := _____

RMB4 Dropout Debounce Messages (1–8)

RMB4DO := _____

RMB5 Pickup Debounce Messages (1–8)

RMB5PU := _____

RMB5 Dropout Debounce Messages (1–8)

RMB5DO := _____

RMB6 Pickup Debounce Messages (1–8)

RMB6PU := _____

RMB6 Dropout Debounce Messages (1–8)

RMB6DO := _____

RMB7 Pickup Debounce Messages (1–8)

RMB7PU := _____

RMB7 Dropout Debounce Messages (1–8)

RMB7DO := _____

RMB8 Pickup Debounce Messages (1–8)

RMB8PU := _____

RMB8 Dropout Debounce Messages (1–8)

RMB8DO := _____

PORT 3 (EIA-232 or EIA-485 Port in Slot B [ordering option])

PROTOCOL (SEL, DNP, MOD, EVMSG, PMU, MBA, MBB, MB8A, MB8B, MBTA, MBTB)

PROTO := _____

Communications

SPEED (300, 1200, 2400, 4800, 9600, 19200, 38400 bps)

SPEED := _____

| | | |
|---|---------------|----------|
| DATA BITS (7, 8 bits) <i>(Hidden if PROTO := MOD, DNP, PMU, EVMSG, or MB_)</i> | BITS | := _____ |
| PARITY (O, E, N) <i>(Hidden if PROTO := EVMSG, PMU, or MB_)</i> | PARITY | := _____ |
| STOP BITS (1, 2 bits) <i>(Hidden if PROTO := MOD, EVMSG, or MB_)</i> | STOP | := _____ |
| PORT TIME-OUT (0–30 min) <i>(Hidden if PROTO := MOD, PMU, EVMSG, or MB_)</i> | T_OUT | := _____ |
| SEND AUTOMESSAGE (Y, N) <i>(Hidden if PROTO := MOD, DNP, PMU, EVMSG, or MB_)</i> | AUTO | := _____ |
| HDWR HANDSHAKING (Y, N) <i>(Hidden if EIA-485 Port or PROTO := MOD, DNP, EVMSG, or MB_)</i> | RTSCTS | := _____ |
| FAST OP MESSAGES (Y, N) <i>(Hidden if PROTO := MOD, DNP, PMU, EVMSG, or MB_)</i> | FASTOP | := _____ |

DNP3 Protocol

(Hidden if PROTO := SEL, EVMSG, MB, PMU or MOD.)

| | | |
|--|-----------------|----------|
| DNP Address (0–65519) | DNPADR | := _____ |
| DNP Address to Report to (0–65519) | REPADR1 | := _____ |
| DNP Map (1–3) | DNPMAPI | := _____ |
| Analog Input Default Variation (1–6) | DVARAI1 | := _____ |
| Class for Binary Event Data (0–3) | ECLASSB1 | := _____ |
| Class for Counter Event Data (0–3) | ECLASSC1 | := _____ |
| Class for Analog Event Data (0–3) | ECLASSA1 | := _____ |
| Currents Scaling Decimal Places (0–3) | DECPLA1 | := _____ |
| Voltages Scaling Decimal Places (0–3) | DECPLV1 | := _____ |
| Misc Data Scaling Decimal Places (0–3) | DECPLM1 | := _____ |
| Amps Reporting Deadband Counts (0–32767) <i>(Hidden if ECLASSA1 := 0)</i> | ANADBA1 | := _____ |
| Volts Reporting Deadband Counts (0–32767) <i>(Hidden if ECLASSA1 := 0)</i> | ANADBV1 | := _____ |
| Misc Data Reporting Deadband Counts (0–32767) <i>(Hidden if ECLASSA1 := 0 and ECLASSC1 := 0)</i> | ANADBM1 | := _____ |
| Minutes for Request Interval (I, M, 1–32767) | TIMERQ1 | := _____ |
| Seconds to Select/Operate Time-Out (0.0–30.0) | STIMEO1 | := _____ |
| Data Link Retries (0–15) | DRETRY1 | := _____ |
| Seconds to Data Link Time-Out (0–5) <i>(Hidden if DRETRY1 := 0)</i> | DTIMEO1 | := _____ |
| Event Message Confirm Time-Out (1–50 sec) | ETIMEO1 | := _____ |
| Enable Unsolicited Reporting (Y, N) <i>(Hidden if ECLASSA1 := 0, ECLASSB1 := 0 and ECLASSC1 := 0)</i> | UNSOL1 | := _____ |
| Enable Unsolicited Reporting at Power-Up (Y, N) <i>(Hidden if UNSOL1 := N)</i> | PUNSOL1 | := _____ |
| Number of Events to Transmit On (1–200) <i>(Hidden if UNSOL1 := N)</i> | NUMEVE1 | := _____ |
| Oldest Event to Tx On (0.0–99999.0 sec) <i>(Hidden if UNSOL1 := N)</i> | AGEEVE1 | := _____ |

| | | |
|---|----------------|----------|
| Unsolicited Message Max Retry Attempts (2–10) (Hidden if <i>UNSOL1</i> := N) | URETRY1 | := _____ |
| Unsolicited Message Offline Time-Out (1–5000 sec) (Hidden if <i>UNSOL1</i> := N) | UTIMEO1 | := _____ |
| Minimum Seconds from DCD to TX (0.00–1.00) | MINDLY | := _____ |
| Maximum Seconds from DCD to TX (0.00–1.00) | MAXDLY | := _____ |
| Settle Time from RTS On to TX (OFF, 0.00–30.00 sec) | PREDLY | := _____ |
| Settle Time from TX to RTS OFF (0.00–30.00 sec) | PSTDLY | := _____ |

Modem Protocol (for DNP3 session and EIA-232 port only)

| | | |
|---|----------------|----------|
| Modem Connected to Port (Y, N) | MODEM | := _____ |
| Modem Startup String (30 characters) | MSTR | := _____ |
| Phone Number for Dial-Out (30 characters) | PH_NUM1 | := _____ |
| Phone Number for Dial-Out (30 characters) | PH_NUM2 | := _____ |
| Retry Attempts for Phone 1 Dial-Out (1–20) | RETRY1 | := _____ |
| Retry Attempts for Phone 2 Dial-Out (1–20) | RETRY2 | := _____ |
| Time to Attempt Dial (5–300 sec) | MDTIME | := _____ |
| Time Between Dial-Out Attempts (5–3600 sec) | MDRET | := _____ |

Modbus Protocol

| | | |
|--|----------------|----------|
| MODBUS SLAVE ID (1–247) (Hidden if <i>PROTO</i> := <i>SEL</i> , <i>DNP</i> , <i>PMU</i> , <i>EVMSG</i> , or <i>MB_</i>) | SLAVEID | := _____ |
|--|----------------|----------|

MIRRORED BITS Protocol

(Hidden if *PROTO* := *SEL*, *DNP*, *PMU*, *EVMSG*, or *MOD*.)

| | | |
|---|---------------|----------|
| MB Transmit Identifier (1–4) | TXID | := _____ |
| MB Receive Identifier (1–4) | RXID | := _____ |
| MB RX Bad Pickup Time (0–10000 seconds) | RBADPU | := _____ |
| MB Channel Bad Pickup (1–10000 ppm) | CBADPU | := _____ |
| MB Receive Default State (8 characters) | RXDFLT | := _____ |
| RMB1 Pickup Debounce Messages (1–8) | RMB1PU | := _____ |
| RMB1 Dropout Debounce Messages (1–8) | RMB1DO | := _____ |
| RMB2 Pickup Debounce Messages (1–8) | RMB2PU | := _____ |
| RMB2 Dropout Debounce Messages (1–8) | RMB2DO | := _____ |
| RMB3 Pickup Debounce Messages (1–8) | RMB3PU | := _____ |
| RMB3 Dropout Debounce Messages (1–8) | RMB3DO | := _____ |
| RMB4 Pickup Debounce Messages (1–8) | RMB4PU | := _____ |
| RMB4 Dropout Debounce Messages (1–8) | RMB4DO | := _____ |
| RMB5 Pickup Debounce Messages (1–8) | RMB5PU | := _____ |
| RMB5 Dropout Debounce Messages (1–8) | RMB5DO | := _____ |
| RMB6 Pickup Debounce Messages (1–8) | RMB6PU | := _____ |

| | | |
|--------------------------------------|---------------|----------|
| RMB6 Dropout Debounce Messages (1–8) | RMB6DO | := _____ |
| RMB7 Pickup Debounce Messages (1–8) | RMB7PU | := _____ |
| RMB7 Dropout Debounce Messages (1–8) | RMB7DO | := _____ |
| RMB8 Pickup Debounce Messages (1–8) | RMB8PU | := _____ |
| RMB8 Dropout Debounce Messages (1–8) | RMB8DO | := _____ |

PORT 4 (EIA-232/485 Port or DeviceNet Port in Slot C)

| | | |
|--|--------------|----------|
| PROTOCOL (SEL, DNP, MOD, DNET, EVMSG, PMU, MBA, MBB, MB8A, MB8B, MBTA, MBTB) | PROTO | := _____ |
|--|--------------|----------|

Interface Select

(Hidden if PROTO := DNET.)

| | | |
|---------------------------|----------------|----------|
| COMM INTERFACE (232, 485) | COMMINF | := _____ |
|---------------------------|----------------|----------|

Communications

| | | |
|--|---------------|----------|
| SPEED (300, 1200, 2400, 4800, 9600, 19200, 38400 bps) (Hidden if PROTO := DNET) | SPEED | := _____ |
| DATA BITS (7, 8 bits) (Hidden if PROTO := DNP, MOD, PMU, EVMSG, MB_, or DNET) | BITS | := _____ |
| PARITY (O, E, N) (Hidden if PROTO := DNET, EVMSG, PMU, or MB_) | PARITY | := _____ |
| STOP BITS (1, 2 bits) (Hidden if PROTO := MOD, EVMSG, MB_, or DNET) | STOP | := _____ |
| PORT TIME-OUT (0–30 min) (Hidden if PROTO := MOD, EVMSG, MB_, PMU or DNET) | T_OUT | := _____ |
| SEND AUTOMESSAGE (Y, N) (Hidden if PROTO := DNP, MOD, EVMSG, MB_, PMU or DNET) | AUTO | := _____ |
| HDWR HANDSHAKING (Y, N) (Hidden if COMMINF := 485 or PROTO := MOD, DNP, EVMSG, MB_, or DNET) | RTSCTS | := _____ |
| FAST OP MESSAGES (Y, N) (Hidden if PROTO := DNP, MOD, EVMSG, MB_, PMU or DNET) | FASTOP | := _____ |

DNP3 Protocol

(Hidden if PROTO := SEL, EVMSG, MB, PMU, DNET or MOD.)

| | | |
|---|-----------------|----------|
| DNP Address (0–65519) | DNPADR | := _____ |
| DNP Address to Report to (0–65519) | REPADR1 | := _____ |
| DNP Map (1–3) | DNPMAPI | := _____ |
| Analog Input Default Variation (1–6) | DVARAI1 | := _____ |
| Class for Binary Event Data (0–3) | ECLASSB1 | := _____ |
| Class for Counter Event Data (0–3) | ECLASSC1 | := _____ |
| Class for Analog Event Data (0–3) | ECLASSA1 | := _____ |
| Currents Scaling Decimal Places (0–3) | DECPLA1 | := _____ |
| Voltages Scaling Decimal Places (0–3) | DECPLV1 | := _____ |
| Misc Data Scaling Decimal Places (0–3) | DECPLM1 | := _____ |
| Amps Reporting Deadband Counts (0–32767) (Hidden if ECLASSAI := 0) | ANADBA1 | := _____ |

| | |
|---|-------------------------|
| Volts Reporting Deadband Counts (0–32767) (Hidden if <i>ECLASSA1</i> := 0) | ANADBV1 := _____ |
| Misc Data Reporting Deadband Counts (0–32767) (Hidden if <i>ECLASSA1</i> := 0 and <i>ECLASSC1</i> := 0) | ANADBM1 := _____ |
| Minutes for Request Interval (I, M, 1–32767) | TIMERQ1 := _____ |
| Seconds to Select/Operate Time-Out (0.0–30.0) | STIMEO1 := _____ |
| Data Link Retries (0–15) | DRETRY1 := _____ |
| Seconds to Data Link Time-Out (0–5) (Hidden if <i>DRETRY1</i> := 0) | DTIMEO1 := _____ |
| Event Message Confirm Time-Out (1–50 sec)) | ETIMEO1 := _____ |
| Enable Unsolicited Reporting (Y, N) (Hidden if <i>ECLASSA1</i> := 0, <i>ECLASSB1</i> := 0, <i>ECLASSC1</i> := 0, and <i>ECLASSV1</i> := 0) | UNSOL1 := _____ |
| Enable Unsolicited Reporting at Power-Up (Y, N) (Hidden if <i>UNSOL1</i> := N) | PUNSOL1 := _____ |
| Number of Events to Transmit On (1–200) (Hidden if <i>UNSOL1</i> := N) | NUMEVE1 := _____ |
| Oldest Event to Tx On (0.0–99999.0 sec) (Hidden if <i>UNSOL1</i> := N) | AGEEVE1 := _____ |
| Unsolicited Message Max Retry Attempts (2–10) (Hidden if <i>UNSOL1</i> := N) | URETRY1 := _____ |
| Unsolicited Message Offline Time-Out (1–5000 sec) (Hidden if <i>UNSOL1</i> := N) | UTIMEO1 := _____ |
| Minimum Seconds from DCD to TX (0.00–1.00) | MINDLY := _____ |
| Maximum Seconds from DCD to TX (0.00–1.00) | MAXDLY := _____ |
| Settle Time from RTS On to TX (OFF, 0.00–30.00 sec) | PREDLY := _____ |
| Settle Time from TX to RTS OFF (0.00–30.00 sec) | PSTDLY := _____ |

Modem Protocol (for DNP3 session and EIA232 port only)

| | |
|---|-------------------------|
| Modem Connected to Port (Y, N) | MODEM := _____ |
| Modem Startup String (30 characters) | MSTR := _____ |
| Phone Number for Dial-Out (30 characters) | PH_NUM1 := _____ |
| Phone Number for Dial-Out (30 characters) | PH_NUM2 := _____ |
| Retry Attempts for Phone 1 Dial-Out (1–20) | RETRY1 := _____ |
| Retry Attempts for Phone 2 Dial-Out (1–20) | RETRY2 := _____ |
| Time to Attempt Dial (5–300 sec) | MDTIME := _____ |
| Time Between Dial-Out Attempts (5–3600 sec) | MDRET := _____ |

Modbus Protocol

| | |
|--|-------------------------|
| MODBUS SLAVE ID (1–247) (Hidden if <i>PROTO</i> := <i>SEL</i> , <i>DNP</i> , <i>PMU</i> , <i>EVMSG</i> , <i>MB_</i> , or <i>DNET</i>) | SLAVEID := _____ |
|--|-------------------------|

MIRRORED BITS Protocol

(Hidden if *PROTO* := *SEL*, *EVMSG*, *DNP*, *PMU*, *DNET* or *MOD*.)

| | |
|------------------------------|----------------------|
| MB Transmit Identifier (1–4) | TXID := _____ |
|------------------------------|----------------------|

| | | |
|---|---------------|----------|
| MB Receive Identifier (1–4) | RXID | := _____ |
| MB RX Bad Pickup Time (0–10000 seconds) | RBADPU | := _____ |
| MB Channel Bad Pickup (1–10000 ppm) | CBADPU | := _____ |
| MB Receive Default State (8 characters) | RXDFLT | := _____ |
| RMB1 Pickup Debounce Messages (1–8) | RMB1PU | := _____ |
| RMB1 Dropout Debounce Messages (1–8) | RMB1DO | := _____ |
| RMB2 Pickup Debounce Messages (1–8) | RMB2PU | := _____ |
| RMB2 Dropout Debounce Messages (1–8) | RMB2DO | := _____ |
| RMB3 Pickup Debounce Messages (1–8) | RMB3PU | := _____ |
| RMB3 Dropout Debounce Messages (1–8) | RMB3DO | := _____ |
| RMB4 Pickup Debounce Messages (1–8) | RMB4PU | := _____ |
| RMB4 Dropout Debounce Messages (1–8) | RMB4DO | := _____ |
| RMB5 Pickup Debounce Messages (1–8) | RMB5PU | := _____ |
| RMB5 Dropout Debounce Messages (1–8) | RMB5DO | := _____ |
| RMB6 Pickup Debounce Messages (1–8) | RMB6PU | := _____ |
| RMB6 Dropout Debounce Messages (1–8) | RMB6DO | := _____ |
| RMB7 Pickup Debounce Messages (1–8) | RMB7PU | := _____ |
| RMB7 Dropout Debounce Messages (1–8) | RMB7DO | := _____ |
| RMB8 Pickup Debounce Messages (1–8) | RMB8PU | := _____ |
| RMB8 Dropout Debounce Messages (1–8) | RMB8DO | := _____ |

Front-Panel Settings (SET F Command)

General

| | | |
|--------------------------------------|---------|----|
| DISPLY PTS ENABL (N, 1–32) | EDP | := |
| LOCAL BITS ENABL (N, 1–32) | ELB | := |
| LCD TIMEOUT (OFF, 1–30 min) | FP_TO | := |
| LCD CONTRAST (1–8) | FP_CONT | := |
| FP AUTOMESSAGES (OVERRIDE, ROTATING) | FP_AUTO | := |
| CLOSE RESET LEDS (Y, N) | RSTLED | := |

Target LED

| | | |
|-----------------------------|----------|----|
| TRIP LATCH T_LED (Y, N) | T01LEDL | := |
| LED1 EQUATION (SELogIC) | T01_LED | := |
| TRIP LATCH T_LED (Y, N) | T02LEDL | := |
| LED2 EQUATION (SELogIC) | T02_LED | := |
| TRIP LATCH T_LED (Y, N) | T03LEDL | := |
| LED3 EQUATION (SELogIC) | T03_LED | := |
| TRIP LATCH T_LED (Y, N) | T04LEDL | := |
| LED4 EQUATION (SELogIC) | T04_LED | := |
| TRIP LATCH T_LED (Y, N) | T05LEDL | := |
| LED5 EQUATION (SELogIC) | T05_LED | := |
| TRIP LATCH T_LED (Y, N) | T06LEDL | := |
| LED6 EQUATION (SELogIC) | T06_LED | := |
| PB1A_LED EQUATION (SELogIC) | PB1A_LED | := |
| PB1B_LED EQUATION (SELogIC) | PB1B_LED | := |
| PB2A_LED EQUATION (SELogIC) | PB2A_LED | := |
| PB2B_LED EQUATION (SELogIC) | PB2B_LED | := |
| PB3A_LED EQUATION (SELogIC) | PB3A_LED | := |
| PB3B_LED EQUATION (SELogIC) | PB3B_LED | := |
| PB4A_LED EQUATION (SELogIC) | PB4A_LED | := |
| PB4B_LED EQUATION (SELogIC) | PB4B_LED | := |

Display Points

Display Point Settings (maximum 60 characters):

- (Boolean): Relay Word Bit Name, "Alias", "Set String", "Clear String"
- (Analog): Analog Quantity Name, "User Text and Formatting"

| | | |
|------------------------------------|------|----|
| DISPLAY POINT DP01 (60 characters) | DP01 | := |
| DISPLAY POINT DP02 (60 characters) | DP02 | := |

DISPLAY POINT DP03 (60 characters)
DISPLAY POINT DP04 (60 characters)
DISPLAY POINT DP05 (60 characters)
DISPLAY POINT DP06 (60 characters)
DISPLAY POINT DP07 (60 characters)
DISPLAY POINT DP08 (60 characters)
DISPLAY POINT DP09 (60 characters)
DISPLAY POINT DP10 (60 characters)
DISPLAY POINT DP11 (60 characters)
DISPLAY POINT DP12 (60 characters)
DISPLAY POINT DP13 (60 characters)
DISPLAY POINT DP14 (60 characters)
DISPLAY POINT DP15 (60 characters)
DISPLAY POINT DP16 (60 characters)
DISPLAY POINT DP17 (60 characters)
DISPLAY POINT DP18 (60 characters)
DISPLAY POINT DP19 (60 characters)
DISPLAY POINT DP20 (60 characters)
DISPLAY POINT DP21 (60 characters)
DISPLAY POINT DP22 (60 characters)
DISPLAY POINT DP23 (60 characters)
DISPLAY POINT DP24 (60 characters)
DISPLAY POINT DP25 (60 characters)
DISPLAY POINT DP26 (60 characters)
DISPLAY POINT DP27 (60 characters)
DISPLAY POINT DP28 (60 characters)
DISPLAY POINT DP29 (60 characters)
DISPLAY POINT DP30 (60 characters)
DISPLAY POINT DP31 (60 characters)
DISPLAY POINT DP32 (60 characters)

DP03 := _____
DP04 := _____
DP05 := _____
DP06 := _____
DP07 := _____
DP08 := _____
DP09 := _____
DP10 := _____
DP11 := _____
DP12 := _____
DP13 := _____
DP14 := _____
DP15 := _____
DP16 := _____
DP17 := _____
DP18 := _____
DP19 := _____
DP20 := _____
DP21 := _____
DP22 := _____
DP23 := _____
DP24 := _____
DP25 := _____
DP26 := _____
DP27 := _____
DP28 := _____
DP29 := _____
DP30 := _____
DP31 := _____
DP32 := _____

Local Bits Labels

LB_NAME (14 characters)
CLEAR LB_LABEL (7 characters)
SET LB_LABEL (7 characters)
PULSE LB_LABEL (7 characters)
LB_NAME (14 characters)
CLEAR LB_LABEL (7 characters)

NLB01 := _____
CLB01 := _____
SLB01 := _____
PLB01 := _____
NLB02 := _____
CLB02 := _____

Date _____
Group _____

| | | |
|--------------------------------|--------------|----------|
| SET LB_ LABEL (7 characters) | SLB02 | := _____ |
| PULSE LB_ LABEL (7 characters) | PLB02 | := _____ |
| LB_ NAME (14 characters) | NLB03 | := _____ |
| CLEAR LB_ LABEL (7 characters) | CLB03 | := _____ |
| SET LB_ LABEL (7 characters) | SLB03 | := _____ |
| PULSE LB_ LABEL (7 characters) | PLB03 | := _____ |
| LB_ NAME (14 characters) | NLB04 | := _____ |
| CLEAR LB_ LABEL (7 characters) | CLB04 | := _____ |
| SET LB_ LABEL (7 characters) | SLB04 | := _____ |
| PULSE LB_ LABEL (7 characters) | PLB04 | := _____ |
| LB_ NAME (14 characters) | NLB05 | := _____ |
| CLEAR LB_ LABEL (7 characters) | CLB05 | := _____ |
| SET LB_ LABEL (7 characters) | SLB05 | := _____ |
| PULSE LB_ LABEL (7 characters) | PLB05 | := _____ |
| LB_ NAME (14 characters) | NLB06 | := _____ |
| CLEAR LB_ LABEL (7 characters) | CLB06 | := _____ |
| SET LB_ LABEL (7 characters) | SLB06 | := _____ |
| PULSE LB_ LABEL (7 characters) | PLB06 | := _____ |
| LB_ NAME (14 characters) | NLB07 | := _____ |
| CLEAR LB_ LABEL (7 characters) | CLB07 | := _____ |
| SET LB_ LABEL (7 characters) | SLB07 | := _____ |
| PULSE LB_ LABEL (7 characters) | PLB07 | := _____ |
| LB_ NAME (14 characters) | NLB08 | := _____ |
| CLEAR LB_ LABEL (7 characters) | CLB08 | := _____ |
| SET LB_ LABEL (7 characters) | SLB08 | := _____ |
| PULSE LB_ LABEL (7 characters) | PLB08 | := _____ |
| LB_ NAME (14 characters) | NLB09 | := _____ |
| CLEAR LB_ LABEL (7 characters) | CLB09 | := _____ |
| SET LB_ LABEL (7 characters) | SLB09 | := _____ |
| PULSE LB_ LABEL (7 characters) | PLB09 | := _____ |
| LB_ NAME (14 characters) | NLB10 | := _____ |
| CLEAR LB_ LABEL (7 characters) | CLB10 | := _____ |
| SET LB_ LABEL (7 characters) | SLB10 | := _____ |
| PULSE LB_ LABEL (7 characters) | PLB10 | := _____ |
| LB_ NAME (14 characters) | NLB11 | := _____ |
| CLEAR LB_ LABEL (7 characters) | CLB11 | := _____ |
| SET LB_ LABEL (7 characters) | SLB11 | := _____ |

| | | |
|--------------------------------|--------------|----|
| PULSE LB_ LABEL (7 characters) | PLB11 | := |
| LB_NAME (14 characters) | NLB12 | := |
| CLEAR LB_ LABEL (7 characters) | CLB12 | := |
| SET LB_ LABEL (7 characters) | SLB12 | := |
| PULSE LB_ LABEL (7 characters) | PLB12 | := |
| LB_NAME (14 characters) | NLB13 | := |
| CLEAR LB_ LABEL (7 characters) | CLB13 | := |
| SET LB_ LABEL (7 characters) | SLB13 | := |
| PULSE LB_ LABEL (7 characters) | PLB13 | := |
| LB_NAME (14 characters) | NLB14 | := |
| CLEAR LB_ LABEL (7 characters) | CLB14 | := |
| SET LB_ LABEL (7 characters) | SLB14 | := |
| PULSE LB_ LABEL (7 characters) | PLB14 | := |
| LB_NAME (14 characters) | NLB15 | := |
| CLEAR LB_ LABEL (7 characters) | CLB15 | := |
| SET LB_ LABEL (7 characters) | SLB15 | := |
| PULSE LB_ LABEL (7 characters) | PLB15 | := |
| LB_NAME (14 characters) | NLB16 | := |
| CLEAR LB_ LABEL (7 characters) | CLB16 | := |
| SET LB_ LABEL (7 characters) | SLB16 | := |
| PULSE LB_ LABEL (7 characters) | PLB16 | := |
| LB_NAME (14 characters) | NLB17 | := |
| CLEAR LB_ LABEL (7 characters) | CLB17 | := |
| SET LB_ LABEL (7 characters) | SLB17 | := |
| PULSE LB_ LABEL (7 characters) | PLB17 | := |
| LB_NAME (14 characters) | NLB18 | := |
| CLEAR LB_ LABEL (7 characters) | CLB18 | := |
| SET LB_ LABEL (7 characters) | SLB18 | := |
| PULSE LB_ LABEL (7 characters) | PLB18 | := |
| LB_NAME (14 characters) | NLB19 | := |
| CLEAR LB_ LABEL (7 characters) | CLB19 | := |
| SET LB_ LABEL (7 characters) | SLB19 | := |
| PULSE LB_ LABEL (7 characters) | PLB19 | := |
| LB_NAME (14 characters) | NLB20 | := |
| CLEAR LB_ LABEL (7 characters) | CLB20 | := |
| SET LB_ LABEL (7 characters) | SLB20 | := |
| PULSE LB_ LABEL (7 characters) | PLB20 | := |

Date _____
Group _____

| | | |
|-------------------------------|-------|----|
| LB_NAME (14 characters) | NLB21 | := |
| CLEAR LB_LABEL (7 characters) | CLB21 | := |
| SET LB_LABEL (7 characters) | SLB21 | := |
| PULSE LB_LABEL (7 characters) | PLB21 | := |
| LB_NAME (14 characters) | NLB22 | := |
| CLEAR LB_LABEL (7 characters) | CLB22 | := |
| SET LB_LABEL (7 characters) | SLB22 | := |
| PULSE LB_LABEL (7 characters) | PLB22 | := |
| LB_NAME (14 characters) | NLB23 | := |
| CLEAR LB_LABEL (7 characters) | CLB23 | := |
| SET LB_LABEL (7 characters) | SLB23 | := |
| PULSE LB_LABEL (7 characters) | PLB23 | := |
| LB_NAME (14 characters) | NLB24 | := |
| CLEAR LB_LABEL (7 characters) | CLB24 | := |
| SET LB_LABEL (7 characters) | SLB24 | := |
| PULSE LB_LABEL (7 characters) | PLB24 | := |
| LB_NAME (14 characters) | NLB25 | := |
| CLEAR LB_LABEL (7 characters) | CLB25 | := |
| SET LB_LABEL (7 characters) | SLB25 | := |
| PULSE LB_LABEL (7 characters) | PLB25 | := |
| LB_NAME (14 characters) | NLB26 | := |
| CLEAR LB_LABEL (7 characters) | CLB26 | := |
| SET LB_LABEL (7 characters) | SLB26 | := |
| PULSE LB_LABEL (7 characters) | PLB26 | := |
| LB_NAME (14 characters) | NLB27 | := |
| CLEAR LB_LABEL (7 characters) | CLB27 | := |
| SET LB_LABEL (7 characters) | SLB27 | := |
| PULSE LB_LABEL (7 characters) | PLB27 | := |
| LB_NAME (14 characters) | NLB28 | := |
| CLEAR LB_LABEL (7 characters) | CLB28 | := |
| SET LB_LABEL (7 characters) | SLB28 | := |
| PULSE LB_LABEL (7 characters) | PLB28 | := |
| LB_NAME (14 characters) | NLB29 | := |
| CLEAR LB_LABEL (7 characters) | CLB29 | := |
| SET LB_LABEL (7 characters) | SLB29 | := |
| PULSE LB_LABEL (7 characters) | PLB29 | := |
| LB_NAME (14 characters) | NLB30 | := |

| | | |
|-------------------------------|-------|----|
| CLEAR LB_LABEL (7 characters) | CLB30 | := |
| SET LB_LABEL (7 characters) | SLB30 | := |
| PULSE LB_LABEL (7 characters) | PLB30 | := |
| LB_NAME (14 characters) | NLB31 | := |
| CLEAR LB_LABEL (7 characters) | CLB31 | := |
| SET LB_LABEL (7 characters) | SLB31 | := |
| PULSE LB_LABEL (7 characters) | PLB31 | := |
| LB_NAME (14 characters) | NLB32 | := |
| CLEAR LB_LABEL (7 characters) | CLB32 | := |
| SET LB_LABEL (7 characters) | SLB32 | := |
| PULSE LB_LABEL (7 characters) | PLB32 | := |

Report Settings (SET R Command)

SER Chatter Criteria

| | | |
|---------------------------------|---------|----|
| Auto-Removal Enable (Y, N) | ESERDEL | := |
| Number of Counts (2–20 counts) | SRDLCNT | := |
| Removal Time (0.1–90.0 seconds) | SRDLTIM | := |

SER Trigger Lists

SERn = As many as 24 Relay-Word elements separated by spaces or commas. Use NA to disable setting.

| | |
|------|----|
| SER1 | := |
| SER2 | := |
| SER3 | := |
| SER4 | := |

Relay Word Bit Aliases

ALIASn= 'RW Bit'(space)'Alias'(space)'Asserted Text'(space)'Deasserted Text'. Alias, Asserted, and Deasserted text strings can be as long as 15 characters. Use NA to disable setting.

| | | |
|------------------------|--------|----|
| Enable ALIAS (N, 1–20) | EALIAS | := |
| ALIAS 1 | ALIAS1 | := |
| ALIAS 2 | ALIAS2 | := |
| ALIAS 3 | ALIAS3 | := |
| ALIAS 4 | ALIAS4 | := |
| ALIAS 5 | ALIAS5 | := |
| ALIAS 6 | ALIAS6 | := |
| ALIAS 7 | ALIAS7 | := |
| ALIAS 8 | ALIAS8 | := |
| ALIAS 9 | ALIAS9 | := |

Date _____
Group _____

ALIAS 10
ALIAS 11
ALIAS 12
ALIAS 13
ALIAS 14
ALIAS 15
ALIAS 16
ALIAS 17
ALIAS 18
ALIAS 19
ALIAS 20

ALIAS10 := _____
ALIAS11 := _____
ALIAS12 := _____
ALIAS13 := _____
ALIAS14 := _____
ALIAS15 := _____
ALIAS16 := _____
ALIAS17 := _____
ALIAS18 := _____
ALIAS19 := _____
ALIAS20 := _____

Event Report

EVENT TRIGGER (SELOGIC)
EVENT LENGTH (15, 64 cyc)
PREFault LENGTH (1–59 cyc {if LER := 15}, 1–10 cyc
{if LER := 64})

ER := _____
LER := _____
PRE := _____

Load Profile

LDP LIST (NA, as many as 17 analog quantities)
LDP ACQ RATE (5, 10, 15, 30, 60 min.)

LDLIST := _____
LDAR := _____

Modbus Map Settings (SET M Command)

Modbus User Map

See Appendix E: Modbus RTU Communications for additional details.

| | | |
|---|----------------|----------|
| User Map Register Label Name (8 characters) | MOD_001 | := _____ |
| User Map Register Label Name (8 characters) | MOD_002 | := _____ |
| User Map Register Label Name (8 characters) | MOD_003 | := _____ |
| User Map Register Label Name (8 characters) | MOD_004 | := _____ |
| User Map Register Label Name (8 characters) | MOD_005 | := _____ |
| User Map Register Label Name (8 characters) | MOD_006 | := _____ |
| User Map Register Label Name (8 characters) | MOD_007 | := _____ |
| User Map Register Label Name (8 characters) | MOD_008 | := _____ |
| User Map Register Label Name (8 characters) | MOD_009 | := _____ |
| User Map Register Label Name (8 characters) | MOD_010 | := _____ |
| User Map Register Label Name (8 characters) | MOD_011 | := _____ |
| User Map Register Label Name (8 characters) | MOD_012 | := _____ |
| User Map Register Label Name (8 characters) | MOD_013 | := _____ |
| User Map Register Label Name (8 characters) | MOD_014 | := _____ |
| User Map Register Label Name (8 characters) | MOD_015 | := _____ |
| User Map Register Label Name (8 characters) | MOD_016 | := _____ |
| User Map Register Label Name (8 characters) | MOD_017 | := _____ |
| User Map Register Label Name (8 characters) | MOD_018 | := _____ |
| User Map Register Label Name (8 characters) | MOD_019 | := _____ |
| User Map Register Label Name (8 characters) | MOD_020 | := _____ |
| User Map Register Label Name (8 characters) | MOD_021 | := _____ |
| User Map Register Label Name (8 characters) | MOD_022 | := _____ |
| User Map Register Label Name (8 characters) | MOD_023 | := _____ |
| User Map Register Label Name (8 characters) | MOD_024 | := _____ |
| User Map Register Label Name (8 characters) | MOD_025 | := _____ |
| User Map Register Label Name (8 characters) | MOD_026 | := _____ |
| User Map Register Label Name (8 characters) | MOD_027 | := _____ |
| User Map Register Label Name (8 characters) | MOD_028 | := _____ |
| User Map Register Label Name (8 characters) | MOD_029 | := _____ |
| User Map Register Label Name (8 characters) | MOD_030 | := _____ |
| User Map Register Label Name (8 characters) | MOD_031 | := _____ |
| User Map Register Label Name (8 characters) | MOD_032 | := _____ |
| User Map Register Label Name (8 characters) | MOD_033 | := _____ |
| User Map Register Label Name (8 characters) | MOD_034 | := _____ |

Date _____
Group _____

| | | |
|---|----------------|------------|
| User Map Register Label Name (8 characters) | MOD_035 | ::= |
| User Map Register Label Name (8 characters) | MOD_036 | ::= |
| User Map Register Label Name (8 characters) | MOD_037 | ::= |
| User Map Register Label Name (8 characters) | MOD_038 | ::= |
| User Map Register Label Name (8 characters) | MOD_039 | ::= |
| User Map Register Label Name (8 characters) | MOD_040 | ::= |
| User Map Register Label Name (8 characters) | MOD_041 | ::= |
| User Map Register Label Name (8 characters) | MOD_042 | ::= |
| User Map Register Label Name (8 characters) | MOD_043 | ::= |
| User Map Register Label Name (8 characters) | MOD_044 | ::= |
| User Map Register Label Name (8 characters) | MOD_045 | ::= |
| User Map Register Label Name (8 characters) | MOD_046 | ::= |
| User Map Register Label Name (8 characters) | MOD_047 | ::= |
| User Map Register Label Name (8 characters) | MOD_048 | ::= |
| User Map Register Label Name (8 characters) | MOD_049 | ::= |
| User Map Register Label Name (8 characters) | MOD_050 | ::= |
| User Map Register Label Name (8 characters) | MOD_051 | ::= |
| User Map Register Label Name (8 characters) | MOD_052 | ::= |
| User Map Register Label Name (8 characters) | MOD_053 | ::= |
| User Map Register Label Name (8 characters) | MOD_054 | ::= |
| User Map Register Label Name (8 characters) | MOD_055 | ::= |
| User Map Register Label Name (8 characters) | MOD_056 | ::= |
| User Map Register Label Name (8 characters) | MOD_057 | ::= |
| User Map Register Label Name (8 characters) | MOD_058 | ::= |
| User Map Register Label Name (8 characters) | MOD_059 | ::= |
| User Map Register Label Name (8 characters) | MOD_060 | ::= |
| User Map Register Label Name (8 characters) | MOD_061 | ::= |
| User Map Register Label Name (8 characters) | MOD_062 | ::= |
| User Map Register Label Name (8 characters) | MOD_063 | ::= |
| User Map Register Label Name (8 characters) | MOD_064 | ::= |
| User Map Register Label Name (8 characters) | MOD_065 | ::= |
| User Map Register Label Name (8 characters) | MOD_066 | ::= |
| User Map Register Label Name (8 characters) | MOD_067 | ::= |
| User Map Register Label Name (8 characters) | MOD_068 | ::= |
| User Map Register Label Name (8 characters) | MOD_069 | ::= |
| User Map Register Label Name (8 characters) | MOD_070 | ::= |
| User Map Register Label Name (8 characters) | MOD_071 | ::= |

| | | |
|---|----------------|----|
| User Map Register Label Name (8 characters) | MOD_072 | := |
| User Map Register Label Name (8 characters) | MOD_073 | := |
| User Map Register Label Name (8 characters) | MOD_074 | := |
| User Map Register Label Name (8 characters) | MOD_075 | := |
| User Map Register Label Name (8 characters) | MOD_076 | := |
| User Map Register Label Name (8 characters) | MOD_077 | := |
| User Map Register Label Name (8 characters) | MOD_078 | := |
| User Map Register Label Name (8 characters) | MOD_079 | := |
| User Map Register Label Name (8 characters) | MOD_080 | := |
| User Map Register Label Name (8 characters) | MOD_081 | := |
| User Map Register Label Name (8 characters) | MOD_082 | := |
| User Map Register Label Name (8 characters) | MOD_083 | := |
| User Map Register Label Name (8 characters) | MOD_084 | := |
| User Map Register Label Name (8 characters) | MOD_085 | := |
| User Map Register Label Name (8 characters) | MOD_086 | := |
| User Map Register Label Name (8 characters) | MOD_087 | := |
| User Map Register Label Name (8 characters) | MOD_088 | := |
| User Map Register Label Name (8 characters) | MOD_089 | := |
| User Map Register Label Name (8 characters) | MOD_090 | := |
| User Map Register Label Name (8 characters) | MOD_091 | := |
| User Map Register Label Name (8 characters) | MOD_092 | := |
| User Map Register Label Name (8 characters) | MOD_093 | := |
| User Map Register Label Name (8 characters) | MOD_094 | := |
| User Map Register Label Name (8 characters) | MOD_095 | := |
| User Map Register Label Name (8 characters) | MOD_096 | := |
| User Map Register Label Name (8 characters) | MOD_097 | := |
| User Map Register Label Name (8 characters) | MOD_098 | := |
| User Map Register Label Name (8 characters) | MOD_099 | := |
| User Map Register Label Name (8 characters) | MOD_100 | := |
| User Map Register Label Name (8 characters) | MOD_101 | := |
| User Map Register Label Name (8 characters) | MOD_102 | := |
| User Map Register Label Name (8 characters) | MOD_103 | := |
| User Map Register Label Name (8 characters) | MOD_104 | := |
| User Map Register Label Name (8 characters) | MOD_105 | := |
| User Map Register Label Name (8 characters) | MOD_106 | := |
| User Map Register Label Name (8 characters) | MOD_107 | := |
| User Map Register Label Name (8 characters) | MOD_108 | := |

Date _____
Group _____

| | | |
|---|----------------|-----------|
| User Map Register Label Name (8 characters) | MOD_109 | := |
| User Map Register Label Name (8 characters) | MOD_110 | := |
| User Map Register Label Name (8 characters) | MOD_111 | := |
| User Map Register Label Name (8 characters) | MOD_112 | := |
| User Map Register Label Name (8 characters) | MOD_113 | := |
| User Map Register Label Name (8 characters) | MOD_114 | := |
| User Map Register Label Name (8 characters) | MOD_115 | := |
| User Map Register Label Name (8 characters) | MOD_116 | := |
| User Map Register Label Name (8 characters) | MOD_117 | := |
| User Map Register Label Name (8 characters) | MOD_118 | := |
| User Map Register Label Name (8 characters) | MOD_119 | := |
| User Map Register Label Name (8 characters) | MOD_120 | := |
| User Map Register Label Name (8 characters) | MOD_121 | := |
| User Map Register Label Name (8 characters) | MOD_122 | := |
| User Map Register Label Name (8 characters) | MOD_123 | := |
| User Map Register Label Name (8 characters) | MOD_124 | := |
| User Map Register Label Name (8 characters) | MOD_125 | := |

DNP3 Map Settings (SET DNP n Command)

Use **SET DNP n** command with n = 1, 2, or 3 to create as many as three DNP User Maps. Refer to Appendix D: DNP3 Communications for details.

This is DNP Map 1 (DNP Map 2 and DNP Map 3 tables are identical to DNP Map 1 table).

Binary Input Map

| | | |
|---|--------------|----------|
| DNP Binary Input Label Name (10 characters) | BI_00 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_01 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_02 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_03 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_04 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_05 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_06 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_07 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_08 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_09 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_10 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_11 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_12 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_13 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_14 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_15 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_16 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_17 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_18 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_19 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_20 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_21 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_22 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_23 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_24 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_25 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_26 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_27 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_28 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_29 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_30 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_31 | := _____ |

Date _____
Group _____

| | | |
|---|--------------|----------|
| DNP Binary Input Label Name (10 characters) | BI_32 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_33 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_34 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_35 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_36 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_37 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_38 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_39 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_40 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_41 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_42 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_43 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_44 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_45 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_46 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_47 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_48 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_49 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_50 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_51 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_52 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_53 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_54 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_55 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_56 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_57 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_58 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_59 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_60 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_61 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_62 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_63 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_64 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_65 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_66 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_67 | := _____ |
| DNP Binary Input Label Name (10 characters) | BI_68 | := _____ |

| | | |
|---|-------|----|
| DNP Binary Input Label Name (10 characters) | BI_69 | := |
| DNP Binary Input Label Name (10 characters) | BI_70 | := |
| DNP Binary Input Label Name (10 characters) | BI_71 | := |
| DNP Binary Input Label Name (10 characters) | BI_72 | := |
| DNP Binary Input Label Name (10 characters) | BI_73 | := |
| DNP Binary Input Label Name (10 characters) | BI_74 | := |
| DNP Binary Input Label Name (10 characters) | BI_75 | := |
| DNP Binary Input Label Name (10 characters) | BI_76 | := |
| DNP Binary Input Label Name (10 characters) | BI_77 | := |
| DNP Binary Input Label Name (10 characters) | BI_78 | := |
| DNP Binary Input Label Name (10 characters) | BI_79 | := |
| DNP Binary Input Label Name (10 characters) | BI_80 | := |
| DNP Binary Input Label Name (10 characters) | BI_81 | := |
| DNP Binary Input Label Name (10 characters) | BI_82 | := |
| DNP Binary Input Label Name (10 characters) | BI_83 | := |
| DNP Binary Input Label Name (10 characters) | BI_84 | := |
| DNP Binary Input Label Name (10 characters) | BI_85 | := |
| DNP Binary Input Label Name (10 characters) | BI_86 | := |
| DNP Binary Input Label Name (10 characters) | BI_87 | := |
| DNP Binary Input Label Name (10 characters) | BI_88 | := |
| DNP Binary Input Label Name (10 characters) | BI_89 | := |
| DNP Binary Input Label Name (10 characters) | BI_90 | := |
| DNP Binary Input Label Name (10 characters) | BI_91 | := |
| DNP Binary Input Label Name (10 characters) | BI_92 | := |
| DNP Binary Input Label Name (10 characters) | BI_93 | := |
| DNP Binary Input Label Name (10 characters) | BI_94 | := |
| DNP Binary Input Label Name (10 characters) | BI_95 | := |
| DNP Binary Input Label Name (10 characters) | BI_96 | := |
| DNP Binary Input Label Name (10 characters) | BI_97 | := |
| DNP Binary Input Label Name (10 characters) | BI_98 | := |
| DNP Binary Input Label Name (10 characters) | BI_99 | := |

Binary Output Map

| | | |
|--|--------------|----------|
| DNP Binary Output Label Name (10 characters) | BO_00 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_01 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_02 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_03 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_04 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_05 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_06 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_07 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_08 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_09 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_10 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_11 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_12 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_13 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_14 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_15 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_16 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_17 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_18 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_19 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_20 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_21 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_22 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_23 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_24 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_25 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_26 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_27 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_28 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_29 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_30 | := _____ |
| DNP Binary Output Label Name (10 characters) | BO_31 | := _____ |

Analog Input Map

DNP Analog Input Label Name (24 characters)

| | | |
|-------|----|--|
| AI_00 | := | |
| AI_01 | := | |
| AI_02 | := | |
| AI_03 | := | |
| AI_04 | := | |
| AI_05 | := | |
| AI_06 | := | |
| AI_07 | := | |
| AI_08 | := | |
| AI_09 | := | |
| AI_10 | := | |
| AI_11 | := | |
| AI_12 | := | |
| AI_13 | := | |
| AI_14 | := | |
| AI_15 | := | |
| AI_16 | := | |
| AI_17 | := | |
| AI_18 | := | |
| AI_19 | := | |
| AI_20 | := | |
| AI_21 | := | |
| AI_22 | := | |
| AI_23 | := | |
| AI_24 | := | |
| AI_25 | := | |
| AI_26 | := | |
| AI_27 | := | |
| AI_28 | := | |
| AI_29 | := | |
| AI_30 | := | |
| AI_31 | := | |
| AI_32 | := | |
| AI_33 | := | |
| AI_34 | := | |

| | | |
|-------|----|--|
| AI_35 | := | |
| AI_36 | := | |
| AI_37 | := | |
| AI_38 | := | |
| AI_39 | := | |
| AI_40 | := | |
| AI_41 | := | |
| AI_42 | := | |
| AI_43 | := | |
| AI_44 | := | |
| AI_45 | := | |
| AI_46 | := | |
| AI_47 | := | |
| AI_48 | := | |
| AI_49 | := | |
| AI_50 | := | |
| AI_51 | := | |
| AI_52 | := | |
| AI_53 | := | |
| AI_54 | := | |
| AI_55 | := | |
| AI_56 | := | |
| AI_57 | := | |
| AI_58 | := | |
| AI_59 | := | |
| AI_60 | := | |
| AI_61 | := | |
| AI_62 | := | |
| AI_63 | := | |
| AI_64 | := | |
| AI_65 | := | |
| AI_66 | := | |
| AI_67 | := | |
| AI_68 | := | |
| AI_69 | := | |
| AI_70 | := | |
| AI_71 | := | |

| | | |
|-------|----|--|
| AI_72 | := | |
| AI_73 | := | |
| AI_74 | := | |
| AI_75 | := | |
| AI_76 | := | |
| AI_77 | := | |
| AI_78 | := | |
| AI_79 | := | |
| AI_80 | := | |
| AI_81 | := | |
| AI_82 | := | |
| AI_83 | := | |
| AI_84 | := | |
| AI_85 | := | |
| AI_86 | := | |
| AI_87 | := | |
| AI_88 | := | |
| AI_89 | := | |
| AI_90 | := | |
| AI_91 | := | |
| AI_92 | := | |
| AI_93 | := | |
| AI_94 | := | |
| AI_95 | := | |
| AI_96 | := | |
| AI_97 | := | |
| AI_98 | := | |
| AI_99 | := | |

Analog Output Map

| | | | |
|---|-------|----|--|
| DNP Analog Output Label Name (6 characters) | AO_00 | := | |
| DNP Analog Output Label Name (6 characters) | AO_01 | := | |
| DNP Analog Output Label Name (6 characters) | AO_02 | := | |
| DNP Analog Output Label Name (6 characters) | AO_03 | := | |
| DNP Analog Output Label Name (6 characters) | AO_04 | := | |
| DNP Analog Output Label Name (6 characters) | AO_05 | := | |
| DNP Analog Output Label Name (6 characters) | AO_06 | := | |

| | | |
|---|--------------|-----------------|
| DNP Analog Output Label Name (6 characters) | AO_07 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_08 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_09 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_10 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_11 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_12 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_13 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_14 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_15 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_16 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_17 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_18 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_19 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_20 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_21 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_22 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_23 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_24 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_25 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_26 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_27 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_28 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_29 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_30 | := _____ |
| DNP Analog Output Label Name (6 characters) | AO_31 | := _____ |

Counter Map

| | | |
|--|--------------|-----------------|
| DNP Counter Label Name (11 characters) | CO_00 | := _____ |
| DNP Counter Label Name (11 characters) | CO_01 | := _____ |
| DNP Counter Label Name (11 characters) | CO_02 | := _____ |
| DNP Counter Label Name (11 characters) | CO_03 | := _____ |
| DNP Counter Label Name (11 characters) | CO_04 | := _____ |
| DNP Counter Label Name (11 characters) | CO_05 | := _____ |
| DNP Counter Label Name (11 characters) | CO_06 | := _____ |
| DNP Counter Label Name (11 characters) | CO_07 | := _____ |
| DNP Counter Label Name (11 characters) | CO_08 | := _____ |
| DNP Counter Label Name (11 characters) | CO_09 | := _____ |
| DNP Counter Label Name (11 characters) | CO_10 | := _____ |

| | | |
|--|--------------|----------|
| DNP Counter Label Name (11 characters) | CO_11 | := _____ |
| DNP Counter Label Name (11 characters) | CO_12 | := _____ |
| DNP Counter Label Name (11 characters) | CO_13 | := _____ |
| DNP Counter Label Name (11 characters) | CO_14 | := _____ |
| DNP Counter Label Name (11 characters) | CO_15 | := _____ |
| DNP Counter Label Name (11 characters) | CO_16 | := _____ |
| DNP Counter Label Name (11 characters) | CO_17 | := _____ |
| DNP Counter Label Name (11 characters) | CO_18 | := _____ |
| DNP Counter Label Name (11 characters) | CO_19 | := _____ |
| DNP Counter Label Name (11 characters) | CO_20 | := _____ |
| DNP Counter Label Name (11 characters) | CO_21 | := _____ |
| DNP Counter Label Name (11 characters) | CO_22 | := _____ |
| DNP Counter Label Name (11 characters) | CO_23 | := _____ |
| DNP Counter Label Name (11 characters) | CO_24 | := _____ |
| DNP Counter Label Name (11 characters) | CO_25 | := _____ |
| DNP Counter Label Name (11 characters) | CO_26 | := _____ |
| DNP Counter Label Name (11 characters) | CO_27 | := _____ |
| DNP Counter Label Name (11 characters) | CO_28 | := _____ |
| DNP Counter Label Name (11 characters) | CO_29 | := _____ |
| DNP Counter Label Name (11 characters) | CO_30 | := _____ |
| DNP Counter Label Name (11 characters) | CO_31 | := _____ |

Section 7

Communications

Overview

A communications interface and protocol are required for communicating with the SEL-787 Transformer Protection Relay. A communications interface is the physical connection on a device. Once you have established a physical connection, you must use a communications protocol to interact with the relay.

The first part of this section describes communications interfaces and protocols available with the relay, including communication interface connections. The remainder of the section describes the ASCII commands you can use to communicate with the relay to obtain information, reports, data, or perform control functions.

Communications Interfaces

The SEL-787 physical interfaces are shown in *Table 7.1*. Several optional SEL devices are available to provide alternative physical interfaces, including EIA-485, EIA-232 fiber-optic serial port, copper or fiber Ethernet® port, single or dual redundant.

Table 7.1 SEL-787 Communications Port Interfaces

| | Communications Port Interfaces | Location | Feature |
|---------------------------|--|----------|-----------------|
| PORT F | EIA-232 | Front | Standard |
| PORT 1 | Option 1: 10/100BASE-T Ethernet (RJ-45 connector) Option 2: Dual, redundant 10/100 BASE-T Ethernet (Port 1A, Port 1B) Option 3: 100BASE-FX Ethernet (LC connector) Option 4: Dual, redundant 100BASE-FX Ethernet (Port 1A, Port 1B) | Rear | Ordering Option |
| PORT 2^a | Multimode Fiber-Optic Serial (ST® connector and SEL-2812 compatible)) | Rear | Standard |
| PORT 3 | Option 1: EIA-232 Option 2: EIA-485 | Rear | Standard |
| PORT 4 | Option 1: EIA-232 or EIA-485 Serial Communications Card Option 2: DeviceNet Communications Card ^b | Rear | Ordering Option |

^a This port can receive the RTD measurement information from the optional external SEL-2600 RTD Module. Refer to the applicable SEL-2600 RTD Module Instruction Manual for information on the fiber-optic interface.

^b Refer to Appendix G: DeviceNet Communications for information on the DeviceNet communications card.

Be sure to evaluate the installation and communications necessary to integrate with existing devices before ordering your SEL-787. For example, consider the fiber-optic interface in noisy installations or for large communications distances. Following is general information on possible applications of the different interfaces.

Serial (EIA-232 and EIA-485) Port

Use the EIA-232 port for communications distances of ≤ 15 m (50 feet) in low noise environments. Use the optional EIA-485 port for communications distances ≤ 1200 m (4000 feet) maximum distance (to achieve this performance, ensure proper line termination at the receiver).

To connect a PC serial port to the relay front-panel serial port and enter relay commands, you will need the following:

- A personal computer equipped with one available EIA-232 serial port
- A communications cable to connect the computer serial port to the relay serial ports
- Terminal emulation software to control the computer serial port
- An SEL-787 Relay

Some of the SEL devices available for integration or communication system robustness are included in the following list:

- SEL Communications Processors (SEL-2032, SEL-2030, SEL-2020)
- SEL-2800 Series Fiber-Optic Transceivers
- SEL-2890 Ethernet Transceiver
- SEL-3010 Event Messenger
- SEL-2505 SEL Remote I/O Module (with the SEL-2812 compatible ST option only for fiber-optic link to Port 2)

A variety of terminal emulation programs on personal computers can communicate with the relay. For the best display, use VT-100 terminal emulation or the closest variation.

The default settings for all EIA-232 serial ports are listed below:

- Baud Rate = 9600
- Data Bits = 8
- Parity = N
- Stop Bits = 1

To change the port settings, use the **SET P** command (see *Section 6: Settings*) or the front-panel. *Section 8: Front-Panel Operations* provides details on making settings with the front panel.

Hardware Flow Control

All EIA-232 serial ports support RTS/CTS hardware handshaking (hardware flow control). To enable hardware handshaking, use the **SET P** command or front-panel **PORT** submenu to set **RTSCTS = Y**. Disable hardware handshaking by setting **RTSCTS := N**.

- If **RTSCTS := N**, the relay permanently asserts the RTS line.
- If **RTSCTS := Y**, the relay deasserts RTS when it is unable to receive characters.
- If **RTSCTS := Y**, the relay does not send characters until the CTS input is asserted.

Fiber-Optic Serial Port

Use the optional fiber-optic port (PORT 2) for safety and communications distances as far as 1 km. Communications distances as far as 4 km can be achieved by using an SEL-2812 transceiver on PORT 3. While PORT 2 and the SEL-2812 are compatible, PORT 2 is less sensitive than the SEL-2812, which limits the distance to 1 km.

Ethernet Port

Use the Ethernet port for interfacing with an Ethernet network environment. SEL-787 Ethernet port choices include single or dual copper or fiber-optic configurations. With dual Ethernet ports the unit has an unmanaged Ethernet switch. Redundant configurations support automatic failover switching from primary to backup network if a failure in the primary network is detected. In addition to failover mode, the unit can operate in a “fixed connection (to netport) mode” or in a “switched mode” (as an unmanaged switch).

Figure 7.1 shows an example of a Simple Ethernet Network Configuration, *Figure 7.2* shows an example of an Ethernet Network Configuration with Dual Redundant Connections, and *Figure 7.3* shows an example of an Ethernet Network Configuration with Ring Structure.

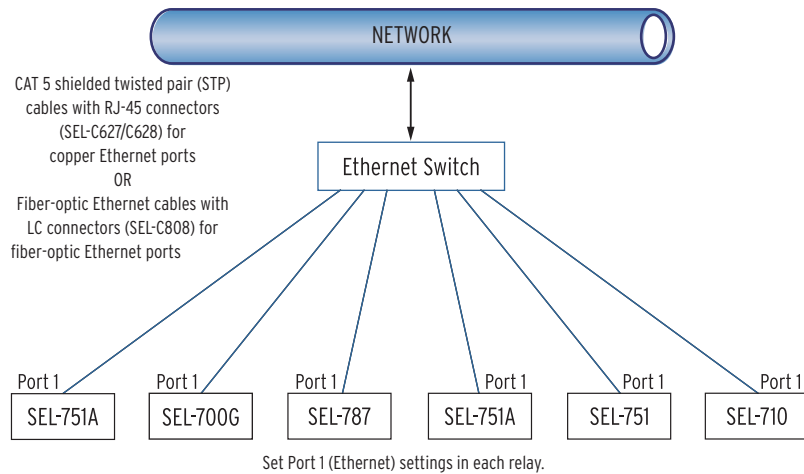


Figure 7.1 Simple Ethernet Network Configuration

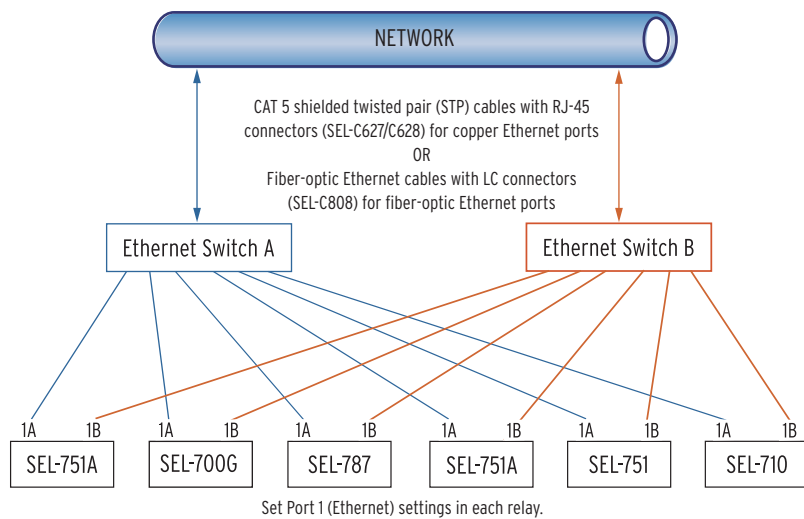


Figure 7.2 Ethernet Network Configuration With Dual Redundant Connections (Failover Mode)

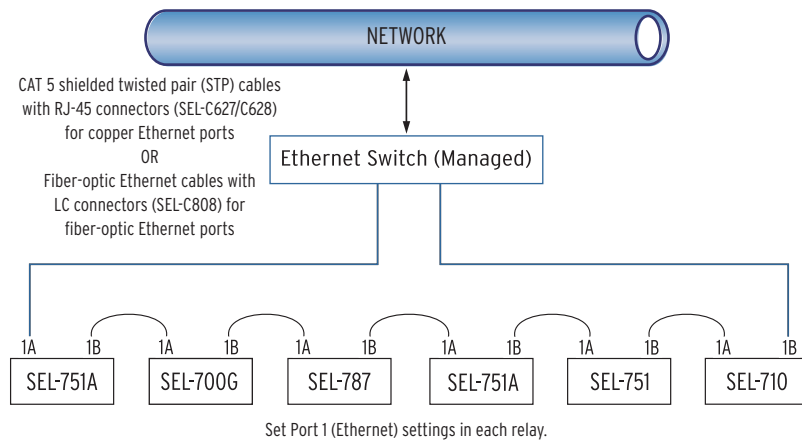


Figure 7.3 Ethernet Network Configuration With Ring Structure (Switched Mode)

Dual Network Port Operation

The SEL-787 dual Ethernet port option has two network ports. Network port failover mode enables the dual Ethernet port to operate as a single network adapter with a primary and standby physical interface. You can connect the two network ports to the same network or to different networks depending on your specific Ethernet network architecture.

Failover Mode

In the failover mode operation, the relay determines the active port. To use failover mode, proceed with the following steps.

- Step 1. Set NETMODE to FAILOVER.
- Step 2. Set FTIME to the desired network port failover time.
- Step 3. Set NETPORT to the preferred network interface.

On startup the relay communicates via NETPORT (primary port) selected. If the SEL-787 detects a link failure on the primary port, it activates the standby port after the failover time, FTIME, elapses. If the link status on the primary link returns to normal before the failover time expires, the failover timer resets and uninterrupted operation continues on the primary network port.

After failover, while communicating via standby port, the SEL-787 checks the primary link periodically and continues checking until it detects a normal link status. The relay continues to communicate via the standby port even after the primary port returns to normal. The port of choice for communications is reevaluated on change of settings or failure of the standby port or on reboot. The relay returns to operation on the primary link under those conditions if it detects a normal link status. When the active and backup links both fail, the relay alternates checking for the link status of the primary and standby ports.

Unmanaged Switch Mode

If you have a network configuration where you want to use the relay as an unmanaged switch, set NETMODE to SWITCHED. In this mode, both links are enabled. The relay will respond to the messages received on either port. All the messages received on one network port that are not addressed to the relay will be transmitted out of the other port without any modifications. In this mode NETPORT setting is ignored.

NOTE: If you change settings for the host port in the relay and the standby network port is active, the relay resets and returns to operation on the primary port.

Fixed Connection Mode

If you have a single network and want to use only one network port, or if you have both ports connected but want to force usage of only one port for various reasons, set NETMODE to FIXED and set NETPORT to the port you want to use. Only the selected network port operates and the other port is disabled.

Autonegotiation, Speed, and Duplex Mode

Single or dual copper Ethernet ports are capable of autonegotiating to determine the link speed and duplex mode. This is accomplished by setting the NETASPD and NETBSPD (network speed) to AUTO. Single or dual copper ports can also be set to a specific speed to be able to apply them in networks with older switch devices. However, the speed setting is ignored for fiber Ethernet ports. The single and dual fiber Ethernet ports are fixed by the hardware to work at 100 Mbps and full duplex mode.

NETPORT Selection

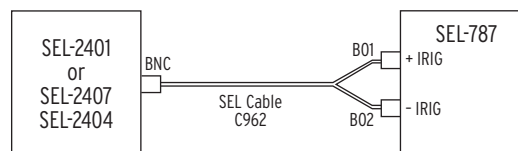
The NETPORT setting gives the user the option to select the primary port of communication in failover or fixed communication modes. Selecting “D” for this setting disables both the ports there by providing the user the security to turn off the ports even if the ports are physically connected to the network.

IRIG-B

The SEL-787 has three different physical interfaces, depending on the model options, to provide demodulated IRIG-B time-code input for time synchronization. If the relay has multiple options for IRIG-B input, only one input can be used at a time. Connection diagrams for IRIG-B and settings selection are in *Figure 7.4* through *Figure 7.6* in this section.

Option 1: Terminals B01 and B02

This input is available on all models with EIA-485 Port 3. Refer to *Figure 7.4* for a connection diagram.



B01-B02 IRIG-B input is available on all models with EIA-485 Port 3.

Cannot bring IRIG-B via Port 2 if **B01-B02** input is used.

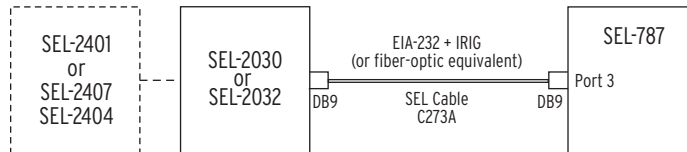
Set Global setting IRIG TIME SOURCE to TIME_SRC := IRIG1.

Figure 7.4 IRIG-B Input (Relay Terminals B01-B02)

Option 2: Port 3 (EIA-232 Option Only)

Connect to an SEL Communications Processor with SEL Cable C273A to bring IRIG-B input with the EIA-232 port. Refer to *Figure 7.5* for a connection diagram.

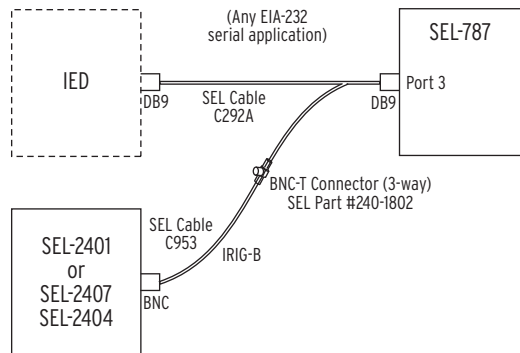
Refer to *Figure 7.6* on how to connect a SEL Time Source (SEL-2401, SEL-2404, SEL-2407) for IRIG-B Input to Port 3.



Cannot use Port 2 if Port 3 is used.

Set Global setting IRIG TIME SOURCE to TIME_SRC := IRIG1.

Figure 7.5 IRIG-B Input Via EIA-232 Port 3 (SEL Communications Processor as Source)



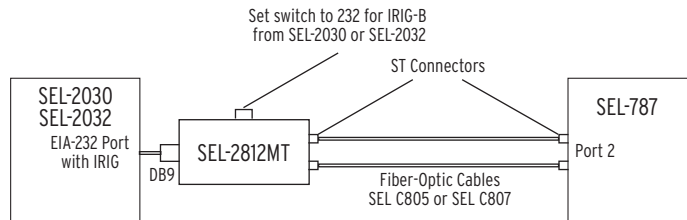
Cannot use Port 2 if Port 3 is used.

Set Global setting IRIG TIME SOURCE to TIME_SRC := IRIG1.

Figure 7.6 IRIG-B Input Via EIA-232 Port 3 (SEL-2401/2404/2407 Time Source)

Option 3: Port 2 (Fiber-Optic Serial Port)

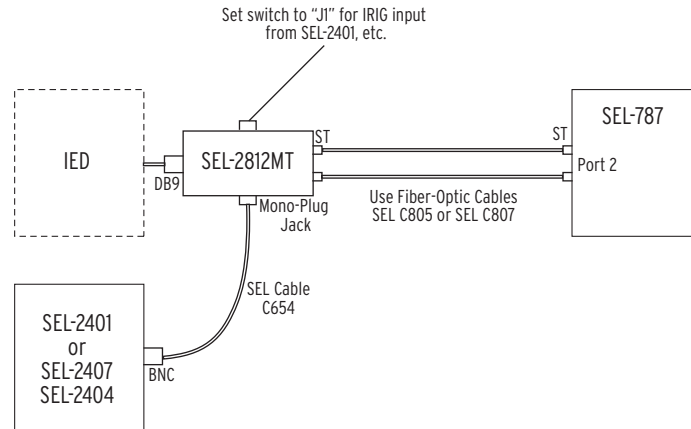
Fiber-Optic Serial Port 2 can be used to bring IRIG-B Input to the relay as shown in *Figure 7.7* and *Figure 7.8*.



Cannot use B01-B02 input or Port 3 input if Port 2 is used for IRIG-B input.

Set Global setting IRIG TIME SOURCE to TIME_SRC := IRIG2.

Figure 7.7 IRIG-B Input VIA Fiber-Optic EIA-232 Port 2 (SEL-2030/2032 Time Source)



Cannot use B01-B02 input or Port 3 input if Port 2 is used for IRIG-B input.

Set Global setting IRIG TIME SOURCE to TIME_SRC := IRIG2.

Figure 7.8 IRIG-B Input VIA Fiber-Optic EIA-232 Port 2 (SEL-2401/2404/2407 Time Source)

+5 Vdc Power Supply

Serial port power can provide as much as 0.25 A total from all of the +5 Vdc pins. Some SEL communications devices require the +5 Vdc power supply. This +5 Vdc is available on Pin 1 only.

Connect Your PC to the Relay

The front port of the SEL-787 is a standard female 9-pin connector. You can connect to a standard 9-pin computer port with SEL cable C234A; wiring for this cable is shown in *Figure 7.10*. SEL cable C234A and other cables are available from SEL. Use the SEL-5801 Cable Selector software to select an appropriate cable for another application. This software is available for free download from the SEL website at www.selinc.com.

For best performance, SEL Cable C234A should not be more than 15 meters (50 feet) long. For long-distance communications and for electrical isolation of communications ports, use the SEL family of fiber-optic transceivers. Contact SEL for more details on these devices.

Port Connector and Communications Cables

Figure 7.9 shows the front-panel EIA-232 serial port (PORT F) DB-9 connector pinout for the SEL-787.

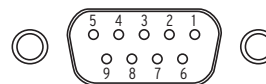


Figure 7.9 EIA-232 DB-9 Connector Pin Numbers

Table 7.2 shows the pin functions for the EIA-232 and EIA-485 serial ports.

Table 7.2 EIA-232/EIA-485 Serial Port Pin Functions (Sheet 1 of 2)

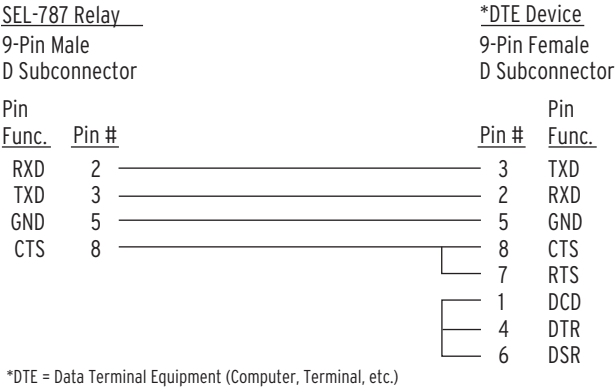
| Pin ^a | PORT 3 EIA-232 | PORT 3 EIA-485 ^a | PORT 4C EIA-232 | PORT 4A EIA-485 ^a | PORT F EIA-232 |
|------------------|-------------------|--------------------------------|--------------------|---------------------------------|-------------------|
| 1 | +5 Vdc | +TX | +5 Vdc | +TX | N/C |
| 2 | RXD | -TX | RXD | -TX | RXD |
| 3 | TXD | +RX | TXD | +RX | TXD |
| 4 | IRIG+ | -RX | N/C | -RX | N/C |
| 5 | GND | Shield | GND | Shield | GND |
| 6 | IRIG- | | N/C | | N/C |
| 7 | RTS | | RTS | | RTS |

Table 7.2 EIA-232/EIA-485 Serial Port Pin Functions (Sheet 2 of 2)

| Pin ^a | PORT 3 EIA-232 | PORT 3 EIA-485 ^a | PORT 4C EIA-232 | PORT 4A EIA-485 ^a | PORT F EIA-232 |
|------------------|-------------------|--------------------------------|--------------------|---------------------------------|-------------------|
| 8 | CTS | | CTS | | CTS |
| 9 | GND | | GND | | GND |

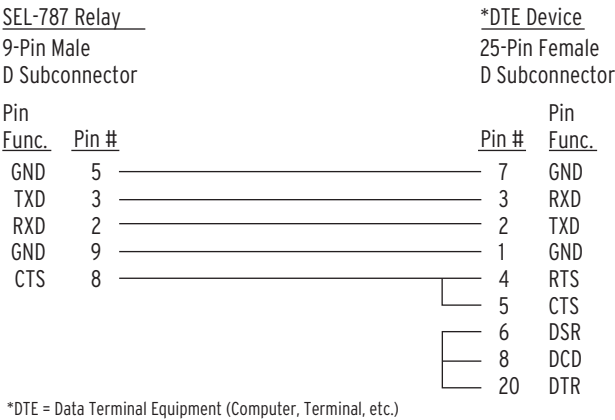
^a For EIA-485, the pin numbers represent relay terminals _01 through _05.

The following cable diagrams show several types of EIA-232 serial communications cables that connect the SEL-787 to other devices. These and other cables are available from SEL. Contact the factory for more information.



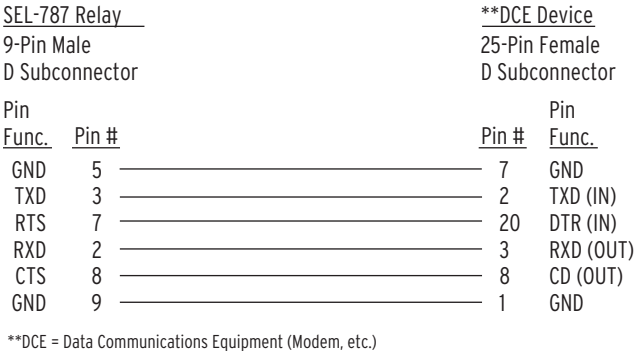
*DTE = Data Terminal Equipment (Computer, Terminal, etc.)

Figure 7.10 SEL Cable C234A–SEL-787 to DTE Device



*DTE = Data Terminal Equipment (Computer, Terminal, etc.)

Figure 7.11 SEL Cable C227A–SEL-787 to DTE Device



**DCE = Data Communications Equipment (Modem, etc.)

Figure 7.12 SEL Cable C222–SEL-787 to Modem

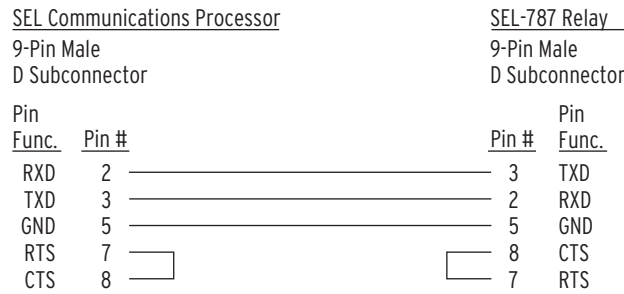


Figure 7.13 SEL Cable C272A–SEL-787 to SEL Communications Processor (Without IRIG-B Signal)

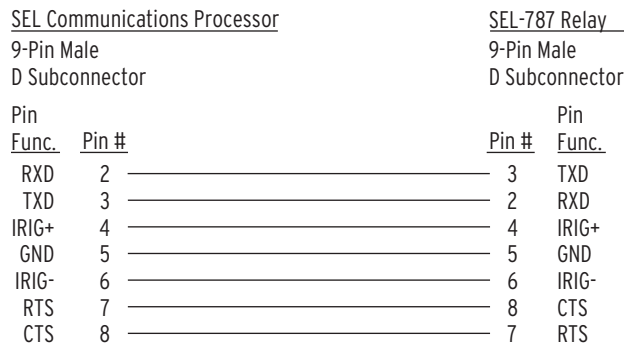
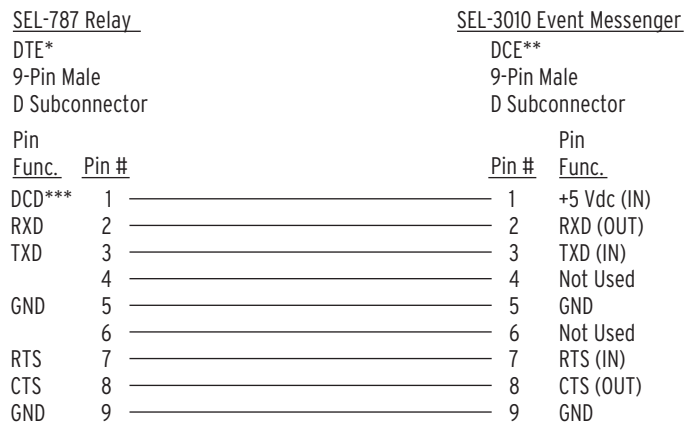


Figure 7.14 SEL Cable C273A–SEL-787 to SEL Communications Processor (With IRIG-B Signal)



*DTE = Data Terminal Equipment

**DCE = Data Communications Equipment (Modem, etc.)

***DC Voltage (+5 V) not available on front-panel EIA-232 port

Figure 7.15 SEL Cable C387–SEL-787 to SEL-3010

Communications Protocols

Protocols

Although the SEL-787 supports a wide range of protocols, not all protocols are available on all ports. In addition, not all hardware options support all protocols.

Be sure to select the correct hardware to support a particular protocol. For example, if Modbus® TCP is necessary for your application, be sure to order the Ethernet option for **Port 1**. *Table 7.3* shows the ports and the protocols available on each port.

Table 7.3 Protocols Supported on the Various Ports

| | Supported Protocol |
|---------------|---|
| PORT F | SEL ASCII and Compressed ASCII Protocols, SELBOOT, File Transfer Protocol, Modbus RTU Slave, C37.118 Protocol (synchrophasor data), and Event Messenger |
| PORT 1 | Modbus TCP/IP, FTP, TCP/IP, IEC 61850, SNTP, DNP3 LAN/WAN, and Telnet TCP/IP (SEL ASCII, Compressed ASCII, SEL Fast Meter, SEL Fast Operate, SEL Fast SER) ^a |
| PORT 2 | All the protocols supported by PORT 3 |
| PORT 3 | SEL ASCII and Compressed ASCII Protocols, SEL Fast Meter, SEL Fast Operate, SEL Fast SER, SEL Settings File Transfer, SEL MIRRORED BITS, DNP3, Modbus RTU Slave, C37.118 Protocol (synchrophasor data), and Event Messenger |
| PORT 4 | All the protocols supported by PORT 3 and DeviceNet |

^a PORT 1 concurrently supports two Modbus, two FTP, two Telnet, six IEC 61850, one SNTP, and three DNP3 LAN/WAN sessions.

NOTE: FTP, Modbus, and DeviceNet protocols ignore the hide rules of the settings.

SEL Communications Protocols

SEL ASCII. This protocol is described in *SEL ASCII Protocol and Commands* on page 7.14.

SEL Compressed ASCII. This protocol provides compressed versions of some of the ASCII commands. The compressed commands are described in *SEL ASCII Protocol and Commands*, and the protocol is described in *Appendix C: SEL Communications Processors*.

SEL Fast Meter. This protocol supports binary messages to transfer metering and digital element messages. Compressed ASCII commands that support Fast Meter are described in *SEL ASCII Protocol and Commands*, and the protocol is described in *Appendix C: SEL Communications Processors*.

SEL Fast Operate. This protocol supports binary messages to transfer operation messages. The protocol is described in *Appendix C: SEL Communications Processors*.

SEL Fast SER. This protocol is used to receive binary Sequential Events Record unsolicited responses. The protocol is described in *Appendix C: SEL Communications Processors*.

SEL Event Messenger. This is an SEL ASCII protocol with 8 data bits, no parity, and 1 stop bit for transmitting data to SEL-3010 Event Messenger. Only the communications speed is user settable to match the settings in the SEL-3010.

MIRRORED BITS Protocol

The SEL-787 supports two MIRRORED BITS communications channels, designated A and B. Within each MIRRORED BITS communications message for a given channel (A or B), there are eight logical data channels (1–8). You can, for example, set MBA on Port 3 of the base unit and MBB on Port 4A of the optional communications card. Attempting to set the PROTO setting to MBA, MB8A, or MBTA when channel A is already assigned to another port (or MBB, MB8B, or MBTB when channel B is already assigned on another port) results in the following error message: *This Mirrored Bits channel is assigned to another port.* After displaying the error message, the device returns to the PROTO setting for reentry.

C37.118 Protocol

The SEL-787 provides C37.118 protocol (synchrophasor data) support at one of the serial ports F, 2, 3, or 4. The protocol is described in *Appendix H: Synchrophasors*.

Modbus RTU Protocol

The SEL-787 provides Modbus RTU support. Modbus is a protocol described in *Appendix E: Modbus RTU Communications*.

DNP3 (Distributed Network Protocol)

The SEL-787 provides DNP3 protocol support if the option is selected. The DNP3 protocol is described in *Appendix D: DNP3 Communications*.

DeviceNet

The SEL-787 provides DeviceNet support. DeviceNet is an optional protocol described in *Appendix G: DeviceNet Communications*.

Ethernet Protocols

As with other communications interfaces, you must choose a data exchange protocol that operates over the Ethernet network link in order to exchange data. The relay supports FTP, Telnet, Ping, Modbus/TCP, IEC 61850, and DNP3 LAN/WAN protocols.

You should carefully design your Ethernet network to maximize reliability, minimize system administration effort, and provide adequate security. Work with a networking professional to design your substation Ethernet network.

FTP Server

Use the single FTP (File Transfer Protocol) session to access the following files:

- CFG.XML—Configuration read-only file in XML format
- CFG.TXT—Configuration read-only file in TXT format
- ERR.TXT—Error read-only file in TXT format
- SET_61850.CID—IEC 61850 CID read-write file
- SET_xx.TXT—Setting files in TXT format

FTP is a standard TCP/IP protocol for exchanging files. A free FTP application is included with most web browser software. You can also obtain a free or inexpensive FTP application from the Internet. When you connect to the relay Ethernet port, you will find files stored in the root (top-level) directory.

Telnet Server

Use the Telnet session (TPORT default setting is port 23) to connect to the relay to use the protocols, which are described in more detail below:

- SEL ASCII
- Compressed ASCII
- Fast Meter
- Fast Operate

NOTE: Use the **QUIT** command prior to closing the Telnet-to-Host session to set the relay to Access Level 0. Otherwise the relay will remain at an elevated access level until TIDLE expires.

Telnet is a terminal connection across a TCP/IP network that operates in a manner very similar to a direct serial port connection to one of the relay ports. As with FTP, Telnet is a part of TCP/IP. A free Telnet application is included with most computer operating systems, or you can obtain low-cost or free Telnet applications on the Internet.

Ping Server

Use a Ping client with the relay Ping server to verify that your network configuration is correct. Ping is an application based on ICMP over an IP network. A free Ping application is included with most computer operating systems.

IEC 61850

Use as many as six sessions of MMS over a TCP network to exchange data with the relay. Use GOOSE to do real-time data exchange with as many as 16 incoming messages and 8 outgoing messages. For more details on the IEC 61850 protocol, see *Appendix F: IEC 61850 Communications*.

Simple Network Time Protocol (SNTP)

When Port 1 (Ethernet port) setting ESntp is not OFF, the internal clock of the relay conditionally synchronizes to the time of day served by a Network Time Protocol (NTP) server. The relay uses a simplified version of NTP called the Simple Network Time Protocol (SNTP). SNTP is not as accurate as IRIG-B. The relay can use SNTP as a less accurate primary time source, or as a backup to the higher accuracy IRIG-B time source.

SNTP as Primary or Backup Time Source

If an IRIG-B time source is connected and either Relay Word bit TSOK or Relay Word bit IRIGOK asserts, then the relay synchronizes the internal time-of-day clock to the incoming IRIG-B time code signal, even if SNTP is configured in the relay and an NTP server is available. If the IRIG-B source is disconnected (if both TSOK and IRIGOK deassert) then the relay synchronizes the internal time-of-day clock to the NTP server, if available. In this way, an NTP server acts either as the primary time source or as a backup time source to the more accurate IRIG-B time source.

Creating an NTP Server

Three SEL application notes, available from the SEL website, describe how to create an NTP server.

- *AN2009-10: Using an SEL-2401, SEL-2404, or SEL-2407 to Serve NTP Via the SEL-3530 RTAC*
- *AN2009-32: Using SEL Satellite-Synchronized Clocks With the SEL-3332 or SEL-3351 to Output NTP*
- *Using an SEL-2401, SEL-2404, or SEL-2407 to Create a Stratum 1 Linux NTP Server*

Configuring SNTP Client in the Relay

To enable SNTP in the relay, make Port 1 setting ESNTTP = UNICAST, MANYCAST, or BROADCAST. Table 7.4 shows each setting associated with SNTP.

Table 7.4 Settings Associated With SNTP

| Setting | Range | Description |
|----------|------------------------------|--|
| ESNTTP | UNICAST, MANYCAST, BROADCAST | Selects the mode of operation of SNTP. See descriptions in <i>SNTP Operation Modes</i> on page 7.13. |
| SNTPPSIP | Valid IP Address | Selects primary NTP server when ENSTP = UNICAST, or broadcast address when ESNTTP = MANYCAST or BROADCAST. |
| SNTPPSIB | Valid IP Address | Selects backup NTP server when ESNTTP = UNICAST. |
| SNTPPORT | 1–65534 | Ethernet port used by SNTP. Leave at default value unless otherwise required. |
| SNTPRATE | 15–3600 seconds | Determines the rate at which the relay asks for updated time from the NTP server when ESNTTP = UNICAST or MANYCAST. Determines the time the relay will wait for an NTP broadcast when ENSTP = BROADCAST. |
| SNTPTO | 5–20 seconds | Determines the time the relay will wait for the NTP master to respond when ENSTP = UNICAST or MANYCAST. |

SNTP Operation Modes

The following sections explain the setting associated with each SNTP operation mode (UNICAST, MANYCAST, and BROADCAST).

ESNTTP = UNICAST

In UNICAST mode of operation, the SNTP client in the relay requests time updates from the primary (IP address setting SNTPPSIP) or backup (IP address setting SNTPBSIP) NTP server at a rate defined by setting SNTPRATE. If the NTP server does not respond with the period defined by setting SNTPTO, then the relay tries the other SNTP server. When the relay successfully synchronizes to the primary NTP time server, Relay Word bit TSNTTP asserts. When the relay successfully synchronizes to the backup NTP time server, Relay Word bit TSNTPB asserts.

ESNTTP = MANYCAST

In the MANYCAST mode of operation, the relay initially sends an NTP request to the broadcast address contained in setting SNTPPSIP. The relay continues to broadcast requests at a rate defined by setting SNTPRATE. When a server replies, the relay considers that server to be the primary NTP server, and switches to UNICAST mode, asserts Relay Word bit TSNTTP, and thereafter requests updates from the primary server. If the NTP server stops responding for time SNTPTO, the relay deasserts TSNTTP and begins to broadcast requests again until the original or another server responds.

ESNTTP = BROADCAST

If setting SNTPPSIP = 0.0.0.0 while setting ESNTTP = BROADCAST, the relay will listen for and synchronize to any broadcasting NTP server. If setting SNTPPSIP is set to a specific IP address while setting ESNTTP =

BROADCAST, then the relay will listen for and synchronize to only NTP server broadcasts from that address. When synchronized, the relay asserts Relay Word bit TSNTTP. Relay Word bit TNSTTP deasserts if the relay does not receive a valid broadcast within five seconds after the period defined by setting SNTPRATE.

SNTP Accuracy Considerations

SNTP time synchronization accuracy is limited by the accuracy of the SNTP Server and by the networking environment. The highest degree of SNTP time synchronization can be achieved by minimizing the number of switches and routers between the SNTP Server and the SEL-787. Network monitoring software can also be used to ensure that average and worst-case network bandwidth use is moderate.

When installed on a network configured with one Ethernet switch between the SEL-787 and the SNTP Server, and when using ESNTTP = UNICAST or MANYCAST, the relay time synchronization error with the SNTP server is typically less than ± 1 millisecond.

SEL ASCII Protocol and Commands

Message Format

SEL ASCII protocol is designed for manual and automatic communication. All commands the relay receives must be of the following form:

```
<command><CR> or <command><CRLF>
```

NOTE: The **<Enter>** key on most keyboards is configured to send the ASCII character 13 (**<Ctrl+M>**) for a carriage return. This manual instructs you to press the **<Enter>** key after commands to send the proper ASCII code to the SEL-787.

A command transmitted to the relay consists of the command followed by either a CR (carriage return) or a CRLF (carriage return and line feed). You can truncate commands to the first three characters. For example, **EVENT 1 <Enter>** becomes **EVE 1 <Enter>**. Use upper- and lowercase characters without distinction, except in passwords.

The relay transmits all messages in the following format:

```
<STX><MESSAGE LINE 1><CRLF>
<MESSAGE LINE 2><CRLF>
.
.
.
<LAST MESSAGE LINE><CRLF><ETX>
```

Each message begins with the start-of-transmission character (ASCII 02) and ends with the end-of-transmission character (ASCII 03). Each line of the message ends with a carriage return and line feed.

Software Flow Control

The relay implements XON/XOFF flow control. You can use the XON/XOFF protocol to control the relay during data transmission. When the relay receives XOFF during transmission, it pauses until it receives an XON character. If there is no message in progress when the relay receives XOFF, it blocks transmission of any message presented to the relay input buffer. Messages will be accepted after the relay receives XON.

The relay transmits XON (ASCII hex 11) and asserts the RTS output (if hardware handshaking is enabled) when the relay input buffer drops below 25 percent full.

The relay transmits XOFF (ASCII hex 13) when the buffer is more than 75 percent full. If hardware handshaking is enabled, the relay deasserts the RTS output when the buffer is approximately 95 percent full. Automatic transmission sources should monitor for the XOFF character to avoid overwriting the buffer. Transmission should terminate at the end of the message in progress when XOFF is received and can resume when the relay sends XON.

The CAN character (ASCII hex 18) aborts a pending transmission. This is useful for terminating an unwanted transmission. You can send control characters from most keyboards with the following keystrokes:

- XOFF: <Ctrl+S> (hold down the <Ctrl> key and press S)
- XON: <Ctrl+Q> (hold down the <Ctrl> key and press Q)
- CAN: <Ctrl+X> (hold down the <Ctrl> key and press X)

Automatic Messages

When the serial port AUTO setting is Y, the relay sends automatic messages to indicate specific conditions. *Table 7.5* lists these messages.

Table 7.5 Serial Port Automatic Messages

| Condition | Description |
|------------------------------|--|
| Power Up | The relay sends a message containing the present date and time, Relay and Terminal Identifiers, and the Access Level 0 prompt when the relay is turned on. |
| Event Trigger | The relay sends an event summary each time an event report is triggered. See <i>Section 9: Analyzing Events</i> . |
| Self-Test Warning or Failure | The SEL-787 sends a status report each time a self-test warning or failure condition is detected. See <i>STATUS Command (Relay Self-Test Status)</i> on page 7.40. |

Access Levels

Commands can be issued to the SEL-787 via the serial port or Ethernet Telnet session to view metering values, change relay settings, etc. The available serial port commands are listed in the *SEL-787 Relay Command Summary* at the end of this manual. These commands can be accessed only from the corresponding access level, as shown in the *SEL-787 Relay Command Summary*. The access levels are:

- Access Level 0 (the lowest access level)
- Access Level 1
- Access Level 2 (the highest access level)
- Access Level C (restricted access level, should be used under direction of SEL only)

Access Level 0

Once serial port communication is established with the SEL-787, the relay sends the following prompt:

```
=====
=
```

This is referred to as Access Level 0. Only a few commands are available at Access Level 0. One is the **ACC** command. See the *SEL-787 Relay Command Summary* at the end of this manual. Enter the **ACC** command at the Access Level 0 prompt:

```
=ACC <Enter>
```

The **ACC** command takes the SEL-787 to Access Level 1. See *Access Commands (ACCESS, 2ACCESS, and CAL)* on page 7.18 for more detail.

Access Level 1

When the SEL-787 is in Access Level 1, the relay sends the following prompt:

```
=>
```

See the *SEL-787 Relay Command Summary* at the end of this manual for the commands available from Access Level 1. The relay can go to Access Level 2 from this level.

The **2AC** command places the relay in Access Level 2. See *Access Commands (ACCESS, 2ACCESS, and CAL)* for more detail. Enter the **2AC** command at the Access Level 1 prompt:

```
=>2AC <Enter>
```

Access Level 2

When the relay is in Access Level 2, the SEL-787 sends the prompt:

```
=>>
```

See the *SEL-787 Relay Command Summary* at the end of this manual for the commands available from Access Level 2.

Any of the Access Level 1 commands are also available in Access Level 2.

Access Level C

The **CAL** access level is used exclusively by the SEL factory and SEL field service personnel to diagnose troublesome installations. A list of **CAL** level commands is available from SEL upon request. Do not enter the **CAL** access level, except as directed by SEL.

The **CAL** command allows the relay to go to Access Level C. Enter the **CAL** command at the Access Level 2 prompt:

```
=>>CAL <Enter>
```

Command Summary

The *SEL-787 Relay Command Summary* at the end of this manual lists the serial port commands alphabetically. Much of the information available from the serial port commands is also available via the front-panel pushbuttons.

Access Level Functions

The serial port commands at the different access levels offer varying levels of control:

- The Access Level 0 commands provide the first layer of security. In addition, Access Level 0 supports several commands required by SEL communications processors.
- The Access Level 1 commands are primarily for reviewing information only (settings, metering, etc.), not changing it.
- The Access Level 2 commands are primarily for changing relay settings.
- Access Level C (restricted access level, should be used under the direction of SEL only)

The SEL-787 responds with `Invalid Access Level` when a command is entered from an access level lower than the specified access level for the command. The relay responds with `Invalid Command` to commands that are not available or are entered incorrectly.

Header

Many of the command responses display the following header at the beginning:

| | |
|---------------|-------------------------------------|
| [RID Setting] | Date: mm/dd/yyyy Time: hh:mm:ss.sss |
| [TID Setting] | Time Source: external |

Table 7.6 lists the header items and their definitions.

Table 7.6 Command Response Header Definitions

| Item | Definition |
|----------------|---|
| [RID Setting]: | This is the RID (Relay Identifier) setting. The relay ships with the default setting RID = SEL-787; see <i>ID Settings on page 4.2</i> . |
| [TID Setting]: | This is the TID (Terminal Identifier) setting. The relay ships with the default setting TID = TRNSFRMR RELAY; see <i>ID Settings on page 4.2</i> . |
| Date: | This is the date when the command response was given, except for relay response to the EVE command (Event), when it is the date the event occurred. You can modify the date display format (Month/Day/Year, Year/Month/Day, or Day/Month/Year) by changing the DATE_F relay setting. |
| Time: | This is the time when the command response was given, except for relay response to the EVE command, when it is the time the event occurred. |
| Time Source: | This is internal if no time-code input is attached and external if an input is attached. |

Command Explanations

This section lists ASCII commands alphabetically. Commands, command options, and command variables to enter are shown in bold. Lowercase italic letters and words in a command represent command variables that are determined based on the application.

Command options appear with brief explanations about the command function. Refer to the references listed with the commands for more information on the control function corresponding to the command or examples of the control response to the command.

You can simplify the task of entering commands by shortening any ASCII command to the first three characters; for example, **ACCESS** becomes **ACC**. Always send a carriage return <CR> character or a carriage return character

followed by a line feed character **<CR><LF>** to command the control to process the ASCII command. Usually, most terminals and terminal programs interpret the Enter key as a **<CR>**. For example, to send the **ACCESS** command, type **ACC <Enter>**.

Tables in this section show the access level(s) where the command or command option is active. Access levels in this device are Access Level 0, Access Level 1, and Access Level 2.

Access Commands (ACCESS, 2ACCESS, and CAL)

The **ACC**, **2AC**, and **CAL** commands (see *Table 7.7*) provide entry to the multiple access levels. Different commands are available at the different access levels, as shown in the *SEL-787 Relay Command Summary* at the end of this manual. Commands **ACC** and **2AC** are explained together because they operate similarly. See *Access Levels on page 7.15* for a discussion of placing the relay in an access level.

Table 7.7 Access Commands

| Command | Description | Access Level |
|------------|--|--------------|
| ACC | Moves from Access Level 0 to Access Level 1. | 0 |
| 2AC | Moves from Access Level 1 to Access Level 2. | 1 |
| CAL | Moves from Access Level 2 to Access Level C. | 2 |

Password Requirements

Passwords are required unless they are disabled. See *PASSWORD Command (Change Passwords) on page 7.33* for the list of default passwords and for more information on changing and disabling passwords.

Access Level Attempt (Password Required). Assume the following conditions:

- Access Level 1 password is not disabled.
- Access Level is 0.

At the Access Level 0 prompt, enter the **ACC** command:

```
=ACC <Enter>
```

Because the password is not disabled, the relay prompts you for the Access Level 1 password:

```
Password: ?
```

The relay is shipped with the default Access Level 1 password shown in *PASSWORD Command (Change Passwords) on page 7.33*. At the prompt, enter the default password and press the **<Enter>** key. The relay responds with the following:

```
[RID Setting]                               Date: mm/dd/yyyy Time: hh:mm:ss
[TID Setting]                               Time Source: external

Level 1
=>
```


The => prompt indicates the relay is now in Access Level 1.

If the entered password is incorrect, the relay prompts you for the password again (Password: ?). The relay prompts for the password as many as three times. If the requested password is incorrectly entered three times, the relay pulses the SALARM Relay Word bit for one second and remains at Access Level 0 (= prompt).

Access Level Attempt (Password Not Required). Assume the following conditions:

- Access Level 1 password is disabled.
- Access Level is 0.

At the Access Level 0 prompt, enter the **ACC** command:

```
=ACC <Enter>
```

Because the password is disabled, the relay does not prompt you for a password and goes directly to Access Level 1. The relay responds with the following:

```
[RID Setting]           Date: mm/dd/yyyy Time: hh:mm:ss.sss
[TID Setting]           Time Source: external
Level 1
=>
```

The => prompt indicates the relay is now in Access Level 1.

The two previous examples demonstrate going from Access Level 0 to Access Level 1. The procedure to go from Access Level 1 to Access Level 2 with the **2AC** command entered at the access level screen prompt is similar. Access Level C can be accessed from Access Level 2 with the **CAL** command. The relay pulses the SALARM Relay Word bit for one second after a successful Level 2 or Level C access, or if access is denied.

ANALOG Command

Use the **ANA** command to test an analog output by temporarily assigning a value to an analog output channel (see *Table 7.8* for the command description and *Table 7.9* for the format). After entering the **ANA** command, the device suspends normal operation of the analog output channel and scales the output to a percentage of full scale. After assigning the specified value for the specified time, the device returns to normal operation.

Entering any character (including pressing the space key) ends the command before reaching the specified interval completion. You can test the analog output in one of the following two modes:

- Fixed percentage: Outputs a fixed percentage of the signal for a specified duration
- Ramp: Ramps the output from minimum to maximum of full scale over the time specified

Table 7.8 ANALOG Command

| Command | Description | Access Level |
|------------------|--|--------------|
| ANA c p t | Temporarily assigns a value to an analog output channel. | 2 |

Table 7.9 ANALOG Command Format

| Parameter | Description |
|-----------|--|
| c | Parameter <i>c</i> is the analog channel (either the channel name, e.g., A0301, or the channel number, e.g., 301). |
| p | Parameter <i>p</i> is a percentage of full scale, or either the letter “R” or “r” to indicate ramp mode. |
| t | Parameter <i>t</i> is the duration (in decimal minutes) of the test. |

NOTE: 0% = low span, 100% = high span. For a scaled output from 4-20 mA, 0 percent is 4 mA and 100 percent is 20 mA.

When parameter *p* is a percentage, the relay displays the following message during the test:

Outputting xx.xx [units] to Analog Output Port for y.y minutes. Press any key to end test

where:

xx.xx is the calculation of percent of full scale
[units] is either mA or V, depending on the channel type setting
y.y is the time in minutes

When parameter *p* is a ramp function, the device displays the following message during the test:

Ramping Analog Output at xx.xx [units]/min; full scale in y.y minutes. Press any key to end test

where:

xx.xx is the calculation based upon range/time t
[units] is either mA or V, depending on the channel type setting
y.y is the time in minutes

For either mode of operation (percentage or ramp), when the time expires, or upon pressing a key, the analog output port returns to normal operation and the device displays the following message:

Analog Output Port Test Complete

Example 1

The following is an example of the device response to the **ANA** command in the percentage mode. For this example, we assume the analog output signal type is 4–20 mA, and we want to test the analog output at 75 percent of rating for 5.5 minutes. To check the device output, calculate the expected mA output as follows:

$$\text{Output} = \left[(20.00 \text{ mA} - 4.00 \text{ mA}) \cdot \frac{75}{100} \right] + 4.00 \text{ mA} = 16.00 \text{ mA}$$

To start the test, enter **ANA A0301 75 5.5** at the Access Level 2 prompt:

```
=>>ANA A0301 75 5.5 <Enter>
Outputting 16.00 mA to Analog Output Port for 5.5 minutes.
Press any key to end test
```

Example 2

The following is an example of the ramp mode when the analog output signal type is 4–20 mA for a 9.0 minute test. To check the device output, calculate the current/time (mA/min) output as follows:

$$\text{Output} = \left[\frac{20.00 \text{ mA} - 4.00 \text{ mA}}{9.0 \text{ min}} \right] = 1.78 \text{ mA/min}$$

To start the test, enter **ANA AO301 R 9.0** at the Access Level 2 prompt:

```
=>>ANA AO301 R 9.0 <Enter>
Ramping Analog Output at 1.78 mA/min; full scale in 9.0 minutes.
Press any key to end test
```

CEV Command

The SEL-787 provides Compressed ASCII event reports to facilitate event report storage and display. SEL communications processors and ACSELERATOR Analytic Assistant SEL-5601 Software take advantage of the Compressed ASCII format. Use the **CHIS** command to display Compressed ASCII event history information. Use the **CSUM** command to display Compressed ASCII event summary information. Use the **CEVENT (CEV)** command to display Compressed ASCII event reports. See *Table C.2* for further information. Compressed ASCII Event Reports contain all of the Relay Word bits. **CEV R** command gives the raw Compressed ASCII event report.

CLOSE n Command (Close Breaker n, where n = 1 or 2)

The **CLO n** (CLOSE *n*) command asserts Relay Word bit CC*n* for 1/4 cycle when it is executed. Relay Word bit CC*n* can then be programmed into the CL*n* SELOGIC control equation to assert the CLOSE *n* Relay Word bit, which in turn asserts an output contact (e.g., OUT102 = CLOSE1) to close circuit breaker *n* (see *Table 4.25* and *Figure 4.50* for factory-default settings CL1 and CL2 and close logic).

To issue the **CLO 1** command, enter the following.

```
=>>CLO 1 <Enter>
Close Breaker1 (Y,N)? Y <Enter>
=>>
```

Typing **N <Enter>** after the above prompt will abort the command.

The **CLO n** commands are supervised by the main board breaker control jumper (see *Table 2.12*). If the breaker control jumper is not in place (breaker control jumper = OFF), the relay does not execute the **CLO n** command and responds with the following.

```
=>>CLO 1 <Enter>
Command Aborted: No Breaker Jumper
=>>
```

COMMUNICATIONS Command

The **COM x** command (see *Table 7.10*) displays communications statistics for the MIRRORRED BITS communications channels. For more information on MIRRORRED BITS communications, see *Appendix I: Mirrored Bits Communications*. The summary report includes information on the failure of ROKA or ROKB. The *Last error* field displays the reason for the most recent channel error, even if the channel was already failed. We define failure reasons as one of the following error types:

- Device disabled
- Framing error
- Parity error
- Overrun
- Re-sync
- Data error
- Loopback
- Underrun

Table 7.10 COM Command

| Command | Description | Access Level |
|----------------------------------|--|--------------|
| COM S A or COM S B | Return a summary report of the last 255 records in the communications buffer for either MIRRORRED BITS communications Channel A or Channel B when only one channel is enabled. | 1 |
| COM A | Return a summary report of the last 255 records in the communications buffer for MIRRORRED BITS communications Channel A. | 1 |
| COM B | Return a summary report of the last 255 records in the communications buffer for MIRRORRED BITS communications Channel B. | 1 |
| COM L A | Appends a long report to the summary report of the last 255 records in the communications buffer for MIRRORRED BITS communications Channel A. | 1 |
| COM L B | Appends a long report to the summary report of the last 255 records in the communications buffer for MIRRORRED BITS communications Channel B. | 1 |
| COM C | Clears all communications records. If both MIRRORRED BITS channels are enabled, omitting the channel specifier (A or B) clears both channels. | 1 |
| COM C A | Clears all communications records for Channel A. | 1 |
| COM C B | Clears all communications records for Channel B. | 1 |

CONTROL Command (Control Remote Bit)

Use the **CON** command (see *Table 7.11*) to control remote bits (Relay Word bits RB01–RB32). You can use the **CON** function from the front panel (*Control > Outputs*) to pulse the outputs. Remote bits are device variables that you set via serial port communication only; you cannot navigate Remote Bits via the front-panel HMI. You can select the control operation from three states: set, clear, or pulse, as described in *Table 7.12*.

Table 7.11 CONTROL Command

| Command | Description | Access Level |
|---|---|--------------|
| CON RBnn^a k^b | Set a Remote Bit to set, clear, or pulse. | 2 |

^a Parameter nn is a number from 01 to 32, representing RB01 through RB32.

^b Parameter k is S, C, or P.

Table 7.12 Three Remote Bit States

| Subcommand | Description | Access Level |
|------------|---|--------------|
| S | Set Remote bit (ON position) | 2 |
| C | Clear Remote bit (OFF position) | 2 |
| P | Pulse Remote bit for 1/4 cycle (MOMENTARY position) | 2 |

For example, use the following command to set Remote bit RB05:

```
=>>CON RB05 S <Enter>
```

COPY Command

Use the **COPY *j k*** command (see *Table 7.13*) to copy the settings of settings Group *j* to the settings of settings Group *k*. The settings of settings Group *j* effectively overwrite the settings of settings Group *k*. Parameters *j* and *k* can be any available settings group number 1 through 4.

Table 7.13 COPY Command

| Command | Description | Access Level |
|------------------------------------|---|--------------|
| COPY <i>j k</i>^a | Copy settings in Group <i>j</i> to settings in Group <i>k</i> . | 2 |

^a Parameters *j* and *k* are 1-4.

For example when you enter the **COPY 1 3** command, the relay responds, Are you sure (Y/N)? Answer **Y <Enter>** (for yes) to complete copying. The resultant settings in Group 3 are overwritten by the settings in Group 1 and pulse the SALARM Relay Word bit.

COUNTER Command (Counter Values)

The device generates the values of the 32 counters in response to the **COU** command (see *Table 7.14*).

Table 7.14 COUNTER Command

| Command | Description | Access Level |
|---------------------|---|--------------|
| COU <i>n</i> | Display current state of device counters <i>n</i> times, with a 1/2-second delay between each display | 1 |

DATE Command (View/Change Date)

Use the **DATE** command (see *Table 7.15*) to view and set the relay date.

Table 7.15 Date Command

| Command | Description | Access Level |
|-------------------------|---|--------------|
| DATE | Display the internal clock date. | 1 |
| DATE <i>date</i> | Set the internal clock date (DATE_F set to MDY, YMD, or DMY). | 1 |

The relay can overwrite the date entered by using other time sources such as IRIG. Enter the **DATE** command with a date to set the internal clock date.

Separate the month, day, and year parameters with spaces, commas, slashes, colons, and semicolons. Set the year in 4-digit form (for dates 2000–2099). Global setting DATE_F sets the date format.

ETH Command

The **ETH** command (Access Level 1) may be used to display the Ethernet port (**Port 1**) status as shown in *Figure 7.16* for the redundant fiber-optic (FX) Ethernet **Port 1A** and **Port 1B** configuration. Copper Ethernet port is labelled as TX. The non-redundant port response is similar.

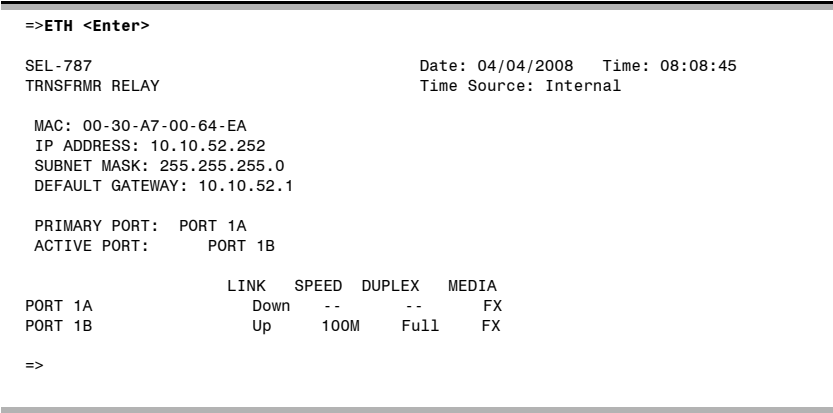


Figure 7.16 Ethernet Port (PORT 1) Status Report

The non-redundant port response is as shown in the example below.

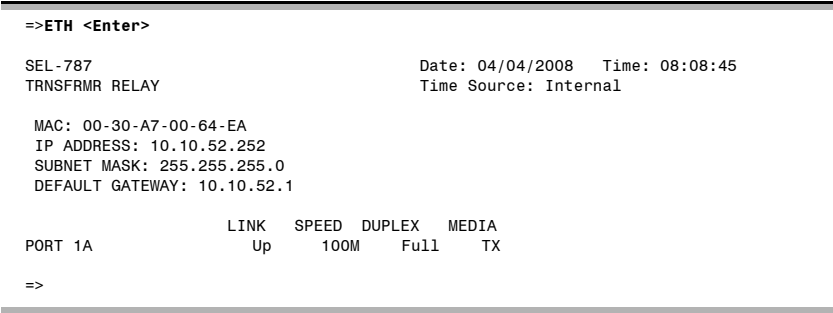


Figure 7.17 Non-Redundant Port Response

EVENT Command (Event Reports)

Use the **EVE** command (see *Table 7.16* and *Table 7.17*) to view event reports. See *Section 9: Analyzing Events* for further details on retrieving and analyzing event reports. See the *HISTORY Command* on page 7.28 for details on clearing event reports.

Table 7.16 EVENT Command (Event Reports) (Sheet 1 of 2)

| Command | Description | Access Level |
|-----------------------|--|--------------|
| EVE n | Return the n event report with 4-samples/cycle data. | 1 |
| EVE n R or EVE R n | Return the n event report with raw (unfiltered) 16 samples/cycle analog data and 4 samples/cycle digital data. | 1 |
| EVE D n | Return the n digital data event report with 4-samples/cycle data. | 1 |

Table 7.16 EVENT Command (Event Reports) (Sheet 2 of 2)

| Command | Description | Access Level |
|--------------------------|---|--------------|
| EVE D <i>n</i> R | Return the <i>n</i> digital data event report with 16-samples/cycle data. | 1 |
| EVE DIF1 <i>n</i> | Return the <i>n</i> differential element 1 event report, with 4-samples/cycle data. | 1 |
| EVE DIF2 <i>n</i> | Return the <i>n</i> differential element 2 event report, with 4-samples/cycle data. | 1 |
| EVE DIF3 <i>n</i> | Return the <i>n</i> differential element 3 event report, with 4-samples/cycle data. | 1 |

Table 7.17 EVENT Command Format

| Parameter | Description |
|-----------|--|
| <i>n</i> | Parameter <i>n</i> specifies the event report number to be returned. Use the HIS command to determine the event report number of the event you want to display. If <i>n</i> is not specified, the relay will display event report 1 by default. |

FILE Command

The **FIL** command (see *Table 7.18*) is intended to be a safe and efficient means of transferring files between intelligent electronic devices (IEDs) and external support software (ESS). The **FIL** command ignores the hide rules and transfers visible as well as hidden settings, except the settings hidden by a part number. Use FTP or Telnet over Ethernet to transfer files.

Table 7.18 FILE Command

| Command | Description | Access Level |
|----------------------------------|--|--------------|
| FIL DIR | Return a list of files. | 1 |
| FIL READ <i>filename</i> | Transfer settings file <i>filename</i> from the relay to the PC. | 1 |
| FIL WRITE <i>filename</i> | Transfer settings file <i>filename</i> from the PC to the relay. | 2 |
| FIL SHOW <i>filename</i> | Filename 1 displays contents of the file <i>filename</i> . | 1 |

GOOSE Command

Use the **GOOSE** command to display transmit and receive GOOSE messaging information, which can be used for troubleshooting. The **GOOSE** command variants and options are shown in *Table 7.19*.

Table 7.19 GOOSE Command Variants

| Command Variant | Description | Access Level |
|--------------------|--|--------------|
| GOOSE | Display GOOSE information. | 1 |
| GOOSE count | Display GOOSE information count times. | 1 |

The following table describes the information displayed for each GOOSE IED.

| IED | Description | | | | | | | | | | | | | | | | |
|-----------------------------------|--|-------------------|-------------|----------------|-----------------------|----------------|---------------------------------|----------------|---------------------|-----------|-----------|---------------|-------------------|-------------|----------------------|---------------|--|
| Transmit GOOSE Control Reference | This field represents the GOOSE control reference information that includes the IED name, IdInst (Logical Device Instance), LN0 InClass (Logical Node Class), and GSEControl name (GSE Control Block Name) (e.g., SEL_787_1CFG/LLN0\$GO\$GooseDSet13). | | | | | | | | | | | | | | | | |
| Receive GOOSE Control Reference | This field represents the goCbRef (GOOSE Control Block Reference) information that includes the iedName (IED name), IdInst (Logical Device Instance), LN0 InClass (Logical Node Class), and cbName (GSE Control Block Name) (e.g., SEL_787_1CFG/LLN0\$GO\$GooseDSet13). | | | | | | | | | | | | | | | | |
| MultiCastAddr (Multicast Address) | This hexadecimal field represents the GOOSE multicast address. | | | | | | | | | | | | | | | | |
| Ptag | This three-bit decimal field represents the priority tag value, where spaces are used if the priority tag is unknown. | | | | | | | | | | | | | | | | |
| Vlan | This 12-bit decimal field represents the virtual LAN (Local Area Network) value, where spaces are used if the virtual LAN is unknown. | | | | | | | | | | | | | | | | |
| StNum (State Number) | This hexadecimal field represents the state number that increments with each state change. | | | | | | | | | | | | | | | | |
| SqNum (Sequence Number) | This hexadecimal field represents the sequence number that increments with each GOOSE message sent. | | | | | | | | | | | | | | | | |
| TTL (Time to Live) | This field contains the time (in ms) before the next message is expected. | | | | | | | | | | | | | | | | |
| Code | <p>This text field contains warning or error condition text when appropriate that is abbreviated as follows:</p> <table> <tr> <th>Code Abbreviation</th><th>Explanation</th></tr> <tr> <td>OUT OF SEQUENC</td><td>Out of sequence error</td></tr> <tr> <td>CONF REV MISMA</td><td>Configuration Revision mismatch</td></tr> <tr> <td>NEED COMMISSIO</td><td>Needs Commissioning</td></tr> <tr> <td>TEST MODE</td><td>Test Mode</td></tr> <tr> <td>MSG CORRUPTED</td><td>Message Corrupted</td></tr> <tr> <td>TTL EXPIRED</td><td>Time to live expired</td></tr> <tr> <td>HOST DISABLED</td><td>Optional code for when the host is disabled or becomes unresponsive after the GOOSE command has been issued</td></tr> </table> | Code Abbreviation | Explanation | OUT OF SEQUENC | Out of sequence error | CONF REV MISMA | Configuration Revision mismatch | NEED COMMISSIO | Needs Commissioning | TEST MODE | Test Mode | MSG CORRUPTED | Message Corrupted | TTL EXPIRED | Time to live expired | HOST DISABLED | Optional code for when the host is disabled or becomes unresponsive after the GOOSE command has been issued |
| Code Abbreviation | Explanation | | | | | | | | | | | | | | | | |
| OUT OF SEQUENC | Out of sequence error | | | | | | | | | | | | | | | | |
| CONF REV MISMA | Configuration Revision mismatch | | | | | | | | | | | | | | | | |
| NEED COMMISSIO | Needs Commissioning | | | | | | | | | | | | | | | | |
| TEST MODE | Test Mode | | | | | | | | | | | | | | | | |
| MSG CORRUPTED | Message Corrupted | | | | | | | | | | | | | | | | |
| TTL EXPIRED | Time to live expired | | | | | | | | | | | | | | | | |
| HOST DISABLED | Optional code for when the host is disabled or becomes unresponsive after the GOOSE command has been issued | | | | | | | | | | | | | | | | |
| Transmit Data Set Reference | This field represents the DataSetReference (Data Set Reference) that includes the IED name, LN0 InClass (Logical Node Class), and GSEControl datSet (Data Set Name) (e.g., SEL_787_1/LLN0\$DSet13). | | | | | | | | | | | | | | | | |
| Receive Data Set Reference | This field represents the datSetRef (Data Set Reference) that includes the iedName (IED name), IdInst (Logical Device Instance), LN0 InClass (Logical Node Class), and datSet (Data Set Name) (e.g., SEL_787_1CFG/LLN0\$DSet13). | | | | | | | | | | | | | | | | |

An example response to the **GOOSE** commands is shown in *Figure 7.18*.

```
#>GOOSE <Enter>
```

GOOSE Transmit Status

| MultiCastAddr | Ptag:Vlan | StNum | SqNum | TTL | Code |
|-------------------------------------|-----------|-------|-------|-----|------|
| ----- | | | | | |
| SEL_787_2CFG/LLN0\$G0\$GooseDSet13 | | | | | |
| 01-0C-CD-01-00-04 | 4:1 | 2 | 20376 | 50 | |
| Data Set: SEL_787_2CFG/LLN0\$DSet13 | | | | | |

GOOSE Receive Status

| MultiCastAddr | Ptag:Vlan | StNum | SqNum | TTL | Code |
|---|-----------|-------|--------|-----|------|
| ----- | | | | | |
| SEL_787_1CFG/LLN0\$G0\$NewGOOSEMessage5 | | | | | |
| 01-0C-CD-01-00-05 | 4:0 | 1 | 100425 | 160 | |
| Data Set: SEL_787_1CFG/LLN0\$DSet10 | | | | | |
| SEL_787_1CFG/LLN0\$G0\$NewGOOSEMessage3 | | | | | |
| 01-0C-CD-01-00-03 | 4:0 | 1 | 98531 | 120 | |
| Data Set: SEL_787_1CFG/LLN0\$DSet05 | | | | | |

GOOSE Receive Status

| MultiCastAddr | Ptag:Vlan | StNum | SqNum | TTL | Code |
|--|-----------|-------|--------|-----|------|
| ----- | | | | | |
| SEL_787_1CFG/LLN0\$G0\$NewGOOSEMessage5 | | | | | |
| 01-0C-CD-01-00-05 | 4:0 | 1 | 100425 | 160 | |
| Data Set: SEL_787_1CFG/LLN0\$DSet10 | | | | | |
| SEL_787_1CFG/LLN0\$G0\$NewGOOSEMessage3 | | | | | |
| 01-0C-CD-01-00-03 | 4:0 | 1 | 98531 | 120 | |
| Data Set: SEL_787_1CFG/LLN0\$DSet05 | | | | | |
| SEL_787_1CFG/LLN0\$G0\$NewGOOSEMessage2 | | | | | |
| 01-0C-CD-01-00-02 | 4:0 | 1 | 97486 | 200 | |
| Data Set: SEL_787_1CFG/LLN0\$DSet04 | | | | | |
| SEL_787_1CFG/LLN0\$G0\$NewGOOSEMessage1 | | | | | |
| 01-0C-CD-01-00-01 | 4:0 | 1 | 96412 | 190 | |
| Data Set: SEL_787_1CFG/LLN0\$DSet03 | | | | | |
| SEL_387E_1CFG/LLN0\$G0\$NewGOOSEMessage5 | | | | | |
| 01-0C-CD-01-00-06 | 4:0 | 1 | 116156 | 140 | |
| Data Set: SEL_387E_1CFG/LLN0\$DSet10 | | | | | |
| SEL_387E_1CFG/LLN0\$G0\$NewGOOSEMessage4 | | | | | |
| 01-0C-CD-01-00-05 | 4:0 | 1 | 116041 | 130 | |
| Data Set: SEL_387E_1CFG/LLN0\$DSet06 | | | | | |
| SEL_387E_1CFG/LLN0\$G0\$NewGOOSEMessage2 | | | | | |
| 01-0C-CD-01-00-02 | 4:0 | 1 | 115848 | 120 | |
| Data Set: SEL_387E_1CFG/LLN0\$DSet04 | | | | | |
| SEL_387E_1CFG/LLN0\$G0\$NewGOOSEMessage1 | | | | | |
| 01-0C-CD-01-00-01 | 4:0 | 1 | 115798 | 150 | |
| Data Set: SEL_387E_1CFG/LLN0\$DSet03 | | | | | |

=>

Figure 7.18 GOOSE Command Response

GROUP Command

Use the **GROUP** command (see *Table 7.20*) to display the active settings group or try to force an active settings group change.

Table 7.20 GROUP Command

| Command | Description | Access Level |
|-----------------------------------|---|--------------|
| GROUP | Display the active settings group. | 1 |
| GROUP <i>n</i>^a | Change the active group to Group <i>n</i> . | 2 |

^a Parameter *n* indicates group numbers 1-4.

When you change the active group, the relay responds with a confirmation prompt: Are you sure (Y/N)? Answer **Y** <Enter> to change the active group. The relay asserts the Relay Word bit SALARM for one second when you change the active group.

If any of the SELOGIC control equations SS1–SS3 are set when you issue the **GROUP *n*** command, the group change will fail. The relay responds: Command Unavailable: Active setting group SELOGIC equations have priority over the GROUP command.

HELP Command

The **HELP** command (see *Table 7.21*) gives a list of commands available at the present access level. You can also get a description of any particular command; type **HELP** followed by the name of the command for help on each command.

Table 7.21 HELP Command

| Command | Description | Access Level |
|----------------------------|---|--------------|
| HELP | Display a list of each command available at the present access level with a one-line description. | 1 |
| HELP <i>command</i> | Display information on the command. | 1 |

HISTORY Command

Use the **HIS** command (see *Table 7.22*) to view a list of one-line descriptions of relay events or clear the list (and corresponding event reports) from nonvolatile memory. For more information on event reports, see *Section 9: Analyzing Events*.

Table 7.22 HISTORY Command

| Command | Description | Access Level |
|---------------------|--|--------------|
| HIS | Return event histories with the oldest at the bottom of the list and the most recent at the top of the list. | 1 |
| HIS <i>n</i> | Return event histories with the oldest at the bottom of the list and the most recent at the top of the list, beginning at event <i>n</i> . | 1 |
| HIS C or R | Clear/reset the event history and all corresponding event reports from nonvolatile memory. | 1 |

IDENTIFICATION Command

Use the **ID** command (see *Table 7.23*) to extract device identification codes.

Table 7.23 IDENTIFICATION Command

| Command | Description | Access Level |
|-----------|---|--------------|
| ID | Return a list of device identification codes. | 0 |

IRI Command

Use the **IRI** command to direct the relay to read the demodulated IRIG-B time code at the serial port or IRIG-B input (see *Table 7.24*).

Table 7.24 IRI Command

| Command | Description | Access Level |
|------------|--|--------------|
| IRI | Force synchronization of internal control clock to IRIG-B time-code input. | 1 |

To force the relay to synchronize to IRIG-B, enter the following command:

```
=>IRI <Enter>
```

If the relay successfully synchronizes to IRIG-B, it sends the following header and access level prompt:

```
SEL-787          Date: 12/10/2007 Time: 08:56:03.190
TRANSFRMR RELAY  Time Source: External
=>
```

If no IRIG-B code is present at the serial port input or if the code cannot be read successfully, the relay responds with **IRIG-B DATA ERROR**.

If an IRIG-B signal is present, the relay synchronizes its internal clock with IRIG-B. It is not necessary to issue the **IRI** command to synchronize the relay clock with IRIG-B. Use the **IRI** command to determine if the relay is properly reading the IRIG-B signal.

LDP Command (Load Profile Report)

Use the **LDP** commands (see *Table 7.25* and *Table 7.26*) to view and manage the Load Profile report (see *Figure 5.15*). If there is no stored data and an **LDP** command is issued, the relay responds with **No data available**.

Table 7.25 LDP Commands

| Command | Description | Access Level |
|--|--|--------------|
| LDP row1 row2 LDP date1 date2 | Use the LDP command to display a numeric progression of all load profile report rows. Use the LDP command with parameters to display a numeric or reverse numeric subset of the load profile rows. | 1 |
| LDP C | Use this command to clear the load profile report from nonvolatile memory. | 1 |

Table 7.26 LDP Command Parameters

| Parameter | Description |
|--------------------|--|
| <i>row1 row2</i> | Append <i>row1</i> to return a chronological progression of the first <i>row1</i> rows. Append <i>row1</i> and <i>row2</i> to return all rows between <i>row1</i> and <i>row2</i> , beginning with <i>row1</i> and ending with <i>row2</i> . Enter the smaller number first to display a numeric progression of rows through the report. Enter the larger number first to display a reverse numeric progression of rows. |
| <i>date1 date2</i> | Append <i>date1</i> to return all rows with this date. Append <i>date1</i> and <i>date2</i> to return all rows between <i>date1</i> and date beginning with <i>date1</i> and ending with <i>date2</i> . Enter the oldest date first to display a chronological progression through the report. Enter the newest date first to display a reverse chronological progression. Date entries are dependent on the date format setting DATE_F. |

L_D Command (Load Firmware)

Use the **L_D** command (see *Table 7.27*) to load firmware. See *Appendix A: Firmware and Manual Versions* for information on changes to the firmware and instruction manual. See *Appendix B: Firmware Upgrade Instructions* for further details on downloading firmware.

Table 7.27 L_D Command (Load Firmware)

| Command | Description | Access Level |
|------------|-----------------------------------|--------------|
| L_D | Download firmware to the control. | 2 |

Only download firmware to the front port.

LOOPBACK Command

The **LOO** command (see *Table 7.28*) is used for testing the MIRRORRED BITS communications channel for proper communication. For more information on MIRRORRED BITS, see *Appendix I: Mirrored Bits Communications*. With the transmitter of the communications channel physically looped back to the receiver, the MIRRORRED BITS addressing will be wrong and ROK will be deasserted. The **LOO** command tells the MIRRORRED BITS software to temporarily expect to see its own data looped back as its input. In this mode, LBOK will assert if error-free data are received. The **LOO** command with just the channel specifier, enables looped back mode on that channel for five minutes, while the inputs are forced to the default values.

Table 7.28 LOO Command

| Command | Description | Access Level |
|--------------|---|--------------|
| LOO | Enable loopback testing of MIRRORRED BITS channels. | 2 |
| LOO A | Enable loopback on MIRRORRED BITS Channel A for the next 5 minutes. | 2 |
| LOO B | Enable loopback on MIRRORRED BITS Channel B for the next 5 minutes. | 2 |

```

==>LOO A <Enter>
Loopback will be enabled on Mirrored Bits channel A for the next 5 minutes.
The RMB values will be forced to default values while loopback is enabled.
Are you sure (Y/N)?
==>

```

If only one MIRRORRED BITS port is enabled, the channel specifier (A or B) may be omitted. To enable loopback mode for other than the 5-minute default, enter the desired number of minutes (1–5000) as a command parameter. To allow the loopback data to modify the RMB values, include the DATA parameter.

```
=>>L00 10 DATA <Enter>
Loopback will be enabled on Mirrored Bits channel A for the next 10 minutes.
The RMB values will be allowed to change while loopback is enabled.
Are you sure (Y/N)? N <Enter>
Canceled.
=>>
```

To disable loopback mode before the selected number of minutes, re-issue the **L00** command with the R parameter. The R parameter returns the device to normal operation. If both MIRRORRED BITS channels are enabled, omitting the channel specifier in the disable command will cause both channels to be disabled.

```
=>>L00 R <Enter>
Loopback is disabled on both channels.
=>>
```

MAC Command

Use the **MAC** command to display the MAC addresses of **PORT 1**, as shown below.

```
=>MAC <Enter>
Port 1 MAC Address: 00-30-A7-00-00-00
=>
```

MET Command (Metering Data)

The **MET** command (see *Table 7.29*, *Table 7.30*, and *Table 7.31*) provides access to the relay metering data.

Table 7.29 Meter Command

| Command | Description | Access Level |
|----------------|------------------------|--------------|
| MET c n | Display metering data. | 1 |
| MET c R | Reset metering data. | 2 |

Table 7.30 Meter Command Parameters

| Parameter | Description |
|-----------|---|
| c | Parameter for identifying meter class. |
| n | Parameter used to specify number of times (1–32767) to repeat the meter response. |

Table 7.31 Meter Class

| c | Meter Class |
|------------------|------------------------------------|
| F | Fundamental Metering |
| E ^a | Energy Metering |
| M ^a | Maximum/Minimum Metering |
| RMS | RMS Metering |
| T | Thermal and RTD Metering |
| AI | Analog Input (transducer) Metering |
| MV | SELOGIC Math Variable Metering |
| DEM ^a | Demand Metering |
| PEA ^a | Peak Demand Metering |
| PM | Synchrophasor Metering |
| H | Harmonic Metering |
| DIF | Differential Metering |

^a Reset metering available.

For more information on metering and example responses for each meter class, see *Section 5: Metering and Monitoring*.

On issuing the **MET c R** command for resetting metering quantities in class *c*, the relay responds: `Reset Metering Quantities (Y,N)?` Upon confirming (pressing **Y**), the metering quantities will be reset and the relay responds with `Reset Complete`.

OPEN n Command (Open Breakern, where n = 1 or 2)

The **OPE n** (OPEN) command asserts Relay Word bit *OCn* for 1/4 cycle when it is executed. Relay Word bit *OCn* can then be programmed into the *TRn* SELOGIC control equation to assert the *TRIPn* Relay Word bit, which in turn asserts an output contact (e.g., *OUT301 = TRIPn*) to open circuit breaker *n* (see *Table 4.25* and *Figure 4.49* for factory-default setting *TRn* and trip logic). To issue the **OPE 1** command, enter the following.

Typing **N <Enter>** after the above prompt will abort the command.

```
==>>OPE 1 <Enter>
Open Breaker1 (Y,N)? Y <Enter>
==>>
```

The **OPE n** command is supervised by the main board breaker control jumper (see *Table 2.12*). If the breaker control jumper is not in place (breaker control jumper = OFF), the relay does not execute the **OPE n** command and responds with the following.

```
==>>OPE 1 <Enter>
Command Aborted: No Breaker Jumper
==>>
```

PASSWORD Command (Change Passwords)

Use the **PAS** command (see *Table 7.32* and *Table 7.33*) to change existing passwords.

Table 7.32 PASSWORD Command

| Command | Description | Access Level |
|------------------|---|--------------|
| PAS level | Change password for Access Level <i>level</i> . | 2, C |

⚠WARNING

This device is shipped with default passwords. Default passwords should be changed to private passwords at installation. Failure to change each default password to a private password may allow unauthorized access. SEL shall not be responsible for any damage resulting from unauthorized access.

Table 7.33 PAS Command Format

| Parameter | Description |
|--------------|---|
| level | Parameter <i>level</i> represents the relay Access Levels 1 or 2. |

The factory-default passwords are as shown in *Table 7.34*.

Table 7.34 Factory-Default Passwords for Access Levels 1, 2, and C

| Access Level | Factory-Default Password |
|--------------|--------------------------|
| 1 | OTTER |
| 2 | TAIL |
| C | CLARKE |

To change the password for Access Level 1 to #0t3579!ij7, enter the following command sequence:

```
=>>PAS 1 <Enter>
New PW: ? ***** <Enter>
Confirm PW: ? ***** <Enter>
Password Changed
=>>
```

Similarly, use **PAS 2** to change Level 2 passwords and **PAS C** to change Level C passwords.

Table 7.35 Valid Password Characters

| | |
|----------------|--|
| Alpha | A B C D E F G H I J K L M N O P Q R S T U V W X Y Z a b c d e f g h i j k l m n o p q r s t u v w x y z |
| Numeric | 0 1 2 3 4 5 6 7 8 9 |
| Special | ! " # \$ % & ' () * + , - . / : ; < = > ? @ [\] ^ _ ` { } ~ |

Passwords can contain as many as 12 characters. Upper- and lowercase letters are treated as different characters. Strong passwords consist of 12 characters, with at least one special character or digit and mixed-case sensitivity, but do not form a name, date, acronym, or word. Passwords formed in this manner are less susceptible to password guessing and automated attacks.

Examples of valid, distinct, and strong passwords are shown below:

- #0t3579!ij7
- \$A24.68&,mvj
- (Ih2dcs)36dn
- *4u-Iwg+?If-

PING Command

When you are setting up or testing substation networks, it is helpful to determine if the network is connected properly and if the other devices are powered up and configured properly. The **PING** command (Access Level 2) allows a user of the relay to determine if a host is reachable across an IP network and/or if the Ethernet port (Port 1) is functioning or configured correctly. A typical **PING** command response is shown in *Figure 7.19*. The command structure is:

PING x.x.x.x t

where:

x.x.x.x is the Host IP address and

't' is the PING interval in seconds, with a 2 to 255 second range.

The default **PING** interval is one second when 't' is not specified. The relay sends ping messages to the remote node until you stop the **PING** test by pressing the 'Q' key.

```
==>>PING 10.201.7.52 <Enter>

Press the Q key to end the ping test.

Pinging 10.201.7.52 every 1 second(s):

Reply from 10.201.7.52
Reply from 10.201.7.52
Reply from 10.201.7.52
Reply from 10.201.7.52
Reply from 10.201.7.52
Reply from 10.201.7.52
Ping test stopped.

Ping Statistics for 10.201.7.52
  Packets: Sent = 7, Received = 6, Lost = 1
    Duplicated = 0

==>>
```

Figure 7.19 PING Command Response

PULSE Command

Use the **PULSE** command (see *Table 7.36*) to pulse any of the relay control outputs for a specified time. This function aids you in relay testing and commissioning. If the output is open, the **PUL** command momentarily closes the output; if the output is closed, the **PUL** command momentarily opens the output. The control outputs are **OUTnnn**, where **nnn** represents 101–103 (standard), 301–304 (optional), 401–404 (optional) or 501–504 (optional).

Table 7.36 PUL OUTnnn Command

| Command | Description | Access Level |
|----------------------------------|------------------------------------|--------------|
| PUL OUTnnn ^a | Pulse output OUTnnn for 1 second. | 2 |
| PUL OUTnnn s ^b | Pulse output OUTnnn for s seconds. | 2 |

^a Parameter nnn is a control output number.

^b Parameter s is time in seconds, with a range of 1-30.

QUIT Command

Use the **QUIT** command (see *Table 7.37*) to revert to Access Level 0.

Table 7.37 QUIT Command

| Command | Description | Access Level |
|-------------|-----------------------|--------------|
| QUIT | Go to Access Level 0. | 0 |

Access Level 0 is the lowest access level; the SEL-787 performs no password check to descend to this level (or to remain at this level).

R_S Command (Restore Factory Defaults)

Use the **R_S** command (see *Table 7.38*) to restore factory-default settings.

Table 7.38 R_S Command (Restore Factory Defaults)

| Command | Description | Access Level |
|------------|---|--------------|
| R_S | Restore the factory-default settings and passwords, and reboot the system. ^a | 2 |

^a Only available after a settings or critical RAM failure.

SER Command (Sequential Events Recorder Report)

Use the **SER** commands (see *Table 7.39* and *Table 7.40*) to view and manage the Sequential Events Recorder report. See *Section 9: Analyzing Events* for further details on SER reports.

Table 7.39 SER Command (Sequential Events Recorder Report)

| Command | Description | Access Level |
|-------------------|---|--------------|
| SER | Use the SER command to display a chronological progression of all available SER rows (as many as 1024 rows). Row 1 is the most recently triggered row, and row 1024 is the oldest. | 1 |
| SER C or R | Use this command to clear/reset the SER records. | 1 |

Table 7.40 SER Command Format

| Parameter | Description |
|--------------------|--|
| <i>row1</i> | Append <i>row1</i> to return a chronological progression of the first <i>row1</i> rows. For example, use SER 5 to return the first five rows. |
| <i>row1 row2</i> | Append <i>row1</i> and <i>row2</i> to return all rows between <i>row1</i> and <i>row2</i> , beginning with <i>row1</i> and ending with <i>row2</i> . Enter the smaller number first to display a numeric progression of rows through the report. Enter the larger number first to display a reverse numeric progression of rows. For example, use SER 1 10 to return the first 10 rows in numeric order or SER 10 1 to return these same items in reverse numeric order. |
| <i>date1</i> | Append <i>date1</i> to return all rows with this date. For example, use SER 1/1/2008 to return all records for January 1, 2008. |
| <i>date1 date2</i> | Append <i>date1</i> and <i>date2</i> to return all rows between <i>date1</i> and <i>date2</i> beginning with <i>date1</i> and ending with <i>date2</i> . Enter the oldest date first to display a chronological progression through the report. Enter the newest date first to display a reverse chronological progression. Date entries are dependent on the date format setting DATE_F. For example, use SER 1/5/2008 1/7/2008 to return all records for January 5, 6, and 7, 2008. |

If the requested SER report rows do not exist, the relay responds with No SER data.

SER D Command

The **SER D** command shows a list of SER items that the relay has automatically removed. These are “chattering” elements. You can automatically remove chattering SER elements in the SER Chatter Criteria category of the Report settings; the enable setting is ESERDEL. See *Section 4: Protection and Logic Functions, Report Settings (SET R Command)* on page 4.106 for more information on SER automatic deletion and reinsertion.

Table 7.41 SER D Command

| Command | Description | Access Level |
|--------------|---|--------------|
| SER D | List chattering SER elements that the relay is removing from the SER records. | 1 |

If you issue the **SER D** command and you have not enabled automatic removal of chattering SER elements (Report setting ESERDEL), the relay responds, Automatic removal of chattering SER elements not enabled.

SET Command (Change Settings)

The **SET** command is for viewing or changing the relay settings (see *Table 7.42* and *Table 7.43*).

Table 7.42 SET Command (Change Settings)

| Command | Description | Access Level |
|--------------------------|---|--------------|
| SET s TERSE | Set the Group settings, beginning at the first setting. | 2 |
| SET DNP n s TERSE | Set DNP3 data map settings for map <i>n</i> (<i>n</i> = 1, 2, or 3) | 2 |
| SET L s TERSE | Set general logic settings. | 2 |
| SET G s TERSE | Set global settings. | 2 |
| SET P n s TERSE | Set serial port settings. <i>n</i> specifies the port (1, 2, 3, 4, or F); <i>n</i> defaults to the active port if not listed. | 2 |
| SET R s TERSE | Set report settings such as Sequential Events Recorder (SER) and Event Report (ER) settings. | 2 |
| SET F s TERSE | Set front-panel settings. | 2 |
| SET M s TERSE | Set Modbus User Map settings. | 2 |

Table 7.43 SET Command Format

| Parameter | Description |
|--------------|--|
| s | Append <i>s</i> , the name of the specific setting you want to view and jumps to this setting. If <i>s</i> is not entered, the relay starts at the first setting. |
| TERSE | Append TERSE to skip the settings display after the last setting. Use this parameter to speed up the SET command. If you want to review the settings before saving, do not use the TERSE option. |

When you issue the **SET** command, the relay presents a list of settings one at a time. Enter a new setting or press **<Enter>** to accept the existing setting. Editing keystrokes are shown in *Table 7.44*.

Table 7.44 SET Command Editing Keystrokes

| Press Key(s) | Results |
|---------------------------|---|
| <Enter> | Retains the setting and moves to the next setting. |
| ^ <Enter> | Returns to the previous setting. |
| < <Enter> | Returns to the previous setting category. |
| > <Enter> | Moves to the next setting category. |
| END <Enter> | Exits the editing session, then prompts you to save the settings. |
| <Ctrl+X> | Aborts the editing session without saving changes. |

The relay checks each setting to ensure that it is within the allowed range. If the setting is not within the allowed range, the relay generates an *Out of Range* message and prompts you for the setting again.

When all the settings are entered, the relay displays the new settings and prompts you for approval to enable them. Answer **Y <Enter>** to enable the new settings. The relay is disabled for as long as one second while it saves the new settings. The SALARM Relay Word bit is set momentarily, and the **ENABLED** LED extinguishes while the relay is disabled.

SHOW Command (Show/View Settings)

When showing settings, the relay displays the settings label and the present value from nonvolatile memory for each setting class. See *Table 7.45* for the **SHOW** command settings and *Table 7.46* for the command format.

Table 7.45 SHOW Command (Show/View Settings)

| Command | Description | Access Level |
|------------------|---|--------------|
| SHO s | Show Group settings. | 1 |
| SHO L s | Show general logic settings. | 1 |
| SHO G s | Show global settings. | 1 |
| SHO P n s | Show serial port settings. <i>n</i> specifies the port (1 , 2 , 3 , 4 , or F); <i>n</i> defaults to the active port if not listed. | 1 |
| SHO R s | Show report settings such as Sequential Events Recorder (SER) and Event Report (ER) settings. | 1 |
| SHO F s | Show front-panel settings. | 1 |
| SHO M s | Show Modbus User Map settings. | 1 |
| SHO DNP n | Display DNP3 data map settings for map <i>n</i> (<i>n</i> = 1, 2, or 3) | 1 |

Table 7.46 SHOW Command Format

| Parameter | Description |
|-----------|---|
| s | Appends <i>s</i> , the name of the specific setting you want to view, and jumps to this setting. If <i>s</i> is not entered, the relay starts at the first setting. |

```

=>>SHO <Enter>

Group 1
Relay Settings

ID Settings
RID      := SEL-787
TID      := TRANSFRMR RELAY

Config Settings
W1CT     := WYE           W2CT     := WYE           CTR1     := 100
CTR2     := 1000          MVA      := 50.0          ICOM     := N
VWDG1    := 138.00        VWDG2    := 13.80          CTRN1    := 120
PTR       := 120.00        VNOM     := 13.80          DELTA_Y  := DELTA
VIWDG     := 2            SINGLEV  := N

DIFF ELEMENT
E87      := Y            TAP1     := 2.09          TAP2     := 2.09
O87P     := 0.30         87AP     := 0.15          87AD     := 5.0
SLP1     := 25           SLP2     := 50           IRS1     := 3.0
U87P     := 10.0         PCT2     := 15          PCT4     := OFF
PCT5     := 35           TH5P     := OFF          HRSTR    := Y
HBLK     := N

Restricted Earth FLT
REF1POL  := OFF
REF1TC   := 1
50REF1P  := 0.25

WDG1 Max Ph IOC
50P11P   := 10.00        50P11D   := 0.00
50P11TC  := 1
50P12P   := 10.00        50P12D   := 0.00
50P12TC  := 1

50P13P   := 10.00        50P13D   := 0.00
50P13TC  := 1
50P14P   := 10.00        50P14D   := 0.00
50P14TC  := 1

WDG1 Res IOC
50G11P   := OFF          50G12P   := OFF

WDG1 Neg Seq IOC
50Q11P   := OFF          50Q12P   := OFF

WDG1 Max Ph TOC
51P1P    := 6.00         51P1C    := U3           51P1TD   := 3.00
51P1RS   := N            51P1CT    := 0.00          51P1MR   := 0.00
51P1TC   := 1

WDG1 Res TOC
51G1P    := 0.50         51G1C    := U3           51G1TD   := 1.50
51G1RS   := N            51G1CT    := 0.00          51G1MR   := 0.00
51G1TC   := 1

WDG1 Neg Seq TOC
51Q1P    := 6.00         51Q1C    := U3           51Q1TD   := 3.00
51Q1RS   := N            51Q1CT    := 0.00          51Q1MR   := 0.00
51Q1TC   := 1

WDG2 Max Ph IOC
50P21P   := 10.00        50P21D   := 0.00
50P21TC  := 1
50P22P   := 10.00        50P22D   := 0.00
50P22TC  := 1
50P23P   := 10.00        50P23D   := 0.00
50P23TC  := 1
50P24P   := 10.00        50P24D   := 0.00
50P24TC  := 1

WDG2 Res IOC
50G21P   := OFF          50G22P   := OFF

WDG2 Neg Seq IOC
50Q21P   := OFF          50Q22P   := OFF

WDG2 Max Ph TOC
51P2P    := 6.00         51P2C    := U3           51P2TD   := 3.00
51P2RS   := N            51P2CT    := 0.00          51P2MR   := 0.00
51P2TC   := 1

```

Figure 7.20 SHOW Command Example (Sheet 1 of 2)

```

WDG2 Res TOC
51G2P  := 0.50          51G2C  := U3          51G2TD  := 1.50
51G2RS := N            51G2CT  := 0.00        51G2MR  := 0.00
51G2TC := 1

WDG2 Neg Seq TOC
51Q2P  := 6.00          51Q2C  := U3          51Q2TD  := 3.00
51Q2RS := N            51Q2CT  := 0.00        51Q2MR  := 0.00
51Q2TC := 1

Neutral IOC
50N11P := OFF          50N12P := OFF

Neutral TOC
51N1P  := OFF

RTD Settings
E49RTD := NONE

Ph Undervoltage
27P1P  := OFF          27P2P  := OFF

Ph Overvoltage
59P1P  := OFF          59P2P  := OFF

NSeq Overvoltage
59Q1P  := OFF          59Q2P  := OFF

Volts per Hertz
E24    := Y            24WDG   := WYE          24D1P   := 105
24D1D  := 1.00         24CCS   := ID           24IP    := 105
24IC   := 2.0          24ITD   := 0.1          24D2P2  := 176
24D2D2 := 3.00         24CR    := 240.00
24TC   := 1

Power Elements
EPWR   := N

Freq Settings
81D1TP := OFF          81D2TP := OFF          81D3TP := OFF
81D4TP := OFF

Demand Mtr Set

EDEM   := OFF
Trip/Close Logic
TDURD  := 0.5          CFD1    := 0.5          CFD2    := 0.5
TR1    := 50P11T OR 51P1T OR 51Q1T OR NOT LT02 AND SV04T OR OC1
TR2    := 51P2T OR 51Q2T OR LT02 AND SV04T OR OC2
TRXFMR := 87R OR 87U
REMTRIP := 0
ULTRIP1 := 0
ULTRIP2 := 0
ULTRXFMR := 0
52A1    := 0
CL1     := SV03T AND NOT LT02 OR CC1
ULCL1   := TRIP1 OR TRIPXFMR
52A2    := 0
CL2     := SV03T AND LT02 OR CC2
ULCL2   := TRIP2 OR TRIPXFMR

=>>>

```

Figure 7.20 SHOW Command Example (Sheet 2 of 2)

STATUS Command (Relay Self-Test Status)

The **STA** command (see *Table 7.47*) displays the status report.

Table 7.47 STATUS Command (Relay Self-Test Status)

| Command | Description | Access Level |
|---------------------|---|--------------|
| STA <i>n</i> | Display the relay self-test information <i>n</i> times (<i>n</i> = 1–32767). Defaults to 1 if <i>n</i> is not specified. | 1 |
| STA S | Display the memory and execution utilization for the SELOGIC control equations. | 1 |
| STA C or R | Reboot the relay and clear self-test warning and failure status results. | 2 |

Refer to *Section 10: Testing and Troubleshooting* for self-test thresholds and corrective actions, as well as hardware configuration conflict resolution.

Table 7.48 shows the status report definitions and message formats for each test. Refer to *Figure 1.2* and *Figure 1.3* for examples of the **STATUS** command response.

Table 7.48 STATUS Command Report and Definitions (Sheet 1 of 2)

| STATUS Report Designator | Definition | Message Format |
|--------------------------|---|----------------|
| Serial Num | Serial number | Number |
| FID | Firmware identifier string | Text Data |
| CID | Firmware checksum identifier | Hex |
| PART NUM | Part number | Text Data |
| FPGA | FPGA programming unsuccessful, or FPGA failed | OK/FAIL |
| GPSB | General Purpose Serial Bus | OK/FAIL |
| HMI | Front-Panel FGPA programming unsuccessful, or Front-Panel FPGA failed | OK/WARN |
| RAM | Volatile memory integrity | OK/FAIL |
| ROM | Firmware integrity | OK/FAIL |
| CR_RAM | Integrity of settings in RAM and code that runs in RAM | OK/FAIL |
| Non_Vol | Integrity of data stored in nonvolatile memory | OK/FAIL |
| Clock | Clock functionality | OK/WARN |
| RTD | Integrity of RTD module/communications | OK/FAIL |
| CID_FILE | Configured IED description file | OK/FAIL |
| x.x V | Power supply status | Voltage/FAIL |
| BATT | Clock battery voltage | Voltage/WARN |
| CARD_C | Integrity of Card C | OK/FAIL |
| CARD_D | Integrity of Card D | OK/FAIL |
| CARD_E | Integrity of Card E | OK/FAIL |
| CURRENT | Integrity of current board | OK/FAIL |
| DN_MAC_ID | Specific DeviceNet card identification | Text Data |
| ASA | Manufacturers identifier for DeviceNet | Text Data |

Table 7.48 STATUS Command Report and Definitions (Sheet 2 of 2)

| STATUS Report Designator | Definition | Message Format |
|--|--|----------------|
| DN_Rate | DeviceNet card network communications data rate of 150, 250, or 500 kbps | Text Data |
| DN_Status | DeviceNet connection and fault status 000b bbbb | Text Data |
| Current Offset (IAW _n , IBW _n , ICW _n (<i>n</i> = 1, 2), IN) | DC offset in hardware circuits of current channels | OK/WARN |
| Voltage Offset (VA, VB, VC) | DC offset in hardware circuits of voltage channels | OK/FAIL |

Figure 7.21 shows the typical relay output for the **STATUS S** command, showing available SELOGIC control equation capability.

```
=>STA S <Enter>
```

```
SEL-787                               Date: 03/10/2008   Time: 15:04:34
TRNSFRMR RELAY                       Time Source: Internal
```

```
Part Number = 0787EX1B0X0X7585023X
```

```
SELogic Equation Available Capacity
```

```
Global (%)    79
FP (%)        56
Report (%)    77
```

| | GROUP 1 | GROUP 2 | GROUP 3 | GROUP 4 |
|---------------|---------|---------|---------|---------|
| Execution (%) | 87 | 87 | 87 | 87 |
| Group (%) | 82 | 82 | 82 | 82 |
| Logic (%) | 89 | 89 | 89 | 89 |

```
=>
```

Figure 7.21 Typical Relay Output for STATUS S Command

SUMMARY Command

The **SUM** command (see Table 7.49) displays an event summary in human readable format.

Table 7.49 SUMMARY Command

| Command | Description | Access Level |
|---------------------|--|--------------|
| SUM <i>n</i> | The command without arguments displays the latest event summary. Use <i>n</i> to display particular event summary. | 1 |
| SUM R or C | Use this command to clear the archive. | 1 |

Each event summary report shows the date, time, current magnitudes (primary values), frequency, and, if the relay has the voltage option, voltage magnitudes (primary values). The relay reports the voltage and current when the largest current occurs during the event. The event summary report also shows the event type.

TARGET Command (Display Relay Word Bit Status)

The **TAR** command (see *Table 7.50* and *Table 7.51*) displays the status of front-panel target LEDs or Relay Word bit, whether these LEDs or Relay Word bits are asserted or deasserted.

Table 7.50 TARGET Command (Display Relay Word Bit Status)

| Command | Description | Access Level |
|---|--|--------------|
| TAR name k TAR n TAR n k | Use TAR without parameters to display Relay Word Row 0 or last displayed target row. | 1 |
| TAR R | Clears front-panel tripping targets. Unlatches the trip logic for testing purposes (see <i>Figure 8.1</i>). Shows Relay Word Row 0. | 1 |

NOTE: The **TARGET R** command cannot reset the latched targets if a TRIP condition is present.

Table 7.51 TARGET Command Format

| Parameter | Description |
|-------------|--|
| name | Display the Relay Word row with Relay Word bit name. |
| n | Show Relay Word row number <i>n</i> . |
| k | Repeat <i>k</i> times (1–32767) |

The elements are represented as Relay Word bits and are listed in rows of eight, called Relay Word rows. The first four rows, representing the front-panel operation and target LEDs, correspond to *Table 7.52*. All Relay Word rows are described in *Table J.1* and *Table J.2*.

Relay Word bits are used in SELOGIC control equations. See *Appendix J: Relay Word Bits*.

The **TAR** command does not remap the front-panel target LEDs, as is done in some previous SEL relays.

Table 7.52 Front-Panel LEDs and the TAR 0 Command

| LEDs | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|---------|----------|---------|---------|---------|---------|---------|---------|
| TAR 0 | ENABLED | TRIP_LED | TLED_01 | TLED_02 | TLED_03 | TLED_04 | TLED_05 | TLED_06 |

TFE Command (Through-Fault Event Report)

The **TFE** command displays the following data for each individually recorded through-fault event:

- Date and time of the through fault
- Duration (seconds) of the through fault
- Maximum current (Amps primary) for each monitored current input

The following cumulative values (updated for each new through-fault event) are also displayed:

- Through-fault count
- Total accumulated percentage of through-fault capability used up per phase

There are various choices for the **TFE** command, listed briefly below. Refer to *Section 5: Metering and Monitoring* for a complete description of the through-fault event reports:

| | |
|--------------|--|
| TFE | Displays cumulative and individual through-fault event data. The 20 most recent individual events are displayed. |
| TFE A | Displays cumulative and individual through-fault event data. All of the most recent individual events are displayed, as many as 500. |
| TFE C | Clears/resets cumulative and individual through-fault event data. |
| TFE n | Displays cumulative and individual through-fault event data. The n most recent individual events are displayed, where n = 1 to 500. |
| TFE P | Preloads cumulative through-fault event data. |
| TFE R | Clears/resets cumulative and individual through-fault event data. |

TIME Command (View/Change Time)

The **TIME** command (see *Table 7.53*) returns information about the SEL-787 internal clock. You can also set the clock if you specify hours and minutes (seconds data are optional). Separate the hours, minutes, and seconds with colons, semicolons, spaces, commas, or slashes.

Table 7.53 TIME Command (View/Change Time)

| Command | Description | Access Level |
|----------------------|---|--------------|
| TIME | Display the present internal clock time. | 1 |
| TIME hh:mm | Set the internal clock to hh:mm . | 1 |
| TIME hh:mm:ss | Set the internal clock to hh:mm:ss . | 1 |

Use the **TIME hh:mm** and **TIME hh:mm:ss** commands to set the internal clock time. The value **hh** is for hours from 0–23; the value **mm** is for minutes from 0–59; the value **ss** is for seconds from 0–59. If you enter a valid time, the relay updates and saves the time in the nonvolatile clock, and displays the time you just entered. If you enter an invalid time, the SEL-787 responds with *Invalid Time*.

TRIGGER Command (Trigger Event Report)

Use the **TRI** command (see *Table 7.54*) to trigger the SEL-787 to record data for high-resolution oscillography and event reports.

Table 7.54 TRIGGER Command (Trigger Event Report)

| Command | Description | Access Level |
|------------|------------------------------------|--------------|
| TRI | Trigger event report data capture. | 1 |

When you issue the **TRI** command, the SEL-787 responds with *Triggered*. If the event did not trigger within one second, the relay responds with *Did not trigger*.

See *Section 9: Analyzing Events* for further details on event reports.

VEC Command (Show Diagnostic Information)

Issue the **VEC** command under the direction of SEL. The information contained in a vector report is formatted for SEL in-house use only. Your SEL application engineer or the factory may request a **VEC** command capture to help diagnose a relay or system problem.

Table 7.55 VEC Command

| Command | Description | Access Level |
|--------------|-------------------------------------|--------------|
| VEC D | Displays the standard vector report | 2 |
| VEC E | Displays the extended vector report | 2 |

Section 8

Front-Panel Operations

Overview

The SEL-787 Transformer Protection Relay front panel makes transformer data collection and control quick and efficient. Use the front panel to analyze operating information, view and change relay settings, and perform control functions. The SEL-787 features a straightforward menu-driven control structure presented on the front-panel liquid crystal display (LCD). Front-panel targets and other LEDs give a clear indication of the SEL-787 operation status. The features that help you operate the relay from the front panel include the following:

- Reading metering
- Inspecting targets
- Accessing settings
- Controlling relay operations
- Viewing diagnostics

Front-Panel Layout

Figure 8.1 shows and identifies the following regions:

- Human-Machine Interface (HMI)
- **TARGET RESET** and navigation pushbuttons
- Operation and target LEDs
- Operator control pushbuttons and pushbutton LEDs
- EIA-232 Serial Port (**PORT F**). See *Section 7: Communications* for details on the serial port.

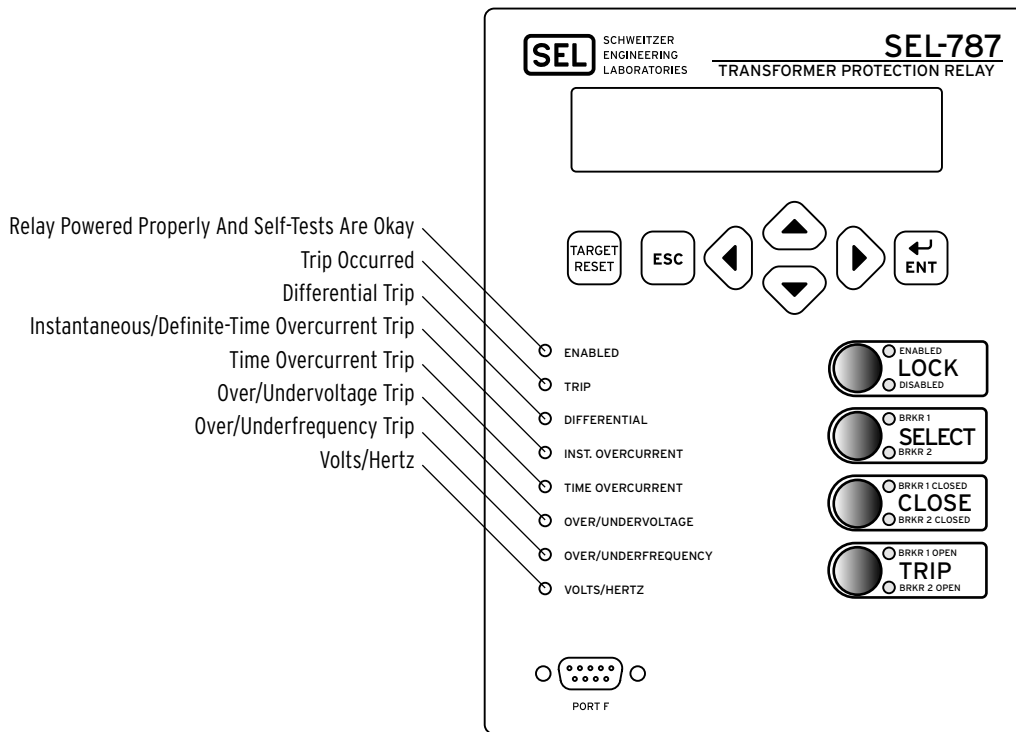


Figure 8.1 Front-Panel Overview

This versatile front panel supports the following features so you can customize it for your needs:

- Rotating display on the HMI
- Programmable target LEDs
- Programmable pushbutton LEDs
- Slide-in configurable front-panel labels to change the identification of target LEDs, pushbuttons, pushbutton LEDs and their operation.

Human-Machine Interface

Contrast

NOTE: See the Preface for an explanation of typographic conventions used to describe menus, the front-panel display, and the front-panel pushbuttons.

You can adjust the LCD screen contrast to suit your viewing angle and lighting conditions. To change screen contrast, press and hold the **ESC** pushbutton for two seconds. The SEL-787 displays a contrast adjustment box. Pressing the **Right Arrow** pushbutton increases the contrast. Pressing the **Left Arrow** pushbutton decreases the screen contrast. When you are finished adjusting the screen contrast, press the **ENT** pushbutton; this process is a shortcut for changing the LCD contrast setting FP_CONT in the front-panel settings.

Front-Panel Automatic Messages

The relay displays automatic messages, overriding the rotating display, under the conditions described in *Table 8.1*, with the relay failure having the highest priority, followed by trip and alarm when the front-panel setting `FP_AUTO := OVERRIDE`.

If the front-panel setting `FP_AUTO := ROTATING`, then the rotating display messages continue and any TRIP or ALARM message is added to the rotation. Relay failure will still override the rotating display.

Table 8.1 Front-Panel Automatic Messages (FP_AUTO := OVERRIDE)

| Condition | Front-Panel Message |
|------------------------------------|--|
| Relay detecting any failure | Displays the type of latest failure (see <i>Section 10: Testing and Troubleshooting</i>). |
| Relay trip has occurred | Displays the type or cause of the trip. Refer to <i>Table 9.1</i> for a list of trip display messages. |
| Relay alarm condition has occurred | Displays the type of alarm. The TRIP LED is also flashing during an alarm condition. |

Front-Panel Security

Front-Panel Access Levels

The SEL-787 front panel typically operates at Access Level 1 and provides viewing of relay measurements and settings. Some activities, such as editing settings and controlling output contacts, are restricted to those operators who know the Access Level 2 passwords.

In the following figures, the padlock symbol indicates restricted activities.



Figure 8.2 Access Level Security Padlock Symbol

Before you can perform a front-panel menu activity that is marked with the padlock symbol, you must enter the correct Access Level 2 passwords. After you have correctly entered the password, you can perform other Access Level 2 activities without reentering the password.

Access Level 2 Password Entry

When you try to perform an Access Level 2 activity, the relay determines whether you have entered the correct Access Level 2 password since the front-panel inactivity timer expired. If you have not, the relay displays the screen shown in *Figure 8.3* for you to enter the password.

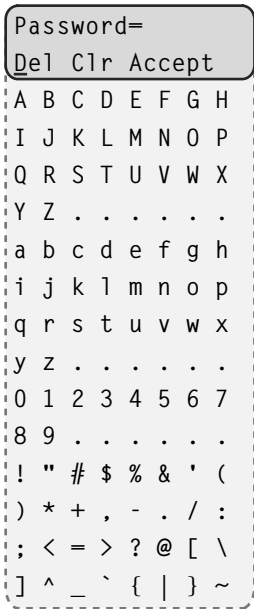


Figure 8.3 Password Entry Screen

See *PASSWORD Command (Change Passwords)* on page 7.33 for the list of default passwords and for more information on changing passwords.

Front-Panel Timeout

To help prevent unauthorized access to password-protected functions, the SEL-787 provides a front-panel timeout, setting FP_TO. A timer is reset every time a front-panel pushbutton is pressed. Once the timeout period has expired, the access level is reset to Access Level 1. Manually reset the access level by selecting Quit from the MAIN menu.

Front-Panel Menus and Screens

Navigating the Menus

The SEL-787 front panel gives you access to most of the information that the relay measures and stores. You can also use front-panel controls to view or modify relay settings.

All of the front-panel functions are accessible through use of the six-button keypad and LCD display. Use the keypad (shown in Figure 8.4) to maneuver within the front-panel menu structure, described in detail throughout the remainder of this section. Table 8.2 describes the function of each front-panel pushbutton.

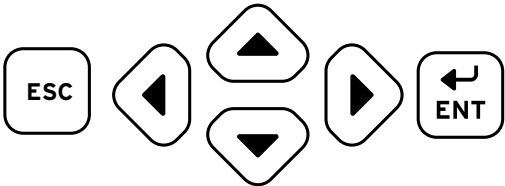








Figure 8.4 Front-Panel Pushbuttons

Table 8.2 Front-Panel Pushbutton Functions

| Pushbutton | Function |
|---|---|
|  Up Arrow | Move up within a menu or data list. While editing a setting value, increase the value of the underlined digit. |
|  Down Arrow | Move down within a menu or data list. While editing a setting value, decrease the value of the underlined digit. |
|  Left Arrow | Move the cursor to the left. |
|  Right Arrow | Move the cursor to the right. |
|  ESC | Escape from the current menu or display. Displays additional information if lockout condition exists. Hold for two seconds to display contrast adjustment screen. |
|  ENT | Move from the rotating display to the MAIN menu. Select the menu item at the cursor. Select the displayed setting to edit that setting. |

The SEL-787 automatically scrolls information that requires more space than provided by a 16-character LCD line. Use the **Left Arrow** and **Right Arrow** pushbuttons to suspend automatic scrolling and enable manual scrolling of this information.

MAIN Menu

Figure 8.5 shows the MAIN menu screen. Using the **Up Arrow** or **Down Arrow** and **ENT** pushbuttons, you can navigate to specific menu item in the MAIN menu. Each menu item is explained in detail in the following paragraphs.

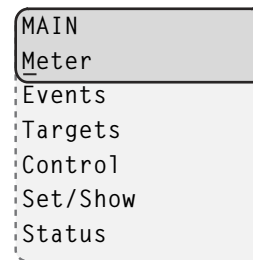


Figure 8.5 Main Menu

Meter Menu

Select the **Meter** menu item from the MAIN menu as shown in *Figure 8.6* to view metering data. The **Meter** menu has menu items for viewing different types of metering data like Fundamental, Thermal, Differential, etc. Select the type of metering and view the data using the **Up Arrow** or **Down Arrow** pushbuttons. See *Metering on page 5.3* for a description of the available data fields.

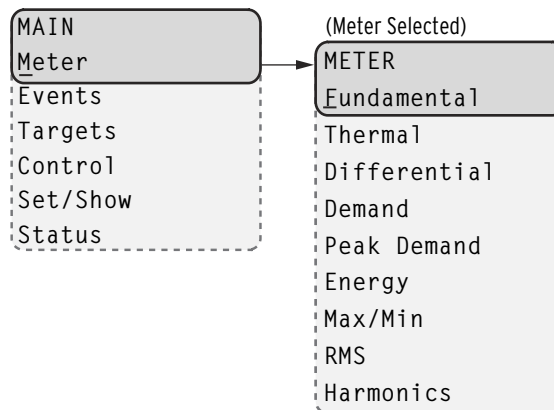


Figure 8.6 MAIN Menu and METER Submenu

For viewing Energy (or Max/Min) metering data, select the Energy (or Max/Min) menu item from the METER menu and select the Display menu item as shown in *Figure 8.7*.

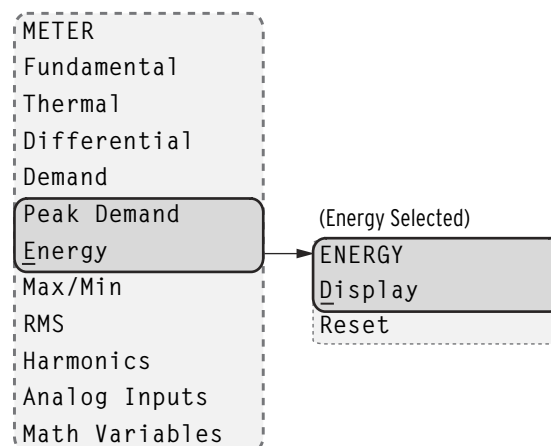


Figure 8.7 METER Menu and ENERGY Submenu

Demand, Peak Demand, Energy, or Max/Min metering data can be reset from the front-panel HMI by selecting the Reset menu item in the Demand, Peak Demand, Energy or Max/Min menu. After selecting Reset and confirming the reset, the relay displays as shown in *Figure 8.8*.

Reset Complete

Figure 8.8 Relay Response When Demand, Peak Demand, Energy, or Max/Min Metering Is Reset

Assume the relay configuration contains no analog input cards. In response to a request for analog data (selecting Analog Inputs), the device displays the message as shown in *Figure 8.9*.

No Analog Input
Cards Present

Figure 8.9 Relay Response When No Analog Cards Are Installed

Assume the math variables are not enabled. In response to a request for math variable data (selecting *Math Variables*), the device displays the message as shown in *Figure 8.10*.

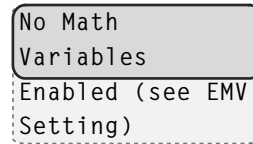


Figure 8.10 Relay Response When No Math Variables Enabled

Events Menu

Select the *Events* menu item from the *MAIN* menu as shown in *Figure 8.11*. *EVENTS* menu has *Display* and *Clear* as menu items. Select *Display* to view events and *Clear* to delete all the events data.

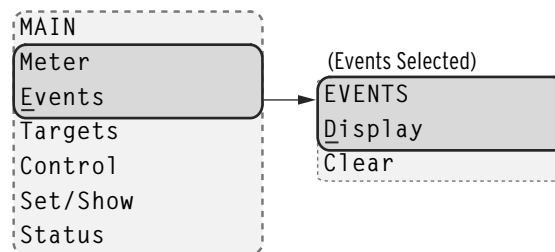


Figure 8.11 MAIN Menu and EVENTS Submenu

Figure 8.12 shows the *DISPLAY* menu when *Display* is selected from the *EVENTS* menu with events in the order of occurrence starting with the most recent. You can select an event from the *DISPLAY* menu and navigate through the event data.

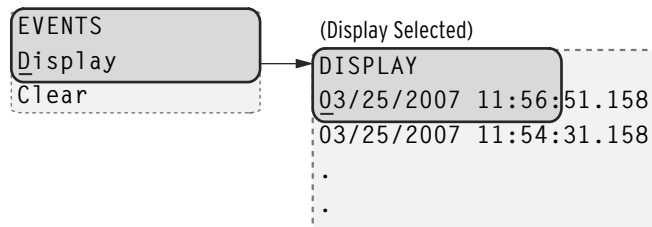


Figure 8.12 EVENTS Menu and DISPLAY Submenu

When *Display* is selected and no event data are available, the relay displays as shown in *Figure 8.13*.

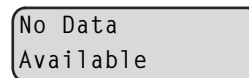


Figure 8.13 Relay Response When No Event Data Available

When *Clear* is selected from the *EVENTS* menu and confirming the selection, the relay displays as shown in *Figure 8.14* after clearing the events data.

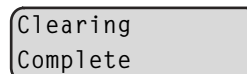


Figure 8.14 Relay Response When Events Are Cleared

Targets Menu

Select the **Targets** menu item on the **MAIN** menu as shown in *Figure 8.15* to view the binary state of the target rows. Each target row has eight Relay Word bits as shown in *Table J.1*.

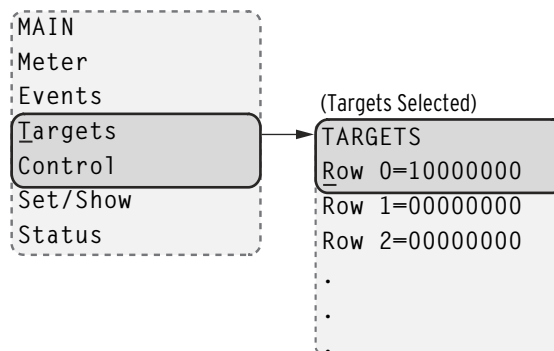


Figure 8.15 MAIN Menu and TARGETS Submenu

Select the target row to display two consecutive Relay Word bits with name and binary state as shown in *Figure 8.16*.

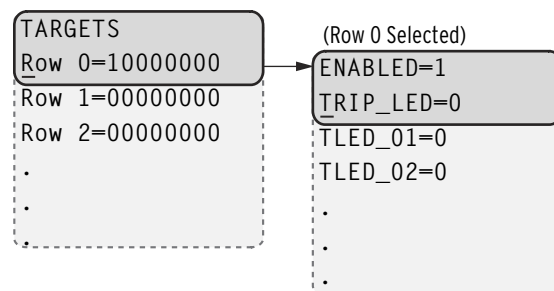


Figure 8.16 TARGETS Menu Navigation

Control Menu

Select the **Control** menu item on the **MAIN** menu as shown in *Figure 8.17* to go to the **CONTROL** menu.

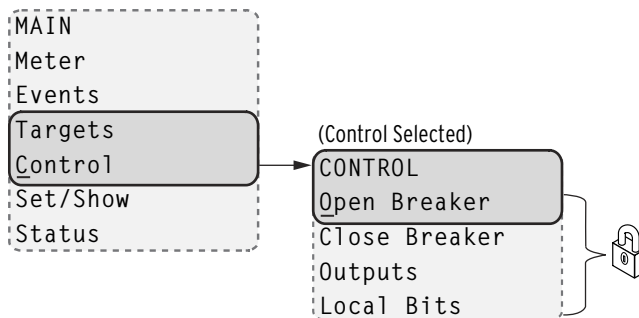


Figure 8.17 MAIN Menu and CONTROL Submenu

The **CONTROL** menu has **Open Breaker** (1 or 2), **Close Breaker** (1 or 2), **Outputs**, and **Local Bits** as menu items.

Select the **Open Breaker 1** or **2** menu item to assert Relay Word bits **OC1** or **OC2**, which will open breaker 1 or 2 via **SELOGIC®** equations **TR1** or **TR2**. See *Table 4.25* for equations **TR1** and **TR2** and *Table J.2* for the definitions of Word bits **OC1** and **OC2**. Note that this requires Level 2 access.

Select the **Close Breaker 1** or **2** menu item to assert Relay Word bits CC1 or CC2, which will close the breaker 1 or 2 via the CL1 or CL2 SELOGIC equation (see *Figure 4.50*). Note that this requires Level 2 access.

Select the **Outputs** menu item from the **CONTROL** menu as shown in *Figure 8.18* to test (pulse) SEL-787 output contacts and associated circuits. Choose the output contact by navigating through the **OUTPUT** menu and test it by pressing the **ENT** pushbutton. Note that testing the output contact requires Level 2 access and reconfirmation.

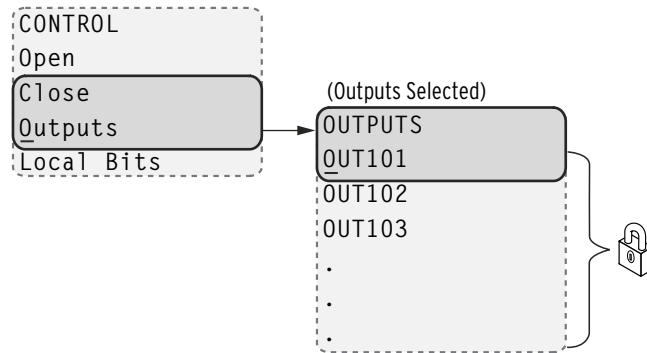


Figure 8.18 CONTROL Menu and OUTPUTS Submenu

Select the **Local Bits** menu item from the **CONTROL** menu for local control action. Local bits take the place of traditional panel switches, and perform isolation, open, close, or pulse operations.

With the settings as per the example in *Section 4* (see *Local Bits* on page 4.103 for more information), local bit 1 replaces a supervisory switch. *Figure 8.19* shows the screens in closing the supervisory switch. In this operation, local bit LB01 is deasserted (**SUPER SW = OPEN**), and changes to asserted (**SUPER SW = CLOSE**) as shown in the final screen of *Figure 8.19*.

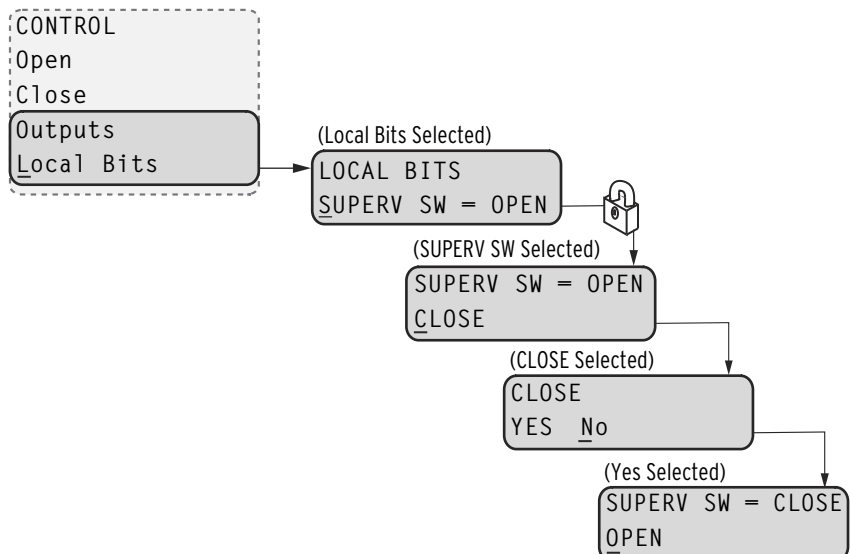


Figure 8.19 CONTROL Menu and LOCAL BITS Submenu

Set/Show Menu

Select the Set/Show menu item on the MAIN menu. The Set/Show menu is used to view or modify the settings (Global, Group, and Port), Active Group, Date, and Time. Note that modifying the settings requires Level 2 access.

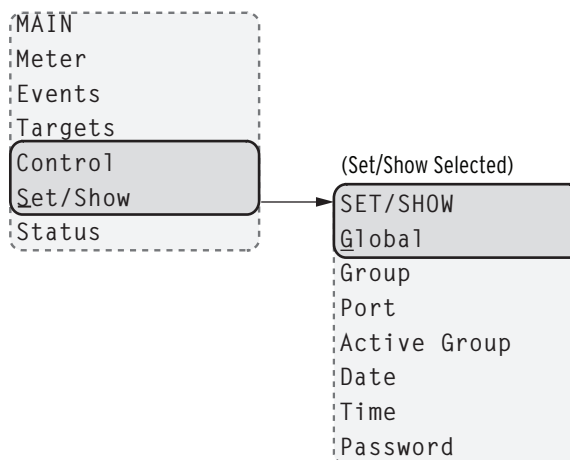


Figure 8.20 MAIN Menu and SET/SHOW Submenu

Each settings class (Global, Group, and Port) includes headings that create subgroups of associated settings as shown in the following illustration. Select the heading that contains the setting of interest, and then navigate to the particular setting. View or edit the setting by pressing the **ENT** pushbutton. For text settings, use the four navigation pushbuttons to scroll through the available alphanumeric and special character settings matrix. For numeric settings, use the **Left Arrow** and **Right Arrow** pushbuttons to select the digit to change and the **Up Arrow** and **Down Arrow** pushbuttons to change the value. Press the **ENT** pushbutton to enter the new setting.

Setting changes can also be made using ACSELERATOR QuickSet® SEL-5030 Software or ASCII **SET** commands via a communications port.

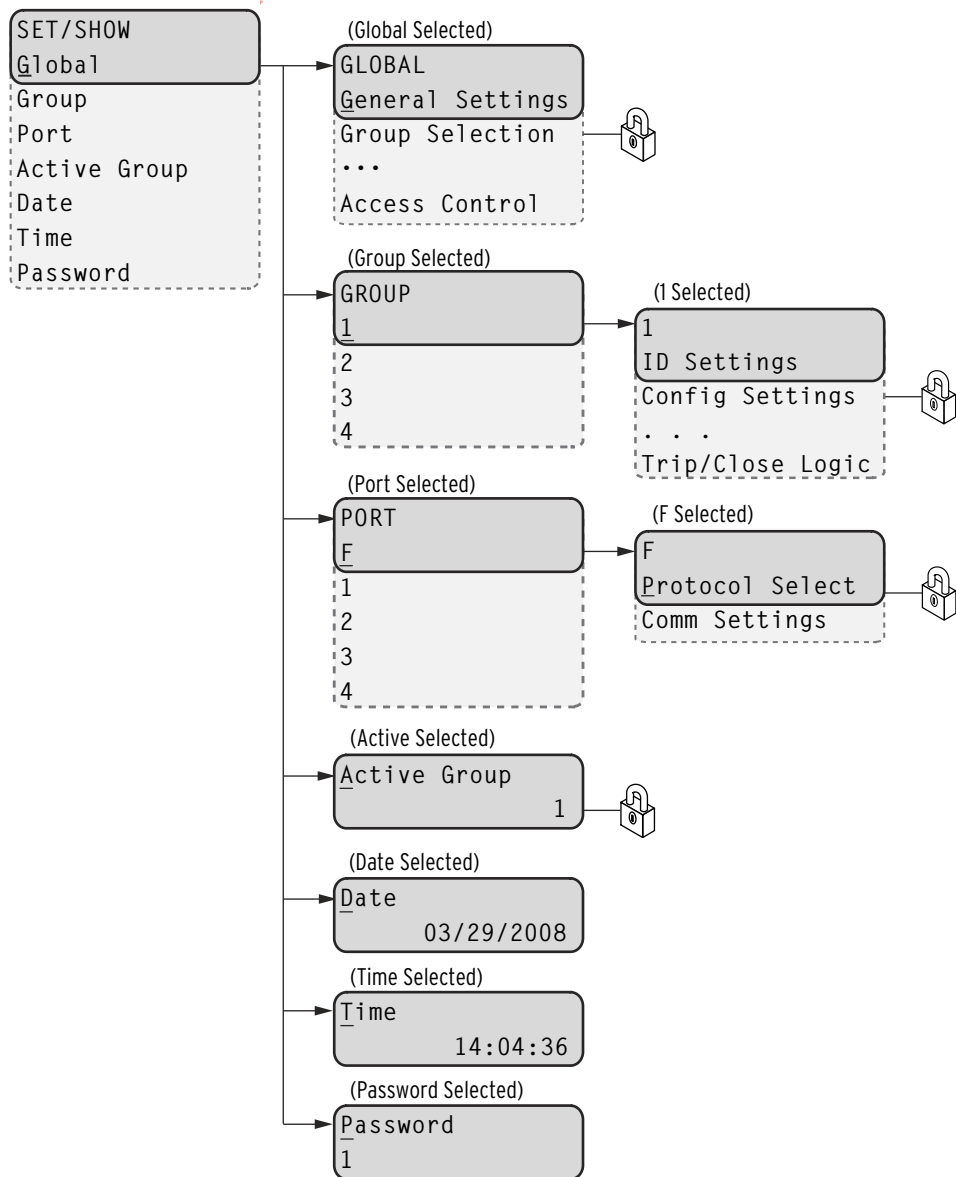


Figure 8.21 SET/SHOW Menu

Status Menu

Select the **Status** menu item on the **MAIN** menu as shown in *Figure 8.22* to access Relay Status data and Reboot Relay. See *STATUS Command (Relay Self-Test Status)* on page 7.40 for the **STATUS** data field description.

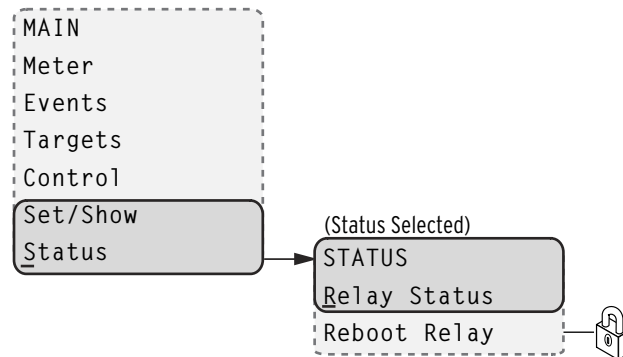


Figure 8.22 MAIN Menu and Status Submenu

Operation and Target LEDs

Programmable LEDs

The SEL-787 provides quick confirmation of relay conditions via operation and target LEDs. *Figure 8.23* shows this region with factory-default text on the front-panel configurable labels. See *Target LED Settings on page 4.104* for the SELOGIC control equations.

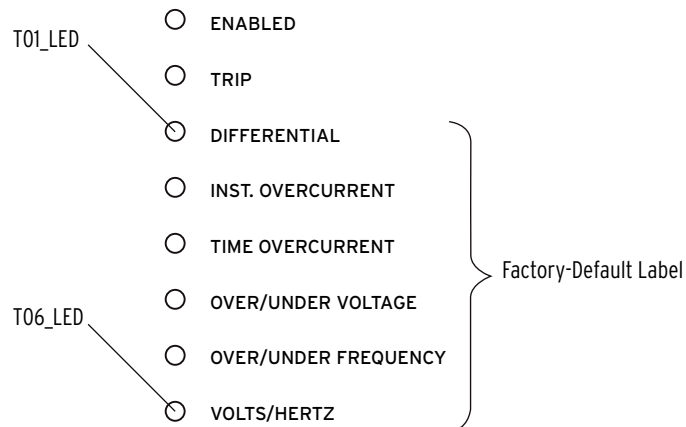


Figure 8.23 Factory-Default Front-Panel LEDs

You can reprogram all of these indicators except the **ENABLED** and **TRIP** LEDs to reflect operating conditions other than the factory-default programming described in this subsection.

T0n_LED settings are SELOGIC control equations that work with the corresponding T0nLEDL latch settings to illuminate the LEDs shown in *Figure 8.23*. Parameter *n* is a number from 1 through 6 that indicates each LED. If the latch setting (T0nLEDL) for a certain LED is set to N, then the LED will follow the status of the corresponding control equation (T0n_LED). When the equation asserts, the LED will illuminate, and when the equation deasserts, the LED will extinguish. If the latch setting is set to Y, the LED will only assert if a trip condition occurs and the T0n_LED equation is asserted at the time of the trip. At this point, the LED will latch in and can be reset using

the **TARGET RESET** pushbutton or the **TAR R** command as long as the target conditions are absent. For a concise listing of the default programming on the front-panel LEDs, see *Table 4.59*.

The SEL-787 comes with blank slide-in labels for custom LED designations that match custom LED logic. The Configurable Label Kit (includes blank labels, word processor templates, and instructions) is shipped with the SEL-787.

The **ENABLED** LED indicates that the relay is powered correctly, is functional, and has no self-test failures. Trip events illuminate the **TRIP** LED. The prominent location of the **TRIP** LED in the top target area aids in recognizing trip events quickly. When the **TRIP** LED is lit continuously, the **TRIP TYPE** is displayed on the LCD display. Refer to *Table 9.1*, for the list of possible trip messages.

The **TRIP** LED has an additional function that notifies you of warning conditions. When the **TRIP** LED is flashing, the warning conditions in *Table 8.3* are active when you set the corresponding relay element. For Relay Word bit definitions see *Appendix J: Relay Word Bits*.

Table 8.3 Possible Warning Conditions (Flashing TRIP LED)

| HMI Message | Condition (Relay Word Bit) |
|--------------------|----------------------------|
| RTD Warning | AMBALRM OR OTHALRM |
| RTD Failure | RTDFLT |
| Comm. Loss Warning | COMMLOSS |
| Comm. Idle Warning | COMMIDLE |

TARGET RESET Pushbutton

Target Reset

For a trip event, the SEL-787 latches the trip-involved target LEDs except for the **ENABLED** LED. Press the **TARGET RESET** pushbutton to reset the latched target LEDs. When a new trip event occurs and the previously latched trip targets have not been reset, the relay clears the latched targets and displays the new trip targets. Pressing and holding the **TARGET RESET** pushbutton illuminates all the LEDs. Upon release of the **TARGET RESET** pushbutton, two possible trip situations can exist: the conditions that caused the relay to trip have cleared, or the trip conditions remain present at the relay inputs. If the trip conditions have cleared, the latched target LEDs turn off. If the trip event conditions remain, the relay re-illuminates the corresponding target LEDs. The **TARGET RESET** pushbutton also removes the trip automatic message displayed on the LCD menu screens if the trip conditions have cleared.



Figure 8.24 Target Reset Pushbutton

Lamp Test

The **TARGET RESET** pushbutton also provides a front-panel lamp test. Pressing and holding **TARGET RESET** illuminates all the front-panel LEDs, and these LEDs remain illuminated for as long as **TARGET RESET** is pressed. The target LEDs return to a normal operational state after release of the **TARGET RESET** pushbutton.

Other Target Reset Options

Use the ASCII command **TAR R** to reset the target LEDs; see *Table 7.12* for more information. Programming specific conditions in the SELOGIC control equation **RSTTRGT** is another method for resetting target LEDs. Access **RSTTRGT** in *Global Settings (SET G Command)* and see *Table 4.42* for further information.

Front-Panel Operator Control Pushbuttons

The SEL-787 features four operator-controlled pushbuttons, each with two programmable pushbutton LEDs, for local control as shown in *Figure 8.25*.

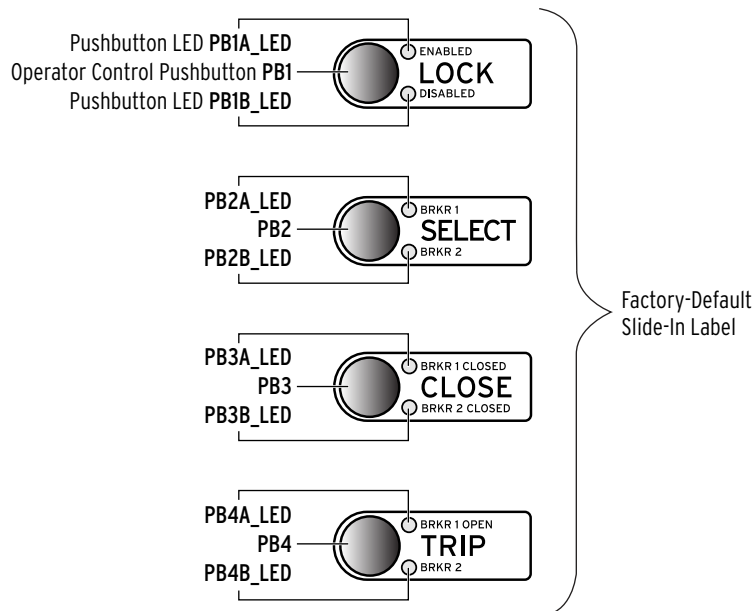


Figure 8.25 Operator Control Pushbuttons and LEDs

Pressing any one of these four pushbuttons asserts the corresponding PB_n ($n = 01$ through 04) Relay Word bit, and the corresponding PB_n_PUL Relay Word bit. The PB_n Relay Word bit remains asserted as long as the pushbutton is pressed, but the PB_n_PUL Relay Word bit asserts only for the initial processing interval, even if the button is still being pressed. Releasing the pushbutton, and then pressing the pushbutton again asserts the corresponding PB_n_PUL Relay Word bit for another processing interval. The pushbutton LEDs are independent of the pushbutton.

Pushbutton LEDs are programmable using front-panel settings PB_{nm_LED} (where $n = 1$ through 4 and $m = A$ or B). PB_{nm_LED} settings are SELOGIC control equations that, when asserted, illuminate the corresponding LED for as long as the input is asserted. When the input deasserts, the LED also deasserts without latching.

Using SELOGIC control equations, you can readily change the default LED and pushbutton functions. The user-configurable slide-in labels can be used to mark the pushbuttons and pushbutton LEDs with custom names to reflect any

programming changes that you make. Included on the SEL-787 Product Literature CD are word processor templates for printing slide-in labels. See the instructions included in the Configurable Label kit for more information on changing the slide-in labels.

Table 8.4 describes front-panel operator controls based on the factory-default settings and operator control labels.

Table 8.4 SEL-787 Front-Panel Operator Control Functions

Continually press the **LOCK** operator control pushbutton for three (3) seconds to engage/disengage the lock function (Latch LT01 functions as Lock with the latch in reset state equivalent to the engaged lock). While this pushbutton is pressed, the corresponding LED flashes on and off, indicating a pending engagement or disengagement of the lock function. The LED illuminates constantly to indicate the engaged state. While the lock function is engaged, the following operator control is “locked in position” (assuming factory-default settings): **CLOSE**.

While “locked in position,” this operator control cannot change state if pressed—the corresponding LEDs remain in the same state. When the lock function is engaged, the **CLOSE** operator control cannot close breaker 1 or 2, but the **TRIP** operator control can still trip breaker 1 or 2.

Press the **SELECT** pushbutton to select breaker 1 or breaker 2. If breaker 1 is selected, **BRKR1** LED is on and if breaker 2 is selected, **BRKR2** LED is on. The **SELECT** pushbutton allows a breaker selection before **CLOSE** or **TRIP** pushbuttons are used.

Press the **CLOSE** operator control pushbutton to close the selected breaker. Corresponding **BRKR CLOSED** LED illuminates to indicate the breaker is closed.

Option: Set a delay, so the operator can press the **CLOSE** operator control pushbutton and then move a safe distance away from the breaker before the SEL-787 issues a close (the **CLOSE** operator control comes with no set delay in the factory settings). With a set delay, press the **CLOSE** operator control pushbutton momentarily, and notice that the corresponding **BRKR CLOSED** LED flashes on and off during the delay time, indicating a pending close. Abort the pending close by pressing the **CLOSE** operator control pushbutton again or by pressing the **TRIP** operator control pushbutton. This delay setting for the **CLOSE** operator control is SV03PU (range: 0 to 3000 seconds; factory set at 0—no delay). The delay is set via the **SET L** command. See Table 4.30 for more information.

Press the **TRIP** operator control pushbutton to trip the selected breaker (and take the control to the lockout state). Corresponding **BRKR OPEN** LED illuminates to indicate the breaker is open.

Option: Set a delay, so the operator can press the **TRIP** operator control pushbutton and then move a safe distance away from the breaker before the SEL-787 issues a trip (the **TRIP** operator control comes with no set delay in the factory settings). With a set delay, press the **TRIP** operator control pushbutton momentarily and notice the corresponding **BRKR OPEN** LED flashes on and off during the delay time, indicating a pending trip. Abort the pending trip by pressing the **TRIP** operator control pushbutton again or by pressing the **CLOSE** operator control pushbutton. This delay setting for the **TRIP** operator control is SV04PU (range: 0 to 3000 seconds; factory-set at 0—no delay). The delay is set via the **SET L** command. See Table 4.30 for more information.



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Section 9

Analyzing Events

Overview

The SEL-787 Transformer Protection Relay provides several tools (listed below) to analyze the cause of relay operations. Use these tools to help diagnose the cause of the relay operation and more quickly restore the protected equipment to service.

- Event Reporting
 - Event Summary Reports
 - Event History Reports
 - Event Reports
- Sequential Events Recorder Report
 - Resolution: 1 ms
 - Accuracy: $\pm 1/4$ cycle

All reports are stored in nonvolatile memory, ensuring that a loss of power to the SEL-787 will not result in lost data.

Event Reporting

Analyze events with the following event reporting functions:

- Event Summaries—Enable automatic messaging to allow the relay to send event summaries out a serial port when port setting `AUTO := Y`. A summary provides a quick overview of an event. The summaries may also be retrieved by using the **SUMMARY** command.
- Event History—The relay keeps an index of stored nonvolatile event reports. Use the **HISTORY** command to obtain this index. The index includes some of the event summary information so that the appropriate event report can be identified and retrieved.
- Event Reports—These detailed reports are stored in nonvolatile memory for later retrieval and detailed analysis.

Each time an event occurs, a new summary, history record, and report are created. Event report information includes:

- Date and time of the event
- Individual sample analog inputs (currents and voltages)
- Digital states of selected Relay Word bits (listed in *Table J.1*)
- Event summary, including the front-panel target states at the time of tripping and fault type
- Group, Logic, Global, and Report settings (that were in service when the event was retrieved)

The SEL-787 provides Compressed ASCII event reports to facilitate event report storage and display. SEL communications processors and the SEL-5601 Analytic Assistant software take advantage of the Compressed ASCII format. Use the **CHIS** command to display Compressed ASCII event history information. Use the **CSUM** command to display Compressed ASCII event summary information. Use the **CEVENT** command to display Compressed ASCII event reports. See *Table C.2* for further information.

Compressed ASCII Event Reports contain *all* of the Relay Word bits.

Sequential Events Recorder (SER)

The SER report captures digital element state changes over time. Settings allow as many as 96 Relay Word bits to be monitored, in addition to the automatically generated triggers for relay power up, settings changes, and active setting group changes. State changes are time-tagged to the nearest millisecond. SER information is stored when state changes occur.

SER report data are useful in commissioning tests and during operation for system monitoring and control.

Event Reporting

Length

IMPORTANT: Changing the LER setting will clear all events in memory. Be sure to save critical event data prior to changing the LER setting.

The SEL-787 provides selectable event report length (LER) and predefault length (PRE). Event report length is either 15 or 64 cycles. Prefault length is 1–10 cycles for LER = 15 and 1–59 cycles for LER = 64. Prefault length is the first part of the total event report length and precedes the event report triggering point. Changing the PRE setting has no effect on the stored reports. The relay stores as many as 19 of the most recent 64-cycle or as many as 77 of the most recent 15-cycle event reports in nonvolatile memory. Refer to the **SET R** command in *SET Command (Change Settings) on page 7.36* and *Report Settings (SET R Command) on page SET.52*.

Triggering

The SEL-787 triggers (generates) an event report when any of the following occur:

- Relay Word bit TRIP asserts
- Programmable SELOGIC® control equation setting ER asserts (in Report settings)
- **TRI** (Trigger Event Reports) serial port command executes

Relay Word Bit TRIP

Refer to *Figure 4.49*. If Relay Word bit TR asserts to logical 1, an event report is automatically generated. Thus, any Relay Word bit that causes a trip does *not* have to be entered in SELOGIC control equation setting ER.

Programmable SELogic Control Equation Setting ER

The programmable SELOGIC control equation event report trigger setting ER is set to trigger event reports for conditions other than trip conditions (see **SET R** in *SET Command (Change Settings) on page 7.36*). When setting ER detects a logical 0 to logical 1 transition, it generates an event report (if the SEL-787 is not already generating a report that encompasses the new transition). The factory setting is shown in *Event Report Settings on page 4.108*.

TRI (Trigger Event Report) Command

The sole function of the **TRI** serial port command is to generate event reports, primarily for testing purposes. See *TRIGGER Command (Trigger Event Report)* on page 7.43 for more information on the **TRI** (Trigger Event Report) command.

Event Summaries

IMPORTANT: Clearing the HISTORY report with the **HIS C** command also clears all event data within the SEL-787 event memory.

For every triggered event, the relay generates and stores an event summary. The relay stores at least the most recent 77 (if event report length setting $LER := 15$) or at least 19 (if $LER := 64$) event summaries. When the relay stores a new event summary, it discards the oldest event and event summary if the event memory is full. Event summaries contain the following information:

- Relay and Terminal Identification (RID and TID)
- Event number, date, time, event type, and frequency (see *Table 9.1*)
- The primary magnitudes of winding phase, neutral (if optional neutral CT is available), and residual currents
- The primary magnitudes of the line to neutral voltage (if DELTA_Y := WYE) or phase-to-phase voltages (if DELTA_Y := DELTA), optional Voltage Inputs card required
- Hottest RTD temperatures, SEL-2600 RTD Module or internal RTD card option required

The relay includes the event summary in the event report. The identifiers, date, and time information are at the top of the event report, and the remaining information follows at the end (See *Figure 9.3*). The example event summary in *Figure 9.1* corresponds to the standard 15-cycle event report in *Figure 9.3*.

NOTE: Figure 9.3 is on multiple pages.

```

=>>>SUM <Enter>

SEL-787                                     Date: 02/14/2008   Time: 13:09:57.353
TRNSFRMR RELAY

Serial No = 0000000000000000
FID = SEL-787-X122HR-V0-Z001001-D20080212      CID = 26FF
EVENT LOGS = 1

Event:      Diff 87 Trip
Targets     11100000
Freq (Hz)   60.0

Winding One Current Mag
      IAW1      IBW1      ICW1      IGW1
(A)    512.0      213.8      215.0      295.00

Winding Two Current Mag
      IAW2      IBW2      ICW2      IGW2
(A)    2138.8      2144.4      2141.1      36.40

Neutral Current Mag
      IN
(A)      0.60

Voltage Mag
      VAB      VBC      VCA
(V)    13501    13500    13687
=>>>

```

Figure 9.1 Example Event Summary

The relay sends event summaries to all serial ports with setting `AUTO := Y` each time an event triggers.

Event Type

The **Event** field displays the event type. Event types and the logic used to determine event types are shown in *Table 9.1*.

Table 9.1 Event Types

| Event Type | Event Type Logic |
|----------------------|---|
| Diff 87 Trip | (87U OR 87R) AND TRIP |
| REF Trip | (REF1F OR REF1P) AND TRIP |
| Wdg1 Ph 50 Trip | (50P11T OR 50P12T OR 50P13T OR 50P14T) AND TRIP |
| Wdg1 Gnd 50 Trip | (50G11T OR 50G12T) AND TRIP |
| Wdg1 50Q Trip | (50Q11T OR 50Q12T) AND TRIP |
| Wdg2 Ph 50 Trip | (50P21T OR 50P22T OR 50P23T OR 50P24T) AND TRIP |
| Wdg2 Gnd 50 Trip | (50G21T OR 50G22T) AND TRIP |
| Wdg2 50Q Trip | (50Q21T OR 50Q22T) AND TRIP |
| Neutral 50 Trip | (50N11T OR 50N12T) AND TRIP |
| Wdg1 Ph 51 Trip | 51P1T AND TRIP |
| Wdg1 Gnd 51 Trip | 51G1T AND TRIP |
| Wdg1 51Q Trip | 51Q1T AND TRIP |
| Wdg2 Ph 51 Trip | 51P2T AND TRIP |
| Wdg2 Gnd 51 Trip | 51G2T AND TRIP |
| Wdg2 51Q Trip | 51Q2T AND TRIP |
| Neutral 51 Trip | 51N1T AND TRIP |
| PowerElemnt Trip | (3PWR1 OR 3PWR2) AND TRIP |
| Undervolt Trip | (27P1T OR 27P2T) AND TRIP |
| Overvolt Trip | (59P1T OR 59P2T OR 59Q1T OR 59Q2T) AND TRIP |
| Volt/Hz 24 Trip | (24D1T OR 24C2T) AND TRIP |
| Frequency 81 Trip | (81D1T OR 81D2T OR 81D3T OR 81D4T) AND TRIP |
| RTD Trip | RTDT AND TRIP |
| RTD Fail Trip | RTDFLT AND TRIP |
| Breaker Failure Trip | (BFT1 OR BFT2) AND TRIP |
| Remote Trip | REMTRIP AND TRIP |
| CommIdleLossTrip | (COMMIDLE OR COMMLOSS) AND TRIP |
| Trigger | Serial port TRI command |
| ER Trigger | ER Equation assertion |
| Trip | TRIP with no known cause |

Currents, Voltages, and RTD Temperatures

The relay determines the maximum winding current during an event. The instant the maximum winding current occurs is marked by an asterisk (*) in the event report (see *Figure 9.3*). This row of data corresponds to the analogs shown in the summary report for the event.

The `Current Mag` fields display the primary current magnitudes at the instant when the maximum winding current was measured. The currents displayed are listed below:

- Winding Currents (I_{AWn} , I_{BWn} , I_{CWn} , I_{GWn} $\{n = 1 \text{ and } 2\}$)
- Neutral Current (I_N)

The `Voltage Mag` fields display the primary voltage magnitudes at the instant when the maximum winding current was measured. The voltages displayed are listed below:

- `DELTA_Y := WYE`
 - Phase-to-Neutral Voltages (V_{AN} , V_{BN} , V_{CN})
 - Residual Voltage V_G , calculated from V_{AN} , V_{BN} , V_{CN}
- `DELTA_Y := DELTA`
 - Phase-to-Phase Voltages (V_{AB} , V_{BC} , V_{CA})

If the RTDs are connected, the hottest RTD (°C) fields display the hottest RTD reading in each RTD group. The hottest RTD temperatures in degrees centigrade (°C) are listed below:

- Ambient
- Other

Event History

The event history report gives you a quick look at recent relay activity. The relay labels each new event in reverse chronological order with 1 as the most recent event. See *Figure 9.2* for a sample event history. Use this report to view the events that are presently stored in the SEL-787.

The event history contains the following:

- Standard report header
 - Relay and terminal identification
 - Date and time of report
 - Time source (Internal or IRIG-B)
- Event number, date, time, event type (see *Table 9.1*)
- Maximum current
- Frequency (actual frequency if voltage card is available otherwise the nominal frequency)
- Target LED status

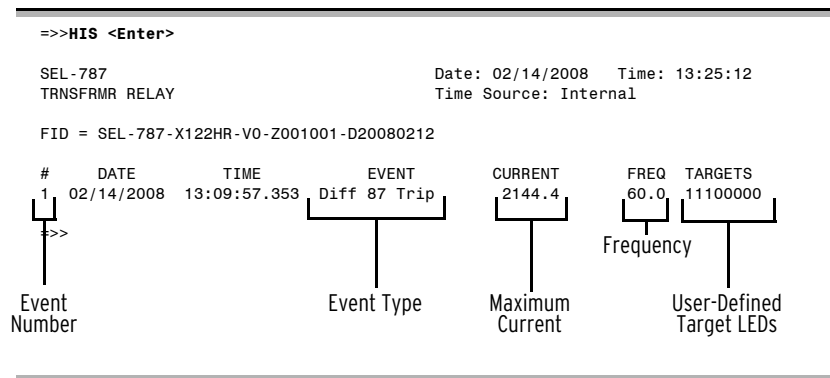


Figure 9.2 Sample Event History

Viewing the Event History

Access the history report from the communications ports, using the **HIS** command or the analysis menu within ACSELERATOR QuickSet. View and download history reports from Access Level 1 and higher.

Use the **HIS** command from a terminal to obtain the event history. You can specify the number of the most recent events that the relay returns. See *HISTORY Command on page 7.28* for information on the **HIS** command.

Use the front-panel **MAIN > Events > Display** menu to display event history data on the SEL-787 front-panel display.

Use the ACSELERATOR QuickSet software to retrieve the relay event history. View the **Relay Event History** dialog box via the **Analysis > Get Event Files** menu.

Clearing

Use the **HIS C** command to clear or reset history data from Access Levels 1 and higher. Clear/reset history data at any communications port. This will clear all event summaries, history records, and reports.

Event Reports

The latest event reports are stored in nonvolatile memory. The 787 relay captures the following types of data:

- Analog values
- Digital states of the protection and control elements, plus status of digital output and input states
- Event Summary
- Settings in service at the time of event retrieval, consisting of Group, Logic, Global, and Report settings classes

The SEL-787 supports the following three separate event report types:

- Standard Analog Event Report (**EVE** command)
- Digital Event Report (**EVE D** command)
- Differential Event Report (**EVE DIFz** command, where z = 1, 2, or 3 for the three 87 elements)

Analog Event Reports (EVE Command)

The Analog Event Report includes:

- Analog values of Winding 1 and 2 currents; IAW, IBW, ICW, IGW, (IGW only if voltage card is not used), neutral current IN (if available), voltages and frequency (if voltage card is used)
- Digital states of the base model digital inputs (2) and digital outputs (3)
- Event Summary
- Relay Settings

If the winding phase CTs are delta connected, the primary currents displayed are derived from the secondary values by multiplying them with CTR (CT ratio) and dividing them by the square root of 3. The phase angles shown are the same as the secondary values. If the CT connection type is known (DAB or DAC), the user can correct the phase angles. The MET response is meant to show steady-state primary values. During unbalanced conditions the primary line currents cannot be reproduced accurately because the delta-connected CTs filter out the zero-sequence component of the line current. Wye-connected CTs do not have any such issue.

Filtered and Unfiltered Analog Event Reports

The SEL-787 samples the power system measurands (ac voltage and ac current) 16 times per power system cycle. A digital filter extracts the fundamental frequency component of the measurands. The relay operates on the filtered values and reports these values in the standard, filtered event report.

To view the raw inputs to the relay, select the unfiltered event report using the **EVE R** command. Use the unfiltered event reports to observe power system conditions:

- Power system transients on current and voltage channels
- Decaying dc offset during fault conditions on current channels

Raw event reports display one extra cycle of data at the beginning of the report.

Also, unlike the filtered report, the raw event report shows the actual relay terminal voltage inputs so if the external connections are for DELTA input, $V_A = V_{ab}$, $V_B = 0$, $V_C = -V_{bc}$ (in primary volts).

Analog Event Report Column Definitions

Refer to the example analog event report in *Figure 9.3* to view event report columns. This example event report displays rows of information each 1/4 cycle. Retrieve this report with the **EVE** command.

The columns contain analog values, including ac current, ac voltage, and frequency, followed by base model input and output information.

NOTE: Figure 9.3 is on multiple pages.

Table 9.2 summarizes the analog event report columns.

Table 9.2 Analog Event Report Columns Definitions

| Column Heading | Column Symbols | Description |
|----------------|----------------|--|
| IAW1 | | Current measured by channel IA, Winding 1 (primary A) |
| IBW1 | | Current measured by channel IB, Winding 1 (primary A) |
| ICW1 | | Current measured by channel IC, Winding 1 (primary A) |
| IGW1 | | Residual current (IAW1 + IBW1 + ICW1, primary A), displayed only when no voltages are shown |
| IAW2 | | Current measured by channel IA, Winding 2 (primary A) |
| IBW2 | | Current measured by channel IB, Winding 2 (primary A) |
| ICW2 | | Current measured by channel IC, Winding 2 (primary A) |
| IGW2 | | Residual current (IAW2 + IBW2 + ICW2, primary A), displayed only when no voltages are shown |
| IN | | Current measured by channel IN (primary A) when neutral CT is present |
| VAN or VAB | | Voltage measured by channel VAN or VAB (primary V), requires voltage input |
| VCN or VCA | | Voltage measured by channel VCN or VCA calculated from VAB and VBC (primary V), requires voltage input |
| In 12 | 1 | IN101 AND NOT IN102 |
| | 2 | NOT IN101 AND IN102 |
| | b | IN101 AND IN102 |
| Out 12 | 1 | OUT101 AND NOT OUT102 |
| | 2 | NOT OUT101 AND OUT102 |
| | b | OUT101 AND OUT102 |
| Out 3 | 3 | OUT103 |

Note that the ac values change from plus to minus (–) values in *Figure 9.3*, indicating the sinusoidal nature of the waveforms.

Other figures help in understanding the information available in the event report current columns:

- *Figure 9.4* shows how analog event report current column data relate to the actual sampled current waveform and rms current values.
- *Figure 9.5* shows how analog event report current column data can be converted to phasor rms current values.

Example 15-Cycle Event Report

The following example of a standard analog 15-cycle event report in *Figure 9.3* also corresponds to the example SER report in *Figure 9.8*.

In *Figure 9.3*, an arrow (>) in the column following the VCA column would identify the “trigger” row. This is the row that corresponds to the Date and Time values at the top of the event report.

The asterisk (*) in the column following the VCA column identifies the row with the maximum phase current. The maximum phase current is calculated from the row identified with the asterisk and the row one quarter-cycle

previous (see *Figure 9.4* and *Figure 9.5*). These currents are listed at the end of the event report in the event summary. If the trigger row (>) and the maximum phase current row (*) are the same row, the * symbol takes precedence.

```

=>>EVE <Enter>
SEL-787
TRNSFRMR RELAY
Serial Number=0000000000000000
FID=SEL-787-X122HR-V0-Z001001-D20080212 CID=26FF
Date: 02/14/2008 Time: 13:09:57.353
Date and Time of Event

0
I
u
n
t
1 13
2 2
Currents (A Pri)
IAW1 IBW1 ICW1 IAW2 IBW2 ICW2 IN VAB VBC VCA Freq
[1]
-54.5 206.0 -150.5 580.0-2085.0 1460.0 -0.6 12582 -10400 -2182 60.03 . .
-206.5 56.0 153.0 2055.0 -505.0-1560.0 0.0 4900 8612 -13512 60.03 . .
54.0 -206.5 149.5 -590.0 2080.0-1465.0 0.0 -12584 10398 2186 60.03 . .
206.0 -56.5 -153.5-2060.0 495.0 1555.0 -1.2 -4895 -8616 13511 60.03 . .
[2]
-54.5 206.0 -150.5 590.0-2085.0 1460.0 -1.2 12586 -10391 -2195 60.02 . .
-206.5 55.5 153.5 2050.0 -500.0-1560.0 1.2 4886 8623 -13510 60.02 . .
54.5 -206.5 149.5 -590.0 2080.0-1460.0 0.0 -12590 10390 2201 60.02 . .
206.0 -56.0 -154.0-2065.0 495.0 1555.0 -1.8 -4883 -8626 13508 60.02 . .
[3]
-55.5 206.0 -150.0 585.0-2085.0 1455.0 -0.6 12590 -10384 -2207 60.03 . .
-206.5 55.5 153.5 2050.0 -500.0-1560.0 1.2 4878 8632 -13510 60.03 . .
50.0 -207.0 149.5 -595.0 2080.0-1460.0 0.0 -12594 10380 2214 60.03 . .
294.0 -55.5 -154.0-2055.0 495.0 1560.0 -1.8 -4872 -8636 13508 60.03 . .
[4]
-89.0 206.5 -150.0 590.0-2085.0 1450.0 -0.6 12595 -10375 -2220 60.02 . .
-438.5 55.0 153.5 2055.0 -500.0-1565.0 0.6 4864 8644 -13507 60.02 . .
131.5 -207.0 149.5 -595.0 2080.0-1455.0 0.0 -12599 10370 2228 60.02 . .
493.5 -55.5 -154.5-2060.0 490.0 1560.0 -1.2 -4858 -8647 13505 60.02 . .
[5]
-132.5 206.5 -150.0 590.0-2085.0 1450.0 -0.6 12600 -10363 -2237 60.03 . .
-494.0 55.0 154.0 2055.0 -495.0-1560.0 0.6 4852 8652 -13504 60.03 . .
132.0 -207.0 149.0 -600.0 2080.0-1460.0 0.0 -12604 10361 2243 60.03 . .
493.5 -55.5 -154.5-2060.0 485.0 1560.0 -1.2 -4848 -8654 13502 60.03> . .
[6]
-133.0 207.0 -149.5 595.0-2085.0 1455.0 -0.6 12607 -10358 -2249 60.03 . .
-494.0 54.5 154.0 2050.0 -490.0-1565.0 0.0 4838 8663 -13501 60.03 . .
132.0 -207.5 148.5 -600.0 2080.0-1460.0 0.0 -12611 10356 2255 60.03 . .
493.5 -55.0 -154.0-2055.0 485.0 1560.0 -1.2 -4832 -8668 13500 60.03 . .
[7]
-133.0 207.0 -149.5 595.0-2085.0 1450.0 -0.6 12611 -10348 -2263 60.02 . .
-494.0 54.5 154.0 2050.0 -490.0-1570.0 0.6 4826 8674 -13500 60.02 . .
133.0 -207.5 149.0 -600.0 2080.0-1450.0 0.6 -12613 10344 2269 60.02 . .
493.0 -54.5 -154.5-2055.0 485.0 1560.0 -1.2 -4819 -8677 13496 60.02 . .
[8]
-133.5 207.0 -149.5 600.0-2085.0 1450.0 -1.2 12614 -10340 -2274 60.03 . .
-493.5 54.0 154.0 2050.0 -490.0-1565.0 0.6 4812 8684 -13496 60.03 . .
133.0 -207.0 149.5 -600.0 2085.0-1455.0 0.0 -12617 10337 2280 60.03 . .
493.5 -55.5 -154.5-2060.0 480.0 1560.0 -1.2 -4808 -8688 13496 60.03 . .
[9]
-134.0 206.5 -149.5 595.0-2085.0 1450.0 -0.6 12618 -10330 -2288 60.02 . .
-493.5 54.5 154.5 2050.0 -485.0-1570.0 0.6 4802 8694 -13496 60.02 . .
133.5 -207.5 148.5 -605.0 2080.0-1455.0 0.0 -12623 10327 2296 60.02 . .
493.0 -55.0 -155.0-2055.0 480.0 1565.0 -1.8 -4798 -8698 13495 60.02 . .
[10]
-134.5 207.0 -149.5 600.0-2090.0 1445.0 -0.6 12625 -10322 -2303 60.03 . .
-494.0 54.0 154.5 2050.0 -485.0-1575.0 0.6 4789 8705 -13494 60.03 . .
134.5 -207.5 149.0 -605.0 2085.0-1450.0 0.0 -12629 10319 2310 60.03 . .
493.5 -54.5 -155.0-2060.0 480.0 1570.0 -0.6 -4784 -8708 13493 60.03 . .
[11]
-135.5 207.0 -149.0 605.0-2090.0 1440.0 -1.2 12629 -10313 -2316 60.03 . .
-493.5 53.5 154.5 2050.0 -480.0-1575.0 0.0 4776 8714 -13490 60.03 . .
135.0 -207.5 148.5 -605.0 2085.0-1450.0 0.6 -12634 10312 2322 60.03 . .
492.5 -54.0 -155.5-2055.0 475.0 1570.0 -1.2 -4771 -8718 13489 60.03 . .
[12]
-135.5 207.0 -148.5 600.0-2090.0 1440.0 -1.2 12635 -10306 -2329 60.03 . .
-493.0 53.5 154.5 2050.0 -480.0-1575.0 0.6 4764 8725 -13489 60.03 . .
135.5 -207.5 148.0 -605.0 2085.0-1445.0 0.0 -12637 10303 2334 60.03 . .
492.5 -54.0 -155.5-2055.0 470.0 1575.0 -1.8 -4760 -8729 13489 60.03 . .
Optional Voltage Card Required
One Cycle of Data

```

Figure 9.3 Example Standard 15-Cycle Analog Event Report 1/4-Cycle Resolution (Sheet 1 of 4)

[13]

| | | | | | | | | | | | | |
|--------|--------|--------|---------|---------|---------|------|--------|--------|--------|-------|---|---|
| -136.0 | 206.5 | -149.0 | 605.0 | -2090.0 | 1440.0 | -1.2 | 12637 | -10298 | -2339 | 60.03 | . | * |
| -493.0 | 53.5 | 155.0 | 2050.0 | -475.0 | -1580.0 | 1.2 | 4753 | 8736 | -13489 | 60.03 | . | * |
| 136.0 | -207.5 | 148.5 | -615.0 | 2080.0 | -1445.0 | 0.0 | -12641 | 10295 | 2346 | 60.03 | . | * |
| 492.5 | -54.5 | -156.0 | -2055.0 | 475.0 | 1570.0 | -1.2 | -4747 | -8738 | 13486 | 60.03 | . | * |

[14]

| | | | | | | | | | | | | |
|--------|--------|--------|---------|---------|---------|------|--------|--------|--------|--------|---|---|
| -136.5 | 207.0 | -148.5 | 610.0 | -2090.0 | 1445.0 | -0.6 | 12642 | -10288 | -2354 | 60.02 | . | * |
| -493.5 | 53.5 | 155.5 | 2050.0 | -480.0 | -1580.0 | 0.0 | 4741 | 8742 | -13483 | 60.02* | . | * |
| 136.0 | -207.5 | 148.0 | -615.0 | 2085.0 | -1450.0 | 0.0 | -12646 | 10285 | 2360 | 60.02 | . | * |
| 492.5 | -54.0 | -156.0 | -2050.0 | 465.0 | 1575.0 | -0.6 | -4734 | -8747 | 13481 | 60.02 | . | * |

```
[15]
-137.0  207.0 -148.0  610.0 -2090.0 1440.0 -0.6 12647 -10279 -2368 60.03 . *
-493.0  53.0 155.5 2045.0 -470.0 -1580.0 0.0 4727 8754 -13481 60.03 . *
136.5 -207.5 147.5 -615.0 2080.0 -1440.0 0.0 -12650 10278 2372 60.03 . *
492.0 -53.5 -155.5 -2055.0 470.0 1575.0 -1.2 -4723 -8758 13481 60.03 . *
```

- Firmware Identifier

- Firmware Checksum Identifier

Winding One Current Mag

Winding Two Current Mag

Neutral Current Mag

Voltage Mag

Global Settings

$$\text{EPMU} \quad := \quad N$$

THFLTD := OFF

IN101D := 10 IN102D := 10

```
RSTTRGT := 0
```

DSABLSET:= 0

Group Settings

RID := SEL-787

TID := TRANSFRMR RELAY

| | | | | | |
|------|----|-----|------|----|-----|
| W1CT | := | WYE | W2CT | := | WYE |
| CTE1 | := | CTE | CTE2 | := | CTE |

| | | | | | | | |
|-------|-----------|-------|----------|-----|---------|------|------|
| CTR1 | := 100 | CTR2 | := 1000 | MVA | := 50.0 | ICOM | := N |
| VWDC1 | := 138.00 | VWDC2 | := 13.80 | | | | |

VWDG1 := 138.00 VWDG2 := 13.80
CTBN1 := 120 PTR := 120.00

```

STRNT      := 120      FTR      := 120.00      VNCM      := 10.00      BETA_1  := BETA
VIWDG      := 2        SINGLEV  := N

```

```
E87      := Y      TAP1      := 2.09      TAP2      := 2.09
```

```
087P      := 0.30      87AP      := 0.15      87AD      := 5.0      SLP1      := 25
```

```
SLP2      := 50      IRS1      := 3.0
```

```
U87P      := 10.0    PCT2      := 15      PCT4      := OFF    PCT5      := 35
TH5P      := OFF     UPSTR      := Y       UPLK       := N
```

THSP := OFF HRSTR := Y HBLK := N

```
REF1POL := OFF      REF1TC  := 1
```

50REF1P := 0.25

Figure 9.3 Example Standard 15-Cycle Analog Event Report 1/4-Cycle Resolution (Sheet 2 of 4)

```
50P11P := 10.00 50P11D := 0.00 50P11TC := 1
50P12P := 10.00 50P12D := 0.00 50P12TC := 1
50P13P := 10.00 50P13D := 0.00 50P13TC := 1
50P14P := 10.00 50P14D := 0.00 50P14TC := 1
50G11P := OFF 50G12P := OFF 50Q11P := OFF 50Q12P := OFF
51P1P := 6.00 51P1C := U3 51P1TD := 3.00 51P1RS := N
51P1CT := 0.00 51P1MR := 0.00 51P1TC := 1

51G1P := 0.50 51G1C := U3 51G1TD := 1.50 51G1RS := N
51G1CT := 0.00 51G1MR := 0.00 51G1TC := 1

51Q1P := 6.00 51Q1C := U3 51Q1TD := 3.00 51Q1RS := N
51Q1CT := 0.00 51Q1MR := 0.00 51Q1TC := 1
50P21P := 10.00 50P21D := 0.00 50P21TC := 1
50P22P := 10.00 50P22D := 0.00 50P22TC := 1
50P23P := 10.00 50P23D := 0.00 50P23TC := 1
50P24P := 10.00 50P24D := 0.00 50P24TC := 1
50G21P := OFF 50G22P := OFF 50Q21P := OFF 50Q22P := OFF
51P2P := 6.00 51P2C := U3 51P2TD := 3.00 51P2RS := N
51P2CT := 0.00 51P2MR := 0.00 51P2TC := 1

51G2P := 0.50 51G2C := U3 51G2TD := 1.50 51G2RS := N
51G2CT := 0.00 51G2MR := 0.00 51G2TC := 1

51Q2P := 6.00 51Q2C := U3 51Q2TD := 3.00 51Q2RS := N
51Q2CT := 0.00 51Q2MR := 0.00 51Q2TC := 1

50N11P := OFF 50N12P := OFF 51N1P := OFF

E49RTD := NONE
27P1P := OFF 27P2P := OFF
59P1P := OFF 59P2P := OFF
59Q1P := OFF 59Q2P := OFF
E24 := Y 24WDG := WYE 24D1P := 105
24D1D := 1.00 24CCS := ID 24IP := 105 24IC := 2.0
24ITD := 0.1
24D2P2 := 176 24D2D2 := 3.00 24CR := 240.00 24TC := 1

EPWR := N

81D1TP := OFF 81D2TP := OFF
81D3TP := OFF
81D4TP := OFF
EDEM := OFF
EALIAS := 4

ALIAS1 :=PB01 FP_AUX1 PICKUP DROPOUT
ALIAS2 :=PB02 FP_LOCK PICKUP DROPOUT
ALIAS3 :=PB03 FP_CLOSE PICKUP DROPOUT
ALIAS4 :=PB04 FP_TRIP PICKUP DROPOUT

ER := R_TRIG ORED51P OR R_TRIG ORED50P
LER := 15 PRE := 5

LDLIST := NA
LDAR := 15

TDURD := 0.5 CFD1 := 0.5 CFD2 := 0.5
TR1 := 50P11T OR 51P1T OR 51Q1T OR NOT LT02 AND SV04T OR OC1
TR2 := 51P2T OR 51Q2T OR LT02 AND SV04T OR OC2
TRXFMR := 87R OR 87U
REMTRIP := 0
ULTRIP1 := 0
ULTRIP2 := 0
ULTRXFMR := 0
52A1 := 0
CL1 := TRIP1 OR TRIPXFMR
ULCL1 := SV03T AND LT02 OR CC2
52A2 := SV03T AND NOT LT02 OR CC1
CL2 := 0
ULCL2 := TRIP2 OR TRIPXFMR

Report Settings

ESERDEL := N

SER1 := IN101 IN102 PB01 PB02 PB03 PB04 52A1 52A2 TRIP1 TRIP2 TRIPXFMR
SER2 := ORED51T ORED50T 87U 87R 27P1T 27P2T 59P1T 59P2T 59Q1T 59Q2T 3PWR1T
3PWR2T REF1F 24D1T 24C2T RTDT
SER3 := 81D1T 81D2T 81D3T 81D4T
SER4 := SALARM
```

Figure 9.3 Example Standard 15-Cycle Analog Event Report 1/4-Cycle Resolution (Sheet 3 of 4)

```

Logic Settings

ELAT      := 4      ESV      := 5      ESC      := N      EMV      := N

SET01     := R_TRIG SV01T AND NOT LT01
RST01     := R_TRIG SV01T AND LT01
SET02     := R_TRIG SV02T AND NOT LT02 AND PB02
RST02     := R_TRIG SV02T AND LT02 AND PB02
SET03     := (PB03 AND R_TRIG SV02T) AND LT01 AND NOT (52A1 AND NOT LT02 OR 52A2 AND LT02)
RST03     := (R_TRIG SV02T OR SV03T) AND LT03
SET04     := (PB04 AND R_TRIG SV02T) AND (52A1 AND NOT LT02 OR 52A2 AND LT02)
RST04     := (R_TRIG SV02T OR SV04T) AND LT04

SV01PU    := 3.00    SV01D0   := 0.00
SV01      := PB01
SV02PU    := 0.25    SV02D0   := 0.00
SV02      := PB01 OR PB02 OR PB03 OR PB04
SV03PU    := 0.00    SV03D0   := 0.00
SV03      := LT03
SV04PU    := 0.00    SV04D0   := 0.00
SV04      := LT04
SV05PU    := 0.25    SV05D0   := 0.25
SV05      := (PB01 OR PB02 OR LT03 OR LT04) AND NOT SV05T

OUT101FS:= Y      OUT101    := HALARM OR SALARM
OUT102FS:= N      OUT102    := 0
OUT103FS:= N      OUT103    := TRIPXFM
=>

```

Figure 9.3 Example Standard 15-Cycle Analog Event Report 1/4-Cycle Resolution (Sheet 4 of 4)

Figure 9.4 and Figure 9.5 look in detail at an example of one cycle of A-phase current (channel IA) data similar to what is shown in Figure 9.3. Figure 9.4 shows how the event report ac current column data relate to the actual sampled waveform and rms values. Figure 9.5 shows how the event report current column data can be converted to phasor rms values. Voltages are processed similarly.

In *Figure 9.4*, note that any two rows of current data from the analog event report, 1/4 cycle apart, can be used to calculate rms current values.

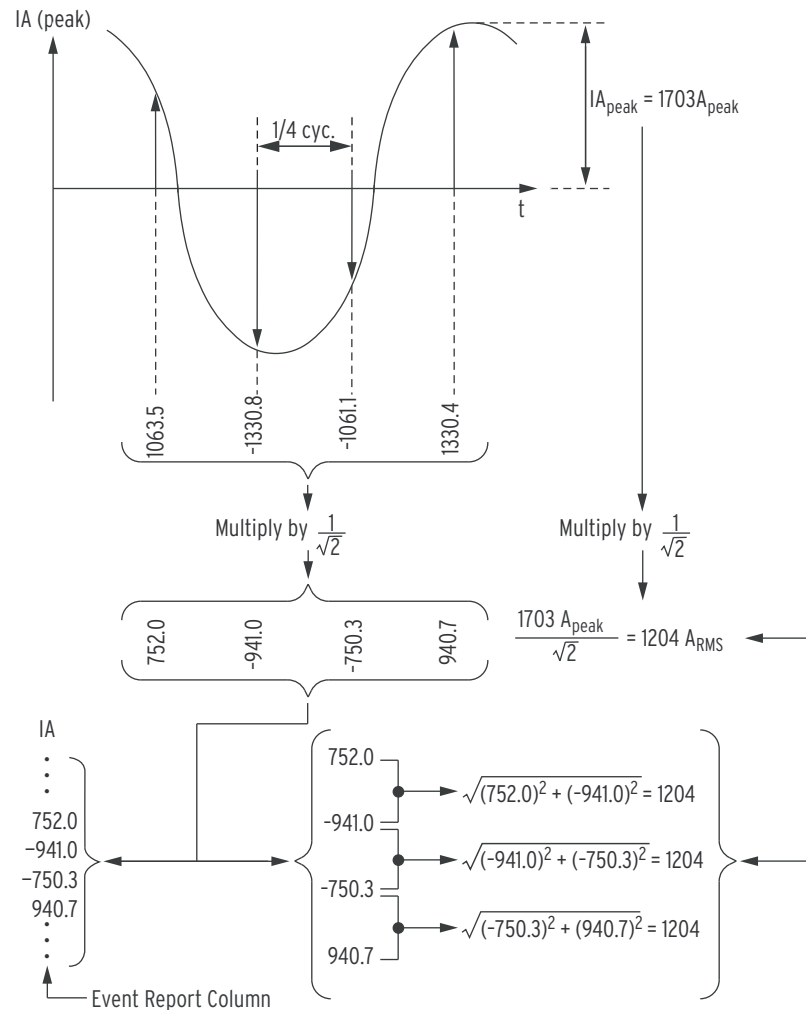


Figure 9.4 Derivation of Analog Event Report Current Values and RMS Current Values From Sampled Current Waveform

In *Figure 9.5*, note that two rows of current data from the analog event report, 1/4 cycle apart, can be used to calculate phasor rms current values. In *Figure 9.5*, at the present sample, the phasor rms current value is:

$$IA = 1204 \text{ A } \angle -38.6^\circ \quad \text{Equation 9.1}$$

The present sample ($IA = 940.7 \text{ A}$) is a real rms current value that relates to the phasor rms current value:

$$1204 \text{ A} \cdot \cos(-38.6^\circ) = 940.7 \text{ A} \quad \text{Equation 9.2}$$

NOTE: The arctan function of many calculators and computing programs does not return the correct angle for the second and third quadrants (when X is negative). When in doubt, graph the X and Y quantities to confirm that the angle that your calculator reports is correct.

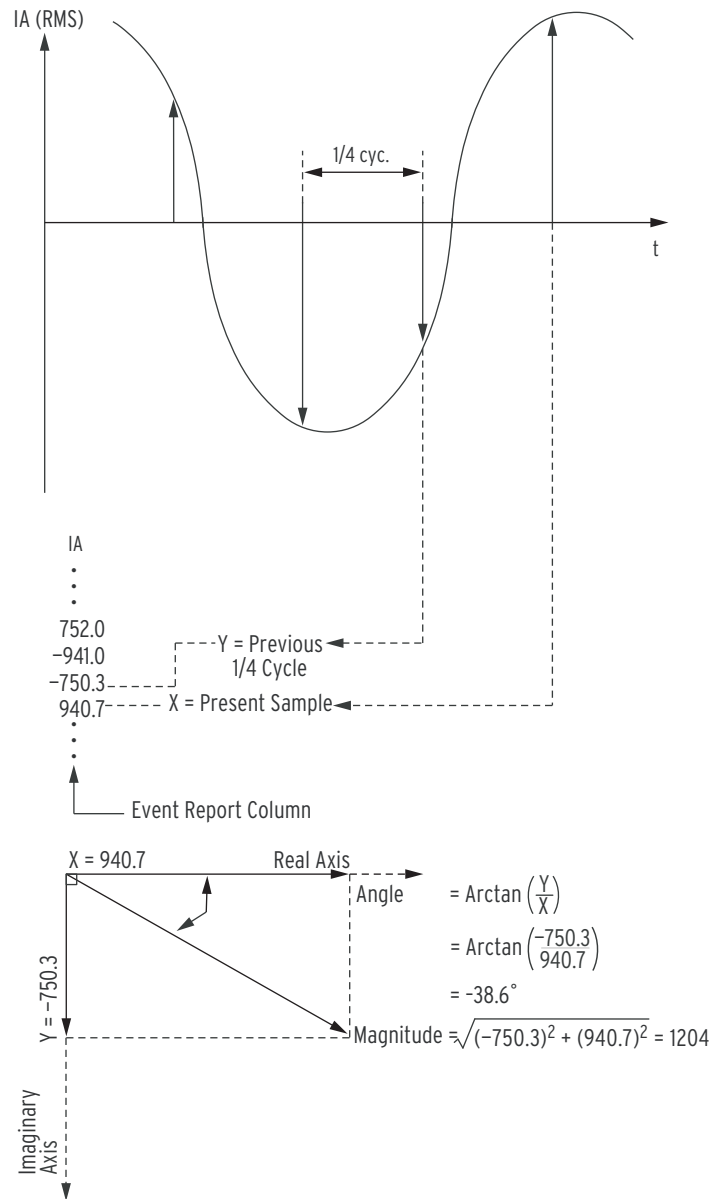


Figure 9.5 Derivation of Phasor RMS Current Values From Event Report Current Values

Digital Event Report (EVE D Command)

The digital event report includes:

- Digital states of control and protection elements, including overcurrent and voltage elements (if voltage inputs are available), plus status of digital inputs and outputs and RTD status
- Event Summary
- Relay Settings

Use the **EVE D n** command to view the normal digital report with 4 samples/cycle for report *n* (if not listed, *n* is assumed to be 1). **EVE D R** gives the RAW report with 16 samples/cycle.

Refer to the example event report in *Figure 9.6* to view the digital event report columns.

This example event report displays rows of information each 1/4 cycle.
Retrieve this report with the **EVE D** command.

Table 9.3 gives the digital event report column definitions for the protection and control elements and the inputs and outputs.

Table 9.3 Digital Event Report Column Definitions (Sheet 1 of 4)

| Column Designation | Column Symbols | Column Symbol Relay Word Bits (RWB) |
|--------------------|----------------|---|
| 50P11 | * t | 50P11P picked up 50 P11T picked up |
| 50P12 | * t | 50P12P picked up 50P12T picked up |
| 50P13 | * t | 50P13P picked up 50P13T picked up |
| 50P14 | * t | 50P14P picked up 50P14T picked up |
| 50G11 | * t | 50G11P picked up 50G11T picked up |
| 50G12 | * t | 50G12P picked up 50G12T picked up |
| 50Q11 | * t | 50Q11P picked up 50Q11T picked up |
| 50Q12 | * t | 50Q12P picked up 50Q12T picked up |
| 51P1 | * t r | 51P1P picked up 51P1T picked up 51P1R picked up |
| 51G1 | * t r | 51G1P picked up 51G1T picked up 51G1R picked up |
| 51Q1 | * t r | 51Q1P picked up 51Q1T picked up 51Q1R picked up |
| 51P21 | * t | 51P21P picked up 51P21T picked up |
| 51P22 | * t | 51P22P picked up 51P22T picked up |
| 51P23 | * t | 51P23P picked up 51P23T picked up |
| 51P24 | * t | 51P24P picked up 51P24T picked up |
| 51G21 | * t | 51G21P picked up 51G21T picked up |
| 51G22 | * t | 51G22P picked up 51G22T picked up |
| 51Q21 | * t | 51Q21P picked up 51Q21T picked up |
| 51Q22 | * t | 51Q22P picked up 51Q22T picked up |

NOTE: Active bits will depend on the options included in the relay.

Table 9.3 Digital Event Report Column Definitions (Sheet 2 of 4)

| Column Designation | Column Symbols | Column Symbol Relay Word Bits (RWB) |
|--------------------|----------------|---|
| 51P2 | * t r | 51P2P picked up 51P2T picked up 51P2R picked up |
| 51G2 | * t r | 51G2P picked up 51G2T picked up 51G2R picked up |
| 51Q2 | * t r | 51Q2P picked up 51Q2T picked up 51Q2R picked up |
| 50N1 | * t | 50N1P picked up 50N1T picked up |
| 50N2 | * t | 50N2P picked up 50N2T picked up |
| 51N1 | * t r | 51N1P picked up 51N1T picked up 51N1R picked up |
| 27P1 | * t | 27P1 picked up 27P1T picked up |
| 27P2 | * t | 27P2 picked up 27P2T picked up |
| 59P1 | * t | 59P1 picked up 59P1T picked up |
| 59P2 | * t | 59P2 picked up 59P2T picked up |
| 24D1 | 1 D | 24D1 picked up 24D1T picked up |
| 24C2 | 2 C r | 24C2 picked up 24C2T picked up 24CR picked up |
| 3PW1 | * t | 3PWR1P picked up 3PWR1T picked up |
| 3PW2 | * t | 3PWR2P picked up 3PWR2T picked up |
| 81D12 | 1 2 b | 81D1T picked up 81D2T picked up Both 81D1T and 81D2T picked up |
| 81D34 | 3 4 b | 81D3T picked up 81D4T picked up Both 81D3T and 81D4T picked up. |
| BFI1 | * t | BFI1 picked up BFT1 picked up |
| BFI2 | * t | BFI2 picked up BFT2 picked up |
| TRIP | * | TRIP picked up |
| REF | * f r | REF1P picked up REF1F picked up REF1R picked up |

Table 9.3 Digital Event Report Column Definitions (Sheet 3 of 4)

| Column Designation | Column Symbols | Column Symbol Relay Word Bits (RWB) |
|--------------------|----------------|-------------------------------------|
| Inputs 3012 | 1 | IN301 picked up |
| | 2 | IN302 picked up |
| | b | Both IN301 and IN302 picked up |
| Inputs 3034 | 3 | IN303 picked up |
| | 4 | IN304 picked up |
| | b | Both IN303 and IN304 picked up |
| Inputs 3056 | 5 | IN305 picked up |
| | 6 | IN306 picked up |
| | b | Both IN305 and IN305 picked up |
| Inputs 3078 | 7 | IN307 picked up |
| | 8 | IN308 picked up |
| | b | Both IN307 and IN308 picked up |
| Inputs 4012 | 1 | IN401 picked up |
| | 2 | IN402 picked up |
| | b | Both IN401 and IN402 picked up |
| Inputs 4034 | 3 | IN403 picked up |
| | 4 | IN404 picked up |
| | b | Both IN403 and IN404 picked up |
| Inputs 4056 | 5 | IN405 picked up |
| | 6 | IN406 picked up |
| | b | Both IN405 and IN406 picked up |
| Inputs 4078 | 7 | IN407 picked up |
| | 8 | IN408 picked up |
| | b | Both IN407 and IN408 picked up |
| Inputs 5012 | 1 | IN501 picked up |
| | 2 | IN502 picked up |
| | b | Both IN501 and IN502 picked up |
| Inputs 5034 | 3 | IN503 picked up |
| | 4 | IN504 picked up |
| | b | Both IN503 and IN504 picked up |
| Inputs5056 | 5 | IN505 picked up |
| | 6 | IN506 picked up |
| | b | Both IN505 and IN506 picked up |
| Inputs 5078 | 7 | IN507 picked up |
| | 8 | IN508 picked up |
| | b | Both IN507 and IN508 picked up |
| Outputs 3012 | 1 | OUT301 picked up |
| | 2 | OUT302 picked up |
| | b | Both OUT301 and OUT302 picked up |
| Outputs 3034 | 3 | OUT303 picked up |
| | 4 | OUT304 picked up |
| | b | Both OUT303 and OUT304 picked up |
| Outputs 4012 | 1 | OUT401 picked up |
| | 2 | OUT402 picked up |
| | b | Both OUT401 and OUT402 picked up |
| Outputs 4034 | 3 | OUT403 picked up |
| | 4 | OUT404 picked up |
| | b | Both OUT403 and OUT404 picked up |
| Outputs 5012 | 1 | OUT501 picked up |
| | 2 | OUT502 picked up |
| | b | Both OUT501 and OUT502 picked up |

Table 9.3 Digital Event Report Column Definitions (Sheet 4 of 4)

| Column Designation | Column Symbols | Column Symbol Relay Word Bits (RWB) |
|--------------------|----------------|-------------------------------------|
| Outputs 5034 | 3 | OUT503 picked up |
| | 4 | OUT504 picked up |
| | b | Both OUT503 and OUT504 picked up |
| RTD Amb | a | AMBALRM picked up |
| | t | AMBTRIP picked up |
| RTD Oth | a | OTHALRM picked up |
| | t | OTHTRIP picked up |
| In12 | 1 | IN101 picked up |
| | 2 | IN102 picked up |
| | b | Both IN101 and IN102 picked up |
| Out12 | 1 | OUT101 picked up |
| | 2 | OUT102 picked up |
| | b | Both OUT101 and OUT102 picked up |
| Out3 | * | OUT103 picked up |

NOTE: The Event Summary and Settings are not shown here as they are the same as in Figure 9.3.

=>>EVE D <Enter>

SEL-787
TRANSFRM RELAY

Date: 02/14/2008 Time: 13:09:57.353

Serial Number=0000000000000000
FID=SEL-787-X122HR-V0-Z001001-D20080212 CID=26FF

| Winding1 | Winding2 | Optional I/O | Inputs | Outputs | RTD | O | | | | | | | | |
|--------------|--------------|--------------|--------|---------|-------|-----|-------|-----|-------|--------------|--------------|--------|-------|-------|
| 50 | 51 | 50 | 51 | 555 | 2255 | 22 | 33 | 81 | BB | T | 333344445555 | 334455 | I | u |
| PPPPGGQQPGQ | PPPPGGQQPGQ | 001 | 7799 | 44 | PP | DD | FF | R | R | 000000000000 | 000000 | A0 | n | t |
| 111111111111 | 222222222222 | NNN | PPPP | DC | WW | 13 | II | E | I | 135713571357 | 131313 | mt | 1 | 13 |
| 12341212 | 12341212 | 121 | 1212 | 12 | 12 | 24 | 12 | F | P | 246824682468 | 242424 | bh | 2 | 2 |
| [1] | | | | | | | | | | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
| [2] | | | | | | | | | | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
| [3] | | | | | | | | | | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
| [4] | | | | | | | | | | | | | | |
|f f f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
| [5] | | | | | | | | | | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
| [6] | | | | | | | | | | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
| [7] | | | | | | | | | | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |
|f * f |f f f | ..f |f | ..f |f | ..f |f | ..f |f | | | | | |

Figure 9.6 Example Standard 15-cycle Digital Event Report (EVE D Command) 1/4 Cycle Resolution (Sheet 1 of 2)

| | | | | | | | | | |
|---------|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| [8] | | | | | | | | | |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
| [9] | | | | | | | | | |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
| [10] | | | | | | | | | |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
| [11] | | | | | | | | | |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
| [12] | | | | | | | | | |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
| [13] | | | | | | | | | |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
| [14] | | | | | | | | | |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
| [15] | | | | | | | | | |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |
|R* |R |R |R |R |R |R |R |R |* |

Figure 9.6 Example Standard 15-cycle Digital Event Report (EVE D Command) 1/4 Cycle Resolution (Sheet 2 of 2)

Differential Event Report (EVE DIFz Command)

The differential event report includes:

- Differential analog quantities for 87-1, 87-2 and 87-3 differential elements
- Digital states of differential and harmonic protection elements, plus status of base model digital inputs and outputs
- Event summary
- Relay settings

Use the **EVE DIFz n** command to view the normal Differential Report ($z = 1$ for 87-1 element, $z = 2$ for 87-2 element and $z = 3$ for 87-3 element) with 4 samples/cycle for report n (if not listed, n is assumed to be 1).

Refer to the example event report in *Figure 9.7* to view the differential event report columns. This example event report displays rows of information each 1/4 cycle. Retrieve this report with the **EVE DIF1** command.

Table 9.4 gives the Differential event report column definitions for the Analog Quantities IOPz, IRTz, IzF2 and IzF5 for $z = 1, 2$ and 3. *Table 9.5* gives the Differential event report digital column definitions for the Protection and Control elements and the base model inputs and outputs.

Table 9.4 Differential Event Report Column Definitions for Analog Quantities

| Column Heading | Description |
|----------------|--|
| IOP1 | Operate Current for Differential element 87-1 (multiples of TAP) |
| IRT1 | Restraint Current for Differential element 87-1 (multiples of TAP) |
| I1F2 | Second Harmonic current for Differential element 87-1 (multiples of TAP) |
| I1F5 | Fifth Harmonic current for Differential element 87-1 (multiples of TAP) |
| IOP2 | Operate Current for Differential element 87-2 (multiples of TAP) |
| IRT2 | Restraint Current for Differential element 87-2 (multiples of TAP) |
| I2F2 | Second Harmonic current for Differential element 87-2 (multiples of TAP) |
| I2F5 | Fifth Harmonic current for Differential element 87-2 (multiples of TAP) |
| IOP3 | Operate Current for Differential element 87-3 (multiples of TAP) |
| IRT3 | Restraint Current for Differential element 87-3 (multiples of TAP) |
| I3F2 | Second Harmonic current for Differential element 87-3 (multiples of TAP) |
| I3F5 | Fifth Harmonic current for Differential element 87-3 (multiples of TAP) |

Table 9.5 Differential Event Report Digital Column Definitions for Protection, Control, and I/O Elements (Sheet 1 of 2)

| Column Designation | Column Symbols | Column Symbol Relay Word Bits (RWB) |
|--------------------|----------------|-------------------------------------|
| 87R | * | 87R picked up |
| 87R12 | 1 | 87R1 picked up |
| | 2 | 87R2 picked up |
| | b | Both 87R1 and 87R2 picked up |
| 87R3 | * | 87R3 picked up |
| 87U12 | 1 | 87U1 picked up |
| | 2 | 87U2 picked up |
| | b | Both 87U1 and 87U2 picked up |
| 87U3 | * | 87U3 picked up |
| 87B12 | 1 | 87BL1 picked up |
| | 2 | 87BL2 picked up |
| | b | Both 87BL1 and 87BL2 picked up |
| 87B3 | * | 87BL3 picked up |
| 87HR12 | 1 | 87HR1 picked up |
| | 2 | 87HR2 picked up |
| | b | Both 87HR1 and 87HR2 picked up |
| 87HR3 | * | 87HR3 picked up |
| HB1 | 2 | 2_4HB1 picked up |
| | 5 | 5HB1 picked up |
| | b | Both 2_4HB1 and 5HB1 picked up |
| HB2 | 2 | 2_4HB2 picked up |
| | 5 | 5HB2 picked up |
| | b | Both 2_4HB2 and 5HB2 picked up |
| HB3 | 2 | 2_4HB3 picked up |
| | 5 | 5HB3 picked up |
| | b | Both 2_4HB3 and 5HB3 picked up |
| TH5 | a | TH5 picked up |
| | t | TH5T picked up |

Table 9.5 Differential Event Report Digital Column Definitions for Protection, Control, and I/O Elements (Sheet 2 of 2)

| Column Designation | Column Symbols | Column Symbol Relay Word Bits (RWB) |
|--------------------|----------------|--|
| In12 | 1 2 b | IN101 picked up IN102 picked up Both IN101 and IN102 picked up |
| Out12 | 1 2 b | OUT101 picked up OUT102 picked up Both OUT101 and OUT102 picked up |
| Out3 | * | OUT103 picked up |

NOTE: The Event Summary and Settings are not shown here as they are the same as in Figure 9.3.

=>>EVE DIF1 (Enter)

```

SEL-787                                     Date: 02/14/2008   Time: 13:09:57.353
TRNSFRMR RELAY
Serial Number=0000000000000000
FID=SEL-787-X122HR-V0-Z001001-D20080212   CID=26FF
                                Differential 0
Differential Quantities 8 87 87 87 87      I u
Multiples of TAP (Amps Api) 7 R U B HR HB T n t
                                R 13 13 13 13      H 1 13
IOP1   IRT1   I1F2   I1F5   2 2 2 2 123 5 2 2
[1]
919.5  561.9   0.0    2.9   . . . . .
919.5  561.9   5.5    5.8   . . . . .
920.9  562.6   0.3    5.0   . . . . .
923.4  563.6   2.6    2.4   . . . . .
[2]
923.3  563.6   2.4    3.4   . . . . .
918.5  561.4   2.4    5.8   . . . . .
918.5  561.4   2.4    5.3   . . . . .
923.3  563.6   2.6    0.2   . . . . .
[3]
922.6  563.3   0.0    2.6   . . . . .
917.7  561.2   3.6    5.7   . . . . .
919.8  561.5   0.5    6.5   . . . . .
882.0  583.2   19.1   4.8   . . . . b* .. 2..
[4]
876.0  585.0   39.6   7.2   . . . . b* .. 2..
809.7  618.5   19.0   7.3   . . . . b* .. 2..
804.6  621.3   0.8    2.9   . . . . .
781.6  635.1   2.4    0.2   . . . . .
[5]
780.8  634.9   2.9    2.6   . 1. . . . .
778.3  633.8   2.6    5.7   . 1. . . . .
779.7  634.5   2.9    5.0   . 1. . . . .
782.3  635.5   2.4    2.4> * 1. . . . 1. . . .
[6]
781.4  635.2   2.6    2.4   * 1. . . . 1. . . . *
776.6  633.1   2.6    5.0   * 1. . . . 1. . . . *
777.4  633.3   2.6    5.0   * 1. . . . 1. . . . *
780.0  634.4   0.2    0.2   * 1. . . . 1. . . . *
[7]
779.1  634.1   2.6    5.0   * 1. . . . 1. . . . *
776.6  633.1   2.4    5.6   * 1. . . . 1. . . . *
777.3  633.4   2.6    2.4   * 1. . . . 1. . . . *
780.1  634.3   2.4    0.2   * 1. . . . 1. . . . *
[8]
780.0  634.3   3.4    2.6   * 1. . . . 1. . . . *
777.5  633.3   2.6    5.5   * 1. . . . 1. . . . *
777.5  633.3   0.0    4.8   * 1. . . . 1. . . . *
782.1  635.6   3.7    2.4   * 1. . . . 1. . . . *
[9]
781.3  635.3   2.4    3.4   * 1. . . . 1. . . . *
776.7  633.0   2.4    3.7   * 1. . . . 1. . . . *
778.2  633.6   0.2    2.9   * 1. . . . 1. . . . *
780.7  634.7   2.4    0.0   * 1. . . . 1. . . . *
[10]
779.9  634.4   2.6    5.3   * 1. . . . 1. . . . *
777.1  633.5   4.8    5.8   * 1. . . . 1. . . . *
777.8  633.8   2.6    3.2   * 1. . . . 1. . . . *
782.6  636.0   0.2    3.4   * 1. . . . 1. . . . *

```

Figure 9.7 Example Standard 15-cycle Differential Event Report (EVE DIF1 Command) 1/4 Cycle Resolution (Sheet 1 of 2)

| | | | | | | | | | |
|-------|-------|-----|------|---|----|---|---|---|---|
| [11] | | | | | | | | | |
| 782.5 | 636.1 | 2.6 | 3.6 | * | 1. | . | . | . | * |
| 777.9 | 633.8 | 3.4 | 3.6 | * | 1. | . | . | . | * |
| 777.9 | 633.7 | 0.3 | 2.6 | * | 1. | . | . | . | * |
| 780.7 | 634.7 | 5.6 | 2.2 | * | 1. | . | . | . | * |
| [12] | | | | | | | | | |
| 779.9 | 634.4 | 0.2 | 3.4 | * | 1. | . | . | . | * |
| 777.4 | 633.3 | 4.8 | 5.5 | * | 1. | . | . | . | * |
| 778.1 | 633.7 | 3.2 | 4.8 | * | 1. | . | . | . | * |
| 780.6 | 634.7 | 3.7 | 0.0 | * | 1. | . | . | . | * |
| [13] | | | | | | | | | |
| 780.6 | 634.7 | 0.2 | 2.6 | * | 1. | . | . | . | * |
| 778.0 | 633.7 | 3.6 | 5.7 | * | 1. | . | . | . | * |
| 779.4 | 634.4 | 2.4 | 5.0 | * | 1. | . | . | . | * |
| 781.9 | 635.4 | 2.4 | 2.2 | * | 1. | . | . | . | * |
| [14] | | | | | | | | | |
| 781.2 | 635.1 | 0.2 | 3.4 | * | 1. | . | . | . | * |
| 778.4 | 634.2 | 3.6 | 5.5* | * | 1. | . | . | . | * |
| 779.2 | 634.5 | 2.6 | 4.8 | * | 1. | . | . | . | * |
| 779.7 | 634.3 | 2.6 | 2.4 | * | 1. | . | . | . | * |
| [15] | | | | | | | | | |
| 778.8 | 634.0 | 2.4 | 5.6 | * | 1. | . | . | . | * |
| 776.3 | 632.9 | 3.4 | 6.9 | * | 1. | . | . | . | * |
| 777.1 | 633.3 | 2.6 | 4.8 | * | 1. | . | . | . | * |
| 782.1 | 635.3 | 3.7 | 0.3 | * | 1. | . | . | . | * |

Figure 9.7 Example Standard 15-cycle Differential Event Report (EVE DIF1 Command) 1/4 Cycle Resolution (Sheet 2 of 2)

Sequential Events Recorder (SER) Report

The SER report captures relay element state changes over an extended period. SER report data are useful in commissioning tests and root-cause analysis studies. SER information is stored when state changes occur. The report records the most recent 1024 state changes if a relay element is listed in the SER trigger equations.

SER Triggering

Settings SER1 through SER4 are used to select entries in the SER report. To capture relay element state changes in the SER report, the relay element name must be programmed into one of the four SER trigger equations. Each of the four programmable trigger equations allows entry of as many as 24 relay elements; the SER report can monitor a total of 96 relay elements.

The relay adds a message to the SER to indicate power up or settings change conditions:

| |
|------------------------|
| Relay Powered Up |
| . |
| . |
| . |
| Relay Settings Changed |

Each entry in the SER includes the SER row number, date, time, element name, and element state.

SER Aliases

You may rename as many as 20 of the SER trigger conditions using the ALIAS settings. For instance, the factory-default alias setting 2 renames Relay Word bit PB02 for reporting in the SER:

```
ALIAS2:= PB02 FP_LOCK PICKUP DROPOUT
```


When Relay Word bit PB02 is asserted, the SER report will show the date and time of FP_LOCK PICKUP. When Relay Word bit PB02 is deasserted, the SER report will show the date and time of FP_LOCK DROPOUT. With this and other alias assignments, the SER record is easier for the operator to review. See *Relay Word Bit Aliases* on page 4.107 for additional details.

Retrieving and Clearing SER Reports

See *SER Command (Sequential Events Recorder Report)* on page 7.35 for details on the **SER** command.

Example SER Report

The example SER report in *Figure* includes records of events that occurred before the beginning of the event summary report in *Figure 9.3*.

```

=>SER <Enter>

SEL-787                               Date: 02/14/2008   Time: 13:22:53
TRANSFRM RELAY                       Time Source: Internal

Serial No = 0000000000000000
FID = SEL-787-X122HR-V0-Z001001-D20080212          CID = 26FF

#   DATE       TIME       ELEMENT       STATE
5  02/14/2008  13:09:57.353  87R        Asserted
4  02/14/2008  13:09:57.353  TRIPXFMR   Asserted
3  02/14/2008  13:09:57.615  ORED51T    Asserted
2  02/14/2008  13:19:17.186  SALARM     Asserted
1  02/14/2008  13:19:18.190  SALARM     Deasserted

```

Figure 9.8 Example Sequential Events Recorder (SER) Event Report

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Section 10

Testing and Troubleshooting

Overview

Relay testing is typically divided into two categories:

- Tests performed at the time the relay is installed or commissioned
- Tests performed periodically once the relay is in service

This section provides information on both types of testing for the SEL-787 Transformer Protection Relay. Because the SEL-787 is equipped with extensive self-tests, traditional periodic test procedures may be eliminated or greatly reduced.

Should a problem arise during either commissioning or periodic tests, the section on *Troubleshooting on page 10.15* provides a guide to isolating and correcting the problem.

Testing Tools

Serial Port Commands

The following serial port commands assist you during relay testing.

The **METER** command shows the ac currents and voltages (magnitude and phase angle) presented to the relay in primary values. In addition, the command shows power system frequency. Compare these quantities against other devices of known accuracy. The **METER** command is available at the serial ports and front-panel display. See *Section 7: Communications* and *Section 8: Front-Panel Operations*.

The relay generates a 15- or 64-cycle event report in response to faults or disturbances. Each report contains current and voltage information, relay element states, and input/output contact information. If you question the relay response or your test method, use the event report for more information. The **EVENT** command is available at the serial ports. See *Section 9: Analyzing Events*.

The relay provides a Sequential Events Recorder (SER) event report that time-tags changes in relay element and input/output contact states. The SER provides a convenient means to verify the pickup/dropout of any element in the relay. The **SER** command is available at the serial ports. See *Section 9: Analyzing Events*.

Use the **TARGET** command to view the state of relay control inputs, relay outputs, and relay elements individually during a test. The **TARGET** command is available at the serial ports and the front panel. See *Section 7: Communications* and *Section 8: Front-Panel Operations*.

Low-Level Test Interface

NOTE: The SEL-RTS Relay Test System consists of the SEL-AMS Adaptive Multichannel Source and SEL-5401 Test System Software.

The SEL-787 has a low-level test interface on the 6 ACI current card (Slot Z) and 1 ACI Neutral current card or 1 ACI/3 AVI current/voltage card (Slot E). You can test the relay in either of two ways: conventionally by applying ac signals to the relay inputs or by applying low magnitude ac voltage signals to the test interface on the printed circuit boards.

The SEL-RTS Low-Level Relay Test System can be used to provide signals to test the relay. *Figure 10.1* shows the Test Interface connectors.

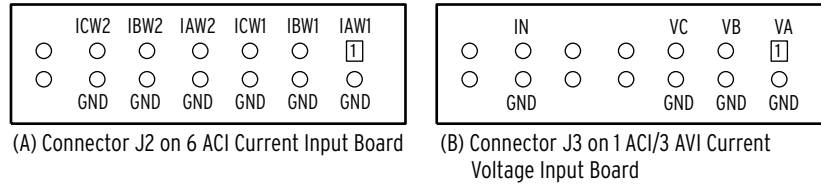


Figure 10.1 Low-Level Test Interface (J2 and J3)

Note that there are two options for the Slot E for low level interface:

- The 1 ACI card supports neutral current input IN only.
- The 1 ACI/3 AVI card supports the neutral current input IN and three-phase ac voltage inputs VA, VB, and VC.

Connector J3 is the same in both options.

Table 10.1 shows the signal scale factor information used by the AMS Relay Test System SEL-5401 Software for the calibrated inputs.

Table 10.1 Resultant Scale Factors for Inputs

| Channel Label | Circuit Board & Connector | SEL-5401 Channel No. | Nominal Input | Scale Factor (A/V or V/V) |
|---------------|---------------------------|----------------------|---------------|---------------------------|
| IAW1 | 6 ACI card/J2 | 1 | 5 A/1 A | 106.14/21.23 |
| IBW1 | 6 ACI card/J2 | 2 | 5 A/1 A | 106.14/21.23 |
| ICW1 | 6 ACI card/J2 | 3 | 5 A/1 A | 106.14/21.23 |
| IAW2 | 6 ACI card/J2 | 4 | 5 A/1 A | 106.14/21.23 |
| IBW2 | 6 ACI card/J2 | 5 | 5 A/1 A | 106.14/21.23 |
| ICW2 | 6 ACI card/J2 | 6 | 5 A/1 A | 106.14/21.23 |
| VA | 1 ACI/3 AVI card/J3 | 7 | 250 V | 218.4 |
| VB | 1 ACI/3 AVI card/J3 | 8 | 250 V | 218.4 |
| VC | 1 ACI/3 AVI card/J3 | 9 | 250 V | 218.4 |
| IN | 1 ACI/3 AVI card/J3 | 12 | 5 A/1 A | 106.14/21.23 |

Access the low-level test interface connectors by using the following procedure.

⚠CAUTION

The relay contains devices sensitive to Electrostatic Discharge (ESD). When working on the relay with the front panel removed, work surfaces and personnel must be properly grounded or equipment damage may result.

- Step 1. Loosen the mounting screws and the ground screw on the back and remove the back cover.
- Step 2. Remove the 6 ACI board from Slot Z.
- Step 3. Locate jumpers JMP1–JMP6 and change them from Pin 1–2 (normal position) to Pin 2–3 (low-level test position).

NOTE: The 14-pin connectors of the SEL-RTS ribbon cable C750A can be used. The connectors are not keyed; make sure Pin 1 is connected to the IAW1/VA channel on the 6 ACI and 1 ACI/3 AVI boards, respectively.

- Step 4. Locate connector J2 and connect low-level signal connector (e.g., ribbon cable connector of SEL-RTS Test System).
- Step 5. Insert the 6 ACI board back in its Slot Z.
- Step 6. Remove the 1 ACI/3 AVI board or 1 ACI board from Slot E.
- Step 7. Locate jumper JMP1 and change it from Pin 1-2 (normal position) to Pin 2-3 (low-level test position)
- Step 8. Locate connector J3 and connect low-level signal connector (e.g., ribbon cable connector of SEL-RTS Test System).
- Step 9. Insert the board back into Slot E.

Refer to the *SEL-RTS Instruction Manual* for additional detail.

When simulating a delta PT connection, $\Delta_Y := \Delta$, with the low-level test interface referenced in *Figure 10.1*, apply the following signals:

- Apply low-level test signal VAB to Pin VA.
- Apply low-level test signal $-VBC$ (equivalent to VCB) to Pin VC.
- Do not apply any signal to pin VB.

Commissioning Tests

SEL performs a complete functional check and calibration of each SEL-787 before it is shipped. This helps to ensure that you receive a relay that operates correctly and accurately. Commissioning tests confirm that the relay is properly connected including the control signal inputs and outputs.

The following connection tests help you enter settings into the SEL-787 and verify that the relay is properly connected. Brief functional tests ensure that the relay settings are correct. It is unnecessary to test every element, timer, and function in these tests. Modify the procedure as necessary to conform to your standard practices. Use the procedure at initial relay installation; you should not need to repeat it unless major changes are made to the relay electrical connections.

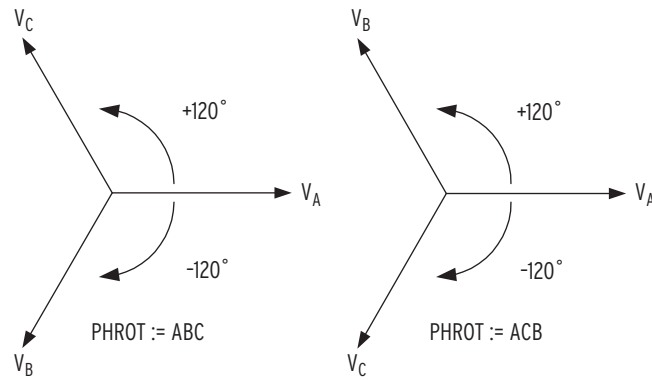
Required Equipment

- The SEL-787, installed and connected according to your protection design
- A PC with serial port, terminal emulation software, and serial communications cable
- *SEL-787 Settings Sheets* with settings appropriate to your application and protection design
- The ac and dc elementary schematics and wiring diagrams for this relay installation
- A continuity tester
- A protective relay ac test source
 - Minimum: single-phase voltage and current with phase angle control
 - Preferred: three-phase voltage and current with phase angle control

Connection Tests

- Step 1. Remove control voltage and ac signals from the SEL-787 by opening the appropriate breaker(s) or removing fuses.
- Step 2. Isolate the relay contact assigned to be the **TRIP** output.
- Step 3. Verify correct ac and dc connections by performing point-to-point continuity checks on the associated circuits.
- Step 4. Apply ac or dc control voltage to the relay.
- After the relay is energized, the front-panel green **ENABLED** LED should illuminate.
- Step 5. Use the appropriate serial cable (SEL cable C234A or equivalent) to connect a PC to the relay.
- Step 6. Start the PC terminal emulation software and establish communication with the relay.
- Refer to *Section 7: Communications* for more information on serial port communications.
- Step 7. Set the correct relay time and date by using either the front-panel or serial port commands (**TIME** *hh:mm:ss* and **DATE** *mm/dd/yy* commands).
- Step 8. Using the **SET**, **SET P**, **SET G**, **SET L**, and **SET R** serial port commands, enter the relay settings from the settings sheets for your application.
- Step 9. If you are connecting an external SEL-2600 RTD Module, follow the substeps below; otherwise continue with the next step.
- Connect the fiber-optic cable to the RTD Module fiber-optic output.
 - Plug the relay end of the fiber-optic cable into the relay fiber-optic Rx input (Port 2).
- Step 10. Verify the relay ac connections.
- Step 11. Connect the ac test source current or voltage to the appropriate relay terminals.
- Disconnect the current transformer and voltage transformer (if present) secondaries from the relay prior to applying test source quantities.
 - If you set the relay to accept phase-to-ground voltages (**DELTA_Y** := **WYE**), set the current and/or voltage phase angles as shown in *Figure 10.2*.
 - If you set the relay to accept delta voltages (**DELTA_Y** := **DELTA**), set the current and/or voltage phase angles as shown in *Figure 10.3*.

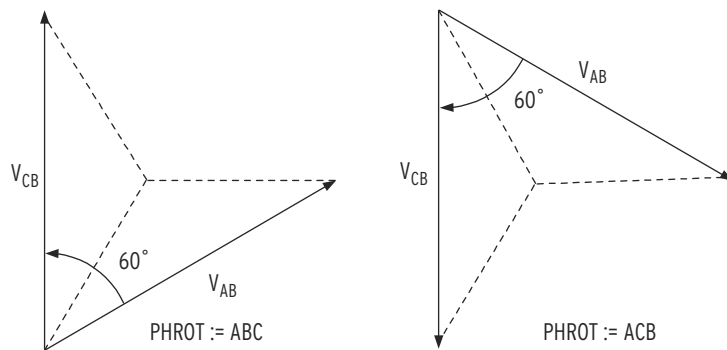
NOTE: Make sure the current transformer secondary windings are shorted before they are disconnected from the relay.



When setting PHROT := ABC, set angle V_A = angle I_A = 0°
 set angle V_B = angle I_B = -120°
 set angle V_C = angle I_C = 120°

When setting PHROT := ACB, set angle V_A = angle I_A = 0°
 set angle V_B = angle I_B = 120°
 set angle V_C = angle I_C = -120°

Figure 10.2 Three-Phase Wye AC Connections



When setting PHROT := ABC, set angle I_A = 0°
 set angle I_B = -120°
 set angle I_C = 120°
 set angle V_{AB} = $+30^\circ$
 set angle V_{CB} = $+90^\circ$

When setting PHROT := ACB, set angle I_A = 0°
 set angle I_B = 120°
 set angle I_C = -120°
 set angle V_{AB} = -30°
 set angle V_{CB} = -90°

Figure 10.3 Three-Phase Open-Delta AC Connections

Step 12. Apply rated current (1 A or 5 A).

Step 13. If the relay is equipped with voltage inputs, apply rated voltage for your application.

Step 14. Use the front-panel **METER** > **Fundamental** function or serial port **METER** command to verify that the relay is measuring the magnitude and phase angle of both voltage and current correctly, taking into account the relay PTR, CTR1, and CTR2 settings and the fact that the quantities are displayed in primary units.

Step 15. If you are using a current transformer for the neutral, apply a single-phase current to the **IN1** terminal. Do not apply voltage.

Step 16. Verify that the relay is measuring the magnitude and phase angle correctly.

The expected magnitude is (applied current) • (CTRN1). The expected phase angle is zero (0).

Step 17. Verify control input connections. Using the front-panel **MAIN > Targets > Row 21** function, check the control input status in the relay (**IN101** or **IN102**).

As you apply rated voltage to each input, the position in Row 21 corresponding to that input should change from zero (0) to one (1).

Step 18. Verify output contact operation:

- a. For each output contact, set the input to logical 1. This causes the output contact to close. For example, setting **OUT101 = 1** causes the output **OUT101** contact to close.
- b. Repeat the process for all contact outputs.
Make sure that each contact closure does what you want it to do in the annunciation, control, or trip circuit associated with that contact closure.

Step 19. Perform any desired protection element tests. Perform only enough tests to prove that the relay operates as intended; exhaustive element performance testing is not necessary for commissioning.

Step 20. Connect the relay for tripping duty.

Step 21. Verify that any settings changed during the tests performed in *Step 18* and *Step 19* are changed back to the correct values for your application.

Step 22. Use the serial port commands in *Table 10.2* to clear the relay data buffers and prepare the relay for operation.

This prevents data generated during commissioning testing from being confused with operational data collected later.

Table 10.2 Serial Port Commands That Clear Relay Data Buffers

| Serial Port Command | Task Performed |
|---------------------|---|
| LDP C | Clears Load Profile Data |
| SER R | Resets Sequential Events Record buffer |
| SUM R | Resets Event Report and Summary Command buffers |

Step 23. When it is safe to do so, energize the transformer.

Step 24. Verify the following ac quantities by using the front-panel **METER > Fundamental** or serial port **METER** command.

- Phase current magnitudes should be nearly equal.
- Phase current angles should be balanced, have proper phase rotation, and have the appropriate phase relationship to the phase voltages.

Step 25. If your relay is equipped with voltage inputs, check the following:

- Phase voltage magnitudes should be nearly equal.
- Phase voltage phase angles should be balanced and have proper phase rotation.

The SEL-787 is now ready for continuous service.

Functional Tests

Phase Current Measuring Accuracy

Step 1. Connect the current source to the relay, as shown in *Figure 10.4*.

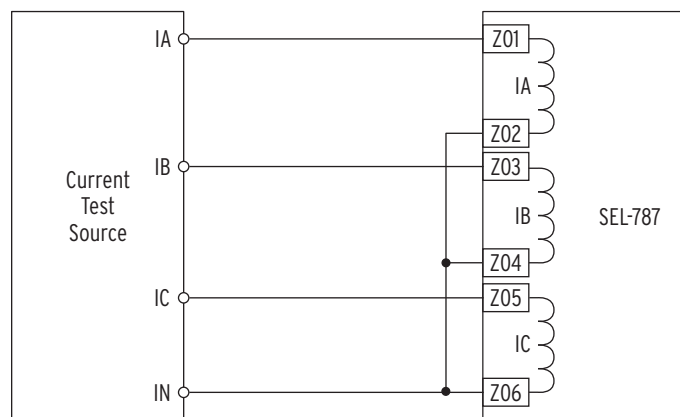


Figure 10.4 CTR1 Current Source Connections

- Step 2. Using the front-panel **SET/SHOW** or the serial port **SHO** command, record the **CTR1** and **PHROT** setting values.
- Step 3. Set the phase current angles to apply balanced three-phase currents in accordance with the **PHROT** setting. Refer to *Figure 10.2*.
- Step 4. Set each phase current magnitude equal to the values listed in Column 1 of *Table 10.3*. Use the front-panel to view the phase current values. The relay should display the applied current magnitude times the **CTR1** setting.

Table 10.3 CTR1 Phase Current Measuring Accuracy

| I Applied (A secondary)^a | Expected Reading CTR1 x I | A-Phase Reading (A primary) | B-Phase Reading (A primary) | C-Phase Reading (A primary) |
|--|--|--|--|--|
| 0.2 x I _{NOM} | | | | |
| 0.9 x I _{NOM} | | | | |
| 1.6 x I _{NOM} | | | | |

^a I_{NOM} = rated secondary amps (1 or 5).

Step 5. Repeat *Step 1* through *Step 4* using *Figure 10.5* and *Table 10.4*.

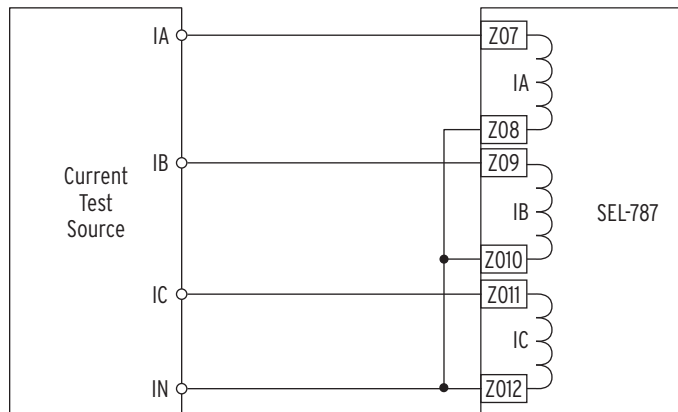


Figure 10.5 CTR2 Current Source Connections

Table 10.4 CTR2 Phase Current Measuring Accuracy

| I Applied (A secondary)^a | Expected Reading CTR2 x I | A-Phase Reading (A primary) | B-Phase Reading (A primary) | C-Phase Reading (A primary) |
|--|--|--|--|--|
| 0.2 x I _{NOM} | | | | |
| 0.9 x I _{NOM} | | | | |
| 1.6 x I _{NOM} | | | | |

^a I_{NOM} = rated secondary amps (1 or 5).

Power and Power Factor Measuring Accuracy

Wye-Connected Voltages

Perform the following steps to test wye-connected voltages:

- Step 1. Connect the current source to the relay, as shown in *Figure 10.4* (VIWDG = 1) or *Figure 10.5* (VIWDG = 2).
- Step 2. Connect the voltage source to the relay, as shown in *Figure 10.6*. Make sure that DELTA_Y := WYE.

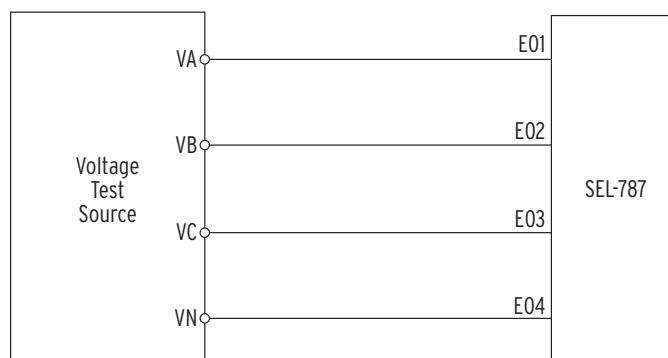


Figure 10.6 Wye Voltage Source Connections

- Step 3. Using the front-panel SET/SHOW or the serial port **SHOW** command, record the CTR_n (where *n* = VIWDG setting), PTR, and PHROT setting values.
- Step 4. Apply the current and voltage quantities shown in Column 1 of *Table 10.5*.

Values are given for PHROT := ABC and PHROT := ACB.

Step 5. Use the front-panel **METER** function or the serial port **MET** command to verify the results.

Table 10.5 Power Quantity Accuracy—Wye Voltages^a

| Applied Currents and Voltages | Real Power (kW) | Reactive Power (kVAR) | Power Factor (pf) |
|--|---|---|---|
| PHROT := ABC IAW _n = 2.5 ∠-26 IBW _n = 2.5 ∠-146 ICW _n = 2.5 ∠+94 VA = 67 ∠0 VB = 67 ∠-120 VC = 67 ∠+120 | Expected: $P = 0.898 \cdot \text{CTR}_n \cdot \text{PTR}$ Measured: | Expected: $Q = 0.438 \cdot \text{CTR}_n \cdot \text{PTR}$ Measured: | Expected: pf = 0.90 lag Measured: |
| PHROT := ACB IAW _n = 2.5 ∠-26 IBW _n = 2.5 ∠+94 ICW _n = 2.5 ∠-146 VA = 67 ∠0 VB = 67 ∠+120 VC = 67 ∠-120 | Expected: $P = 0.898 \cdot \text{CTR}_n \cdot \text{PTR}$ Measured: | Expected: $Q = 0.438 \cdot \text{CTR}_n \cdot \text{PTR}$ Measured: | Expected: pf = 0.90 lag Measured: |

^a n = VIWDG setting

Delta-Connected Voltages

Perform the following steps to test delta-connected voltages:

- Step 1. Connect the current source to the relay, as shown in *Figure 10.4* (VIWDG = 1) or *Figure 10.5* (VIWDG = 2).
- Step 2. Connect the voltage source to the relay, as shown in *Figure 10.7*. Make sure that DELTA_Y := DELTA.

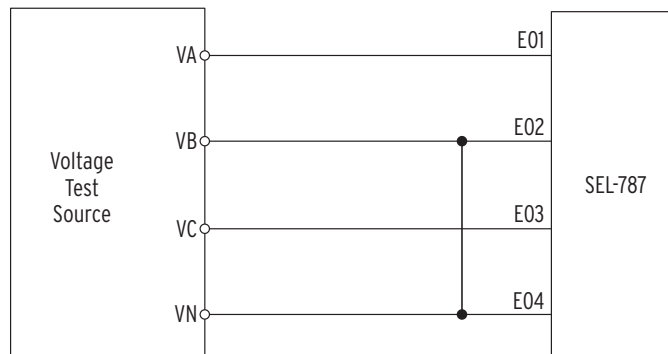


Figure 10.7 Delta Voltage Source Connections

- Step 3. Using the front-panel **SET/SHOW** or the serial port **SHOW** command, record the CTR_n (where n = VIWDG setting), PTR, and PHROT setting values.
- Step 4. Apply the current and voltage quantities shown in Column 1 of *Table 10.6*.

Values are given for PHROT := ABC and PHROT := ACB.
- Step 5. Use the front-panel **METER** or the serial port **MET** command to verify the results.

Table 10.6 Power Quantity Accuracy—Delta Voltages^a

| Applied Currents and Voltages | Real Power (kW) | Reactive Power (kVAR) | Power Factor (pf) |
|--|--|--|---|
| PHROT := ABC IAW _n = 2.5 ∠−26 IBW _n = 2.5 ∠−146 ICW _n = 2.5 ∠+94 VAB = 120 ∠+30 VBC = 120 ∠−90 | Expected: $P = 0.4677 \cdot CTR_n \cdot PTR$ Measured: | Expected: $Q = 0.2286 \cdot CTR_n \cdot PTR$ Measured: | Expected pf = 0.90 lag Measured: |
| PHROT := ACB IAW _n = 2.5 ∠−26 IBW _n = 2.5 ∠+94 ICW _n = 2.5 ∠−146 VAB = 120 ∠−30 VBC = 120 ∠+90 | Expected: $P = 0.4677 \cdot CTR_n \cdot PTR$ Measured: | Expected: $Q = 0.2286 \cdot CTR_n \cdot PTR$ Measured: | Expected: pf = 0.90 lag Measured: |

^a n = VIWDG setting

Periodic Tests (Routine Maintenance)

Because the SEL-787 is equipped with extensive self-tests, the most effective maintenance task is to monitor the front-panel messages after a self-test failure. In addition, each relay event report generated by a fault should be reviewed. Such reviews frequently reveal problems with equipment external to the relay, such as instrument transformers and control wiring.

The SEL-787 does not require specific routine tests, but your operation standards may require some degree of periodic relay verification. If you need or want to perform periodic relay verification, the following checks are recommended.

Table 10.7 Periodic Relay Checks

| Test | Description |
|----------------|---|
| Relay Status | Use the front-panel STATUS or serial port STATUS command to verify that the relay self-tests have not detected any WARN or FAIL conditions. |
| Meter | Verify that the relay is correctly measuring current and voltage (if included) by comparing the relay meter readings to separate external meters. |
| Control Input | Using the front-panel MAIN > Targets > Row 21 function, check the control input status in the relay. As you apply rated voltage to each input, the position in Row 21 corresponding to that input should change from zero (0) to one (1). |
| Contact Output | For each output contact, set the input to Logic 1. This causes the output contact to close. For example, setting OUT101 := 1 causes the output OUT101 contact to close. Repeat the process for all contact outputs. Make sure that each contact closure does what you want it to do in the annunciation, control, or trip circuit associated with that contact closure. |

Self-Test

The SEL-787 runs a variety of self-tests. The relay takes the following corrective actions for out-of-tolerance conditions (see *Table 10.8*):

- **Protection Disabled:** The relay disables protection and control elements and trip/close logic. All output contacts are deenergized. The ENABLED front-panel LED is extinguished.
- **ALARM Output:** Two Relay Word bits, HALARM and SALARM, signal self-test problems. SALARM is pulsed for software programmed conditions, such as settings changes, access level changes, three consecutive unsuccessful password entry attempts, active group changes, copy commands, and password changes. HALARM is pulsed for hardware self-test warnings. HALARM is continuously asserted (set to logical 1) for hardware self-test failures. A diagnostic alarm may be configured as explained in *Section 4: Protection and Logic Functions*. In the Alarm Status column of *Table 10.8*, Latched indicates that HALARM is continuously asserted, Not Latched indicates that HALARM is pulsed for five seconds, and NA indicates that HALARM is not asserted.
- The relay generates automatic STATUS reports at the serial port for warnings and failures (ports with setting AUTO = Y).
- The relay displays failure messages on the relay LCD display for failures.
- For certain failures, the relay will automatically restart as many as three times. In many instances, this will correct the failure. The failure message might not be fully displayed before automatic restart occurs. Indication that the relay restarted will be recorded in the Sequential Events Recorder (SER).

Use the serial port **STATUS** command or front-panel to view relay self-test status. Based on the self-test type, issue the **STA C** command as directed in the Corrective Actions column. Contact SEL if this does not correct the problem.

Table 10.8 Relay Self Tests (Sheet 1 of 4)

| Self Test | Description | Normal Range | Protection Disabled on Failure | Alarm Status | Auto Message on Failure | Front Panel Message on Failure | Corrective Action |
|---|-------------|--------------|--------------------------------|--------------|-------------------------|--------------------------------|--|
| Watchdog Timer Periodic resetting (1/32 cycle) | | | Yes | De-energized | No | No | |
| Mainboard FPGA (power up) Fail if mainboard Field Programmable Gate Array does not accept program or the version number is incorrect | | | Yes | Latched | Yes | Status Fail FPGA Failure | Automatic restart. Contact SEL if failure returns. |
| Mainboard FPGA (run time) Fail on lack of data acquisition interrupts or on detection of a CRC error in the FPGA code | | | Yes | Latched | Yes | Status Fail FPGA Failure | Automatic restart. Contact SEL if failure returns. |
| GPSB (back-plane) communications Fail if GPSB is busy on entry to processing interval | | | Yes | Latched | Yes | Status Fail GPSB Failure | STA C, to clear the warning in the status report. Contact SEL if failure returns. |

Table 10.8 Relay Self Tests (Sheet 2 of 4)

| Self Test | Description | Normal Range | Protection Disabled on Failure | Alarm Status | Auto Message on Failure | Front Panel Message on Failure | Corrective Action |
|---|-------------|------------------------|--------------------------------|--------------|-------------------------|-------------------------------------|--|
| Front-Panel HMI (power up) Fail if ID registers do not match expected or if FPGA programming is unsuccessful | | | No | Not Latched | Yes | NA | STA C, to clear the warning in the status report. Contact SEL if failure returns. |
| External RAM (power up) Performs a read/write test on system RAM | | | Yes | Latched | No | No | |
| External RAM (run time) Performs a read/write test on system RAM | | | Yes | Latched | Yes | Status Fail RAM Failure | Automatic restart. Contact SEL if failure returns. |
| Internal RAM (power up) Performs a read/write test on system CPU RAM | | | Yes | Latched | No | No | |
| Internal RAM (run time) Performs a read/write test on system CPU RAM | | | Yes | Latched | Yes | Status Fail RAM Failure | Automatic restart. Contact SEL if failure returns. |
| Code Flash (power up) SELBOOT qualifies code with a checksum | | | NA | NA | NA | NA | |
| Data Flash (power up) Checksum is computed on critical data | | | Yes | Latched | Yes | Status Fail Non_Vol Failure | |
| Data Flash (run time) Checksum is computed on critical data | | | Yes | Latched | Yes | Status Fail Non_Vol Failure | |
| Critical RAM (settings) Performs a checksum test on the active copy of settings | | | Yes | Latched | Yes | Status Fail CR_RAM Failure | Automatic restart. Contact SEL if failure returns. |
| Critical RAM (run time) Verify instruction matches FLASH image | | | Yes | Latched | Yes | Status Fail CR_RAM Failure | Automatic restart. Contact SEL if failure returns. |
| I/O Board Failure Check if ID register matches part number | | | Yes | Latched | Yes | Status Fail Card [C D E] Failure | |
| DeviceNet Board Failure DeviceNet card does not respond in three consecutive 300 ms time out periods | | | NA | NA | NA | COMMFLT Warning | |
| CT Board (power up) Fail if ID register does not match part number | | | Yes | Latched | Yes | Status Fail CT Card Fail | |
| CT Board A/D Offset Warn Measure dc offset at each input channel | | -50 mV to +50 mV | No | Not Latched | No | NA | STA C, to clear the warning in the status report. Contact SEL if failure returns. |
| VT Board (power up) Fail if ID register does not match part number | | | Yes | Latched | Yes | Status Fail Card E Fail | |

Table 10.8 Relay Self Tests (Sheet 3 of 4)

| Self Test | Description | Normal Range | Protection Disabled on Failure | Alarm Status | Auto Message on Failure | Front Panel Message on Failure | Corrective Action |
|---|-------------|------------------|--------------------------------|--------------|-------------------------|--------------------------------|--|
| VT Board A/D Offset Warn Measure dc offset at each input channel | | -50 mV to +50 mV | No | Not Latched | No | NA | STA C, to clear the warning in the status report. Contact SEL if failure returns. |
| +0.9 V Fail Monitor +0.9 V power supply | | 0.855 to 0.945 V | Yes | Latched | Yes | Status Fail +0.9 V Failure | |
| +1.2 V Fail Monitor +1.2 V power supply | | 1.152 to 1.248 V | Yes | Latched | Yes | Status Fail +1.2 V Failure | |
| +1.5 V Fail Monitor +1.5 V power supply | | 1.35 to 1.65 V | Yes | Latched | Yes | Status Fail +1.5 V Failure | |
| +1.8 V Fail Monitor +1.8 V power supply | | 1.71 to 1.89 V | Yes | Latched | Yes | Status Fail +1.8 V Failure | |
| +3.3 V Fail Monitor +3.3 V power supply | | 3.07 to 3.53 V | Yes | Latched | Yes | Status Fail +3.3 V Failure | |
| +5 V Fail Monitor +5 V power supply | | 4.65 to 5.35 V | Yes | Latched | Yes | Status Fail +5 V Failure | |
| +2.5 V Fail Monitor +2.5 V power supply | | 2.32 to 2.68 V | Yes | Latched | Yes | Status Fail +2.5 V Failure | |
| +3.75 V Fail Monitor +3.75 V power supply | | 3.48 to 4.02 V | Yes | Latched | Yes | Status Fail +3.75 V Failure | |
| -1.25 V Fail Monitor -1.25 V power supply | | -1.16 to -1.34 V | Yes | Latched | Yes | Status Fail -1.25 V Failure | |
| -5 V Fail Monitor -5 V power supply | | -4.65 to -5.35 V | Yes | Latched | Yes | Status Fail -5 V Failure | |
| Clock Battery Monitor Clock Battery | | 2.3 to 3.5 V | No | Not Latched | Yes | NA | STA C, to clear the warning in the status report. Contact SEL if failure returns. |
| Clock Chip Unable to communicate with clock or fails time keeping test | | | No | Not Latched | Yes | NA | STA C, to clear the warning in the status report. Contact SEL if failure returns. |
| Clock Chip RAM Clock chip static RAM fails | | | No | Not Latched | Yes | NA | STA C, to clear the warning in the status report. Contact SEL if failure returns. |
| External RTD Fail if no comm, or the external RTD module reports open RTDs, shorted RTDs, a power supply failure | | | NA | NA | No | RTD Failure | |

Table 10.8 Relay Self Tests (Sheet 4 of 4)

| Self Test | Description | Normal Range | Protection Disabled on Failure | Alarm Status | Auto Message on Failure | Front Panel Message on Failure | Corrective Action |
|-----------|---|--------------|--------------------------------|--------------|-------------------------|---------------------------------|---|
| | CID (Configured IED Description) file (access) Failure to Access/Read CID File | | No | NA | No | Status Fail CID File Failure | |
| | Exception Vector CPU Error | | Yes | Latched | NA | Vector nn Relay Disabled | Automatic restart. Contact SEL if failure returns. |

Troubleshooting

Table 10.9 Troubleshooting

| Symptom/Possible Cause | Diagnosis/Solution |
|---|--|
| The relay ENABLED front-panel LED is dark. | |
| Input power is not present or a fuse is blown. | Verify that input power is present. Check fuse continuity. |
| Self-test failure | View the self-test failure message on the front-panel display. |
| The relay front-panel display does not show characters. | |
| The relay front-panel has timed out. | Press the ESC pushbutton to activate the display. |
| The relay is de-energized. | Verify input power and fuse continuity. |
| The relay does not accurately measure voltages or currents. | |
| Wiring error | Verify input wiring. |
| Incorrect CTR1, CTR2, CTRN, or PTR setting | Verify instrument transformer ratios, connections, and associated settings. |
| Voltage neutral terminal (N) is not properly grounded. | Verify wiring and connections. |
| The relay does not respond to commands from a device connected to the serial port. | |
| Cable is not connected. | Verify the cable connections. |
| Cable is not the correct type. | Verify the cable pinout. |
| The relay or device is at an incorrect baud rate or has another parameter mismatch. | Verify device software setup. |
| The relay serial port has received an XOFF, halting communications. | Type <Ctrl+Q> to send the relay XON and restart communications. |
| The relay does not respond to faults. | |
| The relay is improperly set. | Verify the relay settings. |
| Improper test source settings | Verify the test source settings. |
| Current or voltage input wiring error | Verify input wiring. |
| Failed relay self-test | Use the front-panel RELAY STATUS function to view self-test results. |

Factory Assistance

We appreciate your interest in SEL products and services. If you have questions or comments, please contact us at:

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Appendix A

Firmware and Manual Versions

Firmware

Determining the Firmware Version in Your Relay

To find the firmware version number in your SEL-787 Transformer Protection Relay, use the **STA** command (see *STATUS Command (Relay Self-Test Status)* on page 7.40 for more information on the **STA** command). The firmware revision number is after the R, and the release date is after the D. For example, the following is firmware revision number 203, release date July 30, 2010.

FID=SEL-787-R203-V0-Z001001-D20100730

Table A.1 and Table A.2 list the firmware versions, a description of the modifications, and the instruction manual date code that corresponds to the firmware version. The most recent firmware version is listed first.

Table A.1 200 Series Firmware Revision History (Sheet 1 of 4)

| Firmware Identification (FID) Number | Summary of Revisions | Manual Date Code |
|--------------------------------------|--|------------------|
| SEL-787-R209-V0-Z003001-D20140714 | <ul style="list-style-type: none"> ➤ Revised the firmware to allow anonymous TCP connection from DNP masters when DNPIPx is set to 0.0.0.0. ➤ Added Y-MODEM over Telnet to support file transfer. ➤ Resolved an issue with port timeout when accessing SEL Fast Protocol data over Telnet. In all previous firmware revisions that supported Telnet, it was necessary to send ASCII characters regularly to keep the connection alive. ➤ Modified the default data set and report names in the IEC 61850 CID file. Added additional Logical Nodes for Local Bits and MIRRORED BITS status. ➤ Changed the storage of latch and local bits from volatile to nonvolatile memory. ➤ Revised the firmware for Trip Logic such that RSTTRGT is processed on the rising edge. ➤ Modified Real Time Clock (RTC) diagnostics logic to show a warning only if the RTC diagnostics fail three consecutive times. The self-test check is done every six hours to test the communications and the clock, including the end-of-the-year roll over capability. ➤ Addressed an issue with validating the IPADDR, SUBNETM, DEFRTTR, and other IP addresses and port number settings of enabled protocols. ➤ Added a feature for Event Data registers in Modbus to always show the latest event data unless a specific event is selected by the event selection register. ➤ Improved the security of RTD ALARM and TRIP by adding an approximately six second delay to qualify the event. ➤ Resolved an issue with the DNP Binary Outputs so that they are no longer reported as OFFLINE when the Binary Output is also present in the Binary Input map and the Sequential Events Recorder (SER). | 20140714 |

Table A.1 200 Series Firmware Revision History (Sheet 2 of 4)

| Firmware Identification (FID) Number | Summary of Revisions | Manual Date Code |
|--------------------------------------|--|------------------|
| | <ul style="list-style-type: none"> ➤ Resolved an issue where the front panel showed a blank page after resetting a TRIP message. ➤ Modified the firmware to make the MATHERR Relay Word bit visible. ➤ Improved the frequency measurement and frequency element accuracy to ± 0.01 Hz resolution. ➤ Implemented a firmware enhancement to preserve an existing IEC 61850 CID file while upgrading from a previous firmware version. ➤ Revised the REF element logic to improve the sensitivity for applications with different neutral and phase CT ratings. ➤ Added Flash File System support to make settings and other miscellaneous nonvolatile data storage more robust. ➤ For relays configured with delta-connected CTs, resolved an issue in R207 and R208 firmware versions where power calculations in the MET report were incorrectly scaled down by $\sqrt{3}$. Protection elements were not affected by this issue. ➤ For relays configured with delta-connected CTs, resolved an issue where synchrophasor current magnitude calculations in the MET PM report were incorrectly scaled up by $\sqrt{3}$. Protection elements were not affected by this issue. ➤ For relays configured with delta-connected CTs, resolved an issue in R207 and R208 firmware versions where current harmonic calculations in the MET H report were incorrectly scaled down by $\sqrt{3}$. Protection elements were not affected by this issue. ➤ For relays configured with delta-connected CTs, resolved an issue where Through Fault (TFE) accumulated current calculations in the TFE report were incorrectly scaled up by $\sqrt{3}$. ➤ Resolved an issue that was causing small jumps in the angle calculations for analog quantities. ➤ Addressed an issue with setting the IP address of more than one DNP session to 0.0.0.0. The relay now allows only one DNP session at IP address 0.0.0.0. ➤ Revised the firmware to support front-panel HMI part replacement. The function of the HMI has not changed. ➤ Resolved an issue with the settings change STSET being reported as OFFLINE via DNP. ➤ Resolved an issue with the data type "Units_0" in the IEC 61850 ICD file by changing the unit data type name to SIUnit. ➤ Resolved an initialization issue with the V/Hz (24) element after changing DELTA_Y and 24WDG settings. The element was always initialized and functioned correctly if the settings were changed from the default (DELTA_Y := DELTA and 24WDG := WYE) to any other setting combination. The element was not initialized correctly if the user started with settings DELTA_Y := WYE and 24WDG := WYE and changed to other combinations. The element was initialized correctly for any setting combination if the relay was restarted after a settings change. ➤ Resolved an issue with the V/Hz element for the settings combination DELTA_Y := DELTA and SINGLEV := Y. With this settings combination, the V/Hz did not function and the MET report showed zero for V/Hz. <p>Firmware version R209 is for upgrading relays with R200–R208.</p> | |

Table A.1 200 Series Firmware Revision History (Sheet 3 of 4)

| Firmware Identification (FID) Number | Summary of Revisions | Manual Date Code |
|--------------------------------------|---|------------------|
| SEL-787-R208-V0-Z003001-D20130426 | <ul style="list-style-type: none"> ➤ Forced RTS to high and ignored CTS when PREDLY setting is OFF to power certain fiber-optic transceivers. ➤ Corrected an Ethernet Failover Switching issue for dual Ethernet models. ➤ Corrected an issue where old packets were returned on new connections when polling Modbus at high speed. ➤ Corrected an issue with the initial Gratuitous ARP request not being sent for as long as five minutes after startup. ➤ Corrected an issue that caused port settings to not be accepted when relay settings were downloaded using ACSELERATOR QuickSet® SEL-5030 Software. ACSELERATOR QuickSet reported with a message that settings files were not received. <p>Firmware version R208 is for upgrading relays with R200–R207.</p> | 20130426 |
| SEL-787-R207-V0-Z003001-D20111107 | ➤ Manual update only (see <i>Table A.6</i>). | 20120921 |
| SEL-787-R207-V0-Z003001-D20111107 | ➤ Manual update only (see <i>Table A.6</i>). | 20120903 |
| SEL-787-R207-V0-Z003001-D20111107 | <ul style="list-style-type: none"> ➤ Enhanced firmware to make serial number visible to IEC 61850 protocol and also revised the ICD file to add serial and part number information to PhyNam DO similar to the SEL-400 series relays. ➤ Corrected an issue with the rms meter values, where in some cases the values would spike for a short time. ➤ Corrected primary current magnitude calculation for delta-connected CTs by dividing by square root of 3 factor in the meter and event report delta current quantities. ➤ Revised units for MIRRORED BITS protocol setting CBADPU to ppm (parts per million). | 20111107 |
| SEL-787-R206-V0-Z003001-D20110610 | <ul style="list-style-type: none"> ➤ Added support for Simple Network Time Protocol (SNTP) to Ethernet port (Port 1) including new settings. ➤ Added new settings for time and date management. (including daylight-saving time) under Global Settings. ➤ Corrected issue with reading Communications Counter registers (Registers 1126-1135) using the user map. ➤ Corrected DNP issue so that it allows reading delta voltages quantities even when DELTA_WYE setting is WYE. ➤ Added a squelch threshold for very low-level secondary voltages (below 0.3 V) and currents (below 3% of INOM) in the rms metering quantities command response. ➤ Corrected IEC 61850 KEMA compliance issue (Sisco library). ➤ Revised default value for IRS1 setting (Differential element) from 3.0 to 6.0. ➤ Corrected the issue of SALARM not asserting for a settings group change. | 20110610 |
| SEL-787-R205-V0-Z002001-D20110201 | <ul style="list-style-type: none"> ➤ Corrected issue with Inverse Time Overcurrent elements (did not accumulate time correctly for FNOM = 50 Hz nominal frequency). ➤ Updated firmware revision history for version R204 to show the implementation of improved diagnostics and actions in the relay self-tests. | 20110201 |
| SEL-787-R204-V0-Z002001-D20101115 | ➤ Manual update only (see <i>Table A.6</i>). | 20101217 |
| SEL-787-R204-V0-Z002001-D20101115 | <ul style="list-style-type: none"> ➤ Corrected LDP command issue (relay lockup if data exceeds a threshold) in R200-203 firmware. ➤ Added a squelch threshold for very low-level secondary voltages (below 0.1 V) and currents (below 1% of INOM) in the metering quantities command response. | 20101115 |

Table A.1 200 Series Firmware Revision History (Sheet 4 of 4)

| Firmware Identification (FID) Number | Summary of Revisions | Manual Date Code |
|--------------------------------------|--|------------------|
| | <ul style="list-style-type: none"> ➤ Added calculated phase-to-phase voltages for wye-connected PTs to the analog quantities to allow selection for display points. ➤ Implemented improved diagnostics and actions in the relay self-tests. For certain failures, the relay will automatically restart as many as three times. ➤ Corrected issue with Inverse Time Overcurrent elements (did not accumulate time correctly at off-nominal frequency). | |
| SEL-787-R203-V0-Z002001-D20100730 | <ul style="list-style-type: none"> ➤ Added new Winding 1 and Winding 2, level 1, Phase A, Phase B and Phase C instantaneous overcurrent elements. ➤ Added new Winding 1 and Winding 2 Phase A, Phase B and Phase C time-overcurrent elements. ➤ Updated the error messages for setting interdependency checks to match the global setting AOx0yH. ➤ Extended the CT ratio setting range to 1:10000 for 5 A CTs and 1:50000 for 1 A CTs. ➤ Enhanced REF element logic by adding 52A interlock (new setting REF52BYP). ➤ Added capability to support two Modbus TCP sessions with timeout settings on the Ethernet port. ➤ Added Select Before Operate control (SBO) to the IEC 61850 protocol. ➤ Added Access Control setting BLOCK MODBUS SET (BLKMBSET) to be able to block settings changes from a remote Modbus or DeviceNet master. ➤ Added new I/O card option of 4 DI/3 DO, which has one Form-B and two Form-C outputs. ➤ Corrected relay status reporting via Modbus when relay is disabled. ➤ Updated Ethernet port settings IPADDR, SUBNETM, and DEFRTTR validation to allow addresses in the private address space. ➤ Added FASTOP setting to Port 1 (Ethernet) settings to allow breaker control using Fast Operate. ➤ Added IRIG-B input capability to fiber-optic serial Port 2 option including a new Time-Synchronization Source setting TIME_SRC. ➤ Added front-panel setting FP_AUTO to allow choice between OVERRIDE and ROTATING display messages. | 20100730 |
| SEL-787-R202-V0-Z001001-D20100215 | <ul style="list-style-type: none"> ➤ Factory calibration improvements. Only R200–R201 can be upgraded to R202 firmware. | 20100215 |
| SEL-787-R201-V0-Z001001-D20100118 | <ul style="list-style-type: none"> ➤ Corrected an occasional IEC 61850 communications defect where the firmware incorrectly reads an opcode from Flash memory and results in a vector. | 20100118 |
| SEL-787-R200-V0-Z001001-D20091015 | <ul style="list-style-type: none"> ➤ Revised firmware for processor update. Previous versions cannot be upgraded to R200. ➤ Extended event report storage capability to at least seventy-seven 15-cycle or nineteen 64-cycle event reports. | 20091015 |

Table A.2 100 Series Firmware Revision History (Sheet 1 of 3)

| Firmware Identification (FID) Number | Summary of Revisions | Manual Date Code |
|--------------------------------------|---|------------------|
| SEL-787-R110-V0-Z002001-D20140714 | <ul style="list-style-type: none"> ➤ For relays configured with delta-connected CTs, resolved an issue in R107–R109 firmware versions where power calculations in the MET report were incorrectly scaled down by $\sqrt{3}$. Protection elements were not affected by this issue. ➤ Revised the firmware for Trip Logic such that RSTTRGT is processed on the rising edge. ➤ Modified the firmware to make the MATHERR Relay Word bit visible. ➤ Resolved an issue where the front panel showed a blank page after resetting a TRIP message. ➤ Added a feature for Event Data registers in Modbus to always show the latest event data unless a specific event is selected by the event selection register. ➤ For relays configured with delta-connected CTs, resolved an issue in R107–R109 firmware versions where current harmonic calculations in the MET H report were incorrectly scaled down by $\sqrt{3}$. Protection elements were not affected by this issue. ➤ For relays configured with delta-connected CTs, resolved an issue where Through Fault (TFE) accumulated current calculations in the TFE report were incorrectly scaled up by $\sqrt{3}$. ➤ Addressed an issue with setting the IP address of more than on DNP session to 0.0.0.0. They relay now allows only on DNP session at IP address 0.0.0.0. ➤ Resolved an initialization issue with the V/Hz (24) element after changing DELTA_Y and 24WDG settings. The element was always initialized and functioned correctly if the settings were changed from the default (DELTA_Y := DELTA and 24WDG := WYE) to any other setting combination. The element was not initialized correctly if the user started with settings DELTA_Y := WYE and 24WDG := WYE and changed to other combinations. The element was initialized correctly for any setting combination if the relay was restarted after a settings change. ➤ Resolved an issue with the V/Hz element for the settings combination DELTA_Y := DELTA and SINGLEV := Y. With this settings combination, the V/Hz did not function and the MET report showed zero for V/Hz. <p>Firmware version R110 is for upgrading relays with R100–R109.</p> | 20140714 |
| SEL-787-R109-V0-Z002001-D20130426 | <ul style="list-style-type: none"> ➤ Forced RTS to high and ignored CTS when PREDLY setting is OFF to power certain fiber-optic transceivers. ➤ Corrected an Ethernet Failover Switching issue for dual Ethernet models. ➤ Corrected an issue where old packets were returned on new connections when polling Modbus at high speed. ➤ Corrected an issue with the initial Gratuitous ARP request not being sent for as long as five minutes after startup. ➤ Corrected an issue of missing SER records upon warm start. ➤ Corrected an issue that caused port settings to be rejected when relay settings were downloaded using ACSELERATOR QuickSet® SEL-5030 Software. ACSELERATOR QuickSet reported with a message that settings files were not received. <p>Firmware version R109 is for upgrading relays with R100–R108.</p> | 20130426 |
| SEL-787-R108-V0-Z002001-D20120921 | <ul style="list-style-type: none"> ➤ Corrected an issue with the STA command response in R107 firmware. The relay was displaying incorrect values for the internal power supply level on the main board. ➤ Corrected an I/O card issue in R107 firmware. Firmware was not allowing the relay to accept an I/O card in an empty slot. ➤ Corrected a GPSB failure issue in R107 firmware. | 20120921 |

Table A.2 100 Series Firmware Revision History (Sheet 2 of 3)

| Firmware Identification (FID) Number | Summary of Revisions | Manual Date Code |
|--------------------------------------|--|------------------|
| SEL-787-R107-V0-Z002001-D20111107 | ➤ Manual update only (see <i>Table A.6</i>). | 20120903 |
| SEL-787-R107-V0-Z002001-D20111107 | <ul style="list-style-type: none"> ➤ Corrected an issue with the rms meter values, where in some cases the values would spike for a short time. ➤ Corrected primary current magnitude calculation for delta-connected CTs by dividing by square root of 3 factor in the meter and event report delta current quantities. | 20111107 |
| SEL-787-R106-V0-Z002001-D20110201 | ➤ Manual update only (see <i>Table A.6</i>). | 20110610 |
| SEL-787-R106-V0-Z002001-D20110201 | ➤ Corrected issue with Inverse Time Overcurrent elements (did not accumulate time correctly for FNOM = 50 Hz nominal frequency). | 20110201 |
| SEL-787-R105-V0-Z002001-D20101115 | ➤ Manual update only (see <i>Table A.6</i>). | 20101217 |
| SEL-787-R105-V0-Z002001-D20101115 | <ul style="list-style-type: none"> ➤ Added a squelch threshold for very low-level secondary voltages (below 0.1 V) and currents (below 1% of INOM) in the metering quantities command response. ➤ Added calculated phase-to-phase voltages for wye-connected PTs to the analog quantities to allow selection for display points. ➤ Corrected issue with Inverse Time Overcurrent elements (did not accumulate time correctly at off-nominal frequency). | 20101115 |
| SEL-787-R104-V0-Z002001-D20100730 | <ul style="list-style-type: none"> ➤ Added new Winding 1 and Winding 2, level 1, Phase A, Phase B and Phase C instantaneous overcurrent elements. ➤ Added new Winding 1 and Winding 2 Phase A, Phase B and Phase C Time-Overcurrent elements. ➤ Updated the error messages for setting interdependency checks to match the global setting AOx0yH. ➤ Extended CT ratio setting range to 1:10000 for 5 A CTs and 1:50000 for 1 A CTs. ➤ Enhanced REF element logic by adding 52A interlock (new setting REF52BYP). ➤ Added capability to support two Modbus TCP sessions with timeout settings on the Ethernet port. ➤ Added Select Before Operate control (SBO) to the IEC 61850 protocol. ➤ Added Access Control setting BLOCK MODBUS SET (BLKMBSET) to be able to block settings changes from a remote Modbus or DeviceNet master. ➤ Added new I/O card option of 4 DI/3 DO, which has one Form-B and two Form-C outputs. ➤ Corrected relay status reporting via Modbus when relay is disabled. ➤ Updated Ethernet port settings IPADDR, SUBNETM, and DEFRTTR validation to allow addresses in the private address space. ➤ Added FASTOP setting to Port 1 (Ethernet) settings to allow breaker control using Fast Operate. ➤ Added IRIG-B input capability to fiber-optic serial Port 2 option including a new Time-Synchronization Source setting TIME_SRC. ➤ Added front-panel setting FP_AUTO to allow choice between OVERRIDE and ROTATING display messages. | 20100730 |
| SEL-787-R103-V0-Z001001-D20090420 | ➤ Improved harmonic measurement accuracy. | 20090420 |
| SEL-787-R102-V0-Z001001-D20090218 | <ul style="list-style-type: none"> ➤ Corrected Power Element issue in SEL-787E models when MIRRORRED BITS protocol is selected. ➤ Enhanced IEC 61850 security. ➤ Updated Modbus Register Map: revised registers 276–280 to support addition of MVA SET ENABLE and registers 291–297 to support addition of fractional PT ratio. | 20090218 |

Table A.2 100 Series Firmware Revision History (Sheet 3 of 3)

| Firmware Identification (FID) Number | Summary of Revisions | Manual Date Code |
|--------------------------------------|--|------------------|
| SEL-787-R101-V0-Z001001-D20081022 | <ul style="list-style-type: none"> ► Updated IEC 61850 firmware to enhance security, streamline MMS processing and improve TCP/IP. ► Improved security (see www.selinc.com/privacy.htm for details). | 20081022 |
| SEL-787-R100-V0-Z001001-D20080407 | ► Initial version. | 20080407 |

IEC 61850 and ACSELERATOR Architect Versions

Newer SEL-787 firmware uses a different software library from earlier versions and is unable to process previous version CID files. ACSELERATOR Architect® SEL-5032 Software generates CID files from ICD files, so the ICD file version number and CID file version number are the same. If downloaded to the SEL-787, an incompatible CID file will generate file parse errors during processing and disable the IEC 61850 protocol.

If you perform an SEL-787 firmware upgrade that spans different file version compatibilities, the relay may be unable to process the stored CID file. See the SEL-787 firmware upgrade instructions for CID file conversion procedures. See *Table A.3* for compatibilities between ACSELERATOR Architect, ICD/CID files, and SEL-787 firmware versions.

Table A.3 ACSELERATOR Architect CID File Compatibility

| ACSELERATOR Architect Software Version | ACSELERATOR Architect ICD/CID File Version | SEL-787 Firmware |
|--|--|------------------|
| R.1.1.100.0 or later | Version 004 | R206 and later |
| R.1.1.90.0 or later | Version 003 | R100–R205 |

DeviceNet and Firmware Versions

The firmware on the DeviceNet interface has two versions as listed in *Table A.4*. The version number of this firmware is only accessible via DeviceNet interface. SEL-787 needs DeviceNet firmware version 1.005.

Table A.4 DeviceNet Card Versions

| DeviceNet Card Software Version | Revisions | Release Date |
|--|--|--------------|
| Major Rev: 1, Minor Rev: 1 (Rev 1.001) | Base version (card defines product code = 100, fixed descriptions for DeviceNet Card parameters, etc.) | 20030612 |
| Major Rev: 1, Minor Rev: 5 (Rev 1.005) | Reads product code, DeviceNet card parameter descriptions, etc., from the relay. | 20080407 |

The Electronic Data Sheet (EDS) file is not updated every time a firmware release is made. A new EDS file is released only when there is a change in the Modbus/DeviceNet parameters. The EDS file and an ICON file for the SEL-787 are zipped together on the SEL-787 Product Literature CD (SEL-xxxRxxx.EXE). The file can also be downloaded from the SEL website at www.selinc.com. *Table A.5* lists the compatibility among the EDS files and the various firmware versions of the relay.

Table A.5 EDS File Compatibility

| EDS File | Firmware Revisions Supported | Release Date |
|-----------------|---|--------------|
| SEL-787R301.EDS | R206, R207, R208, and R209 (with DeviceNet version 1.005) | 20110610 |
| SEL-787R201.EDS | R104, R105, R106, R107, R108, R109, R110, R203, R204, R205 (with DeviceNet version 1.005) | 20100722 |
| SEL-787R102.EDS | R102, R103, R200, R201, R202 (with DeviceNet version 1.005) | 20090226 |
| SEL-787R100.EDS | R100, R101 (with DeviceNet version 1.005) | 20080506 |

Instruction Manual

The date code at the bottom of each page of this manual reflects the creation or revision date. *Table A.6* lists the instruction manual release dates and a description of modifications. The most recent instruction manual revisions are listed at the top.

Table A.6 Instruction Manual Revision History (Sheet 1 of 5)

| Revision Date | Summary of Revisions |
|---------------|--|
| 20140714 | <p>Section 1</p> <ul style="list-style-type: none"> ➤ Updated the ac current inputs under <i>AC Current Inputs</i> and the input voltage range under <i>Power Supply</i> in the <i>Specifications</i>. ➤ Added RTD Trip/Alarm Time Delay to the <i>RTD Protection</i> category of the <i>Specifications</i>. ➤ Updated the accuracy specifications. <p>Section 2</p> <ul style="list-style-type: none"> ➤ Updated <i>Card Configuration Procedure</i>. ➤ Added a note stating that the fail-safe option should not be used for fast hybrid output contacts in fail-safe/nonfail-safe tripping. <p>Section 4</p> <ul style="list-style-type: none"> ➤ Added a note to <i>RTD Trip/Warning Levels</i>. ➤ Updated <i>Figure 4.49: Trip Logic</i>. ➤ Updated the average number of latch bit state changes per day from 70 to 5000 in <i>Make Latch Control Switch Settings With Care</i>. ➤ Revised the text for <i>Restricted Earth Fault Element</i> and <i>Differential Element</i>. <p>Section 5</p> <ul style="list-style-type: none"> ➤ Added a note to <i>RTD Trip/Warning Levels</i>. ➤ Updated the number of time-stamp entries that the relay memory can hold for load profiling. <p>Section 10</p> <ul style="list-style-type: none"> ➤ Updated the text for SALARM in the ALARM Output bullet of <i>Self-Test</i>. ➤ Updated <i>Table 10.8: Relay Self-Tests</i>. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware versions R110 and R209. <p>Appendix B</p> <ul style="list-style-type: none"> ➤ Added a note to save the calibration settings before the upgrade in <i>Upgrade Firmware Using a Terminal Emulator</i>. |

Table A.6 Instruction Manual Revision History (Sheet 2 of 5)

| Revision Date | Summary of Revisions |
|---------------|---|
| | <p>Appendix E</p> <ul style="list-style-type: none"> ➤ Revised <i>Reading History Data Using Modbus</i>. <p>Appendix F</p> <ul style="list-style-type: none"> ➤ Updated <i>Figure F.1: SEL-787 Predefined Reports</i> and <i>Figure F.2: SEL-787 Datasets</i>. ➤ Revised <i>Table F.7: New Logical Node Extensions</i>, <i>Table F.8: Thermal Metering Data Logical Node Class Definition</i>, and <i>Table F.9: Demand Metering Statistics Logical Node Class Definition</i>. ➤ Added <i>Table F.10: Compatible Logical Nodes With Extensions</i> and <i>Table F.11: Metering Statistics Logical Node Class Definition</i>. ➤ Revised <i>Table F.12: Logical Device: PRO (Protection)</i>, <i>Table F.13: Logical Device: MET (Metering)</i>, <i>Table F.14: Logical Device: CON (Remote Control)</i>, and <i>Table F.15: Logical Device: ANN (Annunciation)</i>. ➤ Added <i>Table F.16: Logical Device: CFG (Configuration)</i>. <p>Appendix J</p> <ul style="list-style-type: none"> ➤ Updated the definition for the SALARM Relay Word bit. ➤ Added the MATHERR Relay Word bit to <i>Table J.1: SEL-787 Relay Word Bits</i> and <i>Table J.2: Relay Word Bit Definitions</i>. |
| 20130426 | <p>Preface</p> <ul style="list-style-type: none"> ➤ Updated the product and compliance labels for the SEL-787. <p>Section 1</p> <ul style="list-style-type: none"> ➤ Added open state leakage current for <i>Fast Hybrid</i> contacts to the <i>Specifications</i>. ➤ Added current/voltage input terminal block information under <i>Terminal Connections</i> category of the <i>Specifications</i>. <p>Section 2</p> <ul style="list-style-type: none"> ➤ Revised the <i>Table 2.12: Jumper Functions and Default Positions</i> footnote to clarify the impact of the jumper position on breaker control. ➤ Added a note to <i>Figure 2.17: Voltage Connections</i>. <p>Section 4</p> <ul style="list-style-type: none"> ➤ Added a note for display points stating that they are updated approximately every two seconds. ➤ Corrected <i>Table 4.54: Entries for the Four Strings</i> for set and clear strings. ➤ Revised <i>Figure 4.3: Differential Element (87-1) Quantities</i> to include the fifth-harmonic quantities. ➤ Revised <i>Figure 4.12: REF Protection Output (Extremely Inverse-Time O/C)</i> to show IN1PU. <p>Section 7</p> <ul style="list-style-type: none"> ➤ Updated the <i>Fiber-Optic Serial Port</i> paragraph. ➤ Updated the +5 Vdc availability statement in <i>+5 Vdc Power Supply</i>. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware versions R208 and R109. <p>Appendix E</p> <ul style="list-style-type: none"> ➤ Added BLOCK MODBUS SET setting paragraph. <p>Appendix G</p> <ul style="list-style-type: none"> ➤ Added BLOCK MODBUS SET setting paragraph. |
| 20120921 | <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware version R108. |
| 20120903 | <p>Preface</p> <ul style="list-style-type: none"> ➤ Updated product label examples in <i>Product Labels</i>. <p>Section 1</p> <ul style="list-style-type: none"> ➤ Updated <i>Specifications</i>. |
| 20111107 | <p>Section 1</p> <ul style="list-style-type: none"> ➤ Added <i>Compression Plug Mounting Ear Screw Tightening Torque</i> specification. <p>Section 5</p> <ul style="list-style-type: none"> ➤ Revised paragraph on small signal cutoff limits for MET and MET RMS values. ➤ Added note to MET response regarding delta-connected CTs and their impact on metered values. |

Table A.6 Instruction Manual Revision History (Sheet 3 of 5)

| Revision Date | Summary of Revisions |
|---------------|--|
| | <p>Settings Sheets</p> <ul style="list-style-type: none"> ➤ Revised MIRRORRED BITS setting CBADPU units to ppm (parts per million). <p>Section 9</p> <ul style="list-style-type: none"> ➤ Added a note for the impact of delta-connected CTs on event report current quantities. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware versions R107 and R207. <p>Appendix B</p> <ul style="list-style-type: none"> ➤ Added note regarding saving data including events before firmware upgrade. <p>Appendix J</p> <ul style="list-style-type: none"> ➤ Updated with Relay Word Bits TSNTTP and TSNTPB. |
| 20110610 | <p>Section 1</p> <ul style="list-style-type: none"> ➤ Added <i>SNTP Accuracy</i> specification. <p>Section 2</p> <ul style="list-style-type: none"> ➤ Added <i>Power Supply Card</i> description and terminal designations. <p>Section 4</p> <ul style="list-style-type: none"> ➤ Added <i>Time and Date Management</i> subsection. ➤ Added <i>SNTP Protocol</i> cross-reference to <i>Section 7: Communications</i>. <p>Section 6</p> <ul style="list-style-type: none"> ➤ Updated Settings sheets for the new settings. <p>Section 7</p> <ul style="list-style-type: none"> ➤ Added <i>SNTP Protocol</i> subsection. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware version R206. <p>Appendix E</p> <p>Updated <i>Table E.32: Modbus Register Map</i> for new settings.</p> <p>Appendix J</p> <ul style="list-style-type: none"> ➤ Updated for new Relay Word bits. |
| 20110201 | <p>Section 10</p> <ul style="list-style-type: none"> ➤ Updated <i>Self-Test</i> descriptions to reflect the improvements (including automatic restarts in some cases) implemented in firmware version R204. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware versions R106 and R205. ➤ Addendum to R204 for the self-test firmware improvements. |
| 20101217 | <p>Section 1</p> <ul style="list-style-type: none"> ➤ Revised Analog Output (1AO) accuracy specification to $< \pm 1\%$, full scale, at 25°C in <i>Specifications</i>. ➤ Updated Dielectric (HiPot) type tests in <i>Specifications</i>. |
| 20101115 | <p>Preface</p> <ul style="list-style-type: none"> ➤ Updated product compliance label. <p>Section 1</p> <ul style="list-style-type: none"> ➤ Updated <i>Specifications</i> for UL508 certification. <p>Section 5</p> <ul style="list-style-type: none"> ➤ Added paragraph on <i>Small Signal Cutoff for Metering</i> in <i>Metering</i> subsection. <p>Section 8</p> <ul style="list-style-type: none"> ➤ Revised paragraph describing settings T0n_LED and T0nLEDL. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware versions R105 and R204. |

Table A.6 Instruction Manual Revision History (Sheet 4 of 5)

| Revision Date | Summary of Revisions |
|---------------|---|
| 2010730 | <p>Section 1</p> <ul style="list-style-type: none"> ➤ Updated <i>Analog Inputs</i> accuracy specifications and <i>Type Tests</i> descriptive data. Clarified fiber-optic port as ST and SEL-2812 compatible throughout sections. <p>Section 2</p> <ul style="list-style-type: none"> ➤ Added SELECT 4DI/3 DO (2 Form C, 1 Form B) card information. Added note that digital inputs and outputs are polarity neutral. <p>Section 4</p> <ul style="list-style-type: none"> ➤ Extended CT ratio setting range. ➤ Added 52A interlock setting to REF element. ➤ Added Level 1 individual phase overcurrent elements to <i>Figure 4.14: Instantaneous Overcurrent Element Logic</i>. ➤ Added individual phase time-overcurrent elements description and diagram. ➤ Added a description of the new Access Control setting BLOCK MODBUS SET (BLKMBSET), which blocks settings changes from remote Modbus or DeviceNet masters. ➤ Added <i>Time-Synchronization Source</i> setting description. ➤ Revised <i>Figure 4.40: Loss-of-Potential (LOP) Logic</i>. ➤ Added two Modbus sessions capability and timeout settings for the Ethernet port. <p>Section 5</p> <ul style="list-style-type: none"> ➤ Added note for the energy meter rollover value. <p>Settings Sheets</p> <ul style="list-style-type: none"> ➤ Updated the settings sheets with settings added in <i>Section 4</i>. <p>Section 7</p> <ul style="list-style-type: none"> ➤ Added CAL level access and password information. <p>Section 8</p> <ul style="list-style-type: none"> ➤ Added note for the target LEDs latching with trip. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware versions R104 and R203. <p>Appendix D</p> <ul style="list-style-type: none"> ➤ Updated for DNP conformance requirements. <p>Appendix F</p> <ul style="list-style-type: none"> ➤ Updated for Select Before Operate (SBO) changes. <p>Appendix J</p> <ul style="list-style-type: none"> ➤ Added new Relay Word bits for phase overcurrent and phase time-overcurrent elements. <p>Command Summary</p> <p>Added CAL level commands.</p> |
| 20100215 | <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware version R202. |
| 20100118 | <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware version R201. |
| 20091015 | <p>Section 1</p> <ul style="list-style-type: none"> ➤ Updated CT ratings and voltage element and metering accuracy specifications. Updated <i>Figure 1.2: STA Command Response—No Communications Card or EIA-232/EIA-485 Communications Card</i> and <i>Figure 1.3: STA Command Response—Communications Card/DeviceNet Protocol</i>. <p>Section 2</p> <ul style="list-style-type: none"> ➤ Updated <i>Figure 2.7: Pins for Password Jumper, Breaker Control Jumper, and SELBOOT Jumper</i> to show jumper locations on updated processor card. <p>Section 4</p> <ul style="list-style-type: none"> ➤ Updated number of event reports that can be stored. ➤ Revised <i>Figure 4.40: Loss-of-Potential (LOP) Logic</i>. |

Table A.6 Instruction Manual Revision History (Sheet 5 of 5)

| Revision Date | Summary of Revisions |
|---------------|--|
| | <p>Section 10</p> <ul style="list-style-type: none"> ➤ Updated <i>Table 10.8: Relay Self-Tests</i> to show additional voltage checks on updated processor card. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware version R200. |
| 20090420 | <p>Section 4</p> <ul style="list-style-type: none"> ➤ Corrected equation error in <i>Figure 4.35: Volts/Hertz Inverse-Time Characteristic, 24IC = 1</i> and <i>Figure 4.36: Volts/Hertz Inverse-Time Characteristic, 24IC = 2</i>. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware version R103. <p>Appendix D</p> <ul style="list-style-type: none"> ➤ Added information regarding default scaling and deadbands for analog quantities angles. |
| 20090218 | <p>Section 1</p> <ul style="list-style-type: none"> ➤ Added fiber-optic port specifications, and revised 51 element response time specifications. <p>Section 2</p> <ul style="list-style-type: none"> ➤ Revised <i>Figure 2.1: Relay Panel-Mount Dimensions</i>. ➤ Revised <i>Figure 2.7: Pins for Password Jumper, Breaker Control, and SELBOOT Jumper</i> and associated text to clarify breaker control jumper selection. <p>Section 4</p> <ul style="list-style-type: none"> ➤ Revised <i>Figure 4.1: Percentage Restraint Differential Characteristic</i> (scaling issue). ➤ Clarified differential element IRT differences between the SEL-787 and SEL-587/SEL-387 and added differential element settings differences between the SEL-787 and SEL-587/SEL-387. <p>Section 7</p> <ul style="list-style-type: none"> ➤ Added Ethernet network configurations figures and IRIG-connection diagrams. <p>Section 10</p> <ul style="list-style-type: none"> ➤ Revised P, Q values in <i>Table 10.5: Power Quantity Accuracy-Wye Voltages</i>. <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware version R102. <p>Appendix I</p> <ul style="list-style-type: none"> ➤ Corrected row numbers in <i>Table I.2: Positions of the MIRRORED BITS</i> and <i>Table I.3: MIRRORED BITS Values for a RXDFLT Setting of 10100111</i>. |
| 20081022 | <p>Appendix A</p> <ul style="list-style-type: none"> ➤ Updated for firmware version R101. |
| 20080407 | <ul style="list-style-type: none"> ➤ Initial version. |

Appendix B

Firmware Upgrade Instructions

Overview

These firmware upgrade instructions apply to all SEL-700 series industrial products except the SEL-701 Relay and SEL-734 Meter.

SEL occasionally offers firmware upgrades to improve the performance of your relay. Because the SEL-787s store firmware in flash memory, changing physical components is not necessary. Upgrade the relay firmware by downloading a file from a personal computer to the relay via the front-panel serial port via ACSELERATOR QuickSet or terminal emulator as outlined in the following sections. For relays with IEC 61850 option, verify IEC 61850 protocol after the upgrade (see *Relays With IEC 61850 Option*).

Required Equipment

NOTE: Firmware releases are also available as zip files (.zip). Use the zip file for faster download.

Gather the following equipment before starting this firmware upgrade:

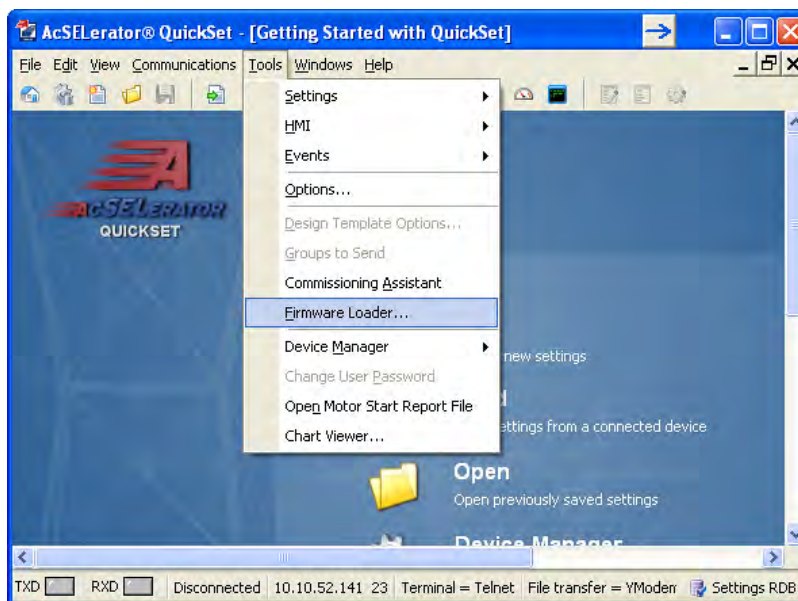
- Personal computer (PC)
- Terminal emulation software that supports Xmodem/CRC or 1k Xmodem/CRC protocol
- Serial communications cable (SEL Cable C234A or equivalent, or a null-modem cable)
- Disk containing the firmware upgrade file (for example, r1017xxx.s19 or r1017xxx.z19)
- ACSELERATOR QuickSet Software

Upgrade Firmware Using ACSELERATOR QuickSet

Select **Tools > Firmware Loader** from the ACSELERATOR QuickSet menu bar to launch a wizard that walks you through the steps to load firmware into your SEL device. Refer to *Section 3: PC Software* for setup and connection procedures for ACSELERATOR QuickSet.

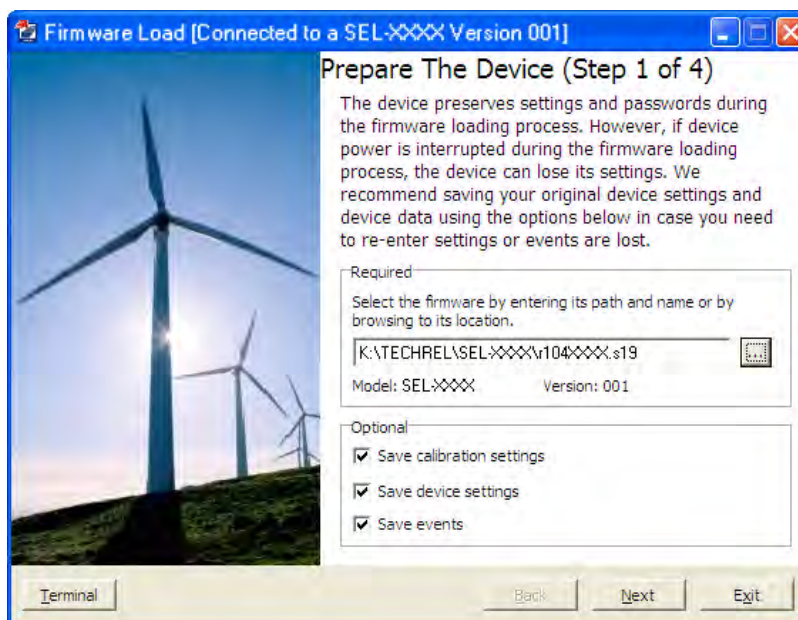
Firmware Loader will not start if:

- The device is unsupported by ACSELERATOR QuickSet.
- The device is not connected to the computer with a communications cable.
- The device is disabled.

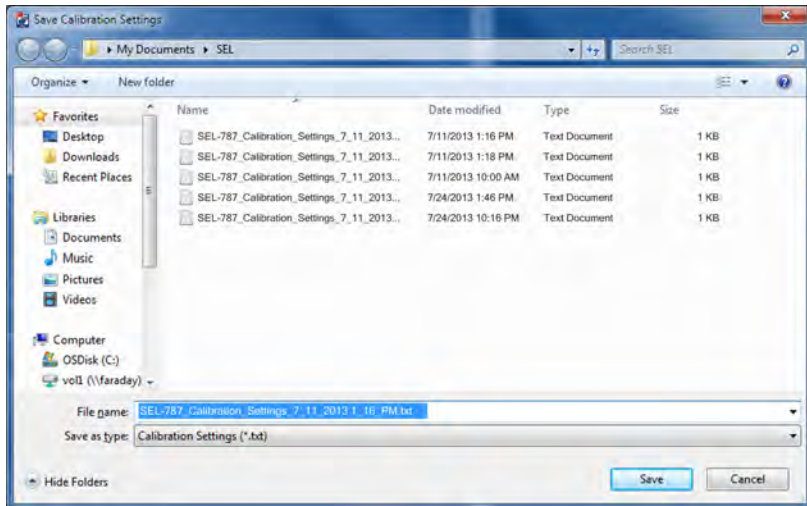


Step 1. Prepare the device.

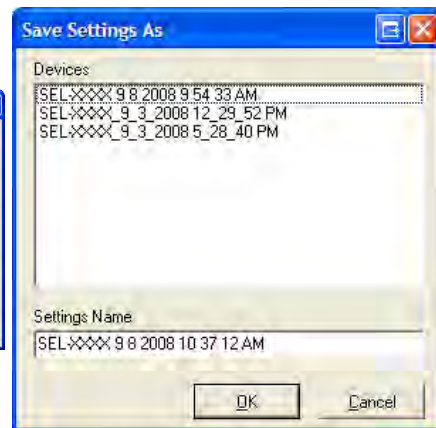
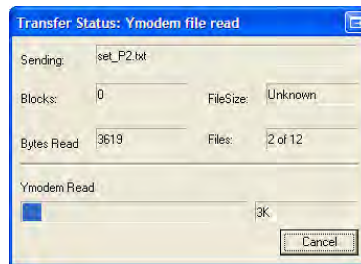
- a. Select the firmware to be loaded using the browse control and select **Save calibration settings**, **Save device settings**, and **Save events** report files. Select **Next** to continue the wizard.



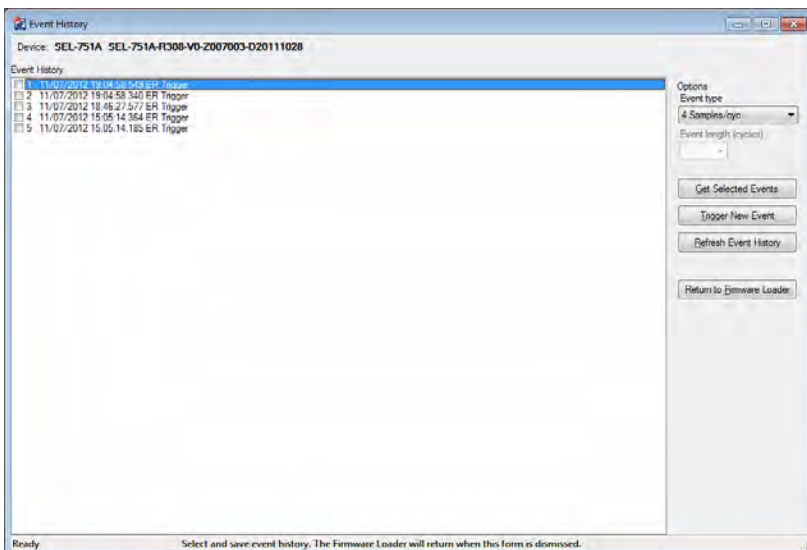
- b. Select a file name to save the selected settings or accept the defaults as shown. Click **Save**.



- c. The **Transfer Status: Ymodem file read** window shows the transfer progress of the settings file. Clicking **Cancel** will stop the transfer. After the device settings are downloaded, select a file name and path to save the settings or accept the default, as shown.

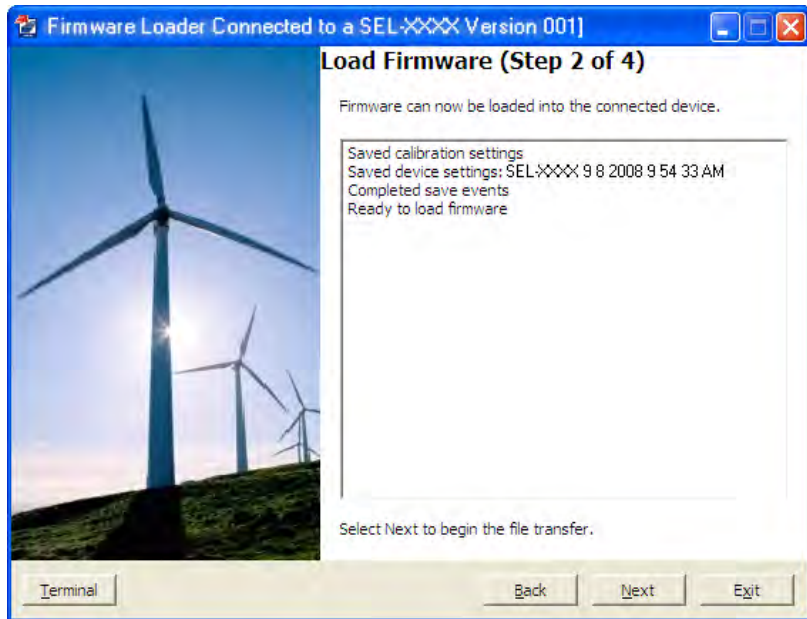


- d. Click **Return to Firmware Loader** if this product does not have any event reports. If there are any event reports to be saved, click the **Get Selected Event** button after selecting the events. After saving them, click the **Return to Firmware Loader** button.



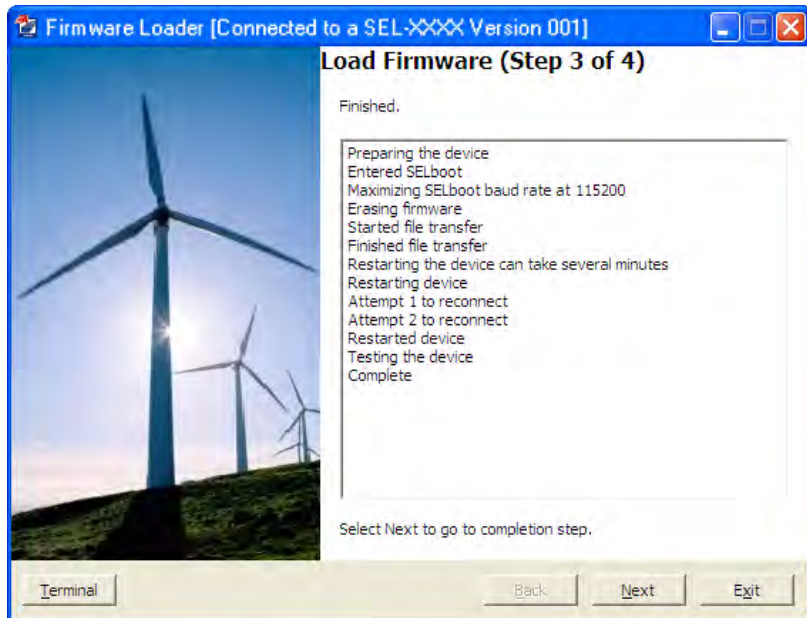
Step 2. Transfer Firmware.

Click **Next** to begin the firmware transfer.



Step 3. Load Firmware.

During this step, the device is put in SELBOOT. The transfer speed is maximized and the firmware transfer begins.



NOTE: The following screen can appear if you have one of the two conditions mentioned.

If the relay is disabled as mentioned in condition number 2, check for the **ENABLED** LED on the front panel of the relay. If the **ENABLED** LED is not illuminated or the front panel displays **STATUS FAIL**, **EEPROM FAILURE**, or **Non_Vol Failure**, use the following procedure to restore the factory-default settings:

- a. Click on the Terminal button on the Firmware Load screen of ACSELERATOR QuickSet.
- b. Set the communications software settings to 9600 baud, 8 data bits, and 1 stop bit.
- c. Enter Access Level 2 by issuing the **2AC** command.
- d. Issue the **R_S** command to restore the factory default.
- e. Enter Access Level 2.
- f. Issue the **STATUS** command.

If the **STATUS** report shows option card FAIL and Relay Disabled and the message:

Confirm Hardware Config

Accept & Reboot (Y/N)?

Enter Y. This will save the relay calibration settings. The relay will respond:

Config Accepted

The relay will reboot and come up **ENABLED**.



Step 4. Verify Device.

Four verification options are provided and when enabled these options perform as follows.

Test Device Communications.

If the device cannot be restarted, then turn power off and back on to restart it. Once the device is enabled, this option reconnects and re-initializes the device.

Compare Device Settings.

This option verifies settings by reading them from the device and comparing them with settings saved to the database.

Restore Device Settings.

This option restores settings by writing settings saved in the database to the device. Settings are converted automatically, if necessary.

Load Firmware into Another Device. Returns the wizard to *Step 1: Prepare Device* to repeat the firmware-loading process with another device.



Upgrade Firmware Using a Terminal Emulator

The following instructions assume you have a working knowledge of your personal computer terminal emulation software. In particular, you must be able to modify your serial communications parameters (baud rate, data bits, parity, etc.), select transfer protocol (Xmodem/CRC or 1k Xmodem/CRC), and transfer files (for example, send and receive binary files).

- Step 1. If the relay is in service, open the relay control circuits.
- Step 2. Connect the PC to the front-panel serial port and enter Access Level 2.
- Step 3. Save the present relay settings.

You can use the PC software (described in the instruction manual PC software section) to save and restore settings easily. Otherwise, use the following steps.

- a. Issue the following commands at the ASCII prompt:
SHO, SHO L, SHO G, SHO P, SHO F, SHO R, SHO C, etc.
- b. Record all the settings for possible re-entry after the firmware upgrade.
- c. We recommend that you save all stored data in the relay, including EVENTS, before the upgrade.

- Step 4. Start upgrading of firmware.
 - a. Issue the **L_D** command to the relay.
 - b. Type **Y <Enter>** at the following prompt:
Disable relay to receive firmware (Y/N)?
 - c. Type **Y <Enter>** at the following prompt:
Are you sure (Y,N)?
The relay will send the **!>** prompt.

- Step 5. Change the baud rate, if necessary.
 - a. Type **BAU 115200 <Enter>**.
This will change the baud rate of the communications port to 115200.
 - b. Change the baud rate of the PC to 115200 to match the relay.

- Step 6. Begin the transfer of new firmware to the relay by issuing the **REC** command.

- Step 7. Type **Y** to erase the existing firmware or press **<Enter>** to abort.

- Step 8. Press any key (for example, **<Enter>**) when the relay sends a prompt.

NOTE: To save the calibration settings, perform **SHO C** from the terminal by logging into the CAL level using the CAL level password. The factory-default password for the CAL level is CLARKE.

NOTE: If you have difficulty at 115200 bps, choose a slower data transfer rate (for example, 38400 bps or 57600 bps). Be sure to match the relay and PC data rates.

Step 9. Start the file transfer.

Select the send file option in your communications software.

Use the Xmodem protocol and send the file that contains the new firmware (for example, r101xxx.s19 or r101xxx.z19).

The file transfer takes less than 5–15 minutes at 115200 baud, depending on the product. After the transfer is complete, the relay will reboot and return to Access Level 0.

Figure B.1 shows the entire process.

```
=>>L_D <Enter>

Disable relay to receive firmware (Y,N)? Y <Enter>
Are you sure (Y,N)? Y <Enter>
Relay Disabled

BFID=BOOTLDR-R500-V0-Z000000-D20090925
!>BAU 115200 <Enter>
!>REC <Enter>
This command uploads new firmware.
When new firmware is uploaded successfully, IED will erase old firmware,
load new firmware and reboot.

Are you sure you want to erase the existing firmware(Y,N)? Y <Enter>
Press any key to begin transfer and then start transfer at the terminal.<Enter>
Erasing firmware.
Erase successful.
Writing new firmware.
Upload completed successfully. Attempting a restart.
```

Figure B.1 Firmware File Transfer Process

Step 10. The relay illuminates the **ENABLED** front-panel LED if the relay settings were retained through the download.

If the **ENABLED** LED is illuminated, proceed to *Step 11*.

If the **ENABLED** LED is not illuminated or the front panel displays **STATUS FAIL**, **EEPROM FAILURE**, or **Non_Vol Failure**, use the following procedure to restore the factory-default settings:

- a. Set the communications software settings to 9600 baud, 8 data bits, and 1 stop bit.
- b. Enter Access Level 2 by issuing the **2AC** command.
- c. Issue the **R_S** command to restore the factory-default settings.

The relay will then reboot with the factory-default settings.

- d. Enter Access Level 2.
- e. Issue the **STATUS** command.

If the relay is **ENABLED** go to *Step f*.

If the **STATUS** report shows option card **FAIL** and **Relay Disabled** and the message:

```
Confirm Hardware Config
Accept & Reboot (Y/N)?
```

Enter **Y**. This will save the relay calibration settings.

The relay will respond:

```
Config Accepted
```

The relay will reboot and come up **ENABLED**.

- f. Restore relay settings back to the settings saved in *Step 3*.

- Step 11. Change the baud rate of the PC to match that of the relay prior to *Step 5*, and enter Access Level 2.
- Step 12. Issue the **STATUS** command; verify all relay self-test results are OK.
- Step 13. Apply current and voltage signals to the relay.
- Step 14. Issue the **METER** command; verify that the current and voltage signals are correct.
- Step 15. Autoconfigure the SEL-2032, SEL-2030, or SEL-2020 port if you have a Communications Processor connected.

This step re-establishes automatic data collection between the SEL-2032, SEL-2030, or SEL-2020 Communications Processor and the SEL relay. Failure to perform this step can result in automatic data collection failure when cycling communications processor power.

Relays With IEC 61850 Option

NOTE: A relay with optional IEC 61850 protocol requires the presence of one valid CID file to enable the protocol. You should only transfer a CID file to the relay if you want to implement a change in the IEC 61850 configuration or if new relay firmware does not support the current CID file version. If you transfer an invalid CID file, the relay will disable the IEC 61850 protocol, because it no longer has a valid configuration. To restart IEC 61850 protocol operation, you must transfer a valid CID file to the relay.

Perform the following steps to verify that the IEC 61850 protocol is still operational after a relay firmware upgrade and if not, reenable it. This procedure assumes that IEC 61850 was operational with a valid CID file immediately before initiating the relay firmware upgrade.

- Step 1. Establish an FTP connection to the relay Ethernet port.
- Step 2. Open the ERR.TXT file.

If the ERR.TXT file is empty, the relay found no errors during CID file processing and IEC 61850 should be enabled. Go to *Step 3* if ERR.TXT is empty.

If the ERR.TXT file contains error messages relating to CID file parsing, the relay has disabled the IEC 61850 protocol. Use ACSELERATOR® Architect™ SEL-5032 Software to convert the existing CID file and make it compatible again.

 - a. Install the ACSELERATOR Architect software upgrade that supports your required CID file version.
 - b. Run ACSELERATOR Architect and open the project that contains the existing CID file for the relay.
 - c. Download the CID file to the relay.
- Step 3. Upon connecting to the relay, ACSELERATOR Architect will detect the upgraded relay firmware and prompt you to allow it to convert the existing CID file to a supported version. Once converted, downloaded, and processed, the valid CID file allows the relay to reenable the IEC 61850 protocol.
- Step 4. In the Telnet session, type GOO <Enter>.
- Step 5. View the GOOSE status and verify that the transmitted and received messages are as expected.

The relay is now ready for your commissioning procedure.

Factory Assistance

We appreciate your interest in SEL products and services. If you have questions or comments, please contact us at:

Schweitzer Engineering Laboratories, Inc.
2350 NE Hopkins Court
Pullman, WA 99163-5603 U.S.A.
Telephone: +1.509.332.1890
Fax: +1.509.332.7990
Email: info@selinc.com
Internet: www.selinc.com

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Appendix C

SEL Communications Processors

SEL Communications Protocols

The SEL-787 Transformer Protection Relay supports the SEL protocols and command sets shown in *Table C.1*.

Table C.1 Supported Serial Command Sets

| Command Set | Description |
|----------------------|---|
| SEL ASCII | Use this protocol to send ASCII commands and receive ASCII responses that are human readable with an appropriate terminal emulation program. |
| SEL Compressed ASCII | Use this protocol to send ASCII commands and receive Compressed ASCII responses that are comma-delimited for use with spreadsheet and database programs or for use by intelligent electronic devices. |
| SEL Fast Meter | Use this protocol to send binary commands and receive binary meter and target responses. |
| SEL Fast Operate | Use this protocol to receive binary control commands. |
| SEL Fast SER | Use this protocol to receive binary Sequential Events Recorder unsolicited responses. |

SEL ASCII Commands

We originally designed SEL ASCII commands for communication between the relay and a human operator via a keyboard and monitor or a printing terminal. A computer with a serial port can also use the SEL ASCII protocol to communicate with the relay, collect data, and issue commands.

SEL Compressed ASCII Commands

The relay supports a subset of SEL ASCII commands identified as Compressed ASCII commands. Each of these commands results in a comma-delimited message that includes a checksum field. Most spreadsheet and database programs can directly import comma-delimited files. Devices with embedded processors connected to the relay can execute software to parse and interpret comma-delimited messages without expending the customization and maintenance labor needed to interpret nondelimited messages. The relay calculates a checksum for each line by numerically summing all of the bytes that precede the checksum field in the message. The program that uses the data can detect transmission errors in the message by summing the characters of the received message and comparing this sum to the received checksum.

Most commands are available in either SEL ASCII or Compressed ASCII. Selected commands have versions in both standard SEL ASCII and Compressed ASCII formats. Compressed ASCII reports generally have fewer characters than conventional SEL ASCII reports because the compressed reports reduce blanks, tabs, and other white space between data fields to a single comma.

Table C.2 lists the Compressed ASCII commands and contents of the command responses.

Table C.2 Compressed ASCII Commands

| Command | Response | Access Level |
|-----------------|--|--------------|
| BNAME | ASCII names of Fast Meter status bits | 0 |
| CASCII | Configuration data of all Compressed ASCII commands | 0 |
| CEVENT | Event report | 1 |
| CHISTORY | List of events | 1 |
| CLDP | Load Profile Data | 1 |
| CMETER | Metering data, including fundamental, differential, thermal demand, peak demand, harmonic, energy, max/min, rms, analog inputs, and math variables | 1 |
| CSE | Sequence Of Events Data | 1 |
| CSTATUS | Relay status | 1 |
| CSUMMARY | Summary of an event report | 1 |
| CTFE | Through-fault event report | 1 |
| DNAME | ASCII names of digital I/O reported in Fast Meter | 0 |
| ID | Relay identification | 0 |
| SNS | ASCII names for SER data reported in Fast Meter | 0 |

Interleaved ASCII and Binary Messages

SEL relays have two separate data streams that share the same physical serial port. Human data communications with the relay consist of ASCII character commands and reports that you view through use of a terminal or terminal emulation package. The binary data streams can interrupt the ASCII data stream to obtain information; the ASCII data stream continues after the interruption. This mechanism uses a single communications channel for ASCII communication (transmission of an event report, for example) interleaved with short bursts of binary data to support fast acquisition of metering data. The device connected to the other end of the link requires software that uses the separate data streams to exploit this feature. However, you do not need a device to interleave data streams to use the binary or ASCII commands. Note that XON, XOFF, and CAN operations operate on only the ASCII data stream.

An example of using these interleaved data streams is when the SEL-787 communicates with an SEL communications processor. These SEL communications processors perform autoconfiguration by using a single data stream and SEL Compressed ASCII and binary messages. In subsequent operations, the SEL communications processor uses the binary data stream for Fast Meter and Fast Operate messages to populate a local database and to perform SCADA operations. At the same time, you can use the binary data stream to connect transparently to the SEL-787 and use the ASCII data stream for commands and responses.

SEL Fast Meter, Fast Operate, and Fast SER

SEL Fast Meter is a binary message that you solicit with binary commands. Fast Operate is a binary message for control. The relay can also send unsolicited Fast SER messages automatically. If the relay is connected to an SEL communications processor, these messages provide the mechanism that the communications processor uses for SCADA or DCS functions that occur simultaneously with ASCII interaction.

SEL Communications Processor

SEL offers SEL communications processors, which are powerful tools for system integration and automation. The SEL-2030 series and the SEL-2020 communications processors are similar, except that the SEL-2030 series has two slots for network protocol cards. These devices provide a single point of contact for integration networks with a star topology, as shown in *Figure C.1*.

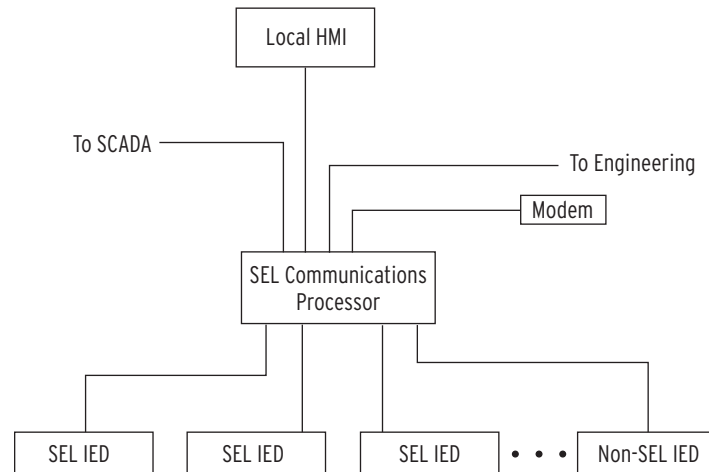


Figure C.1 SEL Communications Processor Star Integration Network

In the star topology network in *Figure C.1* the SEL communications processor uses the following substation integration functions:

- Collection of real-time data from SEL and non-SEL IEDs
- Calculation, concentration, and aggregation of real-time IED data into databases for SCADA, HMI, and other data consumers
- Access to the IEDs for engineering functions including configuration, report data retrieval, and control through local serial, remote dial-in, and Ethernet network connections
- Distribution of IRIG-B time synchronization signal to IEDs based on external IRIG-B input, internal clock, or protocol interface
- Simultaneous collection of SCADA data and engineering connection to SEL IEDs over a single cable
- Automated dial-out on alarms

The SEL communications processors have 16 serial ports plus a front port. This port configuration does not limit the size of a substation integration project, because you can create a multitiered solution as shown in *Figure C.2*. In this multitiered system, the lower-tier SEL communications processors forward data to the upper-tier SEL communications processor that serves as the central point of access to substation data and substation IEDs.

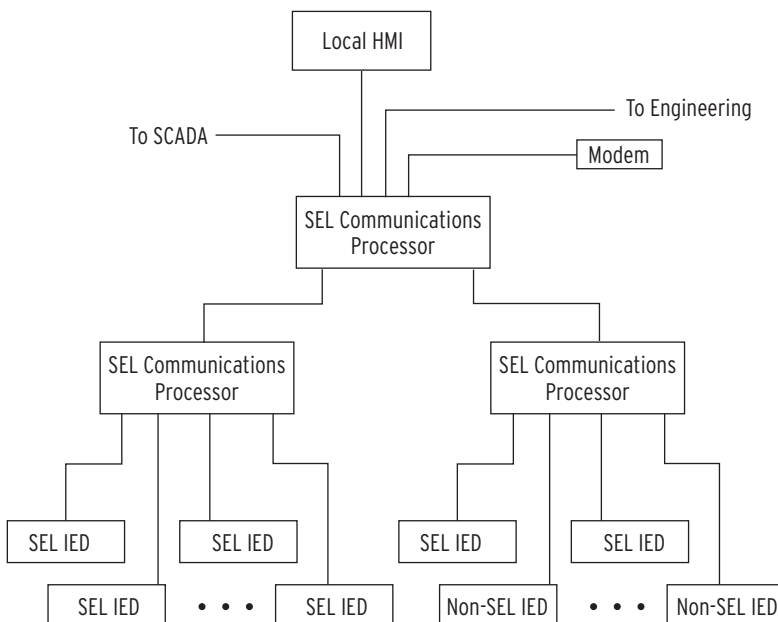


Figure C.2 Multitiered SEL Communications Processor Architecture

You can add additional communications processors to provide redundancy and eliminate possible single points of failure. SEL communications processors provide an integration solution with a reliability comparable to that of SEL relays. In terms of MTBF (mean time between failures), SEL communications processors are 100 to 1000 times more reliable than computer-based and industrial technology-based solutions.

Configuration of an SEL communications processor is different from other general-purpose integration platforms. You can configure SEL communications processors with a system of communication-specific keywords and data movement commands rather than programming in C or another general-purpose computer language. SEL communications processors offer the protocol interfaces listed in *Table C.3*.

Table C.3 SEL Communications Processors Protocol Interfaces

| Protocol | Connect to |
|---|--|
| DNP3 Level 2 Slave | DNP3 masters |
| Modbus® RTU Protocol | Modbus masters |
| SEL ASCII/Fast Message Slave | SEL protocol masters |
| SEL ASCII/Fast Message Master | SEL protocol slaves including other communications processors and SEL relays |
| ASCII and Binary auto messaging | SEL and non-SEL IED master and slave devices |
| Modbus Plus ^a | Modbus Plus peers with global data and Modbus Plus masters |
| FTP (File Transfer Protocol) ^b | FTP clients |
| Telnet ^b | Telnet servers and clients |
| UCA2 GOMSFE ^b | UCA2 protocol masters |
| UCA2 GOOSE ^b | UCA2 protocol and peers |

^a Requires SEL-2711 Modbus Plus protocol card.

^b Requires SEL-2701 Ethernet Processor.

SEL Communications Processor and Relay Architecture

Developing Star Networks

You can apply SEL communications processors and SEL relays in a limitless variety of applications to integrate, automate, and improve station operation. Most system integration architectures using SEL communications processors involve either developing a star network or enhancing a multidrop network.

The simplest architecture using both the SEL-787 and an SEL communications processor is shown in *Figure C.1*. In this architecture, the SEL communications processor collects data from the SEL-787 and other station IEDs. The SEL communications processor acts as a single point of access for local and remote data consumers (local HMI, SCADA, engineers). The communications processor also provides a single point of access for engineering operations including configuration and the collection of report-based information.

By configuring a data set optimized to each data consumer, you can significantly increase the utilization efficiency on each link. A system that uses an SEL communications processor to provide a protocol interface to an RTU will have a shorter lag time (data latency); communication overhead is much less for a single data exchange conversation to collect all substation data (from a communications processor) than for many conversations required to collect data directly from each individual IED. You can further reduce data latency by connecting any SEL communications processor directly to the SCADA master thereby eliminating redundant communication processing in the RTU.

The SEL communications processor is responsible for the protocol interface, so you can install, test, and even upgrade the system in the future without disturbing protective relays and other station IEDs. This insulation of the protective devices from the communications interface assists greatly in situations where different departments are responsible for SCADA operation, communication, and protection.

SEL communications processors equipped with an SEL-2701 Ethernet Processor can provide a UCA2 interface to SEL-787 relays and other serial IEDs. The SEL-787 data appear in models in a virtual device domain. The combination of the SEL-2701 with an SEL communications processor offers a significant cost savings because you can use existing IEDs or purchase less expensive IEDs. For full details on applying the SEL-2701 with an SEL communications processor, see the *SEL-2701 Ethernet Processor Instruction Manual*.

The engineering connection can use either an Ethernet network connection through the SEL-2701 or a serial port connection. This versatility will accommodate the channel that is available between the station and the engineering center. SEL software can use either a serial port connection or an Ethernet network connection from an engineering workstation to the relays in the field.

Enhancing Multidrop Networks

You can also use an SEL communications processor to enhance a multidrop architecture similar to the one shown in *Figure C.3*. In this example, the SEL communications processor enhances a system that uses the SEL-2701 with an Ethernet HMI multidrop network. There are two Ethernet networks, the SCADA LAN and the Engineering LAN. The SCADA LAN provides real-time data directly to the SCADA Control Center via a protocol gateway and to the HMI (Human Machine Interface).

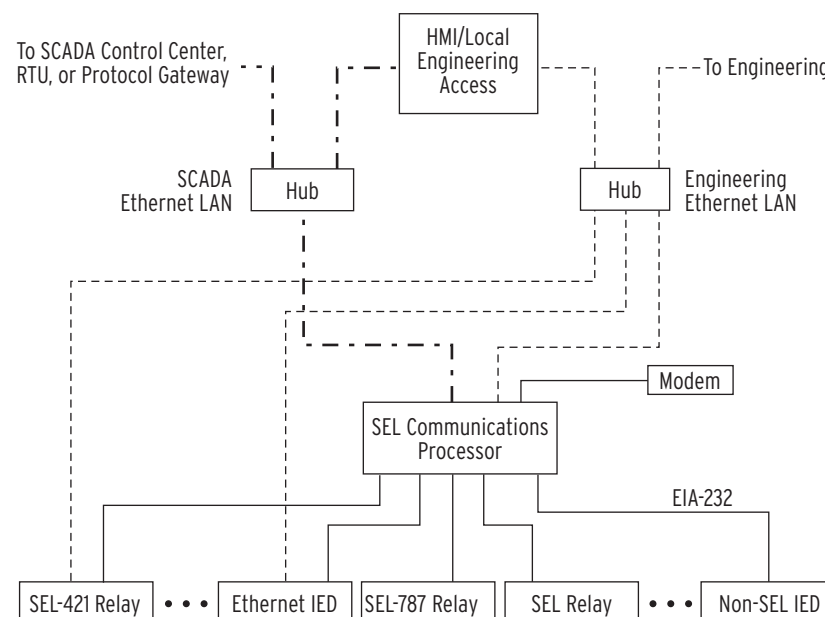


Figure C.3 Enhancing Multidrop Networks With SEL Communications Processors

In the figure, the SEL communications processor provides the following enhancements when compared to a system that employs only the multidrop network:

- Ethernet access for IEDs with serial ports
- Backup engineering access through the dial-in modem
- IRIG-B time signal distribution to all station IEDs
- Integration of IEDs without Ethernet
- Single point of access for real-time data for SCADA, HMI, and other uses
- Significant cost savings by use of existing IEDs with serial ports

SEL Communications Processor Example

This example demonstrates the data and control points available in the SEL communications processor when you connect an SEL-787. The physical configuration used in this example is shown in *Figure C.4*.

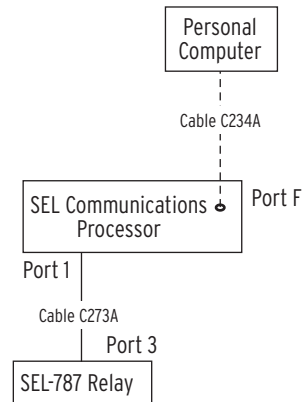


Figure C.4 Example of SEL Relay and SEL Communications Processor Configuration

Table C.4 shows the Port 1 settings for the SEL communications processor.

Table C.4 SEL Communications Processor Port 1 Settings

| Setting Name | Setting | Description |
|--------------|----------------|--|
| DEVICE | S | Connected device is an SEL device |
| CONFIG | Y | Allow autoconfiguration for this device |
| PORTID | <i>Relay 1</i> | Name of connected relay ^a |
| BAUD | 19200 | Channel speed of 19200 bits per second ^a |
| DATABIT | 8 | Eight data bits ^a |
| STOPBIT | 1 | One stop bit |
| PARITY | N | No parity |
| RTS_CTS | N | Hardware flow control enabled |
| XON_XOFF | Y | Enable XON/XOFF flow control |
| TIMEOUT | 30 | Idle timeout that terminates transparent connections of 30 seconds |

^a Automatically collected by the SEL communications processor during autoconfiguration.

Data Collection

The SEL communications processor is configured to collect data from the SEL-787 using the commands listed in Table C.5.

Table C.5 SEL Communications Processor Data Collection Automessages

| Message | Data Collected |
|-----------|---|
| 20METER | Power system metering data |
| 20DEMAND | Demand metering data |
| 20TARGET | Selected Relay Word bit elements |
| 20HISTORY | History command (ASCII) |
| 20STATUS | Status command (ASCII) |
| 20EVENTS | Standard 4 sample/cycle event report (data with settings) |
| 20EVENT | Standard 4 sample/cycle event report (data only) |

Table C.6 shows the automessage (**SET A**) settings for the SEL communications processor.

Table C.6 SEL Communications Processor Port 1 Automatic Messaging Settings

| Setting Name | Setting | Description |
|--------------|--------------|--|
| AUTOBUF | Y | Save unsolicited messages |
| STARTUP | ACC\nOTTER\n | Automatically log-in at Access Level 1 |
| SEND_OPER | Y | Send Fast Operate messages for remote bit and breaker bit control |
| REC_SER | N | Automatic sequential event recorder data collection disabled |
| NOCONN | NA | No SELOGIC® control equation entered to selectively block connections to this port |
| MSG_CNT | 3 | Three automessages |
| ISSUE1 | P00:00:01.0 | Issue Message 1 every second |
| MESG1 | 20METER | Collect metering data |
| ISSUE2 | P00:00:01.0 | Issue Message 2 every second |
| MESG2 | 20TARGET | Collect Relay Word bit data |
| ISSUE3 | P00:01:00.0 | Issue Message 3 every minute |
| MESG3 | 20DEMAND | Collect demand metering data |
| ARCH_EN | N | Archive memory disabled |
| USER | 0 | No USER region registers reserved |

Table C.7 shows the map of regions in the SEL communications processor for data collected from the SEL-787. Use the **MAP n** command to view these data.

Table C.7 SEL Communications Processor Port 1 Region Map

| Region | Data Collection Message Type | Region Name | Description |
|--------|------------------------------|---------------------|---------------------|
| D1 | Binary | METER | Relay metering data |
| D2 | Binary | TARGET | Relay Word bit data |
| D3 | Binary | DEMAND ^a | Demand meter data |
| D4–D8 | n/a | n/a | Unused |
| A1–A3 | n/a | n/a | Unused |
| USER | n/a | n/a | Unused |

^a Demand function is available only when the setting EDEM is not set to OFF.

Relay Metering Data

Table C.8 lists the meter data available in the SEL communications processor and the location and data type for the memory areas within D1 (Data Region 1). The type field indicates the data type and size. The *int* type is a 16-bit integer. The *float* type is a 32-bit IEEE floating point number. Use the **VIE n:D1** command to view these data.

Table C.8 Communications Processor METER Region Map

| Item | Starting Address | Type |
|-------------|------------------|--------|
| _YEAR | 2000h | int |
| DAY_OF_YEAR | 2001h | int |
| TIME (ms) | 2002h | int[2] |
| MONTH | 2004h | char |
| DATE | 2005h | char |
| YEAR | 2006h | char |
| HOUR | 2007h | char |
| MIN | 2008h | char |
| SECONDS | 2009h | char |
| MSEC | 200Ah | int |
| IAW1 | 200Bh | float |
| IBW1 | 200Dh | float |
| ICW1 | 200Fh | float |
| IAW2 | 2011h | float |
| IBW2 | 2013h | float |
| ICW2 | 2015h | float |
| IN | 2017h | float |
| VAB | 2019h | float |
| VBC | 201Bh | float |
| VCA | 201Dh | float |
| P | 201Fh | float |
| Q | 2021h | float |
| S | 2023h | float |
| PF | 2025h | float |
| FREQ | 2027h | float |
| V/HZ | 2029h | float |

Relay Word Bits Information

Table C.9 lists the Relay Word bit data available in the SEL communications processor TARGET region.

Table C.9 Communications Processor TARGET Region Map

| Address | Relay Word Bits (in Bits 7-0) | | | | | | | |
|---------|-------------------------------|---|---|---|---|-------|-------|---|
| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 2804h | * | * | * | * | * | PWRUP | STSET | * |
| 2805h | See Table J.1, Row 0 | | | | | | | |
| 2806h | See Table J.1, Row 1 | | | | | | | |
| 2807h | See Table J.1, Row 2 | | | | | | | |
| 2808h | See Table J.1, Row 3 | | | | | | | |
| 2809h | See Table J.1, Row 4 | | | | | | | |
| 280Ah | See Table J.1, Row 5 | | | | | | | |
| 280Bh | See Table J.1, Row 6 | | | | | | | |
| 280Ch | See Table J.1, Row 7 | | | | | | | |
| 280Dh | See Table J.1, Row 8 | | | | | | | |
| 280Eh | See Table J.1, Row 9 | | | | | | | |
| 280Fh | See Table J.1, Row 10 | | | | | | | |
| 2810h | See Table J.1, Row 11 | | | | | | | |
| 2811h | See Table J.1, Row 12 | | | | | | | |
| • | • | | | | | | | |
| • | • | | | | | | | |
| • | • | | | | | | | |
| 286Fh | See Table J.1, Row 106 | | | | | | | |

Control Points

The SEL communications processor can automatically pass control messages, called Fast Operate messages, to the SEL-787. You must enable Fast Operate messages by using the FASTOP setting in the SEL-787 port settings for the port connected to the SEL communications processor. You must also enable Fast Operate messages in the SEL communications processor by setting the automessage setting SEND_OPER equal to Y.

When you enable Fast Operate functions, the SEL communications processor automatically sends messages to the relay for changes in remote bits RB01–RB32 on the corresponding SEL communications processor port. In this example, if you set RB01 on **Port 1** in the SEL communications processor, it automatically sets RB01 in the SEL-787.

Breaker bits BR1 and BR2 operate differently than remote bits. There are two breaker bits in the SEL-787. For Circuit Breaker n , when you set BR_n , the SEL communications processor sends a message to the SEL-787 that asserts the OC_n bit for one processing interval. If you clear BR_n , the SEL communications processor sends a message to the SEL-787 that asserts the CC_n bit for one processing interval. OC_n will open the breaker (via SELOGIC equation TR_x) and CC_n will close the breaker (via SELOGIC Equation CL_x). See Figure 4.49 and Figure 4.50 for the breaker trip and breaker close logic diagrams, respectively.

Demand Data

Table C.10 lists the demand data available in the SEL Communications Processor and the location and data type for the memory areas within D3 (Data Region 3). The type field indicates the data type and size. The type “int” is a 16-bit integer. The type “float” is a 32-bit IEEE floating point number.

Table C.10 Communications Processor DEMAND Region Map

| Item | Starting Address | Type |
|-------------|------------------|--------|
| _YEAR | 3000h | int |
| DAY_OF_YEAR | 3001h | int |
| TIME(ms) | 3002h | int[2] |
| MONTH | 3004h | char |
| DATE | 3005h | char |
| YEAR | 3006h | char |
| HOUR | 3007h | char |
| MIN | 3008h | char |
| SECONDS | 3009h | char |
| MSEC | 300Ah | int |
| IAD(A) | 300Bh | float |
| IBD(A) | 300Dh | float |
| ICD(A) | 300Fh | float |
| IGD(A) | 3011h | float |
| 3I2D(A) | 3013h | float |

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Appendix D

DNP3 Communications

Overview

The SEL-787 Transformer Protection Relay provides a Distributed Network Protocol Version 3.0 (DNP3) Level 2 Outstation interface for direct serial and LAN/WAN network connections to the device.

This section covers the following topics:

- *Introduction to DNP3 on page D.1*
- *DNP3 in the SEL-787 on page D.6*
- *DNP3 Documentation on page D.13*

Introduction to DNP3

A Supervisory Control and Data Acquisition (SCADA) manufacturer developed the first versions of DNP from the lower layers of IEC 60870-5. Originally designed for use in telecontrol applications, Version 3.0 of the protocol has also become popular for local substation data collection. DNP3 is one of the protocols included in the IEEE® Recommended Practice for Data Communication between Remote Terminal Units (RTUs) and Intelligent Electronic Devices (IEDs) in a Substation.

The DNP Users Group maintains and publishes DNP3 standards. See the DNP Users Group website, www.dnp.org, for more information on standards, implementers, and tools for working with DNP3.

DNP3 Specifications

DNP3 is a feature-rich protocol with many ways to accomplish tasks, defined in an eight-volume series of specifications. Volume 8 of the specification, called the Interoperability Specification, simplifies DNP3 implementation by providing four standard interoperable implementation levels. The levels are listed in *Table D.1*.

Table D.1 DNP3 Implementation Levels

| Level | Description | Equipment Types |
|-------|--|---------------------------|
| 1 | Simple: limited communication requirements | Meters, simple IEDs |
| 2 | Moderately complex: monitoring and metering devices and multifunction devices that contain more data | Protective relays, RTUs |
| 3 | Sophisticated: devices with great amounts of data or complex communication requirements | Large RTUs, SCADA masters |
| 4 | Enhanced: additional data types and functionality for more complex requirements | Large RTUs, SCADA masters |

Each level is a proper superset of the previous lower-numbered level. A higher-level device can act as a master to a lower-level device, but can only use the data types and functions implemented in the lower level device. For example, a typical SCADA master is a Level 3 device and can use Level 2 (or lower) functions to poll a Level 2 (or lower) device for Level 2 (or lower) data. Similarly, a lower-level device can poll a higher-level device, but the lower level device can only access the features and data available to its level.

In addition to the eight-volume DNP3 specification, the protocol is further refined by conformance requirements, optional features, and a series of technical bulletins. The technical bulletins supplement the specifications with discussions and examples of specific features of DNP3.

Data Handling

Objects

DNP3 uses a system of data references called objects, defined by the Basic 4 standard object library. Each subset level specification requires a minimum implementation of object types and recommends several optional object types. DNP3 object types, commonly referred to as objects, are specifications for the type of data the object carries. An object can include a single value or more complex data. Some objects serve as shorthand references for special operations, including collections of data, time synchronization, or even all data within the DNP3 device.

If there can be more than one instance of a type of object, then each instance of the object includes an index that makes it unique. For example, each binary status point (Object 1) has an index. If there are 16 binary status points, these points are Object 1, Index 0 through Object 1, Index 15.

Each object also includes multiple versions called variations. For example, Object 1 (binary inputs) has three variations: 0, 1, and 2. You can use variation 0 to request all variations, variation 1 to specify binary input values only, and variation 2 to specify binary input values with status information.

Each DNP3 device has both a list of objects and a map of object indices. The list of objects defines the available objects, variations, and qualifier codes. The map defines the indices for objects that have multiple instances and defines what data or control points correspond with each index.

A master initiates all DNP3 message exchanges except unsolicited data. DNP3 terminology describes all points from the perspective of the master. Binary points for control that move from the master to the outstation are called Binary Outputs, while binary status points within the outstation are called Binary Inputs.

Function Codes

Each DNP3 message includes a function code. Each object has a limited set of function codes that a master may use to manipulate the object. The object listing for the device shows the permitted function codes for each type of object. The most common DNP3 function codes are listed in *Table D.2*.

Table D.2 Selected DNP3 Function Codes (Sheet 1 of 2)

| Function Code | Function | Description |
|---------------|----------|----------------------------------|
| 1 | Read | Request data from the outstation |
| 2 | Write | Send data to the outstation |

Table D.2 Selected DNP3 Function Codes (Sheet 2 of 2)

| Function Code | Function | Description |
|---------------|--------------------------|--|
| 3 | Select | First part of a Select Before Operate operation |
| 4 | Operate | Second part of a Select Before Operate operation |
| 5 | Direct operate | One-step operation with reply |
| 6 | Direct operate, no reply | One-step operation with no reply |

Qualifier Codes and Ranges

DNP3 masters use qualifier codes and ranges to make requests for specific objects by index. Qualifier codes specify the style of range, and the range specifies the indices of the objects of interest. DNP3 masters use qualifier codes to compose the shortest, most concise message possible when requesting points from a DNP3 outstation.

For example, the qualifier code 01 specifies that the request for points will include a start address and a stop address. Each of these two addresses uses two bytes. An example request using qualifier code 01 might have the four hexadecimal byte range field, 00h 04h 00h 10h, which specifies points in the range 4 to 16.

Access Methods

DNP3 has many features that help obtain maximum possible message efficiency. DNP3 masters send requests with the least number of bytes using special objects, variations, and qualifiers that reduce the message size. Other features eliminate the continual exchange of static (unchanging) data values. These features optimize use of bandwidth and maximize performance over a connection of any speed.

DNP3 event data collection eliminates the need to use bandwidth to transmit values that have not changed. Event data are time-stamped records that show when observed measurements changed. For binary points, the remote device (DNP3 outstation) logs changes from logical 1 to logical 0 and from logical 0 to logical 1. For analog points, the outstation device logs changes that exceed a dead band. DNP3 outstation devices collect event data in a buffer that either the master can request or the device can send to the master without a request message. Data sent from the outstation to the master without a polling request are called unsolicited data.

DNP3 data fit into one of four event classes: 0, 1, 2, or 3. Class 0 is reserved for reading the present value data (static data). Classes 1, 2, and 3 are event data classes. The meaning of Classes 1 to 3 is arbitrary and defined by the application at hand. With outstations that contain great amounts of data or in large systems, the three event classes provide a framework for prioritizing different types of data. For example, you can poll once a minute for Class 1 data, once an hour for Class 2 data, and once a day for Class 3 data.

DNP3 also supports static polling: simple polling of the present value of data points within the outstation. By combining event data, unsolicited polling, and static polling, you can operate your system in one of the four access methods shown in *Table D.3*.

The access methods listed in *Table D.3* are listed in order of increasing communication efficiency. With various trade-offs, each method is less demanding of communication bandwidth than the previous one. For example, unsolicited report-by-exception consumes less communication bandwidth than polled report-by-exception because that method does not require polling

messages from the master. In order to properly evaluate which access method provides optimum performance for your application, you must also consider overall system size and the volume of data communication expected.

Table D.3 DNP3 Access Methods

| Access Method | Description |
|---------------------------------|--|
| Polled static | Master polls for present value (Class 0) data only |
| Polled report-by-exception | Master polls frequently for event data and occasionally for Class 0 data |
| Unsolicited report-by-exception | Outstation devices send unsolicited event data to the master, and the master occasionally polls for Class 0 data |
| Quiescent | Master never polls and relies on unsolicited reports only |

Binary Control Operations

DNP3 masters use Object 12, control device output block, to perform DNP3 binary control operations. The control device output block has both a trip/close selection and a code selection. The trip/close selection allows a single DNP3 index to operate two related control points such as trip and close or raise and lower. Trip/close pair operation is not recommended for new DNP3 devices, but is often included for interoperability with older DNP3 master implementations.

The control device output block code selection specifies either a latch or pulse operation on the point. In many cases, DNP3 outstations have only a limited subset of the possible combinations of the code field. Sometimes, DNP3 outstations assign special operation characteristics to the latch and pulse selections. *Table D.12* describes control point operation for the SEL-787.

Conformance Testing

In addition to the protocol specifications, the DNP Users Group has approved conformance-testing requirements for Level 1 and Level 2 devices. Some implementers perform their own conformance specification testing, while some contract with independent companies to perform conformance testing.

Conformance testing does not always guarantee that a master and outstation will be fully interoperable (that is, work together properly for all implemented features). Conformance testing does help to standardize the testing procedure and move the DNP3 implementers toward a higher level of interpretability.

DNP3 Serial Network Issues

Data Link Layer Operation

DNP3 employs a three-layer version of the seven-layer OSI (Open Systems Interconnect) model called the enhanced performance architecture. The layer definition helps to categorize functions and duties of various software components that make up the protocol. The middle layer, the Data Link Layer, includes several functions for error checking and media access control.

A feature called data link confirmation is a mechanism that provides positive confirmation of message receipt by the receiving DNP3 device. While this feature helps you recognize a failed device or failed communications link quickly, it also adds significant overhead to the DNP3 conversation. You should consider whether you require this link integrity function in your application at the expense of overall system speed and performance.

The DNP3 technical bulletin (*DNP Confirmation and Retry Guidelines 9804-002*) on confirmation processes recommends against using data link confirmations because these processes can add to traffic in situations where communications are marginal. The increased traffic will reduce connection throughput further, possibly preventing the system from operating properly.

Network Medium Contention

When more than one device requires access to a single (serial) network medium, you must provide a mechanism to resolve the resulting network medium contention. For example, unsolicited reporting results in network medium contention if you do not design your serial network as a star topology of point-to-point connections or use carrier detection on a multidrop network.

To avoid collisions among devices trying to send messages, DNP3 includes a collision avoidance feature. Before sending a message, a DNP3 device listens for a carrier signal to verify that no other node is transmitting data. The device transmits if there is no carrier or waits for a random time before transmitting. However, if two nodes both detect a lack of carrier at the same instant, these two nodes could begin simultaneous transmission of data and cause a data collision. If your serial network allows for spontaneous data transmission including unsolicited event data transmissions, you also must use application confirmation to provide a retry mechanism for messages lost due to data collisions.

DNP3 LAN/WAN Overview

NOTE: Link layer confirmations are explicitly disabled for DNP3 LAN/WAN. The IP suite provides a reliable delivery mechanism, which is backed up at the application layer by confirmations when required.

The main process for carrying DNP3 over an Ethernet Network (LAN/WAN) involves encapsulating the DNP3 data link layer data frames within the transport layer frames of the Internet Protocol (IP) suite. This allows the IP stack to deliver the DNP3 data link layer frames to the destination in place of the original DNP3 physical layer.

The DNP User Group Technical Committee has recommended the following guidelines for carrying DNP3 over a network:

- DNP3 shall use the IP suite to transport messages over a LAN/WAN
- Ethernet is the recommended physical link, though others may be used
- TCP must be used for WANs
- TCP is strongly recommended for LANs
- User Datagram Protocol (UDP) may be used for highly reliable single segment LANs
- UDP is necessary if broadcast messages are required
- The DNP3 protocol stack shall be retained in full
- Link layer confirmations shall be disabled

The Technical Committee has registered a standard port number, 20000, for DNP3 with the Internet Assigned Numbers Authority (IANA). This port is used for either TCP or UDP.

TCP/UDP Selection

The Committee recommends the selection of TCP or UDP protocol as per the guidelines in *Table D.4*.

Table D.4 TCP/UDP Selection Guidelines

| Use in the case of... | TCP | UDP |
|--|-----|-----|
| Most situations | X | |
| Non-broadcast or multicast | X | |
| Mesh Topology WAN | X | |
| Broadcast | | X |
| Multicast | | X |
| High-reliability single-segment LAN | | X |
| Pay-per-byte, non-mesh WAN, for example, Cellular Digital Packet Data (CDPD) | | X |
| Low priority data, for example, data monitor or configuration information | | X |

DNP3 in the SEL-787

The SEL-787 is a DNP3 Level 2 remote (outstation) device.

Data Access

Table D.5 lists DNP3 data access methods along with corresponding SEL-787 settings. You must select a data access method and configure each DNP3 master for polling as specified.

NOTE: Because unsolicited messaging is problematic in most circumstances, SEL recommends using the polled report-by-exception access method to maximize performance and minimize risk of configuration problems.

NOTE: In the settings below, the suffix *n* represents the DNP3 session number from 1 to 3. All settings with the same numerical suffix comprise the complete DNP3 session configuration.

Table D.5 DNP3 Access Methods

| Access Method | Master Polling | SEL-787 Settings |
|---------------------------------|---|---|
| Polled static | Class 0 | Set ECLASSB <i>n</i> , ECLASSC <i>n</i> , ECLASSA <i>n</i> to 0; UNSOL <i>n</i> to No |
| Polled report-by-exception | Class 0 occasionally, Class 1, 2, 3 frequently | Set ECLASSB <i>n</i> , ECLASSC <i>n</i> , ECLASSA <i>n</i> to the desired event class; UNSOL <i>n</i> to No |
| Unsolicited report-by-exception | Class 0 occasionally, optional Class 1, 2, 3 less frequently; mainly relies on unsolicited messages | Set ECLASSB <i>n</i> , ECLASSC <i>n</i> , ECLASSA <i>n</i> to the desired event class; set UNSOL <i>n</i> to Yes and PUNSOL <i>n</i> to Yes or No |
| Quiescent | Class 0, 1, 2, 3 never; relies completely on unsolicited messages | Set ECLASSB <i>n</i> , ECLASSC <i>n</i> , ECLASSA <i>n</i> to the desired event class; set UNSOL <i>n</i> and PUNSOL <i>n</i> to Yes. |

In both the unsolicited report-by-exception and quiescent polling methods shown in *Table D.5*, you must make a selection for the PUNSOL*n* setting. This setting enables or disables unsolicited data reporting at power up. If your DNP3 master can send a message to enable unsolicited reporting on the SEL-787, you should set PUNSOL*n* to No.

While automatic unsolicited data transmission on power up is convenient, this can cause problems if your DNP3 master is not prepared to start receiving data immediately on power up. If the master does not acknowledge the unsolicited data with an Application Confirm, the device will resend the data until it is acknowledged. On a large system, or in systems where the processing power

of the master is limited, you may have problems when several devices simultaneously begin sending data and waiting for acknowledgement messages.

The SEL-787 allows you to set the conditions for transmitting unsolicited event data on a class-by-class basis. It also allows you to assign points to event classes on a point-by-point basis (see *Configurable Data Mapping on page D.23*). You can prioritize data transmission with these event class features. For example, you might place high-priority points in event class 1 and set it with low thresholds (NUMEVEN and AGE EVEN settings) so that changes to these points will be sent to the master quickly. You may then place low priority data in event class 2 with higher thresholds.

If the SEL-787 does not receive an Application Confirm in response to unsolicited data, it will wait for ETIMEOn seconds and then repeat the unsolicited message. In order to prevent clogging of the network with unsolicited data retries, the SEL-787 uses the URETRYn and UTIMEOn settings to increase retry time when the number of retries set in URETRYn is exceeded. After URETRYn has been exceeded, the SEL-787 pauses UTIMEOn seconds and then transmits the unsolicited data again. *Figure D.1* provides an example with URETRYn = 2.

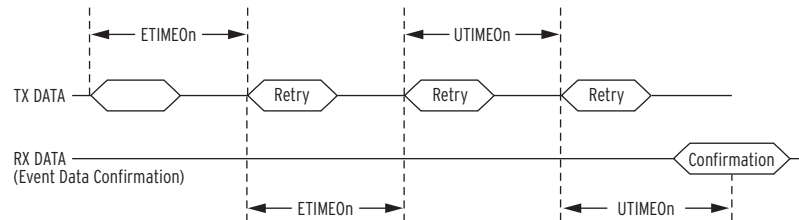


Figure D.1 Application Confirmation Timing With URETRY n = 2

Collision Avoidance

If your application uses unsolicited reporting on a serial network, you must select a half-duplex medium or a medium that includes carrier detection to avoid data collisions. EIA-485 two-wire networks are half-duplex. EIA-485 four-wire networks do not provide carrier detection, while EIA-232 systems can support carrier detection. DNP3 LAN/WAN uses features of the IP suite for collision avoidance, so does not require these settings.

The SEL-787 uses Application Confirmation messages to guarantee delivery of unsolicited event data before erasing the local event data buffer. Data collisions are typically resolved when messages are repeated until confirmed.

The SEL-787 pauses for a random delay between the settings MAXDLY and MINDLY when it detects a carrier through data on the receive line or the CTS pin. For example, if you use the settings of 0.10 seconds for MAXDLY and 0.05 seconds for MINDLY, the SEL-787 will insert a random delay of 50 to 100 ms (milliseconds) between the end of carrier detection and the start of data transmission (see *Figure D.2*).

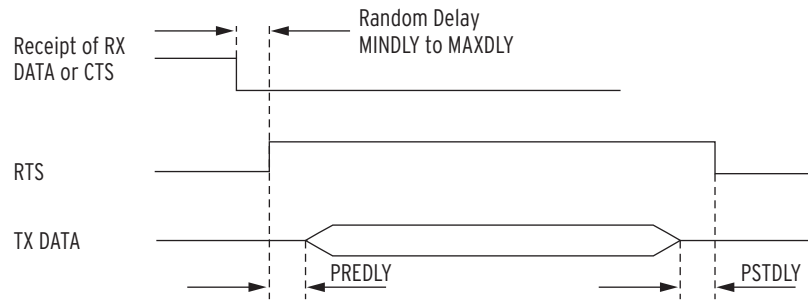


Figure D.2 Message Transmission Timing

Transmission Control

NOTE: PREDLY and POSTDLY settings are only available for EIA-232 and EIA-485 serial port sessions.

If you use a media transceiver (for example, EIA-232 to EIA-485) or a radio system for your DNP3 network, you may need to adjust data transmission properties. Use the PREDLY and POSTDLY settings to provide a delay between RTS signal control and data transmission (see *Figure D.2*). For example, an EIA-485 transceiver typically requires 10 to 20 ms to change from receive to transmit. If you set the pre-delay to 30 ms, you will avoid data loss resulting from data transmission beginning at the same time as RTS signal assertion.

Event Data

DNP3 event data objects contain change-of-state and time-stamp information that the SEL-787 collects and stores in a buffer. Points assigned in the Binary Input Map that are also assigned in the Sequential Events Recorder (SER) settings carry the time stamp of actual occurrence. Binary input points not assigned in the SER settings will carry a time stamp based on the DNP map scan time. This may be significantly delayed from when the original source changed and should not be used for sequence-of-events determination. The DNP map is scanned approximately once per second to generate events. You can configure the SEL-787 to either report the data without a polling request from the master (unsolicited data) or hold the data until the master requests it with an event poll message.

With the event class settings ECLASSB n , ECLASSC n , and ECLASSA n , you can set the event class for binary, counter, and analog inputs for session n . You can use the classes as a simple priority system for collecting event data. The SEL-787 does not treat data of different classes differently with respect to message scanning, but it does allow the master to perform independent class polls.

NOTE: Most RTUs that act as substation DNP3 masters perform an event poll that collects event data of all classes simultaneously. You must confirm that the polling configuration of your master allows independent polling for each class before implementing separate classes in the SEL-787.

For event data collection you must also consider and enter appropriate settings for dead band and scaling operation on analog points shown in *Table D.7*. You can either:

- set and use default dead band and scaling according to data type, or
- use a custom data map to select dead bands on a point-by-point basis.

See *Configurable Data Mapping on page D.23* for a discussion of how to set scaling and dead-band operation on a point-by-point basis. Dead bands for analog inputs can be modified at run-time by writing to object 34.

The settings ANADBA n , ANADBV n , and ANADBM n control default dead-band operation for each type of analog data. Because DNP3 Objects 30 and 32 use integer data, you must use scaling to send digits after the decimal point and avoid rounding to a simple integer value.

With no scaling, the value of 12.632 would be sent as 12. With a scaling setting of 1, the value transmitted is 126. With a scaling setting of 3, the value transmitted is 12632. You must make certain that the maximum value does not exceed 32767 if you are polling the default 16-bit variations for Objects 30 and 32, but you can send some decimal values using this technique. You must also configure the master to perform the appropriate division on the incoming value to display it properly.

You can set the default analog value scaling with the DECPLAN n , DECPLV n , and DECPLM n settings. Application of event reporting dead bands occurs after scaling. For example, if you set DECPLAN n to 2 and ANADBA n to 10, a measured current of 10.14 amps would be scaled to the value 1014 and would have to increase to more than 1024 or decrease to less than 1004 (a change in magnitude of ± 0.1 amps) for the device to report a new event value.

Phase angles have a default scale factor of 10, and the ANADBM dead-band setting applies to them. For the angles to generate events, the corresponding magnitude also has to exceed its dead-band setting (ANADBA).

The SEL-787 uses the NUMEVEN n and AGEEVER n settings to decide when to send unsolicited data to the master. The device sends an unsolicited report when the total number of events accumulated in the event buffer for master n reaches NUMEVEN n . The device also sends an unsolicited report if the age of the oldest event in the master n buffer exceeds AGEEVER n . The SEL-787 has the buffer capacities listed in *Table D.6*.

Table D.6 SEL-787 Event Buffer Capacity

| Type | Maximum Number of Events |
|----------|--------------------------|
| Binary | 1024 |
| Analog | 100 |
| Counters | 32 |

Binary Controls

The SEL-787 provides more than one way to control individual points. The SEL-787 maps incoming control points either to remote bits or to internal command bits that cause circuit breaker operations. *Table D.12* lists control points and control methods available in the SEL-787.

A DNP3 technical bulletin (*Control Relay Output Block Minimum Implementation 9701-002*) recommends that you use one point per Object 12, control block output device. You can use this method to perform Pulse On, Pulse Off, Latch On, and Latch Off operations on selected remote bits.

If your master does not support the single-point-per-index messages or single operation database points, you can use the trip/close operation or use the code field in the DNP3 message to specify operation of the points shown in *Control Point Operation* on page D.22.

Time Synchronization

The accuracy of DNP3 time synchronization is insufficient for most protection and oscillography needs. DNP3 time synchronization provides backup time synchronization in the event the device loses primary synchronization through the IRIG-B input. You can enable time synchronization with the TIMERQ n setting and then use Object 50, Variation 1, and Object 52, Variation 2, to set the time via the Session n DNP3 master (Object 50, variation 3 for DNP3 LAN/WAN).

By default, the SEL-787 accepts and ignores time set requests (TIMERQ n = I for “ignore”). (This mode allows the SEL-787 to use a high accuracy, IRIG time source, but still interoperate with DNP3 masters that send time

synchronization messages.) It can be set to request time synchronization periodically by setting the `TIMERQn` setting to the desired period. It can also be set to not request, but accept time synchronization (`TIMERQn = M` for “master”).

Modem Support

The SEL-787 DNP implementation includes modem support for serial ports. Your DNP3 master can dial-in to the SEL-787 and establish a DNP3 connection. The SEL-787 can automatically dial out and deliver unsolicited DNP3 event data.

When the device dials out, it waits for the “CONNECT” message from the local modem and for assertion of the device CTS line before continuing the DNP transaction. This requires a connection from the modem DCD to the device CTS line.

NOTE: Contact SEL for information on serial cable configurations and requirements for connecting your SEL-787 to other devices.

You can either connect the modem to a computer and configure it before connecting it to the SEL-787, or program the appropriate modem setup string in the modem startup string setting `MSTR`. You should use the `PH_NUM1` and (optional) `PH_NUM2` settings to set the phone numbers that you want the SEL-787 to call. The SEL-787 will automatically send the ATDT modem dial command and then the contents of the `PH_NUM1` setting when dialing the modem. If `PH_NUM2` is set, the `RETRY1` setting is used to configure the number of times the SEL-787 tries to dial `PH_NUM1` before dialing `PH_NUM2`. Similarly, the `RETRY2` setting is the number of attempts the SEL-787 tries to dial `PH_NUM2` before trying `PH_NUM1`. `MDTIME` sets the length of time from initiating the call to declaring it failed because of no connection, and `MDRET` sets the time between dial-out attempts.

NOTE: RTS/CTS hardware flow control is not available for a DNP3 modem connection. You must use either X-ON/X-OFF software flow control or set the port data speed slower than the effective data rate of the modem.

The settings `PH_NUM1` and `PH_NUM2` must conform to the AT modem command set dialing string standard, including:

- A comma (,) inserts a four second pause
- If necessary, use a 9 to reach an outside line
- Include a 1 and the area code if the number requires long distance access
- Add any special codes your telephone service provider designates to block call waiting and other telephone line features.

DNP3 Settings

The DNP3 port configuration settings available on the SEL-787 are shown in *Table D.7*. You can enable DNP3 on Ethernet Port 1 or on any of the serial Ports 2 through 4, to a maximum of three concurrent DNP3 sessions. Each session defines the characteristics of the connected DNP3 Master, to which you assign one of the three available custom maps.

Because some settings apply only to serial DNP3, they are visible only when configuring a serial port. Likewise, settings that apply only to DNP3 LAN/WAN are visible only during Ethernet port configuration.

For example, you only have the ability to define multiple sessions on Port 1, the Ethernet port. The IP address for each session must be unique. Setting the IP address to 0.0.0.0 allows any master IP address to connect to the session, as long as that IP address is not configured for another DNP3 session. Only one connection is supported on the session at a time.

Extreme care should be observed to ensure network security, especially when setting the IP address to 0.0.0.0, as there is no limitation on the DNP3 master that may connect to the session.

Table D.7 Port DNP3 Protocol Settings (Sheet 1 of 2)

| Name | Description | Range | Default |
|---------------------------|---|---------------|---------|
| EDNP ^a | Enable DNP3 Sessions | 0–3 | 0 |
| DNPNUM ^a | DNP3 TCP and UDP Port | 1–65534 | 20000 |
| DNPADR | Device DNP3 address | 0–65534 | 0 |
| Session 1 Settings | | | |
| DNPIP1 ^a | IP address (zzz.yyy.xxx.www) | 15 characters | "" |
| DNPTR1 ^{a b} | Transport protocol | UDP, TCP | TCP |
| DNPUDP1 ^a | UDP response port | REQ, 1–65534 | 20000 |
| REPADR1 | DNP3 address of the Master to send messages to | 0–65519 | 1 |
| DNPMAPI | DNP3 Session Custom Map | 1–3 | 1 |
| DVARAI1 | Analog Input Default Variation | 1–6 | 4 |
| ECLASSB1 | Class for binary event data, 0 disables | 0–3 | 1 |
| ECLASSC1 | Class for counter event data, 0 disables | 0–3 | 0 |
| ECLASSA1 | Class for analog event data, 0 disables | 0–3 | 2 |
| DECPLA1 | Decimal places scaling for Current data | 0–3 | 1 |
| DECPLV1 | Decimal places scaling for Voltage data | 0–3 | 1 |
| DECPLM1 | Decimal places scaling for Miscellaneous data | 0–3 | 1 |
| ANADBA1 | Analog reporting dead band for current; hidden if ECLASSA1 set to 0 | 0–32767 | 100 |
| ANADBV1 | Analog reporting dead band for voltages; hidden if ECLASSA1 set to 0 | 0–32767 | 100 |
| ANADBM1 | Analog reporting dead band for miscellaneous analogs; hidden if ECLASSA and ECLASSC set to 0 | 0–32767 | 100 |
| TIMERQ1 | Time-set request interval, minutes (M = Disables time sync requests, but still accepts and applies time syncs from Master; I = Ignores (does not apply) time syncs from Master) | I, M, 1–32767 | I |
| STIMEO1 | Select/operate time-out, seconds | 0.0–30.0 | 1.0 |
| DNPINA1 ^a | Send Data Link Heartbeat, seconds; hidden if DNPTR1 set to UDP | 0.0–7200 | 120 |
| DRETRY1 ^c | Data link retries | 0–15 | 3 |
| DTIMEO1 ^c | Data link time-out, seconds; hidden if DRETRY1 set to 0 | 0.0–5.0 | 1 |
| ETIMEO1 | Event message confirm time-out, seconds | 1–50 | 5 |
| UNSOL1 | Enable unsolicited reporting; hidden and set to N if ECLASSB1, ECLASSC1, and ECLASSA1 set to 0 | Y, N | N |
| PUNSOL1 | Enable unsolicited reporting at power up; hidden and set to N if UNSOL1 set to N | Y, N | N |
| NUMEVE1 ^d | Number of events to transmit on | 1–200 | 10 |
| AGEEVE1 ^d | Oldest event to transmit on, seconds | 0.0–99999.0 | 2.0 |
| URETRY1 ^d | Unsolicited messages maximum retry attempts | 2–10 | 3 |
| UTIMEO1 ^d | Unsolicited messages offline timeout, seconds | 1–5000 | 60 |
| Session 2 Settings | | | |
| DNPIP2 ^a | IP address (zzz.yyy.xxx.www) | 15 characters | "" |
| DNPTR2 ^a | Transport protocol | UDP, TCP | TCP |
| • | | | |
| • | | | |
| • | | | |
| URETRY2 ^{a,d} | Unsolicited messages maximum retry attempts | 2–10 | 3 |
| UTIMEO2 ^{a,d} | Unsolicited messages offline timeout, seconds | 1–5000 | 60 |

Table D.7 Port DNP3 Protocol Settings (Sheet 2 of 2)

| Name | Description | Range | Default |
|-----------------------------|---|-----------------|---------|
| Session 3 Settings | | | |
| DNPIP3 ^a | IP address (zzz.yyy.xxx.www) | 15 characters | "" |
| DNPTR3 ^a | Transport protocol | UDP, TCP | TCP |
| • | | | |
| • | | | |
| • | | | |
| URETRY3 ^{a,d} | Unsolicited messages maximum retry attempts | 2–10 | 3 |
| UTIMEO3 ^{a,d} | Unsolicited messages offline timeout, seconds | 1–5000 | 60 |
| Serial Port Settings | | | |
| MINDLY ^c | Minimum delay from DCD to TX, seconds | 0.00–1.00 | 0.05 |
| MAXDLY ^c | Maximum delay from DCD to TX, seconds | 0.00–1.00 | 0.10 |
| PREDLY ^c | Settle time from RTS on to TX; Off disables PSTDLY | OFF, 0.00–30.00 | 0.00 |
| PSTDLY ^c | Settle time from TX to RTS off; hidden if PREDLY set to Off | 0.00–30.00 | 0.00 |

^a Available only on Ethernet ports. The DNP IP address of each session (DNPIP1, DNPIP2, etc.) must be unique. Set DNPIPn := 0.0.0.0 to accept connections from any DNP master.

^b If DNPIPn is 0.0.0.0, DNPTRn must be set to TCP.

^c Available only on serial ports.

^d Hidden if UNSOLn set to N.

The modem settings in *Table D.8* are only available for DNP3 serial port sessions.

Table D.8 Serial Port DNP3 Modem Settings

| Name | Description | Range | Default |
|---------|---|--------------------------|-----------------|
| MODEM | Modem connected to port; all following settings are hidden if MODEM set to N | Y, N | N |
| MSTR | Modem startup string | As many as 30 characters | "E0X0&D0S0 = 4" |
| PH_NUM1 | Primary phone number for dial-out | As many as 30 characters | "" |
| PH_NUM2 | Secondary phone number for dial-out | As many as 30 characters | "" |
| RETRY1 | Retry attempts for primary dial-out; hidden and unused if PH_NUM2 set to "" | 1–20 | 5 |
| RETRY2 | Retry attempts for secondary dial-out; hidden and unused if PH_NUM2 set to "" | 1–20 | 5 |
| MDTIME | Time from initiating call to failure due to no connection, seconds | 5–300 | 60 |
| MDRET | Time between dial-out attempts | 5–3600 | 120 |

DNP3 Documentation

Object List

Table D.9 lists the objects and variations with supported function codes and qualifier codes available in the SEL-787. The list of objects conforms to the format laid out in the DNP specifications and includes supported objects for DNP3 implementation Level 2 and above and nonsupported objects for DNP3 implementation Level 2 only. Those that are supported include the function and qualifier codes. The objects that are not supported are shown without any corresponding function and qualifier codes.

Table D.9 SEL-787 DNP Object List (Sheet 1 of 5)

| Obj. | Var. | Description | Request ^a | | Response ^b | |
|------|------|--|---------------------------|--------------------------|---------------------------|--------------------------|
| | | | Funct. Codes ^c | Qual. Codes ^d | Funct. Codes ^c | Qual. Codes ^d |
| 0 | 211 | Device Attributes—User-specific sets of attributes | 1 | 0 | 129 | 0,17 |
| 0 | 212 | Device Attributes—Master data set prototypes | 1 | 0 | 129 | 0,17 |
| 0 | 213 | Device Attributes—Outstation data set prototypes | 1 | 0 | 129 | 0,17 |
| 0 | 214 | Device Attributes—Master data sets | 1 | 0 | 129 | 0,17 |
| 0 | 215 | Device Attributes—Outstation data sets | 1 | 0 | 129 | 0,17 |
| 0 | 216 | Device Attributes—Max binary outputs per request | 1 | 0 | 129 | 0,17 |
| 0 | 219 | Device Attributes—Support for analog output events | 1 | 0 | 129 | 0,17 |
| 0 | 220 | Device Attributes—Max analog output index | 1 | 0 | 129 | 0,17 |
| 0 | 221 | Device Attributes—Number of analog outputs | 1 | 0 | 129 | 0,17 |
| 0 | 222 | Device Attributes—Support for binary output events | 1 | 0 | 129 | 0,17 |
| 0 | 223 | Device Attributes—Max binary output index | 1 | 0 | 129 | 0,17 |
| 0 | 224 | Device Attributes—Number of binary outputs | 1 | 0 | 129 | 0,17 |
| 0 | 225 | Device Attributes—Support for frozen counter events | 1 | 0 | 129 | 0,17 |
| 0 | 226 | Device Attributes—Support for frozen counters | 1 | 0 | 129 | 0,17 |
| 0 | 227 | Device Attributes—Support for counter events | 1 | 0 | 129 | 0,17 |
| 0 | 228 | Device Attributes—Max counter index | 1 | 0 | 129 | 0,17 |
| 0 | 229 | Device Attributes—Number of counters | 1 | 0 | 129 | 0,17 |
| 0 | 230 | Device Attributes—Support for frozen analog inputs | 1 | 0 | 129 | 0,17 |
| 0 | 231 | Device Attributes—Support for analog input events | 1 | 0 | 129 | 0,17 |
| 0 | 232 | Device Attributes—Max analog input index | 1 | 0 | 129 | 0,17 |
| 0 | 233 | Device Attributes—Number of analog inputs | 1 | 0 | 129 | 0,17 |
| 0 | 234 | Device Attributes—Support for double-bit events | 1 | 0 | 129 | 0,17 |
| 0 | 235 | Device Attributes—Max double-bit binary index | 1 | 0 | 129 | 0,17 |
| 0 | 236 | Device Attributes—Number of double-bit binaries | 1 | 0 | 129 | 0,17 |
| 0 | 237 | Device Attributes—Support for binary input events | 1 | 0 | 129 | 0,17 |
| 0 | 238 | Device Attributes—Max binary input index | 1 | 0 | 129 | 0,17 |
| 0 | 239 | Device Attributes—Number of binary inputs | 1 | 0 | 129 | 0,17 |
| 0 | 240 | Device Attributes—Max transmit fragment size | 1 | 0 | 129 | 0,17 |
| 0 | 241 | Device Attributes—Max receive fragment size | 1 | 0 | 129 | 0,17 |
| 0 | 242 | Device Attributes—Device manufacturer's software version | 1 | 0 | 129 | 0,17 |

Table D.9 SEL-787 DNP Object List (Sheet 2 of 5)

| Obj. | Var. | Description | Request ^a | | Response ^b | |
|------|----------------|--|---------------------------|--------------------------|---------------------------|--------------------------|
| | | | Funct. Codes ^c | Qual. Codes ^d | Funct. Codes ^c | Qual. Codes ^d |
| 0 | 243 | Device Attributes—Device manufacturer's hardware version | 1 | 0 | 129 | 0,17 |
| 0 | 245 | Device Attributes—User-assigned location name | 1 | 0 | 129 | 0,17 |
| 0 | 246 | Device Attributes—User assigned ID code/number | 1 | 0 | 129 | 0,17 |
| 0 | 247 | Device Attributes—User assigned ID code/number | 1 | 0 | 129 | 0,17 |
| 0 | 248 | Device Attributes—Device serial number | 1 | 0 | 129 | 0,17 |
| 0 | 249 | Device Attributes—DNP subset and conformance | 1 | 0 | 129 | 0,17 |
| 0 | 250 | Device Attributes—Device manufacturer's product name and model | 1 | 0 | 129 | 0,17 |
| 0 | 252 | Device Attributes—Device manufacturer's name | 1 | 0 | 129 | 0,17 |
| 0 | 254 | Device Attributes—Non-specific all attributes request | 1 | 0 | 129 | 0,17 |
| 0 | 255 | Device Attributes—List of attribute variations | 1 | 0 | 129 | 0,17 |
| 1 | 0 | Binary Input—All Variations | 1 | 0, 1, 6, 7, 8, 17, 28 | | |
| 1 | 1 | Binary Input | 1 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 1 | 2 ^e | Binary Input With Status | 1 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 2 | 0 | Binary Input Change—All Variations | 1 | 6, 7, 8 | | |
| 2 | 1 | Binary Input Change Without Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 2 | 2 ^e | Binary Input Change With Time | 1 | 6, 7, 8 | 129, 130 | 17, 28 |
| 2 | 3 | Binary Input Change With Relative Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 10 | 0 | Binary Output—All Variations | 1 | 0, 1, 6, 7, 8 | | |
| 10 | 1 | Binary Output | | | | |
| 10 | 2 ^e | Binary Output Status | 1 | 0, 1, 6, 7, 8 | 129 | 0, 1 |
| 12 | 0 | Control Block—All Variations | | | | |
| 12 | 1 | Control Relay Output Block | 3, 4, 5, 6 | 17, 28 | 129 | echo of request |
| 12 | 2 | Pattern Control Block | 3, 4, 5, 6 | 7 | 129 | echo of request |
| 12 | 3 | Pattern Mask | 3, 4, 5, 6 | 0, 1 | 129 | echo of request |
| 20 | 0 | Binary Counter—All Variations | 1, 7, 8, 9, 10 | 0, 1, 6, 7, 8, 17, 28 | | |
| 20 | 1 | 32-Bit Binary Counter | 1, 7, 8, 9, 10 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 20 | 2 | 16-Bit Binary Counter | 1, 7, 8, 9, 10 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 20 | 3 | 32-Bit Delta Counter | | | | |
| 20 | 4 | 16-Bit Delta Counter | | | | |
| 20 | 5 | 32-Bit Binary Counter Without Flag | 1, 7, 8, 9, 10 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 20 | 6 ^e | 16-Bit Binary Counter Without Flag | 1, 7, 8, 9, 10 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 20 | 7 | 32-Bit Delta Counter Without Flag | | | | |
| 20 | 8 | 16-Bit Delta Counter Without Flag | | | | |
| 21 | 0 | Frozen Counter—All Variations | | | | |
| 21 | 1 | 32-Bit Frozen Counter | | | | |
| 21 | 2 | 16-Bit Frozen Counter | | | | |
| 21 | 3 | 32-Bit Frozen Delta Counter | | | | |
| 21 | 4 | 16-Bit Frozen Delta Counter | | | | |

Table D.9 SEL-787 DNP Object List (Sheet 3 of 5)

| Obj. | Var. | Description | Request ^a | | Response ^b | |
|-----------------|----------------|---|---------------------------|--------------------------|---------------------------|--------------------------|
| | | | Funct. Codes ^c | Qual. Codes ^d | Funct. Codes ^c | Qual. Codes ^d |
| 21 | 5 | 32-Bit Frozen Counter With Time of Freeze | | | | |
| 21 | 6 | 16-Bit Frozen Counter With Time of Freeze | | | | |
| 21 | 7 | 32-Bit Frozen Delta Counter With Time of Freeze | | | | |
| 21 | 8 | 16-Bit Frozen Delta Counter With Time of Freeze | | | | |
| 21 | 9 | 32-Bit Frozen Counter Without Flag | | | | |
| 21 | 10 | 16-Bit Frozen Counter Without Flag | | | | |
| 21 | 11 | 32-Bit Frozen Delta Counter Without Flag | | | | |
| 21 | 12 | 16-Bit Frozen Delta Counter Without Flag | | | | |
| 22 | 0 | Counter Change Event—All Variations | 1 | 6, 7, 8 | | |
| 22 | 1 | 32-Bit Counter Change Event Without Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 22 | 2 ^e | 16-Bit Counter Change Event Without Time | 1 | 6, 7, 8 | 129, 130 | 17, 28 |
| 22 | 3 | 32-Bit Delta Counter Change Event Without Time | | | | |
| 22 | 4 | 16-Bit Delta Counter Change Event Without Time | | | | |
| 22 | 5 | 32-Bit Counter Change Event With Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 22 | 6 | 16-Bit Counter Change Event With Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 22 | 7 | 32-Bit Delta Counter Change Event With Time | | | | |
| 22 | 8 | 16-Bit Delta Counter Change Event With Time | | | | |
| 23 | 0 | Frozen Counter Event—All Variations | | | | |
| 23 | 1 | 32-Bit Frozen Counter Event Without Time | | | | |
| 23 | 2 | 16-Bit Frozen Counter Event Without Time | | | | |
| 23 | 3 | 32-Bit Frozen Delta Counter Event Without Time | | | | |
| 23 | 4 | 16-Bit Frozen Delta Counter Event Without Time | | | | |
| 23 | 5 | 32-Bit Frozen Counter Event With Time | | | | |
| 23 | 6 | 16-Bit Frozen Counter Event With Time | | | | |
| 23 | 7 | 32-Bit Delta Counter Change Event With Time | | | | |
| 23 | 8 | 16-Bit Delta Counter Change Event With Time | | | | |
| 30 ^f | 0 | Analog Input—All Variations | 1 | 0, 1, 6, 7, 8, 17, 28 | | |
| 30 ^f | 1 | 32-Bit Analog Input | 1 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 30 ^f | 2 | 16-Bit Analog Input | 1 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 30 ^f | 3 | 32-Bit Analog Input Without Flag | 1 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 30 ^f | 4 | 16-Bit Analog Input Without Flag | 1 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 30 ^f | 5 | Short Floating Point Analog Input | 1 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 30 | 6 | Long Floating Point Analog Input | 1 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 31 | 0 | Frozen Analog Input—All Variations | | | | |
| 31 | 1 | 32-Bit Frozen Analog Input | | | | |
| 31 | 2 | 16-Bit Frozen Analog Input | | | | |
| 31 | 3 | 32-Bit Frozen Analog Input With Time of Freeze | | | | |
| 31 | 4 | 16-Bit Frozen Analog Input With Time of Freeze | | | | |
| 31 | 5 | 32-Bit Frozen Analog Input Without Flag | | | | |
| 31 | 6 | 16-Bit Frozen Analog Input Without Flag | | | | |

Table D.9 SEL-787 DNP Object List (Sheet 4 of 5)

| Obj. | Var. | Description | Request ^a | | Response ^b | |
|-----------------|----------------|--|---------------------------|--------------------------|---------------------------|--------------------------|
| | | | Funct. Codes ^c | Qual. Codes ^d | Funct. Codes ^c | Qual. Codes ^d |
| 31 | 7 | Short Floating Point Frozen Analog Input | | | | |
| 31 | 8 | Long Floating Point Frozen Analog Input | | | | |
| 32 | 0 | Analog Change Event—All Variations | 1 | 6, 7, 8 | | |
| 32 ^f | 1 | 32-Bit Analog Change Event Without Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 32 ^f | 2 | 16-Bit Analog Change Event Without Time | 1 | 6, 7, 8 | 129, 130 | 17, 28 |
| 32 ^f | 3 | 32-Bit Analog Change Event With Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 32 ^f | 4 | 16-Bit Analog Change Event With Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 32 ^f | 5 | Short Floating Point Analog Change Event | 1 | 6, 7, 8 | 129 | 17, 28 |
| 32 ^f | 6 | Long Floating Point Analog Change Event | 1 | 6, 7, 8 | 129 | 17, 28 |
| 32 ^f | 7 | Short Floating Point Analog Change Event With Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 32 ^f | 8 | Long Floating Point Analog Change Event With Time | 1 | 6, 7, 8 | 129 | 17, 28 |
| 33 | 0 | Frozen Analog Event—All Variations | | | | |
| 33 | 1 | 32-Bit Frozen Analog Event Without Time | | | | |
| 33 | 2 | 16-Bit Frozen Analog Event Without Time | | | | |
| 33 | 3 | 32-Bit Frozen Analog Event With Time | | | | |
| 33 | 4 | 16-Bit Frozen Analog Event With Time | | | | |
| 33 | 5 | Short Floating Point Frozen Analog Event | | | | |
| 33 | 6 | Long Floating Point Frozen Analog Event | | | | |
| 33 | 7 | Short Floating Point Frozen Analog Event With Time | | | | |
| 33 | 8 | Long Floating Point Frozen Analog Event With Time | | | | |
| 34 | 0 | Analog Dead Band—All Variations | | | | |
| 34 | 1 ^e | 16-Bit Analog Input Reporting Dead-band Object | 1, 2 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 34 | 2 | 32-Bit Analog Input Reporting Dead-band Object | 1, 2 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 34 | 3 | Floating Point Analog Input Reporting Dead-band Object | 1, 2 | 0, 1, 6, 7, 8, 17, 28 | 129 | 0, 1, 17, 28 |
| 40 | 0 | Analog Output Status—All Variations | 1 | 0, 1, 6, 7, 8 | 129 | |
| 40 | 1 | 32-Bit Analog Output Status | 1 | 0, 1, 6, 7, 8 | 129 | 0, 1, 17, 28 |
| 40 | 2 ^e | 16-Bit Analog Output Status | 1 | 0, 1, 6, 7, 8 | 129 | 0, 1, 17, 28 |
| 40 | 3 | Short Floating Point Analog Output Status | 1 | 0, 1, 6, 7, 8 | 129 | 0, 1, 17, 28 |
| 40 | 4 | Long Floating Point Analog Output Status | 1 | 0, 1, 6, 7, 8 | 129 | 0, 1, 17, 28 |
| 41 | 0 | Analog Output Block—All Variations | | | | |
| 41 | 1 | 32-Bit Analog Output Block | 3, 4, 5, 6 | 17, 28 | 129 | echo of request |
| 41 | 2 ^e | 16-Bit Analog Output Block | 3, 4, 5, 6 | 17, 28 | 129 | echo of request |
| 41 | 3 | Short Floating Point Analog Output Block | 3, 4, 5, 6 | 17, 28 | 129 | echo of request |
| 50 | 0 | Time and Date—All Variations | | | | |
| 50 | 1 | Time and Date | 1, 2 | 7, 8 index=0 | 129 | 07, quantity=1 |
| 50 | 2 | Time and Date With Interval | | | | |
| 50 | 3 | Time and Date Last Recorded | 2 | 7 quantity = 1 | 129 | |
| 51 | 0 | Time and Date CTO—All Variations | | | | |
| 51 | 1 | Time and Date CTO | | | | |
| 51 | 2 | Unsynchronized Time and Date CTO | | | 129 | 07, quantity=1 |

Table D.9 SEL-787 DNP Object List (Sheet 5 of 5)

| Obj. | Var. | Description | Request ^a | | Response ^b | |
|------|------|--|---------------------------|--------------------------|---------------------------|--------------------------|
| | | | Funct. Codes ^c | Qual. Codes ^d | Funct. Codes ^c | Qual. Codes ^d |
| 52 | 0 | Time Delay—All Variations | | | | |
| 52 | 1 | Time Delay, Coarse | | | | |
| 52 | 2 | Time Delay, Fine | | | 129 | 7, quantity=1 |
| 60 | 0 | All Classes of Data | 1, 20, 21 | 6, 7, 8 | | |
| 60 | 1 | Class 0 Data | 1, 20, 21 | 6, 7, 8 | | |
| 60 | 2 | Class 1 Data | 1 | 6, 7, 8 | | |
| 60 | 3 | Class 2 Data | 1, 20, 21 | 6, 7, 8 | | |
| 60 | 4 | Class 3 Data | 1, 20, 21 | 6, 7, 8 | | |
| 70 | 1 | File Identifier | | | | |
| 70 | 2 | Authentication Object | | | | |
| 70 | 3 | File Command Object | | | | |
| 70 | 4 | File Command Status Object | | | | |
| 70 | 5 | File Transport Object | | | | |
| 70 | 6 | File Transport Status Object | | | | |
| 70 | 7 | File Descriptor Object | | | | |
| 80 | 1 | Internal Indications | 2 | 0, 1 index=7 | | |
| 81 | 1 | Storage Object | | | | |
| 82 | 1 | Device Profile | | | | |
| 83 | 1 | Private Registration Object | | | | |
| 83 | 2 | Private Registration Object Descriptor | | | | |
| 90 | 1 | Application Identifier | | | | |
| 100 | 1 | Short Floating Point | | | | |
| 100 | 2 | Long Floating Point | | | | |
| 100 | 3 | Extended Floating Point | | | | |
| 101 | 1 | Small Packed Binary-Coded Decimal | | | | |
| 101 | 2 | Medium Packed Binary-Coded Decimal | | | | |
| 101 | 3 | Large Packed Binary-Coded Decimal | | | | |
| 110 | all | Octet String | | | | |
| 111 | all | Octet String Event | | | | |
| 112 | All | Virtual Terminal Output Block | | | | |
| 113 | All | Virtual Terminal Event Data | | | | |
| N/A | | No object required for the following function codes: 13 cold start 14 warm start 23 delay measurement | 13, 14, 23 | | | |

^a Supported in requests from master.^b May generate in response to master.^c Decimal.^d Hexadecimal.^e Default variation.^f Default variation specified by serial port setting DVARAI (or DVARAI_n for Ethernet session n [n = 1, 2, or 3]).

Device Profile

The DNP3 Device Profile document, available on the supplied CD or as a download from the SEL website, contains the standard device profile information for the SEL-787. This information is also available in XML format. Please refer to this document for complete information on DNP3 Protocol support in the SEL-787.

Reference Data Map

NOTE: Dead-band changes via Object 34 are not stored in nonvolatile memory. Make sure to reissue the Object 34 dead bands after a warm (STA C) or cold start (power cycle).

NOTE: Although the reference maps do not include Relay Word bit labels, you can use these labels in creating custom maps.

Table D.10 shows the SEL-787 reference data map. The reference map shows the data available to a DNP3 master. You can use the default map or the custom DNP3 mapping functions of the SEL-787 to retrieve only the points required by your application.

The SEL-787 scales analog values by the indicated settings or fixed scaling indicated in the description. Analog dead bands for event reporting use the indicated settings, or ANADBM if you have not specified a setting.

Table D.10 DNP3 Reference Data Map (Sheet 1 of 2)

| Object | Labels | Description |
|-----------------------|-------------------------------|--|
| Binary Inputs | | |
| 01, 02 | STFAIL | Relay Diagnostic Failure |
| | STWARN | Relay Diagnostic Warning |
| | STSET | Relay Settings Change or Relay Restart |
| | Enabled-T06_LED ^a | Relay Word Elements Target Row 0 (see Table J.1) |
| | 50P11T-TUTCH ^a | Relay Word Elements (see Table J.1) |
| | PFL | Power Factor Leading for Three-Phase Currents |
| | 0 | Logical 0 |
| | 1 | Logical 1 |
| Binary Outputs | | |
| 10, 12 | RB01–RB32 | Remote bits RB01–RB32 |
| 10, 12 | RB01:RB02 | Remote bit pairs RB01–RB32 |
| | RB03:RB04 | |
| | RB05:RB06 | |
| | ... | |
| | RB29:RB30 | |
| 10, 12 | RB31:RB32 | |
| | | |
| 10, 12 | OC1 | Pulse Open Circuit Breaker 1 command |
| 10, 12 | CC1 | Pulse Close Circuit Breaker 1 command |
| 10, 12 | OC1:CC1 | Open/Close pair for Circuit Breaker 1 |
| 10, 12 | OC2 | Pulse Open Circuit Breaker 2 command |
| 10, 12 | CC2 | Pulse Close Circuit Breaker 2 command |
| 10, 12 | OC2:CC2 | Open/Close pair for Circuit Breaker 2 |
| Counters | | |
| 20, 22 | SCxx | SELOGIC Counter Values (xx = 01–32) |
| | GROUP | Active Settings Group |
| Analog Inputs | | |
| 30, 32, 34 | IAW1_MAG–SC32 ^{b, c} | Analog Quantities from Table K.1 with an “x” in the DNP column |
| | 0 | Numeric 0 |
| | 1 | Numeric 1 |

Table D.10 DNP3 Reference Data Map (Sheet 2 of 2)

| Object | Labels | Description |
|----------------|--------|------------------------|
| Analog Outputs | | |
| 40, 41 | GROUP | Active Settings Group |
| | NOOP | No operation, no error |

^a Valid Relay Word bits depend on the relay model.^b Valid analog inputs depend on the relay model.^c Refer to *Default Analog Inputs* for default analog input scaling and dead bands.

Default Data Map

The default data map is an automatically generated subset of the reference map. All data maps are initialized to the default values, based on the SEL-787 part number. *Table D.11* shows the SEL-787 default data map. If the default maps are not appropriate, you can also use the custom DNP mapping commands **SET DNN** and **SHOW DNN** to create the map required for your application.

Table D.11 DNP3 Default Data Map

| Object | Default Index | Point Label |
|------------|---------------|---|
| 01, 02 | 0 | ENABLED |
| | 1 | TRIPXFMR |
| | 2 | TRIP1 |
| | 3 | TRIP2 |
| | 4 | STFAIL |
| | 5 | STSET |
| | 6 | IN101 |
| | 7 | IN102 |
| | 8–99 | A portion of these binary inputs can have default values as described in <i>Default Binary Inputs on page D.20</i> . Outside that scope, they contain the value NA. |
| 10, 12 | 0–31 | RB01–RB32 Remote Bits |
| 20, 22 | 0–31 | NA |
| 30, 32, 34 | 0 | IAW1_MAG |
| | 1 | IBW1_MAG |
| | 2 | ICW1_MAG |
| | 3 | IGW1_MAG |
| | 4 | IAW2_MAG |
| | 5 | IBW2_MAG |
| | 6 | ICW2_MAG |
| | 7 | IGW2_MAG |
| | 8 | IAVW1MAG |
| | 9 | IAVW2MAG |
| | 10 | 3I2W1MAG |
| | 11 | 3I2W1MAG |
| | 12–99 | A portion of these analog inputs can have default values as described in <i>Default Analog Inputs on page D.20</i> . Outside that scope, they contain the value NA. |
| 40, 41 | 0–31 | NA |

Default Binary Inputs

The SEL-787 dynamically creates the default Binary Input map after you issue an **R_S** command. The SEL-787 uses the Part Number to determine the presence of Digital Input cards in slots 3, 4, and 5. If present, each digital input point label, INx0y (where *x* is the slot number and *y* is the point), is added to the default map in numerical order.

Default Analog Inputs

NOTE: Dead-band changes via Object 34 are stored in nonvolatile memory. Make sure to reissue the Object 34 dead bands after a warm (HIS C) or cold start (power cycle).

The SEL-787 dynamically creates the default Analog Input map after you issue an **R_S** command. The SEL-787 first checks for a voltage option in the part number, and if voltages are present, adds IN_MAG, VAB_MAG, VBC_MAG, VCA_MAG, VAVE_MAG, 3V2_MAG, P, Q, S, and PF to the default DNP map. The SEL-787 then uses the Part Number to determine the presence of Analog Input cards in slots 3, 4, and 5. If present, the SEL-787 adds each analog input point label, ALx0y (where *x* is the slot and *y* is the point number), to the default map in numerical order to the DNP map.

Device Attributes (Object 0)

Table D.10 includes the supported Object 0 Device Attributes and variations. In response to Object 0 requests, the SEL-787 will send attributes that apply to that particular DNP3 session. Because the SEL-787 supports custom DNP3 maps, these values will likely be different for each session. The SEL-787 uses its internal settings for the following variations:

- Variation 242—FID string
- Variation 243—Part Number
- Variation 245—TID setting
- Variation 246—RID setting
- Variation 247—RID setting
- Variation 248—Serial Number

Variation 249 shall contain the DNP subset and conformance, “2:2009”.
Variation 250 shall contain the product model, “SEL-787” and variation 252 shall contain “SEL”.

Binary Inputs

Binary Inputs (Objects 1 & 2) are supported as defined by *Table D.11*. The default variation for both static and event inputs is 2. Only the Read function code (1) is allowed with these objects. All variations are supported. Object 2, Variation 3 will be responded to, but will contain no data.

Binary Inputs are scanned approximately once per second to generate events. When time is reported with these event objects, it is the time at which the scanner observed the bit change. This can be significantly delayed from the time when the original source change occurred and should not be used for sequence-of-events determination. Binary inputs registered with SER are derived from the SER and carry the time stamp of actual occurrence. Some additional binary inputs are available only to DNP. For example, STWARN and STFAIL are derived from the diagnostic task data. Another binary input, STSET, is derived from the SER and carries the time stamp of actual occurrence. Static reads of this input will always show 0.

Binary Outputs

Binary Output status (Object 10, Variation 2) is supported. Static reads of points RB1–RB32, OC/CC respond with the on-line bit set and the state of the requested bit. Reads from control-only binary output points respond with the on-line bit set and a state of 0. The SEL-751 supports Control Relay Output Block objects (Object 12, Variation 1). The control relays correspond to the remote bits and other functions as shown previously. Each DNP3 Control message contains a Trip/Close code (TRIP, CLOSE, or NUL) and an Operation type (PULSE ON, LATCH ON, LATCH OFF, or NUL). The Trip/Close code works with the Operation Type to produce set, clear, and pulse operations.

Control operations differ slightly for single-point controls compared to paired outputs. Paired outputs correspond to the complementary two-output model, and single-point controls follow the complementary latch or activation model. In the complementary two-output model, paired points only support Trip or Close operations, which, when issued, will Pulse On the first or second point in the pair, respectively. Latch commands and Pulse operations without a Trip code are not supported. You can cancel an operation in progress by issuing a NUL Trip/Close Code with a NUL Operation Type. Single output points support both Pulse and Latch operations. See *Control Point Operation* for details on control operations.

Use of the Status field is exactly as defined. All other fields are ignored. A pulse operation is asserted for a single processing interval. You should exercise caution if sending multiple remote bit pulses in a single message (i.e., point count > 1), because this can result in some of the pulse commands being ignored and the return of an already active status message. The SEL-787 will only honor the first ten points in an Object 12, Variation 1 request. Any additional points in the request will return the DNP3 status code TOO_MANY_OBJS.

The SEL-787 also supports Pattern Control Blocks (Object 12, Variations 2 and 3) to control multiple binary output points. Variation 2 defines the control type (Trip/Close, Set/Clear, or Pulse) and the range of points to operate. Variation 3 provides a pattern mask that indicates which points in that range should be operated. Object 12, Variations 2 and 3 define the entire control command: the DNP3 master must send both for a successful control. For example, the DNP3 master sends an Object 12, Variation 2 message to request a Trip of the range of indices 0–7. The DNP3 master then sends an Object 12, Variation 3 message with a hexadecimal value of “BB” as the pattern mask (converted to binary notation: 10111011). Read right to left in increasing bit order, the Pattern Block Control command will result in a Trip of indexes 0, 1, 3 to 5, and 7. Multiple binary output point control operations are not guaranteed to occur during the same processing interval.

Control Point Operation

Use the Trip and Close, Latch On/Off and Pulse On operations with Object 12 control relay output block command messages to operate the points shown in *Table D.12*. Pulse operations provide a pulse with duration of one protection processing interval.

Table D.12 SEL-787 Object 12 Control Operations

| Label | Close/Pulse On | Trip/Pulse On | Nul/Latch On | Nul/Latch Off | Nul/Pulse On |
|-----------|--|--|--|-------------------------------|--|
| RB01–RB32 | Pulse Remote Bit RB01–RB32 | Pulse Remote Bit RB01–RB32 | Set Remote Bit RB01–RB32 | Clear Remote Bit RB01–RB32 | Pulse Remote Bit RB01–RB32 |
| RBxx:RByy | Pulse RByy RB01–RB32 | Pulse RBxx RB01–RB32 | Not Supported | Not Supported | Not Supported |
| OC1 | Open Circuit Breaker 1 (Pulse OC1) | Open Circuit Breaker 1 (Pulse OC1) | Open Circuit Breaker 1 (Pulse OC1) | No action | Open Circuit Breaker 1 (Pulse OC1) |
| CC1 | Close Circuit Breaker 1 (Pulse CC1) | Close Circuit Breaker 1 (Pulse CC1) | Close Circuit Breaker 1 (Pulse CC1) | No action | Close Circuit Breaker 1 (Pulse CC1) |
| OC1:CC1 | Close Circuit Breaker 1 (Pulse CC1) | Open Circuit Breaker 1 (Pulse OC1) | Not Supported | Not Supported | Not Supported |
| OC2 | Open Circuit Breaker 2 (Pulse OC2) | Open Circuit Breaker 2 (Pulse OC2) | Open Circuit Breaker 2 (Pulse OC2) | No action | Open Circuit Breaker 2 (Pulse OC2) |
| CC2 | Close Circuit Breaker 2 (Pulse CC2) | Close Circuit Breaker 2 (Pulse CC2) | Close Circuit Breaker 2 (Pulse CC2) | No action | Close Circuit Breaker 2 (Pulse CC2) |
| OC2:CC2 | Close Circuit Breaker 2 (Pulse CC2) | Open Circuit Breaker 2 (Pulse OC2) | Not Supported | Not Supported | Not Supported |

Analog Inputs

Analog Inputs (30) and Analog Change Events (32) are supported as defined in Table D.11. The default variation for both static and event inputs is defined by the DVARAI1 (DVARAI_n for DNP3 LAN/WAN session *n*) setting. Only the Read function code (1) is allowed with these objects.

Unless otherwise indicated, analog values are reported in primary units. See *Appendix K: Analog Quantities* for a list of all available analog inputs.

For all currents, the default scaling is the DECPLA setting on magnitudes and scale factor of 100 on angles. The default dead band for currents is ANADBV on magnitudes and ANADBM on angles. For all voltages, the default scaling is the DECPLV setting on magnitudes and scale factor of 100 on angles. The default dead band for voltages is ANADBV on magnitudes and ANADBM on angles. For all powers and energies, the default scaling is the DECPLM setting and default dead band is ANADBM. For all other quantities, the default scaling is 1 and default dead band is ANADBM.

Default scaling and dead bands may be overridden by per-point scaling and dead band. See *Configurable Data Mapping on page D.23* for more information. Dead bands for analog inputs can also be modified by writing to object 34.

A dead-band check is done after any scaling has been applied. Event class messages are generated whenever an input changes beyond the value given by the appropriate dead-band setting. The voltage and current phase angles will only generate an event if, in addition to their dead-band check, the corresponding magnitude changes beyond its own dead band. Analog inputs are scanned at approximately a one-second rate. All events generated during a scan will use the time the scan was initiated.

NOTE: Dead-band changes via Object 34 are not stored in nonvolatile memory. Be sure to reissue the Object 34 dead-band changes you want to retain after changing DNP port settings, issuing a **STA C** command, or cold-starting the relay (power-cycle).

Configurable Data Mapping

One of the most powerful features of the SEL-787 implementation is the ability to remap DNP3 data and, for analog values, specify per-point scaling and dead bands. Remapping is the process of selecting data from the reference map and organizing it into a data subset optimized for your application. The SEL-787 uses object and point labels, rather than point indices, to streamline the remapping process. This enables you to quickly create a custom map without having to search for each point index in a large reference map.

You may use any of the three available DNP3 maps simultaneously with as many as three unique DNP3 masters. Each map is initially populated with default data points, as described in *Default Data Map on page D.19*. You may remap the points in a default map to create a custom map with as many as:

- 100 Binary Inputs
- 32 Binary Outputs
- 100 Analog Inputs
- 32 Analog Outputs
- 32 Counters

You can use the **SHOW DNP *x* <Enter>** command to view the DNP3 data map settings, where *x* is the DNP3 map number from 1 to 3. See *Figure D.3* for an example display of Map 1.

```
=>>SHO DNP 1 <Enter>
```

DNP Map 1 Settings

Binary Input Map

```
BI_00 := ENABLED
BI_01 := T01_LED
BI_02 := T02_LED
BI_03 := T03_LED
...
BI_97 := IN101
BI_98 := IN102
BI_99 := 52A1
```

Binary Output Map

```
BO_00 := RB01
BO_01 := RB02
BO_02 := RB03
...
BO_29 := RB30
BO_30 := RB31
BO_31 := RB32
```

Analog Input Map

```
AI_00 := IAW1_MAG
AI_01 := IBW1_MAG
AI_02 := ICW1_MAG
...
AI_95 := FREQ
AI_96 := P
AI_97 := Q
AI_98 := S
AI_99 := PF
```

Analog Output Map

```
AO_00 := GROUP
AO_01 := NOOP
AO_02 := NA
...
AO_29 := NA
AO_30 := NOOP
AO_31 := NOOP
```

Counter Map

```
CO_00 := SC01
CO_01 := SC02
CO_02 := SC03
```

Figure D.3 Sample Response to SHO DNP Command (Sheet 1 of 2)

```
...
CO_29      := SC30
CO_30      := SC31
CO_31      := SC32

=>>
```

Figure D.3 Sample Response to SHO DNP Command (Sheet 2 of 2)

You can also use the **MAP DNP y s <Enter>** command to display DNP3 maps, but the parameter **y** is the port number from 1 to 4. Because Port 1, the Ethernet port, can support multiple DNP3 sessions, it may have a different map assigned to each session selected by parameter **s** for sessions 1 to 3. See *Figure D.4* for an example of a **MAP** command that shows the same map as in *Figure D.3*.

```
=>MAP DNP 1 1 <Enter>
```

SEL-787

TRNSFRMR RELAY

Date: 02/14/2008

Time: 09:33:39

Time Source: Internal

Map

1

Transport

TCP

Device IP Address

10.201.5.3

Master IP Address

10.200.0.139

Device DNP TCP and UDP Port

20000

Device DNP Address

15

Master DNP Address

0

Binary Inputs

| INDEX | POINT LABEL | EVENT | CLASS | SER | TIMESTAMP |
|-------|-------------|-------|-------|-----|-----------|
| 0 | ENABLED | 1 | | No | |
| 1 | T01_LED | 1 | | No | |
| 2 | T02_LED | 1 | | No | |
| 3 | T03_LED | 1 | | No | |
| ... | | | | | |
| 97 | IN101 | 1 | | No | |
| 98 | IN102 | 1 | | No | |
| 99 | 52A1 | 1 | | No | |

Binary Outputs

| INDEX | POINT LABEL |
|-------|-------------|
| 0 | RB01 |
| 1 | RB02 |
| 2 | RB03 |
| ... | |
| 29 | RB30 |
| 30 | RB31 |
| 31 | RB32 |

Counters

| INDEX | POINT LABEL | EVENT | CLASS | DEADBAND |
|-------|-------------|-------|-------|----------|
| 0 | SC01 | 0 | | 1 |
| 1 | SC02 | 0 | | 1 |
| 2 | SC03 | 0 | | 1 |
| ... | | | | |
| 29 | SC30 | 0 | | 1 |
| 30 | SC31 | 0 | | 1 |
| 31 | SC32 | 0 | | 1 |

Figure D.4 Port MAP Command (Sheet 1 of 2)

| Analog Inputs | | | | | | |
|----------------|-------------|-------------|--------------|----------|--|--|
| INDEX | POINT LABEL | EVENT CLASS | SCALE FACTOR | DEADBAND | | |
| 0 | IAW1_MAG | 2 | 10.0000 | 1000 | | |
| 1 | IBW1_MAG | 2 | 10.0000 | 1000 | | |
| 2 | ICW1_MAG | 2 | 10.0000 | 1000 | | |
| 3 | IAW2_MAG | 2 | 10.0000 | 1000 | | |
| 4 | IBW2_MAG | 2 | 10.0000 | 1000 | | |
| 5 | ICW2_MAG | 2 | 10.0000 | 1000 | | |
| 6 | IGW1_MAG | 2 | 10.0000 | 1000 | | |
| 7 | IGW2_MAG | 2 | 10.0000 | 1000 | | |
| 8 | IN_MAG | 2 | 10.0000 | 1000 | | |
| 9 | IAVW1MAG | 2 | 10.0000 | 1000 | | |
| 10 | IAVW2MAG | 2 | 10.0000 | 1000 | | |
| 11 | 3I2W1MAG | 2 | 10.0000 | 1000 | | |
| 12 | 3I2W2MAG | 2 | 10.0000 | 1000 | | |
| 13 | FREQ | 2 | 1.0000 | 100 | | |
| 14 | VAB_MAG | 2 | 10.0000 | 2000 | | |
| 15 | VBC_MAG | 2 | 10.0000 | 2000 | | |
| 16 | VCA_MAG | 2 | 10.0000 | 2000 | | |
| 17 | VAVE_MAG | 2 | 10.0000 | 2000 | | |
| 18 | 3V2_MAG | 2 | 10.0000 | 2000 | | |
| ... | | | | | | |
| ... | | | | | | |
| 96 | P | 2 | 10.0000 | 100 | | |
| 97 | Q | 2 | 10.0000 | 100 | | |
| 98 | S | 2 | 10.0000 | 100 | | |
| 99 | PF | 2 | 10.0000 | 100 | | |
| | | | | | | |
| Analog Outputs | | | | | | |
| INDEX | POINT LABEL | | | | | |
| 0 | GROUP | | | | | |
| 1 | NOOP | | | | | |

Figure D.4 Port MAP Command (Sheet 2 of 2)

You can use the command **SET DNP *x***, where *x* is the map number, to edit or create custom DNP3 data maps. You can also use ACSELERATOR QuickSet® SEL-5030 Software, which is recommended for this purpose.

Scaling factors allow you to overcome the limitations imposed by the integer nature of the default variations of Objects 30 and 32. For example, the device rounds a value of 11.4 amps to 11 amps. You may use scaling to include decimal point values by multiplying by a number larger than one. If you use 10 as a scaling factor, 11.4 amps will be transmitted as 114. You must divide the value by 10 in the master to see the original value including one decimal place.

You can also use scaling to avoid overflowing the 16-bit maximum integer value of 32767. For example, if you have a value that can reach 157834, you cannot send it using DNP3 16-bit analog object variations. You could use a scaling factor of 0.1 so that the maximum value reported is 15783. You can then multiply the value by 10 in the master to see a value of 157830. You will lose some precision as the last digit is rounded off in the scaling process, but you can transmit the scaled value using standard DNP3 Objects 30 and 32.

You can customize the DNP3 analog input map with per-point scaling, and dead-band settings. Per-point customization is not required, but class scaling (DECPLA, DECPLV, and DECPLM) and dead-band (ANADBA, ANADBV, and ANADBM) settings are applied to indices that do not have per-point entries. Unlike per-point scaling described above, class-level scaling is specified by an integer in the range 0–3 (inclusive), which indicates the number of decimal place shifts. In other words, you should select 0 to multiply by 1, 1 for 10, 2 for 100, or 3 for 1000.

If it is important to maintain tight data coherency (that is, all data read of a certain type was sampled or calculated at the same time), then you should group that data together within your custom map. For example, if you want all the Winding 1 currents to be coherent, you should group points IAW1_MAG,

IBW1_MAG, ICW1_MAG, and IGW1_MAG together in the custom map. If points are not grouped together, they might not come from the same data sample.

The following example describes how to create a custom DNP3 map by point type. The example demonstrates the SEL ASCII command **SET DNP** for each point type, but the entire configuration may be completed without saving changes between point types. To do this, you simply continue entering data and save the entire map at the end. Alternately, you can use ACSELERATOR QuickSet to simplify custom data map creation.

Consider a case where you want to set the AI points in a map, as shown in *Table D.13*.

Table D.13 Sample Custom DNP3 AI Map

| Desired Point Index | Description | Label | Scaling | Dead Band |
|---------------------|-------------------------------------|----------|---------|-----------|
| 0 | Winding 1, IA magnitude | IAW1_MAG | default | default |
| 1 | Winding 1, IB magnitude | IBW1_MAG | default | default |
| 2 | Winding 1, IC magnitude | ICW1_MAG | default | default |
| 3 | Winding 2, IA magnitude | IAW2_MAG | default | default |
| 4 | 3-Phase Real Power | P | 5 | default |
| 5 | AB Phase-to-Phase Voltage Magnitude | VAB_MAG | default | default |
| 6 | AB Phase-to-Phase Voltage Angle | VAB_ANG | 1 | 15 |
| 7 | Frequency | FREQ | .01 | 1 |

To set these points as part of custom map 1, you can use the command **SET DNP 1 AI_00 TERSE** <Enter> command as shown in *Figure D.5*.

```

==>SET DNP 1 AI_00 TERSE <Enter>
Analog Input Map

DNP Analog Input Label Name (23 characters)
AI_00 := NA
? > IAW1_MAG <Enter>

AI_01 := NA
? > IBW1_MAG <Enter>

AI_02 := NA
? > ICW1_MAG <Enter>

AI_03 := NA
? > IAW2_MAG <Enter>

AI_04 := NA
? > P:5 <Enter>

AI_05 := NA
? > VAB_MAG <Enter>

AI_06 := NA
? > VAB_ANG:1:15 <Enter>

AI_07 := NA
? > FREQ:.01:1 <Enter>

AI_08 := NA
? > end <Enter>

Save changes (Y/N) ? Y <Enter>

==>

```

Figure D.5 Sample Custom DNP3 AI Map Settings

You may also use ACSELERATOR QuickSet to enter the above AI map settings as shown in the screen capture in *Figure D.6*. You can enter scaling and dead-band settings in the same pop-up dialog used to select the AI point, as shown in *Figure D.7*.

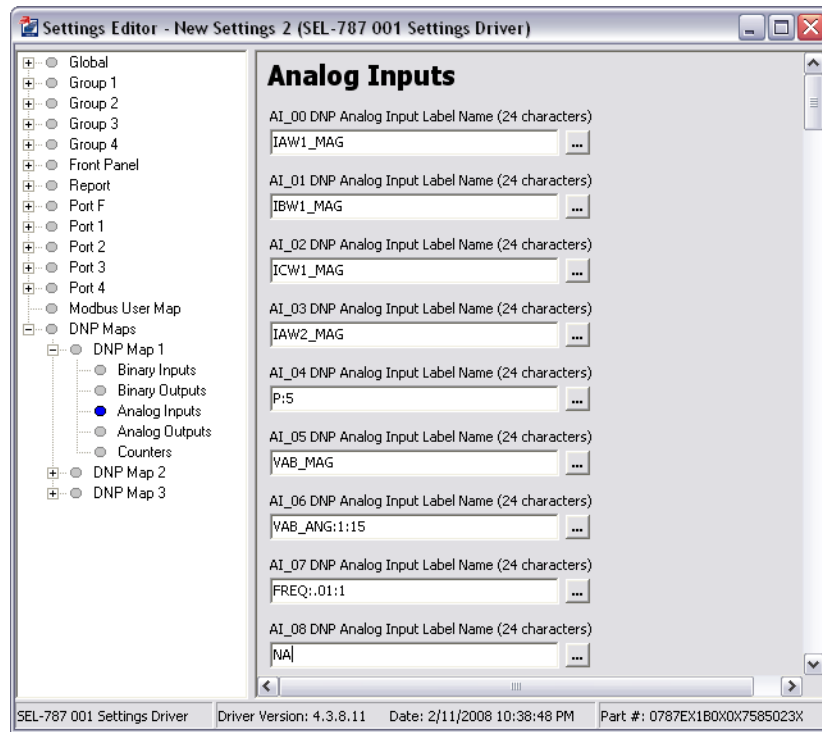


Figure D.6 Analog Input Map Entry in ACSELERATOR QuickSet Software

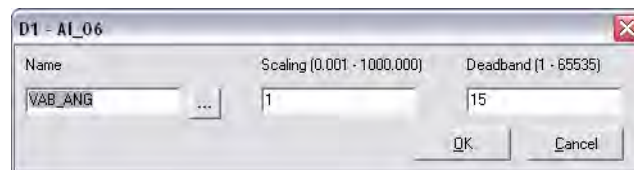


Figure D.7 AI Point Label, Scaling and Dead Band in ACSELERATOR QuickSet Software

The **SET DNP *x* CO_00 <Enter>** command allows you to populate the DNP counter map with per-point dead bands. Entering these settings is similar to defining the analog input map settings.

You can use the command **SET DNP *x* BO_00 TERSE <Enter>** to change the binary output map *x* as shown in *Figure D.8*. You may populate the custom BO map with any of the 32 remote bits (RB01–RB32). You can define bit pairs in BO maps by including a colon (:) between the bit labels.

```

=>>SET DNP 1 BO_00 TERSE <Enter>
Binary Output Map

DNP Binary Output Label Name (23 characters)
BO_00 := NA
? > RB01 <Enter>

DNP Binary Output Label Name (23 characters)
BO_01 := NA
? > RB02 <Enter>

DNP Binary Output Label Name (23 characters)
BO_02 := NA
? > RB03:RB04 <Enter>

DNP Binary Output Label Name (23 characters)
BO_03 := NA
? > RB05:RB06 <Enter>

DNP Binary Output Label Name (23 characters)
BO_04 := NA
? > end <Enter>

=>>

```

Figure D.8 Sample Custom DNP3 BO Map Settings

You may also use ACSELERATOR QuickSet to enter the BO map settings as shown in the screen capture in *Figure D.9*.

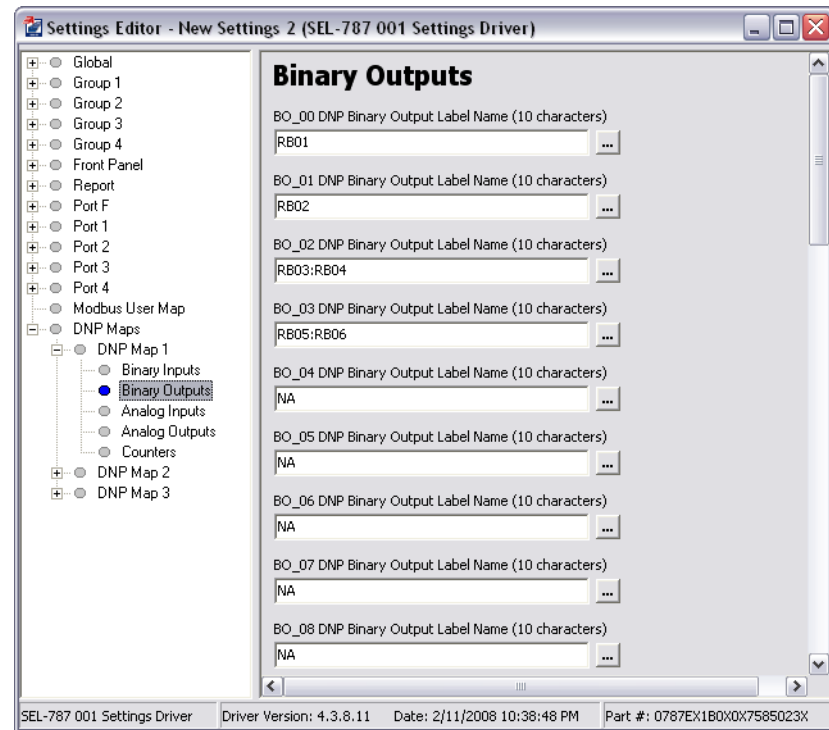


Figure D.9 Binary Output Map Entry in ACSELERATOR QuickSet Software

The binary input (BI) maps are modified in a similar manner, but pairs are not allowed.

Appendix E

Modbus RTU Communications

Overview

This appendix describes the Modbus® RTU communications features supported by the SEL-787 Transformer Protection Relay. Complete specifications for the Modbus protocol are available from the Modbus user's group website at www.modbus.org.

Enable the Modbus TCP protocol with the optional Ethernet port settings. The SEL-787 supports as many as two Modbus TCP sessions. The TCP port number for each session is selected with the Ethernet port settings. The default TCP port number is the Modbus TCP registered port 502. Modbus TCP uses the device IP address as the Modbus identifier and accesses the data in the relay by using the same function codes and data maps as Modbus RTU.

Enable Modbus RTU protocol with the serial port settings. When Modbus RTU protocol is enabled, the relay switches the port to Modbus RTU protocol and deactivates the ASCII protocol.

Modbus RTU is a binary protocol that permits communication between a single master device and multiple slave devices. The communication is half duplex—only one device transmits at a time. The master transmits a binary command that includes the address of the desired slave device. All of the slave devices receive the message, but only the slave device with the matching address responds.

The SEL-787 Modbus communication allows a Modbus master device to do the following:

- Acquire metering, monitoring, and event data from the relay.
- Control SEL-787 output contacts.
- Read the SEL-787 self-test status and learn the present condition of all the relay protection elements.
- Read most of the relay settings and modify the relay settings.

NOTE: Be aware of the following setting in the relay:
Under Global settings =====>
Access Control, there is a setting called BLOCK MODBUS SET.

The BLOCK MODBUS SET setting is used to block relay settings changes via Modbus or DeviceNet protocols. The factory-default setting, **BLKMBSET := NONE**, **allows** all setting changes via Modbus or DeviceNet communications. The **BLKMBSET := R_S** setting **prevents** Modbus or DeviceNet communications from resetting to the factory-default settings. The **BLKMBSET := ALL** setting **blocks** all changes to the settings via the Modbus or the DeviceNet protocol.

You are strongly advised to change the BLKMBSET (BLOCK MODBUS SET) := ALL if you do not want the PLC (Programmable Logic Controller) or DCS (Distributed Control System) to send the settings to the SEL-787 relay. There is a strong possibility that under special conditions like a reboot, the

PLC/DCS will send default settings to the relay, overwriting the existing settings. To protect the existing settings under these conditions it is highly recommended to set the setting to "ALL."

Communications Protocol

Modbus Queries

Modbus RTU master devices initiate all exchanges by sending a query. The query consists of the fields shown in *Table E.1*.

Table E.1 Modbus Query Fields

| Field | Number of Bytes |
|---------------------------------|-----------------|
| Slave Device Address | 1 byte |
| Function Code | 1 byte |
| Data Region | 0–251 bytes |
| Cyclical Redundancy Check (CRC) | 2 bytes |

The SEL-787 SLAVEID setting defines the device address. Set this value to a unique number for each device on the Modbus network. For Modbus communication to operate properly, no two slave devices may have the same address.

The cyclical redundancy check detects errors in the received data. If an error is detected, the relay discards the packet.

Modbus Responses

The slave device sends a response message after it performs the action the query specifies. If the slave cannot execute the query command for any reason, it sends an error response. Otherwise, the slave device response is formatted similarly to the query and includes the slave address, function code, data (if applicable), and a cyclical redundancy check value.

Supported Modbus Function Codes

The SEL-787 supports the Modbus function codes shown in *Table E.2*.

Table E.2 SEL-787 Modbus Function Codes

| Codes | Description |
|-------|--|
| 01h | Read Discrete Output Coil Status |
| 02h | Read Discrete Input Status |
| 03h | Read Holding Registers |
| 04h | Read Input Registers |
| 05h | Force Single Coil |
| 06h | Preset Single Register |
| 08h | Diagnostic Command |
| 10h | Preset Multiple Registers |
| 60h | Read Parameter Information |
| 61h | Read Parameter Text |
| 62h | Read Enumeration Text |
| 7Dh | Encapsulate Modbus Packet With Control |
| 7Eh | NOP (can only be used with the 7Dh function) |

Modbus Exception Responses

The SEL-787 sends an exception code under the conditions described in *Table E.3*.

Table E.3 SEL-787 Modbus Exception Codes

| Exception Code | Error Type | Description |
|----------------|-----------------------|--|
| 1 | Illegal Function Code | The received function code is either undefined or unsupported. |
| 2 | Illegal Data Address | The received command contains an unsupported address in the data field (i.e., cannot write to a read-only register, cannot write because the settings are locked, etc.). |
| 3 | Illegal Data Value | The received command contains a value that is out of range. |
| 4 | Device Error | The SEL-787 is in the wrong state for the function a query specifies. This also stands for Service Failure for DeviceNet interface applications. The relay is unable to perform the action specified by a query (i.e., cannot write to a read-only register, cannot write because settings are locked, etc.). |
| 6 | Busy | The device is unable to process the command at this time, due to a busy resource. |

In the event that any of the errors listed in *Table E.3* occur, the relay assembles a response message that includes the exception code in the data field. The relay sets the most significant bit in the function code field to indicate to the master that the data field contains an error code, instead of the required data.

Cyclical Redundancy Check

The SEL-787 calculates a 2-byte CRC value through use of the device address, function code, and data region. It appends this value to the end of every Modbus response. When the master device receives the response, it recalculates the CRC. If the calculated CRC matches the CRC sent by the SEL-787, the master device uses the data received. If there is no match, the check fails and the message is ignored. The devices use a similar process when the master sends queries.

01h Read Discrete Output Coil Status Command

Use function code 01h to read the On/Off status of the selected bits (coils) (see the Map shown in *Table E.14*). You can read the status of as many as 2000 bits per query, using the fields shown in *Table E.4*. Note that the SEL-787 coil addresses start at 0 (e.g., Coil 1 is located at address zero). The coil status is packed one coil per bit of the data field. The Least Significant Bit (LSB) of the first data byte contains the starting coil address in the query. The other coils follow towards the high order end of this byte and from low order to high order in subsequent bytes.

Table E.4 01h Read Discrete Output Coil Status Command (Sheet 1 of 2)

| Bytes | Field |
|--|--------------------------|
| Requests from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (01h) |
| 2 bytes | Address of the first bit |
| 2 bytes | Number of bits to read |
| 2 bytes | CRC-16 |

Table E.4 01h Read Discrete Output Coil Status Command (Sheet 2 of 2)

| Bytes | Field |
|--|----------------------------|
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (01h) |
| 1 byte | Bytes of data (<i>n</i>) |
| <i>n</i> bytes | Data |
| 2 bytes | CRC-16 |

To build the response, the SEL-787 calculates the number of bytes required to contain the number of bits requested. If the number of bits requested is not evenly divisible by eight, the device adds one more byte to maintain the balance of bits, padded by zeroes to make an even byte. *Table E.14* includes the coil number and lists all possible coils (identified as Outputs and Remote bits) available in the device. Note that the command depends on the device hardware configuration; the device responds only to installed cards.

The relay responses to errors in the query are shown in *Table E.5*.

Table E.5 Responses to 01h Read Discrete Output Coil Query Errors

| Error | Error Code Returned | Communication Counter Increments |
|--------------------------------|----------------------------|----------------------------------|
| Invalid bit to read | Illegal Data Address (02h) | Invalid Address |
| Invalid number of bits to read | Illegal Data Value (03h) | Illegal Register |
| Format error | Illegal Data Value (03h) | Bad Packet Format |

02 Read Input Status Command

Use function code 02h to read the On/Off status of the selected bits (inputs), as shown in *Table E.6*. You can read the status of as many as 2000 bits per query. Note that input addresses start at 0 (e.g., Input 1 is located at address zero). The input status is packed one input per bit of the data field. The LSB of the first data byte contains the starting input address in the query. The other inputs follow towards the high order end of this byte, and from low order to high order in subsequent bytes.

Table E.6 02h Read Input Status Command

| Bytes | Field |
|--|----------------------------|
| Requests from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (02h) |
| 2 bytes | Address of the first bit |
| 2 bytes | Number of bits to read |
| 2 bytes | CRC-16 |
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (02h) |
| 1 byte | Bytes of data (<i>n</i>) |
| <i>n</i> bytes | Data |
| 2 bytes | CRC-16 |

To build the response, the device calculates the number of bytes required to contain the number of bits requested. If the number of bits requested is not evenly divisible by eight, the device adds one more byte to maintain the balance of bits, padded by zeroes to make an even byte.

In each row, the input numbers are assigned from the right-most input to the left-most input (i.e., Input 1 is TLED_06 and Input 8 is ENABLED). Input addresses start at 0000 (i.e., Input 1 is located at Input Address 0000).

Table E.7 includes the coil address in decimal and lists all possible inputs (Relay Word bits) available in the device. Note that the command depends on the device hardware configuration; the device responds only to installed cards.

Table E.7 02h SEL-787 Inputs (Sheet 1 of 3)

| Coil Address (Decimal) | Function Code Supported | Coil Description ^a |
|---------------------------|----------------------------|-------------------------------|
| 0–7 | 2 | Relay Element Status Row 0 |
| 8–15 | 2 | Relay Element Status Row 1 |
| 16–23 | 2 | Relay Element Status Row 2 |
| 24–31 | 2 | Relay Element Status Row 3 |
| 32–39 | 2 | Relay Element Status Row 4 |
| 40–47 | 2 | Relay Element Status Row 5 |
| 48–55 | 2 | Relay Element Status Row 6 |
| 56–63 | 2 | Relay Element Status Row 7 |
| 64–71 | 2 | Relay Element Status Row 8 |
| 72–79 | 2 | Relay Element Status Row 9 |
| 80–87 | 2 | Relay Element Status Row 10 |
| 88–95 | 2 | Relay Element Status Row 11 |
| 96–103 | 2 | Relay Element Status Row 12 |
| 104–111 | 2 | Relay Element Status Row 13 |
| 112–119 | 2 | Relay Element Status Row 14 |
| 120–127 | 2 | Relay Element Status Row 15 |
| 128–135 | 2 | Relay Element Status Row 16 |
| 136–143 | 2 | Relay Element Status Row 17 |
| 144–151 | 2 | Relay Element Status Row 18 |
| 152–159 | 2 | Relay Element Status Row 19 |
| 160–167 | 2 | Relay Element Status Row 20 |
| 168–175 | 2 | Relay Element Status Row 21 |
| 176–183 | 2 | Relay Element Status Row 22 |
| 184–191 | 2 | Relay Element Status Row 23 |
| 192–199 | 2 | Relay Element Status Row 24 |
| 200–207 | 2 | Relay Element Status Row 25 |
| 208–215 | 2 | Relay Element Status Row 26 |
| 216–223 | 2 | Relay Element Status Row 27 |
| 224–231 | 2 | Relay Element Status Row 28 |
| 232–239 | 2 | Relay Element Status Row 29 |
| 240–247 | 2 | Relay Element Status Row 30 |
| 248–255 | 2 | Relay Element Status Row 31 |
| 256–263 | 2 | Relay Element Status Row 32 |

Table E.7 02h SEL-787 Inputs (Sheet 2 of 3)

| Coil Address (Decimal) | Function Code Supported | Coil Description ^a |
|---------------------------|----------------------------|-------------------------------|
| 264–271 | 2 | Relay Element Status Row 33 |
| 272–279 | 2 | Relay Element Status Row 34 |
| 280–287 | 2 | Relay Element Status Row 35 |
| 288–295 | 2 | Relay Element Status Row 36 |
| 296–303 | 2 | Relay Element Status Row 37 |
| 304–311 | 2 | Relay Element Status Row 38 |
| 312–319 | 2 | Relay Element Status Row 39 |
| 320–327 | 2 | Relay Element Status Row 40 |
| 328–335 | 2 | Relay Element Status Row 41 |
| 336–343 | 2 | Relay Element Status Row 42 |
| 344–351 | 2 | Relay Element Status Row 43 |
| 352–359 | 2 | Relay Element Status Row 44 |
| 360–367 | 2 | Relay Element Status Row 45 |
| 368–375 | 2 | Relay Element Status Row 46 |
| 376–383 | 2 | Relay Element Status Row 47 |
| 384–391 | 2 | Relay Element Status Row 48 |
| 392–399 | 2 | Relay Element Status Row 49 |
| 400–407 | 2 | Relay Element Status Row 50 |
| 408–415 | 2 | Relay Element Status Row 51 |
| 416–423 | 2 | Relay Element Status Row 52 |
| 424–431 | 2 | Relay Element Status Row 53 |
| 432–439 | 2 | Relay Element Status Row 54 |
| 440–447 | 2 | Relay Element Status Row 55 |
| 448–455 | 2 | Relay Element Status Row 56 |
| 456–463 | 2 | Relay Element Status Row 57 |
| 464–471 | 2 | Relay Element Status Row 58 |
| 472–479 | 2 | Relay Element Status Row 59 |
| 480–487 | 2 | Relay Element Status Row 60 |
| 488–495 | 2 | Relay Element Status Row 61 |
| 496–503 | 2 | Relay Element Status Row 62 |
| 504–511 | 2 | Relay Element Status Row 63 |
| 512–519 | 2 | Relay Element Status Row 64 |
| 520–527 | 2 | Relay Element Status Row 65 |
| 528–535 | 2 | Relay Element Status Row 66 |
| 536–543 | 2 | Relay Element Status Row 67 |
| 544–551 | 2 | Relay Element Status Row 68 |
| 552–559 | 2 | Relay Element Status Row 69 |
| 560–567 | 2 | Relay Element Status Row 70 |
| 568–575 | 2 | Relay Element Status Row 71 |
| 576–583 | 2 | Relay Element Status Row 72 |
| 584–591 | 2 | Relay Element Status Row 73 |
| 592–599 | 2 | Relay Element Status Row 74 |
| 600–607 | 2 | Relay Element Status Row 75 |

Table E.7 02h SEL-787 Inputs (Sheet 3 of 3)

| Coil Address (Decimal) | Function Code Supported | Coil Description ^a |
|---------------------------|----------------------------|-------------------------------|
| 608–615 | 2 | Relay Element Status Row 76 |
| 616–623 | 2 | Relay Element Status Row 77 |
| 624–631 | 2 | Relay Element Status Row 78 |
| 632–639 | 2 | Relay Element Status Row 79 |
| 640–647 | 2 | Relay Element Status Row 80 |
| 648–655 | 2 | Relay Element Status Row 81 |
| 656–663 | 2 | Relay Element Status Row 82 |
| 664–671 | 2 | Relay Element Status Row 83 |
| 672–679 | 2 | Relay Element Status Row 84 |
| 680–687 | 2 | Relay Element Status Row 85 |
| 688–695 | 2 | Relay Element Status Row 86 |
| 696–703 | 2 | Relay Element Status Row 87 |
| 704–711 | 2 | Relay Element Status Row 88 |
| 712–719 | 2 | Relay Element Status Row 89 |
| 720–727 | 2 | Relay Element Status Row 90 |
| 728–735 | 2 | Relay Element Status Row 91 |
| 736–743 | 2 | Relay Element Status Row 92 |
| 744–751 | 2 | Relay Element Status Row 93 |
| 752–759 | 2 | Relay Element Status Row 94 |
| 760–767 | 2 | Relay Element Status Row 95 |
| 768–775 | 2 | Relay Element Status Row 96 |
| 776–783 | 2 | Relay Element Status Row 97 |
| 784–791 | 2 | Relay Element Status Row 98 |
| 792–799 | 2 | Relay Element Status Row 99 |
| 800–807 | 2 | Relay Element Status Row 100 |
| 808–815 | 2 | Relay Element Status Row 101 |
| 816–823 | 2 | Relay Element Status Row 102 |
| 824–831 | 2 | Relay Element Status Row 103 |
| 832–839 | 2 | Relay Element Status Row 104 |
| 840–847 | 2 | Relay Element Status Row 105 |
| 848–855 | 2 | Relay Element Status Row 106 |

^a The input numbers are assigned from the right-most input to the left-most input in the Relay row as show in the following example.

Address 7 = ENABLED

Address 6 = TRIP

Address 5 = T01_LED

Address 4 = T02_LED

Address 3 = T03_LED

Address 2 = T04_LED

Address 1 = T05_LED

Address 0 = T06_LED

The relay responses to errors in the query are shown in *Table E.8*.

Table E.8 Responses to 02h Read Input Query Errors

| Error | Error Code Returned | Communication Counter Increments |
|--------------------------------|----------------------------|----------------------------------|
| Invalid bit to read | Illegal Data Address (02h) | Invalid Address |
| Invalid number of bits to read | Illegal Data Value (03h) | Illegal Register |
| Format error | Illegal Data Value (03h) | Bad Packet Format |

03h Read Holding Register Command

Use function code 03h to read directly from the Modbus Register Map shown in *Table E.34*. You can read a maximum of 125 registers at once with this function code. Most masters use 4X references with this function code. If you are accustomed to 4X references with this function code, for five-digit addressing, add 40001 to the standard database address.

Table E.9 03h Read Holding Register Command

| Bytes | Field |
|--|-----------------------------|
| Requests from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (03h) |
| 2 bytes | Starting Register Address |
| 2 bytes | Number of Registers to Read |
| 2 bytes | CRC-16 |
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (03h) |
| 1 byte | Bytes of data (<i>n</i>) |
| <i>n</i> bytes | Data (2–250) |
| 2 bytes | CRC-16 |

The relay responses to errors in the query are shown in *Table E.10*.

Table E.10 Responses to 03h Read Holding Register Query Errors

| Error | Error Code Returned | Communication Counter Increments |
|-------------------------------------|----------------------------|----------------------------------|
| Illegal register to read | Illegal Data Address (02h) | Invalid Address |
| Illegal number of registers to read | Illegal Data Value (03h) | Illegal Register |
| Format error | Illegal Data Value (03h) | Bad Packet Format |

04h Read Input Register Command

Use function code 04h to read directly from the Modbus Register Map shown in *Table E.34*. You can read a maximum of 125 registers at once with this function code. Most masters use 3X references with this function code. If you are accustomed to 3X references with this function code, for five-digit addressing, add 30001 to the standard database address.

Table E.11 04h Read Input Register Command

| Bytes | Field |
|--|-----------------------------|
| Requests from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (04h) |
| 2 bytes | Starting Register Address |
| 2 bytes | Number of Registers to Read |
| 2 bytes | CRC-16 |
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (04h) |
| 1 byte | Bytes of data (<i>n</i>) |
| <i>n</i> bytes | Data (2–250) |
| 2 bytes | CRC-16 |

The relay responses to errors in the query are shown in *Table E.12*.

Table E.12 Responses to 04h Read Input Register Query Errors

| Error | Error Code Returned | Communication Counter Increments |
|-------------------------------------|----------------------------|----------------------------------|
| Illegal register to read | Illegal Data Address (02h) | Invalid Address |
| Illegal number of registers to read | Illegal Data Value (03h) | Illegal Register |
| Format error | Illegal Data Value (03h) | Bad Packet Format |

05h Force Single Coil Command

Use function code 05h to set or clear a coil. In *Table E.13*, the command response is identical to the command request.

Table E.13 05h Force Single Coil Command

| Bytes | Field |
|--|---|
| Requests from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (05h) |
| 2 bytes | Coil Reference |
| 1 byte | Operation Code (FF for bit set, 00 for bit clear) |
| 1 byte | Placeholder (00) |
| 2 bytes | CRC-16 |

Table E.14 lists the coil numbers supported by the SEL-787. The physical coils (coils 0–26) are self-resetting. Pulsing a Set remote bit (decimal address 59 through 90) causes the remote bit to be cleared at the end of the pulse.

Table E.14 01h, 05h SEL-787 Output (Sheet 1 of 3)

| Coil Address (Decimal) | Function Code Supported | Coil Description |
|------------------------|-------------------------|-----------------------|
| 0 | 01, 05 | Pulse OUT101 1 second |
| 1 | 01, 05 | Pulse OUT102 1 second |
| 2 | 01, 05 | Pulse OUT103 1 second |
| 3 | 01, 05 | Pulse OUT301 1 second |
| 4 | 01, 05 | Pulse OUT302 1 second |

Table E.14 01h, 05h SEL-787 Output (Sheet 2 of 3)

| Coil Address (Decimal) | Function Code Supported | Coil Description |
|------------------------|-------------------------|-----------------------|
| 5 | 01, 05 | Pulse OUT303 1 second |
| 6 | 01, 05 | Pulse OUT304 1 second |
| 7 | 01, 05 | Reserved |
| 8 | 01, 05 | Reserved |
| 9 | 01, 05 | Reserved |
| 10 | 01, 05 | Reserved |
| 11 | 01, 05 | Pulse OUT401 1 second |
| 12 | 01, 05 | Pulse OUT402 1 second |
| 13 | 01, 05 | Pulse OUT403 1 second |
| 14 | 01, 05 | Pulse OUT404 1 second |
| 15 | 01, 05 | Reserved |
| 16 | 01, 05 | Reserved |
| 17 | 01, 05 | Reserved |
| 18 | 01, 05 | Reserved |
| 19 | 01, 05 | Pulse OUT501 1 second |
| 20 | 01, 05 | Pulse OUT502 1 second |
| 21 | 01, 05 | Pulse OUT503 1 second |
| 22 | 01, 05 | Pulse OUT504 1 second |
| 23 | 01, 05 | Reserved |
| 24 | 01, 05 | Reserved |
| 25 | 01, 05 | Reserved |
| 26 | 01, 05 | Reserved |
| 27 | 01, 05 | RB01 |
| 28 | 01, 05 | RB02 |
| 29 | 01, 05 | RB03 |
| 30 | 01, 05 | RB04 |
| 31 | 01, 05 | RB05 |
| 32 | 01, 05 | RB06 |
| 33 | 01, 05 | RB07 |
| 34 | 01, 05 | RB08 |
| 35 | 01, 05 | RB09 |
| 36 | 01, 05 | RB10 |
| 37 | 01, 05 | RB11 |
| 38 | 01, 05 | RB12 |
| 39 | 01, 05 | RB13 |
| 40 | 01, 05 | RB14 |
| 41 | 01, 05 | RB15 |
| 42 | 01, 05 | RB16 |
| 43 | 01, 05 | RB17 |
| 44 | 01, 05 | RB18 |
| 45 | 01, 05 | RB19 |
| 46 | 01, 05 | RB20 |
| 47 | 01, 05 | RB21 |
| 48 | 01, 05 | RB22 |

Table E.14 01h, 05h SEL-787 Output (Sheet 3 of 3)

| Coil Address (Decimal) | Function Code Supported | Coil Description |
|------------------------|-------------------------|-------------------------|
| 49 | 01, 05 | RB23 |
| 50 | 01, 05 | RB24 |
| 51 | 01, 05 | RB25 |
| 52 | 01, 05 | RB26 |
| 53 | 01, 05 | RB27 |
| 54 | 01, 05 | RB28 |
| 55 | 01, 05 | RB29 |
| 56 | 01, 05 | RB30 |
| 57 | 01, 05 | RB31 |
| 58 | 01, 05 | RB32 |
| 59 | 01, 05 | Pulse RB01 ^a |
| 60 | 01, 05 | Pulse RB02 ^a |
| 61 | 01, 05 | Pulse RB03 ^a |
| 62 | 01, 05 | Pulse RB04 ^a |
| 63 | 01, 05 | Pulse RB05 ^a |
| 64 | 01, 05 | Pulse RB06 ^a |
| 65 | 01, 05 | Pulse RB07 ^a |
| 66 | 01, 05 | Pulse RB08 ^a |
| 67 | 01, 05 | Pulse RB09 ^a |
| 68 | 01, 05 | Pulse RB10 ^a |
| 69 | 01, 05 | Pulse RB11 ^a |
| 70 | 01, 05 | Pulse RB12 ^a |
| 71 | 01, 05 | Pulse RB13 ^a |
| 72 | 01, 05 | Pulse RB14 ^a |
| 73 | 01, 05 | Pulse RB15 ^a |
| 74 | 01, 05 | Pulse RB16 ^a |
| 75 | 01, 05 | Pulse RB17 ^a |
| 76 | 01, 05 | Pulse RB18 ^a |
| 77 | 01, 05 | Pulse RB19 ^a |
| 78 | 01, 05 | Pulse RB20 ^a |
| 79 | 01, 05 | Pulse RB21 ^a |
| 80 | 01, 05 | Pulse RB22 ^a |
| 81 | 01, 05 | Pulse RB23 ^a |
| 82 | 01, 05 | Pulse RB24 ^a |
| 83 | 01, 05 | Pulse RB25 ^a |
| 84 | 01, 05 | Pulse RB26 ^a |
| 85 | 01, 05 | Pulse RB27 ^a |
| 86 | 01, 05 | Pulse RB28 ^a |
| 87 | 01, 05 | Pulse RB29 ^a |
| 88 | 01, 05 | Pulse RB30 ^a |
| 89 | 01, 05 | Pulse RB31 ^a |
| 90 | 01, 05 | Pulse RB32 ^a |

^a Pulsing a Set remote bit will cause the remote bit to be cleared at the end of the pulse (1 SELogic processing interval).

Coil addresses start at 0000 (i.e., Coil 1 is located at Coil address 0000). If the device is disabled it will respond with error code 4 (Device Error). In addition to Error Code 4, the device responses to errors in the query are shown in *Table E.15*.

Table E.15 Responses to 05h Force Single Coil Query Errors

| Error | Error Code Returned | Communication Counter Increments |
|-----------------------------|----------------------------|----------------------------------|
| Invalid bit (coil) | Illegal Data Address (02h) | Invalid Address |
| Invalid bit state requested | Illegal Data Value (03h) | Illegal Register |
| Format Error | Illegal Data Value (03h) | Bad Packet Format |

06h Preset Single Register Command

The SEL-787 uses this function to allow a Modbus master to write directly to a database register. Refer to the Modbus Register Map in *Table E.34* for a list of registers that can be written by using this function code. If you are accustomed to 4X references with this function code, for six-digit addressing, add 400001 to the standard database addresses.

In *Table E.16*, the command response is identical to the command required by the master.

Table E.16 06h Preset Single Register Command

| Bytes | Field |
|---|---------------------|
| Queries from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (06h) |
| 2 bytes | Register Address |
| 2 bytes | Data |
| 2 bytes | CRC-16 |

The relay responses to errors in the query are shown in *Table E.17*.

Table E.17 Responses to 06h Preset Single Register Query Errors

| Error | Error Code Returned | Communication Counter Increments |
|--------------------------|----------------------------|----------------------------------|
| Illegal register address | Illegal Data Address (02h) | Invalid Address Illegal Write |
| Illegal register value | Illegal Data Value (03h) | Illegal Write |
| Format error | Illegal Data Value (03h) | Bad Packet Format |

08h Loopback Diagnostic Command

The SEL-787 uses this function to allow a Modbus master to perform a diagnostic test on the Modbus communications channel and relay. When the subfunction field is 0000h, the relay returns a replica of the received message.

Table E.18 08h Loopback Diagnostic Command

| Bytes | Field |
|--|--|
| Requests from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (08h) |
| 2 bytes | Subfunction (0000h) |
| 2 bytes | Data Field |
| 2 bytes | CRC-16 |
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (08h) |
| 2 bytes | Subfunction (0000h) |
| 2 bytes | Data Field (identical to data in Master request) |
| 2 bytes | CRC-16 |

The relay responses to errors in the query are shown in *Table E.19*.

Table E.19 Responses to 08h Loopback Diagnostic Query Errors

| Error | Error Code Returned | Communication Counter Increments |
|--------------------------|--------------------------|----------------------------------|
| Illegal subfunction code | Illegal Data Value (03h) | Invalid Function Code/Op Code |
| Format error | Illegal Data Value (03h) | Bad Packet Format |

10h Preset Multiple Registers Command

This function code works much like code 06h, except that it allows you to write multiple registers at once, as many as 100 per operation. If you are accustomed to 4X references with the function code, for six-digit addressing, simply add 400001 to the standard database addresses.

Table E.20 10h Preset Multiple Registers Command (Sheet 1 of 2)

| Bytes | Field |
|---|--------------------------------------|
| Queries from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (10h) |
| 2 bytes | Starting Address |
| 2 bytes | Number of Registers to Write |
| 1 byte | Number of Bytes of Data (<i>n</i>) |
| <i>n</i> bytes | Data |
| 2 bytes | CRC-16 |

Table E.20 10h Preset Multiple Registers Command (Sheet 2 of 2)

| Bytes | Field |
|--|---------------------|
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (10h) |
| 2 bytes | Starting Address |
| 2 bytes | Number of Registers |
| 2 bytes | CRC-16 |

The relay responses to errors in the query are shown below.

Table E.21 10h Preset Multiple Registers Query Error Messages

| Error | Error Code Returned | Communication Counter Increments |
|--|----------------------------|------------------------------------|
| Illegal register to set | Illegal Data Address (02h) | Invalid Address Illegal Write |
| Illegal number of registers to set | Illegal Data Value (03h) | Illegal Register Illegal Write |
| Incorrect number of bytes in query data region | Illegal Data Value (03h) | Bad Packet Format Illegal Write |
| Invalid register data value | Illegal Data Value (03h) | Illegal Write |

60h Read Parameter Information Command

The SEL-787 uses this function to allow a Modbus master to read parameter information from the relay. One parameter (setting) is read in each query.

Table E.22 60h Read Parameter Information Command

| Bytes | Field |
|--|----------------------------------|
| Queries from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (60h) |
| 2 bytes | Parameter Number |
| 2 bytes | CRC-16 |
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (60h) |
| 2 bytes | Parameter Number |
| 1 byte | Parameter Descriptor |
| 1 byte | Parameter Conversion |
| 2 bytes | Parameter Minimum Settable Value |
| 2 bytes | Parameter Maximum Settable Value |
| 2 bytes | Parameter Default Value |
| 2 bytes | CRC-16 |

The Parameter Descriptor field is defined in *Table E.23*.

Table E.23 60h Read Parameter Descriptor Field Definition

| Bit | Name | Description |
|-----|--------------------------|--|
| 0 | RO: Read-only | 1 when the setting is read-only |
| 1 | H: Hidden | 1 when the setting is hidden |
| 2 | DBL: 32-bit | 1 when the following setting is a fractional value of this setting |
| 3 | RA: RAM-only | 1 when the setting is not saved in nonvolatile memory |
| 4 | RR: Read-only if running | 1 when the setting is read-only if in running/operational state |
| 5 | P: Power Cycle or Reset | 1 when the setting change requires a power cycle or reset |
| 6 | 0 | Reserved |
| 7 | Extend | Reserved to extend the descriptor table |

The Parameter Conversion field is defined in *Table E.24*.

Table E.24 60h Read Parameter Conversion Field Definition

| Conversion Value | Type | Multiplier | Divisor | Offset | Base |
|------------------|------------------|------------|---------|--------|------|
| 0 | Boolean | 1 | 1 | 0 | 1 |
| 1 | Unsigned Integer | 1 | 1 | 0 | 1 |
| 2 | Unsigned Integer | 1 | 10 | 0 | 1 |
| 3 | Unsigned Integer | 1 | 100 | 0 | 1 |
| 4 | Unsigned Integer | 1 | 1000 | 0 | 1 |
| 5 | Hexadecimal | 1 | 1 | 0 | 1 |
| 6 | Integer | 1 | 1 | 0 | 1 |
| 7 | Integer | 1 | 10 | 0 | 1 |
| 8 | Integer | 1 | 100 | 0 | 1 |
| 9 | Integer | 1 | 1000 | 0 | 1 |
| 10 | Enumeration | 1 | 1 | 0 | 1 |
| 11 | Bit Enumeration | 1 | 1 | 0 | 1 |

Use *Table E.25* to calculate the actual (not scaled) value of the parameter (setting):

$$\text{value} = \frac{(\text{ParameterValue} + \text{Offset}) \cdot \text{Multiplier} \cdot \text{Base}}{\text{Divisor}} \quad \text{Equation E.1}$$

Use *Table E.25* to calculate the scaled setting value:

$$\text{value} = \frac{\text{value} \cdot \text{Divisor}}{\text{Multiplier} \cdot \text{Base}} - \text{Offset} \quad \text{Equation E.2}$$

The relay response to errors in the query are shown *Table E.25*.

Table E.25 Responses to 60h Read Parameter Information Query Errors

| Error | Error Code Returned | Communication Counter Increments |
|---------------------------|-----------------------|----------------------------------|
| Illegal parameter to read | Illegal Address (02h) | Invalid Address |

61h Read Parameter Text Command

The SEL-787 uses this function to allow a Modbus master to read parameter text from the relay. One parameter text (setting name) is read in each query.

Table E.26 61h Read Parameter Text Command

| Bytes | Field |
|--|-------------------------------|
| Queries from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (61h) |
| 2 bytes | Parameter Number |
| 2 bytes | CRC-16 |
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (61h) |
| 2 bytes | Parameter Number |
| 16 bytes | Parameter Text (setting name) |
| 4 bytes | Parameter Units (e.g., Amps) |
| 2 bytes | CRC-16 |

The relay responses to errors in the query are shown in *Table E.27*.

Table E.27 61h Read Parameter Text Query Error Messages

| Error | Error Code Returned | Communication Counter Increments |
|---------------------------|-----------------------|----------------------------------|
| Illegal parameter to read | Illegal Address (02h) | Invalid Address |

62h Read Enumeration Text Command

The SEL-787 uses this function to allow a Modbus master to read parameter enumeration or bit enumeration values (setting lists) from the relay. One parameter enumeration is read in each query.

Table E.28 62h Read Enumeration Text Command

| Bytes | Field |
|--|---------------------|
| Queries from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (62h) |
| 2 bytes | Parameter Number |
| 1 byte | Enumeration Index |
| 2 bytes | CRC-16 |
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (62h) |
| 2 bytes | Parameter Number |
| 1 byte | Enumeration Index |
| 16 bytes | Enumeration Text |
| 2 bytes | CRC-16 |

The relay responses to errors in the query are shown in *Table E.29*.

Table E.29 61h Read Parameter Enumeration Text Query Error Messages

| Error | Error Code Returned | Communication Counter Increments |
|------------------------------|--------------------------|----------------------------------|
| Illegal parameter to read | Illegal Address (02h) | Invalid Address |
| Illegal enumeration in index | Illegal Data Value (03h) | Illegal Register |

7Dh Encapsulated Packet With Control Command

The SEL-787 uses this function to allow a Modbus master to perform control operations and another Modbus function with one query. The Device Net card will transmit this command periodically to achieve high-speed I/O processing and establish a heartbeat between the DeviceNet card and the main board.

Table E.30 7Dh Encapsulated Packet With Control Command

| Bytes | Field |
|--|---|
| Queries from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (7Dh) |
| 2 bytes | Control Command (same as write to 2000h) |
| 1 byte | Embedded Modbus Function |
| <i>n</i> bytes | Optional Data to Support Modbus Function (0–250) |
| 2 bytes | CRC-16 |
| A successful response from the slave will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (7Dh) |
| 2 bytes | Status Information (Register 2100h or 2101h based on Bit 3 in Control Command Word) |
| 1 byte | Embedded Modbus Function |
| <i>n</i> bytes | Optional data to support the Modbus function (0–250) |
| 2 bytes | CRC-16 |

Table E.31 shows the format of the relay responses to errors in the query.

Table E.31 7Dh Encapsulated Packet Query Errors

| Bytes | Field |
|---|---|
| Queries from the master must have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (7Dh) |
| 2 bytes | Status Information (Register 2100h or 2101h based on Bit 3 in Control Command Word) |
| 1 byte | Modbus Function with Error Flag |
| 1 bytes | Function Error Code ^a |
| 2 bytes | CRC-16 |

^a If the embedded function code is invalid, then an illegal function code is returned here and the illegal function counter is incremented. This error code is returned by the embedded function for all valid embedded functions.

7Eh NOP Command

This function code has no operation. This allows a Modbus master to perform a control operation without any other Modbus command. This is only used inside of the 7Dh when no regular Modbus query is required.

Table E.32 7Eh NOP Command

| Bytes | Field |
|--|---------------------|
| An example of a 7D message response using 7E will have the following format: | |
| 1 byte | Slave Address |
| 1 byte | Function Code (7Dh) |
| 2 bytes | Status Information |
| 1 byte | Function Code (7Eh) |
| 2 bytes | CRC-16 |

Reading Parameter Information and Value Using Modbus

Through use of Modbus commands, you can read the present value of a parameter as well as parameter name, units, low limit, high limit, scale, and even the enumeration string (if the parameter is an enumeration type). This means that you can use a general user interface to retrieve and display specific parameter details from the relay. Use the **60h**, **61h**, and **62h** commands to retrieve parameter information, and use the **03** command to retrieve values.

Modifying Relay Settings Using Modbus

The SEL-787 does not provide password protection. It is assumed that because the interface is a binary protocol with CRC-16 protection, the interface is being handled by an intelligent master system. Therefore, the master would provide password protection.

Any of the settings listed in the Modbus Register Map (*Table E.34*) can be changed. The high and low limits provided in the table might cover a wider range than what is acceptable by the particular model or configuration. The settings are not saved as and when they are received. The relay acknowledges the write operation, but it does not change the relay settings. The relay holds these settings until there are no further edits for a time specified by SETTINGS TIMEOUT register (4010h). After this timeout, the relay attempts to save the settings. If there are no errors, the settings are saved. If, however, a setting interdependency rule is violated, the settings are not saved. The relay will set the Config Fault bit in the TRIP STATUS HI register to indicate that the save settings operation has failed. The relay will also set ERROR REGISTER (4016h) flags to indicate the type of error and ERROR ADDRESS Register to indicate the register that caused the issue.

Parameters such as date and time can be changed with the appropriate registers by using Modbus Function Code 06h or 10h.

The ability to change the settings via Modbus protocol can be blocked by the Global Setting BLKMBSET or the BLOCK MODBUS SET register.

Controlling Output Contacts Using Modbus

The SEL-787 includes registers for controlling some of the outputs. See LOGIC COMMAND (2000h), RESET COMMAND (2001h), and registers in the Reset Settings region for the control features supported by the relay. Use Modbus function codes 06h or 10h to write appropriate flags. Remember that when writing to the Logic command register with output contacts, it is not a bit operation. All the bits in that register need to be written together to reflect the state you want for each of the outputs.

User-Defined Modbus Data Region and SET M Command

The SEL-787 Modbus Register Map defines an area of 125 contiguous addresses whose contents are defined by 125 user-settable addresses. This feature allows you to take 125 discrete values from anywhere in the Modbus Register Map and place them in contiguous registers that you can then read in a single command. SEL ASCII command **SET M** provides a convenient method to define the user map addresses. The user map can also be defined by writing to user map registers MOD_001 to MOD_125.

To use the user-defined data region, follow the steps listed below.

- Step 1. Define the list of desired quantities (as many as 125). Arrange the quantities in any order that is convenient for you to use.
- Step 2. Refer to *Table E.33* for a list of the Modbus label for each quantity.
- Step 3. Execute **SET M** command from the command line to map user registers 001 to 125 (MOD_001 to MOD_125) using the labels in *Table E.33*.

Note that this step can also be performed using Modbus protocol. Use Modbus Function Code 06h to write to registers MOD_001 through MOD_125.

- Step 4. Use Modbus function code 03h or 04h to read the desired quantities from addresses 126 through 250 (user map values).

Table E.33 Modbus Register Labels for Use With SET M Command (Sheet 1 of 3)

| Register Address | Label | Register Address | Label | Register Address | Label | Register Address | Label |
|----------------------|----------|----------------------|----------|----------------------|----------|------------------|----------|
| 644 | FPGA | 697 | IBW2_ANG | 745 | ENRGY_Y | 808 | IBW1RMS |
| 645 | GPSB | 698 | ICW2_MAG | 746–753 ^a | | 809 | ICW1RMS |
| 646 | HMI | 699 | ICW2_ANG | 754 | IAD | 810 | IAW2RMS |
| 647 | RAM | 700 | IGW2_MAG | 755 | IBD | 811 | IBW2RMS |
| 648 | ROM | 701 | IGW2_ANG | 756 | ICD | 812 | ICW2RMS |
| 649 | CR_RAM | 702 | 3I2W2MAG | 757 | IGD | 813 | INRMS |
| 650 | NON_VOL | 703 | IADV2MAG | 758 | 3I2D | 814 | VARMS |
| 651 | CLKSTS | 704 | IN_MAG | 759 | IAPD | 815 | VBRMS |
| 652 | CID_FILE | 705 | IN_ANG | 760 | IBPD | 816 | VCRMS |
| 653 | RTD | 706–708 ^a | | 761 | ICPD | 817 | VABRMS |
| 654 | P3P3PS | 709 | VAB_MAG | 762 | IGPD | 818 | VBCRMS |
| 655 | P5PS | 710 | VAB_ANG | 763 | 3I2PD | 819 | VCARMS |
| 656 | P2P5PS | 711 | VBC_MAG | 764 | PDEM_R_S | 820 | IAW1MX |
| 657 | P3P75PS | 712 | VBC_ANG | 765 | PDEM_RMN | 821 | IAW1MN |
| 658 | N1P25PS | 713 | VCA_MAG | 766 | PDEM_R_H | 822 | IBW1MX |
| 659 | N5PS | 714 | VCA_ANG | 767 | PDEM_R_D | 823 | IBW1MN |
| 660 | CLKBAT | 715 | VAVE_MAG | 768 | PDEM_RMO | 824 | ICW1MX |
| 661 | CTBRD | 716 | VA_MAG | 769 | PDEM_R_Y | 825 | ICW1MN |
| 662 | CARDC | 717 | VA_ANG | 770 | IAW1_THD | 826 | IGW1MX |
| 663 | CARDD | 718 | VB_MAG | 771 | IBW1_THD | 827 | IGW1MN |
| 664 | CARDE | 719 | VB_ANG | 772 | ICW1_THD | 828 | IAW2MX |
| 665 | IAW1STS | 720 | VC_MAG | 773 | IAW2_THD | 829 | IAW2MN |
| 666 | IBW1STS | 721 | VC_ANG | 774 | IBW2_THD | 830 | IBW2MX |
| 667 | ICW1STS | 722 | VG_MAG | 775 | ICW2_THD | 831 | IBW2MN |
| 668 | IAW2STS | 723 | VG_ANG | 776 | VA_THD | 832 | ICW2MX |
| 669 | IBW2STS | 724 | VAVE_MAG | 777 | VB_THD | 833 | ICW2MN |
| 670 | ICW2STS | 725 | 3V2_MAG | 778 | VC_THD | 834 | IGW2MX |
| 671 | INSTS | 726 | P | 779 | VAB_THD | 835 | IGW2MN |
| 672 | VASTS | 727 | Q | 780 | VBC_THD | 836 | INMX |
| 673 | VBSTS | 728 | S | 781 | VCA_THD | 837 | INMN |
| 674 | VCSTS | 729 | PF | 782 | RTDAMB | 838 | VABMX |
| 675 | RLYSTS | 730 | VHZ | 783 | RTDOTHMX | 839 | VABMN |
| 676–683 ^a | | 731 | FREQ | 784 | RTD1 | 840 | VBCMX |
| 684 | IAW1_MAG | 732 | MWHPH | 785 | RTD2 | 841 | VBCMN |
| 685 | IAW1_ANG | 733 | MWHPL | 786 | RTD3 | 842 | VCAMX |
| 686 | IBW1_MAG | 734 | MWHNH | 787 | RTD4 | 843 | VCAMN |
| 687 | IBW1_ANG | 735 | MWHNL | 788 | RTD5 | 844 | KW3PMX |
| 688 | ICW1_MAG | 736 | MVRHPH | 789 | RTD6 | 845 | KW3PMN |
| 689 | ICW1_ANG | 737 | MVRHPL | 790 | RTD7 | 846 | KVAR3PMX |
| 690 | IGW1_MAG | 738 | MVRHNL | 791 | RTD8 | 847 | KVAR3PMN |
| 691 | IGW1_ANG | 739 | MVRHNL | 792 | RTD9 | 848 | KVA3PMX |
| 692 | 3I2W1MAG | 740 | ENRGY_S | 793 | RTD10 | 849 | KVA3PMN |
| 693 | IADV1MAG | 741 | ENRGYMN | 794 | RTD11 | 850 | FREQMX |
| 694 | IAW2_MAG | 742 | ENRGY_H | 795 | RTD12 | 851 | FREQMN |
| 695 | IAW2_ANG | 743 | ENRGY_D | 796–806 ^a | | 852 | RTD1MX |
| 696 | IBW2_MAG | 744 | ENRGYMO | 807 | IAW1RMS | 853 | RTD1MN |

Table E.33 Modbus Register Labels for Use With SET M Command (Sheet 2 of 3)

| Register Address | Label | Register Address | Label | Register Address | Label | Register Address | Label |
|------------------|----------|----------------------|----------|----------------------|--------|------------------|-------|
| 854 | RTD2MX | 900 | AI403MXH | 955 | AI404L | 1006 | MV19H |
| 855 | RTD2MN | 901 | AI403MXL | 956 | AI501H | 1007 | MV19L |
| 856 | RTD3MX | 902 | AI403MNH | 957 | AI501L | 1008 | MV20H |
| 857 | RTD3MN | 903 | AI403MNL | 958 | AI502H | 1009 | MV20L |
| 858 | RTD4MX | 904 | AI403MXH | 959 | AI502L | 1010 | MV21H |
| 859 | RTD4MN | 905 | AI403MXL | 960 | AI503H | 1011 | MV21L |
| 860 | RTD5MX | 906 | AI404MNH | 961 | AI503L | 1012 | MV22H |
| 861 | RTD5MN | 907 | AI404MNL | 962 | AI504H | 1013 | MV22L |
| 862 | RTD6MX | 908 | AI501MXH | 963 | AI504L | 1014 | MV23H |
| 863 | RTD6MN | 909 | AI501MXL | 964–969 ^a | | 1015 | MV23L |
| 864 | RTD7MX | 910 | AI501MNH | 970 | MV01H | 1016 | MV24H |
| 865 | RTD7MN | 911 | AI501MNL | 971 | MV01L | 1017 | MV24L |
| 866 | RTD8MX | 912 | AI502MXH | 972 | MV02H | 1018 | MV25H |
| 867 | RTD8MN | 913 | AI502MXL | 973 | MV02L | 1019 | MV25L |
| 868 | RTD9MX | 914 | AI502MNH | 974 | MV03H | 1020 | MV26H |
| 869 | RTD9MN | 915 | AI502MNL | 975 | MV03L | 1021 | MV26L |
| 870 | RTD10MX | 916 | AI503MXH | 976 | MV04H | 1022 | MV27H |
| 871 | RTD10MN | 917 | AI503MXL | 977 | MV04L | 1023 | MV27L |
| 872 | RTD11MX | 918 | AI503MNH | 978 | MV05H | 1024 | MV28H |
| 873 | RTD11MN | 919 | AI503MNL | 979 | MV05L | 1025 | MV28L |
| 874 | RTD12MX | 920 | AI504MXH | 980 | MV06H | 1026 | MV29H |
| 875 | RTD12MN | 921 | AI504MXL | 981 | MV06L | 1027 | MV29L |
| 876 | AI301MXH | 922 | AI504MNH | 982 | MV07H | 1028 | MV30H |
| 877 | AI301MXL | 923 | AI504MNL | 983 | MV07L | 1029 | MV30L |
| 878 | AI301MNH | 924 | MXMN_R_S | 984 | MV08H | 1030 | MV31H |
| 879 | AI301MNL | 925 | MXMN_RMN | 985 | MV08L | 1031 | MV31L |
| 880 | AI302MXH | 926 | MXMN_R_H | 986 | MV09H | 1032 | MV32H |
| 881 | AI302MXL | 927 | MXMN_R_D | 987 | MV09L | 1033 | MV32L |
| 882 | AI302MNH | 928 | MXMN_RMO | 988 | MV10H | 1034 | SC01 |
| 883 | AI302MNL | 929 | MXMN_R_Y | 989 | MV10L | 1035 | SC02 |
| 884 | AI303MXH | 930–939 ^a | | 990 | MV11H | 1036 | SC03 |
| 885 | AI303MXL | 940 | AI301H | 991 | MV11L | 1037 | SC04 |
| 886 | AI303MNH | 941 | AI301L | 992 | MV12H | 1038 | SC05 |
| 887 | AI303MNL | 942 | AI302H | 993 | MV12L | 1039 | SC06 |
| 888 | AI304MXH | 943 | AI302L | 994 | MV13H | 1040 | SC07 |
| 889 | AI304MXL | 944 | AI303H | 995 | MV13L | 1041 | SC08 |
| 890 | AI304MNH | 945 | AI303L | 996 | MV14H | 1042 | SC09 |
| 891 | AI304MNL | 946 | AI304H | 997 | MV14L | 1043 | SC10 |
| 892 | AI401MXH | 947 | AI304L | 998 | MV15H | 1044 | SC11 |
| 893 | AI401MXL | 948 | AI401H | 999 | MV15L | 1045 | SC12 |
| 894 | AI401MNH | 949 | AI401L | 1000 | MV16H | 1046 | SC13 |
| 895 | AI401MNL | 950 | AI402H | 1001 | MV16L | 1047 | SC14 |
| 896 | AI402MXH | 951 | AI402L | 1002 | MV17H | 1048 | SC15 |
| 897 | AI402MXL | 952 | AI403H | 1003 | MV17L | 1049 | SC16 |
| 898 | AI402MNH | 953 | AI403L | 1004 | MV18H | 1050 | SC17 |
| 899 | AI402MNL | 954 | AI404H | 1005 | MV18L | 1051 | SC18 |

Table E.33 Modbus Register Labels for Use With SET M Command (Sheet 3 of 3)

| Register Address | Label | Register Address | Label | Register Address | Label | Register Address | Label |
|------------------------|----------|------------------------|---------|------------------|--------|--|---------|
| 1052 | SC19 | 1119 | WARN_LO | 1174 | ROW_32 | 1220 | ROW_78 |
| 1053 | SC20 | 1120 | WARN_HI | 1175 | ROW_33 | 1221 | ROW_79 |
| 1054 | SC21 | 1121–1125 ^a | | 1176 | ROW_34 | 1222 | ROW_80 |
| 1055 | SC22 | 1126 | NUMRCV | 1177 | ROW_35 | 1223 | ROW_81 |
| 1056 | SC23 | 1127 | NUMOTH | 1178 | ROW_36 | 1224 | ROW_82 |
| 1057 | SC24 | 1128 | INVADR | 1179 | ROW_37 | 1225 | ROW_83 |
| 1058 | SC25 | 1129 | BADCRC | 1180 | ROW_38 | 1226 | ROW_84 |
| 1059 | SC26 | 1130 | UARTERR | 1181 | ROW_39 | 1227 | ROW_85 |
| 1060 | SC27 | 1131 | ILLFUNC | 1182 | ROW_40 | 1228 | ROW_86 |
| 1061 | SC28 | 1132 | ILLREG | 1183 | ROW_41 | 1229 | ROW_87 |
| 1062 | SC29 | 1133 | ILLWR | 1184 | ROW_42 | 1230 | ROW_88 |
| 1063 | SC30 | 1134 | BADPKTF | 1185 | ROW_43 | 1231 | ROW_89 |
| 1064 | SC31 | 1135 | BADPKTL | 1186 | ROW_44 | 1232 | ROW_90 |
| 1065 | SC32 | 1136–1141 ^a | | 1187 | ROW_45 | 1233 | ROW_91 |
| 1066–1081 ^a | | 1142 | ROW_0 | 1188 | ROW_46 | 1234 | ROW_92 |
| 1082 | NUMEVE | 1143 | ROW_1 | 1189 | ROW_47 | 1235 | ROW_93 |
| 1083 | EVESEL | 1144 | ROW_2 | 1190 | ROW_48 | 1236 | ROW_94 |
| 1084 | EVE_S | 1145 | ROW_3 | 1191 | ROW_49 | 1237 | ROW_95 |
| 1085 | EVEMN | 1146 | ROW_4 | 1192 | ROW_50 | 1238 | ROW_96 |
| 1086 | EVE_H | 1147 | ROW_5 | 1193 | ROW_51 | 1239 | ROW_97 |
| 1087 | EVE_D | 1148 | ROW_6 | 1194 | ROW_52 | 1240 | ROW_98 |
| 1088 | EVEMO | 1149 | ROW_7 | 1195 | ROW_53 | 1241 | ROW_99 |
| 1089 | EVE_Y | 1150 | ROW_8 | 1196 | ROW_54 | 1242 | ROW_100 |
| 1090 | EVE_TYPE | 1151 | ROW_9 | 1197 | ROW_55 | 1243 | ROW_101 |
| 1091 | EVE_TRGT | 1152 | ROW_10 | 1198 | ROW_56 | 1244 | ROW_102 |
| 1092 | EVE_IAW1 | 1153 | ROW_11 | 1199 | ROW_57 | 1245 | ROW_103 |
| 1093 | EVE_IBW1 | 1154 | ROW_12 | 1200 | ROW_58 | 1246 | ROW_104 |
| 1094 | EVE_ICW1 | 1155 | ROW_13 | 1201 | ROW_59 | 1247 | ROW_105 |
| 1095 | EVE_IGW1 | 1156 | ROW_14 | 1202 | ROW_60 | 1248 | ROW_106 |
| 1096 | EVE_IAW2 | 1157 | ROW_15 | 1203 | ROW_61 | 1249 | NA |
| 1097 | EVE_IBW2 | 1158 | ROW_16 | 1204 | ROW_62 | ^a All the reserved registers between the data areas in the map may also be assigned to the user registers with a label RES_xxxx, where xxxx is the register number. | |
| 1098 | EVE_ICW2 | 1159 | ROW_17 | 1205 | ROW_63 | | |
| 1099 | EVE_IGW2 | 1160 | ROW_18 | 1206 | ROW_64 | | |
| 1100 | EVE_IN | 1161 | ROW_19 | 1207 | ROW_65 | | |
| 1101 | EVE_VAB | 1162 | ROW_20 | 1208 | ROW_66 | | |
| 1102 | EVE_VBC | 1163 | ROW_21 | 1209 | ROW_67 | | |
| 1103 | EVE_VCA | 1164 | ROW_22 | 1210 | ROW_68 | | |
| 1104 | EVE_VG | 1165 | ROW_23 | 1211 | ROW_69 | | |
| 1105 | EVE_DY | 1166 | ROW_24 | 1212 | ROW_70 | | |
| 1106 | EVE_FREQ | 1167 | ROW_25 | 1213 | ROW_71 | | |
| 1107 | EVE_MAXA | 1168 | ROW_26 | 1214 | ROW_72 | | |
| 1108 | EVE_MAXO | 1169 | ROW_27 | 1215 | ROW_73 | | |
| 1109 | RES_1109 | 1170 | ROW_28 | 1216 | ROW_74 | | |
| 1110–1116 ^a | | 1171 | ROW_29 | 1217 | ROW_75 | | |
| 1117 | TRIP_LO | 1172 | ROW_30 | 1218 | ROW_76 | | |
| 1118 | TRIP_HI | 1173 | ROW_31 | 1219 | ROW_77 | | |

Reading History Data Using Modbus

Through use of the Modbus Register Map (*Table E.34*), you can download a complete history of the last fifty events via Modbus. The history contains the date and time stamp, type of event that triggered the report, currents, and voltages at the time of the event. Please refer to the Historical Data section in the map.

To use Modbus to download history data, write the event number (1–50) to the EVENT LOG SEL register at address 1692 (when event number zero is written by accident for the first time, the relay treats the selected event number as one). Then, read the history of the specific event number you requested from the registers shown in the *Historical Data* section of the Modbus Register Map (*Table E.34*). After a power cycle, the history data registers show the history data corresponding to the latest event. This information updates dynamically. Whenever there is a new event, the history data registers update automatically with new event data. If specific event number data have been retrieved using a write to the EVENT LOG SEL register, the event data registers stay frozen with that specific event history. These registers return to the free running latest event history data mode when a zero is written to the event selection register from a prior nonzero selection.

Modbus Register Map

Table E.34 lists the data available in the Modbus interface and its description, range, and scaling information. The table also shows the parameter number for access using the DeviceNet interface. The DeviceNet parameter number is obtained by adding 100 to the Modbus register address.

Table E.34 Modbus Register Map^a (Sheet 1 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|---------------------------------|-------|-----|-------|------|--------------|-----------------------------|
| 0 (R) | Reserved ^c | | 0 | 100 | 1 | | |
| User Map Register | | | | | | | |
| 1 (R/W) | USER REG #1 | | 644 | 1249 | 684 | 1 | 101 |
| | • | | | | | | |
| | • | | | | | | |
| | • | | | | | | |
| 125 (R/W) | USER REG #125 | | 644 | 1249 | 1249 | 1 | 225 |
| User Map Reg Val | | | | | | | |
| 126–250 (R) | USER REG#1 VAL–USER REG#125 VAL | | 0 | 65535 | 0 | 1 | 226–350 |
| 251–259 (R) | Reserved ^c | | 0 | 0 | 0 | | 351–359 |
| Access Control | | | | | | | |
| 260 (R/W) | BLOCK MODBUS SET | | 0 | 2 | 0 | | 360 |
| | 0 = NONE | | | | | | |
| | 1 = R_S | | | | | | |
| | 2 = ALL | | | | | | |
| General Settings | | | | | | | |
| 261 (R/W) | PHASE ROTATION | | 0 | 1 | 0 | | 361 |
| | 0 = ABC | | | | | | |
| | 1 = ACB | | | | | | |

Table E.34 Modbus Register Map^a (Sheet 2 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--|-------|-----|-------|------|--------------|-----------------------------|
| 262 (R/W) | RATED FREQ. 0 = 50 1 = 60 | Hz | 0 | 1 | 1 | | 362 |
| 263 (R/W) | DATE FORMAT 0 = MDY 1 = YMD 2 = DMY | | 0 | 2 | 0 | | 363 |
| 264 (R/W) | EVE MSG PTS EN | | 0 | 32 | 0 | 1 | 364 |
| Group Selection | | | | | | | |
| 265 (R/W) | GRP CHG DELAY | sec | 0 | 400 | 3 | 1 | 365 |
| Breaker Failure Set | | | | | | | |
| 266 (R/W) | 52A INTERLOCK 0 = N 1 = Y | | 0 | 1 | 0 | | 366 |
| 267 (R/W) | BRKR1 FAIL DELAY | sec | 0 | 200 | 50 | 0.01 | 367 |
| 268 (R/W) | BRKR2 FAIL DELAY | sec | 0 | 200 | 50 | 0.01 | 368 |
| Through-Fault Set | | | | | | | |
| 269 (R/W) | THR FLT WDG 0 = OFF 1 = 1 2 = 2 | | 0 | 2 | 0 | | 369 |
| 270 (R/W) | THR FLT ALARM PU | % | 500 | 9000 | 1000 | 0.1 | 370 |
| 271 (R/W) | XFMR IMPEDANCE | % | 20 | 400 | 100 | 0.1 | 371 |
| 272 (R/W) | IRIG TIME SOURCE 0 = IRIG1 1 = IRIG2 | | 0 | 1 | 0 | | 372 |
| 273–275 (R) | Reserved ^c | | 0 | 0 | 0 | | 373–375 |
| Configuration Settings | | | | | | | |
| 276 (R/W) | WDG1 CT CONN 0 = DELTA 1 = WYE | | 0 | 1 | 1 | | 376 |
| 277 (R/W) | WDG2 CT CONN 0 = DELTA 1 = WYE | | 0 | 1 | 1 | | 377 |
| 278 (R/W) | WDG1 PHASE CTR | | 1 | 50000 | 100 | 1 | 378 |
| 279 (R/W) | WDG2 PHASE CTR | | 1 | 50000 | 1000 | 1 | 379 |
| 280 (R/W) | MVA SET ENABLE | | 0 | 1 | 1 | | 380 |
| 281 (R/W) | MAX XFMR CAP | MVA | 2 | 50000 | 500 | 0.1 | 381 |
| 282 (R/W) | DEFINE CT COMP 0 = N 1 = Y | | 0 | 1 | 0 | | 382 |
| 283 (R/W) | WDG1 CT COMP | | 0 | 12 | 12 | 1 | 383 |
| 284 (R/W) | WDG2 CT COMP | | 0 | 12 | 12 | 1 | 384 |
| 285 (R/W) | WDG1 L-L INT KV | kV | 0 | 1000 | 138 | 1 | 385 |
| 286 (R/W) | WDG1 L-L FRAC KV | kV | 0 | 99 | 0 | 0.01 | 386 |
| 287 (R/W) | WDG2 L-L INT KV | kV | 0 | 1000 | 13 | 1 | 387 |
| 288 (R/W) | WDG2 L-L FRAC KV | kV | 0 | 99 | 80 | 0.01 | 388 |
| 289 (R/W) | NEUT1 CT RATIO | | 1 | 50000 | 120 | 1 | 389 |
| 290 (R/W) | PHASE PT RATIO | | 1 | 10000 | 120 | 1 | 390 |
| 291 (R/W) | PHASE PTR FRAC | | 0 | 99 | 0 | 0.01 | 391 |
| 292 (R/W) | VNOM INT KV | kV | 0 | 1000 | 13 | 1 | 392 |

Table E.34 Modbus Register Map^a (Sheet 3 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--|---------------------------------------|-------|-----|------|-----|--------------|-----------------------------|
| 293 (R/W) | VNOM FRAC ICV | kV | 0 | 99 | 80 | 0.01 | 393 |
| 294 (R/W) | PT CONNECTION 0 = DELTA 1 = WYE | | 0 | 1 | 0 | | 394 |
| 295 (R/W) | VOLT-CURR WDG | | 1 | 2 | 2 | 1 | 395 |
| 296 (R/W) | COMP ANGLE | Deg | 0 | 360 | 0 | 1 | 396 |
| 297 (R/W) | SINGLE V INPUT 0 = N 1 = Y | | 0 | 1 | 0 | | 397 |
| Transformer Differential (Xfmr Differential) | | | | | | | |
| 298 (R/W) | XFMR DIFF ENABLE 0 = N 1 = Y | | 0 | 1 | 1 | | 398 |
| 299 (R/W) | WDG1 CURR TAP | A | 10 | 3100 | 100 | 0.01 | 399 |
| 300 (R/W) | WDG2 CURR TAP | A | 10 | 3100 | 100 | 0.01 | 400 |
| 301 (R/W) | OPERATE CURR LVL | pu | 10 | 100 | 30 | 0.01 | 401 |
| 302 (R/W) | 87A ENABLE 0 = N 1 = Y | | 0 | 1 | 1 | | 402 |
| 303 (R/W) | DIFF CURR AL LVL | pu | 5 | 100 | 15 | 0.01 | 403 |
| 304 (R/W) | DIFF CURR AL DLY | sec | 10 | 1200 | 50 | 0.1 | 404 |
| 305 (R/W) | RESTRAINT SLOPE1 | % | 5 | 90 | 25 | 1 | 405 |
| 306 (R) | Reserved ^c | | 0 | 0 | 0 | | 406 |
| 307 (R/W) | RESTRAINT SLOPE2 | % | 5 | 90 | 70 | 1 | 407 |
| 308 (R/W) | RES SLOPE1 LIMIT | pu | 10 | 200 | 30 | 0.1 | 408 |
| 309 (R/W) | UNRES CURR LVL | pu | 10 | 200 | 100 | 0.1 | 409 |
| 310 (R/W) | PCT2 ENABLE 0 = N 1 = Y | | 0 | 1 | 1 | | 410 |
| 311 (R/W) | 2ND HARM BLOCK | % | 5 | 100 | 15 | 1 | 411 |
| 312 (R/W) | PCT4 ENABLE 0 = N 1 = Y | | 0 | 1 | 1 | | 412 |
| 313 (R/W) | 4TH HARM BLOCK | % | 5 | 100 | 15 | 1 | 413 |
| 314 (R/W) | PCT5 ENABLE 0 = N 1 = Y | | 0 | 1 | 1 | | 414 |
| 315 (R/W) | 5TH HARM BLOCK | % | 5 | 100 | 35 | 1 | 415 |
| 316 (R/W) | TH5 ENABLE 0 = N 1 = Y | | 0 | 1 | 0 | | 416 |
| 317 (R/W) | 5TH HARM AL LVL | pu | 2 | 320 | 10 | 0.01 | 417 |
| 318 (R/W) | 5TH HARM AL DLY | sec | 0 | 1200 | 10 | 0.1 | 418 |
| 319 (R/W) | HARMONIC RESTRNT 0 = N 1 = Y | | 0 | 1 | 1 | | 419 |
| 320 (R/W) | HARM BLOCK 0 = N 1 = Y | | 0 | 1 | 0 | | 420 |
| 321 (R) | Reserved ^c | | 0 | 0 | 0 | | 421 |

Table E.34 Modbus Register Map^a (Sheet 4 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|---|---|-------|-----|------|-----|--------------|-----------------------------|
| Restricted Earth Fault | | | | | | | |
| 322 (R/W) | POL QTY FROM WDG 0 = OFF 1 = 1 2 = 2 3 = 12 | | 0 | 3 | 0 | | 422 |
| 323 (R/W) | REF1 CURR LEVEL | pu | 5 | 300 | 25 | 0.01 | 423 |
| Winding 1 Maximum Phase Instantaneous Overcurrent (WDG1 Max Ph IOC) | | | | | | | |
| 324 (R/W) | WDG1 IOC L1 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 424 |
| 325 (R/W) | PHASE IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 425 |
| 326 (R/W) | PHASE IOC DELAY | sec | 0 | 500 | 0 | 0.01 | 426 |
| 327 (R/W) | WDG1 IOC L2 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 427 |
| 328 (R/W) | PHASE IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 428 |
| 329 (R/W) | PHASE IOC DELAY | sec | 0 | 500 | 0 | 0.01 | 429 |
| 330 (R/W) | WDG1 IOC L3 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 430 |
| 331 (R/W) | PHASE IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 431 |
| 332 (R/W) | PHASE IOC DELAY | sec | 0 | 500 | 0 | 0.01 | 432 |
| 333 (R/W) | WDG1 IOC L4 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 433 |
| 334 (R/W) | PHASE IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 434 |
| 335 (R/W) | PHASE IOC DELAY | sec | 0 | 500 | 0 | 0.01 | 435 |
| Winding 1 Residual Instantaneous Overcurrent (WDG1 Res IOC) | | | | | | | |
| 336 (R/W) | WDG1 RESIOC L1EN 0 = N 1 = Y | | 0 | 1 | 0 | | 436 |
| 337 (R/W) | RES IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 437 |
| 338 (R/W) | RES IOC DELAY | sec | 0 | 500 | 50 | 0.01 | 438 |
| 339 (R/W) | WDG1 RESIOC L2EN 0 = N 1 = Y | | 0 | 1 | 0 | | 439 |
| 340 (R/W) | RES IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 440 |
| 341 (R/W) | RES IOC DELAY | sec | 0 | 500 | 50 | 0.01 | 441 |
| Winding 1 Negative-Sequence Instantaneous Overcurrent (WDG1 Neg Seq IOC) | | | | | | | |
| 342 (R/W) | W1 NSEQ IOC L1EN 0 = N 1 = Y | | 0 | 1 | 0 | | 442 |
| 343 (R/W) | NSEQ IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 443 |
| 344 (R/W) | NSEQ IOC DELAY | sec | 1 | 1200 | 2 | 0.1 | 444 |
| 345 (R/W) | W1 NSEQ IOC L2EN 0 = N 1 = Y | | 0 | 1 | 0 | | 445 |
| 346 (R/W) | NSEQ IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 446 |
| 347 (R/W) | NSEQ IOC DELAY | sec | 1 | 1200 | 2 | 0.1 | 447 |

Table E.34 Modbus Register Map^a (Sheet 5 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|---|---|-------|-----|------|-----|--------------|-----------------------------|
| Winding 1 Maximum Phase Time-Overcurrent (WDG1 Max Ph TOC) | | | | | | | |
| 348 (R/W) | WDG1 TOC ENABLE 0 = N 1 = Y | | 0 | 1 | 0 | | 448 |
| 349 (R/W) | PHASE TOC LEVEL | A | 10 | 1600 | 120 | 0.01 | 449 |
| 350 (R/W) | PHASE TOC CURVE 0 = U1 5 = C1 1 = U2 6 = C2 2 = U3 7 = C3 3 = U4 8 = C4 4 = U5 9 = C5 | | 0 | 9 | 2 | | 450 |
| 351 (R/W) | PHASE TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 451 |
| 352 (R/W) | EM RESET DELAY 0 = N 1 = Y | | 0 | 1 | 0 | | 452 |
| 353 (R/W) | CONST TIME ADDER | sec | 0 | 100 | 0 | 0.01 | 453 |
| 354 (R/W) | MIN RESPONSE TIM | sec | 0 | 100 | 0 | 0.01 | 454 |
| Winding 1 Residual Time Overcurrent (WDG1 Res TOC) | | | | | | | |
| 355 (R/W) | WDG1 RES TOC EN 0 = N 1 = Y | | 0 | 1 | 0 | | 455 |
| 356 (R/W) | RES TOC LEVEL | A | 10 | 1600 | 10 | 0.01 | 456 |
| 357 (R/W) | RES TOC CURVE 0 = U1 5 = C1 1 = U2 6 = C2 2 = U3 7 = C3 3 = U4 8 = C4 4 = U5 9 = C5 | | 0 | 9 | 2 | | 457 |
| 358 (R/W) | RES TOC TDIAL | | 5 | 1500 | 150 | 0.01 | 458 |
| 359 (R/W) | EM RESET DELAY 0 = N 1 = Y | | 0 | 1 | 0 | | 459 |
| 360 (R/W) | CONST TIME ADDER | sec | 0 | 100 | 0 | 0.01 | 460 |
| 361 (R/W) | MIN RESPONSE TIM | sec | 0 | 100 | 0 | 0.01 | 461 |
| Winding 1 Negative-Sequence Time-Overcurrent (WDG1 Neq Seq TOC) | | | | | | | |
| 362 (R/W) | WDG1 NSEQ TOC EN 0 = N 1 = Y | | 0 | 1 | 0 | | 462 |
| 363 (R/W) | NSEQ TOC LEVEL | A | 10 | 1600 | 120 | 0.01 | 463 |
| 364 (R/W) | NSEQ TOC CURVE 0 = U1 5 = C1 1 = U2 6 = C2 2 = U3 7 = C3 3 = U4 8 = C4 4 = U5 9 = C5 | | 0 | 9 | 2 | | 464 |
| 365 (R/W) | NSEQ TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 465 |
| 366 (R/W) | EM RESET DELAY 0 = N 1 = Y | | 0 | 1 | 0 | | 466 |
| 367 (R/W) | CONST TIME ADDER | sec | 0 | 100 | 0 | 0.01 | 467 |
| 368 (R/W) | MIN RESPONSE TIM | sec | 0 | 100 | 0 | 0.01 | 468 |
| Winding 2 Maximum Phase Instantaneous Overcurrent (WDG2 Max Ph IOC) | | | | | | | |
| 369 (R/W) | WDG2 IOC L1 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 469 |

Table E.34 Modbus Register Map^a (Sheet 6 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--|---|-------|-----|------|-----|--------------|-----------------------------|
| 370 (R/W) | PHASE IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 470 |
| 371 (R/W) | PHASE IOC DELAY | sec | 0 | 500 | 0 | 0.01 | 471 |
| 372 (R/W) | WDG2 IOC L2 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 472 |
| 373 (R/W) | PHASE IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 473 |
| 374 (R/W) | PHASE IOC DELAY | sec | 0 | 500 | 0 | 0.01 | 474 |
| 375 (R/W) | WDG2 IOC L3 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 475 |
| 376 (R/W) | PHASE IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 476 |
| 377 (R/W) | PHASE IOC DELAY | sec | 0 | 500 | 0 | 0.01 | 477 |
| 378 (R/W) | WDG2 IOC L4 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 478 |
| 379 (R/W) | PHASE IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 479 |
| 380 (R/W) | PHASE IOC DELAY | sec | 0 | 500 | 0 | 0.01 | 480 |
| Winding 2 Residual Instantaneous Overcurrent (WDG2 Res IOC) | | | | | | | |
| 381 (R/W) | WDG2 RESIOC L1EN 0 = N 1 = Y | | 0 | 1 | 0 | | 481 |
| 382 (R/W) | RES IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 482 |
| 383 (R/W) | RES IOC DELAY | sec | 0 | 500 | 50 | 0.01 | 483 |
| 384 (R/W) | WDG2 RESIOC L2EN 0 = N 1 = Y | | 0 | 1 | 0 | | 484 |
| 385 (R/W) | RES IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 485 |
| 386 (R/W) | RES IOC DELAY | sec | 0 | 500 | 50 | 0.01 | 486 |
| Winding 2 Negative-Sequence Instantaneous Overcurrent (WDG2 Neg Seq IOC) | | | | | | | |
| 387 (R/W) | W2 NSEQ IOC L1EN 0 = N 1 = Y | | 0 | 1 | 0 | | 487 |
| 388 (R/W) | NSEQ IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 488 |
| 389 (R/W) | NSEQ IOC DELAY | sec | 1 | 1200 | 2 | 0.1 | 489 |
| 390 (R/W) | W2 NSEQ IOC L2EN 0 = N 1 = Y | | 0 | 1 | 0 | | 490 |
| 391 (R/W) | NSEQ IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 491 |
| 392 (R/W) | NSEQ IOC DELAY | sec | 1 | 1200 | 2 | 0.1 | 492 |
| Winding 2 Maximum Phase Time-Overcurrent (WDG2 Max Ph TOC) | | | | | | | |
| 393 (R/W) | WDG2 TOC ENABLE 0 = N 1 = Y | | 0 | 1 | 0 | | 493 |
| 394 (R/W) | PHASE TOC LEVEL | A | 10 | 1600 | 120 | 0.01 | 494 |
| 395 (R/W) | PHASE TOC CURVE 0 = U1 1 = U2 2 = U3 3 = U4 4 = U5 5 = C1 6 = C2 7 = C3 8 = C4 9 = C5 | | 0 | 9 | 2 | | 495 |
| 396 (R/W) | PHASE TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 496 |
| 397 (R/W) | EM RESET DELAY | | 0 | 1 | 0 | | 497 |

Table E.34 Modbus Register Map^a (Sheet 7 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|---|--|-------|-----|------|-----|--------------|-----------------------------|
| | 0 = N 1 = Y | | | | | | |
| 398 (R/W) | CONST TIME ADDER | sec | 0 | 100 | 0 | 0.01 | 498 |
| 399 (R/W) | MIN RESPONSE TIM | sec | 0 | 100 | 0 | 0.01 | 499 |
| Winding 2 Residual Time-Overcurrent (WDG2 Res TOC) | | | | | | | |
| 400 (R/W) | WDG2 RES TOC EN 0 = N 1 = Y | | 0 | 1 | 0 | | 500 |
| 401 (R/W) | RES TOC LEVEL | A | 10 | 1600 | 10 | 0.01 | 501 |
| 402 (R/W) | RES TOC CURVE 0 = U1 5 = C1 1 = U2 6 = C2 2 = U3 7 = C3 3 = U4 8 = C4 4 = U5 9 = C5 | | 0 | 9 | 2 | | 502 |
| 403 (R/W) | RES TOC TDIAL | | 5 | 1500 | 150 | 0.01 | 503 |
| 404 (R/W) | EM RESET DELAY 0 = N 1 = Y | | 0 | 1 | 0 | | 504 |
| 405 (R/W) | CONST TIME ADDER | sec | 0 | 100 | 0 | 0.01 | 505 |
| 406 (R/W) | MIN RESPONSE TIM | sec | 0 | 100 | 0 | 0.01 | 506 |
| Winding 2 Negative-Sequence Time-Overcurrent (WDG2 Neg Seq TOC) | | | | | | | |
| 407 (R/W) | WDG2 NSEQ TOC EN 0 = N 1 = Y | | 0 | 1 | 0 | | 507 |
| 408 (R/W) | NSEQ TOC LEVEL | A | 10 | 1600 | 120 | 0.01 | 508 |
| 409 (R/W) | NSEQ TOC CURVE 0 = U1 5 = C1 1 = U2 6 = C2 2 = U3 7 = C3 3 = U4 8 = C4 4 = U5 9 = C5 | | 0 | 9 | 2 | | 509 |
| 410 (R/W) | NSEQ TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 510 |
| 411 (R/W) | EM RESET DELAY 0 = N 1 = Y | | 0 | 1 | 0 | | 511 |
| 412 (R/W) | CONST TIME ADDER | sec | 0 | 100 | 0 | 0.01 | 512 |
| 413 (R/W) | MIN RESPONSE TIM | sec | 0 | 100 | 0 | 0.01 | 513 |
| Neutral Instantaneous Overcurrent | | | | | | | |
| 414 (R/W) | NEUT IOC L1 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 514 |
| 415 (R/W) | NEUT IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 515 |
| 416 (R/W) | NEUT IOC DELAY | sec | 0 | 500 | 50 | 0.01 | 516 |
| 417 (R/W) | NEUT IOC L2 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 517 |
| 418 (R/W) | NEUT IOC LEVEL | A | 10 | 9600 | 200 | 0.01 | 518 |
| 419 (R/W) | NEUT IOC DELAY | sec | 0 | 500 | 50 | 0.01 | 519 |
| Neutral Time-Overcurrent | | | | | | | |
| 420 (R/W) | NEUT TOC LVL EN 0 = N 1 = Y | | 0 | 1 | 0 | | 520 |

Table E.34 Modbus Register Map^a (Sheet 8 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--|-------|-----|------|-----|--------------|-----------------------------|
| 421 (R/W) | NEUT TOC LEVEL | A | 10 | 1600 | 10 | 0.01 | 521 |
| 422 (R/W) | NEUT TOC CURVE 0 = U1 5 = C1 1 = U2 6 = C2 2 = U3 7 = C3 3 = U4 8 = C4 4 = U5 9 = C5 | | 0 | 9 | 2 | | 522 |
| 423 (R/W) | NEUT TOC TDIAL | | 5 | 1500 | 150 | 0.01 | 523 |
| 424 (R/W) | EM RESET DELAY 0 = N 1 = Y | | 0 | 1 | 0 | | 524 |
| 425 (R/W) | CONST TIME ADDER | sec | 0 | 100 | 0 | 0.01 | 525 |
| 426 (R/W) | MIN RESPONSE TIM | sec | 0 | 100 | 0 | 0.01 | 526 |
| 427–431 (R) | Reserved ^c | | 0 | 0 | 0 | | 527–531 |
| RTD Settings | | | | | | | |
| 432 (R/W) | RTD ENABLE 0 = NONE 1 = INT 2 = EXT | | 0 | 2 | 0 | | 532 |
| 433 (R/W) | RTD1 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 533 |
| 434 (R/W) | RTD1 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 534 |
| 435 (R/W) | RTD1 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 535 |
| 436 (R/W) | RTD1 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 536 |
| 437 (R/W) | RTD2 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 537 |
| 438 (R/W) | RTD2 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 538 |
| 439 (R/W) | RTD2 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 539 |
| 440 (R/W) | RTD2 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 540 |
| 441 (R/W) | RTD3 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 541 |
| 442 (R/W) | RTD3 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 542 |
| 443 (R/W) | RTD3 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 543 |
| 444 (R/W) | RTD3 WARN LEVEL | degC | 0 | 250 | 0 | 1 | 544 |

Table E.34 Modbus Register Map^a (Sheet 9 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--|-------|-----|-----|-----|--------------|-----------------------------|
| | 0 = Off | | | | | | |
| 445 (R/W) | RTD4 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 545 |
| 446 (R/W) | RTD4 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 546 |
| 447 (R/W) | RTD4 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 547 |
| 448 (R/W) | RTD4 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 548 |
| 449 (R/W) | RTD5 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 549 |
| 450 (R/W) | RTD5 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 550 |
| 451 (R/W) | RTD5 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 551 |
| 452 (R/W) | RTD5 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 552 |
| 453 (R/W) | RTD6 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 553 |
| 454 (R/W) | RTD6 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 554 |
| 455 (R/W) | RTD6 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 555 |
| 456 (R/W) | RTD6 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 556 |
| 457 (R/W) | RTD7 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 557 |
| 458 (R/W) | RTD7 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 558 |
| 459 (R/W) | RTD7 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 559 |
| 460 (R/W) | RTD7 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 560 |
| 461 (R/W) | RTD8 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 561 |
| 462 (R/W) | RTD8 TYPE 0 = PT100 1 = NI100 | | 0 | 3 | 0 | | 562 |

Table E.34 Modbus Register Map^a (Sheet 10 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|---|-------|-----|-----|-----|--------------|-----------------------------|
| | 2 = NI120 3 = CU10 | | | | | | |
| 463 (R/W) | RTD8 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 563 |
| 464 (R/W) | RTD8 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 564 |
| 465 (R/W) | RTD9 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 565 |
| 466 (R/W) | RTD9 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 566 |
| 467 (R/W) | RTD9 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 567 |
| 468 (R/W) | RTD9 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 568 |
| 469 (R/W) | RTD10 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 569 |
| 470 (R/W) | RTD10 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 570 |
| 471 (R/W) | RTD10 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 571 |
| 472 (R/W) | RTD10 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 572 |
| 473 (R/W) | RTD11 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 573 |
| 474 (R/W) | RTD11 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 574 |
| 475 (R/W) | RTD11 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 575 |
| 476 (R/W) | RTD11 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 576 |
| 477 (R/W) | RTD12 LOCATION 0 = OFF 1 = AMB 2 = OTH | | 0 | 2 | 0 | | 577 |
| 478 (R/W) | RTD12 TYPE 0 = PT100 1 = NI100 2 = NI120 3 = CU10 | | 0 | 3 | 0 | | 578 |
| 479 (R/W) | RTD12 TRIP LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 579 |
| 480 (R/W) | RTD12 WARN LEVEL 0 = Off | degC | 0 | 250 | 0 | 1 | 580 |
| 481–486 (R) | Reserved ^c | | 0 | 0 | 0 | | 581–586 |

Table E.34 Modbus Register Map^a (Sheet 11 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|---|-------|-----|-------|------|--------------|-----------------------------|
| Phase Undervoltage | | | | | | | |
| 487 (R/W) | PHASE UV LVL1 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 587 |
| 488 (R/W) | PHASE UV LEVEL | V | 125 | 3000 | 600 | 0.1 | 588 |
| 489 (R/W) | PHASE UV DELAY | sec | 0 | 1200 | 5 | 0.1 | 589 |
| 490 (R/W) | PHASE UV LVL2 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 590 |
| 491 (R/W) | PHASE UV LEVEL | V | 125 | 3000 | 600 | 0.1 | 591 |
| 492 (R/W) | PHASE UV DELAY | sec | 0 | 1200 | 50 | 0.1 | 592 |
| Phase Overvoltage | | | | | | | |
| 493 (R/W) | PHASE OV LVL1 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 593 |
| 494 (R/W) | PHASE OV LEVEL | V | 125 | 3000 | 2400 | 0.1 | 594 |
| 495 (R/W) | PHASE OV DELAY | sec | 0 | 1200 | 5 | 0.1 | 595 |
| 496 (R/W) | PHASE OV LVL2 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 596 |
| 497 (R/W) | PHASE OV LEVEL | V | 125 | 3000 | 2400 | 0.1 | 597 |
| 498 (R/W) | PHASE OV DELAY | sec | 0 | 1200 | 50 | 0.1 | 598 |
| Negative-Sequence Overvoltage | | | | | | | |
| 499 (R/W) | NSEQ OV LVL1 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 599 |
| 500 (R/W) | NSEQ OV LEVEL | V | 125 | 3000 | 2400 | 0.1 | 600 |
| 501 (R/W) | NSEQ OV DELAY | sec | 0 | 1200 | 5 | 0.1 | 601 |
| 502 (R/W) | NSEQ OV LVL2 EN 0 = N 1 = Y | | 0 | 1 | 0 | | 602 |
| 503 (R/W) | NSEQ OV LEVEL | V | 125 | 3000 | 2400 | 0.1 | 603 |
| 504 (R/W) | NSEQ OV DELAY | sec | 0 | 1200 | 50 | 0.1 | 604 |
| 505–514 (R) | Reserved ^c | | 0 | 0 | 0 | | 605–614 |
| Volts/Hertz | | | | | | | |
| 515 (R/W) | ENABLE V/HZ PROT 0 = N 1 = Y | | 0 | 1 | 1 | | 615 |
| 516 (R/W) | XFMR WDG CONN 0 = DELTA 1 = WYE | | 0 | 1 | 1 | | 616 |
| 517 (R/W) | LVL1 V/HZ PICKUP | % | 100 | 200 | 105 | 1 | 617 |
| 518 (R/W) | LVL1 TIME DLY | sec | 4 | 40000 | 100 | 0.01 | 618 |
| 519 (R/W) | LVL2 CURVE SHAPE 0 = OFF 1 = DD 2 = ID 3 = I 4 = U | | 0 | 4 | 2 | | 619 |
| 520 (R/W) | LVL2 INV-TM PU | % | 100 | 200 | 105 | 1 | 620 |

Table E.34 Modbus Register Map^a (Sheet 12 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|---|-------|-----|-------|-------|--------------|-----------------------------|
| 521 (R/W) | LVL2 INV-TM CURV 0 = 0.5 1 = 1.0 2 = 2.0 | | 0 | 2 | 2 | | 621 |
| 522 (R/W) | LVL2 INV-TM FCTR | sec | 1 | 100 | 1 | 0.1 | 622 |
| 523 (R/W) | LVL2 PICKUP 1 | % | 100 | 200 | 175 | 1 | 623 |
| 524 (R/W) | LVL2 TIME DLY 1 | sec | 4 | 40000 | 300 | 0.01 | 624 |
| 525 (R/W) | LVL2 PICKUP 2 | % | 101 | 200 | 176 | 1 | 625 |
| 526 (R/W) | LVL2 TIME DLY 2 | sec | 4 | 40000 | 300 | 0.01 | 626 |
| 527 (R/W) | LVL2 RESET TIME | sec | 0 | 40000 | 24000 | 0.01 | 627 |
| Power Elements | | | | | | | |
| 528 (R/W) | ENABLE PWR ELEM 0 = N 1 = 3P1 2 = 3P2 | | 0 | 2 | 0 | | 628 |
| 529 (R/W) | ENABLE 3PWR1P 0 = N 1 = Y | | 0 | 1 | 0 | | 629 |
| 530 (R/W) | 3PH PWR ELEM PU | VA | 2 | 65000 | 20000 | 0.1 | 630 |
| 531 (R/W) | PWR ELEM TYPE 0 = +WATTS 1 = -WATTS 2 = +VARs 3 = -VARs | | 0 | 3 | 2 | | 631 |
| 532 (R/W) | PWR ELEM DELAY | sec | 0 | 2400 | 0 | 0.1 | 632 |
| 533 (R/W) | ENABLE 3PWR2P 0 = N 1 = Y | | 0 | 1 | 0 | | 633 |
| 534 (R/W) | 3PH PWR ELEM PU | VA | 2 | 65000 | 20000 | 0.1 | 634 |
| 535 (R/W) | PWR ELEM TYPE 0 = +WATTS 1 = -WATTS 2 = +VARs 3 = -VARs | | 0 | 3 | 2 | | 635 |
| 536 (R/W) | PWR ELEM DELAY | sec | 0 | 2400 | 0 | 0.1 | 636 |
| Frequency Settings | | | | | | | |
| 537 (R/W) | FREQ1 TRIP ENABL 0 = N 1 = Y | | 0 | 1 | 0 | | 637 |
| 538 (R/W) | FREQ1 TRIP LEVEL | Hz | 200 | 700 | 600 | 0.1 | 638 |
| 539 (R/W) | FREQ1 TRIP DELAY | sec | 0 | 2400 | 10 | 0.1 | 639 |
| 540 (R/W) | FREQ2 TRIP ENABL 0 = N 1 = Y | | 0 | 1 | 0 | | 640 |
| 541 (R/W) | FREQ2 TRIP LEVEL | Hz | 200 | 700 | 600 | 0.1 | 641 |
| 542 (R/W) | FREQ2 TRIP DELAY | sec | 0 | 2400 | 10 | 0.1 | 642 |
| 543 (R/W) | FREQ3 TRIP ENABL 0 = N 1 = Y | | 0 | 1 | 0 | | 643 |
| 544 (R/W) | FREQ3 TRIP LEVEL | Hz | 200 | 700 | 600 | 0.1 | 644 |
| 545 (R/W) | FREQ3 TRIP DELAY | sec | 0 | 2400 | 10 | 0.1 | 645 |

Table E.34 Modbus Register Map^a (Sheet 13 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|---------------------------------------|---|-------|-----|------|-----|--------------|-----------------------------|
| 546 (R/W) | FREQ4 TRIP ENABL 0 = N 1 = Y | | 0 | 1 | 0 | | 646 |
| 547 (R/W) | FREQ4 TRIP LEVEL | Hz | 200 | 700 | 600 | 0.1 | 647 |
| 548 (R/W) | FREQ4 TRIP DELAY | sec | 0 | 2400 | 10 | 0.1 | 648 |
| Demand Metering | | | | | | | |
| 549 (R/W) | ENABLE DEM MTR 0 = OFF 1 = W1 2 = W2 | | 0 | 2 | 0 | | 649 |
| 550 (R/W) | DEMAND MTR TYPE 0 = THM 1 = ROL | | 0 | 1 | 0 | | 650 |
| 551 (R/W) | DEM TIME CONSTNT 0 = 5 1 = 10 2 = 15 3 = 30 4 = 60 | min | 0 | 4 | 0 | | 651 |
| 552 (R/W) | PH CURR DEM LVL | A | 1 | 160 | 50 | 0.1 | 652 |
| 553 (R/W) | RES CURR DEM LVL | A | 1 | 160 | 10 | 0.1 | 653 |
| 554 (R/W) | 3I2 CURR DEM LVL | A | 1 | 160 | 10 | 0.1 | 654 |
| 555–564 (R) | Reserved ^c | | 0 | 0 | 0 | | 655–664 |
| Trip/Close Logic | | | | | | | |
| 565 (R/W) | MIN TRIP TIME | sec | 0 | 4000 | 5 | 0.1 | 665 |
| 566 (R/W) | CLOSE1 FAIL DLY | sec | 0 | 4000 | 5 | 0.1 | 666 |
| 567 (R/W) | CLOSE2 FAIL DLY | sec | 0 | 4000 | 5 | 0.1 | 667 |
| 568–575 (R) | Reserved ^c | | 0 | 0 | 0 | | 668–675 |
| SELogic Enables | | | | | | | |
| 576 (R/W) | SELogic LATCHES | | 0 | 32 | 4 | 1 | 676 |
| 577 (R/W) | SV/TIMERS | | 0 | 32 | 5 | 1 | 677 |
| 578 (R/W) | SELogic COUNTERS | | 0 | 32 | 0 | 1 | 678 |
| 579 (R/W) | MATH VARIABLES | | 0 | 32 | 0 | 1 | 679 |
| 580–584 (R) | Reserved ^c | | 0 | 0 | 0 | | 680–684 |
| Output Contacts 0 = N 1 = Y | | | | | | | |
| 585 (R/W) | OUT101 FAIL-SAFE | | 0 | 1 | 1 | | 685 |
| 586 (R/W) | OUT102 FAIL-SAFE | | 0 | 1 | 0 | | 686 |
| 587 (R/W) | OUT103 FAIL-SAFE | | 0 | 1 | 0 | | 687 |
| 588 (R/W) | OUT301 FAIL-SAFE | | 0 | 1 | 0 | | 688 |
| 589 (R/W) | OUT302 FAIL-SAFE | | 0 | 1 | 0 | | 689 |
| 590 (R/W) | OUT303 FAIL-SAFE | | 0 | 1 | 0 | | 690 |
| 591 (R/W) | OUT304 FAIL-SAFE | | 0 | 1 | 0 | | 691 |
| 592 (R/W) | OUT401 FAIL-SAFE | | 0 | 1 | 0 | | 692 |
| 593 (R/W) | OUT402 FAIL-SAFE | | 0 | 1 | 0 | | 693 |
| 594 (R/W) | OUT403 FAIL-SAFE | | 0 | 1 | 0 | | 694 |
| 595 (R/W) | OUT404 FAIL-SAFE | | 0 | 1 | 0 | | 695 |
| 596 (R/W) | OUT501 FAIL-SAFE | | 0 | 1 | 0 | | 696 |
| 597 (R/W) | OUT502 FAIL-SAFE | | 0 | 1 | 0 | | 697 |
| 598 (R/W) | OUT503 FAIL-SAFE | | 0 | 1 | 0 | | 698 |

Table E.34 Modbus Register Map^a (Sheet 14 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|---|-------|-----|------|-----|--------------|-----------------------------|
| 599 (R/W) | OUT504 FAIL-SAFE | | 0 | 1 | 0 | | 699 |
| 600–604 (R) | Reserved ^c | | 0 | 0 | 0 | | 700–704 |
| Event Report Set | | | | | | | |
| 605 (R/W) | EVENT LENGTH 0 = 15 1 = 64 | cyc | 0 | 1 | 0 | | 705 |
| 606 (R/W) | PREFault LENGTH | cyc | 1 | 59 | 5 | 1 | 706 |
| 607 (R) | Reserved ^c | | 0 | 0 | 0 | | 707 |
| 608 (R/W) | ENABLE ALIASES | | 0 | 20 | 4 | 1 | 708 |
| 609 (R/W) | LDP ACQ RATE 0 = 5 1 = 10 2 = 15 3 = 30 4 = 60 | min | 0 | 4 | 2 | | 709 |
| 610 (R/W) | AUTO-REMOVAL EN 0 = N 1 = Y | | 0 | 1 | 0 | | 710 |
| 611 (R) | NUM OF COUNTS | | 2 | 20 | 5 | 1 | 711 |
| 612 (R) | REMOVAL TIME | sec | 1 | 900 | 10 | 0.1 | 712 |
| 613–614 (R) | Reserved ^c | | 0 | 0 | 0 | | 713–714 |
| Front Panel Set | | | | | | | |
| 615 (R/W) | DISPLY PTS ENABL | | 0 | 32 | 4 | 1 | 715 |
| 616 (R/W) | LOCAL BITS ENABL | | 0 | 32 | 0 | 1 | 716 |
| 617 (R/W) | LCD TIMEOUT 0 = Off | min | 0 | 30 | 15 | 1 | 717 |
| 618 (R/W) | LCD CONTRAST | | 1 | 8 | 5 | 1 | 718 |
| 619 (R/W) | CLOSE RESET LEDS 0 = N 1 = Y | | 0 | 1 | 1 | | 719 |
| 620–624 (R) | Reserved ^c | | 0 | 0 | 0 | | 720–724 |
| Reset Settings | | | | | | | |
| 625 (R/W) | RESET DATA Bit 0 = TRIP RESET Bit 1 = SET TO DEFAULTS Bit 2 = RESET STAT DATA Bit 3 = RESET HIST DATA Bit 4 = RESET COMM CNTR Bit 5 = Reserved ^c Bit 6 = RST ENRGY DATA Bit 7 = RST MX/MN DATA Bit 8 = RST DEMAND Bit 9 = RST PEAK DEMAND Bits 10–Bit 15 = Reserved | | 0 | 1023 | 0 | | 725 |
| 626–635 (R) | Reserved ^c | | 0 | 0 | 0 | | 726–735 |
| Date/Time Set | | | | | | | |
| 636 (R/W) | SET SEC | | 0 | 5999 | 0 | 0.01 | 736 |
| 637 (R/W) | SET MIN | | 0 | 59 | 0 | 1 | 737 |
| 638 (R/W) | SET HOUR | | 0 | 23 | 0 | 1 | 738 |
| 639 (R/W) | SET DAY | | 1 | 31 | 1 | 1 | 739 |
| 640 (R/W) | SET MONTH | | 1 | 12 | 1 | 1 | 740 |

Table E.34 Modbus Register Map^a (Sheet 15 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|---|---|-------|-------|-------|------|--------------|-----------------------------|
| 641 (R/W) | SET YEAR | | 2000 | 9999 | 2000 | 1 | 741 |
| 642–643 (R) | Reserved ^c | | 0 | 0 | 0 | | 742–743 |
| Device Status 0 = OK 1 = WARN 2 = FAIL | | | | | | | |
| 644 (R) | FPGA STATUS | | 0 | 2 | 0 | | 744 |
| 645 (R) | GPSB STATUS | | 0 | 2 | 0 | | 745 |
| 646 (R) | HMI STATUS | | 0 | 2 | 0 | | 746 |
| 647 (R) | RAM STATUS | | 0 | 2 | 0 | | 747 |
| 648 (R) | ROM STATUS | | 0 | 2 | 0 | | 748 |
| 649 (R) | CR_RAM STATUS | | 0 | 2 | 0 | | 749 |
| 650 (R) | NON_VOL STATUS | | 0 | 2 | 0 | | 750 |
| 651 (R) | CLOCK STATUS | | 0 | 2 | 0 | | 751 |
| 652 (R) | CID FILE STATUS | | 0 | 2 | 0 | | 752 |
| 653 (R) | RTD STATUS | | 0 | 2 | 0 | | 753 |
| 654 (R) | +3.3V STATUS | | 0 | 2 | 0 | | 754 |
| 655 (R) | +5.0V STATUS | | 0 | 2 | 0 | | 755 |
| 656 (R) | +2.5V STATUS | | 0 | 2 | 0 | | 756 |
| 657 (R) | +3.75V STATUS | | 0 | 2 | 0 | | 757 |
| 658 (R) | -1.25V STATUS | | 0 | 2 | 0 | | 758 |
| 659 (R) | -5.0V STATUS | | 0 | 2 | 0 | | 759 |
| 660 (R) | CLK_BAT STATUS | | 0 | 2 | 0 | | 760 |
| 661 (R) | CT BOARD STATUS | | 0 | 2 | 0 | | 761 |
| 662 (R) | CARD C STATUS | | 0 | 2 | 0 | | 762 |
| 663 (R) | CARD D STATUS | | 0 | 2 | 0 | | 763 |
| 664 (R) | CARD E STATUS | | 0 | 2 | 0 | | 764 |
| 665 (R) | IAW1 STATUS | | 0 | 2 | 0 | | 765 |
| 666 (R) | IBW1 STATUS | | 0 | 2 | 0 | | 766 |
| 667 (R) | ICW1 STATUS | | 0 | 2 | 0 | | 767 |
| 668 (R) | IAW2 STATUS | | 0 | 2 | 0 | | 768 |
| 669 (R) | IBW2 STATUS | | 0 | 2 | 0 | | 769 |
| 670 (R) | ICW2 STATUS | | 0 | 2 | 0 | | 770 |
| 671 (R) | IN STATUS | | 0 | 2 | 0 | | 771 |
| 672 (R) | VA STATUS | | 0 | 2 | 0 | | 772 |
| 673 (R) | VB STATUS | | 0 | 2 | 0 | | 773 |
| 674 (R) | VC STATUS | | 0 | 2 | 0 | | 774 |
| 675 (R) | RELAY STATUS 0 = ENABLED 1 = DISABLED | | 0 | 1 | 0 | | 775 |
| 676–683 (R) | Reserved ^c | | 0 | 0 | 0 | | 776–783 |
| Current Data | | | | | | | |
| 684 (R) | IAW1 CURRENT | A | 0 | 65535 | 0 | 1 | 784 |
| 685 (R) | IAW1 ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 785 |
| 686 (R) | IBW1 CURRENT | A | 0 | 65535 | 0 | 1 | 786 |
| 687 (R) | IBW1 ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 787 |

Table E.34 Modbus Register Map^a (Sheet 16 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|-------------------------------|-------|--------|-------|-----|--------------|-----------------------------|
| 688 (R) | ICW1 CURRENT | A | 0 | 65535 | 0 | 1 | 788 |
| 689 (R) | ICW1 ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 789 |
| 690 (R) | IGW1 CURRENT | A | 0 | 65535 | 0 | 1 | 790 |
| 691 (R) | IGW1 ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 791 |
| 692 (R) | 3I2W1 NSEQ CURR | A | 0 | 65535 | 0 | 1 | 792 |
| 693 (R) | W1 AVERAGE CURR | A | 0 | 65535 | 0 | 1 | 793 |
| 694 (R) | IAW2 CURRENT | A | 0 | 65535 | 0 | 1 | 794 |
| 695 (R) | IAW2 ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 795 |
| 696 (R) | IBW2 CURRENT | A | 0 | 65535 | 0 | 1 | 796 |
| 697 (R) | IBW2 ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 797 |
| 698 (R) | ICW2 CURRENT | A | 0 | 65535 | 0 | 1 | 798 |
| 699 (R) | ICW2 ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 799 |
| 700 (R) | IGW2 CURRENT | A | 0 | 65535 | 0 | 1 | 800 |
| 701 (R) | IGW2 ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 801 |
| 702 (R) | 3I2W2 NSEQ CURR | A | 0 | 65535 | 0 | 1 | 802 |
| 703 (R) | W2 AVERAGE CURR | A | 0 | 65535 | 0 | 1 | 803 |
| 704 (R) | IN CURRENT | A | 0 | 65535 | 0 | 1 | 804 |
| 705 (R) | IN ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 805 |
| 706–708 (R) | Reserved ^c | | 0 | 0 | 0 | | 806–808 |
| Voltage Data | | | | | | | |
| 709 (R) | VAB | V | 0 | 65535 | 0 | 1 | 809 |
| 710 (R) | VAB ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 810 |
| 711 (R) | VBC | V | 0 | 65535 | 0 | 1 | 811 |
| 712 (R) | VBC ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 812 |
| 713 (R) | VCA | V | 0 | 65535 | 0 | 1 | 813 |
| 714 (R) | VCA ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 814 |
| 715 (R) | AVERAGE LINE V ^d | V | 0 | 65535 | 0 | 1 | 815 |
| 716 (R) | VAN | V | 0 | 65535 | 0 | 1 | 816 |
| 717 (R) | VAN ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 817 |
| 718 (R) | VBN | V | 0 | 65535 | 0 | 1 | 818 |
| 719 (R) | VBN ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 819 |
| 720 (R) | VCN | V | 0 | 65535 | 0 | 1 | 820 |
| 721 (R) | VCN ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 821 |
| 722 (R) | VG | V | 0 | 65535 | 0 | 1 | 822 |
| 723 (R) | VG ANGLE | deg | -1800 | 1800 | 0 | 0.1 | 823 |
| 724 (R) | AVERAGE L-N VOLT ^e | V | 0 | 65535 | 0 | 1 | 824 |
| 725 (R) | NEG-SEQ VOLT 3V2 | V | 0 | 65535 | 0 | 1 | 825 |
| Power Data | | | | | | | |
| 726 (R) | REAL POWER | kW | -32768 | 32767 | 0 | 1 | 826 |
| 727 (R) | REACTIVE POWER | kVAR | -32768 | 32767 | 0 | 1 | 827 |
| 728 (R) | APPARENT POWER | kVA | -32768 | 32767 | 0 | 1 | 828 |
| 729 (R) | POWER FACTOR | | -100 | 100 | 0 | 0.01 | 829 |

Table E.34 Modbus Register Map^a (Sheet 17 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|-----------------------|-------|------|-------|------|--------------|-----------------------------|
| 730 (R) | VOLTS PER HERTZ | % | 0 | 1000 | 0 | 0.1 | 830 |
| 731 (R) | FREQUENCY | Hz | 200 | 700 | 600 | 0.1 | 831 |
| Energy Data ^f | | | | | | | |
| 732 (R) | MWHP HI | MWhr | 0 | 65535 | 0 | 0.001 | 832 |
| 733 (R) | MWHP LO | MWhr | 0 | 65535 | 0 | 0.001 | 833 |
| 734 (R) | MWHN HI | MWhr | 0 | 65535 | 0 | 0.001 | 834 |
| 735 (R) | MWHN LO | MWhr | 0 | 65535 | 0 | 0.001 | 835 |
| 736 (R) | MVRHP HI | MVRh | 0 | 65535 | 0 | 0.001 | 836 |
| 737 (R) | MVRHP LO | MVRh | 0 | 65535 | 0 | 0.001 | 837 |
| 738 (R) | MVRHN HI | MVRh | 0 | 65535 | 0 | 0.001 | 838 |
| 739 (R) | MVRHN LO | MVRh | 0 | 65535 | 0 | 0.001 | 839 |
| 740 (R) | LAST RST TIME-ss | | 0 | 5999 | 0 | 0.01 | 840 |
| 741 (R) | LAST RST TIME-mm | | 0 | 59 | 0 | 1 | 841 |
| 742 (R) | LAST RST TIME-hh | | 0 | 23 | 0 | 1 | 842 |
| 743 (R) | LAST RST DATE-dd | | 1 | 31 | 1 | 1 | 843 |
| 744 (R) | LAST RST DATE-mm | | 1 | 12 | 1 | 1 | 844 |
| 745 (R) | LAST RST DATE-yy | | 2000 | 9999 | 2000 | 1 | 845 |
| 746–753 (R) | Reserved ^c | | 0 | 0 | 0 | | 846–853 |
| Demand Data | | | | | | | |
| 754 (R) | IA DEMAND | A | 0 | 65535 | 0 | 1 | 854 |
| 755 (R) | IB DEMAND | A | 0 | 65535 | 0 | 1 | 855 |
| 756 (R) | IC DEMAND | A | 0 | 65535 | 0 | 1 | 856 |
| 757 (R) | IG DEMAND | A | 0 | 65535 | 0 | 1 | 857 |
| 758 (R) | 3I2 DEMAND | A | 0 | 65535 | 0 | 1 | 858 |
| Peak Demand Data | | | | | | | |
| 759 (R) | IA PEAK DEMAND | A | 0 | 65535 | 0 | 1 | 859 |
| 760 (R) | IB PEAK DEMAND | A | 0 | 65535 | 0 | 1 | 860 |
| 761 (R) | IC PEAK DEMAND | A | 0 | 65535 | 0 | 1 | 861 |
| 762 (R) | IG PEAK DEMAND | A | 0 | 65535 | 0 | 1 | 862 |
| 763 (R) | 3I2 PEAK DEMAND | A | 0 | 65535 | 0 | 1 | 863 |
| 764 (R) | PEAKD RST TIM-ss | | 0 | 5999 | 0 | 0.01 | 864 |
| 765 (R) | PEAKD RST TIM-mm | | 0 | 59 | 0 | 1 | 865 |
| 766 (R) | PEAKD RST TIM-hh | | 0 | 23 | 0 | 1 | 866 |
| 767 (R) | PEAKD RST DAT-dd | | 1 | 31 | 1 | 1 | 867 |
| 768 (R) | PEAKD RST DAT-mm | | 1 | 12 | 1 | 1 | 868 |
| 769 (R) | PEAKD RST DAT-yy | | 2000 | 9999 | 2000 | 1 | 869 |
| Harmonic Data | | | | | | | |
| 770 (R) | IAW1 THD | % | 0 | 65535 | 0 | 0.1 | 870 |
| 771 (R) | IBW1 THD | % | 0 | 65535 | 0 | 0.1 | 871 |
| 772 (R) | ICW1 THD | % | 0 | 65535 | 0 | 0.1 | 872 |
| 773 (R) | IAW2 THD | % | 0 | 65535 | 0 | 0.1 | 873 |
| 774 (R) | IBW2 THD | % | 0 | 65535 | 0 | 0.1 | 874 |

Table E.34 Modbus Register Map^a (Sheet 18 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--|-------|--------|-------|-----|--------------|-----------------------------|
| 775 (R) | ICW2 THD | % | 0 | 65535 | 0 | 0.1 | 875 |
| 776 (R) | VA THD | % | 0 | 65535 | 0 | 0.1 | 876 |
| 777 (R) | VB THD | % | 0 | 65535 | 0 | 0.1 | 877 |
| 778 (R) | VC THD | % | 0 | 65535 | 0 | 0.1 | 878 |
| 779 (R) | VAB THD | % | 0 | 65535 | 0 | 0.1 | 879 |
| 780 (R) | VBC THD | % | 0 | 65535 | 0 | 0.1 | 880 |
| 781 (R) | VCA THD | % | 0 | 65535 | 0 | 0.1 | 881 |
| RTD Data | | | | | | | |
| 782 (R) | MAX AMBIENT RTD 7FFFh = Open 8000h = Short 7FFCh = Comm Fail 7FF8h = Stat Fail 7FFEh = Fail 7FF0h = NA | degC | -32768 | 32767 | 0 | 1 | 882 |
| 783 (R) | MAX OTHER RTD | degC | -32768 | 32767 | 0 | 1 | 883 |
| 784 (R) | RTD1 | degC | -32768 | 32767 | 0 | 1 | 884 |
| 785 (R) | RTD2 | degC | -32768 | 32767 | 0 | 1 | 885 |
| 786 (R) | RTD3 | degC | -32768 | 32767 | 0 | 1 | 886 |
| 787 (R) | RTD4 | degC | -32768 | 32767 | 0 | 1 | 887 |
| 788 (R) | RTD5 | degC | -32768 | 32767 | 0 | 1 | 888 |
| 789 (R) | RTD6 | degC | -32768 | 32767 | 0 | 1 | 889 |
| 790 (R) | RTD7 | degC | -32768 | 32767 | 0 | 1 | 890 |
| 791 (R) | RTD8 | degC | -32768 | 32767 | 0 | 1 | 891 |
| 792 (R) | RTD9 | degC | -32768 | 32767 | 0 | 1 | 892 |
| 793 (R) | RTD10 | degC | -32768 | 32767 | 0 | 1 | 893 |
| 794 (R) | RTD11 | degC | -32768 | 32767 | 0 | 1 | 894 |
| 795 (R) | RTD12 | degC | -32768 | 32767 | 0 | 1 | 895 |
| 796–806 (R) | Reserved ^c | | 0 | 0 | 0 | | 896–906 |
| RMS Data | | | | | | | |
| 807 (R) | IAW1 RMS | A | 0 | 65535 | 0 | 1 | 907 |
| 808 (R) | IBW1 RMS | A | 0 | 65535 | 0 | 1 | 908 |
| 809 (R) | ICW1 RMS | A | 0 | 65535 | 0 | 1 | 909 |
| 810 (R) | IAW2 RMS | A | 0 | 65535 | 0 | 1 | 910 |
| 811 (R) | IBW2 RMS | A | 0 | 65535 | 0 | 1 | 911 |
| 812 (R) | ICW2 RMS | A | 0 | 65535 | 0 | 1 | 912 |
| 813 (R) | IN RMS | A | 0 | 65535 | 0 | 1 | 913 |
| 814 (R) | VA RMS | V | 0 | 65535 | 0 | 1 | 914 |
| 815 (R) | VB RMS | V | 0 | 65535 | 0 | 1 | 915 |
| 816 (R) | VC RMS | V | 0 | 65535 | 0 | 1 | 916 |
| 817 (R) | VAB RMS | V | 0 | 65535 | 0 | 1 | 917 |
| 818 (R) | VBC RMS | V | 0 | 65535 | 0 | 1 | 918 |
| 819 (R) | VCA RMS | V | 0 | 65535 | 0 | 1 | 919 |

Table E.34 Modbus Register Map^a (Sheet 19 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--------------|-------|--------|-------|-----|--------------|-----------------------------|
| MAX/MIN MTR Data | | | | | | | |
| 820 (R) | IAW1 MAX | A | 0 | 65535 | 0 | 1 | 920 |
| 821 (R) | IAW1 MIN | A | 0 | 65535 | 0 | 1 | 921 |
| 822 (R) | IBW1 MAX | A | 0 | 65535 | 0 | 1 | 922 |
| 823 (R) | IBW1 MIN | A | 0 | 65535 | 0 | 1 | 923 |
| 824 (R) | ICW1 MAX | A | 0 | 65535 | 0 | 1 | 924 |
| 825 (R) | ICW1 MIN | A | 0 | 65535 | 0 | 1 | 925 |
| 826 (R) | IGW1 MAX | A | 0 | 65535 | 0 | 1 | 926 |
| 827 (R) | IGW1 MIN | A | 0 | 65535 | 0 | 1 | 927 |
| 828 (R) | IAW2 MAX | A | 0 | 65535 | 0 | 1 | 928 |
| 829 (R) | IAW2 MIN | A | 0 | 65535 | 0 | 1 | 929 |
| 830 (R) | IBW2 MAX | A | 0 | 65535 | 0 | 1 | 930 |
| 831 (R) | IBW2 MIN | A | 0 | 65535 | 0 | 1 | 931 |
| 832 (R) | ICW2 MAX | A | 0 | 65535 | 0 | 1 | 932 |
| 833 (R) | ICW2 MIN | A | 0 | 65535 | 0 | 1 | 933 |
| 834 (R) | IGW2 MAX | A | 0 | 65535 | 0 | 1 | 934 |
| 835 (R) | IGW2 MIN | A | 0 | 65535 | 0 | 1 | 935 |
| 836 (R) | IN MAX | A | 0 | 65535 | 0 | 1 | 936 |
| 837 (R) | IN MIN | A | 0 | 65535 | 0 | 1 | 937 |
| 838 (R) | VAB/VA MAX | V | 0 | 65535 | 0 | 1 | 938 |
| 839 (R) | VAB/VA MIN | V | 0 | 65535 | 0 | 1 | 939 |
| 840 (R) | VBC/VB MAX | V | 0 | 65535 | 0 | 1 | 940 |
| 841 (R) | VBC/VB MIN | V | 0 | 65535 | 0 | 1 | 941 |
| 842 (R) | VCA/VC MAX | V | 0 | 65535 | 0 | 1 | 942 |
| 843 (R) | VCA/VC MIN | V | 0 | 65535 | 0 | 1 | 943 |
| 844 (R) | KW3P MAX | kW | -32768 | 32767 | 0 | 1 | 944 |
| 845 (R) | KW3P MIN | kW | -32768 | 32767 | 0 | 1 | 945 |
| 846 (R) | KVAR3P MAX | kVAR | -32768 | 32767 | 0 | 1 | 946 |
| 847 (R) | KVAR3P MIN | kVAR | -32768 | 32767 | 0 | 1 | 947 |
| 848 (R) | KVA3P MAX | kVA | -32768 | 32767 | 0 | 1 | 948 |
| 849 (R) | KVA3P MIN | kVA | -32768 | 32767 | 0 | 1 | 949 |
| 850 (R) | FREQ MAX | Hz | 0 | 65535 | 0 | 0.1 | 950 |
| 851 (R) | FREQ MIN | Hz | 0 | 65535 | 0 | 0.1 | 951 |
| MAX/MIN RTD Data | | | | | | | |
| 852 (R) | RTD1 MAX | degC | -32768 | 32767 | 0 | 1 | 952 |
| 853 (R) | RTD1 MIN | degC | -32768 | 32767 | 0 | 1 | 953 |
| 854 (R) | RTD2 MAX | degC | -32768 | 32767 | 0 | 1 | 954 |
| 855 (R) | RTD2 MIN | degC | -32768 | 32767 | 0 | 1 | 955 |
| 856 (R) | RTD3 MAX | degC | -32768 | 32767 | 0 | 1 | 956 |
| 857 (R) | RTD3 MIN | degC | -32768 | 32767 | 0 | 1 | 957 |
| 858 (R) | RTD4 MAX | degC | -32768 | 32767 | 0 | 1 | 958 |
| 859 (R) | RTD4 MIN | degC | -32768 | 32767 | 0 | 1 | 959 |

Table E.34 Modbus Register Map^a (Sheet 20 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--------------|-------|--------|-------|-----|--------------|-----------------------------|
| 860 (R) | RTD5 MAX | degC | -32768 | 32767 | 0 | 1 | 960 |
| 861 (R) | RTD5 MIN | degC | -32768 | 32767 | 0 | 1 | 961 |
| 862 (R) | RTD6 MAX | degC | -32768 | 32767 | 0 | 1 | 962 |
| 863 (R) | RTD6 MIN | degC | -32768 | 32767 | 0 | 1 | 963 |
| 864 (R) | RTD7 MAX | degC | -32768 | 32767 | 0 | 1 | 964 |
| 865 (R) | RTD7 MIN | degC | -32768 | 32767 | 0 | 1 | 965 |
| 866 (R) | RTD8 MAX | degC | -32768 | 32767 | 0 | 1 | 966 |
| 867 (R) | RTD8 MIN | degC | -32768 | 32767 | 0 | 1 | 967 |
| 868 (R) | RTD9 MAX | degC | -32768 | 32767 | 0 | 1 | 968 |
| 869 (R) | RTD9 MIN | degC | -32768 | 32767 | 0 | 1 | 969 |
| 870 (R) | RTD10 MAX | degC | -32768 | 32767 | 0 | 1 | 970 |
| 871 (R) | RTD10 MIN | degC | -32768 | 32767 | 0 | 1 | 971 |
| 872 (R) | RTD11 MAX | degC | -32768 | 32767 | 0 | 1 | 972 |
| 873 (R) | RTD11 MIN | degC | -32768 | 32767 | 0 | 1 | 973 |
| 874 (R) | RTD12 MAX | degC | -32768 | 32767 | 0 | 1 | 974 |
| 875 (R) | RTD12 MIN | degC | -32768 | 32767 | 0 | 1 | 975 |
| MAX/MIN AI3 Data ^f | | | | | | | |
| 876 (R) | AI301 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 976 |
| 877 (R) | AI301 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 977 |
| 878 (R) | AI301 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 978 |
| 879 (R) | AI301 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 979 |
| 880 (R) | AI302 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 980 |
| 881 (R) | AI302 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 981 |
| 882 (R) | AI302 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 982 |
| 883 (R) | AI302 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 983 |
| 884 (R) | AI303 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 984 |
| 885 (R) | AI303 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 985 |
| 886 (R) | AI303 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 986 |
| 887 (R) | AI303 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 987 |
| 888 (R) | AI304 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 988 |
| 889 (R) | AI304 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 989 |
| 890 (R) | AI304 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 990 |
| 891 (R) | AI304 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 991 |
| MAX/MIN AI4 Data ^f | | | | | | | |
| 892 (R) | AI401 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 992 |
| 893 (R) | AI401 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 993 |
| 894 (R) | AI401 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 994 |
| 895 (R) | AI401 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 995 |
| 896 (R) | AI402 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 996 |
| 897 (R) | AI402 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 997 |
| 898 (R) | AI402 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 998 |
| 899 (R) | AI402 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 999 |

Table E.34 Modbus Register Map^a (Sheet 21 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|-----------------------|-------|--------|-------|------|--------------|-----------------------------|
| 900 (R) | AI403 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 1000 |
| 901 (R) | AI403 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 1001 |
| 902 (R) | AI403 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 1002 |
| 903 (R) | AI403 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 1003 |
| 904 (R) | AI404 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 1004 |
| 905 (R) | AI404 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 1005 |
| 906 (R) | AI404 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 1006 |
| 907 (R) | AI404 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 1007 |
| MAX/MIN AI5 Data^f | | | | | | | |
| 908 (R) | AI501 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 1008 |
| 909 (R) | AI501 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 1009 |
| 910 (R) | AI501 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 1010 |
| 911 (R) | AI501 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 1011 |
| 912 (R) | AI502 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 1012 |
| 913 (R) | AI502 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 1013 |
| 914 (R) | AI502 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 1014 |
| 915 (R) | AI502 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 1015 |
| 916 (R) | AI503 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 1016 |
| 917 (R) | AI503 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 1017 |
| 918 (R) | AI503 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 1018 |
| 919 (R) | AI503 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 1019 |
| 920 (R) | AI504 MX-HI | EU | -32768 | 32767 | 0 | 0.001 | 1020 |
| 921 (R) | AI504 MX-LO | EU | -32768 | 32767 | 0 | 0.001 | 1021 |
| 922 (R) | AI504 MN-HI | EU | -32768 | 32767 | 0 | 0.001 | 1022 |
| 923 (R) | AI504 MN-LO | EU | -32768 | 32767 | 0 | 0.001 | 1023 |
| MAX/MIN RST Data | | | | | | | |
| 924 (R) | MX/MN RST TIM-ss | | 0 | 5999 | 0 | 0.01 | 1024 |
| 925 (R) | MX/MN RST TIM-mm | | 0 | 59 | 0 | 1 | 1025 |
| 926 (R) | MX/MN RST TIM-hh | | 0 | 23 | 0 | 1 | 1026 |
| 927 (R) | MX/MN RST DAT-dd | | 1 | 31 | 1 | 1 | 1027 |
| 928 (R) | MX/MN RST DAT-mm | | 1 | 12 | 1 | 1 | 1028 |
| 929 (R) | MX/MN RST DAT-yy | | 2000 | 9999 | 2000 | 1 | 1029 |
| 930–939 (R) | Reserved ^c | | 0 | 0 | 0 | | 1030–1039 |
| Analog Input Data^f | | | | | | | |
| 940 (R) | AI301-HI | EU | -32768 | 32767 | 0 | 0.001 | 1040 |
| 941 (R) | AI301-LO | EU | -32768 | 32767 | 0 | 0.001 | 1041 |
| 942 (R) | AI302-HI | EU | -32768 | 32767 | 0 | 0.001 | 1042 |
| 943 (R) | AI302-LO | EU | -32768 | 32767 | 0 | 0.001 | 1043 |
| 944 (R) | AI303-HI | EU | -32768 | 32767 | 0 | 0.001 | 1044 |
| 945 (R) | AI303-LO | EU | -32768 | 32767 | 0 | 0.001 | 1045 |
| 946 (R) | AI304-HI | EU | -32768 | 32767 | 0 | 0.001 | 1046 |
| 947 (R) | AI304-LO | EU | -32768 | 32767 | 0 | 0.001 | 1047 |

Table E.34 Modbus Register Map^a (Sheet 22 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|-----------------------|-------|--------|-------|-----|--------------|-----------------------------|
| 948 (R) | AI401–HI | EU | -32768 | 32767 | 0 | 0.001 | 1048 |
| 949 (R) | AI401–LO | EU | -32768 | 32767 | 0 | 0.001 | 1049 |
| 950 (R) | AI402–HI | EU | -32768 | 32767 | 0 | 0.001 | 1050 |
| 951 (R) | AI402–LO | EU | -32768 | 32767 | 0 | 0.001 | 1051 |
| 952 (R) | AI403–HI | EU | -32768 | 32767 | 0 | 0.001 | 1052 |
| 953 (R) | AI403–LO | EU | -32768 | 32767 | 0 | 0.001 | 1053 |
| 954 (R) | AI404–HI | EU | -32768 | 32767 | 0 | 0.001 | 1054 |
| 955 (R) | AI404–LO | EU | -32768 | 32767 | 0 | 0.001 | 1055 |
| 956 (R) | AI501–HI | EU | -32768 | 32767 | 0 | 0.001 | 1056 |
| 957 (R) | AI501–LO | EU | -32768 | 32767 | 0 | 0.001 | 1057 |
| 958 (R) | AI502–HI | EU | -32768 | 32767 | 0 | 0.001 | 1058 |
| 959 (R) | AI502–LO | EU | -32768 | 32767 | 0 | 0.001 | 1059 |
| 960 (R) | AI503–HI | EU | -32768 | 32767 | 0 | 0.001 | 1060 |
| 961 (R) | AI503–LO | EU | -32768 | 32767 | 0 | 0.001 | 1061 |
| 962 (R) | AI504–HI | EU | -32768 | 32767 | 0 | 0.001 | 1062 |
| 963 (R) | AI504–LO | EU | -32768 | 32767 | 0 | 0.001 | 1063 |
| 964–969 (R) | Reserved ^c | | 0 | 0 | 0 | | 1064–1069 |
| Math Variables ^f | | | | | | | |
| 970 (R) | MV01–HI | | -32768 | 32767 | 0 | 0.01 | 1070 |
| 971 (R) | MV01–LO | | -32768 | 32767 | 0 | 0.01 | 1071 |
| 972 (R) | MV02–HI | | -32768 | 32767 | 0 | 0.01 | 1072 |
| 973 (R) | MV02–LO | | -32768 | 32767 | 0 | 0.01 | 1073 |
| 974 (R) | MV03–HI | | -32768 | 32767 | 0 | 0.01 | 1074 |
| 975 (R) | MV03–LO | | -32768 | 32767 | 0 | 0.01 | 1075 |
| 976 (R) | MV04–HI | | -32768 | 32767 | 0 | 0.01 | 1076 |
| 977 (R) | MV04–LO | | -32768 | 32767 | 0 | 0.01 | 1077 |
| 978 (R) | MV05–HI | | -32768 | 32767 | 0 | 0.01 | 1078 |
| 979 (R) | MV05–LO | | -32768 | 32767 | 0 | 0.01 | 1079 |
| 980 (R) | MV06–HI | | -32768 | 32767 | 0 | 0.01 | 1080 |
| 981 (R) | MV06–LO | | -32768 | 32767 | 0 | 0.01 | 1081 |
| 982 (R) | MV07–HI | | -32768 | 32767 | 0 | 0.01 | 1082 |
| 983 (R) | MV07–LO | | -32768 | 32767 | 0 | 0.01 | 1083 |
| 984 (R) | MV08–HI | | -32768 | 32767 | 0 | 0.01 | 1084 |
| 985 (R) | MV08–LO | | -32768 | 32767 | 0 | 0.01 | 1085 |
| 986 (R) | MV09–HI | | -32768 | 32767 | 0 | 0.01 | 1086 |
| 987 (R) | MV09–LO | | -32768 | 32767 | 0 | 0.01 | 1087 |
| 988 (R) | MV10–HI | | -32768 | 32767 | 0 | 0.01 | 1088 |
| 989 (R) | MV10–LO | | -32768 | 32767 | 0 | 0.01 | 1089 |
| 990 (R) | MV11–HI | | -32768 | 32767 | 0 | 0.01 | 1090 |
| 991 (R) | MV11–LO | | -32768 | 32767 | 0 | 0.01 | 1091 |
| 992 (R) | MV12–HI | | -32768 | 32767 | 0 | 0.01 | 1092 |
| 993 (R) | MV12–LO | | -32768 | 32767 | 0 | 0.01 | 1093 |
| 994 (R) | MV13–HI | | -32768 | 32767 | 0 | 0.01 | 1094 |
| 995 (R) | MV13–LO | | -32768 | 32767 | 0 | 0.01 | 1095 |
| 996 (R) | MV14–HI | | -32768 | 32767 | 0 | 0.01 | 1096 |

Table E.34 Modbus Register Map^a (Sheet 23 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|-----------------------|-------|--------|-------|-----|--------------|-----------------------------|
| 997 (R) | MV14-LO | | -32768 | 32767 | 0 | 0.01 | 1097 |
| 998 (R) | MV15-HI | | -32768 | 32767 | 0 | 0.01 | 1098 |
| 999 (R) | MV15-LO | | -32768 | 32767 | 0 | 0.01 | 1099 |
| 1000 (R) | MV16-HI | | -32768 | 32767 | 0 | 0.01 | 1100 |
| 1001 (R) | MV16-LO | | -32768 | 32767 | 0 | 0.01 | 1101 |
| 1002 (R) | MV17-HI | | -32768 | 32767 | 0 | 0.01 | 1102 |
| 1003 (R) | MV17-LO | | -32768 | 32767 | 0 | 0.01 | 1103 |
| 1004 (R) | MV18-HI | | -32768 | 32767 | 0 | 0.01 | 1104 |
| 1005 (R) | MV18-LO | | -32768 | 32767 | 0 | 0.01 | 1105 |
| 1006 (R) | MV19-HI | | -32768 | 32767 | 0 | 0.01 | 1106 |
| 1007 (R) | MV19-LO | | -32768 | 32767 | 0 | 0.01 | 1107 |
| 1008 (R) | MV20-HI | | -32768 | 32767 | 0 | 0.01 | 1108 |
| 1009 (R) | MV20-LO | | -32768 | 32767 | 0 | 0.01 | 1109 |
| 1010 (R) | MV21-HI | | -32768 | 32767 | 0 | 0.01 | 1110 |
| 1011 (R) | MV21-LO | | -32768 | 32767 | 0 | 0.01 | 1111 |
| 1012 (R) | MV22-HI | | -32768 | 32767 | 0 | 0.01 | 1112 |
| 1013 (R) | MV22-LO | | -32768 | 32767 | 0 | 0.01 | 1113 |
| 1014 (R) | MV23-HI | | -32768 | 32767 | 0 | 0.01 | 1114 |
| 1015 (R) | MV23-LO | | -32768 | 32767 | 0 | 0.01 | 1115 |
| 1016 (R) | MV24-HI | | -32768 | 32767 | 0 | 0.01 | 1116 |
| 1017 (R) | MV24-LO | | -32768 | 32767 | 0 | 0.01 | 1117 |
| 1018 (R) | MV25-HI | | -32768 | 32767 | 0 | 0.01 | 1118 |
| 1019 (R) | MV25-LO | | -32768 | 32767 | 0 | 0.01 | 1119 |
| 1020 (R) | MV26-HI | | -32768 | 32767 | 0 | 0.01 | 1120 |
| 1021 (R) | MV26-LO | | -32768 | 32767 | 0 | 0.01 | 1121 |
| 1022 (R) | MV27-HI | | -32768 | 32767 | 0 | 0.01 | 1122 |
| 1023 (R) | MV27-LO | | -32768 | 32767 | 0 | 0.01 | 1123 |
| 1024 (R) | MV28-HI | | -32768 | 32767 | 0 | 0.01 | 1124 |
| 1025 (R) | MV28-LO | | -32768 | 32767 | 0 | 0.01 | 1125 |
| 1026 (R) | MV29-HI | | -32768 | 32767 | 0 | 0.01 | 1126 |
| 1027 (R) | MV29-LO | | -32768 | 32767 | 0 | 0.01 | 1127 |
| 1028 (R) | MV30-HI | | -32768 | 32767 | 0 | 0.01 | 1128 |
| 1029 (R) | MV30-LO | | -32768 | 32767 | 0 | 0.01 | 1129 |
| 1030 (R) | MV31-HI | | -32768 | 32767 | 0 | 0.01 | 1130 |
| 1031 (R) | MV31-LO | | -32768 | 32767 | 0 | 0.01 | 1131 |
| 1032 (R) | MV32-HI | | -32768 | 32767 | 0 | 0.01 | 1132 |
| 1033 (R) | MV32-LO | | -32768 | 32767 | 0 | 0.01 | 1133 |
| Device Counters | | | | | | | |
| 1034 (R) | COUNTER SC01 | | 0 | 65000 | 0 | 1 | 1134 |
| | • | | | | | | • |
| | • | | | | | | • |
| | • | | | | | | • |
| 1065 (R) | COUNTER SC32 | | 0 | 65000 | 0 | 1 | 1165 |
| 1066–1081 (R) | Reserved ^c | | 0 | 0 | 0 | | 1166–1181 |

Table E.34 Modbus Register Map^a (Sheet 24 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|-----------------------|-------|-----|-------|------|--------------|-----------------------------|
| Historical Data | | | | | | | |
| 1082 (R) | NO. EVENT LOGS | | 0 | 50 | 0 | 1 | 1182 |
| 1083 (R/W) | EVENT LOG SEL | | 0 | 50 | 0 | 1 | 1183 |
| 1084 (R) | EVENT TIME ss | | 0 | 5999 | 0 | 0.01 | 1184 |
| 1085 (R) | EVENT TIME mm | | 0 | 59 | 0 | 1 | 1185 |
| 1086 (R) | EVENT TIME hh | | 0 | 23 | 0 | 1 | 1186 |
| 1087 (R) | EVENT DAY dd | | 0 | 31 | 1 | 1 | 1187 |
| 1088 (R) | EVENT DAY mm | | 0 | 12 | 1 | 1 | 1188 |
| 1089 (R) | EVENT DAY yy | | 0 | 9999 | 2000 | 1 | 1189 |
| 1090 (R) | EVENT TYPE | | 0 | 29 | 0 | | 1190 |
| | 0 = TRIP* | | | | | | |
| | 1 = DIFF 87 TRIP | | | | | | |
| | 2 = REF TRIP | | | | | | |
| | 3 = WDG1 PH 50 TRIP | | | | | | |
| | 4 = WDG1 GND 50 TRIP | | | | | | |
| | 5 = WDG1 50Q TRIP | | | | | | |
| | 6 = WDG2 PH 50 TRIP | | | | | | |
| | 7 = WDG2 GND 50 TRIP | | | | | | |
| | 8 = WDG2 50Q TRIP | | | | | | |
| | 9 = NEUTRAL 50 TRIP | | | | | | |
| | 10 = WDG1 PH 51 TRIP | | | | | | |
| | 11 = WDG1 GND 51 TRIP | | | | | | |
| | 12 = WDG1 51Q TRIP | | | | | | |
| | 13 = WDG2 PH 51 TRIP | | | | | | |
| | 14 = WDG2 GND 51 TRIP | | | | | | |
| | 15 = WDG2 51Q TRIP | | | | | | |
| | 16 = NEUTRAL 51 TRIP | | | | | | |
| | 17 = POWERELEMNT TRIP | | | | | | |
| | 18 = UNDERVOLT TRIP | | | | | | |
| | 19 = OVERVOLT TRIP | | | | | | |
| | 20 = VOLT/HZ 24 TRIP | | | | | | |
| | 21 = FREQUENCY81 TRIP | | | | | | |
| | 22 = RTD TRIP | | | | | | |
| | 23 = RTD FAIL TRIP | | | | | | |
| | 24 = BKR FAILURE TRIP | | | | | | |
| | 25 = REMOTE TRIP | | | | | | |
| | 26 = COMMIDLELOSTRIP | | | | | | |
| | 27 = TRIGGER | | | | | | |
| | 28 = ER TRIGGER | | | | | | |
| | 29 = TRIP | | | | | | |
| | 30 = WDG1 PH A 50TRIP | | | | | | |
| | 31 = WDG1 PH B 50TRIP | | | | | | |
| | 32 = WDG1 PH C 50TRIP | | | | | | |
| | 33 = WDG2 PH A 50TRIP | | | | | | |
| | 34 = WDG2 PH B 50TRIP | | | | | | |
| | 35 = WDG2 PH C 50TRIP | | | | | | |
| | 36 = WDG1 PH A 51TRIP | | | | | | |
| | 37 = WDG1 PH B 51TRIP | | | | | | |
| | 38 = WDG1 PH C 51TRIP | | | | | | |
| | 39 = WDG2 PH A 51TRIP | | | | | | |
| | 40 = WDG2 PH B 51TRIP | | | | | | |
| | 41 = WDG2 PH C 51TRIP | | | | | | |
| 1091 (R) | EVENT TARGETS | | 0 | 255 | 0 | | 1191 |
| | Bit 0 = TLED_06 | | | | | | |
| | Bit 1 = TLED_05 | | | | | | |
| | Bit 2 = TLED_04 | | | | | | |
| | Bit 3 = TLED_03 | | | | | | |
| | Bit 4 = TLED_02 | | | | | | |
| | Bit 5 = TLED_01 | | | | | | |
| | Bit 6 = TRIP_LED | | | | | | |
| | Bit 7 = ENABLED | | | | | | |
| 1092 (R) | EVENT IAW1 | A | 0 | 65535 | 0 | 1 | 1192 |
| 1093 (R) | EVENT IBW1 | A | 0 | 65535 | 0 | 1 | 1193 |
| 1094 (R) | EVENT ICW1 | A | 0 | 65535 | 0 | 1 | 1194 |
| 1095 (R) | EVENT IGW1 | A | 0 | 65535 | 0 | 1 | 1195 |
| 1096 (R) | EVENT IAW2 | A | 0 | 65535 | 0 | 1 | 1196 |
| 1097 (R) | EVENT IBW2 | A | 0 | 65535 | 0 | 1 | 1197 |
| 1098 (R) | EVENT ICW2 | A | 0 | 65535 | 0 | 1 | 1198 |
| 1099 (R) | EVENT IGW2 | A | 0 | 65535 | 0 | 1 | 1199 |
| 1100 (R) | EVENT IN | A | 0 | 65535 | 0 | 1 | 1200 |
| 1101 (R) | EVENT VAB/VAN | V | 0 | 65535 | 0 | 1 | 1201 |
| 1102 (R) | EVENT VBC/VBN | V | 0 | 65535 | 0 | 1 | 1202 |

Table E.34 Modbus Register Map^a (Sheet 25 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|---|-------|--------|-------|------|--------------|-----------------------------|
| 1103 (R) | EVENT VCA/VCN | V | 0 | 65535 | 0 | 1 | 1203 |
| 1104 (R) | EVENT VG | V | 0 | 65535 | 0 | 1 | 1204 |
| 1105 (R) | EVENT DELTA/WYE 0 = DELTA 1 = WYE | | 0 | 1 | 0 | | 1205 |
| 1106 (R) | EVENT FREQ | Hz | 2000 | 7000 | 6000 | 0.01 | 1206 |
| 1107 (R) | EVNT MAX AMB RTD | degC | -32768 | 32767 | 0 | 1 | 1207 |
| 1108 (R) | EVNT MAX OTH RTD | degC | -32768 | 32767 | 0 | 1 | 1208 |
| 1109–1116 (R) | Reserved ^c | | 0 | 0 | 0 | | 1209–1216 |

Trip/Warn Data

The Trip and Warn Status registers bits are “sticky” (once set they are not cleared until the target reset is issued from any interface) when a trip event occurs.

| | | | | | | | |
|---------------|--|--|---|-------|---|--|-----------|
| 1117 (R) | TRIP STATUS LO Bit 0 = WDG1 50 PHASE Bit 1 = WDG1 50 GROUND Bit 2 = WDG1 50 NEGSEQ Bit 3 = WDG1 51 PHASE Bit 4 = WDG1 51 GROUND Bit 5 = WDG1 51 NEGSEQ Bit 6 = WDG2 50 PHASE Bit 7 = WDG2 50 GROUND Bit 8 = WDG2 50 NEGSEQ Bit 9 = WDG2 51 PHASE Bit 10 = WDG2 51 GROUND Bit 11 = WDG2 51 NEGSEQ Bit 12 = NEUTRAL 50 Bit 13 = NEUTRAL 51 Bit 14 = RESTR DIFF 87R Bit 15 = UNRESTR DIFF 87U | | 0 | 65535 | 0 | | 1217 |
| 1118 (R) | TRIP STATUS HI Bit 0 = UNDERVOLT 27P Bit 1 = OVERVOLT 59P Bit 2 = NSEQVOLT 59Q Bit 3 = POWER ELEMENTS Bit 4 = FREQUENCY 81 Bit 5 = VOLTS/HERTZ Bit 6 = RESTRCTD EARTH Bit 7 = RTD TRIP Bit 8 = BREAKER FAIL Bit 9 = REMOTE TRIP Bit 10–Bit 14 = RESERVED Bit 15 = TRIP | | 0 | 65535 | 0 | | 1218 |
| 1119 (R) | WARN STATUS LO Bit 0 = THR FAULT ALARM Bit 1 = DEMAND ALARM Bit 2 = RTD FAULT Bit 3 = CONFIG FAULT Bit 4 = COMM FAULT Bit 5 = COMM IDLE Bit 6 = COMM LOSS Bit 7 = DIFF ALARM 87A Bit 8 = 5TH HARMONIC ALM Bit 9 = RTD ALARM Bit 10 = LOSS OF POTNTIAL Bit 11 = AI HI/LO ALARM Bit 12 = RESERVED Bit 13 = HALARM Bit 14 = SALARM Bit 15 = WARNING | | 0 | 65535 | 0 | | 1219 |
| 1120 (R) | WARN STATUS HI Bit 0–Bit 15 = RESERVED | | 0 | 65535 | 0 | | 1220 |
| 1121–1125 (R) | Reserved ^c | | 0 | 0 | 0 | | 1221–1225 |

Table E.34 Modbus Register Map^a (Sheet 26 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--|--|-------|-----|-------|-----|--------------|-----------------------------|
| Commn Counters | | | | | | | |
| 1126 (R) | NUM MSG RCVD | | 0 | 65535 | 0 | 1 | 1226 |
| 1127 (R) | NUM OTHER MSG | | 0 | 65535 | 0 | 1 | 1227 |
| 1128 (R) | INVALID ADDR | | 0 | 65535 | 0 | 1 | 1228 |
| 1129 (R) | BAD CRC | | 0 | 65535 | 0 | 1 | 1229 |
| 1130 (R) | UART ERROR | | 0 | 65535 | 0 | 1 | 1230 |
| 1131 (R) | ILLEGAL FUNCTION | | 0 | 65535 | 0 | 1 | 1231 |
| 1132 (R) | ILLEGAL REGISTER | | 0 | 65535 | 0 | 1 | 1232 |
| 1133 (R) | ILLEGAL WRITE | | 0 | 65535 | 0 | 1 | 1233 |
| 1134 (R) | BAD PKT FORMAT | | 0 | 65535 | 0 | 1 | 1234 |
| 1135 (R) | BAD PKT LENGTH | | 0 | 65535 | 0 | 1 | 1235 |
| 1136–1141 (R) | Reserved ^c | | 0 | 0 | 0 | | 1236–1241 |
| Relay Elements | | | | | | | |
| Only a few Relay Element rows report actual bit enumeration strings specific to that row. Other Relay Element rows report generic bit enumeration strings (as shown for <i>ROW 10</i>). For exact bit enumerations of these elements see <i>Appendix J: Relay Word Bits</i> . | | | | | | | |
| 1142 (R) | ROW 0 Bit 0 = TLED_06 Bit 1 = TLED_05 Bit 2 = TLED_04 Bit 3 = TLED_03 Bit 4 = TLED_02 Bit 5 = TLED_01 Bit 6 = TRIP_LED Bit 7 = ENABLED | | 0 | 255 | 0 | | 1242 |
| 1143 (R) | ROW 1 Bit 0 = 50P24T Bit 1 = 50P23T Bit 2 = 50P22T Bit 3 = 50P21T Bit 4 = 50P14T Bit 5 = 50P13T Bit 6 = 50P12T Bit 7 = 50P11T | | 0 | 255 | 0 | | 1243 |
| 1144 (R) | ROW 2 Bit 0 = 50Q22T Bit 1 = 50Q21T Bit 2 = 50G22T Bit 3 = 50G21T Bit 4 = 50Q12T Bit 5 = 50Q11T Bit 6 = 50G12T Bit 7 = 50G11T | | 0 | 255 | 0 | | 1244 |
| 1145 (R) | ROW 3 Bit 0 = REF1P Bit 1 = REF1R Bit 2 = REF1F Bit 3 = 50GREF1 Bit 4 = REF1E Bit 5 = 50NREF1 Bit 6 = 50N12T Bit 7 = 50N11T | | 0 | 255 | 0 | | 1245 |
| 1146 (R) | ROW 4 Bit 0 = * Bit 1 = 51N1T Bit 2 = 51Q2T Bit 3 = 51Q1T Bit 4 = 51G2T Bit 5 = 51G1T | | 0 | 255 | 0 | | 1246 |

Table E.34 Modbus Register Map^a (Sheet 27 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|---|-------|-----|-----|-----|--------------|-----------------------------|
| 1147 (R) | Bit 6 = 51P2T Bit 7 = 51P1T ROW 5 Bit 0 = 87R Bit 1 = 87R3 Bit 2 = 87R2 Bit 3 = 87R1 Bit 4 = 87U Bit 5 = 87U3 Bit 6 = 87U2 Bit 7 = 87U1 | | 0 | 255 | 0 | | 1247 |
| 1148 (R) | ROW 6 Bit 0 = 3PWR2T Bit 1 = 3PWR1T Bit 2 = 59P2T Bit 3 = 59P1T Bit 4 = 27P2T Bit 5 = 27P1T Bit 6 = 87AT Bit 7 = TH5T | | 0 | 255 | 0 | | 1248 |
| 1149 (R) | ROW 7 Bit 0 = 59Q2T Bit 1 = 59Q1T Bit 2 = BFT2 Bit 3 = BFT1 Bit 4 = 81D4T Bit 5 = 81D3T Bit 6 = 81D2T Bit 7 = 81D1T | | 0 | 255 | 0 | | 1249 |
| 1150 (R) | ROW 8 Bit 0 = RTDT Bit 1 = * Bit 2 = * Bit 3 = 24CR Bit 4 = 24C2T Bit 5 = 24C2 Bit 6 = 24D1T Bit 7 = 24D1 | | 0 | 255 | 0 | | 1250 |
| 1151 (R) | ROW 9 Bit 0 = ORED51T Bit 1 = ORED50T Bit 2 = * Bit 3 = * Bit 4 = * Bit 5 = * Bit 6 = * Bit 7 = REMTRIP | | 0 | 255 | 0 | | 1251 |
| 1152 (R) | ROW 10 Bit 0 = 50P24P Bit 1 = 50P23P Bit 2 = 50P22P Bit 3 = 50P21P Bit 4 = 50P14P Bit 5 = 50P13P Bit 6 = 50P12P Bit 7 = 50P11P | | 0 | 255 | 0 | | 1252 |
| 1153 (R) | ROW 11 Bit 0 = 50Q22P Bit 1 = 50Q21P Bit 2 = 50G22P Bit 3 = 50G21P Bit 4 = 50Q12P Bit 5 = 50Q11P Bit 6 = 50G12P Bit 7 = 50G11P | | 0 | 255 | 0 | | 1253 |

Table E.34 Modbus Register Map^a (Sheet 28 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--|-------|-----|-----|-----|--------------|-----------------------------|
| 1154 (R) | ROW 12 Bit 0 = 52A2 Bit 1 = 52A1 Bit 2 = 51P2AR Bit 3 = 51P1CR Bit 4 = 51P1BR Bit 5 = 51P1AR Bit 6 = 50N12P Bit 7 = 50N11P | | 0 | 255 | 0 | | 1254 |
| 1155 (R) | ROW 13 Bit 0 = 51P2BR Bit 1 = 51N1P Bit 2 = 51Q2P Bit 3 = 51Q1P Bit 4 = 51G2P Bit 5 = 51G1P Bit 6 = 51P2P Bit 7 = 51P1P | | 0 | 255 | 0 | | 1255 |
| 1156 (R) | ROW 14 Bit 0 = 51P2CR Bit 1 = 51N1R Bit 2 = 51Q2R Bit 3 = 51Q1R Bit 4 = 51G2R Bit 5 = 51G1R Bit 6 = 51P2R Bit 7 = 51P1R | | 0 | 255 | 0 | | 1256 |
| 1157 (R) | ROW 15 Bit 0 = 5HBL Bit 1 = 5HB3 Bit 2 = 5HB2 Bit 3 = 5HB1 Bit 4 = 2_4HBL Bit 5 = 2_4HB3 Bit 6 = 2_4HB2 Bit 7 = 2_4HB1 | | 0 | 255 | 0 | | 1257 |
| 1158 (R) | ROW 16 Bit 0 = 87HR Bit 1 = 87HR3 Bit 2 = 87HR2 Bit 3 = 87HR1 Bit 4 = 87HB Bit 5 = 87BL3 Bit 6 = 87BL2 Bit 7 = 87BL1 | | 0 | 255 | 0 | | 1258 |
| 1159 (R) | ROW 17 Bit 0 = 3PWR2P Bit 1 = 3PWR1P Bit 2 = 59P2 Bit 3 = 59P1 Bit 4 = 27P2 Bit 5 = 27P1 Bit 6 = 87AP Bit 7 = TH5 | | 0 | 255 | 0 | | 1259 |
| 1160 (R) | ROW 18 Bit 0 = 59Q2 Bit 1 = 59Q1 Bit 2 = BFI2 Bit 3 = BFI1 Bit 4 = OTHTRIP Bit 5 = OTHALRM Bit 6 = AMBTRIP Bit 7 = AMBALRM | | 0 | 255 | 0 | | 1260 |
| 1161 (R) | ROW 19 Bit 0 = OUT304 Bit 1 = OUT303 Bit 2 = OUT302 | | 0 | 255 | 0 | | 1261 |

Table E.34 Modbus Register Map^a (Sheet 29 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--|-------|-----|-----|-----|--------------|-----------------------------|
| 1162 (R) | Bit 3 = OUT301 Bit 4 = OUT103 Bit 5 = OUT102 Bit 6 = OUT101 Bit 7 = TRIP ROW 20 Bit 0 = OUT504 Bit 1 = OUT503 Bit 2 = OUT502 Bit 3 = OUT501 Bit 4 = OUT404 Bit 5 = OUT403 Bit 6 = OUT402 Bit 7 = OUT401 | | 0 | 255 | 0 | | 1262 |
| 1163 (R) | ROW 21 Bit 0 = IN108 Bit 1 = * Bit 2 = * Bit 3 = * Bit 4 = * Bit 5 = * Bit 6 = IN102 Bit 7 = IN101 | | 0 | 255 | 0 | | 1263 |
| 1164 (R) | ROW 22 Bit 0 = IN308 Bit 1 = IN307 Bit 2 = IN306 Bit 3 = IN305 Bit 4 = IN304 Bit 5 = IN303 Bit 6 = IN302 Bit 7 = IN301 | | 0 | 255 | 0 | | 1264 |
| 1165 (R) | ROW 23 Bit 0 = IN408 Bit 1 = IN407 Bit 2 = IN406 Bit 3 = IN405 Bit 4 = IN404 Bit 5 = IN403 Bit 6 = IN402 Bit 7 = IN401 | | 0 | 255 | 0 | | 1265 |
| 1166 (R) | ROW 24 Bit 0 = IN508 Bit 1 = IN507 Bit 2 = IN506 Bit 3 = IN505 Bit 4 = IN504 Bit 5 = IN503 Bit 6 = IN502 Bit 7 = IN501 | | 0 | 255 | 0 | | 1266 |
| 1167 (R) | ROW 25 Bit 0 = FAULT Bit 1 = IRIGOK Bit 2 = TSOK Bit 3 = WARNING Bit 4 = SALARM Bit 5 = PMDOK Bit 6 = LINKBOK Bit 7 = LINKAOK | | 0 | 255 | 0 | | 1267 |

Table E.34 Modbus Register Map^a (Sheet 30 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--|-------|-----|------|-----|--------------|-----------------------------|
| 1168 (R) | ROW 26 Bit 0 = LOP Bit 1 = * Bit 2 = * Bit 3 = * Bit 4 = CFGFLT Bit 5 = COMMFLT Bit 6 = COMMLOSS Bit 7 = COMMIDLE | | 0 | 255 | 0 | | 1268 |
| 1169 (R) | ROW 27 Bit 0 = RSTPKDEM Bit 1 = RSTDEM Bit 2 = RSTMXMN Bit 3 = RSTENRGY Bit 4 = * Bit 5 = * Bit 6 = ER Bit 7 = FREQTRK | | 0 | 255 | 0 | | 1269 |
| 1170 (R) | ROW 28 Bit 0 = HALARM Bit 1 = RSTTRGT Bit 2 = DSABLSET Bit 3 = * Bit 4 = RTDA Bit 5 = TRGTR Bit 6 = RTDIN Bit 7 = RTDFLT | | 0 | 255 | 0 | | 1270 |
| 1171 (R) | ROW 29 • • • | | 0 | 255 | 0 | | 1271 • • • |
| 1248 (R) | ROW 106 | | 0 | 255 | 0 | | 1348 |
| 1249–1270 (R) | Reserved ^c | | 0 | 0 | 0 | | 1349–1370 |
| Extra Settings | | | | | | | |
| WDG1 Per Ph TOC | | | | | | | |
| 1271 (RW) | W1 PH-A TOC EN 0 = N 1 = Y | | 0 | 1 | 0 | | 1371 |
| 1272 (RW) | W1 PH-A TOC LVL | A | 10 | 1600 | 120 | 0.01 | 1372 |
| 1273 (RW) | W1 PHA TOC CURVE 0 = U1 1 = U2 2 = U3 3 = U4 4 = U5 5 = C1 6 = C2 7 = C3 8 = C4 9 = C5 | | 0 | 9 | 2 | 1 | 1373 |
| 1274 (RW) | W1 PHA TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 1374 |
| 1275 (RW) | W1 PHA EMRST DLY 0 = N 1 = Y | | 0 | 1 | 0 | | 1375 |
| 1276 (RW) | W1 PHA CONST TIM | sec | 0 | 100 | 0 | 0.01 | 1376 |
| 1277 (RW) | W1 PHA MIN TIM | sec | 0 | 100 | 0 | 0.01 | 1377 |
| 1278 (RW) | W1 PH-B TOC EN 0 = N 1 = Y | | 0 | 1 | 0 | | 1378 |
| 1279 (RW) | W1 PH-B TOC LVL | A | 10 | 1600 | 120 | 0.01 | 1379 |
| 1280 (RW) | W1 PHB TOC CURVE 0 = U1 1 = U2 5 = C1 6 = C2 | | 0 | 9 | 2 | 1 | 1380 |

Table E.34 Modbus Register Map^a (Sheet 31 of 36)

| Modbus Register Address ^b | | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|------|--|-------|-----|------|------|--------------|-----------------------------|
| | | 2 = U3 3 = U4 4 = U5 7 = C3 8 = C4 9 = C5 | | | | | | |
| 1281 | (RW) | W1 PHB TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 1381 |
| 1282 | (RW) | W1 PHB EMRST DLY 0 = N 1 = Y | | 0 | 1 | 0 | | 1382 |
| 1283 | (RW) | W1 PHB CONST TIM | sec | 0 | 100 | 0 | 0.01 | 1383 |
| 1284 | (RW) | W1 PHB MIN TIM | sec | 0 | 100 | 0 | 0.01 | 1384 |
| 1285 | (RW) | W1 PH-C TOC EN 0 = N 1 = Y | | 0 | 1 | 0 | | 1385 |
| 1286 | (RW) | W1 PH-C TOC LVL | A | 10 | 1600 | 120 | 0.01 | 1386 |
| 1287 | (RW) | W1 PHC TOC CURVE 0 = U1 1 = U2 2 = U3 3 = U4 4 = U5 5 = C1 6 = C2 7 = C3 8 = C4 9 = C5 | | 0 | 9 | 2 | 1 | 1387 |
| 1288 | (RW) | W1 PHC TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 1388 |
| 1289 | (RW) | W1 PHC EMRST DLY 0 = N 1 = Y | | 0 | 1 | 0 | | 1389 |
| 1290 | (RW) | W1 PHC CONST TIM | sec | 0 | 100 | 0 | 0.01 | 1390 |
| 1291 | (RW) | W1 PHC MIN TIM | sec | 0 | 100 | 0 | 0.01 | 1391 |
| WDG2 Per Ph TOC | | | | | | | | |
| 1292 | (RW) | W2 PH-A TOC EN 0 = N 1 = Y | | | 0 | 1 | 0 | 1392 |
| 1293 | (RW) | W2 PH-A TOC LVL | A | 10 | 1600 | 120 | 0.01 | 1393 |
| 1294 | (RW) | W2 PHA TOC CURVE 0 = U1 1 = U2 2 = U3 3 = U4 4 = U5 5 = C1 6 = C2 7 = C3 8 = C4 9 = C5 | 0 | | 9 | 2 | 1 | 1394 |
| 1295 | (RW) | W2 PHA TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 1395 |
| 1296 | (RW) | W2 PHA EMRST DLY 0 = N 1 = Y | | | 0 | 1 | 0 | 1396 |
| 1297 | (RW) | W2 PHA CONST TIM | sec | 0 | 100 | 0 | 0.01 | 1397 |
| 1298 | (RW) | W2 PHA MIN TIM | sec | 0 | 100 | 0 | 0.01 | 1398 |
| 1299 | (RW) | W2 PH-B TOC EN 0 = N 1 = Y | 0 | 1 | 0 | 1399 | | |
| 1300 | (RW) | W2 PH-B TOC LVL | A | 10 | 1600 | 120 | 0.01 | 1400 |
| 1301 | (RW) | W2 PHB TOC CURVE 0 = U1 1 = U2 2 = U3 3 = U4 4 = U5 5 = C1 6 = C2 7 = C3 8 = C4 9 = C5 | | 0 | 9 | 2 | 1 | 1401 |
| 1302 | | W2 PHB TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 1402 |

Table E.34 Modbus Register Map^a (Sheet 32 of 36)

| Modbus Register Address ^b | | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|------|--|-------|-----|-------|-----|--------------|-----------------------------|
| 1303 | (RW) | W2 PHB EMRST DLY 0 = N 1 = Y | | | 0 | 1 | 0 | 1403 |
| 1304 | (RW) | W2 PHB CONST TIM | sec | 0 | 100 | 0 | 0.01 | 1404 |
| 1305 | (RW) | W2 PHB MIN TIM | sec | 0 | 100 | 0 | 0.01 | 1405 |
| 1306 | (RW) | W2 PH-C TOC EN 0 = N 1 = Y | | | 0 | 1 | 0 | 1406 |
| 1307 | (RW) | W2 PH-C TOC LVL | A | 10 | 1600 | 120 | 0.01 | 1407 |
| 1308 | (RW) | W2 PHC TOC CURVE 0 = U1 5 = C1 1 = U2 6 = C2 2 = U3 7 = C3 3 = U4 8 = C4 4 = U5 9 = C5 | | 0 | 9 | 2 | 1 | 1408 |
| 1309 | (RW) | W2 PHC TOC TDIAL | | 5 | 1500 | 300 | 0.01 | 1409 |
| 1310 | (RW) | W2 PHC EMRST DLY 0 = N 1 = Y | | | 0 | 1 | 0 | 1410 |
| 1311 | (RW) | W2 PHC CONST TIM | sec | 0 | 100 | 0 | 0.01 | 1411 |
| 1312 | (RW) | W2 PHC MIN TIM | sec | 0 | 100 | 0 | 0.01 | 1412 |
| Control I/O Commands | | | | | | | | |
| 2000H | (W) | LOGIC COMMAND Bit 0 = Breaker1 Close Bit 1 = Breaker1 Open Bit 2 = Breaker2 Close Bit 3 = Return Status 0/1 Bit 4 = DN Aux 1 Cmd Bit 5 = DN Aux 2 Cmd Bit 6 = DN Aux 3 Cmd Bit 7 = DN Aux 4 Cmd Bit 8 = DN Aux 5 Cmd Bit 9 = DN Aux 6 Cmd Bit 10 = DN Aux 7 Cmd Bit 11 = DN Aux 8 Cmd Bit 12 = DN Aux 9 Cmd Bit 13 = DN Aux 10 Cmd Bit 14 = DN Aux 11 Cmd Bit 15 = Breaker2 Open | | 0 | 65535 | 0 | na | |
| 2001H | (W) | RESET COMMAND Bit 0 = Trip Reset Bit 1 = Set to Defaults Bit 2 = Reset Stat Data Bit 3 = Reset Hist Data Bit 4 = Reset Comm Cntr Bit 5 = Reserved Bit 6 = Rst Enrgy Data Bit 7 = Rst Mx/Mn Data Bit 8 = Rst Demand Bit 9 = Rst Peak Demand Bit 10–Bit 15 = Reserved | | 0 | 255 | 0 | na | |
| Relay Elements | | | | | | | | |
| 2100H | (R) | FAST STATUS 0 Bit 0 = Faulted Bit 1 = Warning Bit 2 = IN1/IN101 Status Bit 3 = IN2/IN102 Status Bit 4 = IN3/IN401 Status Bit 5 = IN4/IN402 Status Bit 6 = IN5/IN403 Status Bit 7 = Reserved Bit 8 = AUX1/OUT101 Status | | 0 | 65535 | 0 | na | |

Table E.34 Modbus Register Map^a (Sheet 33 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--|-------|-----|-------|-----|--------------|-----------------------------|
| 2101H (R) | Bit 9 = AUX2/OUT102 Status Bit 10 = AUX3/OUT401 Status Bit 11 = AUX4/OUT402 Status Bit 12 = AUX5/OUT403 Status Bit 13 = AUX6/OUT404 Status Bit 14–Bit 15 = Reserved FAST STATUS 1 Bit 0 = Enabled Bit 1 = Reserved Bit 2 = IN6/IN404 Status Bit 3 = IN7/IN501 Status Bit 4 = IN8/IN502 Status Bit 5 = IN9/IN503 Status Bit 6 = IN10/IN504 Status Bit 7 = Reserved Bit 8 = AUX7/OUT501 Status Bit 9 = AUX8/OUT502 Status Bit 10 = AUX9/OUT503 Status Bit 11 = AUX10/OUT504 Status Bit 12–Bit 15 = Reserved | | 0 | 65535 | 0 | na | |
| 2102H (R) | TRIP STATUS LO | | | | | na | |
| 2103H (R) | TRIP STATUS HI | | | | | na | |
| 2104H (R) | WARN STATUS LO | | | | | na | |
| 2105H (R) | WARN STATUS HI | | | | | na | |
| 2106H (R) | AVERAGE CURRENT | | | | | na | |
| 2107H (R) | IAW1 CURRENT | | | | | na | |
| 2108H (R) | IBW1 CURRENT | | | | | na | |
| 2109H (R) | ICW1 CURRENT | | | | | na | |
| 210AH–210CH (R) | Reserved ^c | | | | | na | |
| 210DH (R) | IGW1 CURRENT | | | | | na | |
| 210EH (R) | IN1 CURRENT | | | | | na | |
| 210FH (R) | Reserved ^c | | | | | na | |
| 2110H (R) | FAST STATUS 2 Bit 0 = IN11/IN301 Status Bit 1 = IN12/IN302 Status Bit 2 = IN13/IN303 Status Bit 3 = IN14/IN304 Status Bit 4 = OUT11/OUT301 Status Bit 5 = OUT12/OUT302 Status Bit 6 = OUT13/OUT303 Status Bit 7 = OUT14/OUT304 Status Bit 8 = IN15/IN305 Status Bit 9 = IN16/IN306 Status Bit 10 = IN17/IN307 Status Bit 11 = IN18/IN308 Status Bit 12–Bit 15 = Reserved | | 0 | 65535 | 0 | na | |
| 2111H (R) | FAST STATUS 3 Bit 0 = IN19/IN405 Status Bit 1 = IN20/IN406 Status Bit 2 = IN21/IN407 Status Bit 3 = IN22/IN408 Status Bit 4 = IN23/IN505 Status Bit 5 = IN24/IN506 Status Bit 6 = IN25/IN507 Status Bit 7 = IN26/IN508 Status Bit 8–Bit 15 = Reserved | | 0 | 65535 | 0 | na | |
| PAR GROUP INDICES | | | | | | | |
| 3000H (R) | Reserved ^c | | 0 | 0 | 0 | na | |
| 3001H (R) | USER MAP REG | | 1 | 125 | 1 | 1 | |

Table E.34 Modbus Register Map^a (Sheet 34 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|-------------------|-------|-----|-----|-----|--------------|-----------------------------|
| 3002H (R) | USER MAP REG VAL | | 126 | 250 | 126 | 1 | |
| 3003H (R) | RESERVED AREA1 | | 251 | 259 | 259 | 1 | |
| 3004H (R) | ACCESS CONTROL | | 260 | 260 | 260 | 1 | |
| 3005H (R) | GENERAL SETTINGS | | 261 | 264 | 261 | 1 | |
| 3006H (R) | GROUP SELECTION | | 265 | 265 | 265 | 1 | |
| 3007H (R) | BRKR FAILURE SET | | 266 | 268 | 266 | 1 | |
| 3008H (R) | THR FAULT SET | | 269 | 275 | 269 | 1 | |
| 3009H (R) | CONFIG SETTINGS | | 276 | 297 | 276 | 1 | |
| 300AH (R) | XFMR DIFFERENTIAL | | 298 | 321 | 298 | 1 | |
| 300BH (R) | RESTR EARTH FLT | | 322 | 323 | 322 | 1 | |
| 300CH (R) | WDG1 MAX PH IOC | | 324 | 335 | 324 | 1 | |
| 300DH (R) | WDG1 RES IOC | | 336 | 341 | 336 | 1 | |
| 300EH (R) | WDG1 NEG SEQ IOC | | 342 | 347 | 342 | 1 | |
| 300FH (R) | WDG1 MAX PH TOC | | 348 | 354 | 348 | 1 | |
| 3010H (R) | WDG1 RES TOC | | 355 | 361 | 355 | 1 | |
| 3011H (R) | WDG1 NEG SEQ TOC | | 362 | 368 | 362 | 1 | |
| 3012H (R) | WDG2 MAX PH IOC | | 369 | 380 | 369 | 1 | |
| 3013H (R) | WDG2 RES IOC | | 381 | 386 | 381 | 1 | |
| 3014H (R) | WDG2 NEG SEQ IOC | | 387 | 392 | 387 | 1 | |
| 3015H (R) | WDG2 MAX PH TOC | | 393 | 399 | 393 | 1 | |
| 3016H (R) | WDG2 RES TOC | | 400 | 406 | 400 | 1 | |
| 3017H (R) | WDG2 NEG SEQ TOC | | 407 | 413 | 407 | 1 | |
| 3018H (R) | NEUTRAL IOC | | 414 | 419 | 414 | 1 | |
| 3019H (R) | NEUTRAL TOC | | 420 | 431 | 420 | 1 | |
| 301AH (R) | RTD SETTINGS | | 432 | 486 | 432 | 1 | |
| 301BH (R) | PH UNDERVOLTAGE | | 487 | 492 | 487 | 1 | |
| 301CH (R) | PH OVERVOLTAGE | | 493 | 498 | 493 | 1 | |
| 301DH (R) | NSEQ OVERVOLTAGE | | 499 | 504 | 499 | 1 | |
| 301EH (R) | RESERVED AREA2 | | 505 | 514 | 505 | 1 | |
| 301FH (R) | VOLTS PER HERTZ | | 515 | 527 | 515 | 1 | |
| 3020H (R) | POWER ELEMENTS | | 528 | 536 | 528 | 1 | |
| 3021H (R) | FREQ SETTINGS | | 537 | 548 | 537 | 1 | |
| 3022H (R) | DEMAND MTR SET | | 549 | 554 | 549 | 1 | |
| 3023H (R) | RESERVED AREA3 | | 555 | 564 | 555 | 1 | |
| 3024H (R) | TRIP/CLOSE LOGIC | | 565 | 575 | 565 | 1 | |
| 3025H (R) | SELogIC ENABLES | | 576 | 584 | 576 | 1 | |
| 3026H (R) | OUTPUT CONTACTS | | 585 | 604 | 585 | 1 | |
| 3027H (R) | EVENT REPORT SET | | 605 | 614 | 605 | 1 | |
| 3028H (R) | FRONT PANEL SET | | 615 | 624 | 615 | 1 | |
| 3029H (R) | RESET SETTINGS | | 625 | 635 | 625 | 1 | |
| 302AH (R) | DATE/TIME SET | | 636 | 643 | 636 | 1 | |
| 302BH (R) | DEVICE STATUS | | 644 | 683 | 644 | 1 | |

Table E.34 Modbus Register Map^a (Sheet 35 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|--|-------|------|-------|------|--------------|-----------------------------|
| 302CH (R) | CURRENT DATA | | 684 | 708 | 684 | 1 | |
| 302DH (R) | VOLTAGE DATA | | 709 | 725 | 709 | 1 | |
| 302EH (R) | POWER DATA | | 726 | 731 | 726 | 1 | |
| 302FH (R) | ENERGY DATA | | 732 | 753 | 732 | 1 | |
| 3030H (R) | DEMAND DATA | | 754 | 758 | 754 | 1 | |
| 3031H (R) | PEAK DEMAND DATA | | 759 | 769 | 759 | 1 | |
| 3032H (R) | HARMONIC DATA | | 770 | 781 | 770 | 1 | |
| 3033H (R) | RTD DATA | | 782 | 796 | 782 | 1 | |
| 3034H (R) | RESERVED AREA4 | | 797 | 806 | 797 | 1 | |
| 3035H (R) | RMS DATA | | 807 | 819 | 807 | 1 | |
| 3036H (R) | MAX/MIN MTR DATA | | 820 | 851 | 820 | 1 | |
| 3037H (R) | MAX/MIN RTD DATA | | 852 | 875 | 852 | 1 | |
| 3038H (R) | MAX/MIN AI3 DATA | | 876 | 891 | 876 | 1 | |
| 3039H (R) | MAX/MIN AI4 DATA | | 892 | 907 | 892 | 1 | |
| 303AH (R) | MAX/MIN AI5 DATA | | 908 | 923 | 908 | 1 | |
| 303BH (R) | MAX/MIN RST DATA | | 924 | 939 | 924 | 1 | |
| 303CH (R) | ANA INP DATA | | 940 | 969 | 940 | 1 | |
| 303DH (R) | MATH VARIABLES | | 970 | 1033 | 970 | 1 | |
| 303EH (R) | DEVICE COUNTERS | | 1034 | 1065 | 1034 | 1 | |
| 303FH (R) | RESERVED AREA5 | | 1066 | 1081 | 1066 | 1 | |
| 3040H (R) | HISTORICAL DATA | | 1082 | 1116 | 1082 | 1 | |
| 3041H (R) | TRIP/WARN DATA | | 1117 | 1125 | 1117 | 1 | |
| 3042H (R) | COMMN COUNTERS | | 1126 | 1141 | 1126 | 1 | |
| 3043H (R) | RELAY ELEMENTS | | 1142 | 1249 | 1142 | 1 | |
| 3044H (R) | RESERVED AREA6 | | 1250 | 1270 | 1250 | 1 | |
| 3045H (R) | WDG1 PER PH TOC | | 1271 | 1291 | 1271 | 1 | |
| 3046H (R) | WDG2 PER PH TOC | | 1292 | 1312 | 1292 | 1 | |
| PRODUCT INFORMATION | | | | | | | |
| 4000H (R) | VENDOR CODE 865 = SEL | | 0 | 65535 | 865 | na | |
| 4001H (R) | PRODDUCT CODE | | 0 | 65535 | 105 | na | |
| 4002H (R/W) | ASA NUMBER LOW | | 0 | 65535 | | na | |
| 4003H (R/W) | ASA NUMBER HIGH | | 0 | 65535 | | na | |
| 4004H (R) | FIRMWARE REVISION | | 1 | 32639 | | na | |
| 4005H (R) | NUM OF PAR | | 1 | 2000 | 1312 | na | |
| 4006H (R) | NUM OF PAR GROUP | | 1 | 100 | 70 | na | |
| 4007H (R/W) | MAC ID 64-99 = Swr Configurable | | 1 | 99 | 0 | na | |
| 4008H (R/W) | DN BAUD RATE 0 = 125 kbps 1 = 250 kbps 2 = 500 kbps 3 = AUTO 4-9 = Swr Configurable | | 0 | 9 | 0 | na | |
| 4009H (R/W) | DN STATUS Bit 0 = Explicit Cnxn Bit 1 = I/O Cnxn | | 0 | 31 | 0 | na | |

Table E.34 Modbus Register Map^a (Sheet 36 of 36)

| Modbus Register Address ^b | Name / Enums | Units | Min | Max | Def | Scale Factor | DeviceNet Parameter Numbers |
|--------------------------------------|---|-------|-------|-------|-----|--------------|-----------------------------|
| | Bit 2 = Explicit Fault Bit 3 = I/O Fault Bit 4 = I/O Idle Bit 5–Bit 15 = Reserved | | | | | | |
| 400AH | not used | | | | | | |
| 400BH (R) | CONFIG PAR CKSUM | | | | 0 | na | |
| 400CH (R) | LANGUAGE CODE 0 = English 1 = French 2 = Spanish (Mexican) 3 = Italian 4 = German 5 = Japanese 6 = Portuguese 7 = Mandarin Chinese 8 = Russian 9 = Dutch | | | | 0 | na | |
| 400DH (R) | FIRMWARE BUILD NUM | | 16400 | 16400 | 0 | na | |
| 400EH | not used | | | | | | |
| 400FH (R) | PRODUCT SUPPORT BITS Bit 0 = 2nd IO Card installed Bits 1–15 = Reserved | | | | | na | |
| 4010H (R/W) | SETTINGS TIMEOUT | ms | 500 | 65535 | 750 | na | |
| 4011H–4013H | Reserved ^c | | | | | | |
| 4014H (R) | CONFIGURED BIT Bit 0 = Unit Configured Bits 1–15 = Reserved | | | | 0 | na | |
| 4015H (R) | Reserved ^c | | 0 | 0 | 0 | na | |
| 4016H (R) | ERROR REGISTER Bit 0 = Settings Read Error, Bit 1 = Setting Write Error, Bit 2 = Settings Update Error, Bit 3 = Settings Resource Error, Bit 4 = Settings Locked, Bit 5 = Group Settings Error, Bit 6 = Global Settings Error, Bit 7 = Logic Settings Error Bit 8 = Report Settings Error Bit 9 = Front Panel Settings Error Bit 10 = Memory Not Available, Bit 11 = Settings Prep Error, Bit 12 = Setting Changes Disabled, Bit 13 = Memory Diag Error Bit 14–Bit 15 = Reserved | | 0 | 65535 | 0 | na | |
| 4017H (R) | Error Address | | 0 | 65535 | 0 | na | |
| 4018H–401FH (R) | Reserved ^c | | 0 | 0 | 0 | na | |

^a All addresses in this table refer to the register addresses in the Modbus packet.

^b Registers labeled (R)/(W) are read-write registers. Registers labeled (W) are write-only registers. Registers Labeled (R) are read-only registers.

^c Reserved addresses return 0.

^d Read this register only when the PT connection is DELTA.

^e Read this register only when the PT connection is WYE.

^f The HI and LO registers are high and low 16-bits, respectively. They provide 32-bit information by combining to form a 32-bit register and then applying sign and scaling attributes.

Appendix F

IEC 61850 Communications

Features

The SEL-787 relay supports the following features using Ethernet® and IEC 61850:

- **SCADA**—Connect as many as six simultaneous IEC 61850 MMS client sessions. The SEL-787 also supports as many as six buffered and six unbuffered report control blocks. See *Table F.14*, the CON Logical Device table for Logical Node mapping that enables SCADA control via a Manufacturing Messaging Specification (MMS) browser. Controls support the direct control, Select Before Operate (SBO), and SBO with enhanced security control models.
- **Peer-to-Peer Real-Time Status and Control**—Use GOOSE with as many as 16 incoming (receive) and 8 outgoing (transmit) messages. Virtual bits (VB001–VB128), Breaker Open (OC1, OC2), and Breaker Close (CC1, CC2) bits can be mapped from incoming GOOSE messages.
- **Configuration**—Use FTP client software or ACSELERATOR Architect® SEL-5032 Software to transfer the Substation Configuration Language (SCL) Configured IED Description (CID) file to the relay.
- **Commissioning and Troubleshooting**—Use software, such as MMS Object Explorer and AX-S4 MMS from Cisco, Inc., to browse the relay logical nodes and verify functionality.

NOTE: The SEL-787 supports one CID file, which should be transferred only if a change in the relay configuration is required. If an invalid CID file is transferred, the relay will no longer have a valid IEC 61850 configuration, and the protocol will stop operating. To restart protocol operation, a valid CID must be transferred to the relay.

This appendix presents the information you need to use the IEC 61850 features of the SEL-787:

- Introduction to IEC 61850
- IEC 61850 Operation
- IEC 61850 Configuration
- Logical Node Extensions
- Protocol Implementation Conformance Statement
- ACSI Conformance Statement

Introduction to IEC 61850

In the early 1990s, the Electric Power Research Institute (EPRI) and the Institute of Electrical and Electronics Engineers, Inc. (IEEE) began to define a Utility Communications Architecture (UCA). They initially focused on inter-control center and substation-to-control center communications and produced the Inter-Control Center Communications Protocol (ICCP) specification. This specification, later adopted by the IEC as 60870-6 TASE.2, became the standard protocol for real-time exchange of data between databases.

In 1994, EPRI and IEEE began work on UCA 2.0 for Field Devices (simply referred to as UCA2). In 1997, they combined efforts with Technical Committee 57 of the IEC to create a common international standard. Their joint efforts created the current IEC 61850 standard.

The IEC 61850 standard, a superset of UCA2, contains most of the UCA2 specification, plus additional functionality. The standard describes client/server and peer-to-peer communications, substation design and configuration, testing, and project standards. The IEC 61850 standard consists of the parts listed in *Table F.1*.

Table F.1 IEC 61850 Document Set

| IEC 61850 Sections | Definitions |
|--------------------|--|
| IEC 61850-1 | Introduction and overview |
| IEC 61850-2 | Glossary |
| IEC 61850-3 | General requirements |
| IEC 61850-4 | System and project management |
| IEC 61850-5 | Communication requirements |
| IEC 61850-6 | Configuration description language for substation IEDs |
| IEC 61850-7-1 | Basic communication structure for substations and feeder equipment—Principles and models |
| IEC 61850-7-2 | Basic communication structure for substations and feeder equipment—Abstract Communication Service Interface (ACSI) |
| IEC 61850-7-3 | Basic communication structure for substations and feeder equipment—Common data classes |
| IEC 61850-7-4 | Basic communication structure for substations and feeder equipment—Compatible logical node (LN) classes and data classes |
| IEC 61850-8-1 | SCSM-Mapping to Manufacturing Messaging Specification (MMS) (ISO/IEC 9506-1 and ISO/IEC 9506-2 over ISO/IEC 8802-3) |
| IEC 61850-9-1 | SCSM-Sampled values over serial multidrop point-to-point link |
| IEC 61850-9-2 | SCSM-Sampled values over ISO/IEC 8802-3 |
| IEC 61850-10 | Conformance testing |

The IEC 61850 document set, available directly from the IEC at <http://www.iec.ch>, contains information necessary for successful implementation of this protocol. SEL strongly recommends that anyone involved with the design, installation, configuration, or maintenance of IEC 61850 systems be familiar with the appropriate sections of these documents.

IEC 61850 Operation

Ethernet Networking

IEC 61850 and Ethernet networking are available as options in the SEL-787. In addition to IEC 61850, the Ethernet port provides support protocols and data exchange, including FTP and Telnet. Access the SEL-787 Port 1 settings to configure all of the Ethernet settings, including IEC 61850 enable settings.

The SEL Ethernet port supports IEC 61850 services, including transport of Logical Node objects, over TCP/IP. The Ethernet port can coordinate a maximum of six concurrent IEC 61850 sessions.

Object Models

The IEC 61850 standard relies heavily on the Abstract Communication Service Interface (ACSI) model to define a set of service and the responses to those services. In terms of network behavior, abstract modeling enables all IEDs to act identically. These abstract models are used to create objects (data items) and services that exist independently of any underlying protocols. These objects are in conformance with the common data class (CDC) specification IEC 61850-7-3, which describes the type and structure of each element within a logical node. CDCs for status, measurements, controllable analogs and statuses, and settings all have unique CDC attributes. Each CDC attribute belongs to a set of functional constraints that groups the attributes into specific categories such as status (ST), description (DC), and substituted value (SV). Functional constraints, CDCs and CDC attributes are used as building blocks for defining Local Nodes.

UCA2 uses GOMSFE (Generic Object Models for Substation and Feeder Equipment) to present data from station IEDs as a series of objects called models or bricks. The IEC working group has incorporated GOMSFE concepts into the standard, with some modifications to terminology; one change was the renaming of bricks to logical nodes. Each logical node represents a group of data (controls, status, measurements, etc.) associated with a particular function. For example, the MMXU logical node (polyphase measurement unit) contains measurement data and other points associated with three-phase metering including voltages and currents. Each IED may contain many functions such as protection, metering, and control. Multiple logical nodes represent the functions in multifunction devices.

Logical nodes can be organized into logical devices that are similar to directories on a computer disk. As represented in the IEC 61850 network, each physical device can contain many logical devices, and each logical device can contain many logical nodes. Many relays, meters, and other IEC 61850 devices contain one primary logical device where all models are organized.

IEC 61850 devices are capable of self-description. You do not need to refer to the specifications for the logical nodes, measurements, and other components to request data from another IEC 61850 device. IEC 61850 clients can request and display a list and description of the data available in an IEC 61850 server device. This process is similar to the autoconfiguration process used within SEL communications processors (SEL-2032 and SEL-2030). Simply run an MMS browser to query devices on an IEC 61850 network and discover what data are available. Self-description also permits extensions to both standard and custom data models. Instead of having to look up data in a profile stored in its database, an IEC 61850 client can simply query an IEC 61850 device and receive a description of all logical devices, logical nodes, and available data.

Unlike other Supervisory Control and Data Acquisition (SCADA) protocols that present data as a list of addresses or indices, IEC 61850 presents data with descriptors in a composite notation made up of components. *Table F.2* shows how the Winding 1A-phase current expressed as MMXU\$A1\$phsA\$cVal is broken down into its component parts.

Table F.2 Example IEC 61850 Descriptor Components

| Components | | Description |
|------------|-----------------|------------------------------------|
| MMXU | Logical Node | Polyphase measurement unit |
| A1 | Data Object | Phase-to-ground amperes, Winding 1 |
| PhsA | Sub-Data Object | Phase A |
| cVal | Data Attribute | Complex value |

Data Mapping

Device data are mapped to IEC 61850 Logical Nodes (LN) according to rules defined by SEL. Refer to IEC 61850-5:2003(E) and IEC 61850-7-4:2003(E) for the mandatory content and usage of these LNs. The SEL-787 Logical Nodes are grouped under Logical Devices for organization based on function. See *Table F.3* for descriptions of the Logical Devices in an SEL-787. See *Logical Nodes* for a description of the LNs that make up these Logical Devices.

Table F.3 SEL-787 Logical Devices

| Logical Device | Description |
|----------------|--|
| ANN | Annunciator elements—alarms, status values |
| CFG | Configuration elements—datasets and report control blocks |
| CON | Control elements—Remote bits |
| MET | Metering or Measurement elements—currents, voltages, power, etc. |
| PRO | Protection elements—protection functions and breaker control |

MMS

Manufacturing Messaging Specification (MMS) provides services for the application-layer transfer of real-time data within a substation LAN. MMS was developed as a network independent data exchange protocol for industrial networks in the 1980s and standardized as ISO 9506.

In theory, you can map IEC 61850 to any protocol. However, it can be unwieldy and quite complicated to map objects and services to a protocol that only provides access to simple data points via registers or index numbers. MMS supports complex named objects and flexible services that enable mapping to IEC 61850 in a straightforward manner. This was why the UCA users group used MMS for UCA from that start, and why the IEC chose to keep it for IEC 61850.

GOOSE

The Generic Object Oriented Substation Event (GOOSE) object within IEC 61850 is for high-speed control messaging. IEC 61850 GOOSE automatically broadcasts messages containing status, controls, and measured values onto the network for use by other devices. IEC 61850 GOOSE sends the messages several times, increasing the likelihood that other devices receive the messages.

IEC 61850 GOOSE objects can quickly and conveniently transfer status, controls, and measured values between peers on an IEC 61850 network. Configure SEL devices to respond to GOOSE messages from other network

with ACSELERATOR Architect. Also, configure outgoing GOOSE messages for SEL devices in ACSELERATOR Architect. See the ACSELERATOR Architect online help for more information.

Each IEC 61850 GOOSE sender includes a text identification string (GOOSE Control Block Reference) in each outgoing message and an Ethernet multicast group address. Devices that receive GOOSE messages use the text identification and multicast group to identify and filter incoming GOOSE messages.

NOTE: Any device bits mapped to GOOSE subscriptions retain state until overwritten or the device restarts. When loading a new CID file, be sure to issue an **STA C** command or cycle power to the device to clear the device bits if the configuration has changed.

Virtual bits (VB001–VB128) are control inputs that you can map to GOOSE receive messages using ACSELERATOR Architect. See the *VBnnn* bits in *Table F.15* for details on which logical nodes and names are used for these bits. This information can be useful when searching through device data with MMS browsers. If you intend to use any SEL-787 virtual bits for controls, you must create ACSELERATOR Architect equations to define these operations. The Virtual Bit Logical Nodes only contain Virtual Bit status, and only those Virtual Bits that are assigned to an SER report will be able to track bit transitions (via reporting) between LN data update scans.

In addition to the Virtual Bits, the breaker control bits *CCn* and *OCn* can also be mapped to GOOSE receive messages.

File Services

The Ethernet File System allows reading or writing data as files. The File System supports FTP. The File System provides:

- A means for the devices to transfer data as files
- A hierarchical file structure for the device data (root level only for SEL-700 series devices)

SCL Files

Substation Configuration Language (SCL) is an XML-based configuration language used to support the exchange of database configuration data between different tools, which may come from different manufacturers. There are four types of SCL files:

- IED Capability Description file (.ICD)
- System Specification Description (.SSD) file
- Substation Configuration Description file (.SCD)
- Configured IED Description file (.CID)

The ICD file described the capabilities of an IED, including information on LN and GOOSE support. The SSD file describes the single-line diagram of the substation and the required LNs. The SCD file contains information on all IEDs, communications configuration data, and a substation description. The CID file, of which there may be several, describes a single instantiated IED within the project, and includes address information.

Reports

The SEL-787 supports buffered and unbuffered report control blocks in the report model as defined in IEC 61850-8-1:2004(E). The predefined reports shown in *Figure F.1* are available by default via IEC 61850.

| Reports | | | |
|---|--------|---------------------------------|----------|
| Drag a column header here to group by that column | | | |
| | | | Print |
| ID | Name | Description | Dataset |
| BRep01 | BRep01 | Predefined Buffered Report 01 | BRDSet01 |
| BRep02 | BRep02 | Predefined Buffered Report 02 | BRDSet02 |
| BRep03 | BRep03 | Predefined Buffered Report 03 | BRDSet03 |
| BRep04 | BRep04 | Predefined Buffered Report 04 | BRDSet04 |
| BRep05 | BRep05 | Predefined Buffered Report 05 | BRDSet05 |
| BRep06 | BRep06 | Predefined Buffered Report 06 | BRDSet06 |
| URep01 | URep01 | Predefined Unbuffered Report 01 | URDSet01 |
| URep02 | URep02 | Predefined Unbuffered Report 02 | URDSet02 |
| URep03 | URep03 | Predefined Unbuffered Report 03 | URDSet03 |
| URep04 | URep04 | Predefined Unbuffered Report 04 | URDSet04 |
| URep05 | URep05 | Predefined Unbuffered Report 05 | URDSet05 |
| URep06 | URep06 | Predefined Unbuffered Report 06 | URDSet06 |

Figure F.1 SEL-787 Predefined Reports

There are 12 report control blocks, six buffered reports and six unbuffered. For each report control block, there can be just one client association, i.e., only one client can be associated to a report control block (BRCB or URCB) at any given time. The number of reports (12) and the type of reports (buffered or unbuffered) cannot be changed. However, by using ACSELERATOR Architect, you can reallocate data within each report dataset to present different data attributes for each report beyond the predefined datasets. For buffered reports, connected clients may edit the report parameters shown in *Table F.4*.

Table F.4 Buffered Report Control Block Client Access

| RCB Attribute | User changeable (Report Disabled) | User changeable (Report Enabled) | Default Values |
|---------------|--------------------------------------|-------------------------------------|--|
| RptId | YES | | BRep01–BRep06 |
| RptEna | YES | YES | FALSE |
| OptFlds | YES | | seqNum timeStamp dataSet configRef reasonCode dataRef |
| BufTm | YES | | 500 |
| TrgOp | YES | | dchg qchg |
| IntgPd | YES | | 0 |
| GI | YES ^{a b} | YES ^a | FALSE |
| PurgeBuf | YES ^a | | FALSE |
| EntryId | YES | | 0 |

^a Exhibits a pulse behavior. Write a one to issue the command. Once the command is accepted, it will return to zero. Always read as zero.

^b When disabled, a GI will be processed and the report buffered if a buffer has been previously established. A buffer is established when the report is enabled for the first time.

Similarly, for unbuffered reports, connected clients may edit the report parameters shown in *Table F.5*.

Table F.5 Unbuffered Report Control Block Client Access

| RCB Attribute | User changeable (Report Disabled) | User changeable (Report Enabled) | Default Values |
|---------------|--------------------------------------|-------------------------------------|--|
| RptId | YES | | URep01–URep06 |
| RptEna | YES | YES | FALSE |
| Resv | YES | | FALSE |
| OptFlds | YES | | seqNum timeStamp dataSet configRef reasonCode dataRef |
| BufTm | YES | | 250 |
| TrgOps | YES | | dchg qchg |
| IntgPd | YES | | 0 |
| GI | | YES ^a | 0 |

^a Exhibits a pulse behavior. Write a one to issue the command. Once the command is accepted, it will return to zero. Always read as zero.

For Buffered Reports, only one client can enable the RptEna attribute of the BRCB at a time resulting in a client association for that BRCB. Once enabled, the associated client has exclusive access to the BRCB until the connection is closed or the client disables the RptEna attribute. Once enabled, all unassociated clients have read only access to the BRCB.

For Unbuffered Reports, as many as six (6) clients can enable the RptEna attribute of the URCB at a time, resulting in multiple client associations for that URCB. Once enabled, each client has independent access to a copy of that URCB. The Resv attribute is writable, however, the SEL-787 does not support reservations. Writing any field of the URCB causes the client to obtain their own copy of the URCB-in essence, acquiring a reservation.

Reports are serviced at a 2 Hz rate. The client can set the IntgPd to any value with a resolution of 1 ms. However, the integrity report is only sent when the period has been detected as having expired. The report service rate of 2 Hz results in a report being sent within 500 ms of expiration of the IntgPd. The new IntgPd will begin at the time that the current report is serviced.

Datasets

Datasets are configured using ACSELERATOR Architect and contain data attributes that represent real data values within the SEL-787 device. See *Logical Nodes* for the logical node tables that list the available data attributes for each logical node and the Relay Word bit mapping for these data attributes. The datasets listed in *Figure F.2* are the defaults for an SEL-787 device. Datasets BRDSet01–BRDSet06 and URDSet01–URDSet06 are preconfigured with common FCDAs to be used for reporting. These datasets can be configured to represent the data you want to monitor. Dataset GPDSet01, which contains breaker status and control data attributes, is used in the default Goose Control Publication.

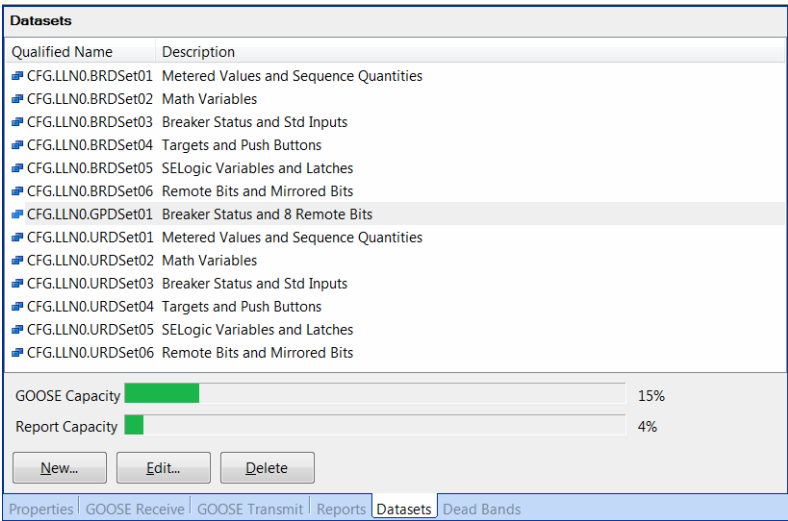


Figure F.2 SEL-787 Datasets

Within ACSELERATOR Architect, IEC 61850 datasets have two main purposes:

- GOOSE: You can use predefined or edited datasets, or create new datasets for outgoing GOOSE transmission.
- Reports: Twelve predefined datasets (BRDSet01 to BRDSet06 and URDSet01 to URDSet06) correspond to the default six buffered and six unbuffered reports. Note that you cannot change the number (12) or type of reports (buffered or unbuffered) within ACSELERATOR Architect. However, you can alter the data attributes that a dataset contains and so define what data an IEC 61850 client receives with a report.

NOTE: Do not edit the dataset names used in reports. Changing or deleting any of those dataset names will cause a failure in generating the corresponding report.

Supplemental Software

Examine the data structure and value of the supported IEC 61850 LNs with an MMS browser such as MMS Object Explorer and AX-S4 MMS from Sisco, Inc. The settings needed to browse an SEL-787 with an MMS browser are shown below:

| | |
|----------------------------------|----------|
| OSI-PSEL (Presentation Selector) | 00000001 |
| OSI-SSEL (Session Selector) | 0001 |
| OSI-TSEL (Transport Selector) | 0001 |

Time Stamps and Quality

In addition to the various data values, the two attributes quality and t (time stamp) are available at any time. The time stamp is determined when data or quality change is detected.

The timestamp is applied to all data and quality attributes (Boolean, Bstrings, Analogs, etc.) in the same fashion when a data or quality change is detected. However, there is a difference in how the change is detected between the different attribute types. For points that are assigned as SER points, i.e., programmed in the SER report, the change is detected as the receipt of an SER record (which contains the SER timestamp) within the relay.

For all other Booleans or Bstrings, the change is detected via the scanner, which compares the last state against the previous state to detect the change. For analogs, the scanner looks at the amount of change relative to the deadband configured for the point to indicate a change and apply the timestamp. In all cases, these timestamps are used for the reporting model.

Functionally Constrained Data Attributes mapped to points assigned to the SER report have 4 ms SER-accurate timestamps for data change events. In order to ensure that you will get SER-quality timestamps for changes to certain points, you must include those points in the SER report. All other FCDAs are scanned for data changes on a 1/2-second interval and have 1/2-second timestamp accuracy. See the **SET R** command for information on programming the SER report.

The SEL-787 uses GOOSE quality attributes to indicate the quality of the data in its transmitted GOOSE messages. Under normal conditions, all attributes are zero, indicating good quality data. *Figure F.3* shows the GOOSE quality attributes available to devices that subscribe to GOOSE messages from SEL-787 datasets that contain them. Internal status indicators provide the information necessary for the device to set these attributes. For example, if the device becomes disabled, as shown via status indications (e.g., an internal self-test failure), the SEL-787 will set the Validity attribute to invalid and the Failure attribute to TRUE. Note that the SEL-787 does not set any of the other quality attributes. These attributes will always indicate FALSE (0). See the ACSELERATOR Architect online help for additional information on GOOSE quality attributes.



Figure F.3 Goose Quality

GOOSE Processing

SEL devices support GOOSE processing as defined by IEC 61850-7-1:2003(E), IEC 61850-7-2:2003(E), and IEC 61850-8-1:2004(E) via the installed Ethernet port. Outgoing GOOSE messages are processed in accordance with the following constraints:

- The user can define as many as eight outgoing GOOSE messages consisting of any Data Attribute (DA) from any Logical Node. A single DA can be mapped to one or more outgoing GOOSE, or one or more times within the same outgoing GOOSE. A user can also map a single GOOSE dataset to multiple GOOSE control blocks.
- The SEL-787 will transmit all configured GOOSE immediately upon successful initialization. If a GOOSE is not retrigged, then, following initial transmission, the SEL-787 will retransmit that GOOSE on a curve. The curve begins at 10 ms and doubles for each retransmission until leveling at the maximum specified in the CID file for that GOOSE. For example, a message with a maximum retransmit interval of 100 ms is retransmitted at intervals of 10 ms, 20 ms, 40 ms, 80 ms, and 100 ms, then repeated every 100 ms until a trigger causes the transmission sequence to be repeated. The time-to-live reported in each transmitted message, is three times the current interval, or two times the interval, if the maximum time-to-live has been reached (30 ms, 60 ms, 120 ms, 240 ms, and 200 ms for the example above; see IEC 61850-8-1, sec. 18.1).
- GOOSE transmission is squelched (silenced) after a permanent (latching) self-test failure.
- Each outgoing GOOSE includes communication parameters (VLAN, Priority, and Multicast Address) and is transmitted entirely in a single network frame.
- The SEL-787 will maintain the configuration of outgoing GOOSE through a power cycle and device reset.

Incoming GOOSE messages are processed in accordance with the following constraints:

- The user can configure the SEL-787 to subscribe to as many as 16 incoming GOOSE messages.

The SEL-787 will recognize incoming GOOSE messages as valid based on the following content. Any GOOSE message that fails these checks shall be rejected.
 - Source broadcast MAC address
 - Dataset Reference
 - Application ID
 - GOOSE Control Reference
- Rejection of all DA contained in an incoming GOOSE, based on the accumulation of the following error indications created by inspection of the received GOOSE:
 - **Configuration Mismatch:** the configuration number of the incoming GOOSE changes.
 - **Needs Commissioning:** this Boolean parameter of the incoming GOOSE is true.

- **Test Mode:** this Boolean parameter of the incoming GOOSE is true.
- **Decode Error:** the format of the incoming GOOSE is not as configured.
- The SEL-787 will discard incoming GOOSE under the following conditions:
 - after a permanent (latching) self-test failure
 - when the relay is disabled
 - when EGSE is set to No

Link-layered priority tagging and virtual LAN is supported as described in Annex C of IEC 61850-8-1:2004(E).

IEC 61850 Configuration

Settings

Table F.6 lists IEC 61850 settings. IEC 61850 settings are available only if your device includes the optional IEC 61850 protocol.

Table F.6 IEC 61850 Settings

| Label | Description | Range | Default |
|--------|---------------------------------------|--------------------|---------|
| E61850 | IEC 61850 interface enable | Y, N | N |
| EGSE | Outgoing IEC 61850 GSE message enable | Y ^a , N | N |

^a Requires E61850 set to Y to send IEC 61850 GSE messages.

Configure all other IEC 61850 settings, including subscriptions to incoming GOOSE messages, with ACSELERATOR Architect.

ACSELERATOR Architect

ACSELERATOR Architect enables protection and integration engineers to design and commission IEC 61850 substations containing SEL IEDs. Engineers can use ACSELERATOR Architect to:

- Organize and configure all SEL IEDs in a substation project
- Configure incoming and outgoing GOOSE messages
- Read non-SEL IED Capability Description (ICD) and Configured IED Description (CID) files and determine the available IEC 61850 messaging options
- Load device settings and IEC 61850 CID files into SEL IEDs
- Generate ICD files that will provide SEL IED descriptions to other manufacturer's tools so they can use SEL GOOSE messages and reporting features
- Configure protection, logic, control, and communication settings of all SEL IEDs in the substation

NOTE: Any device bits mapped to GOOSE subscriptions retain state until overwritten or the device restarts. When loading a new CID file, be sure to issue an **STA C** command or cycle power to the device to clear the device bits if the configuration has changed.

ACSELERATOR Architect provides a Graphical User Interface (GUI) for engineers to select, edit, and create IEC 61850 GOOSE messages important for substation protection, coordination, and control schemes. Typically, the engineer first places icons representing IEDs in a substation container, then edits the outgoing GOOSE messages or creates new ones for each IED. The engineer may also select incoming GOOSE messages for each IED to receive from any other IEDs in the domain. ACSELERATOR Architect can read other manufacturer's ICD and CID files, enabling the engineer to map the data seamlessly into SEL IED logic. See the ACSELERATOR Architect Instruction Manual or online help for more information.

SEL ICD File Versions

ACSELERATOR Architect version R.1.1.69.0 and later supports multiple ICD file versions for each type of IED in a project. Because relays with different firmware versions can require different CID file versions, users can manage the CID files of all IEDs within a single project.

Please ensure that you work with the appropriate version of ACSELERATOR Architect relative to your current configuration, existing project files, and ultimate goals. If you want the best available IEC 61850 functionality for your SEL relay, obtain the latest version of ACSELERATOR Architect and select the appropriate ICD version(s) for your needs.

As of this writing, ACSELERATOR Architect comes with two versions of the SEL-787 ICD file for use with new or existing projects. Ensure that you use the “SEL-787 004 787 R209 and above” version for configuration of the SEL-787. Use of this file requires SEL-787 firmware version R209 or higher. Note that the ICD file versions “SEL-787 004 R206” and “SEL-787 004 R207” can be used with firmware versions R208 and earlier, as well as with newer firmware versions.

Logical Node Extensions

The following Logical Nodes and Data Classes were created in this device as extensions to the IEC 61850 standard, in accordance with IEC 61850 guidelines.

Table F.7 New Logical Node Extensions

| Logical Node | IEC 61850 | Description or Comments |
|--|-----------|--|
| Thermal Measurements (for equipment or ambient temperature readings) | MTHR | This LN shall be used to represent values from RTDs and to calculate thermal quantities for Thermal Monitoring. |
| Demand Metering Statistics | MDST | This LN shall be used for calculation of demand currents in a three-phase system. This shall not be used for billing purposes. |

Table F.8 defines the data class, Thermal Metering Data. This class is a collection of simultaneous measurements (or evaluations) that represent the RTD thermal metering values. Valid data depend on the presence and configuration of the RTD module(s).

Table F.8 Thermal Metering Data Logical Node Class Definition

| MTHR Class | | | | |
|---------------------------------|------------|---|----------------|----------------------|
| Attribute Name | Attr. Type | Explanation | T ^a | M/O/C/E ^b |
| LNName | | The name shall be composed of the class name, the LN-Prefix, and the LN-Instance-ID according to IEC 61850-7-2. | | |
| Common Logical Node Information | | | | |
| | | LN shall inherit all Mandatory Data from Common Logical Node Class. | | M |
| EEHealth | INS | External equipment health (RTD Communications Status) | | E |
| Data Objects | | | | |
| Measured values | | | | |
| MaxAmbTmp | MV | Maximum Ambient Temperature | | E |
| MaxWdgTmp | MV | Maximum Winding Temperature | | E |
| Tmp | MV | Temperature | | E |

^a Transient data objects—the status of data objects with this designation is momentary and must be logged or reported to provide evidence of their momentary state

^b M: Mandatory; O: Optional; C: Conditional; E: Extension

Table F.9 defines the data class Demand Metering Statistics. This class is a collection of demand currents and energy.

Table F.9 Demand Metering Statistics Logical Node Class Definition (Sheet 1 of 2)

| MDST Class | | | | |
|---------------------------------|------------|---|----------------|----------------------|
| Attribute Name | Attr. Type | Explanation | T ^a | M/O/C/E ^b |
| LNName | | The name shall be composed of the class name, the LN-Prefix, and the LN-Instance-ID according to IEC 61850-7-2. | | |
| Common Logical Node Information | | | | |
| | | LN shall inherit all Mandatory Data from Common Logical Node Class. | | M |

Table F.9 Demand Metering Statistics Logical Node Class Definition (Sheet 2 of 2)

| MDST Class | | | | |
|-----------------|------------|--|----------------|----------------------|
| Attribute Name | Attr. Type | Explanation | T ^a | M/O/C/E ^b |
| Data Objects | | | | |
| Measured values | | | | |
| DmdA | WYE | Demand Currents | | E |
| PkDmdA | WYE | Peak Demand Currents | | E |
| SupWh | MV | Real energy supply (default supply direction: energy flow towards busbar) | | E |
| SupVARh | MV | Reactive energy supply (default supply direction: energy flow towards busbar) | | E |
| DmdWh | MV | Real energy demand (default demand direction: energy flow from busbar away) | | E |
| DmdVARh | MV | Reactive energy demand (default demand direction: energy flow from busbar away) | | E |

^a Transient data objects—the status of data objects with this designation is momentary and must be logged or reported to provide evidence of their momentary state

^b M: Mandatory; O: Optional; C: Conditional; E: Extension

Table F.10 Compatible Logical Nodes With Extensions

| Logical Node | IEC 61850 | Description or Comments |
|---------------------|-----------|---|
| Metering Statistics | MSTA | This LN is used for power system metering statistics. |

Table F.11 Metering Statistics Logical Node Class Definition (Sheet 1 of 2)

| MSTA Class | | | | |
|---------------------------------|------------|---|----------------|----------------------|
| Attribute Name | Attr. Type | Explanation | T ^a | M/O/C/E ^b |
| LNName | | The name shall be composed of the class name, the LN-Prefix, and the LN-Instance-ID according to IEC 61850-7-2. | | |
| Common Logical Node Information | | | | |
| | | LN shall inherit all Mandatory Data from Common Logical Node Class. | | M |
| Data Objects | | | | |
| Measured and Metered values | | | | |
| AvAmps | MV | Average Current | | O |
| AvVolts | MV | Average Voltage | | O |
| MaxVA | MV | Maximum apparent power | | O |
| MinVA | MV | Minimum apparent power | | O |
| MaxW | MV | Maximum real power | | O |
| MinW | MV | Minimum real power | | O |
| MaxVAr | MV | Maximum reactive power | | O |
| MinVAr | MV | Minimum reactive power | | O |
| MaxA | WYE | Maximum Phase Currents | | E |
| MinA | WYE | Minimum Phase Currents | | E |

Table F.11 Metering Statistics Logical Node Class Definition (Sheet 2 of 2)

| MSTA Class | | | | |
|----------------|------------|----------------------------------|----------------|----------------------|
| Attribute Name | Attr. Type | Explanation | T ^a | M/O/C/E ^b |
| MaxPhV | WYE | Maximum Phase to Ground Voltages | | E |
| MinPhV | WYE | Minimum Phase to Ground Voltages | | E |
| MaxP2PV | DEL | Maximum Phase to Phase Voltages | | E |
| MinP2PV | DEL | Minimum Phase to Phase Voltages | | E |

^a Transient data objects—the status of data objects with this designation is momentary and must be logged or reported to provide evidence of their momentary state

^b M: Mandatory; O: Optional; C: Conditional; E: Extension

Logical Nodes

The following tables, *Table F.12* through *Table F.16*, show the Logical Nodes (LNs) supported in the SEL-787 and the associated Relay Word bits or measured quantities. *Table F.12* shows the LN associated with protection elements defined as Logical Device PRO.

Table F.12 Logical Device: PRO (Protection) (Sheet 1 of 7)

| Logical Node | Attribute | Data Source | Comment |
|----------------------------|-----------------|------------------|---|
| Functional Constraint = CO | | | |
| W1CSWI1 | Pos.Oper.ctlVal | CC1 ^a | Breaker1 close/open command |
| W2CSWI2 | Pos.Oper.ctlVal | CC2 ^a | Breaker2 close/open command |
| Functional Constraint = DC | | | |
| DevIDLPHD1 | PhyNam.model | PARTNO | Part number |
| Functional Constraint = ST | | | |
| BFR1RBRF1 | OpEx.general | BFT1 | Breaker1 failure trip |
| BFR1RBRF1 | Str.general | BFI1 | Breaker1 failure initiation |
| BFR2RBRF2 | OpEx.general | BFT2 | Breaker2 failure trip |
| BFR2RBRF2 | Str.general | BFI2 | Breaker2 failure initiation |
| C2PVPH2 | Op.general | 24C2T | Level 2 Volts/Hertz composite element timed out |
| C2PVPH2 | Str.general | 24C2 | Level 2 Volts/Hertz composite element pickup |
| C2PVPH2 | Str.dirGeneral | unknown | Direction undefined |
| D1PTOF1 | Op.general | 81D1T | Level 1 definite-time over-/underfrequency trip |
| D1PTOF1 | Str.general | 81D1T | Level 1 definite-time over-/underfrequency trip |
| D1PTOF1 | Str.dirGeneral | unknown | Direction undefined |
| D1PVPH1 | Op.general | 24D1T | Level 1 Volts/Hertz definite-time element timed out |
| D1PVPH1 | Str.general | 24D1 | Level 1 Volts/Hertz instantaneous pickup |
| D1PVPH1 | Str.dirGeneral | unknown | Direction undefined |
| D2PTOF2 | Op.general | 81D2T | Level 2 definite-time over-/underfrequency trip |
| D2PTOF2 | Str.general | 81D2T | Level 2 definite-time over-/underfrequency trip |
| D2PTOF2 | Str.dirGeneral | unknown | Direction undefined |

Table F.12 Logical Device: PRO (Protection) (Sheet 2 of 7)

| Logical Node | Attribute | Data Source | Comment |
|--------------|----------------|-------------|--|
| D3PTOF3 | Op.general | 81D3T | Level 3 definite-time over-/underfrequency trip |
| D3PTOF3 | Str.general | 81D3T | Level 3 definite-time over-/underfrequency trip |
| D3PTOF3 | Str.dirGeneral | unknown | Direction undefined |
| D4PTOF4 | Op.general | 81D4T | Level 4 definite-time over-/underfrequency trip |
| D4PTOF4 | Str.general | 81D4T | Level 4 definite-time over-/underfrequency trip |
| D4PTOF4 | Str.dirGeneral | unknown | Direction undefined |
| D87APDIF3 | Op.general | 87AT | Differential current alarm element trip |
| D87APDIF3 | Str.general | 87AP | Differential current alarm element pickup |
| D87APDIF3 | Str.dirGeneral | unknown | Direction undefined |
| D87RPDIF2 | Op.general | 87R | Restrained differential element trip |
| D87RPDIF2 | Op.phsA | 87R1 | Restrained Differential Element 1 |
| D87RPDIF2 | Op.phsB | 87R2 | Restrained Differential Element 2 |
| D87RPDIF2 | Op.phsC | 87R3 | Restrained Differential Element 3 |
| D87UPDIF1 | Op.general | 87U | Unrestrained differential element trip |
| D87UPDIF1 | Op.phsA | 87U1 | Unrestrained Differential Element 1 trip |
| D87UPDIF1 | Op.phsB | 87U2 | Unrestrained Differential Element 2 trip |
| D87UPDIF1 | Op.phsC | 87U3 | Unrestrained Differential Element 3 trip |
| G11PIOC11 | Op.general | 50G11T | Level 1 residual ground instantaneous overcurrent element trip–Winding 1 |
| G11PIOC11 | Str.general | 50G11P | Level 1 residual ground instantaneous overcurrent element pickup–Winding 1 |
| G11PIOC11 | Str.dirGeneral | unknown | Direction undefined |
| G12PIOC12 | Op.general | 50G12T | Level 2 residual ground instantaneous overcurrent element trip–Winding 1 |
| G12PIOC12 | Str.general | 50G12P | Level 2 residual ground instantaneous overcurrent element pickup–Winding 1 |
| G12PIOC12 | Str.dirGeneral | unknown | Direction undefined |
| G1PTOC4 | Op.general | 51G1T | Residual ground time-overcurrent element trip–Winding 1 |
| G1PTOC4 | Str.general | 51G1P | Residual ground time-overcurrent element pickup–Winding 1 |
| G1PTOC4 | Str.dirGeneral | unknown | Direction undefined |
| G21PIOC13 | Op.general | 50G21T | Level 1 residual ground instantaneous overcurrent element trip–Winding 2 |
| G21PIOC13 | Str.general | 50G21P | Level 1 residual ground instantaneous overcurrent element pickup–Winding 2 |
| G21PIOC13 | Str.dirGeneral | unknown | Direction undefined |
| G22PIOC14 | Op.general | 50G22T | Level 2 residual ground instantaneous overcurrent element trip–Winding 2 |
| G22PIOC14 | Str.general | 50G22P | Level 2 residual ground instantaneous overcurrent element pickup–Winding 2 |
| G22PIOC14 | Str.dirGeneral | unknown | Direction undefined |
| G2PTOC5 | Op.general | 51G2T | Residual ground time-overcurrent element trip–Winding 2 |
| G2PTOC5 | Str.general | 51G2P | Residual ground time-overcurrent element pickup–Winding 2 |
| G2PTOC5 | Str.dirGeneral | unknown | Direction undefined |
| HB24PHAR1 | Str.phsA | 2_4HB1 | Second or fourth-harmonic block asserted for Differential Element 1 |

Table F.12 Logical Device: PRO (Protection) (Sheet 3 of 7)

| Logical Node | Attribute | Data Source | Comment |
|--------------|----------------|-------------|---|
| HB24PHAR1 | Str.phsB | 2_4HB2 | Second or fourth-harmonic block asserted for Differential Element 2 |
| HB24PHAR1 | Str.phsC | 2_4HB3 | Second or fourth-harmonic block asserted for Differential Element 3 |
| HB24PHAR1 | Str.general | 2_4HBL | Second or fourth-harmonic block asserted (2_4HB1 OR 2_4HB2 OR 2_4HB3) |
| HB24PHAR1 | Str.dirGeneral | unknown | Direction undefined |
| HB24PHAR1 | Str.dirPhsA | unknown | Direction undefined |
| HB24PHAR1 | Str.dirPhsB | unknown | Direction undefined |
| HB24PHAR1 | Str.dirPhsC | unknown | Direction undefined |
| HB5PHAR2 | Str.phsA | 5HB1 | Fifth-harmonic block asserted for Differential Element 1 |
| HB5PHAR2 | Str.phsB | 5HB2 | Fifth-harmonic block asserted for Differential Element 2 |
| HB5PHAR2 | Str.phsC | 5HB3 | Fifth-harmonic block asserted for Differential Element 3 |
| HB5PHAR2 | Str.general | 5HBL | Fifth-harmonic block asserted (5HB1 OR 5HB2 OR 5HB3) |
| HB5PHAR2 | Str.dirGeneral | unknown | Direction undefined |
| HB5PHAR2 | Str.dirPhsA | unknown | Direction undefined |
| HB5PHAR2 | Str.dirPhsB | unknown | Direction undefined |
| HB5PHAR2 | Str.dirPhsC | unknown | Direction undefined |
| LOPPTUV3 | Op.general | LOP | Loss of potential |
| LOPPTUV3 | Str.general | LOP | Loss of potential |
| LOPPTUV3 | Str.dirGeneral | unknown | Direction undefined |
| N11PIOC9 | Op.general | 50N11T | Level 1 neutral ground instantaneous overcurrent element trip–Input 1 |
| N11PIOC9 | Str.general | 50N11P | Level 1 neutral ground instantaneous overcurrent element pickup–Input 1 |
| N11PIOC9 | Str.dirGeneral | unknown | Direction undefined |
| N12PIOC10 | Op.general | 50N12T | Level 2 neutral ground instantaneous overcurrent element trip–Input 1 |
| N12PIOC10 | Str.general | 50N12P | Level 2 neutral ground instantaneous overcurrent element pickup–Input 1 |
| N12PIOC10 | Str.dirGeneral | unknown | Direction undefined |
| N1PTOC3 | Op.general | 51N1T | Neutral ground time-overcurrent element trip–Input 1 |
| N1PTOC3 | Str.general | 51N1P | Neutral ground time-overcurrent element pickup–Input 1 |
| N1PTOC3 | Str.dirGeneral | unknown | Direction undefined |
| P11APIOC19 | Op.general | 50P11AT | Level 1 A-phase instantaneous overcurrent element trip–Winding 1 |
| P11APIOC19 | Str.general | 50P11AP | Level 1 A-phase instantaneous overcurrent element pickup–Winding 1 |
| P11APIOC19 | Str.dirGeneral | unknown | Direction undefined |
| P11BPIOC20 | Op.general | 50P11BT | Level 1 B-phase instantaneous overcurrent element trip–Winding 1 |
| P11BPIOC20 | Str.general | 50P11BP | Level 1 B-phase instantaneous overcurrent element pickup–Winding 1 |
| P11BPIOC20 | Str.dirGeneral | unknown | Direction undefined |
| P11CPIOC21 | Op.general | 50P11CT | Level 1 C-phase instantaneous overcurrent element trip–Winding 1 |
| P11CPIOC21 | Str.general | 50P11CP | Level 1 C-phase instantaneous overcurrent element pickup–Winding 1 |
| P11CPIOC21 | Str.dirGeneral | unknown | Direction undefined |
| P11PIOC1 | Op.general | 50P11T | Level 1 phase instantaneous overcurrent element trip–Winding 1 |
| P11PIOC1 | Str.general | 50P11P | Level 1 phase instantaneous overcurrent element pickup–Winding 1 |

Table F.12 Logical Device: PRO (Protection) (Sheet 4 of 7)

| Logical Node | Attribute | Data Source | Comment |
|--------------|----------------|-------------|--|
| P11PIOC1 | Str.dirGeneral | unknown | Direction undefined |
| P12PIOC2 | Op.general | 50P12T | Level 2 phase instantaneous overcurrent element trip–Winding 1 |
| P12PIOC2 | Str.general | 50P12P | Level 2 phase instantaneous overcurrent element pickup–Winding 1 |
| P12PIOC2 | Str.dirGeneral | unknown | Direction undefined |
| P13PIOC3 | Op.general | 50P13T | Level 3 phase instantaneous overcurrent element trip–Winding 1 |
| P13PIOC3 | Str.general | 50P13P | Level 3 phase instantaneous overcurrent element pickup–Winding 1 |
| P13PIOC3 | Str.dirGeneral | unknown | Direction undefined |
| P14PIOC4 | Op.general | 50P14T | Level 4 phase instantaneous overcurrent element trip–Winding 1 |
| P14PIOC4 | Str.general | 50P14P | Level 4 phase instantaneous overcurrent element pickup–Winding 1 |
| P14PIOC4 | Str.dirGeneral | unknown | Direction undefined |
| P1APTOC8 | Op.general | 51P1AT | Level 1 A-phase time-overcurrent element trip–Winding 1 |
| P1APTOC8 | Str.general | 51P1AP | Level 1 A-phase time-overcurrent element pickup–Winding 1 |
| P1APTOC8 | Str.dirGeneral | unknown | Direction undefined |
| P1BPTOC9 | Op.general | 51P1BT | Level 1 B phase time-overcurrent element trip–Winding 1 |
| P1BPTOC9 | Str.general | 51P1BP | Level 1 B phase time-overcurrent element pickup–Winding 1 |
| P1BPTOC9 | Str.dirGeneral | unknown | Direction undefined |
| P1CPTOC10 | Op.general | 51P1CT | Level 1 C phase time-overcurrent element trip–Winding 1 |
| P1CPTOC10 | Str.general | 51P1CP | Level 1 C phase time-overcurrent element pickup–Winding 1 |
| P1CPTOC10 | Str.dirGeneral | unknown | Direction undefined |
| P1PTOC1 | Op.general | 51P1T | Maximum phase time-overcurrent element trip–Winding 1 |
| P1PTOC1 | Str.general | 51P1P | Maximum phase time-overcurrent element pickup–Winding 1 |
| P1PTOC1 | Str.dirGeneral | unknown | Direction undefined |
| P1PTOV1 | Op.general | 59P1T | Level 1 phase overvoltage element trip |
| P1PTOV1 | Str.general | 59P1 | Level 1 phase overvoltage element pickup |
| P1PTOV1 | Str.dirGeneral | unknown | Direction undefined |
| P1PTUV1 | Op.general | 27P1T | Level 1 phase undervoltage element trip |
| P1PTUV1 | Str.general | 27P1 | Level 1 phase undervoltage element pickup |
| P1PTUV1 | Str.dirGeneral | unknown | Direction undefined |
| P21APIOC22 | Op.general | 50P21AT | Level 1 A-phase instantaneous overcurrent element trip–Winding 2 |
| P21APIOC22 | Str.general | 50P21AP | Level 1 A-phase instantaneous overcurrent element pickup–Winding 2 |
| P21APIOC22 | Str.dirGeneral | unknown | Direction undefined |
| P21BPIOC23 | Op.general | 50P21BT | Level 1 B-phase instantaneous overcurrent element trip–Winding 2 |
| P21BPIOC23 | Str.general | 50P21BP | Level 1 B-phase instantaneous overcurrent element pickup–Winding 2 |
| P21BPIOC23 | Str.dirGeneral | unknown | Direction undefined |
| P21CPIOC24 | Op.general | 50P21CT | Level 1 C-phase instantaneous overcurrent element trip–Winding 2 |
| P21CPIOC24 | Str.general | 50P21CP | Level 1 C-phase instantaneous overcurrent element pickup–Winding 2 |
| P21CPIOC24 | Str.dirGeneral | unknown | Direction undefined |
| P21PIOC5 | Op.general | 50P21T | Level 1 phase instantaneous overcurrent element trip–Winding 2 |

Table F.12 Logical Device: PRO (Protection) (Sheet 5 of 7)

| Logical Node | Attribute | Data Source | Comment |
|--------------|----------------|-------------|--|
| P21PIOC5 | Str.general | 50P21P | Level 1 phase instantaneous overcurrent element pickup–Winding 2 |
| P21PIOC5 | Str.dirGeneral | unknown | Direction undefined |
| P22PIOC6 | Op.general | 50P22T | Level 2 phase instantaneous overcurrent element trip–Winding 2 |
| P22PIOC6 | Str.general | 50P22P | Level 2 phase instantaneous overcurrent element pickup–Winding 2 |
| P22PIOC6 | Str.dirGeneral | unknown | Direction undefined |
| P23PIOC7 | Op.general | 50P23T | Level 3 phase instantaneous overcurrent element trip–Winding 2 |
| P23PIOC7 | Str.general | 50P23P | Level 3 phase instantaneous overcurrent element pickup–Winding 2 |
| P23PIOC7 | Str.dirGeneral | unknown | Direction undefined |
| P24PIOC8 | Op.general | 50P24T | Level 3 phase instantaneous overcurrent element trip–Winding 2 |
| P24PIOC8 | Str.general | 50P24P | Level 3 phase instantaneous overcurrent element pickup–Winding 2 |
| P24PIOC8 | Str.dirGeneral | unknown | Direction undefined |
| P2APTOC11 | Op.general | 51P2AT | Level 1 A-phase time-overcurrent element trip–Winding 2 |
| P2APTOC11 | Str.general | 51P2AP | Level 1 A-phase time-overcurrent element pickup–Winding 2 |
| P2APTOC11 | Str.dirGeneral | unknown | Direction undefined |
| P2BPTOC12 | Op.general | 51P2BT | Level 1 B-phase time-overcurrent element trip–Winding 2 |
| P2BPTOC12 | Str.general | 51P2BP | Level 1 B-phase time-overcurrent element pickup–Winding 2 |
| P2BPTOC12 | Str.dirGeneral | unknown | Direction undefined |
| P2CPTOC13 | Op.general | 51P2CT | Level 1 C-phase time-overcurrent element trip–Winding 2 |
| P2CPTOC13 | Str.general | 51P2CP | Level 1 C-phase time-overcurrent element pickup–Winding 2 |
| P2CPTOC13 | Str.dirGeneral | unknown | Direction undefined |
| P2PTOC2 | Op.general | 51P2T | Maximum phase time-overcurrent element trip–Winding 2 |
| P2PTOC2 | Str.general | 51P2P | Maximum phase time-overcurrent element pickup–Winding 2 |
| P2PTOC2 | Str.dirGeneral | unknown | Direction undefined |
| P2PTOV2 | Op.general | 59P2T | Level 2 phase overvoltage element trip |
| P2PTOV2 | Str.general | 59P2 | Level 2 phase overvoltage element pickup |
| P2PTOV2 | Str.dirGeneral | unknown | Direction undefined |
| P2PTUV2 | Op.general | 27P2T | Level 2 phase undervoltage element trip |
| P2PTUV2 | Str.general | 27P2 | Level 2 phase undervoltage element pickup |
| P2PTUV2 | Str.dirGeneral | unknown | Direction undefined |
| PWR1PDOP1 | Op.general | 3PWR1T | 3-Phase Power Element 1 trip |
| PWR1PDOP1 | Str.general | 3PWR1P | 3-Phase Power Element 1 pickup |
| PWR1PDOP1 | Str.dirGeneral | unknown | Direction undefined |
| PWR1PDUP1 | Op.general | 3PWR1T | 3-Phase Power Element 1 trip |
| PWR1PDUP1 | Str.general | 3PWR1P | 3-Phase Power Element 1 pickup |
| PWR1PDUP1 | Str.dirGeneral | unknown | Direction undefined |
| PWR2PDOP2 | Op.general | 3PWR2T | 3-Phase Power Element 2 trip |
| PWR2PDOP2 | Str.general | 3PWR2P | 3-Phase Power Element 2 pickup |
| PWR2PDOP2 | Str.dirGeneral | unknown | Direction undefined |

Table F.12 Logical Device: PRO (Protection) (Sheet 6 of 7)

| Logical Node | Attribute | Data Source | Comment |
|--------------|----------------|-------------|--|
| PWR2PDUP2 | Op.general | 3PWR2T | 3-Phase Power Element 2 trip |
| PWR2PDUP2 | Str.general | 3PWR2P | 3-Phase Power Element 2 pickup |
| PWR2PDUP2 | Str.dirGeneral | unknown | Direction undefined |
| Q11PIOC15 | Op.general | 50Q11T | Level 1 negative-sequence instantaneous overcurrent element trip–Winding 1 |
| Q11PIOC15 | Str.general | 50Q11P | Level 1 negative-sequence instantaneous overcurrent element pickup–Winding 1 |
| Q11PIOC15 | Str.dirGeneral | unknown | Direction undefined |
| Q12PIOC16 | Op.general | 50Q12T | Level 2 negative-sequence instantaneous overcurrent element trip–Winding 1 |
| Q12PIOC16 | Str.general | 50Q12P | Level 2 negative-sequence instantaneous overcurrent element pickup–Winding 1 |
| Q12PIOC16 | Str.dirGeneral | unknown | Direction undefined |
| Q1PTOC6 | Op.general | 51Q1T | Negative-sequence time-overcurrent element trip–Winding 1 |
| Q1PTOC6 | Str.general | 51Q1P | Negative-sequence time-overcurrent element pickup–Winding 1 |
| Q1PTOC6 | Str.dirGeneral | unknown | Direction undefined |
| Q1TPTOV2 | Op.general | 59Q1T | Level 1 negative-sequence overvoltage element trip |
| Q1TPTOV2 | Str.general | 59Q1 | Level 1 negative-sequence overvoltage element pickup |
| Q1TPTOV2 | Str.dirGeneral | unknown | Direction undefined |
| Q21PIOC17 | Op.general | 50Q21T | Level 1 negative-sequence instantaneous overcurrent element trip–Winding 2 |
| Q21PIOC17 | Str.general | 50Q21P | Level 1 negative-sequence instantaneous overcurrent element pickup–Winding 2 |
| Q21PIOC17 | Str.dirGeneral | unknown | Direction undefined |
| Q22PIOC18 | Op.general | 50Q22T | Level 2 negative-sequence instantaneous overcurrent element trip–Winding 2 |
| Q22PIOC18 | Str.general | 50Q22P | Level 2 negative-sequence instantaneous overcurrent element pickup–Winding 2 |
| Q22PIOC18 | Str.dirGeneral | unknown | Direction undefined |
| Q2PTOC7 | Op.general | 51Q2T | Negative-sequence time-overcurrent element trip–Winding 2 |
| Q2PTOC7 | Str.general | 51Q2P | Negative-sequence time-overcurrent element pickup–Winding 2 |
| Q2PTOC7 | Str.dirGeneral | unknown | Direction undefined |
| Q2TPTOV3 | Op.general | 59Q2T | Level 2 negative-sequence overvoltage element trip |
| Q2TPTOV3 | Str.general | 59Q2 | Level 2 negative-sequence overvoltage element pickup |
| Q2TPTOV3 | Str.dirGeneral | unknown | Direction undefined |
| REF1FPDIF4 | Op.general | REF1F | REF element forward (internal) fault declaration |
| REF1PPDIF5 | Op.general | REF1P | Restricted earth fault inverse-time O/C element timed-out |
| REF1RPDIF6 | Op.general | REF1R | REF element reverse (external) fault declaration |
| TRIP1PTRC1 | Tr.general | TRIP1 | Trip1 logic output |
| TRIP2PTRC2 | Tr.general | TRIP2 | Trip2 logic output |
| TRIP3PTRC3 | Tr.general | TRIPXFMR | TripXFMR logic output |

Table F.12 Logical Device: PRO (Protection) (Sheet 7 of 7)

| Logical Node | Attribute | Data Source | Comment |
|--------------|---------------|-----------------------|--|
| W1CSWI1 | OpCls.general | CC1 | Breaker1 close control |
| W1CSWI1 | OpOpn.general | OC1 | Breaker1 open control |
| W1CSWI1 | Pos.stVal | 52A1?1:2 ^b | Breaker1 position (52A = false, breaker opened; 52A = true, breaker closed) |
| W1XCBR1 | BlkCls.stVal | 0 | Breaker close blocking not configured by default |
| W1XCBR1 | BlkOpn.stVal | 0 | Breaker open blocking not configured by default |
| W1XCBR1 | CBOpCap.stVal | None | Breaker physical operation capabilities not known to relay |
| W1XCBR1 | Loc.stVal | 0 | Breaker local control status not configured by default |
| W1XCBR1 | OpCnt.stVal | 0 | Breaker operation counts not available |
| W1XCBR1 | Pos.stVal | 52A1?1:2 ^b | Breaker1 position (52A = false, breaker opened; 52A = true, breaker closed) |
| W2CSWI2 | OpCls.general | CC2 | Breaker2 close control |
| W2CSWI2 | OpOpn.general | OC2 | Breaker2 open control |
| W2CSWI2 | Pos.stVal | 52A2?1:2 ^b | Breaker2 position (52A = false, breaker opened; 52A = true, breaker closed) |
| W2XCBR2 | BlkCls.stVal | 0 | Breaker close blocking not configured by default |
| W2XCBR2 | BlkOpn.stVal | 0 | Breaker open blocking not configured by default |
| W2XCBR2 | CBOpCap.stVal | None | Breaker physical operation capabilities not known to relay |
| W2XCBR2 | Loc.stVal | 0 | Breaker local control status not configured by default |
| W2XCBR2 | OpCnt.stVal | 0 | Breaker operation counts not available |
| W2XCBR2 | Pos.stVal | 52A2?1:2 ^b | Breaker2 position (52A = false, breaker opened; 52A = true, breaker closed) |

^a Writing a 0 to WnCSWI.n.CO.Pos.Oper.ctiVal (n = 1, 2) will cause OCn to assert and writing any other value will cause CCn to assert.

^b If breaker/contactor is closed, value = 10(2); if breaker/contactor is opened, value = 01(1).

Table F.13 shows the LN associated with measuring elements defined as Logical Device MET.

Table F.13 Logical Device: MET (Metering) (Sheet 1 of 5)

| Logical Node | Attribute | Data Source | Comment |
|---|----------------------------|-------------|---------------------------------------|
| Functional Constraint = DC | | | |
| DevIDLPHD1 | PhyNam.model | PARTNO | Part number |
| Functional Constraint = MX ^{a b} | | | |
| METMDST1 | DmdA.nseq.instCVal.mag.f | 3I2D | Negative-sequence current demand |
| METMDST1 | DmdA.phsA.instCVal.mag.f | IAD | Phase-A current demand |
| METMDST1 | DmdA.phsB.instCVal.mag.f | IBD | Phase-B current demand |
| METMDST1 | DmdA.phsC.instCVal.mag.f | ICD | Phase-C current demand |
| METMDST1 | DmdA.res.instCVal.mag.f | IGD | Residual current demand |
| METMDST1 | DmdVARh.instMag.f | MVARHP | Reactive energy, 3-phase positive |
| METMDST1 | DmdWh.instMag.f | MWHP | Real energy, 3-phase positive |
| METMDST1 | PkDmdA.nseq.instCVal.mag.f | 3I2PD | Negative-sequence current peak demand |
| METMDST1 | PkDmdA.phsA.instCVal.mag.f | IAPD | Phase-A current peak demand |

Table F.13 Logical Device: MET (Metering) (Sheet 2 of 5)

| Logical Node | Attribute | Data Source | Comment |
|--------------|-----------------------------|-------------|--|
| METMDST1 | PkDmdA.phsB.instCVal.mag.f | IBPD | Phase-B current peak demand |
| METMDST1 | PkDmdA.phsC.instCVal.mag.f | ICPD | Phase-C current peak demand |
| METMDST1 | PkDmdA.res.instCVal.mag.f | IGPD | Residual current peak demand |
| METMDST1 | SupVArh.instMag.f | MVARHN | Reactive energy, 3-phase negative |
| METMDST1 | SupWh.instMag.f | MWHN | Real energy, 3-phase negative |
| METMHA1I | ThdA1.phsA.instCVal.mag.f | IAW1_THD | Winding1 A-phase current THD |
| METMHA1I | ThdA1.phsB.instCVal.mag.f | IBW1_THD | Winding1 B-phase current THD |
| METMHA1I | ThdA1.phsC.instCVal.mag.f | ICW1_THD | Winding1 C-phase current THD |
| METMHA1I | ThdA1.neut.instCVal.mag.f | IN_THD | Neutral current THD |
| METMHA1I | ThdA2.phsA.instCVal.mag.f | IAW2_THD | Winding2 A-phase current THD |
| METMHA1I | ThdA2.phsB.instCVal.mag.f | IBW2_THD | Winding2 B-phase current THD |
| METMHA1I | ThdA2.phsC.instCVal.mag.f | ICW2_THD | Winding2 C-phase current THD |
| METMHA1I | ThdPhV.phsA.instCVal.mag.f | VA_THD | A-phase-to-neutral voltage THD |
| METMHA1I | ThdPhV.phsB.instCVal.mag.f | VB_THD | B-phase-to-neutral voltage THD |
| METMHA1I | ThdPhV.phsC.instCVal.mag.f | VC_THD | C-phase-to-neutral voltage THD |
| METMHA1I | ThdPPV.phsAB.instCVal.mag.f | VAB_THD | A-to-B-phase voltage THD |
| METMHA1I | ThdPPV.phsBC.instCVal.mag.f | VBC_THD | B-to-C-phase voltage THD |
| METMHA1I | ThdPPV.phsCA.instCVal.mag.f | VCA_THD | C-to-A-phase voltage THD |
| METMMXU1 | A.neut.instCVal.ang.f | IN_ANG | Current, neutral, angle |
| METMMXU1 | A.neut.instCVal.mag.f | IN_MAG | Current, neutral, magnitude |
| METMMXU1 | A1.phsA.instCVal.ang.f | IAW1_ANG | Winding1 current, A-phase, angle |
| METMMXU1 | A1.phsA.instCVal.mag.f | IAW1_MAG | Winding1 current, A-phase, magnitude |
| METMMXU1 | A1.phsB.instCVal.ang.f | IBW1_ANG | Winding1 current, B-phase, angle |
| METMMXU1 | A1.phsB.instCVal.mag.f | IBW1_MAG | Winding1 current, B-phase, magnitude |
| METMMXU1 | A1.phsC.instCVal.ang.f | ICW1_ANG | Winding1 current, C-phase, angle |
| METMMXU1 | A1.phsC.instCVal.mag.f | ICW1_MAG | Winding1 current, C-phase, magnitude |
| METMMXU1 | A1.res.instCVal.ang.f | IGW1_ANG | Winding1 current, calculated-residual, angle |
| METMMXU1 | A1.res.instCVal.mag.f | IGW1_MAG | Winding1 current, calculated-residual, magnitude |
| METMMXU1 | A2.phsA.instCVal.ang.f | IAW2_ANG | Winding2 current, A-phase, angle |
| METMMXU1 | A2.phsA.instCVal.mag.f | IAW2_MAG | Winding2 current, A-phase, magnitude |
| METMMXU1 | A2.phsB.instCVal.ang.f | IBW2_ANG | Winding2 current, B-phase, angle |
| METMMXU1 | A2.phsB.instCVal.mag.f | IBW2_MAG | Winding2 current, B-phase, magnitude |
| METMMXU1 | A2.phsC.instCVal.ang.f | ICW2_ANG | Winding2 current, C-phase, angle |
| METMMXU1 | A2.phsC.instCVal.mag.f | ICW2_MAG | Winding2 current, C-phase, magnitude |
| METMMXU1 | A2.res.instCVal.ang.f | IGW2_ANG | Winding2 current, calculated-residual, angle |
| METMMXU1 | A2.res.instCVal.mag.f | IGW2_MAG | Winding2 current, calculated-residual, magnitude |
| METMMXU1 | Hz.instMag.f | FREQ | Frequency |
| METMMXU1 | PhV.phsA.instCVal.ang.f | VA_ANG | Voltage, A-phase-to-neutral, angle |

Table F.13 Logical Device: MET (Metering) (Sheet 3 of 5)

| Logical Node | Attribute | Data Source | Comment |
|--------------|--------------------------|-------------|--|
| METMMXU1 | PhV.phsA.instCVal.mag.f | VA_MAG | Voltage, A-phase-to-neutral, magnitude |
| METMMXU1 | PhV.phsB.instCVal.ang.f | VB_ANG | Voltage, B-phase-to-neutral, angle |
| METMMXU1 | PhV.phsB.instCVal.mag.f | VB_MAG | Voltage, B-phase-to-neutral, magnitude |
| METMMXU1 | PhV.phsC.instCVal.ang.f | VC_ANG | Voltage, C-phase-to-neutral, angle |
| METMMXU1 | PhV.phsC.instCVal.mag.f | VC_MAG | Voltage, C-phase-to-neutral, magnitude |
| METMMXU1 | PhV.res.instCVal.ang.f | VG_ANG | Zero-sequence voltage, angle |
| METMMXU1 | PhV.res.instCVal.mag.f | VG_MAG | Zero-sequence voltage, magnitude |
| METMMXU1 | PPV.phsAB.instCVal.ang.f | VAB_ANG | Voltage, A-to-B-phase, angle |
| METMMXU1 | PPV.phsAB.instCVal.mag.f | VAB_MAG | Voltage, A-to-B-phase, magnitude |
| METMMXU1 | PPV.phsBC.instCVal.ang.f | VBC_ANG | Voltage, B-to-C-phase, angle |
| METMMXU1 | PPV.phsBC.instCVal.mag.f | VBC_MAG | Voltage, B-to-C-phase, magnitude |
| METMMXU1 | PPV.phsCA.instCVal.ang.f | VCA_ANG | Voltage, C-to-A-phase, angle |
| METMMXU1 | PPV.phsCA.instCVal.mag.f | VCA_MAG | Voltage, C-to-A-phase, magnitude |
| METMMXU1 | TotPF.instMag.f | PF | Power factor, 3-phase, magnitude |
| METMMXU1 | TotVA.instMag.f | S | Apparent power, 3-phase, magnitude |
| METMMXU1 | TotVAr.instMag.f | Q | Reactive power, 3-phase, magnitude |
| METMMXU1 | TotW.instMag.f | P | Real power, 3-phase, magnitude |
| METMSQI1 | SeqA1.c2.instCVal.ang.f | 3I2W1ANG | Winding1 current, negative-sequence, angle |
| METMSQI1 | SeqA1.c2.instCVal.mag.f | 3I2W1MAG | Winding1 current, negative-sequence, magnitude |
| METMSQI1 | SeqA1.c1.instCVal.ang.f | I1W1_ANG | Winding1 current, positive-sequence, angle |
| METMSQI1 | SeqA1.c1.instCVal.mag.f | I1W1_MAG | Winding1 current, positive-sequence, magnitude |
| METMSQI1 | SeqA1.c3.instCVal.ang.f | IGW1_ANG | Winding1 current, zero-sequence, angle |
| METMSQI1 | SeqA1.c3.instCVal.mag.f | IGW1_MAG | Winding1 current, zero-sequence, magnitude |
| METMSQI1 | SeqA2.c2.instCVal.ang.f | 3I2W2ANG | Winding2 current, negative-sequence, angle |
| METMSQI1 | SeqA2.c2.instCVal.mag.f | 3I2W2MAG | Winding2 current, negative-sequence, magnitude |
| METMSQI1 | SeqA2.c1.instCVal.ang.f | I1W2_ANG | Winding2 current, positive-sequence, angle |
| METMSQI1 | SeqA2.c1.instCVal.mag.f | I1W2_MAG | Winding2 current, positive-sequence, magnitude |
| METMSQI1 | SeqA2.c3.instCVal.ang.f | IGW2_ANG | Winding2 current, zero-sequence, angle |
| METMSQI1 | SeqA2.c3.instCVal.mag.f | IGW2_MAG | Winding2 current, zero-sequence, magnitude |
| METMSQI1 | SeqV.c2.instCVal.ang.f | 3V2_ANG | Voltage, negative-sequence, angle |
| METMSQI1 | SeqV.c2.instCVal.mag.f | 3V2_MAG | Voltage, negative-sequence, magnitude |
| METMSQI1 | SeqV.c1.instCVal.ang.f | V1_ANG | Voltage, positive-sequence, angle |
| METMSQI1 | SeqV.c1.instCVal.mag.f | V1_MAG | Voltage, positive-sequence, magnitude |
| METMSQI1 | SeqV.c3.instCVal.ang.f | VG_ANG | Voltage, zero-sequence, angle |
| METMSQI1 | SeqV.c3.instCVal.mag.f | VG_MAG | Voltage, zero-sequence, magnitude |
| METMSTA1 | AvAmps01.instMag.f | IAVW1MAG | Winding1 average current, magnitude |
| METMSTA1 | AvAmps02.instMag.f | IAVW2MAG | Winding2 average current, magnitude |
| METMSTA1 | AvVolts.instMag.f | VAVE_MAG | Average voltage, magnitude |

Table F.13 Logical Device: MET (Metering) (Sheet 4 of 5)

| Logical Node | Attribute | Data Source | Comment |
|--------------|------------------------------|-------------|--|
| METMSTA1 | MaxA.instCVal.mag.f | INMX | Current, neutral, maximum magnitude |
| METMSTA1 | MaxA1.phsA.instCVal.mag.f | IAW1MX | Winding1 current, A-phase, maximum magnitude |
| METMSTA1 | MaxA1.phsB.instCVal.mag.f | IBW1MX | Winding1 current, B-phase, maximum magnitude |
| METMSTA1 | MaxA1.phsC.instCVal.mag.f | ICW1MX | Winding1 current, C-phase, maximum magnitude |
| METMSTA1 | MaxA1.res.instCVal.mag.f | IGW1MX | Winding1 current, residual, maximum magnitude |
| METMSTA1 | MaxA2.phsA.instCVal.mag.f | IAW2MX | Winding2 current, A-phase, maximum magnitude |
| METMSTA1 | MaxA2.phsB.instCVal.mag.f | IBW2MX | Winding2 current, B-phase, maximum magnitude |
| METMSTA1 | MaxA2.phsC.instCVal.mag.f | ICW2MX | Winding2 current, C-phase, maximum magnitude |
| METMSTA1 | MaxA2.res.instCVal.mag.f | IGW2MX | Winding2 current, residual, maximum magnitude |
| METMSTA1 | MaxP2PV.phsAB.instCVal.mag.f | VABMX | Voltage, A-to-B-phase, maximum magnitude |
| METMSTA1 | MaxP2PV.phsBC.instCVal.mag.f | VBCMIX | Voltage, B-to-C-phase, maximum magnitude |
| METMSTA1 | MaxP2PV.phsCA.instCVal.mag.f | VCAMX | Voltage, C-to-A-phase, maximum magnitude |
| METMSTA1 | MaxPhV.phsA.instCVal.mag.f | VAMX | Voltage, A-phase-to-neutral, maximum magnitude |
| METMSTA1 | MaxPhV.phsB.instCVal.mag.f | VBMX | Voltage, B-phase-to-neutral, maximum magnitude |
| METMSTA1 | MaxPhV.phsC.instCVal.mag.f | VCMX | Voltage, C-phase-to-neutral, maximum magnitude |
| METMSTA1 | MaxVA.instMag.f | KVA3PMX | Apparent power magnitude, 3-phase, maximum |
| METMSTA1 | MaxVAr.instMag.f | KVAR3PMX | Reactive power magnitude, 3-phase, maximum |
| METMSTA1 | MaxW.instMag.f | KW3PMX | Real power magnitude, 3-phase, maximum |
| METMSTA1 | MinA.instCVal.mag.f | INMN | Current, neutral, minimum magnitude |
| METMSTA1 | MinA1.phsA.instCVal.mag.f | IAW1MN | Winding1 current, A-phase, minimum magnitude |
| METMSTA1 | MinA1.phsB.instCVal.mag.f | IBW1MN | Winding1 current, B-phase, minimum magnitude |
| METMSTA1 | MinA1.phsC.instCVal.mag.f | ICW1MN | Winding1 current, C-phase, minimum magnitude |
| METMSTA1 | MinA1.res.instCVal.mag.f | IGW1MN | Winding1 current, residual, minimum magnitude |
| METMSTA1 | MinA2.phsA.instCVal.mag.f | IAW2MN | Winding2 current, A-phase, minimum magnitude |
| METMSTA1 | MinA2.phsB.instCVal.mag.f | IBW2MN | Winding2 current, B-phase, minimum magnitude |
| METMSTA1 | MinA2.phsC.instCVal.mag.f | ICW2MN | Winding2 current, C-phase, minimum magnitude |
| METMSTA1 | MinA2.res.instCVal.mag.f | IGW2MN | Winding2 current, residual, minimum magnitude |
| METMSTA1 | MinP2PV.phsAB.instCVal.mag.f | VABMN | Voltage, A-to-B-phase, minimum magnitude |
| METMSTA1 | MinP2PV.phsBC.instCVal.mag.f | VBCMNI | Voltage, B-to-C-phase, minimum magnitude |
| METMSTA1 | MinP2PV.phsCA.instCVal.mag.f | VCAMNI | Voltage, C-to-A-phase, minimum magnitude |
| METMSTA1 | MinPhV.phsA.instCVal.mag.f | VAMNI | Voltage, A-phase-to-neutral, minimum magnitude |
| METMSTA1 | MinPhV.phsB.instCVal.mag.f | VBMNI | Voltage, B-phase-to-neutral, minimum magnitude |
| METMSTA1 | MinPhV.phsC.instCVal.mag.f | VCMNI | Voltage, C-phase-to-neutral, minimum magnitude |
| METMSTA1 | MinVA.instMag.f | KVA3PMNI | Apparent power magnitude, 3-phase, minimum |
| METMSTA1 | MinVAr.instMag.f | KVAR3PMNI | Reactive power magnitude, 3-phase, minimum |
| METMSTA1 | MinW.instMag.f | KW3PMNI | Real power magnitude, 3-phase, minimum |
| RMS1MMXU2 | A1.phsA.instCVal.mag.f | IAW1RMS | Winding1 RMS current, A-phase, magnitude |
| RMS1MMXU2 | A1.phsB.instCVal.mag.f | IBW1RMS | Winding1 RMS current, B-phase, magnitude |

Table F.13 Logical Device: MET (Metering) (Sheet 5 of 5)

| Logical Node | Attribute | Data Source | Comment |
|----------------------------|---------------------------------|---------------------------|--|
| RMS1MMXU2 | A1.phsC.instCVal.mag.f | ICW1RMS | Winding1 RMS current, C-phase, magnitude |
| RMS1MMXU2 | A2.phsA.instCVal.mag.f | IAW2RMS | Winding2 RMS current, A-phase, magnitude |
| RMS1MMXU2 | A2.phsB.instCVal.mag.f | IBW2RMS | Winding2 RMS current, B-phase, magnitude |
| RMS1MMXU2 | A2.phsC.instCVal.mag.f | ICW2RMS | Winding2 RMS current, C-phase, magnitude |
| RMS2MMXU3 | A.neut.instCVal.mag.f | INRMS | Neutral RMS current, magnitude |
| RMS2MMXU3 | PhV.phsA.instCVal.mag.f | VARMS | RMS voltage, A-phase-to-neutral, magnitude |
| RMS2MMXU3 | PhV.phsB.instCVal.mag.f | VBRMS | RMS voltage, B-phase-to-neutral, magnitude |
| RMS2MMXU3 | PhV.phsC.instCVal.mag.f | VCRMS | RMS voltage, C-phase-to-neutral, magnitude |
| RMS2MMXU3 | PPV.phsAB.instCVal.mag.f | VABRMS | RMS voltage, A-to-B-phase, magnitude |
| RMS2MMXU3 | PPV.phsBC.instCVal.mag.f | VBCRMS | RMS voltage, B-to-C-phase, magnitude |
| RMS2MMXU3 | PPV.phsCA.instCVal.mag.f | VCARMS | RMS voltage, C-to-A-phase, magnitude |
| THERMMTHR1 | MaxAmbTmp.instMag.f | RTDAMB ^c | Ambient RTD temperature |
| THERMMTHR1 | MaxOthTmp.instMag.f | RTDOTHMX ^c | Other maximum RTD temperature |
| THERMMTHR1 | Tmp01.instMag.f–Tmp12.instMag.f | RTD1 - RTD12 ^c | RTD1–RTD12 temperature |
| Functional Constraint = ST | | | |
| THERMMTHR1 | EEHealth.stVal | RTDFLT?1:3 ^c | RTD input or communication status |

^a MX values contain instantaneous attributes (instMag and instCVal), which are updated whenever the source updates and other attributes which are only updated when the source goes outside the data sources dead band (mag and cVal). Only the instantaneous values are shown in the table.

^b Data validity depend on the relay model and installed card options. Refer to Section 1: Introduction and Specifications for different relay models and available card options. Refer to Section 5: Metering and Monitoring for the model dependent metering quantities.

^c Valid data depend on E49RTD and RTD1LOC–RTD12LOC settings.

Table F.14 shows the LN associated with control elements defined as Logical Device CON.

Table F.14 Logical Device: CON (Remote Control)

| Logical Node | Status | Control | Relay Word Bit | Comment |
|--------------|-----------------------------|---|----------------|-----------------------|
| RBGGIO1 | SPCSO01.stVal–SPCSO08.stVal | SPCSO01.Oper.ctlVal–SPCSO08.Oper.ctlVal | RB01–RB08 | Remote Bits RB01–RB08 |
| RBGGIO2 | SPCSO09.stVal–SPCSO16.stVal | SPCSO09.Oper.ctlVal–SPCSO16.Oper.ctlVal | RB09–RB16 | Remote Bits RB09–RB16 |
| RBGGIO3 | SPCSO17.stVal–SPCSO24.stVal | SPCSO17.Oper.ctlVal–SPCSO24.Oper.ctlVal | RB17–RB24 | Remote Bits RB17–RB24 |
| RBGGIO4 | SPCSO25.stVal–SPCSO32.stVal | SPCSO25.Oper.ctlVal–SPCSO32.Oper.ctlVal | RB25–RB32 | Remote Bits RB25–RB32 |

Table F.15 shows the LN associated with annunciation elements defined as Logical Device ANN.

Table F.15 Logical Device: ANN (Annunciation) (Sheet 1 of 3)

| Logical Node | Attribute | Data Source | Comment |
|---|---------------------------------------|--------------------------|--|
| Functional Constraint = DC | | | |
| DevIDLPHD1 | PhyNam.model | PARTNO | Part number |
| Functional Constraint = MX ^a | | | |
| AINCGGIO21 | AnIn01.instMag.f– AnIn04.instMag.f | AI301–AI304 ^b | Analog inputs (AI301 to AI304)—Slot C |
| AINDGGIO22 | AnIn01.instMag.f– AnIn04.instMag.f | AI401–AI404 ^b | Analog inputs (AI401 to AI404)—Slot D |
| AINEGGIO23 | AnIn01.instMag.f– AnIn04.instMag.f | AI501–AI504 ^b | Analog inputs (AI501 to AI504)—Slot E |
| MVGGIO12 | AnIn01.instMag.f– AnIn32.instMag.f | MV01–MV32 ^c | Math variables (MV01 to MV32) |
| SCGGIO20 | AnIn01.instMag.f– AnIn32.instMag.f | SC01–SC32 ^d | SELOGIC counters (SC01 to SC32) |
| Functional Constraint = ST | | | |
| INAGGIO1 | Ind01.stVal–Ind02.stVal | IN101–IN102 | Digital inputs (IN101 to IN102)—Slot A |
| INCGGIO13 | Ind01.stVal–Ind08.stVal | IN301–IN308 ^b | Digital inputs (IN301 to IN308)—Slot C |
| INDGGIO15 | Ind01.stVal–Ind08.stVal | IN401–IN408 ^b | Digital inputs (IN401 to IN408)—Slot D |
| INEGGIO17 | Ind01.stVal–Ind08.stVal | IN501–IN508 ^b | Digital inputs (IN501 to IN508)—Slot E |
| LBGGIO25 | Ind01.stVal–Ind32.stVal | LB01–LB32 ^e | Local bits (LB01 to LB32) |
| LTGGIO5 | Ind01.stVal–Ind32.stVal | LT01–LT32 ^f | Latch bits (LT01 to LT32) |
| MBOKGGIO26 | Ind01.stVal | ROKA | Channel A, received data ok |
| MBOKGGIO26 | Ind02.stVal | RBADA | Channel A, outage duration over threshold |
| MBOKGGIO26 | Ind03.stVal | CBADA | Channel A, channel unavailability over threshold |
| MBOKGGIO26 | Ind04.stVal | LBOKA | Channel A, looped back ok |
| MBOKGGIO26 | Ind05.stVal | ROKB | Channel B, received data ok |
| MBOKGGIO26 | Ind06.stVal | RBADB | Channel B, outage duration over threshold |
| MBOKGGIO26 | Ind07.stVal | CBADB | Channel B, channel unavailability over threshold |
| MBOKGGIO26 | Ind08.stVal | LBOKB | Channel B, looped back ok |
| MISCGGIO27 | Ind01.stVal–Ind04.stVal | SG1–SG4 | Setting Group 1 to 4 selection |
| MISCGGIO27 | Ind05.stVal | HALARM | Indication of a diagnostic failure or warning that warrants an ALARM |
| MISCGGIO27 | Ind06.stVal | SALARM | Indication of software or user activity that warrants an ALARM |
| MISCGGIO27 | Ind07.stVal | WARNING | Relay Word WARNING |
| MISCGGIO27 | Ind08.stVal | IRIGOK | IRIG-B time synch input data are valid |
| MISCGGIO27 | Ind09.stVal | TSOK | Time synchronization OK |
| MISCGGIO27 | Ind10.stVal | DST | Daylight-Saving Time active |
| MISCGGIO27 | Ind11.stVal | LINKA | Asserted when a valid link is detected on Port 1A |
| MISCGGIO27 | Ind12.stVal | LINKB | Asserted when a valid link is detected on Port 1B |

Table F.15 Logical Device: ANN (Annunciation) (Sheet 2 of 3)

| Logical Node | Attribute | Data Source | Comment |
|--------------|-------------------------|----------------------------|--|
| MISCGGIO27 | Ind13.stVal | LINKFAIL | Asserted when a valid link is not detected on the active port(s) |
| MISCGGIO27 | Ind14.stVal | PASEL | Asserted when Port 1A is active |
| MISCGGIO27 | Ind15.stVal | PBSEL | Asserted when Port 1B is active |
| MISCGGIO27 | Ind16.stVal | COMMLOSS | DeviceNet communication failure |
| MISCGGIO27 | Ind17.stVal | COMMFLT | DeviceNet internal communication failure |
| MISCGGIO27 | Ind18.stVal | MATHERR | Error in SEL Math computation |
| MISCGGIO27 | Ind19.stVal–Ind32.stVal | 0 | Reserved for future use |
| OUTAGGIO2 | Ind01.stVal–Ind03.stVal | OUT101–OUT103 | Digital outputs (OUT101 to OUT103)—Slot A |
| OUTCGGIO14 | Ind01.stVal–Ind04.stVal | OUT301–OUT304 ^b | Digital outputs (OUT301 to OUT304)—Slot C |
| OUTDGGIO16 | Ind01.stVal–Ind04.stVal | OUT401–OUT404 ^b | Digital outputs (OUT401 to OUT404)—Slot D |
| OUTEGGIO18 | Ind01.stVal–Ind04.stVal | OUT501–OUT504 ^b | Digital outputs (OUT501 to OUT504)—Slot E |
| PBLEDGGIO7 | Ind01.stVal | PB1A_LED | Pushbutton PB1A LED |
| PBLEDGGIO7 | Ind02.stVal | PB1B_LED | Pushbutton PB1B LED |
| PBLEDGGIO7 | Ind03.stVal | PB2A_LED | Pushbutton PB2A LED |
| PBLEDGGIO7 | Ind04.stVal | PB2B_LED | Pushbutton PB2B LED |
| PBLEDGGIO7 | Ind05.stVal | PB3A_LED | Pushbutton PB3A LED |
| PBLEDGGIO7 | Ind06.stVal | PB3B_LED | Pushbutton PB3B LED |
| PBLEDGGIO7 | Ind07.stVal | PB4A_LED | Pushbutton PB4A LED |
| PBLEDGGIO7 | Ind08.stVal | PB4B_LED | Pushbutton PB4B LED |
| PROGGIO24 | Ind01.stVal | REMTRIP | Remote trip |
| PROGGIO24 | Ind02.stVal | ULTRIP1 | Unlatch (auto reset) trip from SELOGIC equation |
| PROGGIO24 | Ind03.stVal | ULTRIP2 | Unlatch (auto reset) trip from SELOGIC equation |
| PROGGIO24 | Ind04.stVal | ULTRXFMR | Unlatch (auto reset) trip from SELOGIC equation |
| PROGGIO24 | Ind05.stVal | ULCL1 | Unlatch close conditions SELOGIC Equation CL1 state |
| PROGGIO24 | Ind06.stVal | ULCL2 | Unlatch close conditions SELOGIC Equation CL2 state |
| PROGGIO24 | Ind07.stVal | RTDT | Asserts when any RTD trip is asserted |
| PROGGIO24 | Ind08.stVal | AMBTRIP | Ambient temperature trip |
| PROGGIO24 | Ind09.stVal | OTHTRIP | Other temperature trip |
| PROGGIO24 | Ind10.stVal | TH5T | Fifth-harmonic alarm threshold exceeded for longer than TH5D |
| PROGGIO24 | Ind11.stVal | TH5 | Fifth-harmonic alarm threshold exceeded |
| PROGGIO24 | Ind12.stVal | RTDFLT | Asserts when an open or short circuit condition is detected on any enabled RTD input, or communication with the external RTD module has been interrupted |
| PROGGIO24 | Ind13.stVal | PHDEM | Phase current demand pickup |
| PROGGIO24 | Ind14.stVal | 3I2DEM | Negative-sequence current demand pickup |
| PROGGIO24 | Ind15.stVal | GNDEM | Zero-sequence current demand pickup |
| PROGGIO24 | Ind16.stVal | 50GREF1 | Normalized residual current sensitivity threshold exceeded |
| PROGGIO24 | Ind17.stVal | 50NREF1 | Neutral current sensitivity threshold exceeded |

Table F.15 Logical Device: ANN (Annunciation) (Sheet 3 of 3)

| Logical Node | Attribute | Data Source | Comment |
|--------------|---------------------------|--------------------------|--|
| PROGGIO24 | Ind18.stVal | AMBALRM | Ambient temperature alarm |
| PROGGIO24 | Ind19.stVal | OTHALRM | Other temperature alarm |
| PROGGIO24 | Ind20.stVal | FREQTRK | Frequency tracking enable bit |
| PROGGIO24 | Ind21.stVal–Ind32.stVal | 0 | Reserved for future use |
| RMBAGGIO8 | Ind01.stVal–Ind08.stVal | RMB1A–RMB8A | Receive MIRRORRED BITS (RMB1A to RMB8A) |
| RMBBGGIO10 | Ind01.stVal–Ind08.stVal | RMB1B–RMB8B | Receive MIRRORRED BITS (RMB1B to RMB8B) |
| SVGGIO3 | Ind01.stVal–Ind32.stVal | SV01–SV32 ^g | SELOGIC variables (SV01 to SV32) |
| SVTGGIO4 | Ind01.stVal–Ind32.stVal | SV01T–SV32T ^g | SELOGIC variable timers (SV01T to SV32T) |
| TLEDGGIO6 | Ind01.stVal | ENABLED | ENABLED LED |
| TLEDGGIO6 | Ind02.stVal | TRIP_LED | TRIP LED |
| TLEDGGIO6 | Ind03.stVal–Ind08.stVal | TLED_01–TLED_06 | Target LEDs TLED_01 to TLED_06 |
| TMBAGGIO9 | Ind01.stVal–Ind08.stVal | TMB1A–TMB8A | Transmit MIRRORRED BITS (TMB1A to TMB8A) |
| TMBBGGIO11 | Ind01.stVal–Ind08.stVal | TMB1B–TMB8B | Transmit MIRRORRED BITS (TMB1B to TMB8B) |
| VBGGIO19 | Ind001.stVal–Ind128.stVal | VB001–VB128 | Virtual bits (VB001 to VB128) |

Table F.16 Logical Device: CFG (Configuration)

| Logical Node | Attribute | Data Source | Comment |
|----------------------------|---------------|-------------|-------------------|
| Functional Constraint = DC | | | |
| DevIDLPHD1 | PhyNam.model | PARTNO | Part number |
| DevIDLPHD1 | PhyNam.serNum | SER_NUM | Serial number |
| LLN0 | NamPlt.swRev | FID | Firmware revision |

Protocol Implementation Conformance Statement

Table F.17 and Table F.18 are as shown in the IEC 61850 standard, Part 8-1, Section 24. Note that since the standard explicitly dictates which services and functions must be implemented to achieve conformance, only the optional services and functions are listed.

Table F.17 PICS for A-Profile Support

| Profile | | Client | Server | Value/Comment |
|---------|----------------------|--------|--------|---------------------------------|
| A1 | Client/Server | N | Y | Only GOOSE, not GSSE Management |
| A2 | GOOSE/GSE management | Y | Y | |
| A3 | GSSE | N | N | |
| A4 | Time Sync | N | N | |

Table F.18 PICS for T-Profile Support

| Profile | | Client | Server | Value/Comment |
|---------|-----------|--------|--------|----------------------|
| T1 | TCP/IP | N | Y | Only GOOSE, Not GSSE |
| T2 | OSI | N | N | |
| T3 | GOOSE/GSE | Y | Y | |
| T4 | GSSE | N | N | |
| T5 | Time Sync | N | N | |

Refer to the ACSI Conformance statements in the Reference Manual for information on the supported services.

MMS Conformance

The Manufacturing Messaging Specification (MMS) stack provides the basis for many IEC 61850 Protocol services. Table F.19 defines the service support requirement and restrictions of the MMS services in the SEL-700 series products supporting IEC 61850. Generally, only those services whose implementation is not mandatory are shown. Refer to the IEC 61850 standard Part 8-1 for more information.

Table F.19 MMS Service Supported Conformance (Sheet 1 of 3)

| MMS Service Supported CBB | Client-CR Supported | Server-CR Supported |
|------------------------------|---------------------|---------------------|
| status | | Y |
| getNameList | | Y |
| identify | | Y |
| rename | | |
| read | | Y |
| write | | Y |
| getVariableAccessAttributes | | Y |
| defineNamedVariable | | |
| defineScatteredAccess | | |
| getScatteredAccessAttributes | | |
| deleteVariableAccess | | |

Table F.19 MMS Service Supported Conformance (Sheet 2 of 3)

| MMS Service Supported CBB | Client-CR Supported | Server-CR Supported |
|--------------------------------|---------------------|---------------------|
| defineNamedVariableList | | |
| getNamedVariableListAttributes | | Y |
| deleteNamedVariableList | | |
| defineNamedType | | |
| getNamedTypeAttributes | | |
| deleteNamedType | | |
| input | | |
| output | | |
| takeControl | | |
| relinquishControl | | |
| defineSemaphore | | |
| deleteSemaphore | | |
| reportPoolSemaphoreStatus | | |
| reportSemaphoreStatus | | |
| initiateDownloadSequence | | |
| downloadSegment | | |
| terminateDownloadSequence | | |
| initiateUploadSequence | | |
| uploadSegment | | |
| terminateUploadSequence | | |
| requestDomainDownload | | |
| requestDomainUpload | | |
| loadDomainContent | | |
| storeDomainContent | | |
| deleteDomain | | |
| getDomainAttributes | | Y |
| createProgramInvocation | | |
| deleteProgramInvocation | | |
| start | | |
| stop | | |
| resume | | |
| reset | | |
| kill | | |
| getProgramInvocationAttributes | | |
| obtainFile | | |
| defineEventCondition | | |
| deleteEventCondition | | |
| getEventConditionAttributes | | |

Table F.19 MMS Service Supported Conformance (Sheet 3 of 3)

| MMS Service Supported CBB | Client-CR Supported | Server-CR Supported |
|--------------------------------|---------------------|---------------------|
| reportEventConditionStatus | | |
| alterEventConditionMonitoring | | |
| triggerEvent | | |
| defineEventAction | | |
| deleteEventAction | | |
| alterEventEnrollment | | |
| reportEventEnrollmentStatus | | |
| getEventEnrollmentAttributes | | |
| acknowledgeEventNotification | | |
| getAlarmSummary | | |
| getAlarmEnrollmentSummary | | |
| readJournal | | |
| writeJournal | | |
| initializeJournal | | |
| reportJournalStatus | | |
| createJournal | | |
| deleteJournal | | |
| fileOpen | | |
| fileRead | | |
| fileClose | | |
| fileRename | | |
| fileDelete | | |
| fileDirectory | | |
| unsolicitedStatus | | |
| informationReport | | Y |
| eventNotification | | |
| attachToEventCondition | | |
| attachToSemaphore | | |
| conclude | | Y |
| cancel | | Y |
| getDataExchangeAttributes | | |
| exchangeData | | |
| defineAccessControlList | | |
| getAccessControlListAttributes | | |
| reportAccessControlledObjects | | |
| deleteAccessControlList | | |
| alterAccessControl | | |
| ReconfigureProgramInvocation | | |

Table F.20 lists specific settings for the MMS parameter Conformance Building Block (CBB).

Table F.20 MMS Parameter CBB

| MMS Parameter CBB | Client-CR Supported | Server-CR Supported |
|-------------------|---------------------|---------------------|
| STR1 | | Y |
| STR2 | | Y |
| VNAM | | Y |
| VADR | | Y |
| VALT | | Y |
| TPY | | Y |
| VLIS | | Y |
| CEI | | |

The following Variable Access Conformance Statements (Table F.21 through Table F.28) are listed in the order specified in the IEC 61850 standard, Part 8-1. Generally, only those services whose implementation is not mandatory are shown. Refer to the IEC 61850 standard Part 8-1 for more information.

Table F.21 Alternate Access Selection Conformance Statement

| Alternate Access Selection | Client-CR Supported | Server-CR Supported |
|----------------------------|---------------------|---------------------|
| accessSelection | | Y |
| component | | Y |
| index | | |
| indexRange | | |
| allElements | | |
| alternateAccess | | Y |
| selectAccess | | Y |
| component | | Y |
| index | | |
| indexRange | | |
| allElements | | |

Table F.22 VariableAccessSpecification Conformance Statement

| VariableAccessSpecification | Client-CR Supported | Server-CR Supported |
|-----------------------------|---------------------|---------------------|
| listOfVariable | | Y |
| variableSpecification | | Y |
| alternateAccess | | Y |
| variableListName | | Y |

Table F.23 VariableSpecification Conformance Statement

| VariableSpecification | Client-CR Supported | Server-CR Supported |
|----------------------------|---------------------|---------------------|
| name | | Y |
| address | | |
| variableDescription | | |
| scatteredAccessDescription | | |
| invalidated | | |

Table F.24 Read Conformance Statement

| Read | Client-CR Supported | Server-CR Supported |
|-----------------------------|---------------------|---------------------|
| Request | | |
| specificationWithResult | | |
| variableAccessSpecification | | |
| Response | | |
| variableAccessSpecification | | Y |
| listOfAccessResult | | Y |

Table F.25 GetVariableAccessAttributes Conformance Statement

| GetVariableAccessAttributes | Client-CR Supported | Server-CR Supported |
|-----------------------------|---------------------|---------------------|
| Request | | |
| name | | |
| address | | |
| Response | | |
| mmsDeletable | | |
| address | | |
| typeSpecification | | |

Table F.26 DefineNamedVariableList Conformance Statement

| DefineVariableAccessAttributes | Client-CR Supported | Server-CR Supported |
|--------------------------------|---------------------|---------------------|
| Request | | |
| variableListName | | |
| listOfVariable | | |
| variableSpecification | | |
| alternateAccess | | |
| Response | | |

Table F.27 GetNamedVariableListAttributes Conformance Statement

| GetNamedVariableListAttributes | Client-CR Supported | Server-CR Supported |
|--------------------------------|---------------------|---------------------|
| Request | | |
| ObjectName | | |
| Response | | |
| mmsDeletable | | Y |
| listOfVariable | | Y |
| variableSpecification | | Y |
| alternateAccess | | Y |

Table F.28 DeleteNamedVariableList

| DeleteNamedVariableList | Client-CR Supported | Server-CR Supported |
|-------------------------------|---------------------|---------------------|
| Request | | |
| Scope | | |
| listOfVariableListName | | |
| domainName | | |
| Response | | |
| numberMatched | | |
| numberDeleted | | |
| DeleteNamedVariableList-Error | | |

GOOSE Services Conformance Statement

Table F.29 GOOSE Conformance

| | Subscriber | Publisher | Value/Comment |
|----------------------------|------------|-----------|---------------|
| GOOSE Services | Y | Y | |
| SendGOOSEMessage | | Y | |
| GetGoReference | | | |
| GetGOOSEElementNumber | | | |
| GetGoCBValues | | Y | |
| SetGoCBValues | | | |
| GSENotSupported | | | |
| GOOSE Control Block (GoCB) | | Y | |

ACSI Conformance Statements

Table F.30 ACSI Basic Conformance Statement

| | | Client/Subscriber | Server/Publisher | SEL-787 Support |
|--|--|-------------------|------------------|-----------------|
| Client-Server Roles | | | | |
| B11 | Server side (of Two-Party Application-Association) | - | c1 ^a | YES |
| B12 | Client side (of Two-Party Application-Association) | c1 ^a | - | |
| SCMS Supported | | | | |
| B21 | SCSM: IEC 61850-8-1 used | | | YES |
| B22 | SCSM: IEC 61850-9-1 used | | | |
| B23 | SCSM: IEC 61850-9-2 used | | | |
| B24 | SCSM: other | | | |
| Generic Substation Event Model (GSE) | | | | |
| B31 | Publisher side | - | O ^b | YES |
| B32 | Subscriber side | O ^b | - | YES |
| Transmission of Sampled Value Model (SVC) | | | | |
| B41 | Published side | - | O ^b | |
| B42 | Subscriber side | O ^b | - | |

^a c1 shall be mandatory if support for LOGICAL-DEVICE model has been declared.

^b O = optional.

Table F.31 ACSI Models Conformance Statement (Sheet 1 of 2)

| | | Client/Subscriber | Server/Publisher | SEL-787 Support |
|---------------------------------------|-------------------------|-------------------|------------------|-----------------|
| If Server Side (B11) Supported | | | | |
| M1 | Logical device | c2 ^a | c2 ^a | YES |
| M2 | Logical node | c3 ^b | c3 ^b | YES |
| M3 | Data | c4 ^c | c4 ^c | YES |
| M4 | Data set | c5 ^d | c5 ^d | YES |
| M5 | Substation | O ^e | O ^e | |
| M6 | Setting group control | O ^e | O ^e | |
| Reporting | | | | |
| M7 | Buffered report control | O ^e | O ^e | YES |
| M7-1 | sequence-number | | | YES |
| M7-2 | report-time-stamp | | | YES |
| M7-3 | reason-for-inclusion | | | YES |
| M7-4 | data-set-name | | | YES |
| M7-5 | data-reference | | | YES |
| M7-6 | buffer-overflow | | | YES |
| M7-7 | entryID | | | YES |
| M7-8 | BufTm | | | YES |

Table F.31 ACSI Models Conformance Statement (Sheet 2 of 2)

| | | Client/Subscriber | Server/Publisher | SEL-787 Support |
|-------------------------------------|---------------------------|-------------------|------------------|-----------------|
| M7-9 | IntgPd | | | YES |
| M7-10 | G1 | | | YES |
| M8 | Unbuffered report control | O ^e | O ^e | YES |
| M8-1 | sequence-number | | | YES |
| M8-2 | report-time-stamp | | | YES |
| M8-3 | reason-for-inclusion | | | YES |
| M8-4 | data-set-name | | | YES |
| M8-5 | data-reference | | | YES |
| M8-6 | BufTm | | | YES |
| M8-7 | IntgPd | | | YES |
| M-8-8 | GI | | | YES |
| Logging | | O ^e | O ^e | |
| M9 | Log control | O ^e | O ^e | |
| M9-1 | IntgPd | | | |
| M10 | Log | O ^e | O ^e | |
| M11 | Control | M ^f | M ^g | YES |
| If GSE (B31/32) Is Supported | | | | |
| M12 | GOOSE | O ^e | O ^e | YES |
| M12-1 | entryID | | | YES |
| M12-2 | DataRefInc | | | YES |
| M13 | GSSE | O ^e | O ^e | |
| If GSE (B41/42) Is Supported | | | | |
| M14 | Multicast SVC | O ^e | O ^e | |
| M15 | Unicast SVC | O ^e | O ^e | |
| M16 | Time | M ^f | M ^f | |
| M17 | File Transfer | O ^e | O ^e | |

^a c2 shall be "M" if support for LOGICAL-NODE model has been declared.

^b c3 shall be "M" if support for DATA model has been declared.

^c c4 shall be "M" if support for DATA-SET, Substitution, Report, Log Control, or Time model has been declared.

^d c5 shall be "M" if support for Report, GSE, or SV models has been declared.

^e O = Optional.

^f M = Mandatory.

^g M = Mandatory.

Table F.32 ACSI Services Conformance Statement (Sheet 1 of 3)

| Services | | AA: TP/MC | Client/ Subscriber | Service/ Publisher | SEL-787 Support |
|---|------------------------|-----------|-----------------------|-----------------------|-----------------|
| Server (Clause 6) | | | | | |
| S1 | ServerDirectory | TP | | M ^a | YES |
| Application Association (Clause 7) | | | | | |
| S2 | Associate | | M ^a | M ^a | YES |
| S3 | Abort | | M ^a | M ^a | YES |
| S4 | Release | | M ^a | M ^a | YES |
| Logical Device (Clause 8) | | | | | |
| S5 | LogicalDeviceDirectory | TP | M ^a | M ^a | YES |
| Logical Node (Clause 9) | | | | | |
| S6 | LogicalNodeDirectory | TP | M ^a | M ^a | YES |
| S7 | GetAllDataValues | TP | O ^b | M ^a | YES |
| Data (Clause 10) | | | | | |
| S8 | GetDataValues | TP | M ^a | M ^a | YES |
| S9 | SetDataValues | TP | O ^b | O ^b | YES |
| S10 | GetDataDirectory | TP | O ^b | M ^a | YES |
| S11 | GetDataDefinition | TP | O ^b | M ^a | YES |
| Data Set (Clause 11) | | | | | |
| S12 | GetDataSetValues | TP | O ^b | M ^a | YES |
| S13 | SetDataSetValues | TP | O ^b | O ^b | YES |
| S14 | CreateDataSet | TP | O ^b | O ^b | |
| S15 | DeleteDataSet | TP | O ^b | O ^b | |
| S16 | GetDataSetDirectory | TP | O ^b | O ^b | YES |
| Substitution (Clause 12) | | | | | |
| S17 | SetDataValues | TP | M ^a | M ^a | |
| Setting Group Control (Clause 13) | | | | | |
| S18 | SelectActiveSG | TP | O ^b | O ^b | |
| S19 | SelectEditSG | TP | O ^b | O ^b | |
| S20 | SetSGvalues | TP | O ^b | O ^b | |
| S21 | ConfirmEditSGVal | TP | O ^b | O ^b | |
| S22 | GetSGValues | TP | O ^b | O ^b | |
| S23 | GetSGCBValues | TP | O ^b | O ^b | |
| S24 | Report | TP | c6 ^c | c6 ^c | YES |
| S24-1 | data-change (dchg) | | | | YES |
| S24-2 | qchg-change (qchg) | | | | YES |
| S24-3 | data-update (dupd) | | | | |
| S25 | GetBRCBValues | TP | c6 ^c | c6 ^c | YES |
| S26 | SetBRCBValues | TP | c6 ^c | c6 ^c | YES |

Table F.32 ACSI Services Conformance Statement (Sheet 2 of 3)

| Services | | AA: TP/MC | Client/ Subscriber | Service/ Publisher | SEL-787 Support |
|--|--------------------|----------------|-----------------------|-----------------------|-----------------|
| Unbuffered Report Control Block (URCB) | | | | | |
| S27 | Report | TP | c6 ^c | c6 ^c | YES |
| S27-1 | data-change (dchg) | | | | YES |
| S27-2 | qchg-change (qchg) | | | | YES |
| S27-3 | data-update (dupd) | | | | |
| S28 | GetURCBValues | TP | c6 ^c | c6 ^c | YES |
| S29 | SetURCBValues | TP | c6 ^c | c6 ^c | YES |
| Logging (Clause 14) | | | | | |
| Log Control Block | | | | | |
| S30 | GetLCBValues | TP | M ^a | M ^a | |
| S31 | SetLCBValues | TP | O ^b | M ^a | |
| LOG | | | | | |
| S32 | QueryLogByTime | TP | c7 ^d | M ^a | |
| S33 | QueryLogByEntry | TP | c7 ^d | M ^a | |
| S34 | GetLogStatusValues | TP | M ^a | M ^a | |
| Generic Substation Event Model (GSE) (Clause 14.3.5.3.4) | | | | | |
| GOOSE-Control-Block | | | | | |
| S35 | SendGOOSEMessage | MC | c8 ^e | c8 ^e | YES |
| S36 | GetReference | TP | O ^b | c9 ^f | |
| S37 | GetGOOSEElement | | | | |
| Number | TP | O ^b | c9 ^f | | |
| S38 | GetGoCBValues | TP | O ^b | O ^b | YES |
| S39 | SetGoCBValues | TP | O ^b | O ^b | Client/Sub |
| ONLY | | | | | |
| GSSE-Control-Block | | | | | |
| S40 | SendGSSEMessage | MC | c8 ^e | c8 ^e | |
| S41 | GetReference | TP | O ^b | c9 ^f | |
| S42 | GetGSSEElement | | | | |
| Number | TP | Ob | c9 ^f | | |
| S43 | GetGsCBValues | TP | O ^b | O ^b | |
| S44 | GetGsCBValues | TP | O ^b | O ^b | |
| Transmission of Sample Value Model (SVC) (Clause 16) | | | | | |
| Multicast SVC | | | | | |
| S45 | SendMSVMessage | MC | c10 ^g | c10 ^g | |
| S46 | GetMSVCBValues | TP | O ^b | O ^b | |
| S47 | SetMSVCBValues | TP | O ^b | O ^b | |

Table F.32 ACSI Services Conformance Statement (Sheet 3 of 3)

| Services | | AA: TP/MC | Client/ Subscriber | Service/ Publisher | SEL-787 Support |
|---------------------------|--|-----------|-----------------------|-----------------------|--|
| Unicast SVC | | | | | |
| S48 | SendUSVMessage | MC | c10 ^g | c10 ^g | |
| S49 | GetUSVCBValues | TP | O ^b | O ^b | |
| S50 | SetUSVCBValues | TP | O ^b | O ^b | |
| Control (Clause 16.4.8) | | | | | |
| S51 | Select | | M ^a | O ^b | YES |
| S52 | SelectWithValue | TP | M ^a | O ^b | YES |
| S53 | Cancel | TP | O ^b | M ^a | YES |
| S54 | Operate | TP | M ^a | M ^a | YES |
| S55 | Command-Termination | TP | M ^a | M ^a | YES |
| S56 | TimeActivated-Operate | TP | O ^b | O ^b | |
| File Transfer (Clause 20) | | | | | |
| S57 | GetFile | TP | O ^b | M ^a | |
| S58 | SetFile | TP | O ^b | O ^b | |
| S59 | DeleteFile | TP | O ^b | O ^b | |
| S60 | GetFileAttributeValues | TP | O ^b | M ^a | |
| Time (Clause 5.5) | | | | | |
| T1 | Time resolution of internal clock (nearest negative power of 2 in seconds) | | | | 20 (1 μs) |
| T2 | Time accuracy of internal clock | | | | 7 (10 ms) for SNTP 18 (4 μs) for IRIG-B |
| | T1 | | | | YES (for IRIG-B) |
| | T2 | | | | YES (for IRIG-B) |
| | T3 | | | | YES (for IRIG-B) |
| | T4 | | | | YES (for IRIG-B) |
| T3 | Supported TimeStamp resolution (nearest negative power of 2 in seconds) | | | | 7 (10 ms) for SNTP 18 (4 μs) for IRIG-B |

^a M = Mandatory.

^b O = Optional.

^c c6 shall declare support for at least one (BRCB or URCB).

^d c7 shall declare support for at least one (QueryLogByTime or QueryLogAfter).

^e c8 shall declare support for at least one (SendGOOSEMessage or SendGSSEMessage).

^f c9 shall declare support if TP association is available.

^g c10 shall declare support for at least one (SendMSVMessage or SendUSVMessage).

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Appendix G

DeviceNet Communications

Overview

This appendix describes DeviceNet communications features supported by the SEL-787 Transformer Protection Relay.

DeviceNet is a low-level communications network that provides direct connectivity among industrial devices, resulting in improved communication and device-level diagnostics that are otherwise either unavailable or inaccessible through expensive hardwired I/O interfaces. Industrial devices for which DeviceNet provides this direct connectivity include limit switches, photoelectric sensors, valve manifolds, motor starters, process sensors, bar code readers, variable frequency drives, panel displays, and operator interfaces.

The *SEL DeviceNet Communications Card User's Guide* contains more information on the installation and use of the DeviceNet card or the DeviceNet protocol.

NOTE: Be aware of the following setting in the relay:
Under Global settings category Access Control, there is a setting called BLOCK MODBUS SET.

The BLOCK MODBUS SET setting is used to block relay settings changes via Modbus or DeviceNet protocols. The factory-default setting, BLKMBSET := NONE, **allows** all setting changes via Modbus or DeviceNet communications. The BLKMBSET := R_S setting **prevents** Modbus or DeviceNet communications from resetting to the factory-default settings. The BLKMBSET := ALL setting **blocks** all changes to the settings via the Modbus or the DeviceNet protocol.

You are strongly advised to change the BLKMBSET (BLOCK MODBUS SET) := ALL if you do not want the PLC (Programmable Logic Controller) or DCS (Distributed Control System) to send the settings to the SEL-787 relay. There is a strong possibility that under special conditions like a reboot, the PLC/DCS will send default settings to the relay, overwriting the existing settings. To protect the existing settings under these conditions it is highly recommended to set the setting to "ALL."

DeviceNet Card

The DeviceNet Card is an optional accessory that enables connection of the SEL-787 to the DeviceNet automation network. The card (see *Figure G.1*) occupies the communications expansion Slot C in the relay.

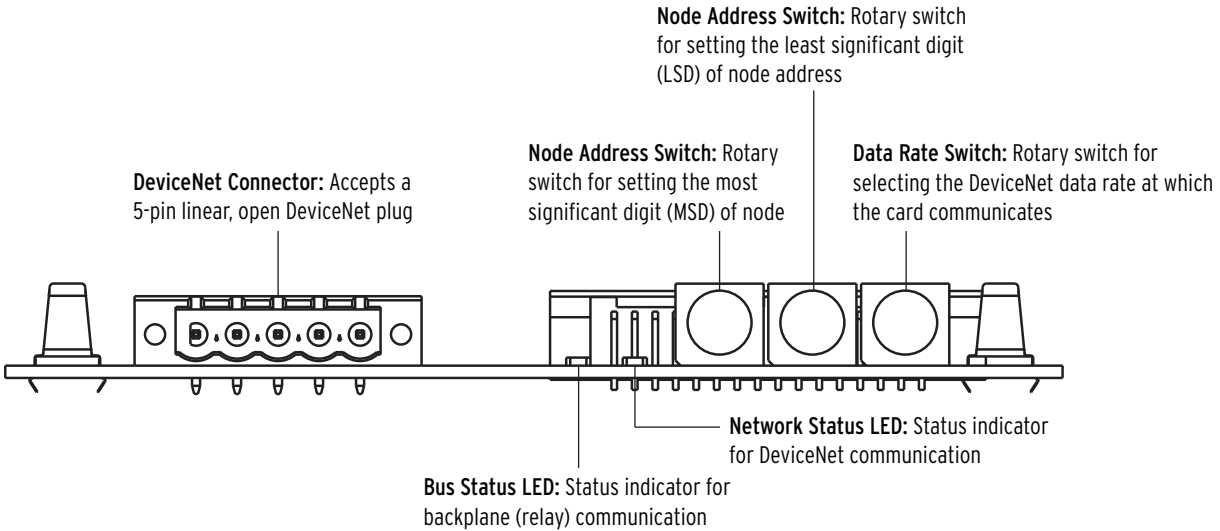


Figure G.1 DeviceNet Card Component Overview

Features

The DeviceNet Card features the following:

- The card receives the required power from the DeviceNet network.
- Rotary switches let you set the node address and network data rate prior to mounting in the SEL-787 and applying power. Alternatively, the switches can be set to positions that allow for configuration of these settings over the DeviceNet network, utilizing a network configuration tool such as RSNetWorx for DeviceNet.
- Status indicators report the status of the device bus and network communications. They are visible from the back panel of the SEL-787 as installed.

You can do the following with the DeviceNet interface:

- Retrieve metering data such as the following:
 - Currents
 - Voltages
 - Power
 - Energy
 - Max/Min
 - Analog Inputs
 - Counters

- Retrieve and modify relay settings
- Read and set time
- Monitor device status, trip/warning status, and I/O status
- Perform high-speed control
- Reset trip, target, and accumulated data
- Retrieve events history

The DeviceNet interface can be configured through the use of address and data transmission rate switches. Indicators on the card at the back of the relay show network status and network activity.

Electronic Data Sheet

The Electronic Data Sheet (EDS) is a specially formatted file that includes configurable parameters for the device and public interfaces to those parameters. The EDS file contains information such as number of parameters; groupings; parameter name; minimum, maximum, and default values; units; data format; and scaling. This information makes possible user-friendly configuration tools (e.g., RSNetWorx for DeviceNet or DeviceNet Configurator from OMRON®) for device parameter monitoring, modification, or both. The interface to the device can also be easily updated without revision of the configuration software tool itself.

All the registers defined in the Modbus® Register Map (*Table E.34*) are available as parameters in a DeviceNet configuration. Parameter names, data ranges, and scaling; enumeration values and strings; parameter groups; and product information are the same as specified in the Modbus Register Map defined in *Table E.34*. The parameter numbers are offset by a count of 100 from the register numbers.

The EDS file for the SEL-787, SEL-xxxRxxx.EDS, is located on the SEL-787 Product Literature CD. It can also be downloaded from the SEL website at www.selinc.com.

Complete specifications for the DeviceNet protocol are available on the Open DeviceNet Vendor's Association (ODVA) website www.odva.org. ODVA is an independent supplier organization that manages the DeviceNet specification and supports the worldwide growth of DeviceNet.

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Appendix H

Synchrophasors

Introduction

The SEL-787 Transformer Protection Relay provides Phasor Measurement Control Unit (PMCU) capabilities when connected to an IRIG-B time source with an accuracy of $\pm 10 \mu\text{s}$ or better. Synchrophasor data are available via the **MET PM** ASCII command and the C37.118 Protocol.

Synchrophasor measurement refers to the concept of providing measurements taken on a synchronized schedule at precise instants in time. A high-accuracy clock, commonly called a Global Positioning System (GPS) receiver such as the SEL-2407 Satellite-Synchronized Clock, makes synchrophasor measurement possible.

The availability of an accurate time reference over a large geographic area allows multiple devices, such as SEL-787 relays, to synchronize the gathering of power system data. The accurate clock allows precise event report triggering and other off-line analysis functions.

The SEL-787 Global settings class contains the synchrophasor settings, including the choice of transmitted synchrophasor data set. The Port settings class selects which serial port(s) can be used for synchrophasor protocol use. See *Settings for Synchrophasors on page H.4*.

The SEL-787 timekeeping function generates status Relay Word bits and time-quality information that is important for synchrophasor measurement. Some protection SELOGIC® control equation variables, and programmable digital trigger information is also added to the Relay Word bits for synchrophasors. See *Synchrophasor Relay Word Bits on page H.9*.

When synchrophasor measurement is enabled, the SEL-787 creates the synchrophasor data set at a user-defined rate. Synchrophasor data are available in ASCII format over a serial port set to **PROTO = SEL**. See *View Synchrophasors Using the MET PM Command on page H.10*.

The value of synchrophasor data increases greatly when the data can be shared over a communications network in real time. A synchrophasor protocol is available in the SEL-787 that allows for a centralized device to collect data efficiently from several phasor measurement units (PMUs). Some possible uses of a system-wide synchrophasor system include the following:

- Power-system state measurement
- Wide-area network protection and control schemes
- Small-signal analysis
- Power-system disturbance analysis

The SEL-3306 Synchrophasor Processor is a PC-based communications processor specifically designed to interface with PMUs. The SEL-3306 has

two primary functions. The first is to collect and correlate synchrophasor data from multiple PMUs. The second is to then compact and transmit synchrophasor data either to a data historian for post-analysis or to visualization software for real-time viewing of a power system.

The SEL-787 supports the protocol portion of the IEEE C37.118, Standard for Synchrophasors for Power Systems. In the SEL-787, this protocol is referred to simply as C37.118. See *Settings Affect Message Contents on page H.11*.

Synchrophasor Measurement

The phasor measurement unit in the SEL-787 measures three voltages and six currents on a constant-time basis. These samples are time-stamped with the IRIG time source. The phase angle is measured relative to an absolute time reference, which is represented by a cosine function in *Figure H.1*. The time-of-day is shown for the two time marks. The reference is consistent with the phase reference defined in the C37.118 standard. During steady-state conditions, the SEL-787 synchrophasor values can be directly compared to values from other phasor measurement units that conform to C37.118. Synchrophasor values are available for the full frequency range of the SEL-787.

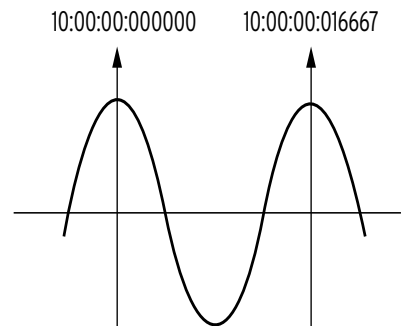


Figure H.1 Phase Reference

The TSOK Relay Word bit asserts when the SEL-787 has determined that the IRIG-B time source has sufficient accuracy and the synchrophasor data meets the specified accuracy. Synchrophasors are still measured if the time source threshold is not met, as indicated by Relay Word bit TSOK = logical 0. The **MET PM** command is not available in this case.

The instrumentation transformers (PTs or CTs) and the interconnecting cables may introduce a time shift in the measured signal. Global settings VCOMP, IW1COMP, and IW2COMP, entered in degrees, are added to the measured phasor angles to create the corrected phasor angles, as shown in *Figure H.2*, *Figure H.3*, and *Equation H.1*. The VCOMP, IW1COMP, and IW2COMP settings may be positive or negative values.

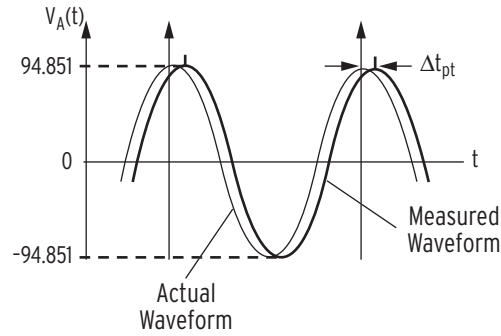


Figure H.2 Waveform at Relay Terminals May Have a Phase Shift

$$\begin{aligned} \text{Compensation Angle} &= \frac{\Delta t_{pt}}{\left(\frac{1}{\text{freq}_{\text{nominal}}}\right)} \cdot 360^\circ \\ &= \Delta t_{pt} \cdot \text{freq}_{\text{nominal}} \cdot 360^\circ \end{aligned} \quad \text{Equation H.1}$$

If the time shift on the pt measurement path $\Delta t_{pt} = 0.784$ ms and the nominal frequency, $\text{freq}_{\text{nominal}} = 60\text{Hz}$, use *Equation H.2* to obtain the correction angle:

$$0.784 \cdot 10^{-3} \text{ s} \cdot 60 \text{ s}^{-1} \cdot 360^\circ = 16.934^\circ \quad \text{Equation H.2}$$

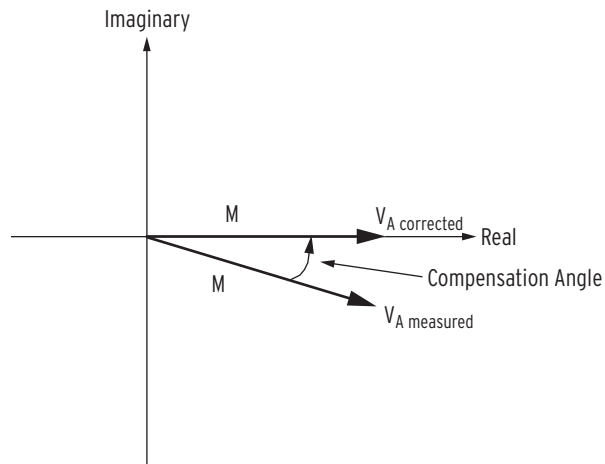


Figure H.3 Correction of Measured Phase Angle

The phasors are rms values scaled in primary units, as determined by Group setting PTR, CTR1, and CTR2 (for the IW1 and IW2 current sources).

Because the sampling reference is based on the GPS clock (IRIG-B signal) and not synchronized to the power system, an examination of successive synchrophasor data sets will almost always show some angular change between samples of the same signal. This is not a malfunction of the relay or the power system, but is merely a result of viewing data from one system with an instrument with an independent time base. In other words, a power system has a nominal frequency of either 50 or 60 Hz, but on closer examination, it is usually running a little faster or slower than nominal.

Settings for Synchrophasors

The phasor measurement unit (PMU) settings are listed in *Table H.1*. Modify these settings when you want to use the C37.118 synchrophasor protocol.

The Global enable setting EPMU must be set to Y before the remaining SEL-787 synchrophasor settings are available. No synchrophasor data collection can take place when EPMU := N.

You must make the serial port settings in *Table H.2* to transmit data with a synchrophasor protocol. It is possible to set EPMU := Y without using any serial ports for synchrophasor protocols. For example, the serial port **MET PM** ASCII command can still be used.

Table H.1 PMU Settings in the SEL-787 for C37.118 Protocol in Global Settings

| Setting | Description | Default |
|---------------------|--|----------------------------------|
| EPMU | Enable Synchronized Phasor Measurement (Y, N) | N ^a |
| MRATE | Messages per Second {1, 2, 5, 10} | 10 |
| PMSTN | Station Name (16 characters) | SEL-787 XFRMR 1 |
| PMID | PMU Hardware ID (1–65534) | 1 |
| PHDATAV | Phasor Data Set, Voltages (V1, ALL, NA) | V1 |
| VCOMP | Voltage Angle Comp Factor (–179.99 to 180 deg) | 0.00 |
| PHDATAI | Phasor Data Set, Currents (I1, ALL, NA) | NA |
| PHCURR ^b | Current Source (IW1, IW2, BOTH) | BOTH |
| IW1COMP | IW1 Angle Comp Factor (–179.99 to 180 deg) | 0.00 |
| IW2COMP | IW2 Angle Comp Factor (–179.99 to 180 deg) | 0.00 |
| NUMANA | Number of Analog Values (0–4) | 0 |
| NUMDSW | Number of 16-bit Digital Status Words (0, 1) | 0 |
| TREA1 | Trigger Reason Bit 1 (SELOGIC) | TRIP or ER |
| TREA2 | Trigger Reason Bit 2 (SELOGIC) | 81D1T OR 81D2T OR 81D3T OR 81D4T |
| TREA3 | Trigger Reason Bit 3 (SELOGIC) | 59P1T OR 59P2T OR 59Q1T OR 59Q2T |
| TREA4 | Trigger Reason Bit 4 (SELOGIC) | 27P1T OR 27P2T |
| PMTRIG | Trigger (SELOGIC) | TREA1 OR TREA2 OR TREA3 OR TREA4 |
| IRIGC | IRIG-B Control Bits Definition (NONE, C37.118) | NONE |

^a Set EPMU := Y to access the remaining settings.

^b Setting hidden when PHDATAI := NA.

Certain settings in *Table H.1* are hidden, depending on the status of other settings. For example, if PHDATAI := NA, the PHCURR setting is hidden to limit the number of settings for your synchrophasor application.

The Port settings for PROTO := PMU, shown in *Table H.2*, do not include the settings DATABIT and PARITY; these two settings are internally fixed as

DATABIT := 8, PARITY := N (None). See *Section 7: Communications* for descriptions of these functions.

Table H.2 SEL-787 Serial Port Settings for Synchrophasors

| Setting | Description | Default |
|---------|---|------------------|
| PROTO | Protocol (SEL, MOD, EVMSG, PMU, MBA, MBB, MB8A, MB8B, MBTA, MBTB) ^{a, b} | SEL ^c |
| SPEED | Data Speed (300, 1200, 2400, 4800, 9600, 19200, 38400 bps) | 9600 |
| STOPBIT | Stop Bits (1, 2) | 1 |
| RTSCTS | HDWR HANDSHAKING (Y, N) | N |

^a Some of the other PROTO setting choices may not be available.

^b Setting choice PMU is not available on PORT 1.

^c Set PROTO := PMU to enable (on this port) the synchrophasor protocol.

PROTO := PMU Does Not Allow Commands on That Serial Port

The PROTO := PMU settings choice in *Table H.2* can be made even when Global setting EPMU := N. However, in this situation, the serial port will not respond to any commands or requests. Either enable synchrophasors by making the *Table H.1* settings, or change the port PROTO setting to SEL.

If you use a computer terminal session or ACSELERATOR QuickSet® SEL-5030 Software connected to a serial port, and then set that same serial port PROTO setting to PMU, you will lose the ability to communicate with the relay through ASCII commands or virtual file interface commands. If this happens, either connect via another serial port (that has PROTO := SEL) or use the front-panel HMI SET/SHOW screen to change the disabled port PROTO setting back to SEL.

Descriptions of Synchrophasor Settings

Definitions for the settings in *Table H.1* are as follows:

MRATE

Selects the message rate in messages per second for synchrophasor data streaming on serial ports.

Choose the MRATE setting that suits the needs of your PMU application. This setting is one of six settings that determine the minimum port SPEED necessary to support the synchrophasor data packet rate and size. See *Communications Bandwidth on page H.12* for detailed information.

PMSTN and PMID

Defines the name and number of the PMU.

The PMSTN setting is an ASCII string with as many as 16 characters. The PMID setting is a numeric value. Use your utility or synchrophasor data concentrator naming convention to determine these settings.

PHDATAV and VCOMP

PHDATAV selects which voltage synchrophasors to include in the data packet. Consider the burden on your synchrophasor processor and offline storage requirements when deciding how much data to transmit. This setting is one of six settings that determine the minimum port SPEED necessary to support the

synchrophasor data packet rate and size—see *Communications Bandwidth on page H.12* for detailed information.

- PHDATAV := V1 will transmit only positive-sequence voltage, V_1
- PHDATAV := ALL will transmit V_1 , V_A , V_B , and V_C
- PHDATAV := NA will not transmit any voltages

Table H.3 describes the order of synchrophasors inside the data packet.

The VCOMP setting allows correction for any steady-state voltage phase errors (from the potential transformers or wiring characteristics). See *Synchrophasor Measurement on page H.2* for details on this setting.

PHDATAI, PHCURR, IW1COMP, and IW2COMP

PHDATAI and PHCURR select which current synchrophasors to include in the data packet. Consider the burden on your synchrophasor processor and offline storage requirements when deciding how much data to transmit. These settings are two of the six settings that determine the minimum port SPEED necessary to support the synchrophasor data packet rate and size—see *Communications Bandwidth on page H.12* for detailed information.

- PHDATAI := I1 will transmit only positive-sequence current, I_1
- PHDATAI := ALL will transmit I_1 , I_A , I_B , and I_C for the Windings selected by PHCURR
- PHDATAI := NA will not transmit any currents

PHCURR selects the source current(s) for the synchrophasor data selected by PHDATAI.

- PHCURR := IW1 uses the currents measured on the IAW1, IBW1, and ICW1 inputs
- PHCURR := IW2 uses the currents measured on the IAW2, IBW2, and ICW2 inputs
- PHCURR := BOTH uses the currents measured on both the I_W1 inputs and I_W2 inputs

Table H.3 describes the order of synchrophasors inside the data packet.

The IW1COMP and IW2COMP settings allow correction for any steady-state phase errors (from the current transformers or wiring characteristics). See *Synchrophasor Measurement on page H.2* for details on these settings.

Table H.3 Synchrophasor Order in Data Stream (Voltages and Currents)

| Synchrophasors ^a | | Included When Global Settings Are as Follows: |
|-----------------------------|-------|---|
| Polar | | |
| Magnitude | Angle | |
| V1 | V1 | PHDATAV := V1 or ALL |
| VA | VA | PHDATAV := ALL |
| VB | VB | |
| VC | VC | |
| I1W1 | I1W1 | |
| IAW1 | IAW1 | (PHDATAI := I1 or ALL) AND (PHCURR := IW2 or BOTH) |
| IBW1 | IBW1 | |
| ICW1 | ICW1 | |
| I1W2 | I1W2 | |
| IAW2 | IAW2 | PHDATAI := ALL AND (PHCURR := IW2 or BOTH) |
| IBW2 | IBW2 | |
| ICW2 | ICW2 | |

^a Synchrophasors are included in the order shown (i.e., voltages, if selected, will always precede currents).

NUMANA

Selects the number of user-definable analog values to be included in the synchrophasor data stream.

This setting is one of six settings that determine the minimum port **SPEED** necessary to support the synchrophasor data packet rate and size—see *Communications Bandwidth on page H.12* for detailed information.

The choices for this setting depend on the synchrophasor system design.

- Setting NUMANA := 0 sends no user-definable analog values.
- Setting NUMANA := 1–4 sends the user-definable analog values, as listed in *Table H.4*.

The format of the user-defined analog data is always floating point, and each value occupies four bytes.

Table H.4 User-Defined Analog Values Selected by the NUMANA Setting

| NUMANA Setting | Analog Quantities Sent | Total Number of Bytes Used for Analog Values |
|----------------|------------------------|--|
| 0 | None | 0 |
| 1 | MV29 | 4 |
| 2 | Above, plus MV30 | 8 |
| 3 | Above, plus MV31 | 12 |
| 4 | Above, plus MV32 | 16 |

NUMDSW

Selects the number of user-definable digital status words to be included in the synchrophasor data stream.

This setting is one of six settings that determine the minimum port **SPEED** necessary to support the synchrophasor data packet rate and size—see *Communications Bandwidth* on page H.12 for detailed information.

The choices for this setting depend on the synchrophasor system design. The inclusion of binary data can help indicate breaker status or other operational data to the synchrophasor processor.

- Setting NUMDSW := 0 sends no user-definable binary status words.
- Setting NUMDSW := 1 sends the user-definable binary status words, as listed in *Table H.5*.

Table H.5 User-Defined Digital Status Words Selected by the NUMDSW Setting

| NUMDSW Setting | Digital Status Words Sent | Total Number of Bytes Used for Digital Values |
|----------------|---------------------------|---|
| 0 | None | 0 |
| 1 | [SV32, SV31...SV17] | 2 |

TREA1, TREA2, TREA3, TREA4, and PMTRIG

Defines the programmable trigger bits as allowed by IEEE C37.118.

Each of the four Trigger Reason settings, TREA1–TREA4, and the PMU Trigger setting, PMTRIG, are SELOGIC control equations in the Global settings class. The SEL-787 evaluates these equations and places the results in Relay Word bits with the same names: TREA1–TREA4, and PMTRIG.

NOTE: The PM Trigger function is not associated with the SEL-787 Event Report Trigger ER, a SELOGIC control equation in the Report settings class.

The trigger reason equations represent the Trigger Reason bits in the STAT field of the data packet. After the trigger reason bits are set to convey a message, the PMTRIG Equation should be asserted for a reasonable amount of time, to allow the synchrophasor processor to read the TREA1–TREA4 fields.

The IEEE C37.118 standard defines the first eight of 16 binary combinations of these trigger reason bits (bits 0–3). The remaining eight binary combinations are available for user definition.

Table H.6 PM Trigger Reason Bits–IEEE C37.118 Assignments (Sheet 1 of 2)

| TREA4 | TREA3 | TREA2 | TREA1 | Hexadecimal | Meaning ^a |
|---------|---------|---------|---------|-------------|----------------------|
| (bit 3) | (bit 2) | (bit 1) | (bit 0) | | |
| 0 | 0 | 0 | 0 | 0x00 | Manual |
| 0 | 0 | 0 | 1 | 0x01 | Magnitude Low |
| 0 | 0 | 1 | 0 | 0x02 | Magnitude High |
| 0 | 0 | 1 | 1 | 0x03 | Phase Angle Diff. |
| 0 | 1 | 0 | 0 | 0x04 | Frequency High/Low |
| 0 | 1 | 0 | 1 | 0x05 | df/dt High |
| 0 | 1 | 1 | 0 | 0x06 | Reserved |
| 0 | 1 | 1 | 1 | 0x07 | Digital |

Table H.6 PM Trigger Reason Bits–IEEE C37.118 Assignments (Sheet 2 of 2)

| TREA4 | TREA3 | TREA2 | TREA1 | Hexadecimal | Meaning ^a |
|---------|---------|---------|---------|-------------|----------------------|
| (bit 3) | (bit 2) | (bit 1) | (bit 0) | | |
| 1 | 0 | 0 | 0 | 0x08 | User |
| 1 | 0 | 0 | 1 | 0x09 | User |
| 1 | 0 | 1 | 0 | 0x0A | User |
| 1 | 0 | 1 | 1 | 0x0B | User |
| 1 | 1 | 0 | 0 | 0x0C | User |
| 1 | 1 | 0 | 1 | 0x0D | User |
| 1 | 1 | 1 | 0 | 0x0E | User |
| 1 | 1 | 1 | 1 | 0x0F | User |

^a When PMTRIG is asserted. The terminology comes from IEEE C37.118.

The SEL-787 automatically sets the TREA1–TREA4 or PMTRIG Relay Word bits based on their default SELOGIC equation. To change the operation of these bits they must be programmed.

These bits may be used to send various messages at a low bandwidth via the synchrophasor message stream. Digital Status Words may also be used to send binary information directly, without the need to manage the coding of the trigger reason messages in SELOGIC.

Use these Trigger Reason bits if your synchrophasor system design requires these bits. The SEL-787 synchrophasor processing and protocol transmission are not affected by the status of these bits.

IRIGC

Defines if IEEE C37.118 control bit extensions are in use. Control bit extensions contain information such as Leap Second, UTC time, Daylight-Saving Time, and Time Quality. When your satellite-synchronized clock provides these extensions your relay will be able adjust the synchrophasor time-stamp accordingly.

- IRIGC := NONE will ignore bit extensions
- IRIGC := C37.118 will extract bit extensions and correct synchrophasor time accordingly

Synchrophasor Relay Word Bits

Table H.7 and *Table H.8* list the SEL-787 Relay Word bits that are related to synchrophasor measurement.

The Synchrophasor Trigger Relay Word bits in *Table H.7* follow the state of the SELOGIC control equations of the same name, listed at the bottom of *Table H.1*. These Relay Word bits are included in the IEEE C37.118 synchrophasor data frame STAT field. See *Table H.5* for standard definitions for these settings.

Table H.7 Synchrophasor Trigger Relay Word Bits

| Name | Description |
|--------|--------------------------------|
| PMTRIG | Trigger (SELOGIC) |
| TREA4 | Trigger Reason Bit 4 (SELOGIC) |
| TREA3 | Trigger Reason Bit 3 (SELOGIC) |
| TREA2 | Trigger Reason Bit 2 (SELOGIC) |
| TREA1 | Trigger Reason Bit 1 (SELOGIC) |

The Time Synchronization Relay Word bits in *Table H.8* indicate the present status of the timekeeping function of the SEL-787.

Table H.8 Time Synchronization Relay Word Bits

| Name | Description |
|--------|---|
| IRIGOK | Asserts while relay time is based on IRIG-B time source. |
| TSOK | Time Synchronization OK. Asserts while time is based on an IRIG-B time source of sufficient accuracy for synchrophasor measurement. |
| PMDOK | Phasor Measurement Data OK. Asserts when the SEL-787 is enabled and synchrophasors are enabled (Global setting EPMU := Y). |

View Synchrophasors Using the MET PM Command

The **MET PM** serial port ASCII command may be used to view the SEL-787 synchrophasor measurements. See *MET Command (Metering Data) on page 7.31* for general information on the **MET** command.

There are multiple ways to use the **MET PM** command:

- As a test tool, to verify connections, phase rotation, and scaling
- As an analytical tool, to capture synchrophasor data at an exact time, in order to compare it with similar data captured in other phasor measurement unit(s) at the same time
- As a method of periodically gathering synchrophasor data through a communications processor

The **MET PM** command displays the same set of analog synchrophasor information, regardless of the Global settings PHDATAV, PHDATAI, and PHCURR. The **MET PM** command can function even when no serial ports are sending synchrophasor data—it is unaffected by serial port setting PROTO.

The **MET PM** command will only operate when the SEL-787 is in the IRIG timekeeping mode, as indicated by Relay Word bit TSOK = logical 1.

Figure H.4 shows a sample **MET PM** command response. The synchrophasor data are also available via the **HMI > Meter PM** menu in ACSELERATOR QuickSet, and has a similar format to *Figure H.4*.

The **MET PM time** command can be used to direct the SEL-787 to display the synchrophasor for an exact specified time, in 24-hour format. For example, entering the command **MET PM 14:14:12** will result in a response similar to *Figure H.4* occurring just after 14:14:12, with the time stamp 14:14:12.000.

NOTE: In order to have the **MET PM xx:yy:zz** response transmitted from a serial port, the corresponding port must have the AUTO setting set to YES (Y). Also note that the **MET PM** response is not available on the Ethernet port.

See *Section 7: Communications* for complete command options, and error messages.

| | | | | | | | | | | | | |
|------------------------------------|-------|------|-------|-------------------------------------|--------|---------|--------|-----------------------|--|--|--|--|
| SEL-787 | | | | Date: 02/05/2008 | | | | Time: 17:22:07 | | | | |
| TRNSFRMR RELAY | | | | Time Source: External | | | | | | | | |
| Time Quality | | | | Maximum time synchronization error: | | | | 0.000 (ms) TSOK = 1 | | | | |
| Synchrophasors | | | | | | | | | | | | |
| | | | | Phase Voltages | | | | Pos. Sequence Voltage | | | | |
| | | | | VA | VB | VC | V1 | | | | | |
| MAG (kV) | | | | 134.14 | 131.64 | 128.60 | 131.45 | | | | | |
| ANG (DEG) | | | | 129.57 | 10.57 | -111.89 | 129.47 | | | | | |
| | | | | Phase Currents | | | | Pos. Sequence Current | | | | |
| | | | | IAW1 | IBW1 | ICW1 | I1W1 | | | | | |
| MAG (A) | | | | 365.26 | 359.22 | 379.91 | 367.91 | | | | | |
| ANG (DEG) | | | | 114.03 | -2.46 | -120.25 | 117.03 | | | | | |
| | | | | IAW2 | IBW2 | ICW2 | I1W2 | | | | | |
| MAG (A) | | | | 617.05 | 587.00 | 599.40 | 600.93 | | | | | |
| ANG (DEG) | | | | 136.34 | 13.93 | -106.93 | 134.65 | | | | | |
| FREQ (Hz) 60.00 | | | | | | | | | | | | |
| Rate-of-change of FREQ (Hz/s) 0.00 | | | | | | | | | | | | |
| Digitals | | | | | | | | | | | | |
| SV24 | SV23 | SV22 | SV21 | SV20 | SV19 | SV18 | SV17 | | | | | |
| 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 | | | | | |
| SV32 | SV31 | SV30 | SV29 | SV28 | SV27 | SV26 | SV25 | | | | | |
| 0 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | | | | | |
| Analog | | | | | | | | | | | | |
| MV29 | 2.300 | MV30 | 0.150 | MV31 | 17.400 | MV32 | -9.230 | | | | | |
| => | | | | | | | | | | | | |

Figure H.4 Sample MET PM Command Response

C37.118 Synchrophasor Protocol

The SEL-787 complies with IEEE C37.118, Standard for Synchrophasors for Power Systems. The protocol is available on serial ports 2, 3, 4, and F by setting the corresponding Port setting PROTO := PMU.

This subsection does not cover the details of the protocol, but highlights some of the important features and options that are available.

Settings Affect Message Contents

The SEL-787 allows several options for transmitting synchrophasor data. These are controlled by Global settings described in *Settings for Synchrophasors on page H.4*. You can select how often to transmit the synchrophasor messages (MRATE) and which synchrophasors to transmit (PHDATAV, PHDATAI, and PHCURR). The SEL-787 automatically includes the frequency and rate-of-change-of-frequency in the synchrophasor messages.

The relay can include as many as four user-programmable analog values in the synchrophasor message, as controlled by Global setting NUMANA, and 0 or 16 digital status values, as controlled by Global setting NUMDSW.

The SEL-787 always includes the results of four synchrophasor trigger reason SELOGIC equations TREA1, TREA2, TREA3, and TREA4, and the trigger SELOGIC equation result PMTRIG, in the synchrophasor message.

Communications Bandwidth

A phasor measurement unit (PMU) that is configured to transmit a single synchrophasor (positive-sequence voltage, for example) at a message rate of once per second places little burden on the communications channel. As more synchrophasors, analog values, or digital status words are added, or if the message rate is increased, some communications channel restrictions come into play.

The C37.118 synchrophasor message format always includes 18 bytes for the message header and terminal ID, time information, status bits, and CRC value. The selection of synchrophasor data, numeric format, programmable analog, and programmable digital data will add to the byte requirements. *Table H.9* can be used to calculate the number of bytes in a synchrophasor message.

Table H.9 Size of a C37.118 Synchrophasor Message

| Item | Possible Number of Quantities | Bytes per Quantity | Minimum Number of Bytes | Maximum Number of Bytes |
|-----------------------------|----------------------------------|--------------------|-------------------------|-------------------------|
| Fixed | | | 18 | 18 |
| Synchrophasors | 0, 1, 2, 3, 4, 5, 6, 8, 9, or 12 | 4 | 0 | 48 |
| Frequency | 2 (fixed) | 2 | 4 | 4 |
| Analog Values | 0–4 | 4 | 0 | 16 |
| Digital Status Words | 0–1 | 2 | 0 | 2 |
| Total (Minimum and Maximum) | | | 22 | 88 |

Table H.10 lists the baud settings available on any SEL-787 serial port (setting SPEED), and the maximum message size that can fit within the port bandwidth. Blank entries indicate bandwidths of less than 20 bytes.

Table H.10 Serial Port Bandwidth for Synchrophasors (in Bytes)

| Global Setting MRATE | Port Setting SPEED | | | | | | | |
|----------------------|--------------------|-----|------|------|------|------|-------|-------|
| | 300 | 600 | 1200 | 2400 | 4800 | 9600 | 19200 | 38400 |
| 1 | 21 | 42 | 85 | 170 | 340 | 680 | 1360 | 2720 |
| 2 | | 21 | 42 | 85 | 170 | 340 | 680 | 1360 |
| 5 | | | | 34 | 68 | 136 | 272 | 544 |
| 10 | | | | | 34 | 68 | 136 | 272 |

Referring to *Table H.9* and *Table H.10*, it is clear that the lower SPEED settings are very restrictive.

The smallest practical synchrophasor message would be comprised of one digital status word, and this message would consume 24 bytes. This type of message could be sent at any message rate (MRATE) when SPEED := 4800 to 38400, as much as MRATE := 5 when SPEED := 2400, and as much as MRATE := 1 when SPEED := 600.

Another example application has messages comprised of eight synchrophasors, one digital status word, and two analog values. This type of message would consume 64 bytes. The 64-byte message could be sent at any message rate (MRATE) when SPEED := 9600.

Protocol Operation

NOTE: Only one serial port can be set to PROTO:=PMU at one time.

The SEL-787 will only transmit synchrophasor messages over serial ports that have setting PROTO := PMU. The connected device will typically be a synchrophasor processor, such as the SEL-3306. The synchrophasor processor controls the PMU functions of the SEL-787, with IEEE C37.118 commands, including commands to start and stop synchrophasor data transmission, and commands to request a configuration block from the relay, so the synchrophasor processor can automatically build a database structure.

Transmit Mode Control

The SEL-787 will not begin transmitting synchrophasors until an enable message is received from the synchrophasor processor. The relay will stop synchrophasor transmission when the appropriate command is received from the synchrophasor processor. The SEL-787 can also indicate when a configuration change occurs, so the synchrophasor processor can request a new configuration block and keep its database up-to-date.

The SEL-787 will only respond to configuration block request messages when it is in the non-transmitting mode.

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Appendix I

MIRRORED BITS Communications

Overview

IMPORTANT: Be sure to configure the port before connecting to a MIRRORED BITS device. If you connect an unconfigured port to a MIRRORED BITS device, the device will appear to be locked up.

NOTE: Complete all of the port settings for a port that you use for MIRRORED BITS communications before you connect an external MIRRORED BITS communications device. If you connect a MIRRORED BITS communications device to a port that is not set for MIRRORED BITS communications operation, the port will be continuously busy.

MIRRORED BITS® communications is a direct relay-to-relay communications protocol that allows IEDs to exchange information quickly, securely, and with minimal expense. Use MIRRORED BITS for functions such as remote control and remote sensing. The SEL-787 Transformer Protection Relay supports two MIRRORED BITS communications channels, designated A and B. Use the port setting **PROTO** to assign one of the MIRRORED BITS communications channels to a serial port; **PROTO:=MBA** for MIRRORED BITS communications Channel A or **PROTO:=MBB** for MIRRORED BITS communications Channel B. MIRRORED BITS are either Transmit MIRRORED BITS (TMB) or Received MIRRORED BITS (RMB). Transmit MIRRORED BITS include TMB1A–TMB8A (channel A) and TMB1B–TMB8B (channel B). The last letter (A or B) designates with which channel the bits are associated. Received bits include RMB1A–RMB8A and RMB1B–RMB8B. Control the transmit MIRRORED BITS in SELOGIC® control equations. Use the received MIRRORED BITS as arguments in SELOGIC control equations. The channel status bits are ROKA, RBADA, CBADA, LBOKA, ROKB, RBADB, CBADB, and LBOKB. You can also use these channel status bits as arguments in SELOGIC control equations. Use the **COM** command (see *Section 7: Communications*) for additional channel status information.

Because of different applications, the SEL product range supports several variations of the MIRRORED BITS communications protocol. Through port settings, you can set the SEL-787 for compatible operation with SEL-300 series devices, SEL-2505 Remote I/O Modules, and SEL-2100 Logic Processors. When communicating with an SEL-400 series relay, be sure to set the transmission mode setting in the SEL-400 series relay to paced transmission (**TXMODE: = P**).

Operation

Message Transmission

In the SEL-787, the MIRRORED BITS transmission rate is a function of both the baud rate and the power system cycle. At baud rates below 9600, the SEL-787 transmits MIRRORED BITS as fast as possible for the given baud. At rates at and above 9600 baud the SEL-787 self-paces, using a technique similar to the SEL-400 series pacing mode. There are no settings to enable or disable the self-pacing mode; the SEL-787 automatically enters the self-pacing mode at baud rates of 9600, 19200, and 38400. *Table I.1* shows the transmission rates of the MIRRORED BITS messages at different baud.

NOTE: Exercise caution when applying a MIRRORED BITS channel to relays that protect systems that may not be synchronized because the automatic pacing modes operate under the assumption that both relays are protecting systems of similar frequency. To maintain MIRRORED BITS channel dependability for this application, it is recommended that you use baud rates of 2400 or 4800.

Table I.1 Number of MIRRORED BITS Messages for Different Baud

| Baud Rate | Transmission Rate of MIRRORED BITS Packets |
|-----------|--|
| 2400 | 15 ms |
| 4800 | 7.5 ms |
| 9600 | 4 times a power system cycle (automatic pacing mode) |
| 19200 | 4 times a power system cycle (automatic pacing mode) |
| 38400 | 4 times a power system cycle (automatic pacing mode) |

Transmitting at longer intervals for baud rates above 9600 avoids overflowing relays that receive MIRRORED BITS at a slower rate.

Message Reception Overview

During synchronized MIRRORED BITS communications with the communications channel in normal state, the relay decodes and checks each received message. If the message is valid, the relay sends each received logic bit (RMB_n , where $n = 1$ through 8) to the corresponding pickup and dropout security counters, that in turn set or clear the RMB_nA and RMB_nB relay element bits.

Message Decoding and Integrity Checks

Set the RX_ID of the local SEL-787 to match the TX_ID of the remote SEL-787. The SEL-787 provides indication of the status of each MIRRORED BITS communications channel with Relay Word bits $ROKA$ (receive OK) and $ROKB$. During normal operation, the relay sets the ROK_c ($c = A$ or B). Upon detecting any of the following conditions, the relay clears the ROK_c bit when:

- The relay is disabled.
- MIRRORED BITS are not enabled.
- Parity, framing, or overrun errors.
- Receive message identification error.
- No message received in the time three messages have been sent when $PROTO = MB_c$, or seven messages have been sent when $PROTO = MB_{8c}$.
- Loopback is enabled.

The relay asserts ROK_c only after successful synchronization as described below and two consecutive messages pass all of the data checks described above. After ROK_c is reasserted, received data may be delayed while passing through the security counters described below.

While ROK_c is deasserted, the relay does not transfer new RMB data to the pickup-dropout security counters described below. Instead, the relay sends one of the user-definable default values to the security counter inputs. For each RMB_n , use the $RXDFLT$ setting to determine the default state the MIRRORED BITS should use in place of received data if an error condition is detected. The setting is a mask of 1s, 0s, and/or Xs (for RMB_{1A} – RMB_{8A}), where X represents the most recently received valid value. The positions of the 1s and 0s correspond to the respective positions of the MIRRORED BITS in the Relay Word bits (see *Appendix J: Relay Word Bits*). *Table I.2* is an extract of *Table J.1* on page J.1, showing the positions of the MIRRORED BITS.

Table I.2 Positions of the MIRRORED BITS

| Bit/ Row | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|-------|-------|-------|-------|-------|-------|-------|-------|
| 70 | RMB8A | RMB7A | RMB6A | RMB5A | RMB4A | RMB3A | RMB2A | RMB1A |
| 72 | RMB8B | RMB7B | RMB6B | RMB5B | RMB4B | RMB3B | RMB2B | RMB1B |

Table I.3 shows an example of the values of the MIRRORED BITS for a RXDFLT setting of 10100111.

Table I.3 MIRRORED BITS Values for a RXDFLT Setting of 10100111

| Bit/ Row | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|---|---|---|---|---|---|---|---|
| 70 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 1 |

Individual pickup and dropout security counters supervise the movement of each received data bit into the corresponding RMB n element. You can set each pickup/dropout security counter from 1 to 8. A setting of 1 causes a security counter to pass every occurrence, while a setting of 8 causes a counter to wait for eight consecutive occurrences in the received data before updating the data bits. The pickup and dropout security count settings are separate. Control the security count settings with the settings RMB n PU and RMB n DO.

A pickup/dropout security counter operates identically to a pickup/dropout timer, except that the counter uses units of counted received messages instead of time. Select a setting for the security counter in accordance with the transmission rate (see Table I.1). For example, when transmitting at 2400 baud, a security counter set to 2 counts delays a bit by about 30 ms. However, when operating at 9600 baud, a setting of 2 counts delays a bit by about 8.5 ms.

You must consider the impact of the security counter settings in the receiving relay to determine the channel timing performance, particularly when two relays of different processing rates are communicating via MIRRORED BITS, such as an SEL-321 and an SEL-787. The SEL-321 processes power system information each 1/8 power system cycle, but, when transmitting at 19200 baud, the SEL-787 processes MIRRORED BITS messages at 4.15 ms at 60 Hz (4 times per power system cycle at 60 Hz). Although the SEL-321 processes power system information each 1/8 power system cycle, the relay processes the MIRRORED BITS pickup/dropout security counters as MIRRORED BITS messages are received. Because the SEL-787 transmits messages at approximately 1/4-cycle processing interval (9600 baud and above, see Table I.1), a counter set to two in the SEL-321 delays a received bit by another approximately 1/2 cycle. However, a security counter in the SEL-787 with a setting of two delays a received bit from the SEL-321 by 1/4 cycle, because the SEL-787 is receiving new MIRRORED BITS messages each 1/8 cycle from the SEL-321.

Channel Synchronization

When an SEL-787 detects a communications error, it deasserts ROKA or ROKB. If an SEL-787 detects two consecutive communications errors, it transmits an attention message, which includes the TXID setting. The relay transmits an attention message until it receives an attention message that includes a match to the TXID setting value. If the attention message is successful, the relay has properly synchronized and data transmission resumes. If the attention message is not successful, the relay repeats the attention message until it is successful.

In summary, when a relay detects an error, it transmits an attention message until it receives an attention message with its own TX_ID included. If three or four relays are connected in a ring topology, the attention message will go all the way around the loop until the originating relay receives it. The message then dies and data transmission resumes. This method of synchronization allows the relays to reliably determine which byte is the first byte of the message. It also forces unsynchronized UARTs to become resynchronized. On the down side, this method takes down the entire loop for a receive error at any relay in the loop. This decreases availability. It also makes one-way communications impossible.

Loopback Testing

Use the **LOOP** command to enable loopback testing. In the loopback mode, you loop the transmit port to the receive port of the same relay to verify transmission messages. While in loopback mode, ROK_c is deasserted, and another user accessible Relay Word bit, LBOK_c (Loop Back OK) asserts and deasserts based on the received data checks (see the *Section 7: Communications* for the ACSII commands).

Channel Monitoring

Based on the results of data checks (described above), the relay collects information regarding the 255 most recent communications errors. Each record contains at least the following fields:

- DATE—Date when the dropout occurred
- TIME—Time when the dropout occurred
- RECOVERY_DATE—Date when the channel returned to service (if the channel is currently failed, it is displayed and included in the calculations, as if its recovery were to occur at the time the report was requested)
- RECOVERY_TIME—Time when the channel returned to service (if the channel is currently failed, it is displayed and included in the calculations, as if its recovery were to occur at the time the report was requested)
- DURATION—Time elapsed during dropout
- CAUSE—Reason for dropout (see *Message Decoding and Integrity Checks on page I.2*)

There is a single record for each outage, but an outage can evolve. For example, the initial cause could be a data disagreement, but framing errors can extend the outage. If the channel is currently failed, it is displayed and included in the calculations, as if its recovery were to occur at the time the report was requested.

NOTE: Combine error conditions including RBADA, RBADB, CBADA, and CBADB with other alarm conditions using SELogic control equations. You can use these alarm conditions to program the relay to take appropriate action when it detects a communications channel failure.

When the duration of an outage on Channel A or B exceeds a user-definable threshold, the relay asserts a user-accessible Relay Word bit, RBADA or RBADB. When channel unavailability exceeds a user-definable threshold for Channel A or B, the relay asserts a user-accessible Relay Word bit, CBADA or CBADB. Use the **COMM** command to generate a long or summary report of the communications errors.

Use the RBADPU setting to determine how long a channel error must last before the meter element RBADA is asserted. RBADA is deasserted when the channel error is corrected. RBADPU is accurate to ± 1 second.

Use the CBADPU setting to determine the ratio of channel down time to the total channel time before the meter element CBADA is asserted. The times used in the calculation are those that are available in the COM records. See the *COMMUNICATIONS Command* in *Section 7: Communications* for more information.

MIRRORED BITS Protocol for the Pulsar 9600 Baud Modem

To use a Pulsar MBT modem, set setting **PROTO** := MBTA or MBTB (Port settings). Setting **PROTO** := MBTA or MBTB hides setting **SPEED** (forces the baud to 9600), hides setting **PARITY** (forces parity to a value of 0), hides setting **RTSCTS** (forces RTSCTS to a value of N), and forces the transmit time to be faster than double the power system cycle. *Table I.4* shows the difference in message transmission periods when not using the Pulsar modem (**PROTO** ≠ MBTA or MBTB), and using the Pulsar MBT modem (**PROTO** = MBTA or MBTB).

NOTE: You must consider the idle time in calculations of data transfer latency through a Pulsar MBT modem system.

Table I.4 MIRRORED BITS Communications Message Transmission Period

| Baud | PROTO ≠ MBTA or MBTB | PROTO = MBTA or MBTB |
|-------|------------------------------|------------------------------|
| 38400 | 4 times a power system cycle | n/a |
| 19200 | 4 times a power system cycle | n/a |
| 9600 | 4 times a power system cycle | 2 times a power system cycle |
| 4800 | 7.5 ms | n/a |

The relay sets RTS to a negative voltage at the EIA-232 connector to signify that MIRRORED BITS communications matches this specification.

Settings

Set **PROTO** = MBA or MB8A to enable the MIRRORED BITS protocol channel A on this port. Set **PROTO** = MBB or MB8B to enable the MIRRORED BITS protocol channel B on this port. The standard MIRRORED BITS protocols MBA and MBB use a 6-data bit format for data encoding. The MB8 protocols MB8A and MB8B use an 8-data bit format, which allows MIRRORED BITS to operate on communication channels requiring an 8-data bit format. For the remainder of this section, **PROTO** = MBA is assumed. *Table I.5* shows the MIRRORED BITS protocol port settings, ranges, and default settings for Port F, Port 3, and Port 4.

Table I.5 MIRRORED BITS Protocol Settings (Sheet 1 of 2)

| Setting Prompt | Setting Description | Factory-Default Setting |
|----------------|--|-------------------------|
| TXID | MIRRORED BITS ID of This Device (1–4) | 2 |
| RXID | MIRRORED BITS ID of Device Receiving From (1–4) | 1 |
| RBADPU | Outage Duration to Set RBAD (0–10000 seconds) | 60 |
| CBADPU | Channel Unavailability to Set CBAD (1–10000 ppm) | 1000 |
| RXDFLT | 8 char string of 1s, 0s, or Xs | XXXXXXXX |
| RMB1PU | RMB1 Pickup Debounce Messages (1–8 messages) | 1 |
| RMB1DO | RMB1 Dropout Debounce Messages (1–8 messages) | 1 |

Table I.5 MIRRORED BITS Protocol Settings (Sheet 2 of 2)

| Setting Prompt | Setting Description | Factory-Default Setting |
|----------------|---|-------------------------|
| RMB2PU | RMB2 Pickup Debounce Messages (1–8 messages) | 1 |
| RMB2DO | RMB2 Dropout Debounce Messages (1–8 messages) | 1 |
| RMB3PU | RMB3 Pickup Debounce Messages (1–8 messages) | 1 |
| RMB3DO | RMB3 Dropout Debounce Messages (1–8 messages) | 1 |
| RMB4PU | RMB4 Pickup Debounce Messages (1–8 messages) | 1 |
| RMB4DO | RMB4 Dropout Debounce Messages (1–8 messages) | 1 |
| RMB5PU | RMB5 Pickup Debounce Messages (1–8 messages) | 1 |
| RMB5DO | RMB5 Dropout Debounce Messages (1–8 messages) | 1 |
| RMB6PU | RMB6 Pickup Debounce Messages (1–8 messages) | 1 |
| RMB6DO | RMB6 Dropout Debounce Messages (1–8 messages) | 1 |
| RMB7PU | RMB7 Pickup Debounce Messages (1–8 messages) | 1 |
| RMB7DO | RMB7 Dropout Debounce Messages (1–8 messages) | 1 |
| RMB8PU | RMB8 Pickup Debounce Messages (1–8 messages) | 1 |
| RMB8DO | RMB8 Dropout Debounce Messages (1–8 messages) | 1 |

Appendix J

Relay Word Bits

Overview

The protection and control element results are represented by Relay Word bits in the SEL-787 Transformer Protection Relay. Each Relay Word bit has a label name and can be in either of the following states:

- 1 (logical 1)
- 0 (logical 0)

Logical 1 represents an element being picked up or otherwise asserted.
Logical 0 represents an element being dropped out or otherwise deasserted.

Table J.1 and Table J.2 show a list of Relay Word bits and corresponding descriptions. The Relay Word bit row numbers correspond to the row numbers used in the **TAR** command (see *TARGET Command (Display Relay Word Bit Status)* on page 7.42).

Any Relay Word bit (except Row 0) can be used in SELOGIC® control equations (see Section 4: Protection and Logic Functions) and the Sequential Events Recorder (SER) trigger list settings (see Section 9: Analyzing Events).

Table J.1 SEL-787 Relay Word Bits (Sheet 1 of 4)

| Bit/ Row | Relay Word Bits | | | | | | | |
|--------------|-----------------|----------|---------|---------|---------|---------|---------|---------|
| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| TAR 0 | ENABLED | TRIP_LED | TLED_01 | TLED_02 | TLED_03 | TLED_04 | TLED_05 | TLED_06 |
| 1 | 50P11T | 50P12T | 50P13T | 50P14T | 50P21T | 50P22T | 50P23T | 50P24T |
| 2 | 50G11T | 50G12T | 50Q11T | 50Q12T | 50G21T | 50G22T | 50Q21T | 50Q22T |
| 3 | 50N11T | 50N12T | 50NREF1 | REF1E | 50GREF1 | REF1F | REF1R | REF1P |
| 4 | 51P1T | 51P2T | 51G1T | 51G2T | 51Q1T | 51Q2T | 51N1T | a |
| 5 | 87U1 | 87U2 | 87U3 | 87U | 87R1 | 87R2 | 87R3 | 87R |
| 6 | TH5T | 87AT | 27P1T | 27P2T | 59P1T | 59P2T | 3PWR1T | 3PWR2T |
| 7 | 81D1T | 81D2T | 81D3T | 81D4T | BFT1 | BFT2 | 59Q1T | 59Q2T |
| 8 | 24D1 | 24D1T | 24C2 | 24C2T | 24CR | a | a | RTDT |
| 9 | REMTRIP | a | a | a | a | a | ORED50T | ORED51T |
| 10 | 50P11P | 50P12P | 50P13P | 50P14P | 50P21P | 50P22P | 50P23P | 50P24P |
| 11 | 50G11P | 50G12P | 50Q11P | 50Q12P | 50G21P | 50G22P | 50Q21P | 50Q22P |
| 12 | 50N11P | 50N12P | 51P1AR | 51P1BR | 51P1CR | 51P2AR | 52A1 | 52A2 |
| 13 | 51P1P | 51P2P | 51G1P | 51G2P | 51Q1P | 51Q2P | 51N1P | 51P2BR |
| 14 | 51P1R | 51P2R | 51G1R | 51G2R | 51Q1R | 51Q2R | 51N1R | 51P2CR |

Table J.1 SEL-787 Relay Word Bits (Sheet 2 of 4)

| Bit/ Row | Relay Word Bits | | | | | | | |
|-------------|-----------------|----------|----------|----------|----------|----------|----------|----------|
| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 15 | 2_4HB1 | 2_4HB2 | 2_4HB3 | 2_4HBL | 5HB1 | 5HB2 | 5HB3 | 5HBL |
| 16 | 87BL1 | 87BL2 | 87BL3 | 87HB | 87HR1 | 87HR2 | 87HR3 | 87HR |
| 17 | TH5 | 87AP | 27P1 | 27P2 | 59P1 | 59P2 | 3PWR1P | 3PWR2P |
| 18 | AMBALRM | AMBTRIP | OTHALRM | OTHTRIP | BFI1 | BFI2 | 59Q1 | 59Q2 |
| 19 | TRIP | OUT101 | OUT102 | OUT103 | OUT301 | OUT302 | OUT303 | OUT304 |
| 20 | OUT401 | OUT402 | OUT403 | OUT404 | OUT501 | OUT502 | OUT503 | OUT504 |
| 21 | IN101 | IN102 | a | a | a | a | a | a |
| 22 | IN301 | IN302 | IN303 | IN304 | IN305 | IN306 | IN307 | IN308 |
| 23 | IN401 | IN402 | IN403 | IN404 | IN405 | IN406 | IN407 | IN408 |
| 24 | IN501 | IN502 | IN503 | IN504 | IN505 | IN506 | IN507 | IN508 |
| 25 | LINKA | LINKB | PMDOK | SALARM | WARNING | TSOK | IRIGOK | FAULT |
| 26 | COMMIDLE | COMMLOSS | COMMFLT | CFGFLT | LINKFAIL | PASEL | PBSEL | LOP |
| 27 | FREQTRK | ER | a | a | RSTENRGY | RSTMXMN | RSTDEN | RSTPKDEM |
| 28 | RTDFLT | RTDIN | TRGTR | a | RTDA | DSABLSET | RSTTRGT | HALARM |
| 29 | RTD1A | RTD1T | RTD2A | RTD2T | RTD3A | RTD3T | RTD4A | RTD4T |
| 30 | RTD5A | RTD5T | RTD6A | RTD6T | RTD7A | RTD7T | RTD8A | RTD8T |
| 31 | RTD9A | RTD9T | RTD10A | RTD10T | RTD11A | RTD11T | RTD12A | RTD12T |
| 32 | CLOSE1 | CF1 | CC1 | a | a | CLOSE2 | CF2 | CC2 |
| 33 | SG1 | SG2 | SG3 | SG4 | TREA1 | TREA2 | TREA3 | TREA4 |
| 34 | OC1 | OC2 | TR1 | TR2 | TRXFMR | TRIP1 | TRIP2 | TRIPXFMR |
| 35 | CL1 | CL2 | ULTRIP1 | ULTRIP2 | ULTRXFMR | ULCL1 | ULCL2 | PMTRIG |
| 36 | DNAUX1 | DNAUX2 | DNAUX3 | DNAUX4 | DNAUX5 | DNAUX6 | DNAUX7 | DNAUX8 |
| 37 | DNAUX9 | DNAUX10 | DNAUX11 | RELAY_EN | a | INR1 | INR2 | INR3 |
| 38 | PB01 | PB02 | PB03 | PB04 | PB01_PUL | PB02_PUL | PB03_PUL | PB04_PUL |
| 39 | PB1A_LED | PB1B_LED | PB2A_LED | PB2B_LED | PB3A_LED | PB3B_LED | PB4A_LED | PB4B_LED |
| 40 | a | a | T01_LED | T02_LED | T03_LED | T04_LED | T05_LED | T06_LED |
| 41 | PHDEM | 3I2DEM | GNDEM | a | a | TFLTALA | TFLTALB | TFLTALC |
| 42 | LB01 | LB02 | LB03 | LB04 | LB05 | LB06 | LB07 | LB08 |
| 43 | LB09 | LB10 | LB11 | LB12 | LB13 | LB14 | LB15 | LB16 |
| 44 | LB17 | LB18 | LB19 | LB20 | LB21 | LB22 | LB23 | LB24 |
| 45 | LB25 | LB26 | LB27 | LB28 | LB29 | LB30 | LB31 | LB32 |
| 46 | RB01 | RB02 | RB03 | RB04 | RB05 | RB06 | RB07 | RB08 |
| 47 | RB09 | RB10 | RB11 | RB12 | RB13 | RB14 | RB15 | RB16 |
| 48 | RB17 | RB18 | RB19 | RB20 | RB21 | RB22 | RB23 | RB24 |
| 49 | RB25 | RB26 | RB27 | RB28 | RB29 | RB30 | RB31 | RB32 |
| 50 | SV01 | SV02 | SV03 | SV04 | SV05 | SV06 | SV07 | SV08 |
| 51 | SV01T | SV02T | SV03T | SV04T | SV05T | SV06T | SV07T | SV08T |
| 52 | SV09 | SV10 | SV11 | SV12 | SV13 | SV14 | SV15 | SV16 |
| 53 | SV09T | SV10T | SV11T | SV12T | SV13T | SV14T | SV15T | SV16T |
| 54 | SV17 | SV18 | SV19 | SV20 | SV21 | SV22 | SV23 | SV24 |

Table J.1 SEL-787 Relay Word Bits (Sheet 3 of 4)

| Bit/ Row | Relay Word Bits | | | | | | | |
|-------------|-----------------|----------|----------|---------|----------|----------|----------|---------|
| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 55 | SV17T | SV18T | SV19T | SV20T | SV21T | SV22T | SV23T | SV24T |
| 56 | SV25 | SV26 | SV27 | SV28 | SV29 | SV30 | SV31 | SV32 |
| 57 | SV25T | SV26T | SV27T | SV28T | SV29T | SV30T | SV31T | SV32T |
| 58 | LT01 | LT02 | LT03 | LT04 | LT05 | LT06 | LT07 | LT08 |
| 59 | LT09 | LT10 | LT11 | LT12 | LT13 | LT14 | LT15 | LT16 |
| 60 | LT17 | LT18 | LT19 | LT20 | LT21 | LT22 | LT23 | LT24 |
| 61 | LT25 | LT26 | LT27 | LT28 | LT29 | LT30 | LT31 | LT32 |
| 62 | SC01QU | SC02QU | SC03QU | SC04QU | SC05QU | SC06QU | SC07QU | SC08QU |
| 63 | SC01QD | SC02QD | SC03QD | SC04QD | SC05QD | SC06QD | SC07QD | SC08QD |
| 64 | SC09QU | SC10QU | SC11QU | SC12QU | SC13QU | SC14QU | SC15QU | SC16QU |
| 65 | SC09QD | SC10QD | SC11QD | SC12QD | SC13QD | SC14QD | SC15QD | SC16QD |
| 66 | SC17QU | SC18QU | SC19QU | SC20QU | SC21QU | SC22QU | SC23QU | SC24QU |
| 67 | SC17QD | SC18QD | SC19QD | SC20QD | SC21QD | SC22QD | SC23QD | SC24QD |
| 68 | SC25QU | SC26QU | SC27QU | SC28QU | SC29QU | SC30QU | SC31QU | SC32QU |
| 69 | SC25QD | SC26QD | SC27QD | SC28QD | SC29QD | SC30QD | SC31QD | SC32QD |
| 70 | RMB8A | RMB7A | RMB6A | RMB5A | RMB4A | RMB3A | RMB2A | RMB1A |
| 71 | TMB8A | TMB7A | TMB6A | TMB5A | TMB4A | TMB3A | TMB2A | TMB1A |
| 72 | RMB8B | RMB7B | RMB6B | RMB5B | RMB4B | RMB3B | RMB2B | RMB1B |
| 73 | TMB8B | TMB7B | TMB6B | TMB5B | TMB4B | TMB3B | TMB2B | TMB1B |
| 74 | LBOKB | CBADB | RBADB | ROKB | LBOKA | CBADA | RBADA | ROKA |
| 75 | VB001 | VB002 | VB003 | VB004 | VB005 | VB006 | VB007 | VB008 |
| 76 | VB009 | VB010 | VB011 | VB012 | VB013 | VB014 | VB015 | VB016 |
| 77 | VB017 | VB018 | VB019 | VB020 | VB021 | VB022 | VB023 | VB024 |
| 78 | VB025 | VB026 | VB027 | VB028 | VB029 | VB030 | VB031 | VB032 |
| 79 | VB033 | VB034 | VB035 | VB036 | VB037 | VB038 | VB039 | VB040 |
| 80 | VB041 | VB042 | VB043 | VB044 | VB045 | VB046 | VB047 | VB048 |
| 81 | VB049 | VB050 | VB051 | VB052 | VB053 | VB054 | VB055 | VB056 |
| 82 | VB057 | VB058 | VB059 | VB060 | VB061 | VB062 | VB063 | VB064 |
| 83 | VB065 | VB066 | VB067 | VB068 | VB069 | VB070 | VB071 | VB072 |
| 84 | VB073 | VB074 | VB075 | VB076 | VB077 | VB078 | VB079 | VB080 |
| 85 | VB081 | VB082 | VB083 | VB084 | VB085 | VB086 | VB087 | VB088 |
| 86 | VB089 | VB090 | VB091 | VB092 | VB093 | VB094 | VB095 | VB096 |
| 87 | VB097 | VB098 | VB099 | VB100 | VB101 | VB102 | VB103 | VB104 |
| 88 | VB105 | VB106 | VB107 | VB108 | VB109 | VB110 | VB111 | VB112 |
| 89 | VB113 | VB114 | VB115 | VB116 | VB117 | VB118 | VB119 | VB120 |
| 90 | VB121 | VB122 | VB123 | VB124 | VB125 | VB126 | VB127 | VB128 |
| 91 | AILW1 | AILW2 | AILAL | 50P11AP | AIHW1 | AIHW2 | AIHAL | 50P11AT |
| 92 | AI301LW1 | AI301LW2 | AI301LAL | 50P11BP | AI301HW1 | AI301HW2 | AI301HAL | 50P11BT |
| 93 | AI302LW1 | AI302LW2 | AI302LAL | 50P11CP | AI302HW1 | AI302HW2 | AI302HAL | 50P11CT |
| 94 | AI303LW1 | AI303LW2 | AI303LAL | 50P21AP | AI303HW1 | AI303HW2 | AI303HAL | 50P21AT |

Table J.1 SEL-787 Relay Word Bits (Sheet 4 of 4)

| Bit/ Row | Relay Word Bits | | | | | | | |
|-------------|-----------------|----------|----------|---------|----------|----------|----------|---------|
| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 95 | AI304LW1 | AI304LW2 | AI304LAL | 50P21BP | AI304HW1 | AI304HW2 | AI304HAL | 50P21BT |
| 96 | AI401LW1 | AI401LW2 | AI401LAL | 50P21CP | AI401HW1 | AI401HW2 | AI401HAL | 50P21CT |
| 97 | AI402LW1 | AI402LW2 | AI402LAL | 51P1AP | AI402HW1 | AI402HW2 | AI402HAL | 51P1AT |
| 98 | AI403LW1 | AI403LW2 | AI403LAL | 51P1BP | AI403HW1 | AI403HW2 | AI403HAL | 51P1BT |
| 99 | AI404LW1 | AI404LW2 | AI404LAL | 51P1CP | AI404HW1 | AI404HW2 | AI404HAL | 51P1CT |
| 100 | AI501LW1 | AI501LW2 | AI501LAL | 51P2AP | AI501HW1 | AI501HW2 | AI501HAL | 51P2AT |
| 101 | AI502LW1 | AI502LW2 | AI502LAL | 51P2BP | AI502HW1 | AI502HW2 | AI502HAL | 51P2BT |
| 102 | AI503LW1 | AI503LW2 | AI503LAL | 51P2CP | AI503HW1 | AI503HW2 | AI503HAL | 51P2CT |
| 103 | AI504LW1 | AI504LW2 | AI504LAL | a | AI504HW1 | AI504HW2 | AI504HAL | a |
| 104 | DI_A1 | DI_B1 | DI_C1 | DI_A2 | DI_B2 | DI_C2 | a | MATHERR |
| 105 | TQUAL1 | TQUAL2 | TQUAL4 | TQUAL8 | DST | DSTP | LPSEC | LPSECP |
| 106 | TSNTPB | TSNTPP | TUTCS | TUTC1 | TUTC2 | TUTC4 | TUTC8 | TUTCH |

^a Reserved for future use.

Definitions

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 1 of 10)

| Bit | Definition | Row |
|--------|---|-----|
| a | Reserved | — |
| 2_4HB1 | Second or Fourth Harmonic block asserted for differential element 1 | 15 |
| 2_4HB2 | Second or Fourth Harmonic block asserted for differential element 2 | 15 |
| 2_4HB3 | Second or Fourth Harmonic block asserted for differential element 3 | 15 |
| 2_4HBL | Second or Fourth Harmonic block asserted (2_4HB1 OR 2_4HB2 OR 2_4HB3) | 15 |
| 24C2 | Level 2 Volts/Hertz composite element pickup | 8 |
| 24C2T | Level 2 Volts/Hertz composite element timed out | 8 |
| 24CR | Level 2 Volts/Hertz element fully reset | 8 |
| 24D1 | Level 1 Volts/Hertz instantaneous pickup | 8 |
| 24D1T | Level 1 Volts/Hertz definite-time element timed out | 8 |
| 27P1 | Level 1 phase undervoltage element pickup | 17 |
| 27P1T | Level 1 phase undervoltage element trip | 6 |
| 27P2 | Level 2 phase undervoltage element pickup | 17 |
| 27P2T | Level 2 phase undervoltage element trip | 6 |
| 3I2DEM | Negative-sequence current demand pickup | 41 |
| 3PWR1P | Three phase power element 1 pickup | 17 |
| 3PWR1T | Three phase power element 1 trip | 6 |
| 3PWR2P | Three phase power element 2 pickup | 17 |

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 2 of 10)

| Bit | Definition | Row |
|---------|--|-----|
| 3PWR2T | Three phase power element 2 trip | 6 |
| 50G11P | Level 1 residual ground instantaneous overcurrent element pickup—Winding 1 | 11 |
| 50G11T | Level 1 residual ground instantaneous overcurrent element trip—Winding 1 | 2 |
| 50G12P | Level 2 residual ground instantaneous overcurrent element pickup—Winding 1 | 11 |
| 50G12T | Level 2 residual ground instantaneous overcurrent element trip—Winding 1 | 2 |
| 50G21P | Level 1 residual ground instantaneous overcurrent element pickup—Winding 2 | 11 |
| 50G21T | Level 1 residual ground instantaneous overcurrent element trip—Winding 2 | 2 |
| 50G22P | Level 2 residual ground instantaneous overcurrent element pickup—Winding 2 | 11 |
| 50G22T | Level 2 residual ground instantaneous overcurrent element trip—Winding 2 | 2 |
| 50GREF1 | Normalized residual current sensitivity threshold exceeded | 3 |
| 50N11P | Level 1 neutral ground instantaneous overcurrent element pickup—Input 1 | 12 |
| 50N11T | Level 1 neutral ground instantaneous overcurrent element trip—Input 1 | 3 |
| 50N12P | Level 2 neutral ground instantaneous overcurrent element pickup—Input 1 | 12 |
| 50N12T | Level 2 neutral ground instantaneous overcurrent element trip—Input 1 | 3 |
| 50NREF1 | Neutral current sensitivity threshold exceeded | 3 |
| 50P11P | Level 1 maximum phase instantaneous overcurrent element pickup—Winding 1 | 10 |
| 50P11T | Level 1 maximum phase instantaneous overcurrent element trip—Winding 1 | 1 |
| 50P11AP | Level 1 A-phase instantaneous overcurrent element pickup—Winding 1 | 91 |
| 50P11AT | Level 1 A-phase instantaneous overcurrent element trip—Winding 1 | 91 |
| 50P11BP | Level 1 B-phase instantaneous overcurrent element pickup—Winding 1 | 92 |
| 50P11BT | Level 1 B-phase instantaneous overcurrent element trip—Winding 1 | 92 |
| 50P11CP | Level 1 C-phase instantaneous overcurrent element pickup—Winding 1 | 93 |
| 50P11CT | Level 1 C-phase instantaneous overcurrent element trip—Winding 1 | 93 |
| 50P12P | Level 2 maximum phase instantaneous overcurrent element pickup—Winding 1 | 10 |
| 50P12T | Level 2 maximum phase instantaneous overcurrent element trip—Winding 1 | 1 |
| 50P13P | Level 3 maximum phase instantaneous overcurrent element pickup—Winding 1 | 10 |
| 50P13T | Level 3 maximum phase instantaneous overcurrent element trip—Winding 1 | 1 |
| 50P14P | Level 4 maximum phase instantaneous overcurrent element pickup—Winding 1 | 10 |
| 50P14T | Level 4 maximum phase instantaneous overcurrent element trip—Winding 1 | 1 |
| 50P21P | Level 1 maximum phase instantaneous overcurrent element pickup—Winding 2 | 10 |
| 50P21T | Level 1 maximum phase instantaneous overcurrent element trip—Winding 2 | 1 |
| 50P21AP | Level 1 A-phase instantaneous overcurrent element pickup—Winding 2 | 94 |
| 50P21AT | Level 1 A-phase instantaneous overcurrent element trip—Winding 2 | 94 |
| 50P21BP | Level 1 B-phase instantaneous overcurrent element pickup—Winding 2 | 95 |
| 50P21BT | Level 1 B-phase instantaneous overcurrent element trip—Winding 2 | 95 |
| 50P21CP | Level 1 C-phase instantaneous overcurrent element pickup—Winding 2 | 96 |
| 50P21CT | Level 1 C-phase instantaneous overcurrent element trip—Winding 2 | 96 |
| 50P22P | Level 2 maximum phase instantaneous overcurrent element pickup—Winding 2 | 10 |

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 3 of 10)

| Bit | Definition | Row |
|--------|--|-----|
| 50P22T | Level 2 maximum phase instantaneous overcurrent element trip—Winding 2 | 1 |
| 50P23P | Level 3 maximum phase instantaneous overcurrent element pickup—Winding 2 | 10 |
| 50P23T | Level 3 maximum phase instantaneous overcurrent element trip—Winding 2 | 1 |
| 50P24P | Level 4 maximum phase instantaneous overcurrent element pickup—Winding 2 | 10 |
| 50P24T | Level 4 maximum phase instantaneous overcurrent element trip—Winding 2 | 1 |
| 50Q11P | Level 1 negative-sequence instantaneous overcurrent element pickup—Winding 1 | 11 |
| 50Q11T | Level 1 negative-sequence instantaneous overcurrent element trip—Winding 1 | 2 |
| 50Q12P | Level 2 negative-sequence instantaneous overcurrent element pickup—Winding 1 | 11 |
| 50Q12T | Level 2 negative-sequence instantaneous overcurrent element trip—Winding 1 | 2 |
| 50Q21P | Level 1 negative-sequence instantaneous overcurrent element pickup—Winding 2 | 11 |
| 50Q21T | Level 1 negative-sequence instantaneous overcurrent element trip—Winding 2 | 2 |
| 50Q22P | Level 2 negative-sequence instantaneous overcurrent element pickup—Winding 2 | 11 |
| 50Q22T | Level 2 negative-sequence instantaneous overcurrent element trip—Winding 2 | 2 |
| 51G1P | Residual ground time-overcurrent element pickup—Winding 1 | 13 |
| 51G1R | Residual ground time-overcurrent element reset—Winding 1 | 14 |
| 51G1T | Residual ground time-overcurrent element trip—Winding 1 | 4 |
| 51G2P | Residual ground time-overcurrent element pickup—Winding 2 | 13 |
| 51G2R | Residual ground time-overcurrent element reset—Winding 2 | 14 |
| 51G2T | Residual ground time-overcurrent element trip—Winding 2 | 4 |
| 51N1P | Neutral ground time-overcurrent element pickup—Input 1 | 13 |
| 51N1R | Neutral ground time-overcurrent element reset | 14 |
| 51N1T | Neutral ground time-overcurrent element trip—Input 1 | 4 |
| 51P1P | Maximum phase time-overcurrent element pickup—Winding 1 | 13 |
| 51P1R | Maximum phase time-overcurrent element reset—Winding 1 | 14 |
| 51P1T | Maximum phase time-overcurrent element trip—Winding 1 | 4 |
| 51P1AP | A-phase time-overcurrent element pickup—Winding 1 | 97 |
| 51P1AR | A-phase time-overcurrent element reset—Winding 1 | 12 |
| 51P1AT | A-phase time-overcurrent element trip—Winding 1 | 97 |
| 51P1BP | B-phase time-overcurrent element pickup—Winding 1 | 98 |
| 51P1BR | B-phase time-overcurrent element reset—Winding 1 | 12 |
| 51P1BT | B-phase time-overcurrent element trip—Winding 1 | 98 |
| 51P1CP | C-phase time-overcurrent element pickup—Winding 1 | 99 |
| 51P1CR | C-phase time-overcurrent element reset—Winding 1 | 12 |
| 51P1CT | C-phase time-overcurrent element trip—Winding 1 | 99 |
| 51P2P | Maximum phase time-overcurrent element pickup—Winding 2 | 13 |
| 51P2R | Maximum phase time-overcurrent element reset—Winding 2 | 14 |
| 51P2T | Maximum phase time-overcurrent element trip—Winding 2 | 4 |
| 51P2AP | A-phase time-overcurrent element pickup—Winding 2 | 100 |

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 4 of 10)

| Bit | Definition | Row |
|--------|---|-----|
| 51P2AR | A-phase time-overcurrent element reset—Winding 2 | 12 |
| 51P2AT | A-phase time-overcurrent element trip—Winding 2 | 100 |
| 51P2BP | B-phase time-overcurrent element pickup—Winding 2 | 101 |
| 51P2BR | B-phase time-overcurrent element reset—Winding 2 | 13 |
| 51P2BT | C-phase time-overcurrent element trip—Winding 2 | 101 |
| 51P2CP | C-phase time-overcurrent element pickup—Winding 2 | 102 |
| 51P2CR | C-phase time-overcurrent element reset—Winding 2 | 14 |
| 51P2CT | C-phase time-overcurrent element trip—Winding 2 | 102 |
| 51Q1P | Negative-sequence time-overcurrent element pickup—Winding 1 | 13 |
| 51Q1R | Negative-sequence time-overcurrent element reset—Winding 1 | 14 |
| 51Q1T | Negative-sequence time-overcurrent element trip—Winding 1 | 4 |
| 51Q2P | Negative-sequence time-overcurrent element pickup—Winding 2 | 13 |
| 51Q2R | Negative-sequence time-overcurrent element reset—Winding 2 | 14 |
| 51Q2T | Negative-sequence time-overcurrent element trip—Winding 2 | 4 |
| 52A1 | Circuit breaker 1, contact A | 12 |
| 52A2 | Circuit breaker 2, contact A | 12 |
| 59P1 | Level 1 phase overvoltage element pickup | 17 |
| 59P1T | Level 1 phase overvoltage element trip | 6 |
| 59P2 | Level 2 phase overvoltage element pickup | 17 |
| 59P2T | Level 2 phase overvoltage element trip | 6 |
| 59Q1 | Level 1 negative-sequence overvoltage element pickup | 18 |
| 59Q1T | Level 1 negative-sequence overvoltage element trip | 7 |
| 59Q2 | Level 2 negative-sequence overvoltage element pickup | 18 |
| 59Q2T | Level 2 negative-sequence overvoltage element trip | 7 |
| 5HB1 | Fifth Harmonic block asserted for differential element 1 | 15 |
| 5HB2 | Fifth Harmonic block asserted for differential element 2 | 15 |
| 5HB3 | Fifth Harmonic block asserted for differential element 3 | 15 |
| 5HBL | Fifth Harmonic block asserted (5HB1 OR 5HB2 OR 5HB3) | 15 |
| 81D1T | Level 1 definite-time over/under frequency trip | 7 |
| 81D2T | Level 2 definite-time over/under frequency trip | 7 |
| 81D3T | Level 3 definite-time over/under frequency trip | 7 |
| 81D4T | Level 4 definite-time over/under frequency trip | 7 |
| 87AP | Differential Current Alarm element pickup | 17 |
| 87AT | Differential Current Alarm element trip | 6 |
| 87BL1 | Harmonic block asserted for differential element 1 | 16 |
| 87BL2 | Harmonic block asserted for differential element 2 | 16 |
| 87BL3 | Harmonic block asserted for differential element 3 | 16 |
| 87HB | Harmonic block differential element asserted | 16 |

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 5 of 10)

| Bit | Definition | Row |
|----------|--|--------|
| 87HR | Harmonic restrained element (HR1 OR HR2 OR HR3) ^b | 16 |
| 87HR1 | Harmonic restrained element 1 | 16 |
| 87HR2 | Harmonic restrained element 2 | 16 |
| 87HR3 | Harmonic restrained element 3 | 16 |
| 87R | Restrained differential element Trip (87HR OR 87HB) | 5 |
| 87R1 | Restrained differential element 1 (not considering harmonic blocks) | 5 |
| 87R2 | Restrained differential element 2 (not considering harmonic blocks) | 5 |
| 87R3 | Restrained differential element 3 (not considering harmonic blocks) | 5 |
| 87U | Unrestrained differential element Trip (87U1 OR 87U2 OR 87U3) | 5 |
| 87U1 | Unrestrained differential element 1 Trip | 5 |
| 87U2 | Unrestrained differential element 2 Trip | 5 |
| 87U3 | Unrestrained differential element 3 Trip | 5 |
| AIHAL | Analog inputs High Alarm Limit. If any AInnnHAL = 1, then AIHAL = 1 | 91 |
| AIHW1 | Analog inputs High Warning, Level 1. If any AinnnHW1 = 1, then AIHW1 = 1 | 91 |
| AIHW2 | Analog inputs High Warning, Level 2. If any AinnnHW2 = 1, then AIHW2 = 1 | 91 |
| AILAL | Analog inputs Low Alarm Limit. If any AInnnLAL = 1, then AILAL = 1 | 91 |
| AILW1 | Analog inputs Low Warning, Level 1. If any AinnnLW1 = 1, then AILW1 = 1 | 91 |
| AILW2 | Analog inputs Low Warning, Level 2. If any AinnnLW2 = 1, then AILW2 = 1 | 91 |
| AInnnHAL | Analog inputs 301–504 Warnings/Alarms (where nnn = 301–504) High Alarm Limit | 92-103 |
| AInnnHW1 | Analog inputs 301–504 Warnings/Alarms (where nnn = 301–504) High Warning, Level 1 | 92-103 |
| AInnnHW2 | Analog inputs 301–504 Warnings/Alarms (where nnn = 301–504) High Warning, Level 2 | 92-103 |
| AInnnLAL | Analog inputs 301–504 Warnings/Alarms (where nnn = 301–504) Low Alarm Limit | 92-103 |
| AInnnLW1 | Analog inputs 301–504 Warnings/Alarms (where nnn = 301–504) Low Warning, Level 1 | 92-103 |
| AInnnLW2 | Analog inputs 301–504 Warnings/Alarms (where nnn = 301–504) Low Warning, Level 2 | 92-103 |
| AMBALRM | Ambient Temperature Alarm. AMBALRM asserts if the healthy ambient RTD temperature exceeds its alarm set point. | 18 |
| AMBTRIP | Ambient Temperature Trip. AMBTRIP asserts when the healthy Ambient RTD temperature exceeds its trip set point. | 18 |
| BFI1 | Breaker 1 Failure Initiation. Asserts when the SELOGIC control equation BFI1 results in a logical 1. Use to indicate that the Breaker 2 Failure logic has started. | 18 |
| BFI2 | Breaker 2 Failure Initiation. Asserts when the SELOGIC control equation BFI2 results in a logical 1. Use to indicate that the Breaker 1 Failure logic has started. | 18 |
| BFT1 | Breaker 1 Failure Trip. Asserts when the relay issues a Breaker 1 Failure trip. | 7 |
| BFT2 | Breaker 2 Failure Trip. Asserts when the relay issues a Breaker 2 Failure trip. | 7 |
| CBADA | Channel A, channel unavailability over threshold | 74 |
| CBADB | Channel B, channel unavailability over threshold | 74 |
| CC1 | Close command. Asserts when serial port command CC1 (CLOSE Breaker1) or front-panel or Modbus/ DeviceNet CLOSE command is issued to Close Breaker1. | 32 |
| CC2 | Close command. Asserts when serial port command CC2 (CLOSE Breaker2) or front-panel or Modbus/ DeviceNet CLOSE command is issued to Close Breaker2. | 32 |
| CF1 | Breaker 1 Close condition failure on | 32 |

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 6 of 10)

| Bit | Definition | Row |
|--------------------|--|-----|
| CF2 | Breaker 2 Close condition failure on | 32 |
| CFGFLT | Asserts on failed settings interdependency check during Modbus setting change | 26 |
| CL1 | Close SELOGIC control equation CL1 | 35 |
| CL2 | Close SELOGIC control equation CL2 | 35 |
| CLOSE1 | Close logic output for Breaker1 | 32 |
| CLOSE2 | Close logic output for Breaker2 | 32 |
| COMMFLT | Time-out of internal communication between CPU board and DeviceNet board | 26 |
| COMMIDLE | DeviceNet card in programming mode | 26 |
| COMMLOSS | DeviceNet communication failure | 26 |
| DI _{xn} | Distortion index, where x = phase A, B, or C and n = winding 1 or 2 | 104 |
| DNAUX _n | DeviceNet/ModBus AUX _n assert bit, where n = 1 through 8 | 36 |
| DNAUX _n | DeviceNet/ModBus AUX _n assert bit, where n = 9 through 11 | 37 |
| DSABLSET | SELOGIC control equation: Do not allow settings changes from front-panel interface when asserted | 28 |
| DST | Daylight-Saving Time | 105 |
| DSTP | Daylight-Saving Time Pending | 105 |
| ER | Event report trigger SELOGIC control equation | 27 |
| FAULT | Indicates fault condition. Asserts when SELOGIC control equation FAULT result in a logical 1. | 25 |
| FREQTRK | Frequency tracking enable bit-tracking enabled when bit is asserted | 27 |
| GNDEM | Zero sequence current demand pickup | 41 |
| HALARM | Diagnostics failure | 28 |
| IN301–IN304 | Contact inputs IN301–IN304 (available only with optional I/O module) | 22 |
| IN305–IN308 | Contact inputs IN305–IN308 (available only with optional I/O module) | 22 |
| IN401–IN404 | Contact inputs IN401–IN404 (available only with optional I/O module) | 23 |
| IN405–IN408 | Contact inputs IN405–IN408 (available only with optional I/O module) | 23 |
| IN501–IN504 | Contact inputs IN501–IN504 (available only with optional I/O module) | 24 |
| IN505–IN508 | Contact inputs IN505–IN508 (available only with optional I/O module) | 24 |
| IN _{nnn} | Contact inputs IN101 and IN102 | 21 |
| INR1 | 87-1 Differential element in high security mode (see <i>Figure 4.4</i>) | 37 |
| INR2 | 87-2 Differential element in high security mode (see <i>Figure 4.4</i>) | 37 |
| INR3 | 87-3 Differential element in high security mode (see <i>Figure 4.4</i>) | 37 |
| IRIGOK | IRIG-B time synch input data are valid | 25 |
| LB01–LB08 | Local Bits 01 through 08 | 42 |
| LB09–LB16 | Local Bits 09 through 16 | 43 |
| LB17–LB24 | Local Bits 17 through 24 | 44 |
| LB25–LB32 | Local Bits 25 through 32 | 45 |
| LBOKA | Channel A, looped back ok | 74 |
| LBOKB | Channel B, looped back ok Channel B, channel unavailability over threshold | 74 |
| LINKA | Assert if Ethernet Port A detects link | 25 |

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 7 of 10)

| Bit | Definition | Row |
|---------------|---|-----|
| LINKB | Assert if Ethernet Port B detects link | 25 |
| LINKFAIL | Failure of active Ethernet port link | 26 |
| LOP | Loss-of-Potential | 26 |
| LPSEC | Direction of the upcoming leap second. During the time that LPSECP is asserted, if LPSEC is asserted, the upcoming leap second is deleted; otherwise, the leap second is added. | 105 |
| LPSECP | Leap second pending | 105 |
| LT01–LT08 | Latch bits 1through 8 | 58 |
| LT09–LT16 | Latch bits 09 through 16 | 59 |
| LT17–LT24 | Latch bits 17 through 24 | 60 |
| LT25–LT32 | Latch bits 25 through 32 | 61 |
| MATHERR | SELOGIC math error bit asserted for divide-by-zero, etc., in SELOGIC math functions | 104 |
| OC1 | Open command. Asserts when serial port command Open Breaker1 or Front Panel or Modbus/DeviceNet Open Breaker1 command is issued. | 34 |
| OC2 | Open command. Asserts when serial port command Open Breaker2 or Front Panel or Modbus/DeviceNet Open Breaker2 command is issued. | 34 |
| ORED50T | Logical OR of all the instantaneous overcurrent elements Tripped outputs | 9 |
| ORED51T | Logical OR of all the time overcurrent elements Tripped outputs | 9 |
| OTHALRM | Other Temperature Alarm. OTHALRM asserts when any healthy other RTD temperature exceeds its alarm set point. | 18 |
| OTHTRIP | Other RTD temperatures exceed their trip set points | 18 |
| OUT101–OUT103 | SELOGIC control equation for contact outputs OUT101 through OUT103 | 19 |
| OUT301–OUT304 | SELOGIC control equation for contact outputs OUT301 through OUT304 (available only with optional I/O module) | 19 |
| OUT401–OUT404 | SELOGIC control equation for contact outputs OUT401 through OUT404 (available only with optional I/O module) | 20 |
| OUT501–OUT504 | Control equation for contact outputs OUT501 through OUT504 (available only with optional I/O module) | 20 |
| PASEL | Ethernet Port A is selected for communications | 26 |
| PB01 | Front-panel pushbutton 1 bit (asserted when PB01 is pressed) | 38 |
| PB01_PUL | Front-panel pushbutton 1 pulse bit (asserted for one processing interval when PB01 is pressed) | 38 |
| PB02 | Front-panel pushbutton 2 bit (asserted when PB02 is pressed) | 38 |
| PB02_PUL | Front-panel pushbutton 2 pulse bit (asserted for one processing interval when PB02 is pressed) | 38 |
| PB03 | Front-panel pushbutton 3 bit (asserted when PB03 is pressed) | 38 |
| PB03_PUL | Front-panel pushbutton 3 pulse bit (asserted for one processing interval when PB03 is pressed) | 38 |
| PB04 | Front-panel pushbutton 4 bit (asserted when PB04 is pressed) | 38 |
| PB04_PUL | Front-panel pushbutton 4 pulse bit (asserted for one processing interval when PB04 is pressed) | 38 |
| PB1A_LED | SELOGIC control equation: drives LED PB1A | 39 |
| PB1B_LED | SELOGIC control equation: drives LED PB1B | 39 |
| PB2A_LED | SELOGIC control equation: drives LED PB2A | 39 |
| PB2B_LED | SELOGIC control equation: drives LED PB2B | 39 |
| PB3A_LED | SELOGIC control equation: drives LED PB3A | 39 |

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 8 of 10)

| Bit | Definition | Row |
|-----------|--|-----|
| PB3B_LED | SELOGIC control equation: drives LED PB3B | 39 |
| PB4A_LED | SELOGIC control equation: drives LED PB4A | 39 |
| PB4B_LED | SELOGIC control equation: drives LED PB4B | 39 |
| PBSEL | Ethernet Port B is selected for communications | 26 |
| PHDEM | Phase current demand pickup | 41 |
| PMDOK | Assert if data acquisition system is operating correctly | 25 |
| PMTRIG | Trigger for synchrophasors | 35 |
| RB01–RB08 | Remote Bits 01 through 08 | 46 |
| RB09–RB16 | Remote Bits 09 through 16 | 47 |
| RB17–RB24 | Remote Bits 17 through 24 | 48 |
| RB25–RB32 | Remote Bits 25 through 32 | 49 |
| RBADA | Channel A, outage duration over threshold | 74 |
| RBADB | Channel B, outage duration over threshold | 74 |
| REF1E | Internal enable for the REF element | 3 |
| REF1F | REF element forward (internal) fault declaration | 3 |
| REF1P | Restricted earth fault inverse-time O/C element timed-out | 3 |
| REF1R | REF element reverse (external) fault declaration | 3 |
| RELAY_EN | Relay Data Quality Flag | 37 |
| REMTRIP | Remote Trip | 9 |
| RMBnA | Channel A receive mirror bits RMB1A through RMB8A | 70 |
| RMBnB | Channel B receive mirror bits RMB1B through RMB8B | 72 |
| ROKA | Channel A, received data ok | 74 |
| ROKB | Channel B, received data ok | 74 |
| RSTDEM | Reset demand meter. | 27 |
| RSTENRGY | Reset Energy metering. Assert when the SELOGIC control equation RSTENRG result is logical 1. | 27 |
| RSTMXMN | Reset Max Min metering. Assert when the SELOGIC control equation RSTMXMN result is logical 1. | 27 |
| RSTPKDEM | Reset peak demand meter | 27 |
| RSTTRGT | SELOGIC control equation: reset trip logic and targets when asserted | 28 |
| RTDA | Asserts when any RTD alarm (RTD_A) is asserted. | 28 |
| RTDFLT | Asserts when an open or short circuit condition is detected on any enabled RTD input, or communication with the external RTD module has been interrupted | 28 |
| RTDIN | Indicates status of contact connected to SEL-2600A RTD module | 28 |
| RTDnA | RTD1A through RTD4A (Alarms) | 29 |
| RTDnA | RTD5A through RTD8A (Alarms) | 30 |
| RTDnA | RTD9A through RTD12A (Alarms) | 31 |
| RTDnT | RTD1T through RTD4T (Trips) | 29 |
| RTDnT | RTD5T through RTD8T (Trips) | 30 |
| RTDnT | RTD9T through RTD12T (Trips) | 31 |

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 9 of 10)

| Bit | Definition | Row |
|-----------------|--|-----|
| RTDT | Asserts when any RTD trip (RTD_T) is asserted | 8 |
| SALARM | Software Alarms: invalid password, changing access levels, settings changes, active group changes, copy commands, and password changes | 25 |
| SCnnQD | SELOGIC Counters 01 through 08 asserted when counter = 0 | 63 |
| SCnnQD | SELOGIC Counters 09 through 16 asserted when counter = 0 | 65 |
| SCnnQD | SELOGIC Counters 17 through 24 asserted when counter = 0 | 67 |
| SCnnQD | SELOGIC Counters 25 through 32 asserted when counter = 0 | 69 |
| SCnnQU | SELOGIC Counters 01 through 08 asserted when counter = preset value | 62 |
| SCnnQU | SELOGIC Counters 09 through 16 asserted when counter = preset value | 64 |
| SCnnQU | SELOGIC Counters 17 through 24 asserted when counter = preset value | 66 |
| SCnnQU | SELOGIC Counters 25 through 32 asserted when counter = preset value | 68 |
| SG1 | Asserts when setting group 1 is active | 33 |
| SG2 | Asserts when setting group 2 is active | 33 |
| SG3 | Asserts when setting group 3 is active | 33 |
| SG4 | Asserts when setting group 4 is active | 33 |
| SV01–SV08 | SELOGIC control equation variables SV01 through SV08 | 50 |
| SV01T–SV08T | SELOGIC control equation variable SV01T through SV08T with settable pickup and dropout time delay | 51 |
| SV09–SV16 | SELOGIC control equation variables SV09 through SV16 | 52 |
| SV09T–SV16T | SELOGIC control equation variable SV09T through SV16T with settable pickup and dropout time delay | 53 |
| SV17–SV24 | SELOGIC control equation variables SV17 through SV24 | 54 |
| SV17T–SV24T | SELOGIC control equation variable SV17T through SV24T with settable pickup and dropout time delay | 55 |
| SV25–SV32 | SELOGIC control equation variables SV25 through SV32 | 56 |
| SV25T–SV32T | SELOGIC control equation variable SV25T through SV32T with settable pickup and dropout time delay | 57 |
| T01_LED–T06_LED | SELOGIC control equation: drives T01_LED through T06_LED | 40 |
| TFLTALA | Through fault alarm, phase A | 41 |
| TFLTALB | Through fault alarm, phase B | 41 |
| TFLTALC | Through fault alarm, phase C | 41 |
| TH5 | Fifth Harmonic alarm threshold exceeded | 17 |
| TH5T | Fifth Harmonic alarm threshold exceeded for longer than TH5D | 6 |
| TMBnA | Channel A transmit mirror bits TMB1A through TMB8A | 71 |
| TMBnB | Channel B transmit mirror bits TMB1B through TMB8B | 73 |
| TQUAL1 | Time Quality Bit, add 1 when asserted | 105 |
| TQUAL2 | Time Quality Bit, add 2 when asserted | 105 |
| TQUAL4 | Time Quality Bit, add 4 when asserted | 105 |
| TQUAL8 | Time Quality Bit, add 8 when asserted | 105 |
| TR1 | Trip SELOGIC control equation TR1 (Also has been referred to as TRIPEQ1) | 34 |

Table J.2 Relay Word Bit Definitions for the SEL-787 (Sheet 10 of 10)

| Bit | Definition | Row |
|----------|---|-------|
| TR2 | Trip SELOGIC control equation TR2 (Also has been referred to as TRIPEQ2) | 34 |
| TREA1 | Trigger Reason Bit 1 for synchrophasors | 33 |
| TREA2 | Trigger Reason Bit 2 for synchrophasors | 33 |
| TREA3 | Trigger Reason Bit 3 for synchrophasors | 33 |
| TREA4 | Trigger Reason Bit 4 for synchrophasors | 33 |
| TRGTR | Target Reset. Asserts for one quarter-cycle when you execute a front-panel, serial port target reset command, or Modbus target reset. | 28 |
| TRIP | Trip Logic Output | 19 |
| TRIP1 | Trip1 Logic Output | 34 |
| TRIP2 | Trip2 Logic Output | 34 |
| TRIPXFMR | TripXFMR Logic Output | 34 |
| TRXFMR | Trip SELOGIC control equation TRXFMR (Also has been referred to as TRXFMREQ) | 34 |
| TSNTPB | SNTP Secondary Server is active | 106 |
| TSNTPP | SNTP Primary Server is active | 106 |
| TSOK | Assert if current time source accuracy is sufficient for synchronized phasor measurements | 25 |
| TUTC1 | Offset hours from UTC time, binary, add 1 if asserted | 106 |
| TUTC2 | Offset hours from UTC time, binary, add 2 if asserted | 106 |
| TUTC4 | Offset hours from UTC time, binary, add 4 if asserted | 106 |
| TUTC8 | Offset hours from UTC time, binary, add 8 if asserted | 106 |
| TUTCH | Offset half-hour from UTC time, binary, add 0.5 if asserted | 106 |
| TUTCS | Offset hours sign from UTC time, subtract the UTC offset if TUTCS is asserted; otherwise, add | 106 |
| ULCL1 | Unlatch close conditions SELOGIC control equation CL1 state | 35 |
| ULCL2 | Unlatch close conditions SELOGIC control equation CL2 state | 35 |
| ULTRIP1 | Unlatch (auto reset) trip from SELOGIC control equation TR1 | 35 |
| ULTRIP2 | Unlatch (auto reset) trip from SELOGIC control equation TR2 | 35 |
| ULTRXFMR | Unlatch (auto reset) trip from SELOGIC control equation TRXFMR | 35 |
| VB nnn | Virtual Bits used for Incoming GOOSE messages ($nnn = 1$ through 128) | 75-90 |
| WARNING | Relay Word WARNING | 25 |

^a Reserved.

^b Harmonic restraint enabled.

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Appendix K

Analog Quantities

The SEL-787 Transformer Protection Relay contains several analog quantities that can be used for more than one function.

The actual analog quantities available depend on the part number of the relay used. Analog quantities are typically generated and used by a primary function, such as, metering and selected quantities are made available for one or more supplemental functions, for example, the load profile.

Note that all analog quantities available for use in SELOGIC® are processed every 100 ms and may not be suitable for fast-response control and protection applications.

Table K.1 lists analog quantities that can be used in the following specific functions:

- SELOGIC control equations (see *Section 4: Protection and Logic Functions*)
- Display points (see *Section 8: Front-Panel Operations*)
- Load profile recorder (see *Section 5: Metering and Monitoring*)
- DNP (see *Appendix D: DNP3 Communications*)
- Fast Meter (see *Appendix C: SEL Communications Processors*)

For a list of analog quantities available for Modbus® communications, see *Appendix E: Modbus RTU Communications*.

Table K.1 Analog Quantities (Sheet 1 of 6)

| Label | Description | Units | Display Points | SELOGIC | Load Profile | DNP | Fast Meter |
|------------------------------------|---|-----------|----------------|---------|--------------|-----|------------|
| Fundamental Instantaneous Metering | | | | | | | |
| IAW1_MAG | Winding 1 current, A-phase, magnitude | A primary | x | x | x | x | x |
| IAW1_ANG | Winding 1 current, A-phase, angle | degrees | x | x | x | x | |
| IBW1_MAG | Winding 1 current, B-phase, magnitude | A primary | x | x | x | x | x |
| IBW1_ANG | Winding 1 current, B-phase, angle | degrees | x | x | x | x | |
| ICW1_MAG | Winding 1 current, C-phase, magnitude | A primary | x | x | x | x | x |
| ICW1_ANG | Winding 1 current, C-phase, angle | degrees | x | x | x | x | |
| IAVW1MAG | Winding 1 average current, magnitude | A primary | x | x | x | x | |
| IGW1_MAG | Winding 1 current, calculated-residual, magnitude | A primary | x | x | x | x | |
| IGW1_ANG | Winding 1 current, calculated-residual, angle | degrees | x | x | x | x | |
| 3I2W1MAG | Winding 1 current, negative-sequence, magnitude | A primary | x | x | x | x | |
| IAW2_MAG | Winding 2 current, A-phase, magnitude | A primary | x | x | x | x | x |
| IAW2_ANG | Winding 2 current, A-phase, angle | degrees | x | x | x | x | |

Table K.1 Analog Quantities (Sheet 2 of 6)

| Label | Description | Units | Display Points | SELogic | Load Profile | DNP | Fast Meter |
|------------------|---|--------------|----------------|---------|--------------|-----|------------|
| IBW2_MAG | Winding 2 current, B-phase, magnitude | A primary | x | x | x | x | x |
| IBW2_ANG | Winding 2 current, B-phase, angle | degrees | x | x | x | x | |
| ICW2_MAG | Winding 2 current, C-phase, magnitude | A primary | x | x | x | x | x |
| ICW2_ANG | Winding 2 current, C-phase, angle | degrees | x | x | x | x | |
| IAVW2MAG | Winding 2 average current, magnitude | A primary | x | x | x | x | |
| IGW2_MAG | Winding 2 current, calculated-residual, magnitude | A primary | x | x | x | x | |
| IGW2_ANG | Winding 2 current, calculated-residual, angle | degrees | x | x | x | x | |
| 3I2W2MAG | Winding 2 current, negative-sequence, magnitude | A primary | x | x | x | x | |
| IN_MAG | Current, neutral, magnitude | A primary | x | x | x | x | x |
| IN_ANG | Current, neutral, angle | degrees | x | x | x | x | |
| VA_MAG | Voltage, A-phase-to-neutral, magnitude | V primary | x | x | x | x | x |
| VA_ANG | Voltage, A-phase-to-neutral, angle | degrees | x | x | x | x | |
| VB_MAG | Voltage, B-phase-to-neutral, magnitude | V primary | x | x | x | x | x |
| VB_ANG | Voltage, B-phase-to-neutral, angle | degrees | x | x | x | x | |
| VC_MAG | Voltage, C-phase-to-neutral, magnitude | V primary | x | x | x | x | x |
| VC_ANG | Voltage, C-phase-to-neutral, angle | degrees | x | x | x | x | |
| VAB_MAG | Voltage, A-to-B-phase, magnitude | V primary | x | x | x | x | x |
| VAB_ANG | Voltage, A-to-B-phase, angle | degrees | x | x | x | x | |
| VBC_MAG | Voltage, B-to-C-phase, magnitude | V primary | x | x | x | x | x |
| VBC_ANG | Voltage, B-to-C-phase, angle | degrees | x | x | x | x | |
| VCA_MAG | Voltage, C-to-A-phase, magnitude | V primary | x | x | x | x | x |
| VCA_ANG | Voltage, C-to-A-phase, angle | degrees | x | x | x | x | |
| VG_MAG | Zero Sequence Voltage, magnitude | V primary | x | x | x | x | x |
| VG_ANG | Zero Sequence Voltage, angle | degrees | x | x | x | x | |
| VAVE_MAG | Average voltage, magnitude | V primary | x | x | x | x | |
| 3V2_MAG | Voltage, negative-sequence, magnitude | V primary | x | x | x | x | |
| P | Real power magnitude, 3-phase | kW primary | x | x | x | x | |
| | | W primary | | | | | x |
| Q | Reactive power magnitude, 3-phase | kVAR primary | x | x | x | x | |
| | | VAR primary | | | | | x |
| S | Apparent power magnitude, 3-phase | kVA primary | x | x | x | x | |
| | | VA primary | | | | | x |
| PF | Power factor, magnitude 3-phase | unitless | x | x | x | x | x |
| FREQ | Frequency | Hz | x | x | x | x | x |
| VHZ | V/Hz | % | x | x | x | x | x |
| Thermal Metering | | | | | | | |
| RTDAMB | Ambient RTD Temperature | °C | x | x | x | x | |
| RTDOTHMX | Other Maximum RTD Temperature | °C | x | x | x | x | |
| RTD1 to RTD12 | RTD1 to RTD12 Temperature ^a | °C | x | x | x | x | |

Table K.1 Analog Quantities (Sheet 3 of 6)

| Label | Description | Units | Display Points | SELogic | Load Profile | DNP | Fast Meter |
|---------------------------------|---|---------------|----------------|---------|--------------|-----|------------|
| Analog Input Metering | | | | | | | |
| AI301 to AI304 | Analog Inputs for an analog input card in Slot C ^b | EU | x | x | x | x | |
| AI401 to AI404 | Analog Inputs for an analog input card in Slot D ^b | EU | x | x | x | x | |
| AI501 to AI504 | Analog Inputs for an analog input card in Slot E ^b | EU | x | x | x | x | |
| Energy Metering | | | | | | | |
| EM_LRDH | Energy Last Reset Date/Time High Word | | | | | x | |
| EM_LRDM | Energy Last Reset Date/Time Middle Word | | | | | x | |
| EM_LRDL | Energy Last Reset Date/Time Low Word | | | | | x | |
| MWHP | Real energy, 3-phase Positive | MWh primary | x | x | | x | |
| MWHN | Real energy, 3-phase Negative | MWh primary | x | x | | x | |
| MVARHP | Reactive energy, 3-phase Positive | MVARh primary | x | x | | x | |
| MVARHN | Reactive energy, 3-phase Negative | MVARh primary | x | x | | x | |
| Maximum/minimum Metering | | | | | | | |
| MM_LRDH | Max/Min Last Reset Date/Time High Word | | | | | x | |
| MM_LRDM | Max/Min Last Reset Date/Time Middle Word | | | | | x | |
| MM_LRDL | Max/Min Last Reset Date/Time Low Word | | | | | x | |
| IAW1MX | Winding 1 Current, A-phase, maximum magnitude | A primary | x | x | | x | |
| IBW1MX | Winding 1 Current, B-phase, maximum magnitude | A primary | x | x | | x | |
| ICW1MX | Winding 1 Current, C-phase, maximum magnitude | A primary | x | x | | x | |
| IGW1MX | Winding 1 Current, residual, maximum magnitude | A primary | x | x | | x | |
| IAW2MX | Winding 2 Current, A-phase, maximum magnitude | A primary | x | x | | x | |
| IBW2MX | Winding 2 Current, B-phase, maximum magnitude | A primary | x | x | | x | |
| ICW2MX | Winding 2 Current, C-phase, maximum magnitude | A primary | x | x | | x | |
| IGW2MX | Winding 2 Current, residual, maximum magnitude | A primary | x | x | | x | |
| INMX | Current, neutral, maximum magnitude | A primary | x | x | | x | |
| IAW1MN | Winding 1 Current, A-phase, minimum magnitude | A primary | x | x | | x | |
| IBW1MN | Winding 1 Current, B-phase, minimum magnitude | A primary | x | x | | x | |
| ICW1MN | Winding 1 Current, C-phase, minimum magnitude | A primary | x | x | | x | |
| IGW1MN | Winding 1 Current, residual, minimum magnitude | A primary | x | x | | x | |
| IAW2MN | Winding 2 Current, A-phase, minimum magnitude | A primary | x | x | | x | |
| IBW2MN | Winding 2 Current, B-phase, minimum magnitude | A primary | x | x | | x | |
| ICW2MN | Winding 2 Current, C-phase, minimum magnitude | A primary | x | x | | x | |
| IGW2MN | Winding 2 Current, residual, minimum magnitude | A primary | x | x | | x | |
| INMN | Current, neutral, minimum magnitude | A primary | x | x | | x | |
| VABMX | Voltage, A-to-B-phase, maximum magnitude | V primary | x | x | | x | |
| VBCMX | Voltage, B-to-C-phase, maximum magnitude | V primary | x | x | | x | |

Table K.1 Analog Quantities (Sheet 4 of 6)

| Label | Description | Units | Display Points | SELogic | Load Profile | DNP | Fast Meter |
|--------------------|--|--------------|----------------|---------|--------------|-----|------------|
| VCAMX | Voltage, C-to-A-phase, maximum magnitude | V primary | x | x | | x | |
| VAMX | Voltage, A-phase-to-neutral, maximum magnitude | V primary | x | x | | x | |
| VBMX | Voltage, B-phase-to-neutral, maximum magnitude | V primary | x | x | | x | |
| VCMX | Voltage, C-phase-to-neutral, maximum magnitude | V primary | x | x | | x | |
| VABMN | Voltage, A-to-B-phase, minimum magnitude | V primary | x | x | | x | |
| VBCMN | Voltage, B-to-C-phase, minimum magnitude | V primary | x | x | | x | |
| VCAMN | Voltage, C-to-A-phase, minimum magnitude | V primary | x | x | | x | |
| VAMN | Voltage, A-phase-to-neutral, minimum magnitude | V primary | x | x | | x | |
| VBMN | Voltage, B-phase-to-neutral, minimum magnitude | V primary | x | x | | x | |
| VCMN | Voltage, C-phase-to-neutral, minimum magnitude | V primary | x | x | | x | |
| KVA3PMX | Apparent power magnitude, 3-phase, maximum | kVA primary | x | x | | x | |
| KW3PMX | Real power magnitude, 3-phase, maximum | kW primary | x | x | | x | |
| KVAR3PMX | Reactive power magnitude, 3-phase, maximum | kVAR primary | x | x | | x | |
| KVA3PMN | Apparent power magnitude, 3-phase, minimum | kVA primary | x | x | | x | |
| KW3PMN | Real power magnitude, 3-phase, minimum | kW primary | x | x | | x | |
| KVAR3PMN | Reactive power magnitude, 3-phase, minimum | kVAR primary | x | x | | x | |
| FREQMX | Maximum frequency | Hz | x | x | | x | |
| FREQMN | Minimum frequency | Hz | x | x | | x | |
| RTD1MX to RTD12MX | RTD1 maximum to RTD12 maximum | °C | x | x | | x | |
| RTD1MN to RTD12MN | RTD1 minimum to RTD12 minimum | °C | x | x | | x | |
| AI301MX to AI304MX | Analog transducer input 301–304 maximum ^b | EU | x | x | | x | |
| AI301MN to AI304MN | Analog transducer input 301–304 minimum ^b | EU | x | x | | x | |
| AI401MX to AI404MX | Analog transducer input 401–404 maximum ^b | EU | x | x | | x | |
| AI401MN to AI404MN | Analog transducer input 401–404 minimum ^b | EU | x | x | | x | |
| AI501MX to AI504MX | Analog transducer input 501–504 maximum ^b | EU | x | x | | x | |
| AI501MN to AI504MN | Analog transducer input 501–504 minimum ^b | EU | x | x | | x | |
| RMS Metering | | | | | | | |
| IAW1RMS | Winding 1 rms current, A-phase, magnitude | A primary | x | x | x | x | |
| IBW1RMS | Winding 1 rms current, B-phase, magnitude | A primary | x | x | x | x | |
| ICW1RMS | Winding 1 rms current, C-phase, magnitude | A primary | x | x | x | x | |
| IAW2RMS | Winding 2 rms current, A-phase, magnitude | A primary | x | x | x | x | |
| IBW2RMS | Winding 2 rms current, B-phase, magnitude | A primary | x | x | x | x | |
| ICW2RMS | Winding 2 rms current, C-phase, magnitude | A primary | x | x | x | x | |
| INRMS | Neutral rms current, magnitude | A primary | x | x | x | x | |

Table K.1 Analog Quantities (Sheet 5 of 6)

| Label | Description | Units | Display Points | SELogic | Load Profile | DNP | Fast Meter |
|-----------------------------|--|-----------|----------------|---------|--------------|-----|------------|
| VARMS | RMS Voltage, A-phase-to-neutral, magnitude | V primary | x | x | x | x | |
| VBRMS | RMS Voltage, B-phase-to-neutral, magnitude | V primary | x | x | x | x | |
| VCRMS | RMS Voltage, C-phase-to-neutral, magnitude | V primary | x | x | x | x | |
| VABRMS | RMS Voltage, A-to-B-phase, magnitude | V primary | x | x | x | x | |
| VBCRMS | RMS Voltage, B-to-C-phase, magnitude | V primary | x | x | x | x | |
| VCARMS | RMS Voltage, C-to-A-phase, magnitude | V primary | x | x | x | x | |
| Demand Metering | | | | | | | |
| IAD | Phase A Current Demand | A primary | x | x | | x | x |
| IBD | Phase B Current Demand | A primary | x | x | | x | x |
| ICD | Phase C Current Demand | A primary | x | x | | x | x |
| IGD | Residual Current Demand | A primary | x | x | | x | x |
| 3I2D | Negative-Sequence Current Demand | A primary | x | x | | x | x |
| Peak Demand Metering | | | | | | | |
| PM_LRDH | Peak Demand Last Reset Date/Time High Word | | | | | x | |
| PM_LRDM | Peak Demand Last Reset Date/Time Middle Word | | | | | x | |
| PM_LRDL | Peak Demand Last Reset Date/Time Low Word | | | | | x | |
| IAPD | Phase A Current Peak Demand | A primary | x | x | | x | x |
| IBPD | Phase B Current Peak Demand | A primary | x | x | | x | x |
| ICPD | Phase C Current Peak Demand | A primary | x | x | | x | x |
| IGPD | Residual Current Peak Demand | A primary | x | x | | x | x |
| 3I2PD | Negative-Sequence Current Peak Demand | A primary | x | x | | x | x |
| Harmonics Metering | | | | | | | |
| IAW1_THD | Winding 1 A-phase current THD | % | | | | x | |
| IBW1_THD | Winding 1 B-phase current THD | % | | | | x | |
| ICW1_THD | Winding 1 C-phase current THD | % | | | | x | |
| IAW2_THD | Winding 2 A-phase current THD | % | | | | x | |
| IBW2_THD | Winding 2 B-phase current THD | % | | | | x | |
| ICW2_THD | Winding 2 C-phase current THD | % | | | | x | |
| IN_THD | Neutral current THD | % | | | | x | |
| VA_THD | A-phase-to-neutral voltage THD | % | | | | x | |
| VB_THD | B-phase-to-neutral voltage THD | % | | | | x | |
| VC_THD | C-phase-to-neutral voltage THD | % | | | | x | |
| VAB_THD | A-to-B-phase voltage THD | % | | | | x | |
| VBC_THD | B-to-C-phase voltage THD | % | | | | x | |
| VCA_THD | C-to-A-phase voltage THD | % | | | | x | |
| Date/Time | | | | | | | |
| DATE | Present date ^c | | x | | | x | |
| TIME | Present time ^c | | x | | | x | |
| YEAR | Year number (0000-9999) | | | x | | | |
| DAYY | Day of Year number (1-366) | | | x | | | |

Table K.1 Analog Quantities (Sheet 6 of 6)

| Label | Description | Units | Display Points | SELogic | Load Profile | DNP | Fast Meter |
|-------------------------------|--|-------|----------------|---------|--------------|-----|------------|
| WEEK | Week number (1-52) | | | x | | | |
| DAYW | Day of Week number (1-7) | | | x | | | |
| MINSM | Minutes since Midnight | | | x | | | |
| RID/TID | | | | | | | |
| RID | Relay Identifier | | x | | | | |
| TID | Terminal Identifier | | x | | | | |
| Setting Group | | | | | | | |
| GROUP | Active Setting Group # | | x | x | | x | |
| Math Variables | | | | | | | |
| MV01 to MV32 | Math Variable 01 to Math Variable 32 | | x | x | x | x | |
| SELogic Counters ^d | | | | | | | |
| SC01 to SC32 | SELOGIC Counter 01 to SELOGIC Counter 32 | | x | x | x | x | |

^a RTD open is equivalent to +32767 and RTD short is equivalent to -32768 when RTDs are monitored via LDP.

^b See the Engineering Unit settings (e.g., AI301EU) of the respective analog input.

^c Also available via DNP object 50.

^d Also available as DNP counter object.

Glossary

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| A | Abbreviation for amps or amperes; units of electrical current magnitude. |
| ACSELERATOR QuickSet® SEL-5030 Software | A Windows®-based program that simplifies settings and provides analysis support. |
| ACSELERATOR Architect® SEL-5032 Software | Design and commissioning tool for IEC61850 communications. |
| Ambient Temperature | Temperature of the ambient air adjacent to the transformer. Measured by an RTD whose location setting is AMB. |
| Analog | In this instruction manual, Analog is synonymous with Transducer. |
| ANSI Standard Device Numbers | <p>A list of standard numbers used to represent electrical protection and control relays. The standard device numbers used in this instruction manual include:</p> <ul style="list-style-type: none">24 Volts/Hz Element (Overexcitation)27 Undervoltage Element32 Directional Power50 Instantaneous Overcurrent Element51 Inverse Time-Overcurrent Element52 AC Circuit Breaker55 Power Factor Element59 Overvoltage Element81 Frequency Element87 Differential Element <p>These numbers are frequently used within a suffix letter to further designate application. The suffix letters used in this instruction manual include:</p> <ul style="list-style-type: none">P Phase ElementG Residual/Ground ElementN Neutral/Ground ElementQ Negative-Sequence (3I2) Element |
| Apparent Power, S | Complex power expressed in units of volt-amps (VA), kilovolt-amps (kVA), or megavolt-amps (MVA). Accounts for both real (P) and reactive (Q) power dissipated in a circuit: $S = P + jQ$. |
| ASCII | Abbreviation for American Standard Code for Information Interchange. Defines a standard way to communicate text characters between two electronic devices. The SEL-787 Transformer Protection Relay uses ASCII text characters to communicate using the relay front- and rear-panel EIA-232 serial ports. |
| Assert | To activate; to fulfill the logic or electrical requirements needed to operate a device. To apply a short-circuit or closed contact to an SEL-787 input. To set a logic condition to the true state (logical 1). To close a normally-open output contact. To open a normally-closed output contact. |

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| Breaker Auxiliary Contact | A spare electrical contact associated with a circuit breaker that opens or closes to indicate the breaker position. A form-a breaker auxiliary contact (ANSI Standard Device Number 52A) closes when the breaker is closed, opens when the breaker is open. A form-b breaker auxiliary contact (ANSI Standard Device Number 52B) opens when the breaker is closed and closes when the breaker is open. |
| Checksum | A numeric identifier of the firmware in the relay. Calculated by the result of a mathematic sum of the relay code. |
| CID | Abbreviation for Checksum Identifier. The checksum of the specific firmware installed in the relay. |
| Contiguous | Items in sequence; the second immediately following the first. |
| CR_RAM | Abbreviation for Critical RAM. Refers to the area of relay Random Access Memory (RAM) where the relay stores mission-critical data. |
| CRC-16 | Abbreviation for Cyclical Redundancy Check-16. A mathematical algorithm applied to a block of digital information to produce a unique, identifying number. Used to ensure that the information was received without data corruption. |
| CT | Abbreviation for current transformer. |
| Current Differential Element | A protection element that measures the difference current between the two windings to detect internal faults. |
| Deassert | To deactivate; to remove the logic or electrical requirements needed to operate a device. To remove a short-circuit or closed contact from an SEL-787 input. To clear a logic condition to the false state (logical 0). To open a normally-open output contact. To close a normally-closed output contact. |
| Delta | A phase-to-phase connection of voltage transformers for electrical measuring purposes. Typically, two voltage transformers are used with one primary lead of the first transformer connected to A-phase and the other lead connected to B-phase. The second voltage transformer is connected to measure the voltage from B-phase to C-phase. When two transformers are used, this connection is frequently called "Open-Delta." |
| Dropout Time | The time measured from the removal of an input signal until the output signal deasserts. The time can be settable, as in the case of a logic variable timer, or can be a result of the characteristics of an element algorithm, as in the case of an overcurrent element dropout time. |
| EEPROM | Abbreviation for Electrically Erasable Programmable Read-Only Memory. Nonvolatile memory where relay settings, event reports, SER records, and other nonvolatile data are stored. |
| Event History | A quick look at recent relay activity that includes a standard report header; event number, date, time, and type; maximum fault phase current; and targets. |
| Event Report | A text-based collection of data stored by the relay in response to a triggering condition, such as a fault or command. The data show relay measurements before and after the trigger, in addition to the states of protection elements, relay inputs, and relay outputs each processing interval. After an electrical system fault, use event reports to analyze relay and system performance. |

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| Event Summary | A shortened version of stored event reports. An event summary includes items such as event date and time, event type, fault voltages, currents, etc. The relay sends an event report summary (if auto messaging is enabled) to the relay serial port a few seconds after an event. |
| Fail-Safe | Refers to an output contact that is energized during normal relay operation and de-energized when relay power is removed or if the relay fails. |
| Fast Meter, Fast Operate | Binary serial port commands that the relay recognizes at the relay front-and-rear-panel EIA-232 serial ports. These commands and the responses from the relay make relay data collection by a communications processor faster and more efficient than transfer of the same data through use of formatted ASCII text commands and responses. |
| FID | Relay firmware identification string. Lists the relay model, firmware version and date code, and other information that uniquely identifies the firmware installed in a particular relay. |
| Firmware | The nonvolatile program stored in the relay that defines relay operation. |
| Flash | A type of nonvolatile relay memory used for storing large blocks of nonvolatile data, such as load profile records. |
| Fundamental Frequency | The component of the measured electrical signal for which frequency is equal to the normal electrical system frequency, usually 50 or 60 Hz. Generally used to differentiate between the normal system frequency and any harmonic frequencies present. |
| Fundamental Meter | Type of meter data presented by the SEL-787 that includes the present values measured at the relay ac inputs. The word “Fundamental” is used to indicate that the values are Fundamental Frequency values and do not include harmonics. |
| IA, IB, IC | Measured A-, B-, and C-phase currents. |
| IEC 61850 | Standard protocol for real-time exchange of data between databases in multi-vendor devices. |
| IG | Residual current, calculated from the sum of the phase currents. In normal, balanced operation, this current is very small or zero. When a ground fault occurs, this current can be large. |
| IN | Neutral current measured by the relay IN input. The IN input is typically connected to the secondary winding of a window-CT for ground fault detection on resistance-grounded systems. |
| LCD | Abbreviation for Liquid Crystal Display. Used as the relay front-panel alphanumeric display. |
| LED | Abbreviation for Light-Emitting Diode. Used as indicator lamps on the relay front panel. |
| MIRRORED BITS® Communications | Protocol for direct relay-to-relay communications. |
| NEMA | Abbreviation for National Electrical Manufacturers Association. |

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| Neutral Overcurrent Element | A protection element that causes the relay to trip when the neutral current magnitude (measured by the IN input) exceeds a user settable value. Used to detect and trip in response to ground faults. |
| Nominal Frequency | Normal electrical system frequency, usually 50 or 60 Hz. |
| Nonfail-Safe | Refers to an output contact that is not energized during normal relay operation. When referred to a trip output contact, the protected equipment remains in operation unprotected when relay power is removed or if the relay fails. |
| Nonvolatile Memory | Relay memory that is able to correctly maintain data it is storing even when the relay is de-energized. |
| Overfrequency Element | A protection element that causes the relay to trip when the measured electrical system frequency exceeds a settable frequency. |
| Phase Rotation | The sequence of voltage or current phasors in a multi-phase electrical system. In an ABC phase rotation system, the B-phase voltage lags the A-phase voltage by 120 degrees, and the C-phase voltage lags B-phase voltage by 120 degrees. In an ACB phase rotation system, the C-phase voltage lags the A-phase voltage by 120°, and the B-phase voltage lags the C-phase voltage by 120 degrees. |
| Pickup Time | The time measured from the application of an input signal until the output signal asserts. The time can be settable, as in the case of a logic variable timer, or can be a result of the characteristics of an element algorithm, as in the case of an overcurrent element pickup time. |
| Pinout | The definition or assignment of each electrical connection at an interface. Typically refers to a cable, connector, or jumper. |
| Power, P | Real part of the complex power (S) expressed in units of Watts (W), kilovolt-watts (kW), or megawatts (MW). |
| Power Factor | The cosine of the angle by which phase current lags phase voltage in an ac electrical circuit. Power factor equals 1.0 for power flowing to a resistive load. |
| Power, Q | Reactive part of the complex power (S) expressed in units of Vars (W), kilovars (kVar), or megavars (MVar). |
| PT | Abbreviation for potential transformer. Also referred to as a voltage transformer or VT. |
| RAM | Abbreviation for Random Access Memory. Volatile memory where the relay stores intermediate calculation results, Relay Word bits, and other data that are updated every processing interval. |
| Relay Word | The collection of relay element and logic results. Each element or result is represented by a unique identifier, known as a Relay Word bit. |
| Relay Word Bit | A single relay element or logic result that the relay updates once each processing interval. A Relay Word bit can be equal to either logical 1 or logical 0. Logical 1 represents a true logic condition, picked up element, or asserted contact input or contact output. Logical 0 represents a false logic condition, dropped out element, or deasserted contact input or contact output. You can use Relay Word bits in SELOGIC control equations to control relay tripping, event triggering, and output contacts, as well as other functions. |

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| Remote Bit | A Relay Word bit for which state is controlled by serial port commands, including the CONTROL command, binary Fast Operate command, or Modbus [®] command. |
| Residual Current | The sum of the measured phase currents. In normal, balanced operation, this current is very small or zero. When a ground fault occurs, this current can be large. |
| Restricted Earth Fault Element (REF) | Provides sensitive protection against ground faults in wye-connected transformer windings. The element is “restricted” to ground faults within a zone defined by neutral and line CT placement. |
| RMS | Abbreviation for Root-Mean-Square. Refers to the effective value of the sinusoidal current and voltage measured by the relay, accounting for the fundamental frequency and higher order harmonics in the signal. |
| ROM | Abbreviation for Read-Only Memory. Nonvolatile memory where the relay firmware is stored. |
| RTD | Abbreviation for Resistance Temperature Device. An RTD is made of a metal having a precisely known resistance and temperature coefficient of resistance. The SEL-787 (and the SEL-2600 RTD Module RTD modules) can measure the resistance of the RTD, and thus, determine the temperature at the RTD location, typically embedded in the transformer and oil tank. |
| Transducer | Device that converts the input to the device to an analog output quantity of either current (± 1 , 2.5, 5, 10 and 20 mA, or 4–20 ma), or voltage (± 1 , 2.5, 5, or 10 V). |
| Self-Test | A function that verifies the correct operation of a critical device subsystem and indicates if an out-of-tolerance condition is detected. The SEL-787 is equipped with self-tests that validate the relay power supply, microprocessor, memory, and other critical systems. |
| SELOGIC[®] Control Equation | A relay setting that allows you to control a relay function (such as an output contact) by using a logical combination of relay element outputs and fixed logic outputs. Logical AND, OR, INVERT, rising edge [/], and falling edge [\] operators, plus a single level of parentheses are available to use in each control equation setting. |
| Sequential Events Recorder | A relay function that stores a record of the date and time of each assertion and deassertion of every Relay Word bit in a settable list. Provides a useful way to determine the order and timing of events following a relay operation. |
| SER | Abbreviation for Sequential Events Recorder or the relay serial port command to request a report of the latest 1024 sequential events. |
| Synchrophasors | The word synchrophasor is derived from two words: synchronized phasor. Synchrophasor measurement refers to the concept of providing measurements taken on a synchronized schedule in multiple locations. A high-accuracy clock, commonly a Global Positioning System (GPS) receiver such as the SEL-2407 Satellite-Synchronized Clock, makes synchrophasor measurement possible. |
| TFE | A Through-Fault Event (TFE) monitor is designed to capture cumulative mechanical stresses caused by faults that occur outside the transformer unit protection zone. |

| | |
|------------------------------------|--|
| Terminal Emulation Software | Personal computer (PC) software that can be used to send and receive ASCII text messages via the PC serial port. |
| Underfrequency Element | A protection element that causes the relay to trip when the measured electrical system frequency is less than a settable frequency. |
| VA, VB, VC | Measured A-, B-, and C-phase-to-neutral voltages. |
| VAB, VBC, VCA | Measured or calculated phase-to-phase voltages. |
| VG | Residual voltage calculated from the sum of the three phase-to-neutral voltages, if connected. |
| VT | Abbreviation for voltage transformer. Also referred to as a potential transformer or PT. |
| Volts/Hz | The ratio of voltage to frequency is a measure of transformer excitation and the Volts/Hz element protects against overexcitation. |
| Wye | As used in this instruction manual, a phase-to-neutral connection of voltage transformers for electrical measuring purposes. Three voltage transformers are used with one primary lead of the first transformer connected to A-phase and the other lead connected to ground. The second and third voltage transformers are connected to measure the voltage from B-phase and C-phase-to-ground, respectively. This connection is frequently called “four-wire wye,” alluding to the three phase leads plus the neutral lead. |
| Z-Number | That portion of the relay RID string that identifies the proper ACSELERATOR QuickSet relay driver version when creating or editing relay settings files. |

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Page numbers appearing in bold mark the location of the topic's primary discussion.

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SEL-787 Relay Command Summary

The table below lists the front serial port ASCII commands associated with particular activities. The commands are shown in uppercase letters, but they can also be entered using lowercase letters.

| Serial Port Command | Command Description |
|--------------------------------|---|
| Access Level 0 Commands | |
| ACC | Go to Access Level 1. |
| ID | Relay identification code. |
| QUI | Go to Access Level 0. |
| Access Level 1 Commands | |
| 2AC | Go to Access Level 2. |
| CEV <i>n</i> | Show compressed event report number <i>n</i> , at 1/4-cycle resolution. Attach DIF for compressed differential element report, at 1/4-cycle resolution. Attach R for compressed raw report, at 1/16-cycle resolution. |
| COM A | Return a summary report of the last 255 records in the communications buffer for MIRRORED BITS® communications Channel A. |
| COM B | Return a summary report of the last 255 records in the communications buffer for MIRRORED BITS communications Channel B. |
| COM C | Clears all communications records. If both MIRRORED BITS channels are enabled, omitting the channel specifier (A or B) clears both channels. |
| COM C A | Clears all communications records for Channel A. |
| COM C B | Clears all communications records for Channel B. |
| COM L | Appends a long report to the summary report of the last 255 records in the MIRRORED BITS communications buffer. |
| COM L A | Appends a long report to the summary report of the last 255 records in the communications buffer for MIRRORED BITS communications Channel A. |
| COM L B | Appends a long report to the summary report of the last 255 records in the communications buffer for MIRRORED BITS communications Channel B. |
| COM S | Return a summary report of the last 255 records in the MIRRORED BITS communications buffer. |
| COU <i>n</i> | Show current state of device counters. <i>n</i> = repeat the report <i>n</i> times, with a 1/2 second delay between each report. |
| DAT | View the date. |
| DAT <i>dd/mm/yyyy</i> | Enter date in DMY format. |
| DAT <i>mm/dd/yyyy</i> | Enter date in MDY format if DATE_F setting is MDY. |
| DAT <i>yyyy/mm/dd</i> | Enter date in YMD format if DATE_F setting is YMD. |
| ETH | Show the Ethernet port status. |
| EVE <i>n</i> | Show standard analog event report <i>n</i> with 4 samples per cycle. If <i>n</i> is omitted, most recent report is displayed. |
| EVE <i>nR</i> | Show standard analog event report <i>n</i> with raw (unfiltered) 16 samples per cycle data. |
| EVE D <i>n</i> | Show digital data event report number <i>n</i> , with 1/4-cycle resolution. |
| EVE D <i>nR</i> | Show digital data event report number <i>n</i> , with 1/16-cycle resolution. |

| Serial Port Command | Command Description |
|---------------------------------|---|
| EVE DIF1 <i>n</i> | Show differential element 1 event report number <i>n</i> , with 1/4-cycle resolution. |
| EVE DIF2 <i>n</i> | Show differential element 2 event report number <i>n</i> , with 1/4-cycle resolution. |
| EVE DIF3 <i>n</i> | Show differential element 3 event report number <i>n</i> , with 1/4-cycle resolution. |
| EVE R <i>n</i> | Show raw analog data event report number <i>n</i> , with 1/16-cycle resolution, same as EVE <i>n</i> R . |
| FIL DIR | Return a list of files. |
| FIL READ <i>filename</i> | Transfer settings file <i>filename</i> from the relay to the PC. |
| FIL SHOW <i>filename</i> | Filename 1 displays contents of the file <i>filename</i> . |
| GOO <i>k</i> | Display transmit and receive GOOSE messaging information. Enter number <i>k</i> to scroll the GOOSE data <i>k</i> times on the screen. |
| GRO | Display active group setting. |
| HEL | Display a short description of selected commands. |
| HIS <i>n</i> | Show summary of <i>n</i> latest event reports, where <i>n</i> = 1 is the most recent entry. If <i>n</i> is not specified, all event report summaries are displayed. |
| HIS C or R | Clear or reset history buffer. |
| IRIG | Force synchronization of internal control clock to IRIG-B time-code input. |
| LDP | Display signal profile data. |
| LDP C | Clear signal profile data. |
| MAC | Display the MAC address of the Ethernet® port (PORT 1). |
| MET | Display fundamental metering data. (Can also use MET F .) |
| MET <i>k</i> | Display fundamental metering data <i>k</i> times, where <i>k</i> is between 1 and 32767. |
| MET AI | Display analog input (transducer) data. |
| MET DEM <i>k</i> | Display demand metering data, in primary amperes. Enter number <i>k</i> to scroll metering <i>k</i> times on screen. |
| MET DIF <i>k</i> | Display differential metering data. Enter number <i>k</i> to scroll metering <i>k</i> times on screen. |
| MET E | Display energy metering data. |
| MET H | Generate harmonic report for all input currents and voltages, showing first- to fifth-harmonic levels and %THD (total harmonic distortion). |
| MET M | Display minimum and maximum metering data. |
| MET MV | Display SELOGIC math variable data. |
| MET PEA <i>k</i> | Display peak demand metering data, in primary amperes. Enter number <i>k</i> to scroll metering <i>k</i> times on screen. |
| MET PM | Display synchrophasor metering data. |
| MET RD | Reset demand metering values. |
| MET RE | Reset energy metering data. |
| MET RM | Reset minimum and maximum metering data. |
| MET RMS | Display RMS metering data. |
| MET RP | Reset peak demand metering values. |
| MET T | Display RTD metering data. |

| Serial Port Command | Command Description |
|-----------------------|--|
| PING x.x.x.x t | Determine if Ethernet port is functioning or configured properly. x.x.x.x is the IP address and “t” is the PING interval settable from 2 to 255 seconds. Default “t” is 1 second. Press Q to stop. |
| SER | Display all Sequential Events Recorder (SER) data. |
| SER d1 | Display all SER records made on date <i>d1</i> . |
| SER d1 d2 | Display all SER records made from dates <i>d2</i> to <i>d1</i> , inclusive, starting with <i>d2</i> . |
| SER n | Display the <i>n</i> most recent SER records starting with record <i>n</i> . |
| SER n1 n2 | Display SER records <i>n2</i> to <i>n1</i> , starting with <i>n2</i> . |
| SER C or R | Clear SER data. |
| SER D | Display SER delete report, which shows deleted items (use when SER Auto Deletion is selected to remove chatter) |
| SHO n | Display relay group settings (<i>n</i> = 1, 2, 3, or 4), shows <i>n</i> = 1 if <i>n</i> is not listed. |
| SHO DNP n | Display DNP data map settings for map <i>n</i> (<i>n</i> = 1, 2, or 3). |
| SHO F | Display front-panel settings. |
| SHO G | Display global settings. |
| SHO L | Display general logic settings. |
| SHO M | Display Modbus User Map settings. |
| SHO P n | Display port settings, where <i>n</i> specifies the port (1, 2, 3, 4, or F); <i>n</i> defaults to the active port if not listed. |
| SHO R | Display report settings. |
| STA | Display relay self-test status. |
| STA S | Display SELOGIC usage status report. |
| SUM | Display an event summary. |
| SUM R or C | Reset event summary buffer. |
| TAR | Display default target row or the most recently viewed target row. |
| TAR n | Display target row <i>n</i> . |
| TAR n k | Display target row <i>n</i> . Repeat display of row <i>n</i> for repeat count <i>k</i> . |
| TAR name | Display the target row with target name in the row. |
| TAR name k | Display the target row with target name in the row. Repeat display of this row for repeat count <i>k</i> . |
| TAR R | Reset any latched targets and the most recently viewed target row. |
| TFE | Displays cumulative and individual through-fault event data. The twenty (20) most recent individual events are displayed. |
| TFE n | Displays cumulative and individual through-fault event data. The <i>n</i> most recent individual events are displayed, where <i>n</i> = 1 to 500. |
| TFE A | Displays cumulative and individual through-fault event data. The most recent individual events are displayed, as many as 500. |
| TFE R or C | Clears/resets cumulative and individual through-fault event data. |
| TFE P | Preloads cumulative through-fault event data. |
| TIM | View time. |
| TIM hh:mm:ss | Set time by entering TIM followed by hours, minutes, and seconds, as shown (24-hour clock). |
| TRI | Trigger an event report data capture. |

| Serial Port Command | Command Description |
|----------------------------------|---|
| Access Level 2 Commands | |
| ANA <i>c p t</i> | Test analog output channel where <i>c</i> is the channel name or number, <i>p</i> is a percentage of full scale or either letter "R" or "r" indicates ramp mode, and <i>t</i> is the duration of the test in decimal minutes. |
| CAL | Enter Access Level C. If the main board Access jumper is not in place, the relay prompts for the entry of the Access Level C password. Access Level C is reserved for SEL use only. |
| CLO <i>n</i> | Close circuit breaker <i>n</i> , where <i>n</i> = 1 or 2. |
| CON RB<i>nn k</i> | Select a remote bit to set, clear, or pulse where <i>nn</i> is a number from 01 to 32, representing RB01 through RB32. <i>k</i> is S, C, or P for Set, Clear, or Pulse. |
| COP <i>m n</i> | Copy relay and logic settings from Group <i>m</i> to Group <i>n</i> . |
| DTO | Downloads the volts/hertz user curve from the SEL-5806 Curve Designer Software. |
| FIL WRITE <i>filename</i> | Transfer settings file <i>filename</i> from the PC to the relay. |
| GRO <i>n</i> | Modify active group setting, where <i>n</i> = 1, 2, 3, or 4. |
| L_D | Load new firmware. |
| LOO | Enables loopback testing of MIRRORED BITS channels. |
| LOO A | Enable loopback on MIRRORED BITS Channel A for the next 5 minutes. |
| LOO B | Enable loopback on MIRRORED BITS Channel B for the next 5 minutes. |
| OPE <i>n</i> | Open circuit breaker <i>n</i> , where <i>n</i> = 1 or 2. |
| PAS 1 | Change Access Level 1 password. |
| PAS 2 | Change Access Level 2 password. |
| PUL <i>n t</i> | Pulse Output Contact <i>n</i> (<i>n</i> = OUT101...) for <i>t</i> (1 to 30, default is 1) seconds. |
| SET | Modify relay settings. |
| SET <i>name</i> | For all SET commands, jump ahead to a specific setting by entering the setting name, e.g., 50P1P. |
| SET DNP <i>n</i> | Modify DNP data map settings for map <i>n</i> , where <i>n</i> = 1, 2, or 3. |
| SET F | Modify front-panel settings. |
| SET G | Modify global settings. |
| SET L | Modify SELOGIC variable and timer settings. |
| SET M | Modify Modbus User Map settings. |
| SET P <i>n</i> | Modify port <i>n</i> settings, where <i>n</i> = 1, 2, 3, 4, or F. If not specified, the default is the active port. |
| SET R | Modify report settings. |
| SET ... TERSE | For all SET commands, TERSE disables the automatic SHO command after the settings entry. |
| STA R or C | Clear self-test status and restart relay. |
| Access Level C Commands | |
| PAS C | Change Access Level C password. |

SEL-787 Relay Command Summary

The table below lists the front serial port ASCII commands associated with particular activities. The commands are shown in uppercase letters, but they can also be entered using lowercase letters.

| Serial Port Command | Command Description |
|--------------------------------|---|
| Access Level 0 Commands | |
| ACC | Go to Access Level 1. |
| ID | Relay identification code. |
| QUI | Go to Access Level 0. |
| Access Level 1 Commands | |
| 2AC | Go to Access Level 2. |
| CEV <i>n</i> | Show compressed event report number <i>n</i> , at 1/4-cycle resolution. Attach DIF for compressed differential element report, at 1/4-cycle resolution. Attach R for compressed raw report, at 1/16-cycle resolution. |
| COM A | Return a summary report of the last 255 records in the communications buffer for MIRRORED BITS® communications Channel A. |
| COM B | Return a summary report of the last 255 records in the communications buffer for MIRRORED BITS communications Channel B. |
| COM C | Clears all communications records. If both MIRRORED BITS channels are enabled, omitting the channel specifier (A or B) clears both channels. |
| COM C A | Clears all communications records for Channel A. |
| COM C B | Clears all communications records for Channel B. |
| COM L | Appends a long report to the summary report of the last 255 records in the MIRRORED BITS communications buffer. |
| COM L A | Appends a long report to the summary report of the last 255 records in the communications buffer for MIRRORED BITS communications Channel A. |
| COM L B | Appends a long report to the summary report of the last 255 records in the communications buffer for MIRRORED BITS communications Channel B. |
| COM S | Return a summary report of the last 255 records in the MIRRORED BITS communications buffer. |
| COU <i>n</i> | Show current state of device counters. <i>n</i> = repeat the report <i>n</i> times, with a 1/2 second delay between each report. |
| DAT | View the date. |
| DAT <i>dd/mm/yyyy</i> | Enter date in DMY format. |
| DAT <i>mm/dd/yyyy</i> | Enter date in MDY format if DATE_F setting is MDY. |
| DAT <i>yyyy/mm/dd</i> | Enter date in YMD format if DATE_F setting is YMD. |
| ETH | Show the Ethernet port status. |
| EVE <i>n</i> | Show standard analog event report <i>n</i> with 4 samples per cycle. If <i>n</i> is omitted, most recent report is displayed. |
| EVE <i>nR</i> | Show standard analog event report <i>n</i> with raw (unfiltered) 16 samples per cycle data. |
| EVE D <i>n</i> | Show digital data event report number <i>n</i> , with 1/4-cycle resolution. |
| EVE D <i>nR</i> | Show digital data event report number <i>n</i> , with 1/16-cycle resolution. |

| Serial Port Command | Command Description |
|---------------------------------|---|
| EVE DIF1 <i>n</i> | Show differential element 1 event report number <i>n</i> , with 1/4-cycle resolution. |
| EVE DIF2 <i>n</i> | Show differential element 2 event report number <i>n</i> , with 1/4-cycle resolution. |
| EVE DIF3 <i>n</i> | Show differential element 3 event report number <i>n</i> , with 1/4-cycle resolution. |
| EVE R <i>n</i> | Show raw analog data event report number <i>n</i> , with 1/16-cycle resolution, same as EVE <i>n</i> R . |
| FIL DIR | Return a list of files. |
| FIL READ <i>filename</i> | Transfer settings file <i>filename</i> from the relay to the PC. |
| FIL SHOW <i>filename</i> | Filename 1 displays contents of the file <i>filename</i> . |
| GOO <i>k</i> | Display transmit and receive GOOSE messaging information. Enter number <i>k</i> to scroll the GOOSE data <i>k</i> times on the screen. |
| GRO | Display active group setting. |
| HEL | Display a short description of selected commands. |
| HIS <i>n</i> | Show summary of <i>n</i> latest event reports, where <i>n</i> = 1 is the most recent entry. If <i>n</i> is not specified, all event report summaries are displayed. |
| HIS C or R | Clear or reset history buffer. |
| IRIG | Force synchronization of internal control clock to IRIG-B time-code input. |
| LDP | Display signal profile data. |
| LDP C | Clear signal profile data. |
| MAC | Display the MAC address of the Ethernet® port (PORT 1). |
| MET | Display fundamental metering data. (Can also use MET F .) |
| MET <i>k</i> | Display fundamental metering data <i>k</i> times, where <i>k</i> is between 1 and 32767. |
| MET AI | Display analog input (transducer) data. |
| MET DEM <i>k</i> | Display demand metering data, in primary amperes. Enter number <i>k</i> to scroll metering <i>k</i> times on screen. |
| MET DIF <i>k</i> | Display differential metering data. Enter number <i>k</i> to scroll metering <i>k</i> times on screen. |
| MET E | Display energy metering data. |
| MET H | Generate harmonic report for all input currents and voltages, showing first- to fifth-harmonic levels and %THD (total harmonic distortion). |
| MET M | Display minimum and maximum metering data. |
| MET MV | Display SELOGIC math variable data. |
| MET PEA <i>k</i> | Display peak demand metering data, in primary amperes. Enter number <i>k</i> to scroll metering <i>k</i> times on screen. |
| MET PM | Display synchrophasor metering data. |
| MET RD | Reset demand metering values. |
| MET RE | Reset energy metering data. |
| MET RM | Reset minimum and maximum metering data. |
| MET RMS | Display RMS metering data. |
| MET RP | Reset peak demand metering values. |
| MET T | Display RTD metering data. |

| Serial Port Command | Command Description |
|-----------------------|--|
| PING x.x.x.x t | Determine if Ethernet port is functioning or configured properly. x.x.x.x is the IP address and “t” is the PING interval settable from 2 to 255 seconds. Default “t” is 1 second. Press Q to stop. |
| SER | Display all Sequential Events Recorder (SER) data. |
| SER d1 | Display all SER records made on date <i>d1</i> . |
| SER d1 d2 | Display all SER records made from dates <i>d2</i> to <i>d1</i> , inclusive, starting with <i>d2</i> . |
| SER n | Display the <i>n</i> most recent SER records starting with record <i>n</i> . |
| SER n1 n2 | Display SER records <i>n2</i> to <i>n1</i> , starting with <i>n2</i> . |
| SER C or R | Clear SER data. |
| SER D | Display SER delete report, which shows deleted items (use when SER Auto Deletion is selected to remove chatter) |
| SHO n | Display relay group settings (<i>n</i> = 1, 2, 3, or 4), shows <i>n</i> = 1 if <i>n</i> is not listed. |
| SHO DNP n | Display DNP data map settings for map <i>n</i> (<i>n</i> = 1, 2, or 3). |
| SHO F | Display front-panel settings. |
| SHO G | Display global settings. |
| SHO L | Display general logic settings. |
| SHO M | Display Modbus User Map settings. |
| SHO P n | Display port settings, where <i>n</i> specifies the port (1, 2, 3, 4, or F); <i>n</i> defaults to the active port if not listed. |
| SHO R | Display report settings. |
| STA | Display relay self-test status. |
| STA S | Display SELOGIC usage status report. |
| SUM | Display an event summary. |
| SUM R or C | Reset event summary buffer. |
| TAR | Display default target row or the most recently viewed target row. |
| TAR n | Display target row <i>n</i> . |
| TAR n k | Display target row <i>n</i> . Repeat display of row <i>n</i> for repeat count <i>k</i> . |
| TAR name | Display the target row with target name in the row. |
| TAR name k | Display the target row with target name in the row. Repeat display of this row for repeat count <i>k</i> . |
| TAR R | Reset any latched targets and the most recently viewed target row. |
| TFE | Displays cumulative and individual through-fault event data. The twenty (20) most recent individual events are displayed. |
| TFE n | Displays cumulative and individual through-fault event data. The <i>n</i> most recent individual events are displayed, where <i>n</i> = 1 to 500. |
| TFE A | Displays cumulative and individual through-fault event data. The most recent individual events are displayed, as many as 500. |
| TFE R or C | Clears/resets cumulative and individual through-fault event data. |
| TFE P | Preloads cumulative through-fault event data. |
| TIM | View time. |
| TIM hh:mm:ss | Set time by entering TIM followed by hours, minutes, and seconds, as shown (24-hour clock). |
| TRI | Trigger an event report data capture. |

| Serial Port Command | Command Description |
|----------------------------------|---|
| Access Level 2 Commands | |
| ANA <i>c p t</i> | Test analog output channel where <i>c</i> is the channel name or number, <i>p</i> is a percentage of full scale or either letter "R" or "r" indicates ramp mode, and <i>t</i> is the duration of the test in decimal minutes. |
| CAL | Enter Access Level C. If the main board Access jumper is not in place, the relay prompts for the entry of the Access Level C password. Access Level C is reserved for SEL use only. |
| CLO <i>n</i> | Close circuit breaker <i>n</i> , where <i>n</i> = 1 or 2. |
| CON RB<i>nn k</i> | Select a remote bit to set, clear, or pulse where <i>nn</i> is a number from 01 to 32, representing RB01 through RB32. <i>k</i> is S, C, or P for Set, Clear, or Pulse. |
| COP <i>m n</i> | Copy relay and logic settings from Group <i>m</i> to Group <i>n</i> . |
| DTO | Downloads the volts/hertz user curve from the SEL-5806 Curve Designer Software. |
| FIL WRITE <i>filename</i> | Transfer settings file <i>filename</i> from the PC to the relay. |
| GRO <i>n</i> | Modify active group setting, where <i>n</i> = 1, 2, 3, or 4. |
| L_D | Load new firmware. |
| LOO | Enables loopback testing of MIRRORED BITS channels. |
| LOO A | Enable loopback on MIRRORED BITS Channel A for the next 5 minutes. |
| LOO B | Enable loopback on MIRRORED BITS Channel B for the next 5 minutes. |
| OPE <i>n</i> | Open circuit breaker <i>n</i> , where <i>n</i> = 1 or 2. |
| PAS 1 | Change Access Level 1 password. |
| PAS 2 | Change Access Level 2 password. |
| PUL <i>n t</i> | Pulse Output Contact <i>n</i> (<i>n</i> = OUT101...) for <i>t</i> (1 to 30, default is 1) seconds. |
| SET | Modify relay settings. |
| SET <i>name</i> | For all SET commands, jump ahead to a specific setting by entering the setting name, e.g., 50P1P. |
| SET DNP <i>n</i> | Modify DNP data map settings for map <i>n</i> , where <i>n</i> = 1, 2, or 3. |
| SET F | Modify front-panel settings. |
| SET G | Modify global settings. |
| SET L | Modify SELOGIC variable and timer settings. |
| SET M | Modify Modbus User Map settings. |
| SET P <i>n</i> | Modify port <i>n</i> settings, where <i>n</i> = 1, 2, 3, 4, or F. If not specified, the default is the active port. |
| SET R | Modify report settings. |
| SET ... TERSE | For all SET commands, TERSE disables the automatic SHO command after the settings entry. |
| STA R or C | Clear self-test status and restart relay. |
| Access Level C Commands | |
| PAS C | Change Access Level C password. |