The image features two book covers. The left cover is green and titled 'Expanding the Limits of SPC' with the subtitle 'Process Parameter Optimization and Process Capability Prediction with Variable Tolerance Limits'. It is identified as ASME Y14.5M-1994 and 'AN ASME STANDARD'. The right cover is dark blue and titled 'Statistical Process Control SPC', featuring a globe and logos for Ford and GM.

*Expanding The Limits Of SPC*

**Process Parameter Optimization  
& Process Capability Prediction  
with  
Variable Tolerance Limits**

Paul F. Jackson 4/25/2006

# Contents

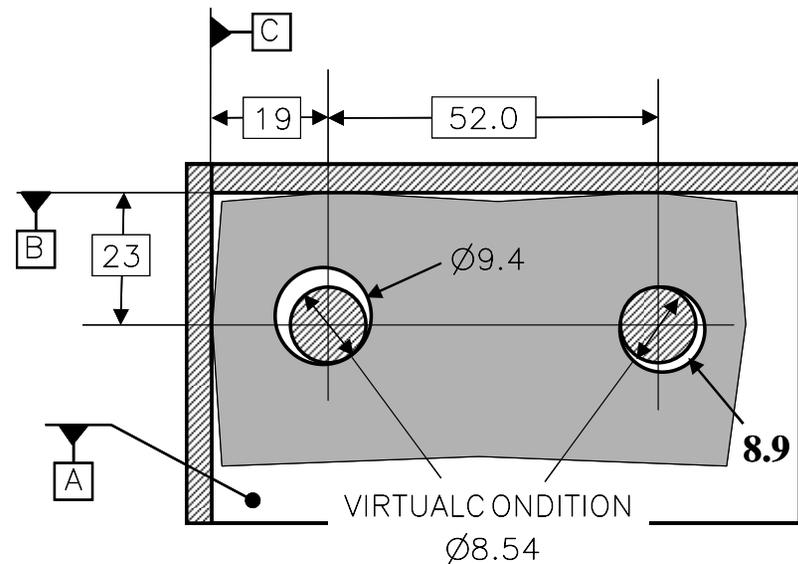
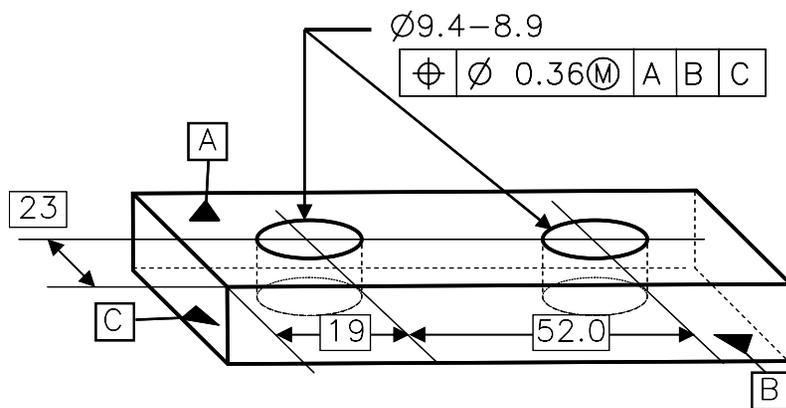
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- ✓ How to recognize a variable tolerance limit.
- ✓ How discreet and continuous data is gathered for  $\oplus$  @  $\textcircled{M}$ .
- ✓ How the data is typically used in a capability analysis.
- ✓ How a variable tolerance can be visualized in a histogram.
- ✓ What statistical model reflects the probability of defect with a variable tolerance.
- ✓ Why coordinate tolerance distributions are often non-normal.
- ✓ How process potential can be examined and optimized with both constant and variable tolerances.
- ✓ How typical and proposed capability analysis methods compare relative to variable tolerances.
- ✓ What the risks are in applying the proposed analysis methods with variable tolerance distributions

this presentation does not address process control. The capability predictions herein are demonstrated assuming that the process variation is “in-control”, due solely to common cause (random) variation, and void of special cause variation.

# How Can Tolerance Limits Be Variable?

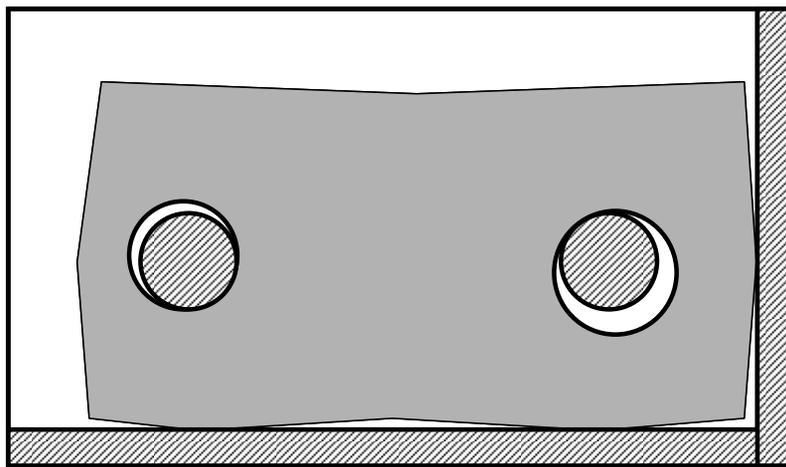
Specifications with  $\textcircled{M}$  or  $\textcircled{L}$  make the tolerance variable with respect to size.



A gage built to the virtual condition of the feature will allow the larger hole "9.4" to be further off-location than the smaller MMC hole "8.9".

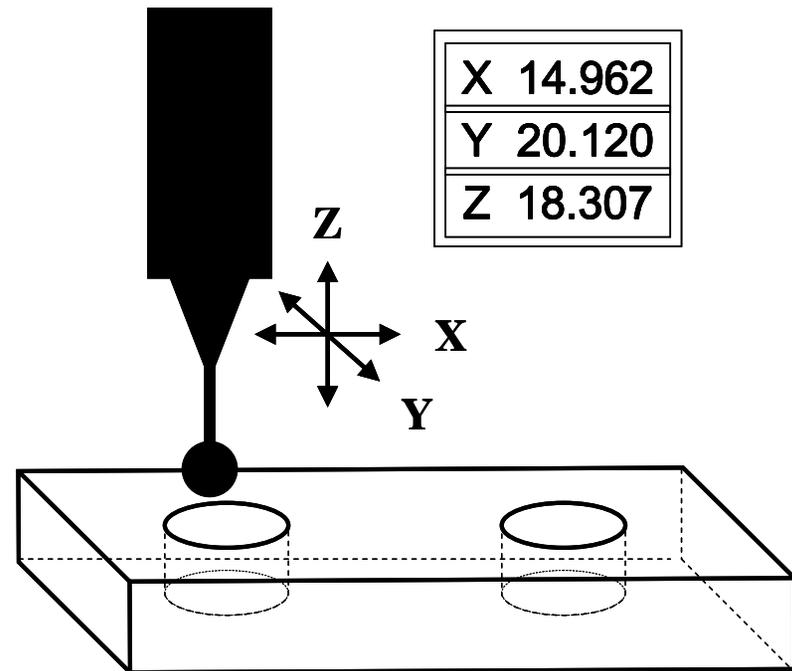
# How Is Data Gathered For SPC? (Features With Variable Tolerance)

Discreet Data  
With attribute gages



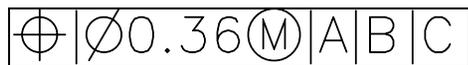
PASS / FAIL

Continuous Data  
With Variables Gages



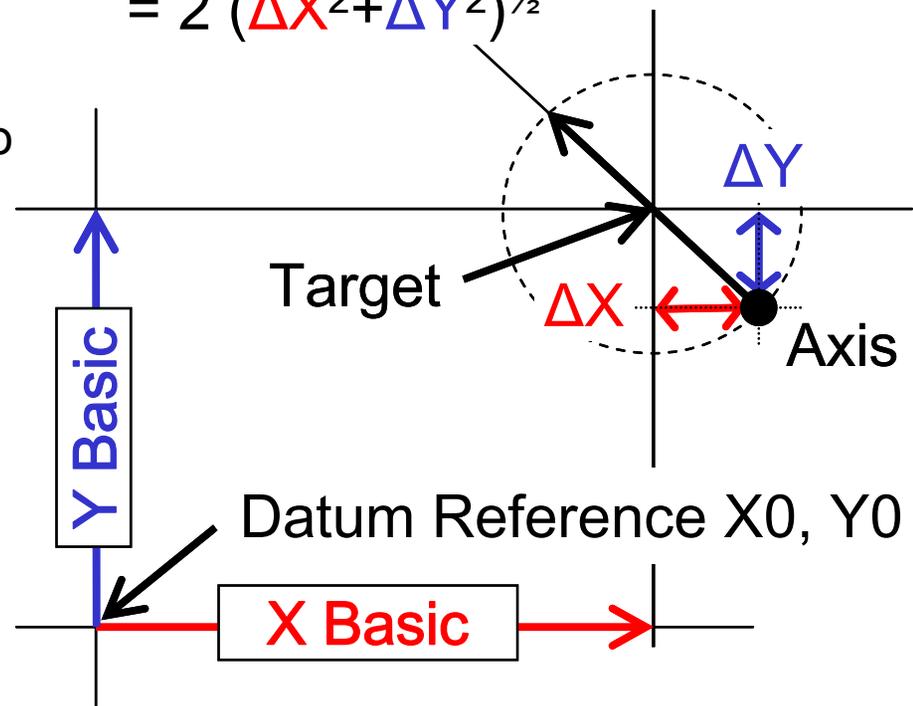
# What Is Done With Continuous Coordinate Data?

Individual coordinate deviations are converted into the equivalent form as the tolerance specified so that the tolerance required to contain the deviation can be compared directly to the tolerance specified.



Commonly the feature axis must reside within a diametrical or cylindrical tolerance zone so the individual coordinate deviations are converted into their resultant diametrical zone.

$$\varnothing \text{ Deviation} = 2 (\Delta X^2 + \Delta Y^2)^{1/2}$$



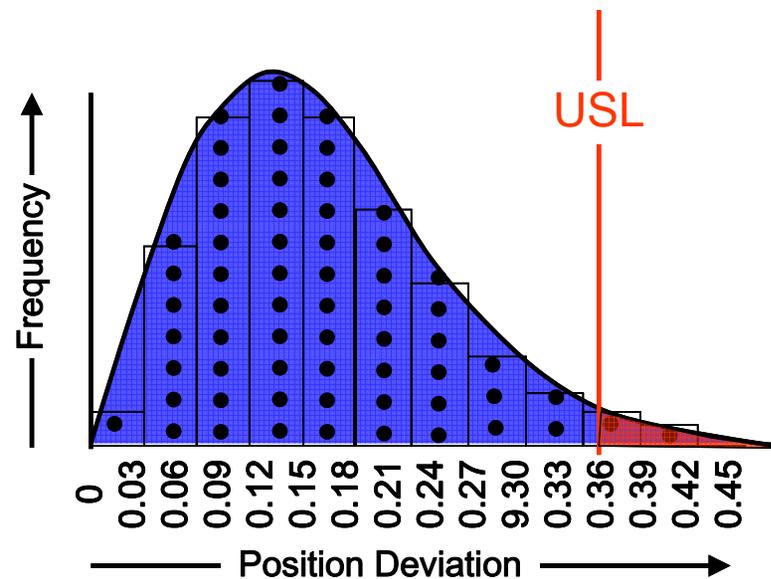
# How Is Conformance Predicted?

## Discreet Data

**% defective figured from the ratio of position gage failures to the total number of parts sampled.**

## Continuous Data

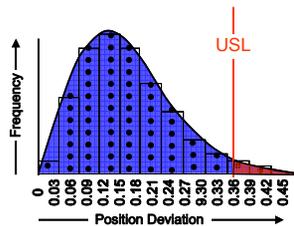
**% defective figured from the area under the fitted curve  $>$  USL compared to the total area under the fitted curve.**



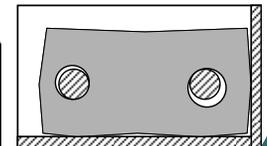
# What's The Difference?

Typical continuous data predictions of variable tolerance limits compare the position deviation to the specified limit as if it were a constant value whereas the discrete data predictions use both the specified minimum value plus the variable portion of tolerance to test acceptance.

23 Basic	Y Deviation	19 Basic	X Deviation	$\oplus \left  \varnothing 0.36(M) \right $ Ø Deviation	Ø Dev < Constant Tolerance (0.36)?	Hole Size 9.4~8.9	Bonus (size - MMC hole)	Variable Tolerance USL+Bonus	Ø Dev < Variable Tolerance (0.36+Bonus)?
23.056	0.056	19.009	0.009	0.114	Pass	9.027	0.127	0.487	Pass
23.109	0.109	19.136	0.136	0.349	Pass	9.036	0.136	0.496	Pass
23.186	0.186	18.943	-0.057	0.389	Fail	9.078	0.178	0.538	Pass
23.014	0.014	19.066	0.066	0.135	Pass	9.069	0.169	0.529	Pass
23.063	0.063	19.290	0.290	0.594	Fail	9.057	0.157	0.517	Fail
23.036	0.036	19.218	0.218	0.443	Fail	9.049	0.149	0.509	Pass
22.943	-0.057	19.269	0.269	0.551	Fail	9.051	0.151	0.511	Fail
23.063	0.063	19.075	0.075	0.196	Pass	9.029	0.129	0.489	Pass
23.075	0.075	18.906	-0.094	0.241	Pass	9.057	0.157	0.517	Pass
23.199	0.199	19.063	0.063	0.417	Fail	9.018	0.118	0.478	Pass



Constant Tolerance 0.417 > 0.36 **Fail**  
 Variable Tolerance 0.417 < 0.478 **Pass**  
**50% vs. 20% Defective!**



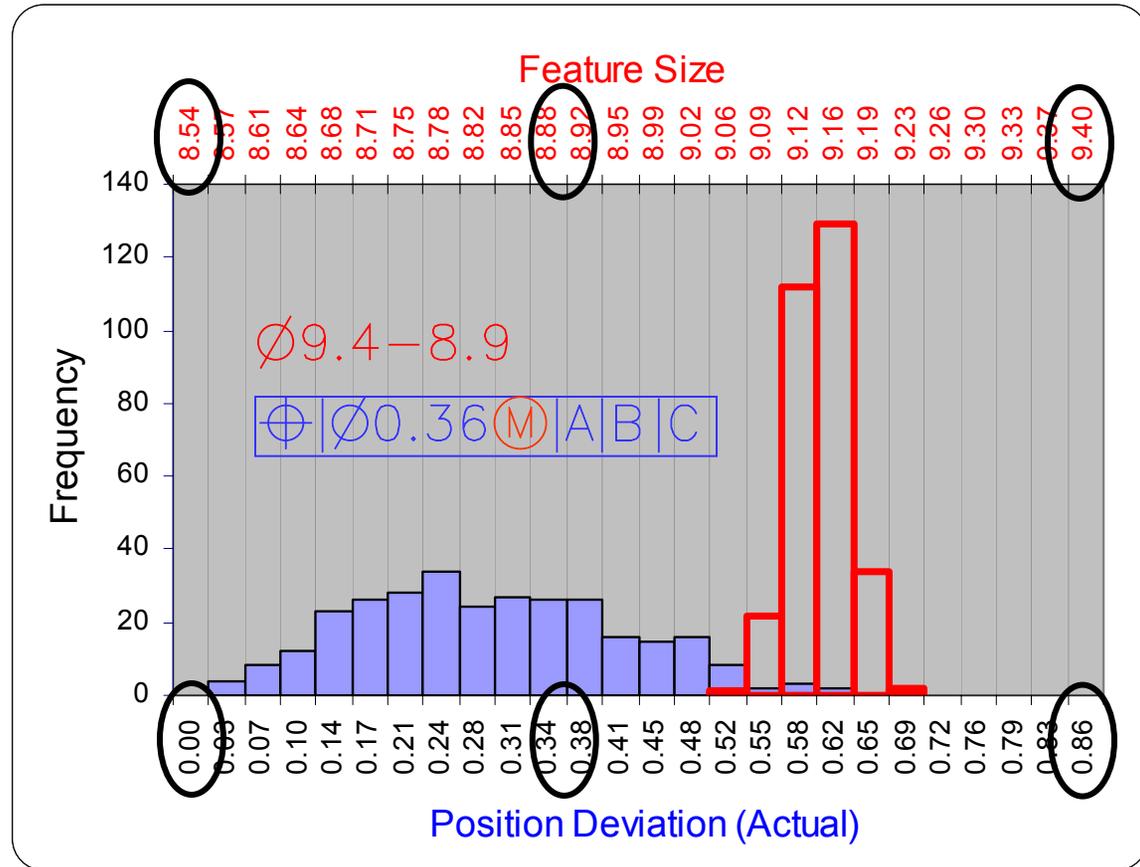
# Can A Histogram Show A Variable Tolerance?

Both size and position are plotted on the same histogram.  
 Feature sizes align with their respective position tolerances.

**Virtual Condition**  
**8.54 = 0.0 Position**

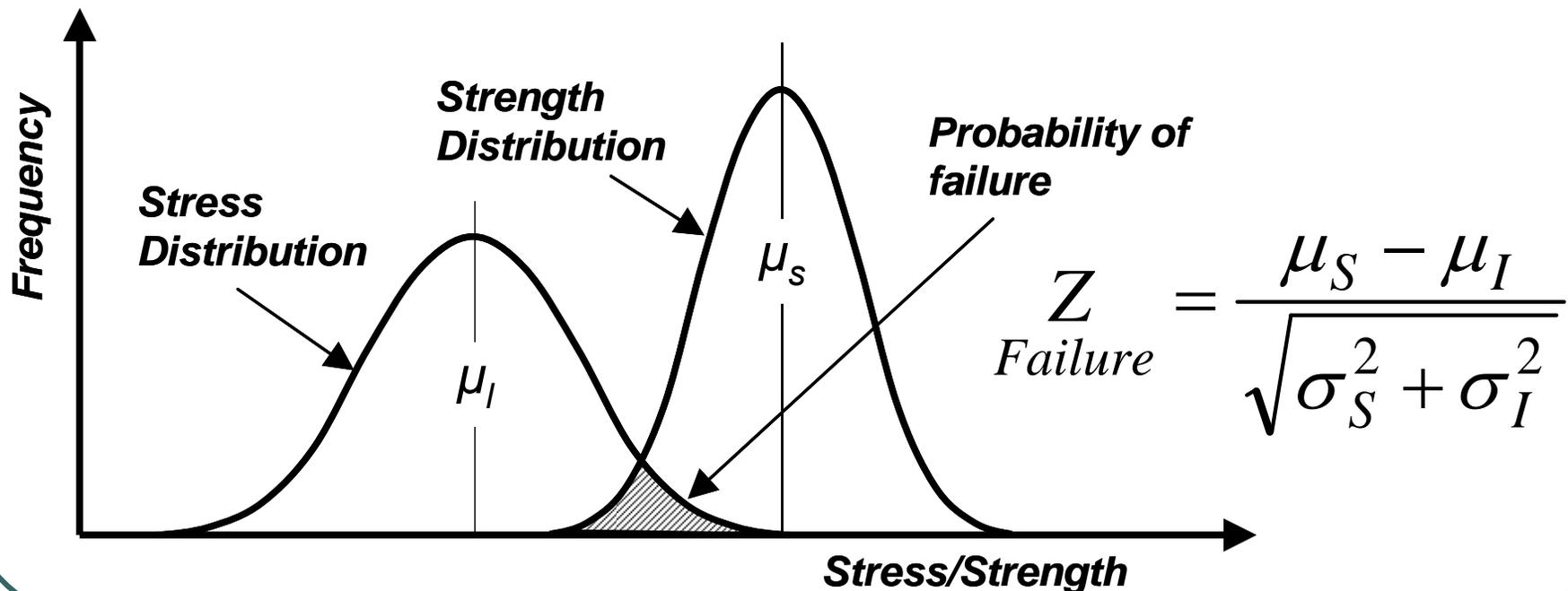
**MMC**  
**8.9 = 0.36 Position**

**LMC**  
**9.4 = 0.86 Position**

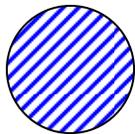
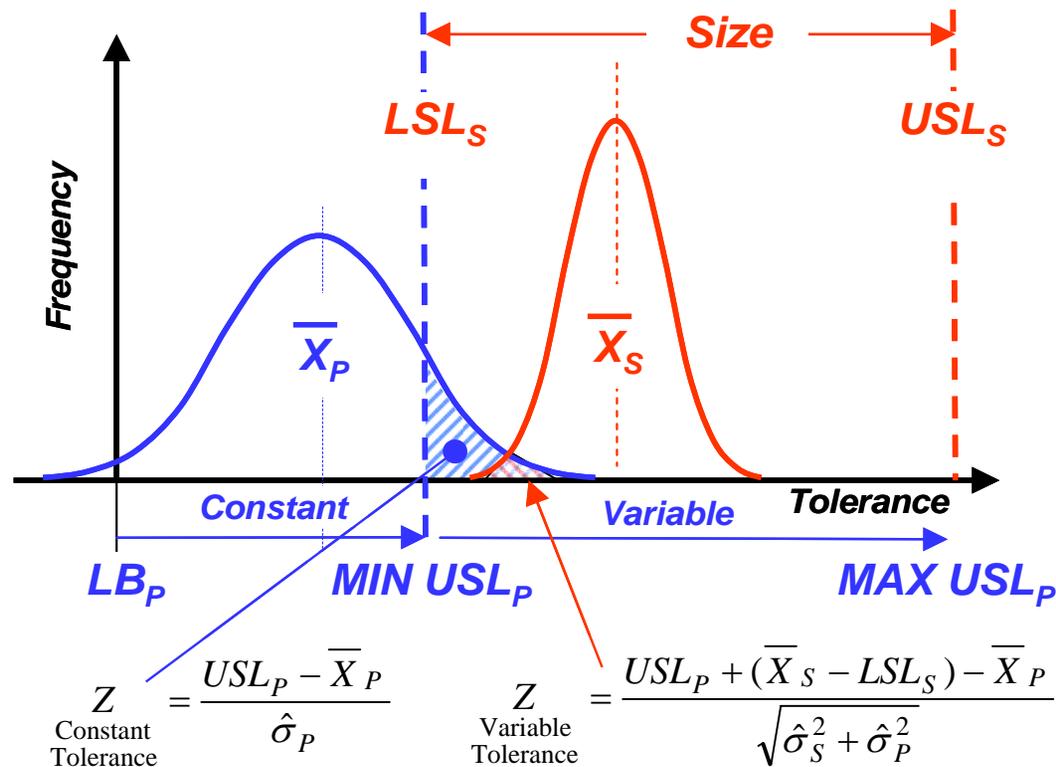


# Figuring The Probability Of A Defect With A Variable Tolerance?

The classic reliability distribution model for stress vs. strength parallels the adjacent intersecting distribution analysis needed with the variable tolerance. With both distributions “normal” the Z value of the probability of failure is:

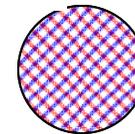


# $Z_{Upper}$ (Constant Tolerance) Vs. $Z_{Upper}$ (Variable Tolerance)

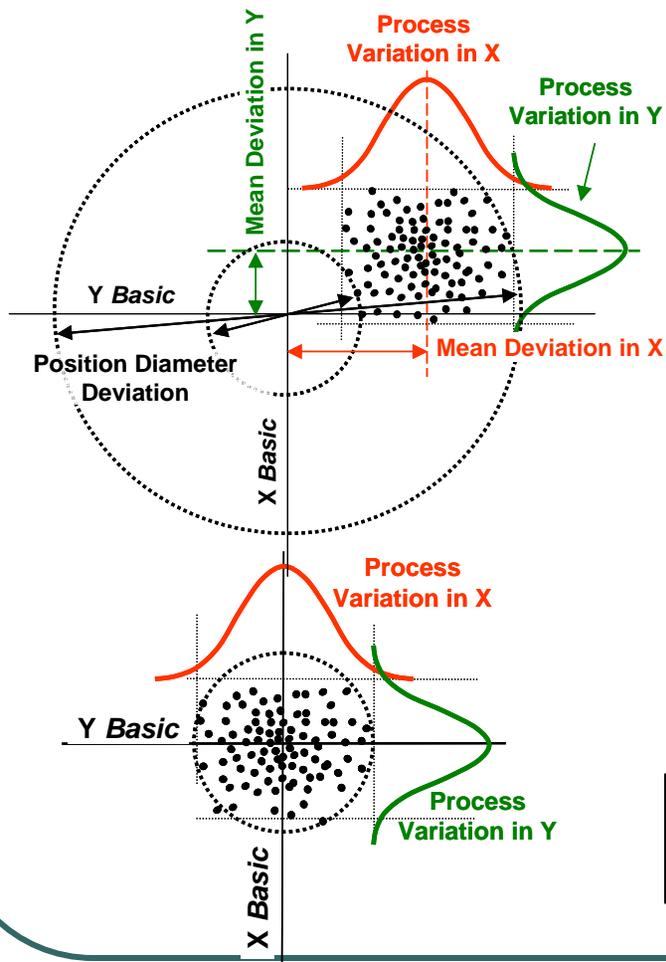


$\oplus \varnothing 0.36 \text{ A B C}$

$\oplus \varnothing 0.36 \text{ (M) A B C}$



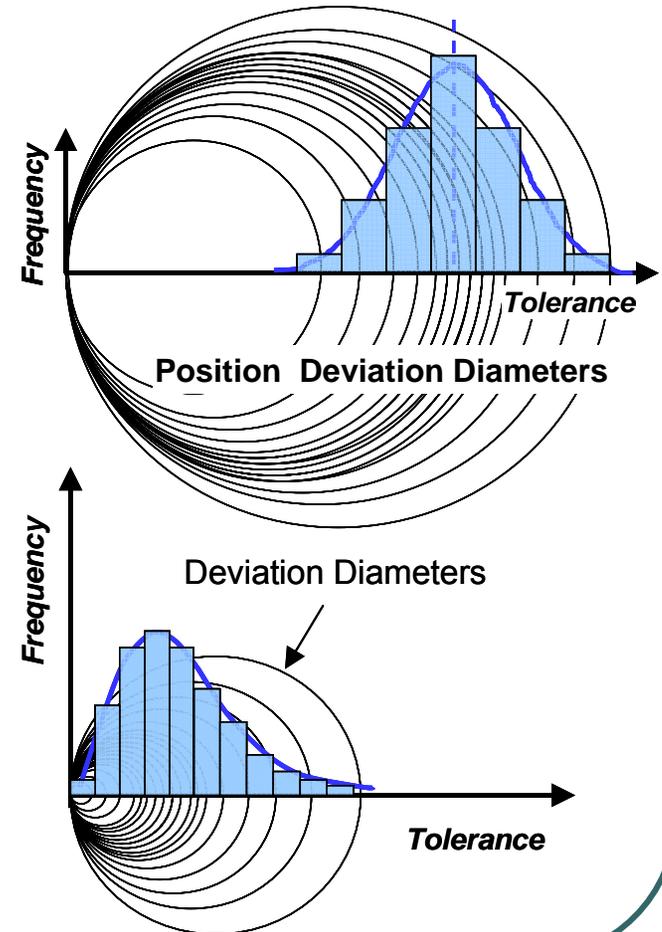
# Why Are Coordinate Position Distributions Often Non-normal?



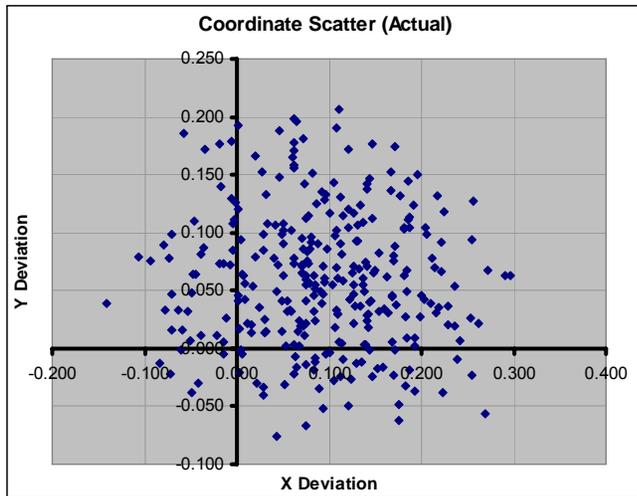
**Off Target Normal**

The diameter of the deviation is always a positive value so equivalent radial deviations in any polar direction from the target will have the same value. A well centered cluster with deviations surrounding the target will produce a more skewed distribution.

**On Target Skewed**

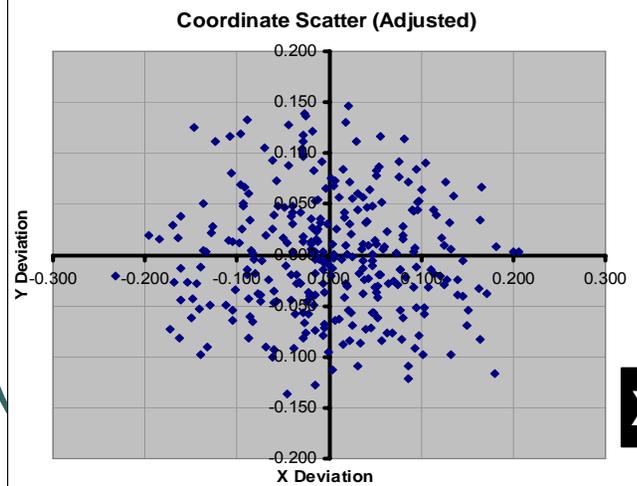


# Analyzing Process Potential (Pp) With Coordinate Position Tolerances?

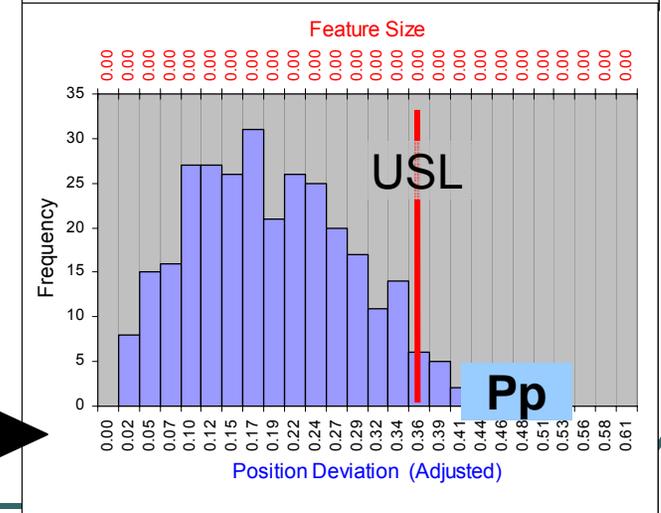
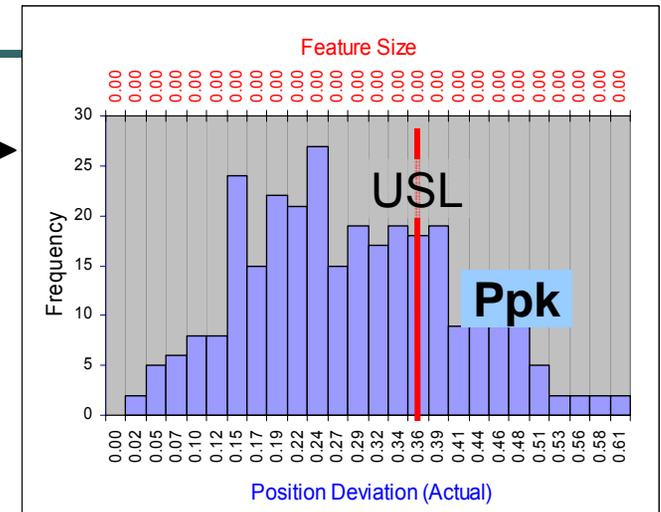


**X&Y means actual**

Many claim that Process Potential (Pp) for a constant (RFS) unilateral tolerance cannot be predicted but by centering the X and Y means of the coordinate distribution at its basic targets and re-computing the position deviations Pp can be estimated.

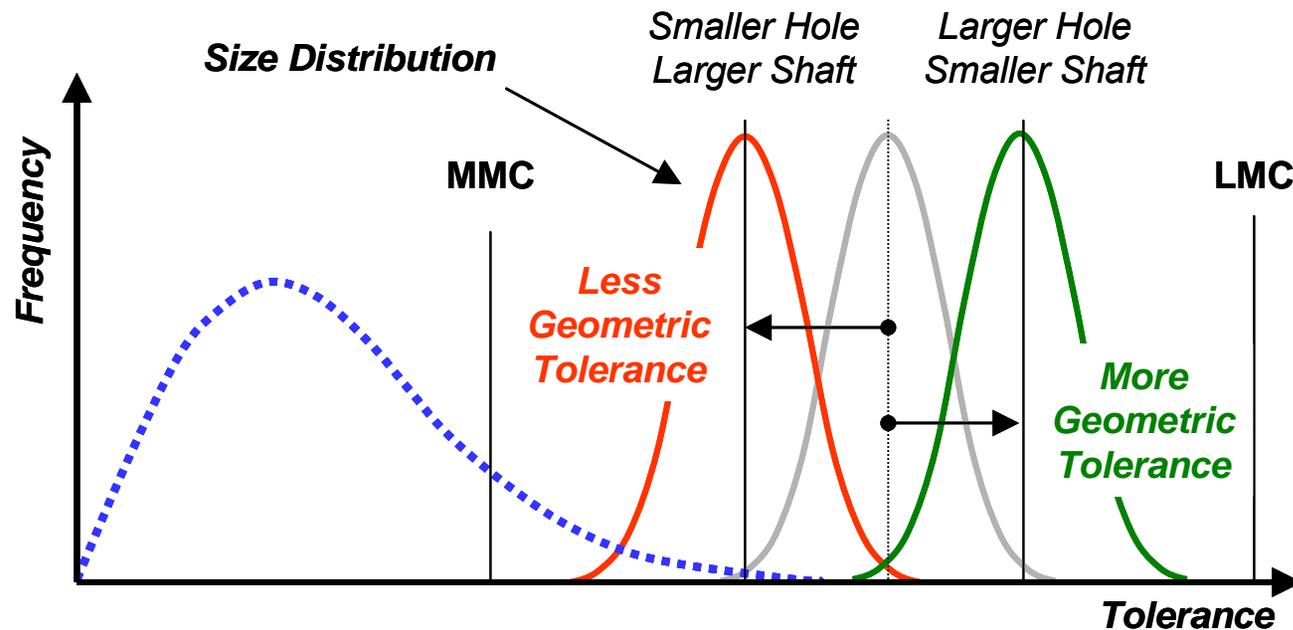


**X&Y means centered**

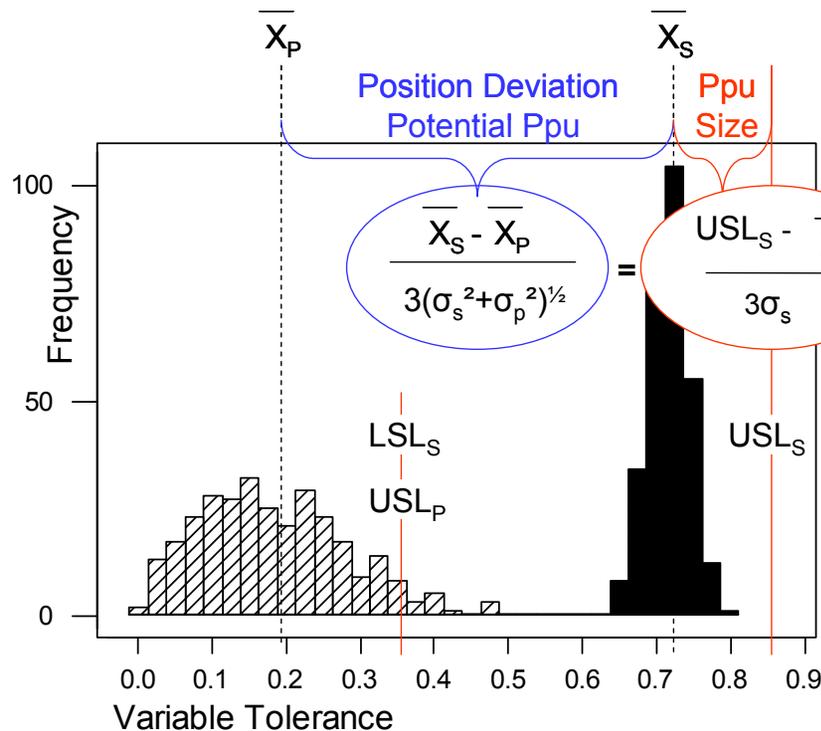


# Pp for a variable tolerance?

The process potential of a variable tolerance distribution is not only dependent upon the centrality of the coordinate distributions but it is also dependent upon the target for feature size. As the mean feature size moves away from the position deviation distribution variable tolerances increases consequently as it moves toward the tolerance decreases.



# Figuring Optimum Feature Size For A Variable Tolerance Specification?



The % defective can be minimized for both size and position simultaneously by setting the equations for Zu or Ppu of the size and variable tolerance equal to each other and solving for the corresponding value of mean feature size or mean variable tolerance.

Since the corresponding size and position are different scalar values one must be converted to solve for the other.

$$\begin{matrix} \bar{X}_P \\ (=Size) \end{matrix} = \begin{matrix} MMC \\ Size \end{matrix} - \begin{matrix} USL \\ Position \end{matrix} + \begin{matrix} \bar{X}_P \\ Position \end{matrix} \qquad \begin{matrix} \bar{X}_S \\ (=Position) \end{matrix} = \begin{matrix} \bar{X}_S \\ Size \end{matrix} - \begin{matrix} MMC \\ Size \end{matrix} + \begin{matrix} USL \\ Position \end{matrix}$$

$$Z_{\text{Upper Position}} = \frac{\bar{X}_S - \bar{X}_P}{\sqrt{\hat{\sigma}_S^2 + \hat{\sigma}_P^2}} = \frac{USL_S - \bar{X}_S}{\hat{\sigma}_S} = Z_{\text{Upper Size}}$$

$$\bar{X}_S = \frac{\hat{\sigma}_S \times \bar{X}_P + \sqrt{\hat{\sigma}_S^2 + \hat{\sigma}_P^2} \times USL_S}{\hat{\sigma}_S + \sqrt{\hat{\sigma}_S^2 + \hat{\sigma}_P^2}}$$

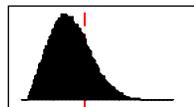
# Typical Process Capability Results Position (Non-normal Transformation)

## Ppk $\oplus$ (Variable "bonus" Ignored)

Box-Cox Transformation (Actual)

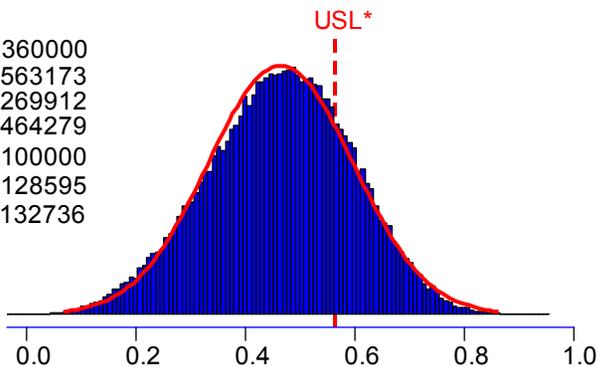
Position Ppu = 0.25

Position PPM Defective 228,123



Position Deviation XY(Actual)  
Box-Cox Transformation, With Lambda = 0.562

Process Data	
USL	0.360000
USL*	0.563173
Mean	0.269912
Mean*	0.464279
Sample N	100000
StDev (Overall)	0.128595
StDev* (Overall)	0.132736



Overall Capability	
PPU	0.25
Ppk	0.25

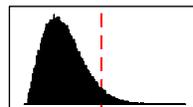
Observed Performance	Expected Performance
PPM > USL 235470.00	PPM > USL* 228123.15
PPM Total 235470.00	PPM Total 228123.15

## Pp $\oplus$ (Not Typically Considered)

Box-Cox Transformation (Potential)

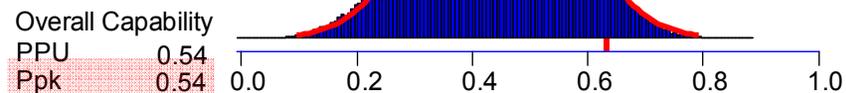
Position Pp = 0.54

Position PPM Defective 52,247



Position Deviation XY(Centered)  
Box-Cox Transformation, With Lambda = 0.449

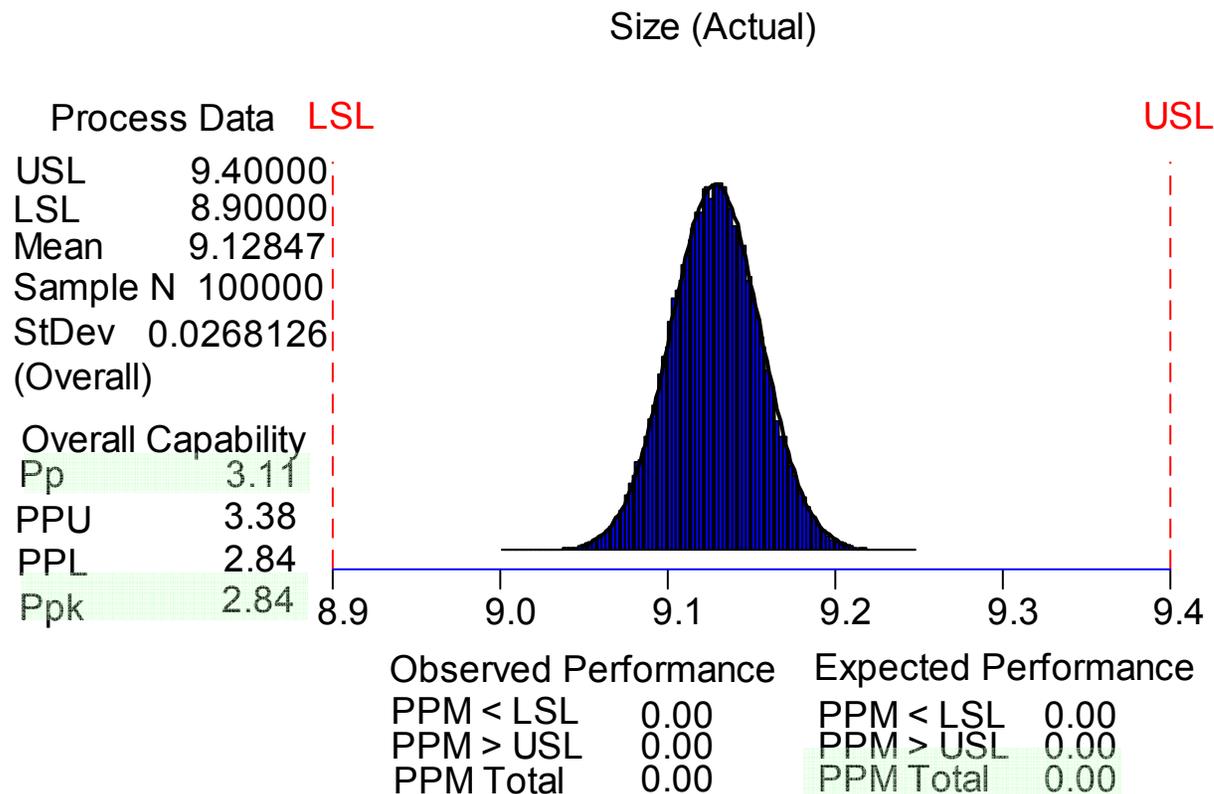
Process Data	
USL	0.360000
USL*	0.632091
Mean	0.179043
Mean*	0.443903
Sample N	100000
StDev (Overall)	0.096816
StDev* (Overall)	0.115919



Overall Capability	
PPU	0.54
Ppk	0.54

Observed Performance	Expected Performance
PPM > USL 48330.00	PPM > USL* 52247.36
PPM Total 48330.00	PPM Total 52247.36

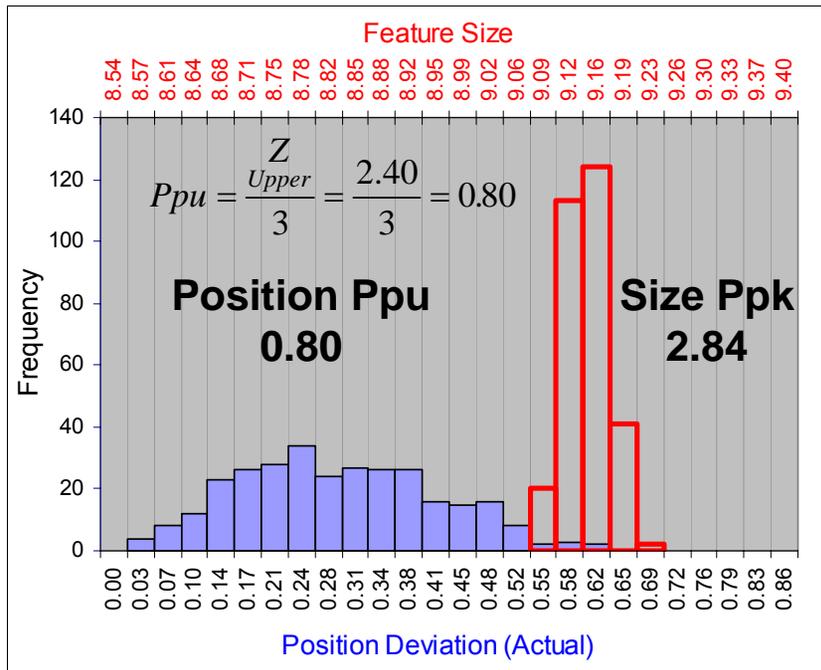
# Typical Process Capability Results Size



# Figuring the Capability of a Variable Tolerance

Position (M) & Size (Actual)

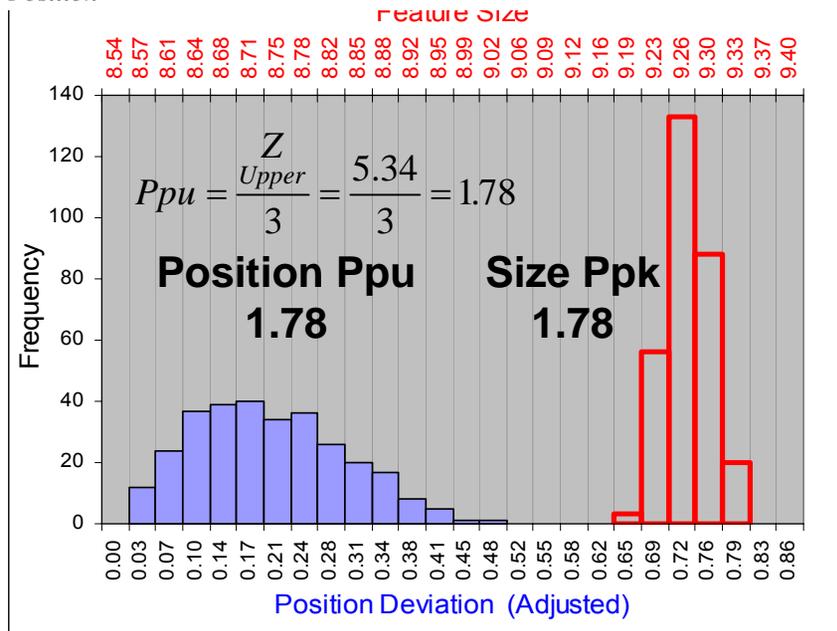
$$Z_{Upper Position} = \frac{\bar{X}_S - \bar{X}_P}{\sqrt{\hat{\sigma}_S^2 + \hat{\sigma}_P^2}} \quad Z_{Upper Position} = \frac{0.588 - 0.270}{\sqrt{.0268^2 + .1296^2}} = 2.40$$



Potential Pos & Size (Optimum)

$$\bar{X}_S = \frac{.0268 \times 8.719 + \sqrt{.0268^2 + .0968^2} \times 9.4}{.0268 + \sqrt{.0268^2 + .0968^2}} = 9.257$$

$$Z_{Upper Position} = \frac{0.717 - 0.179}{\sqrt{.0268^2 + .0968^2}} = 5.34 = \frac{9.4 - 9.257}{.0268} = Z_{Upper Size}$$



# Targeting size to minimize PPM defective of size & variable position simultaneously

Size (Optimum)

Process Data **LSL**

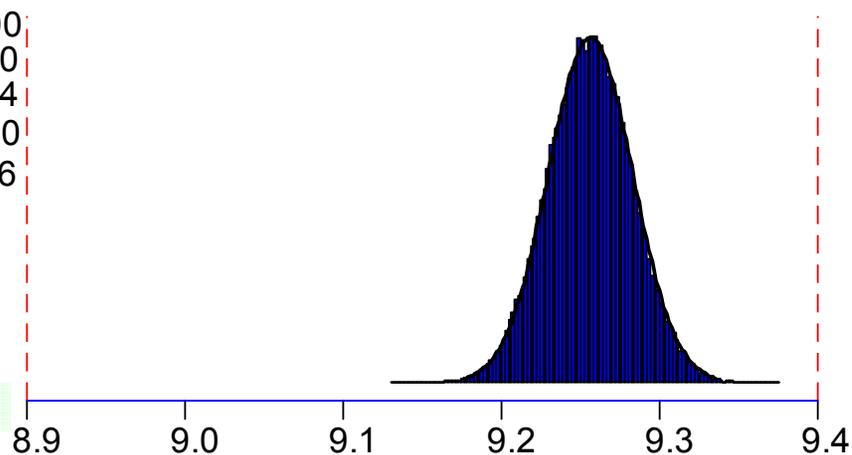
USL 9.40000  
 LSL 8.90000  
 Mean 9.25654  
 Sample N 100000  
 StDev 0.0268126

(Overall)

Overall Capability

Pp 3.11  
 PPU 1.78  
 PPL 4.43  
 Ppk 1.78

**USL**



Observed Performance

PPM < LSL 0.00  
 PPM > USL 0.00  
 PPM Total 0.00

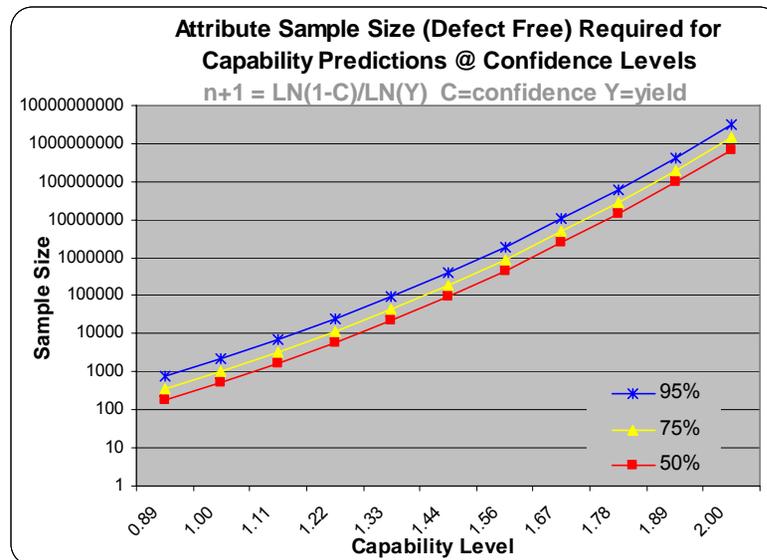
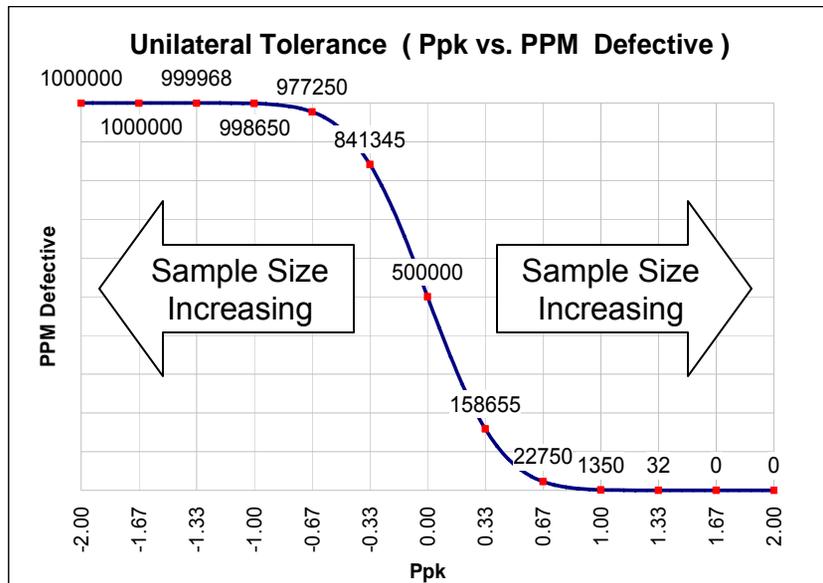
Expected Performance

PPM < LSL 0.00  
 PPM > USL 0.04  
 PPM Total 0.04

# How do the continuous data predictions compare with discrete data predictions?

Attribute predictions are typically unreliable when there are not significant differences between the portion conforming and non-conforming, For typically required levels of process capability very large samples are required.

## How big must that sample be?



# Monte Carlo Simulation of an Attribute Gage

---

100,000 random - normally distributed values for x-dev, y-dev, and size were generated. The X & Y values were converted to position deviations and each instance was evaluated as a variable tolerance.

## Attribute Gage

**Variable Position with (X&Y Actual) & Size (Actual)**

**1,398 Failed**

---

**100,000 Sampled**

**PPM Defective 13,980**

## Attribute Gage

**Variable Position with X&Y (Centered) & Size (Optimum)**

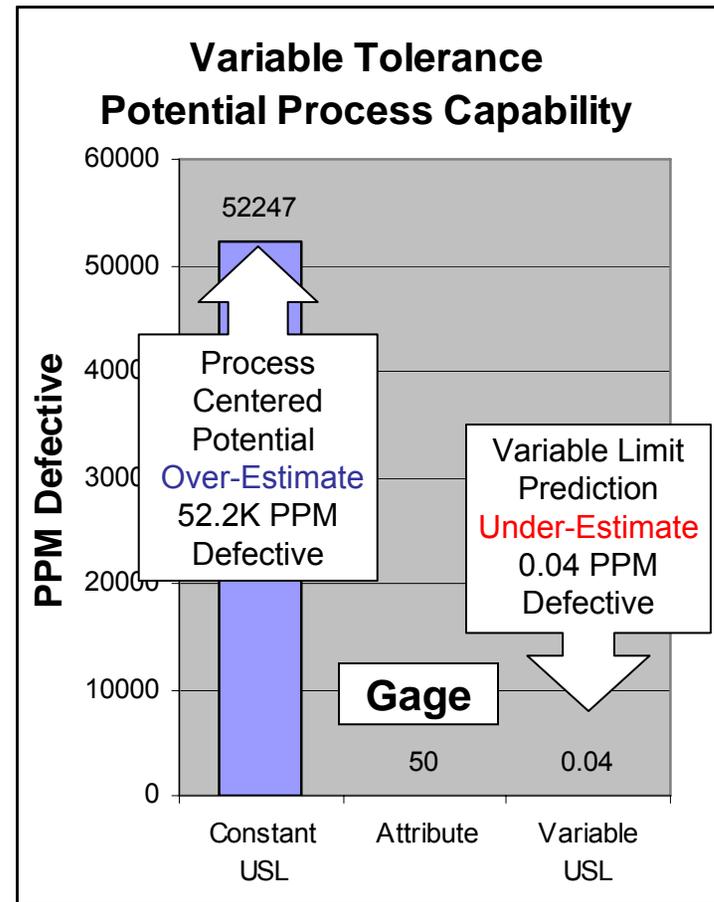
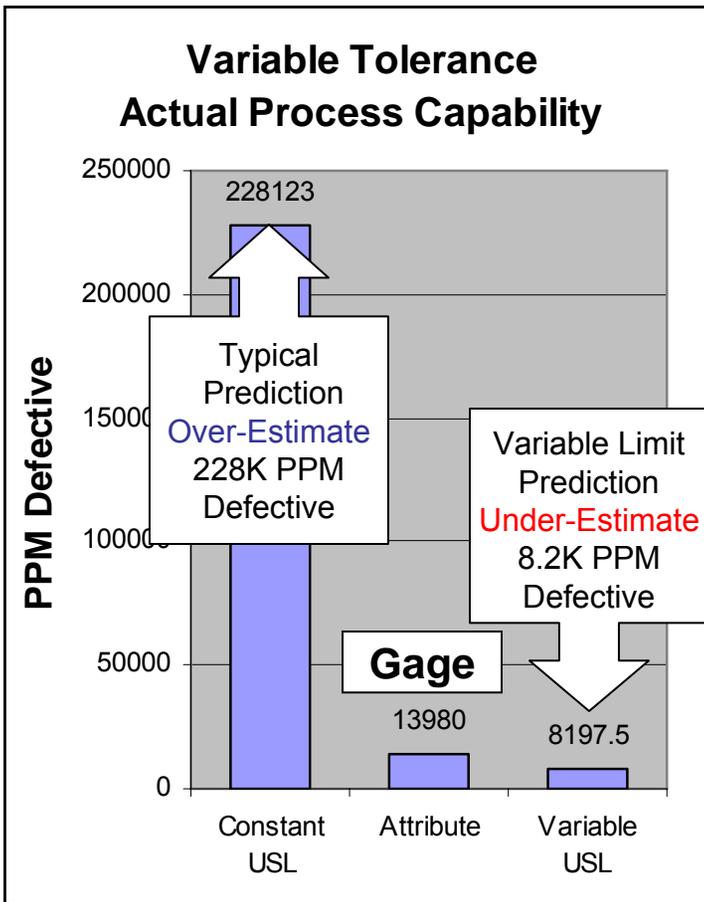
**5 Fail**

---

**100,000 Sampled**

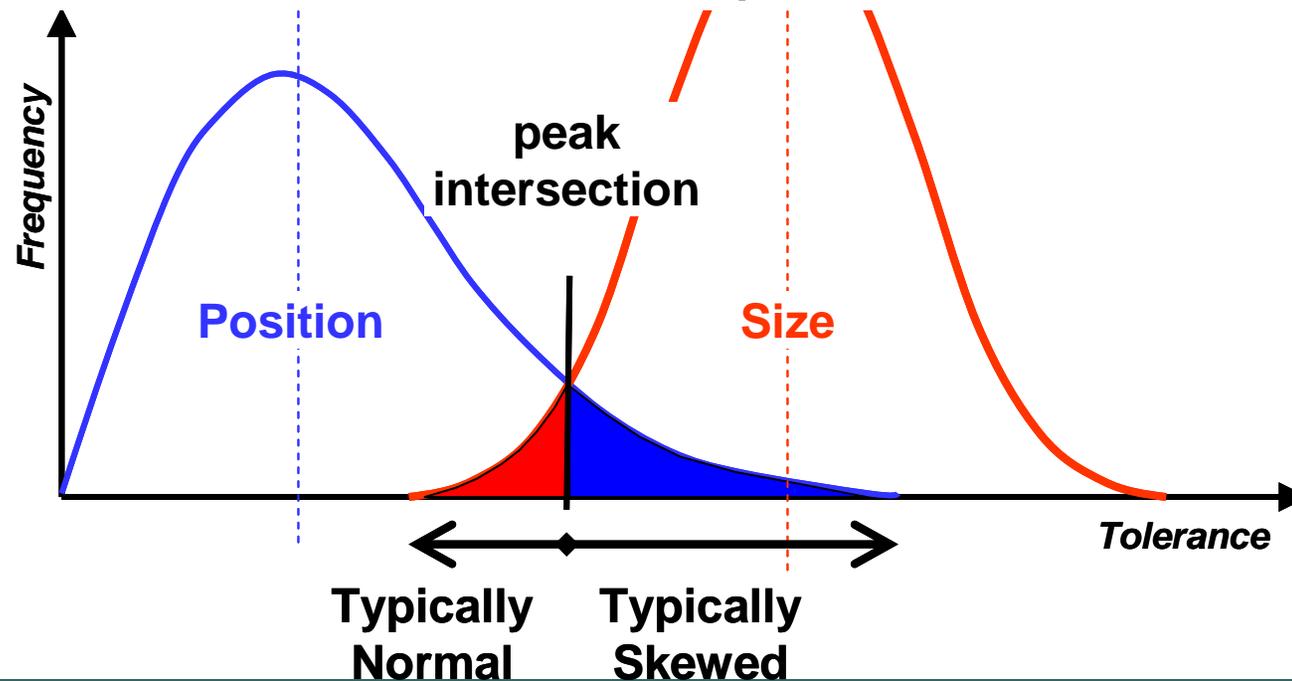
**PPM Defective 50**

# What is the difference in the predictions?



# What is the probability of a defect of a variable geometric tolerance?

The probability of a defect with a variable tolerance can be visualized as the intersecting area relative to the combined area of adjacent distributions. The shape of that intersecting area is a composite reflection of the tails of both distributions back-to-back at the peak of the intersection.

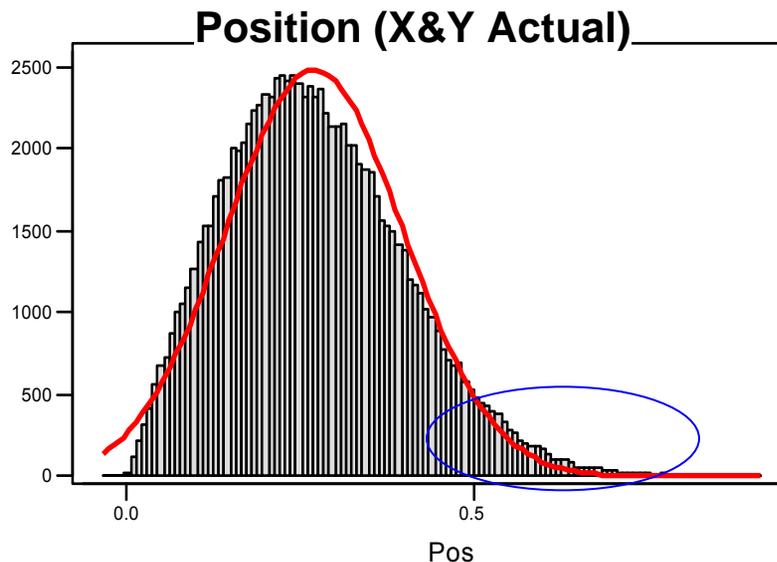


# What are the risks?

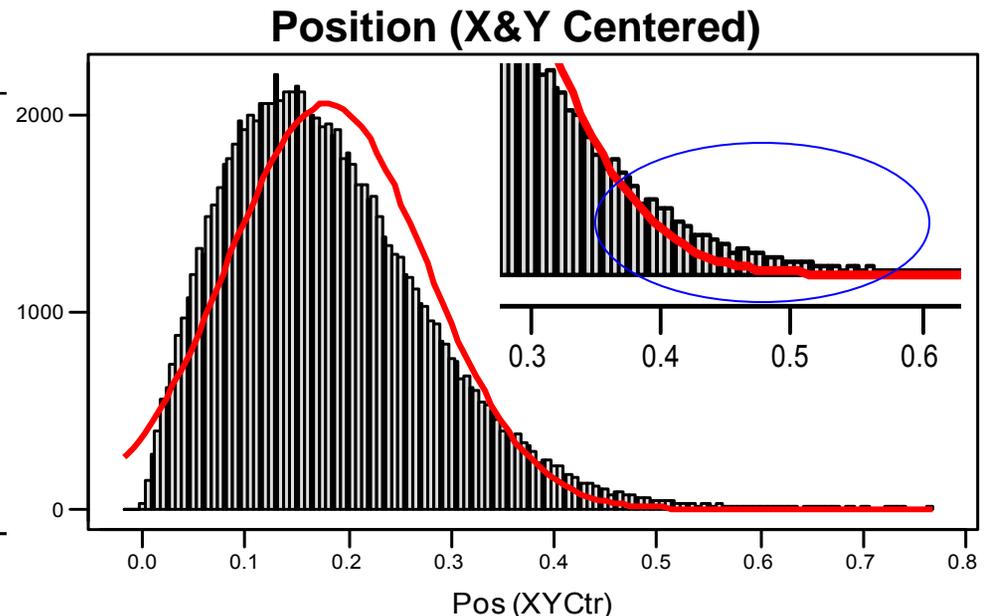
(Predicting variable tolerance capability with both intersecting distributions assumed "normal")

Typical 4 and 5 sigma 1.33-1.67 Ppk customer targeted capability requirements ensure that the area of a position distribution curve intersecting with the distribution for size that could be considered for conformance to specification will be limited to the distribution's tail.

Histogram of Pos, with Normal Curve



Histogram of Pos (XYCtr), with Normal Curve



Typically skewed position distributions fitted with normal distribution curves show that occurrence frequencies in the tail areas will be slightly underestimated.