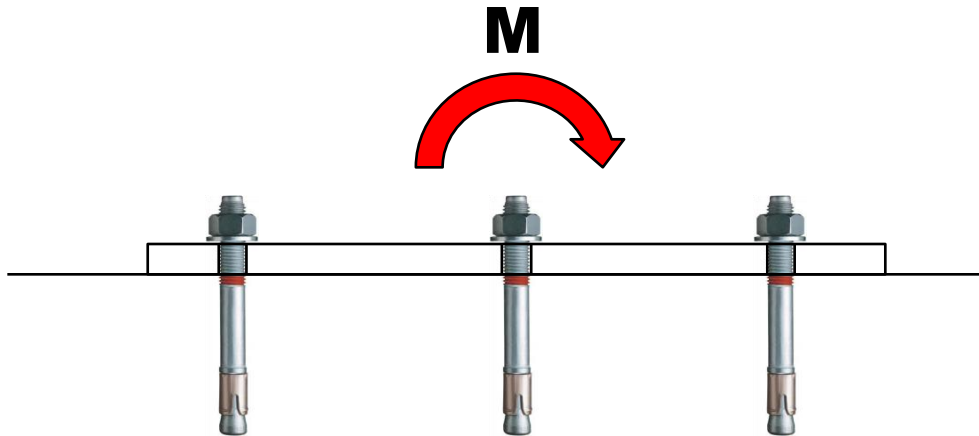
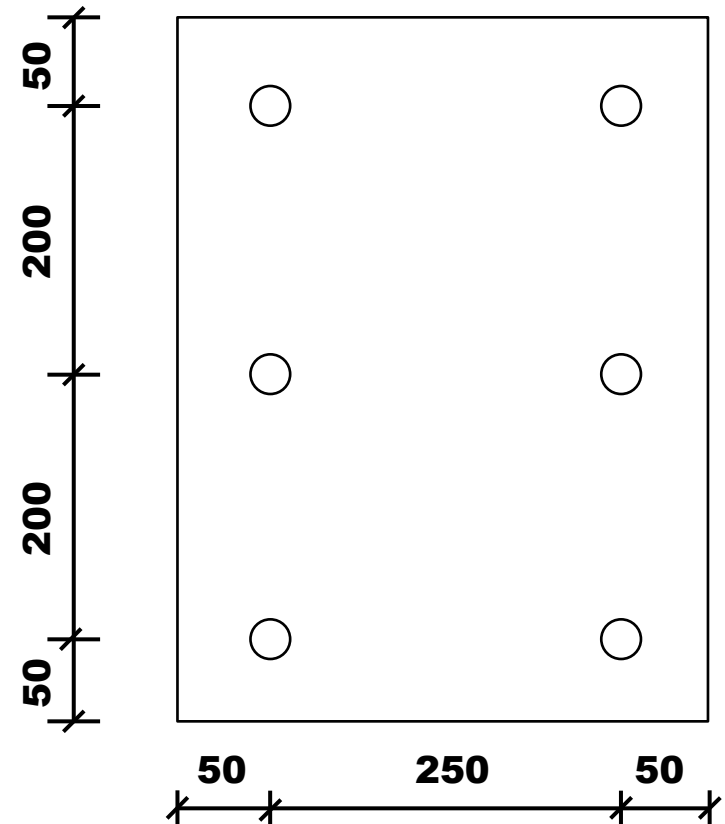


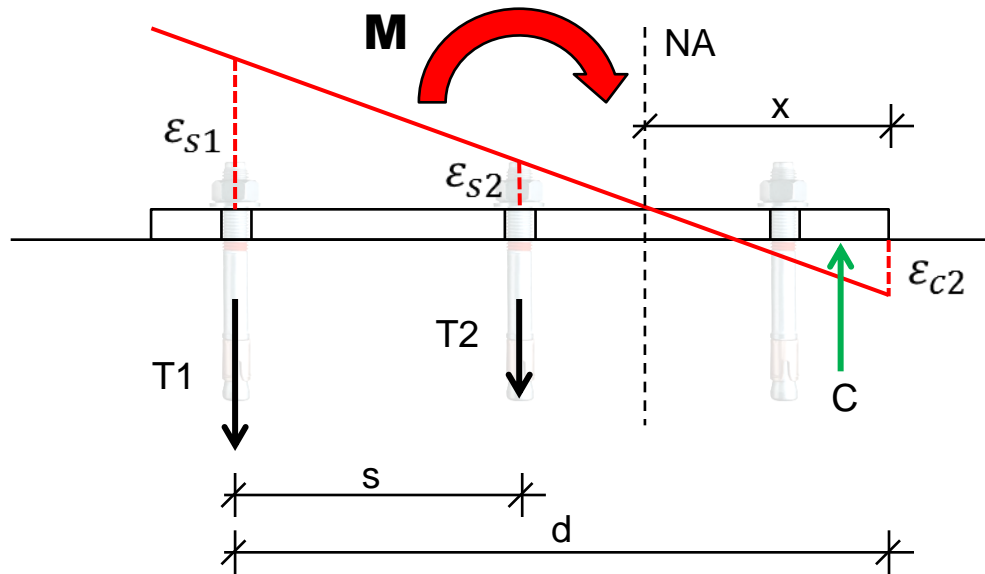
Moment Analysis on 6 or more Nos. Bolts Group



Analysis Assumption:

- Elasticity theory
- Rigid Base Plate (no deformation)
- All anchors have equal stiffness
- Anchors not transfer the compression





$$E = \frac{\sigma}{\epsilon}$$

$$\frac{E_s}{E_c} = m$$

$$\frac{\epsilon_c}{x} = \frac{\epsilon_{s1}}{d-x} = \frac{\epsilon_{s2}}{d-x-s}$$

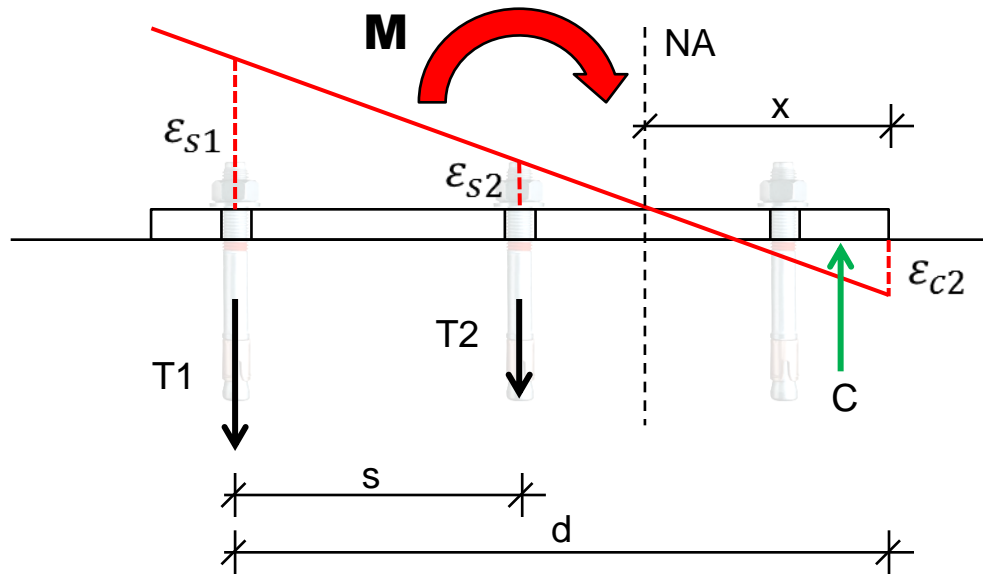
$$T1 = \sigma_{s1} A_s = \epsilon_{s1} E_s A_s = \frac{\epsilon_c (d-x)}{x} m E_c A_s$$

$$T2 = \sigma_{s2} A_s = \frac{\epsilon_c (d-x-s)}{x} m E_c A_s$$

$$C = \frac{\sigma_c x}{2} b = \frac{\epsilon_c E_c x}{2} b$$

$$\sum F = 0$$

$$C = T1 + T2$$



$$T1 = \sigma_{s1}A_s = \epsilon_{s1}E_sA_s = \frac{\epsilon_c(d-x)}{x}mE_cA_s$$

$$T2 = \sigma_{s2}A_s = \frac{\epsilon_c(d-x-s)}{x}mE_cA_s$$

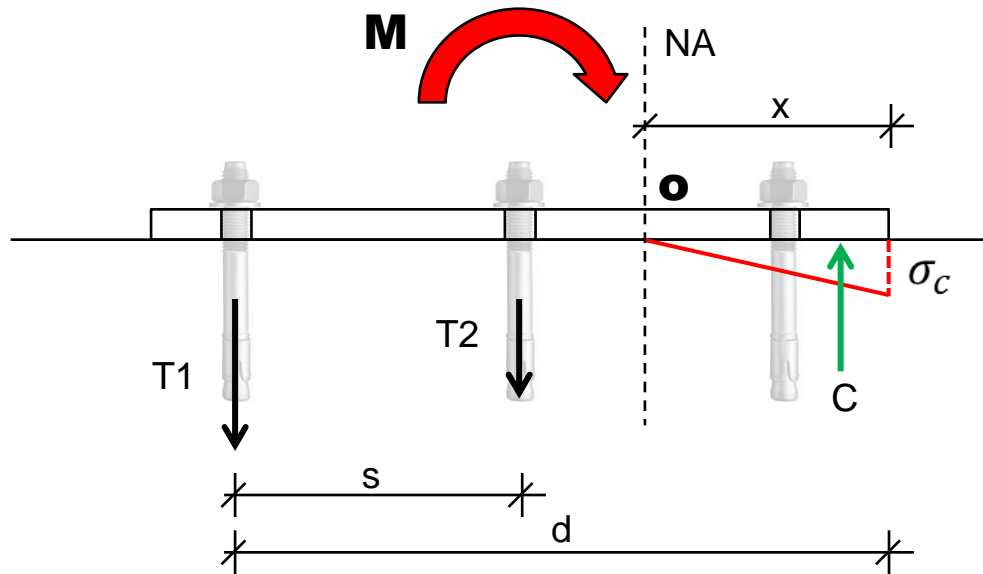
$$C = \frac{\sigma_c x}{2}b = \frac{\epsilon_c E_c x}{2}b$$

$$\sum F = 0$$

$$C = T1 + T2$$

$$\frac{\epsilon_c E_c b}{2}x = mE_cA_s\epsilon_c \left[\frac{(d-x) + (d-x-s)}{x} \right]$$

$$\frac{b}{2}x^2 + 2mA_sx - mA_s(2d-s) = 0$$



$$T1 = \sigma_{s1} A_s = \varepsilon_{s1} E_s A_s = \frac{\varepsilon_c (d - x)}{x} m E_c A_s$$

$$T2 = \sigma_{s2} A_s = \frac{\varepsilon_c (d - x - s)}{x} m E_c A_s$$

$$C = \frac{\sigma_c x}{2} b = \frac{\varepsilon_c E_c x}{2} b$$

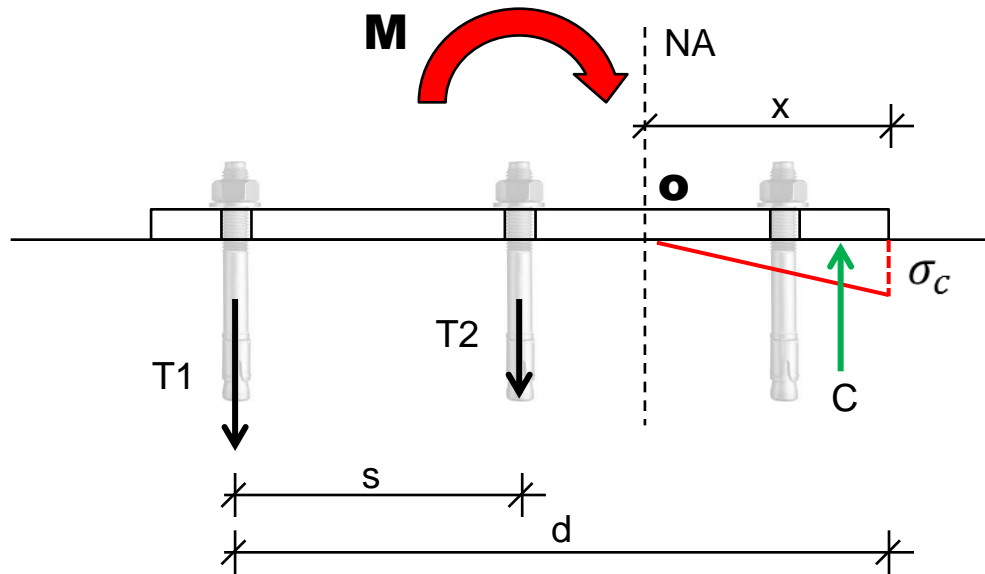
$$T1 = \frac{(d - x)}{x} m \sigma_c A_s$$

$$T2 = \frac{(d - x - s)}{x} m \sigma_c A_s$$

$$\sum M_o = 0$$

$$M = C \frac{2}{3} x + T1(d - x) + T2(d - x - s)$$

$$M = \frac{\sigma_c b}{3} x^2 + m \sigma_c A_s \left[\frac{(d - x)^2 + (d - x - s)^2}{x} \right]$$

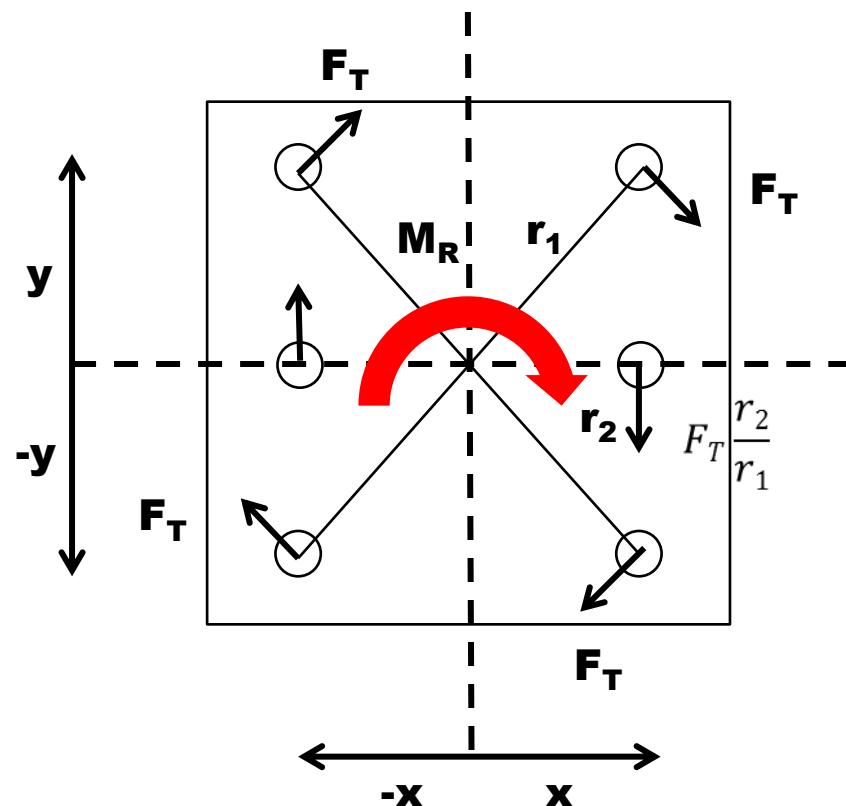
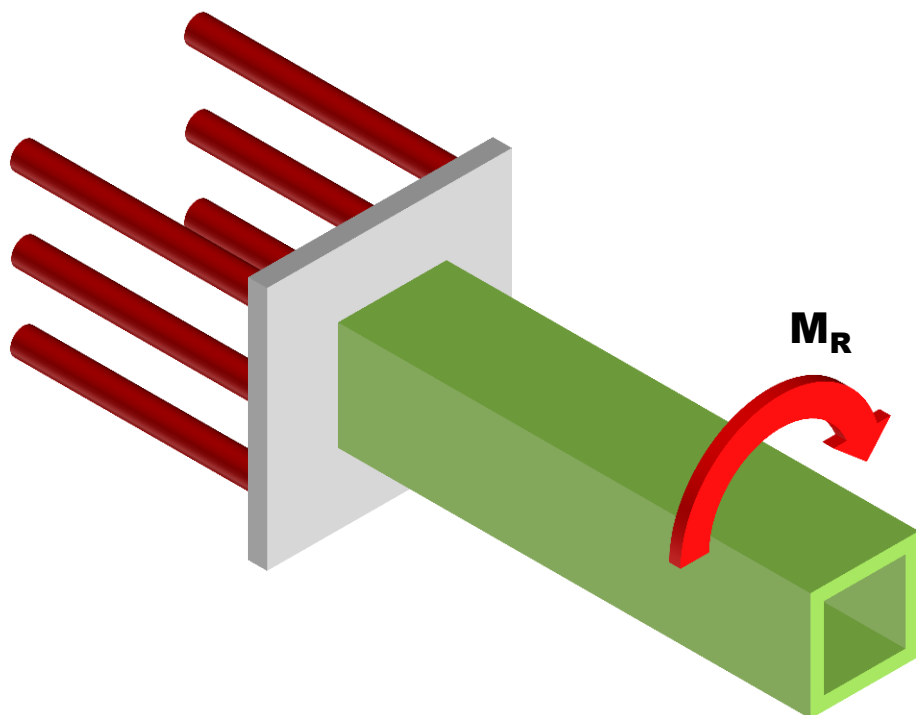


$$\sigma_c = \frac{M}{\frac{b}{3}x^2 + mA_s \left[\frac{(d-x)^2 + (d-x-s)^2}{x} \right]}$$

$$T1 = \frac{(d-x)}{x} m \sigma_c A_s$$

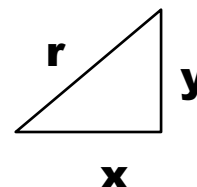
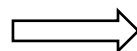
$$T2 = \frac{(d-x-s)}{x} m \sigma_c A_s$$

Torsional Analysis on Bolts Group of Embed



$$M_R = F_T \times r_1 + F_T \frac{r_2}{r_1} r_2 + \dots$$

$$M_R = \frac{F_T}{r_1} \times (r_1^2 + r_2^2 + \dots)$$



$$r^2 = x^2 + y^2$$

$$M_R = \frac{F_T}{r_1} \sum (x^2 + y^2)$$

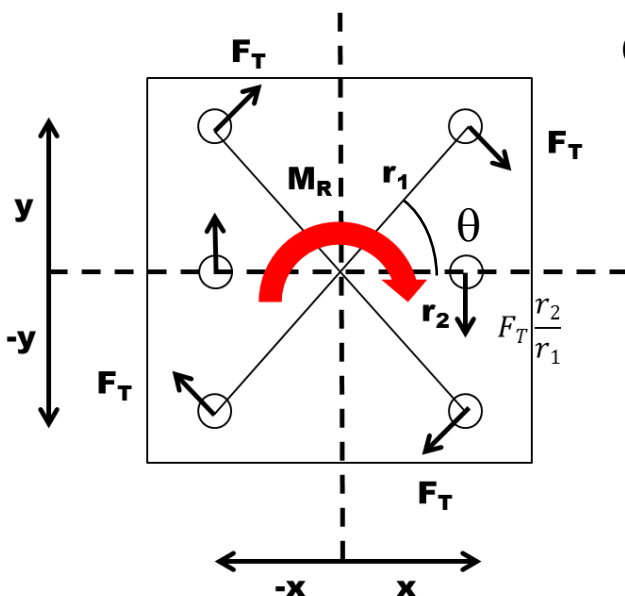
$$F_T = \frac{M_R \times r_1}{\sum (x^2 + y^2)}$$

Applied Torsional Moment

Longest distance of the bolt from center of the rotation of the bolt group

Summation of the coordinate square

Shear Force due to torsional moment



Combined Vertical and Horizontal direct Shear Force

Vertical Shear $F_{vs} = F_{dvs} + F_T \cos \theta$

Horizontal Shear $F_{hs} = F_{dhs} + F_T \sin \theta$

$$F_{RS} = \sqrt{(F_{dvs} + F_T \cos \theta)^2 + (F_{dhs} + F_T \sin \theta)^2}$$