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[ STUDENT > # RotorHeatingSymbols.mws by electricpete
[ STUDENT >
[ STUDENT > # Compute the total  $I^2R$  energy dissipated during the
[         start
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[ STUDENT > # =====
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[ STUDENT > #=====
[ STUDENT > # Section 1 - Symbols
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[ STUDENT >
[ STUDENT > # RH = RH_unloaded = total energy dissipated in rotor only
[         during an unloaded (inertia-only) start
[ STUDENT > # RH_loaded = total energy dissipated in rotor only during
[         an loaded (inertia-plus load torque) start
[ STUDENT > # TotalHeating - total energy dissipated in both rotor and
[         stator during the start
[ STUDENT > # I2 = Rotor current, referred to the stator side
[ STUDENT > # Im = magnetizing current
[ STUDENT > # Pout = motor output power
[ STUDENT > # T = Telec = motor torque
[ STUDENT > # Tmech = load torque
[ STUDENT > # s = slip
[ STUDENT > # s0 = initial slip (1)
[ STUDENT > # sfinal = final slip (usually close to 0)
[ STUDENT > # t = time
[ STUDENT > # t0 = initial time
[ STUDENT > # tfinal = final time
[ STUDENT > # tfinal - t0 = duration of the start
[ STUDENT > # w = rotational radian speed
[ STUDENT > # wsync = synchronous rotational radian speed
[ STUDENT > # KE = Kinetic Energy of the running motor and load
[ STUDENT > # J = rotational inertia
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[ STUDENT > # =====
[ STUDENT > # Section 2 - Unloaded start - rotor heating only
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[ STUDENT > restart;
[ STUDENT > # Rate of rotor heating is I2^2*R2
[ STUDENT > # Total rotor heating energy is integral over time
[ STUDENT > eq1:=RH=3*Int(I2^2*R2,t=t0..tfinal);

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$$eq1 := RH = 3 \int_{t0}^{tfinal} I2^2 R2 dt$$

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[ STUDENT > # Change of variables
[ STUDENT > eq2:=RH=Int(3*I2^2*R2/Diff(s,t),s=s0..sfinal);

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$$eq2 := RH = \int_{s0}^{sfinal} 3 \frac{I2^2 R2}{\frac{\partial}{\partial t} s} ds$$

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[ STUDENT > # Some calculations to determine ds/dt
[ STUDENT > eq3:=w=(1-s)*wsync;

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$$eq3 := w = (1 - s) wsync$$

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[ STUDENT > eq4:=Diff(w,t)=-wsync*Diff(s,t);

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$$eq4 := \frac{\partial}{\partial t} w = -wsync \left(\frac{\partial}{\partial t} s \right)$$

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[ STUDENT > # T = J dw/dt. This is rotational analog of F=ma =
[ m*dv/dt.

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[ STUDENT > eq5:=Diff(w,t)=T/J;

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$$eq5 := \frac{\partial}{\partial t} w = \frac{T}{J}$$

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[ STUDENT > # compare equation 4 and 5

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[ STUDENT > eq6:=rhs(eq4)=rhs(eq5);

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$$eq6 := -wsync \left(\frac{\partial}{\partial t} s \right) = \frac{T}{J}$$

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[ STUDENT > eq7:=Diff(s,t)=solve(eq6,Diff(s,t));

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$$eq7 := \frac{\partial}{\partial t} s = - \frac{T}{wsync J}$$

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[ STUDENT > # Now we want expression for T

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[ STUDENT > eq8:=T=Pout/(w);

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$$eq8 := T = \frac{Pout}{w}$$

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[ STUDENT > eq8a:=subs(w=(1-s)*wsync,eq8);

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[

$$eq8a := T = \frac{P_{out}}{(1-s) \omega_{sync}}$$

STUDENT > eq9:=Pout=3*I2^2*R2*(1-s)/s;

$$eq9 := P_{out} = 3 \frac{I_2^2 R_2 (1-s)}{s}$$

STUDENT > eq10:=subs(eq9,eq8a);

$$eq10 := T = 3 \frac{I_2^2 R_2}{s \omega_{sync}}$$

STUDENT > eq11:=subs(eq10,eq7);

$$eq11 := \frac{\partial}{\partial t} s = -3 \frac{I_2^2 R_2}{s \omega_{sync}^2 J}$$

STUDENT > eq12:=subs(eq11,eq2);

$$eq12 := RH = \int_{s0}^{sfinal} -s \omega_{sync}^2 J ds$$

STUDENT > # evaluate the integral
STUDENT > eq13 := RH = int(-s*wsync^2*J,s = s0 .. sfinal);
STUDENT >

$$eq13 := RH = -\frac{1}{2} sfinal^2 \omega_{sync}^2 J + \frac{1}{2} s0^2 \omega_{sync}^2 J$$

STUDENT > # Assume that sfinal ~ 0, s0=1
STUDENT > eq14:=subs({sfinal=0,s0=1},eq13);

$$eq14 := RH = \frac{1}{2} \omega_{sync}^2 J$$

STUDENT > # This result shows the total rotor heating during
starting of an UNLOADED (no load torque) motor is equal to
the kinetic energy of the system at full speed.
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STUDENT > # =====
STUDENT > # Section 3 - Unloaded start - total rotor and stator
heating
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STUDENT >
STUDENT > # If we neglect magnetizing current Im on the basis that
load current I2>>Im during most of the start, the total
(rotor plus stator) I^2*R heating during the start can be
estimated as
STUDENT > eq15:=TotalHeating=(R1+R2)/R2*rhs(eq14);

$$eq15 := TotalHeating = \frac{1}{2} \frac{(R1 + R2) \omega_{sync}^2 J}{R2}$$


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[ STUDENT > # Section 4 - Loaded - rotor heating only
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[ STUDENT >
[ STUDENT > #==== Now look at the effect of adding load=====
[ STUDENT > # start with equation 7 rewritten as Taccel = Telec-Tmech
[ STUDENT > instead of previous T representing Telec only.
[ STUDENT >
[ STUDENT >
[ STUDENT > eq16:=subs(T=Telec-Tmech,eq7);
[

$$eq16 := \frac{\partial}{\partial t} s = - \frac{Telec - Tmech}{wsync J}$$

[ STUDENT >
[ STUDENT > eq25:=subs({eq16,RH=RH_loaded},eq2);
[

$$eq25 := RH\_loaded = \int_{s0}^{sfinal} -3 \frac{I2^2 R2 wsync J}{Telec - Tmech} ds$$

[ STUDENT > # Compare above RH_loaded (loaded rotor heating RH_loaded)
[ STUDENT > to below RH_unloaded (unloaded rotor heating RH from
[ STUDENT > equation 2 and 7)
[ STUDENT > eq2a:=subs({subs(T=Telec,eq7),RH=RH_unloaded},eq2);
[

$$eq2a := RH\_unloaded = \int_{s0}^{sfinal} -3 \frac{I2^2 R2 wsync J}{Telec} ds$$

[ STUDENT >
[ STUDENT > # Comparison of eq25 and eq2a shows that the integrand for
[ STUDENT > the loaded start is equal to Telec/(Telec-Tmech) times the
[ STUDENT > integrand for the unloaded start
[ STUDENT >
[ STUDENT > # Therefore we can adjust equation 12 to incorporate the
[ STUDENT > effects of adding load as follows:
[ STUDENT > eq26:=RH_loaded =
[ STUDENT > Int(-s*wsync^2*J*Telec(s)/(Telec(s)-Tmech(s)),s = s0 ..
[ STUDENT > sfinal);

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$$eq26 := RH_loaded = \int_{s0}^{sfinal} - \frac{s \, wsync^2 \, J \, Telec(s)}{Telec(s) - Tmech(s)} ds$$

[STUDENT >

[STUDENT > # Express this in terms of the kinetic energy (at sync speed) KE=wsync^2*J/2

[STUDENT > eq27:=RH_loaded =
2*KE*Int(-s*Telec(s)/(Telec(s)-Tmech(s)),s = s0 ..
sfinal);

$$eq27 := RH_loaded = 2 \, KE \int_{s0}^{sfinal} - \frac{s \, Telec(s)}{Telec(s) - Tmech(s)} ds$$

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[STUDENT > # Reverse the limits of integration (removes negative sign) and assume s0=1

[STUDENT > eq27:=RH_loaded = 2*Int(s*Telec(s)/(Telec(s)-Tmech(s)),s =
sfinal .. 1)*KE;

$$eq27 := RH_loaded = 2 \int_{sfinal}^1 \frac{s \, Telec(s)}{Telec(s) - Tmech(s)} ds \, KE$$

[STUDENT > # *** From equation 27 we find the total starting heating for loaded start will now be approximately the final kinetic energy times Integral{2s*(Telec/(Telec-Tmech))}ds. That integral equates to a weighted average of (Telec/(Telec-Tmech)) with 2s being the weighting factor.

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[STUDENT > # graphical example as follows:

[STUDENT > Telec:=V^2/((R1+R2/s)^2+(X1+X2)^2)*R2/s/wsync:

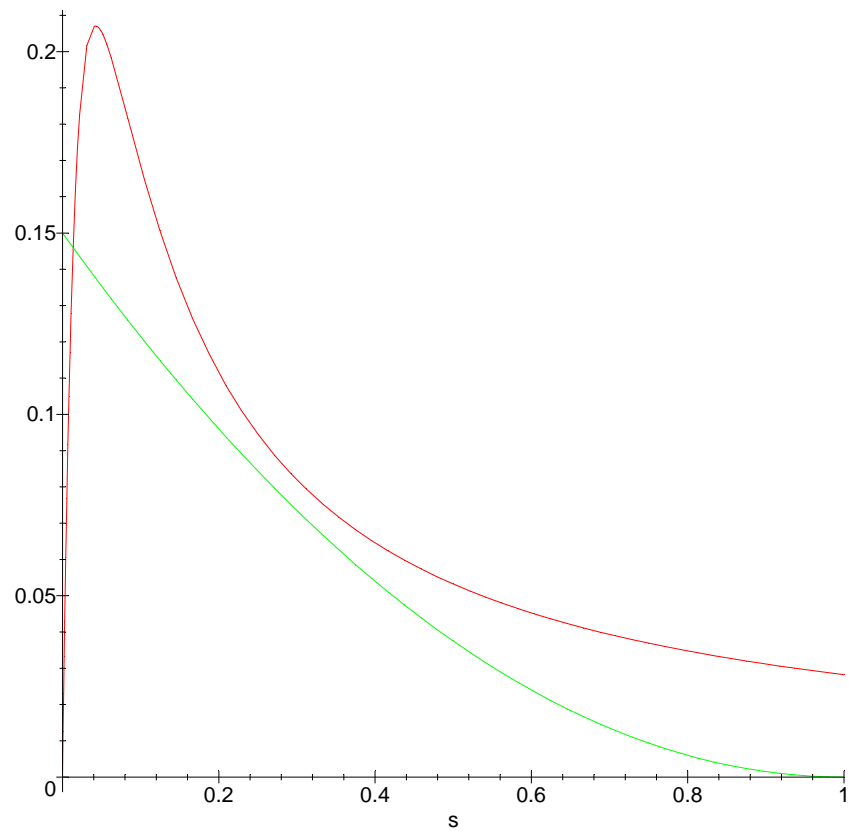
[STUDENT > Telec:=subs({R2=0.06,R1=1,X1=0.5,X2=0.5,V=1,wsync=1},Telec):

[STUDENT > Tmech:=subs(k=0.15,k*(1-s)^2):

[STUDENT > mytitle:=convert([Telectrical, Tmechanical],string);
plot({Tmech,Telec},s=0.0001..1,title=mytitle);

mytitle := [Telectrical, Tmechanical]

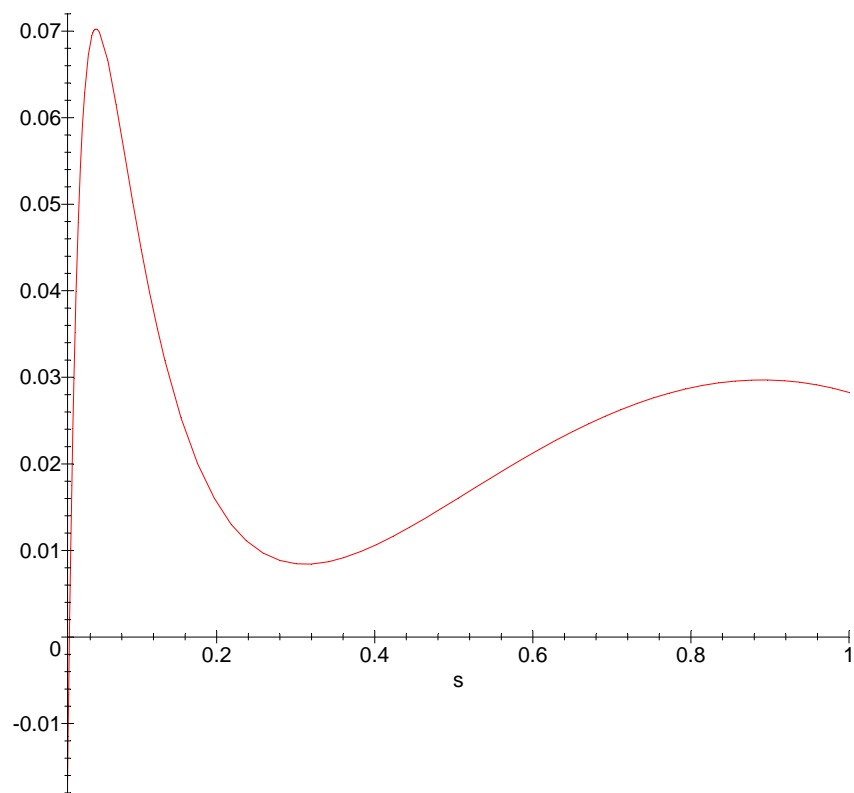
[Telectrical, Tmechanical]



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STUDENT > mytitle:=convert([Telectrical - Tmechanical],string):  
           plot(Telec-Tmech,s=0.0113..1,title=mytitle);
```

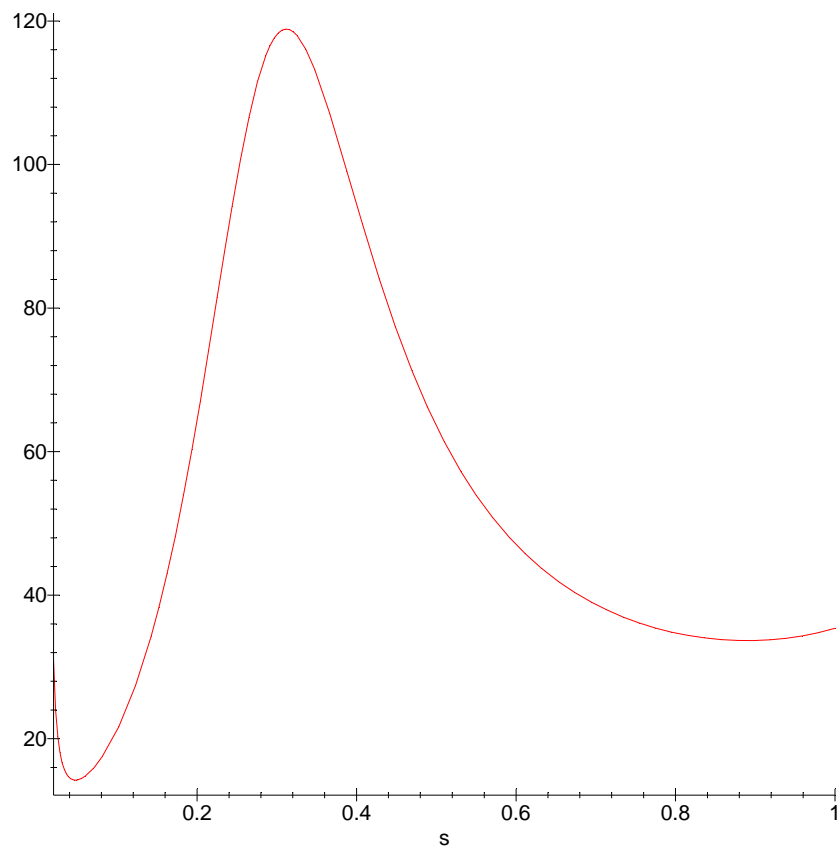
[Telectrical-Tmechanical]



[STUDENT >

[STUDENT > mytitle:=convert([1 / (Telectrical - Tmechanical
)],string):
plot(1/(Telec-Tmech),s=0.02..1,title=mytitle);

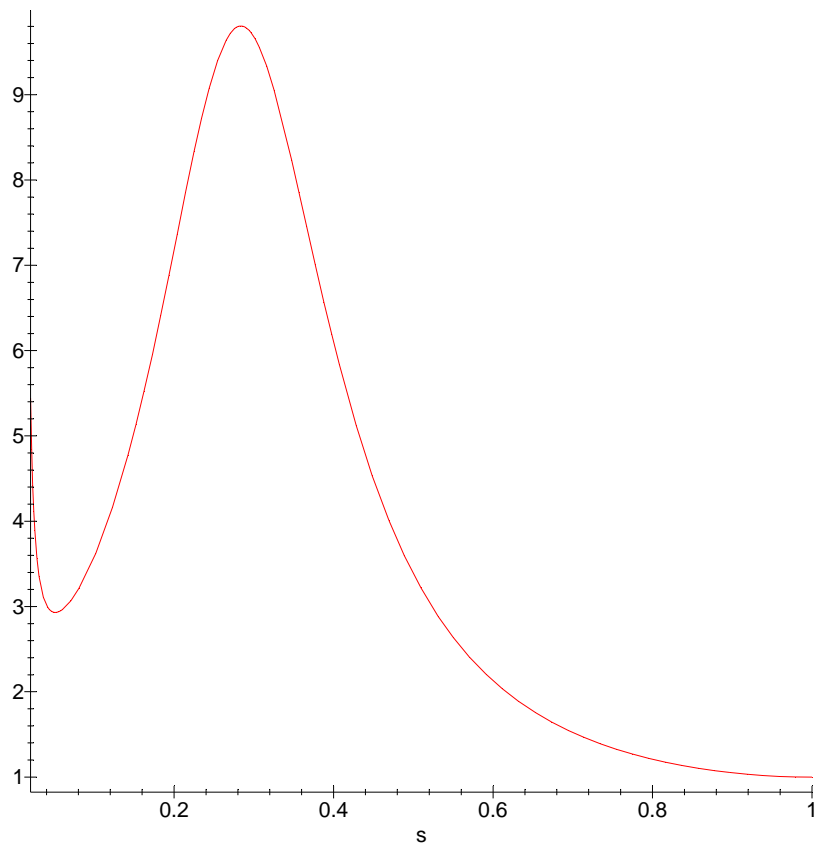
[1/(Telectrical-Tmechanical)]



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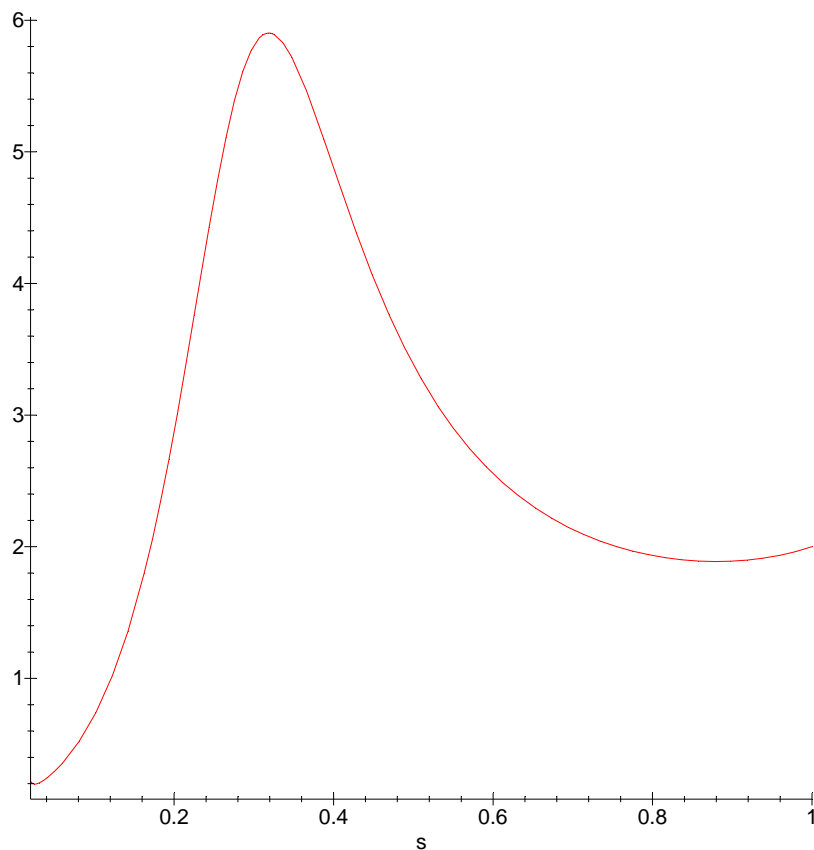
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[ STUDENT > mytitle:=convert([Telectrical / ( Telectrical -  
    Tmechanical )],string):  
    plot(Telec/(Telec-Tmech),s=0.02..1,title=mytitle);
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[Telectrical/(Telectrical-Tmechanical)]



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STUDENT > mytitle:=convert([2 * s * Telectrical / ( Telectrical -  
Tmechanical )],string):  
plot(2 * s*Telec/(Telec-Tmech),s=0.02..1,title=mytitle);
```

$$[2*s*Telectrical/(Telectrical-Tmechanical)]$$



STUDENT > # Note the area under the above curve is always more than one since $Te/(Te-Tm)$ always ≥ 1 and Integral $(2*s*1)$ from zero to 1 gives 1.

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STUDENT > # ** The rotor total heating during the loaded start is the area under the above curve times the final kinetic energy.

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STUDENT > # Section 5 - Loaded start - total rotor plus stator heating

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STUDENT > # Using similar logic as described for equation 15, the total (rotor plus stator) heating during a loaded start would be approx the above rotor heating times $(R1+R2)/R2$

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